

Classification of ribbon 2-knots with ribbon crossing number up to four

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1 Introduction

A ribbon 2-knot is a knotted 2-sphere in \mathbb{R}^4 that bounds a ribbon 3-disk, which is an immersed 3-disk with only ribbon singularities. The ribbon crossing number of a ribbon 2-knot is the minimal number of the ribbon singularities of any ribbon 3-disk bounding the knot [14]. Yasuda has classified ribbon 2-knots with ribbon crossing number up to three in [13] and has enumerated those with ribbon crossing number four in [15]. In this paper we classify these ribbon 2-knots.

Theorem 1. *The number of mutually non-isotopic ribbon 2-knots with ribbon crossing number four is either 111 or 112. Amongst them 9 or 10 knots are positive-amphicheiral. So, if each chiral pair is counted as one knot, the number of ribbon 2-knots with ribbon crossing number four is either 60 or 61; see Table 1.*

Table 1: Numbers of the ribbon 2-knots with ribbon crossing number up to four.

| Ribbon crossing number | 0 | 1 | 2 | 3 | 4 |
|--|---|---|---|----|---------|
| (i) Number of ribbon 2-knots, each chiral pair is counted separately | 1 | 0 | 3 | 13 | 111/112 |
| (ii) Number of ribbon 2-knots, each chiral pair is counted as one knot | 1 | 0 | 2 | 7 | 60/61 |

The ribbon 2-knots with ribbon crossing number with up to three are completely classified by the Alexander polynomial. However, those with ribbon crossing number four listed in [15] have not been classified. Theorem 1 means that there is an indistinguishable pair of ribbon 2-knots, Y43 and Y46 in Table 3, which are positive-amphicheiral; they have isomorphic knot group. Also, there is one knot, Y112 (the ribbon handlebody is shown in Fig. 1), which had been missed in [15].

Satoh [8] introduced a virtual arc presentation for a ribbon 2-knot. If a ribbon 2-knot K is presented by a virtual arc with n classical crossings, then the ribbon crossing number of K is at most n . In [2] ribbon 2-knots presented by a virtual arc with up to four crossings are enumerated, and in [6] those ribbon 2-knots are classified. There are 24 ribbon 2-knots with ribbon crossing number up to four, which are not presented by a virtual arc with up to four crossings. So, we have only to consider these knots. We have 27 sets of ribbon 2-knots \mathcal{A}_i ($i = 1, 2, \dots, 17$) and $\mathcal{A}_j!$ ($j = 2, 3, 4, 7, 8, 10, 11, 12, 14, 16$), which consist of knots sharing the same Alexander polynomial; $\mathcal{A}_j!$ is the set consisting

of the mirror images of the knots in \mathcal{A}_j . The knots in the sets \mathcal{A}_i with $i \leq 13$ (and so \mathcal{A}_j with $j \leq 12$) have been classified in [6]. Thus, we classify the knots in \mathcal{A}_i with $i = 14, 15, 16, 17$ (Sec. 5). The knots in these sets are ribbon 2-knots of 1-fusion. In order to classify the knots in these sets we use the trace set, or the twisted Alexander polynomial associated to the representations to $\mathrm{SL}(2, \mathbb{C})$. The *trace set* is an invariant defined for a ribbon 2-knot of 1-fusion from the representations of the knot group to $\mathrm{SL}(2, \mathbb{C})$; see Sec. 4 in [7]. For the twisted Alexander polynomial of a ribbon 2-knot, see [4].

This paper is organized as follows: In Secs. 2 and 3, we review a ribbon handlebody presentation of a ribbon 2-knot and the stable transformations for a ribbon handlebody presentation, which were introduced in [3]. In Sec. 4 we give Yasuda's table of the ribbon 2-knots with ribbon crossing number up to four (Tables 2 and 3), which contain the 1-fusion notation of the knots. In Sec. 5 we classify the knots in \mathcal{A}_i , $i = 14, 15, 16, 17$, which completes the proof of Theorem 1.

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2 Ribbon handlebody presentation of a ribbon 2-knot

In this section we review a ribbon handlebody presentation of a ribbon 2-knot introduced in [3]. A *ribbon handlebody* \mathcal{H} is a ribbon 2-disk, which is a 2-dimensional handlebody in \mathbb{R}^3 consisting of $(m + 1)$ 0-handles D_0, D_1, \dots, D_m and m 1-handles B_1, B_2, \dots, B_m such that the preimage of each ribbon singularity consists of an arc in the interior of a 0-handle and a cocore of a 1-handle. We set $\mathcal{H} = \mathcal{D} \cup \mathcal{B}$, where $\mathcal{D} = D_0 \cup D_1 \cup \dots \cup D_m$ and $\mathcal{B} = B_1 \cup B_2 \cup \dots \cup B_m$. We associate to a ribbon handlebody \mathcal{H} an immersed 3-disk $V_{\mathcal{H}}$ in \mathbb{R}^4 defined by

$$V_{\mathcal{H}} = \mathcal{D} \times [-2, 2] \cup \mathcal{B} \times [-1, 1]. \quad (1)$$

Then $V_{\mathcal{H}}$ is a ribbon 3-disk for the ribbon 2-knot $K_{\mathcal{H}} = \partial V_{\mathcal{H}}$ in \mathbb{R}^4 . Conversely, for any ribbon 2-knot K in \mathbb{R}^4 , there exists a ribbon handlebody \mathcal{H} such that K is ambient isotopic to the associated 2-knot $K_{\mathcal{H}}$; see [1, 10, 12].

We suppose that each 1-handle B_q is the image of an embedding $b_q : I \times I \rightarrow \mathbb{R}^3$, $q = 1, 2, \dots, m$. Let $\beta_q : I \rightarrow \mathbb{R}^3$ be the center line of the 1-handle B_p defined by $\beta_q(t) = b_q(1/2, t)$, which is an oriented path such that

$$\begin{aligned} \beta_q(I) \cap \mathcal{D} &= \{\beta_q(0), \beta_q(t_{q,1}), \beta_q(t_{q,2}), \dots, \beta_q(t_{q,\ell_q}), \beta_q(1)\}, \\ 0 &< t_{q,1} < t_{q,2} < \dots < t_{q,\ell_q} < 1. \end{aligned} \quad (2)$$

Let $\iota_q, \tau_q, \lambda(q, j)$ ($j = 1, 2, \dots, \ell_q$) be integers in $\{0, 1, \dots, m\}$ determined by

$$\beta_q(0) \in \partial D_{\iota_q}, \quad \beta_q(1) \in \partial D_{\tau_q}, \quad \beta_q(t_{q,j}) \in \mathrm{Int} D_{\lambda(q,j)}, \quad j = 1, 2, \dots, \ell_q. \quad (3)$$

Thus, β is an oriented path joining D_{ι_q} and D_{τ_q} . At the intersection $\beta_q(t_{q,j})$ if β_q passes from the negative side of $D_{\lambda(q,j)}$ through to the positive side we define $\epsilon(q,j) = +1$, and if it passes in the opposite direction we define $\epsilon(q,j) = -1$.

Then for a ribbon handlebody \mathcal{H} we define a *ribbon handlebody presentation* $[X | R]$ consisting of:

- $X = \{x_0, x_1, \dots, x_m\}$, where each letter x_q corresponds to the 0-handle D_q ,
- $R = \{\rho_1, \rho_2, \dots, \rho_m\}$, where each relation $\rho_q : x_{\iota_q}^{w_q} = x_{\tau_q}$ (or $x_{\tau_q} = x_{\iota_q}^{w_q}$) corresponds to the 1-handle B_q that joins D_{ι_q} to D_{τ_q} passing through 0-handles according to the word w_q :

$$w_q = x_{\lambda(q,1)}^{\epsilon(q,1)} x_{\lambda(q,2)}^{\epsilon(q,2)} \cdots x_{\lambda(q,\ell_q)}^{\epsilon(q,\ell_q)}. \quad (4)$$

In particular, if $\beta_q(I) \cap \mathcal{D} = \{\beta_q(0), \beta_q(1)\}$, then $\rho_q : x_{\iota_q} = x_{\tau_q}$.

For a ribbon handlebody presentation $P = [X | R]$, $X = \{x_0, x_1, \dots, x_m\}$ and $R = \{\rho_1, \rho_2, \dots, \rho_m\}$ with $\rho_q : x_{\iota_q}^{w_q} = x_{\tau_q}$, $w_q \in F[X]$, we can associate an oriented labelled tree $\tilde{P} = (X, E, \lambda)$, where X is a set of vertices, E is a set of oriented edges:

$$E = \{\overrightarrow{x_{\iota_q} x_{\tau_q}} \mid q = 1, \dots, m\}, \quad (5)$$

and $\lambda : E \rightarrow F[X]$ is a labeling function defined by $\lambda(\overrightarrow{x_{\iota_q} x_{\tau_q}}) = w_q$.

Conversely, for an oriented labeled tree (X, E, λ) as above, we obtain a unique ribbon handlebody presentation $P = [X | R]$ and also the associated ribbon 2-knot of m -fusion, which we denote by K_P ; cf. Proposition 3.3 in [3]. Note that the knot group of K_P , $\pi_1(\mathbb{R}^4 - K_P)$, is presented by $\langle X | \tilde{R} \rangle$, where \tilde{R} is a set of relations $\{\tilde{\rho}_1, \tilde{\rho}_2, \dots, \tilde{\rho}_m\}$ with $\tilde{\rho}_q : w_q^{-1} x_{\iota_q} w_q = x_{\tau_q}$; see [11].

Therefore, any ribbon 2-knot with ribbon crossing number r is obtained from an oriented labeled tree (X, E, λ) as above such that $\sum_{q=1}^m \ell_q = r$, where ℓ_q is the word length of the word w_q as in Eq. (4).

3 Stable transformations of a ribbon handlebody presentation

Let $P = [X | R]$ be a ribbon handlebody presentation, where $X = \{x_0, x_1, \dots, x_m\}$ and $R = \{\rho_1, \dots, \rho_m\}$ with

$$\rho_q : x_{\iota_q}^{w_q} = x_{\tau_q}, \quad w_q = x_{\lambda(q,1)}^{\epsilon(q,1)} x_{\lambda(q,2)}^{\epsilon(q,2)} \cdots x_{\lambda(q,\ell_q)}^{\epsilon(q,\ell_q)}, \quad \epsilon(q,s) = \pm 1. \quad (6)$$

We call the following transformations of a ribbon handlebody presentation *stable transformations*:

- S1. Replace $\rho_q : x_{\iota_q}^{w_q} = x_{\tau_q}$ by $x_{\iota_q} = x_{\tau_q}^{(w_q^{-1})}$.
- S2. Replace $\rho_q : x_{\iota_q}^{w_q} = x_{\tau_q}$ by either $x_{\iota_q}^{\epsilon w_q} = x_{\tau_q}$ or $x_{\iota_q}^{w_q \epsilon} = x_{\tau_q}$, $\epsilon = \pm 1$.
- S3. Add a generator y and a relation $y = x_p^w$ or $x_p = y^w$, where w is a word in x_0, x_1, \dots, x_m .

S3'. Inverse transformation of S3.

- S4. (i) Suppose $\tau_p = \iota_q$. Replace either $\rho_p : x_{\iota_p}^{w_p} = x_{\tau_p}$ or $\rho_q : x_{\iota_q}^{w_q} = x_{\tau_q}$ by $x_{\iota_p}^{w_p w_q} = x_{\tau_q}$.
(ii) Suppose $\iota_p = \iota_q$. Replace $\rho_p : x_{\iota_p}^{w_p} = x_{\tau_p}$ by $x_{\tau_q}^{w_q^{-1} w_p} = x_{\tau_p}$.
(iii) Suppose $\tau_p = \tau_q$. Replace $\rho_p : x_{\iota_p}^{w_p} = x_{\tau_p}$ by $x_{\iota_p}^{w_p w_q^{-1}} = x_{\iota_q}$.
- S5. (i) Suppose $\lambda(p, s) = \tau_q$. Replace $x_{\lambda(p, s)} (= x_{\tau_q})$ in w_p in ρ_p by $w_q^{-1} x_{\iota_q} w_q$.
(ii) Suppose $\lambda(p, s) = \iota_q$. Replace $x_{\lambda(p, s)} (= x_{\iota_q})$ in w_p in ρ_p by $w_q x_{\tau_q} w_q^{-1}$.

Then we have the following (Proposition 4.1 in [3]):

Proposition 2. *Suppose that ribbon handlebody presentations P and P' are related by a finite sequence of stable transformations S1–S5. Then, the associated ribbon 2-knots K_P and $K_{P'}$ are ambient isotopic.*

We denote by

$$R(p_1, q_1, \dots, p_n, q_n), \quad p_1, q_1, \dots, p_n, q_n, \in \mathbb{Z}, \quad (7)$$

a ribbon 2-knot of 1-fusion, which is presented by the ribbon handlebody presentation

$$[x, y \mid x = y^w \ (w = x^{p_1} y^{q_1} \dots x^{p_n} y^{q_n})]. \quad (8)$$

cf. [5, Sect. 2]. Then, by the transformation S1 we have:

$$R(p_1, q_1, \dots, p_n, q_n) \approx R(-q_n, -p_n, \dots, -q_1, -p_1) \quad (9)$$

$$R(p_1, q_1, \dots, p_n, q_n)! \approx R(-p_1, -q_1, \dots, -p_n, -q_n) \approx R(q_n, p_n, \dots, q_1, p_1), \quad (10)$$

where $K \approx K'$ denotes that the two 2-knots K and K' are ambient isotopic and $K!$ the mirror image of K .

Example 3. The ribbon 2-knot Y43 presented by

$$P(\text{Y43}) = [x_1, x_2, x_3 \mid \rho_1 : x_1^{x_2 x_1} = x_2, \rho_2 : x_1^{x_3 x_2} = x_3]. \quad (11)$$

is isotopic to the ribbon 2-knot of 1-fusion $R(1, 1, -1, -1, -1, -1, 1, 1)$. Thus, by Eqs. (9) and (10) Y43 is positive-amphicheiral.

Proof By the transformation S5(ii), we replace x_1 in the power of ρ_1 with $x_3 x_2 x_3 x_2^{-1} x_3^{-1}$ coming from ρ_2 . Then $P(\text{Y43})$ is deformed into

$$P(\text{Y43})_1 = [x_1, x_2, x_3 \mid \rho'_1 : x_1^{x_2 x_3 x_2 x_3 x_2^{-1} x_3^{-1}} = x_2, \rho_2 : x_1^{x_3 x_2} = x_3]. \quad (12)$$

By the transformation S4(ii), we replace ρ'_1 by $\rho''_1 : x_3^{(x_3 x_2)^{-1} x_2 x_3 x_2 x_3 x_2^{-1} x_3^{-1}} = x_2$. Then $P(\text{Y43})_1$ is deformed into

$$P(\text{Y43})_2 = [x_1, x_2, x_3 \mid \rho''_1 : x_3^{x_2^{-1} x_3^{-1} x_2 x_3 x_2 x_3 x_2^{-1} x_3^{-1}} = x_2, \rho_2 : x_1^{x_3 x_2} = x_3]. \quad (13)$$

By the transformation S3', $P(\text{Y43})_2$ is deformed into

$$P(\text{Y43})_3 = [x_2, x_3 \mid x_3^{x_2^{-1} x_3^{-1} x_2 x_3 x_2 x_3 x_2^{-1} x_3^{-1}} = x_2], \quad (14)$$

which presents $R(-1, -1, 1, 1, 1, 1, -1, -1) (\approx R(1, 1, -1, -1, -1, -1, 1, 1))$. \square

4 Yasuda's Table

Yasuda enumerated ribbon 2-knots with ribbon crossing number up to three in [13] and ribbon 2-knots with ribbon crossing four in [15]. He claims that any ribbon 2-knots with ribbon crossing number up to four is presented by one of the following ribbon handlebody presentations:

$$P_1(w) = [x_1, x_2 \mid x_1^w = x_2]; \quad (15)$$

$$P_2(w_1, w_2) = [x_1, x_2, x_3 \mid x_1^{w_1} = x_2, x_1^{w_2} = x_3]; \quad (16)$$

$$P_3(w_1, w_2, w_3) = [x_1, x_2, x_3, x_4 \mid x_1^{w_1} = x_2, x_2^{w_2} = x_3, x_3^{w_3} = x_4]; \quad (17)$$

$$P_4(w_1, w_2, w_3) = [x_1, x_2, x_3, x_4 \mid x_1^{w_1} = x_2, x_1^{w_2} = x_3, x_1^{w_3} = x_4]; \quad (18)$$

$$P_5(w_1, w_2, w_3, w_4) = [x_1, x_2, x_3, x_4, x_5 \mid x_1^{w_1} = x_2, x_1^{w_2} = x_3, x_1^{w_3} = x_4, x_2^{w_4} = x_5]; \quad (19)$$

$$P_6(w_1, w_2, w_3, w_4) = [x_1, x_2, x_3, x_4, x_5 \mid x_1^{w_1} = x_2, x_1^{w_2} = x_3, x_1^{w_3} = x_4, x_1^{w_4} = x_5]. \quad (20)$$

Remark 4. A ribbon 2-knot with ribbon crossing number up to four presented by the ribbon handlebody presentation

$$[x_1, x_2, x_3, x_4, x_5 \mid x_1^{w_1} = x_2, x_2^{w_2} = x_3, x_3^{w_3} = x_4, x_4^{w_4} = x_5], \quad (21)$$

$w_i \in F[x_1, x_2, x_3, x_4, x_5]$, is transformed into a ribbon 2-knot presented by one of the ribbon handlebody presentations (15)–(18).

In a similar way to Example 3, we can deform a ribbon 2-knot with up to four ribbon crossing by a finite sequence of stable transformations S1–S5 (Proposition 2) into one of the following two types:

- Type 1: a ribbon 2-knot of 1-fusion.
- Type 2: a composition of two ribbon 2-knots of 1-fusion.

In order to determine the type of a ribbon 2-knot we use the following proposition (Proposition 3.1 in [6]). Indeed, the fundamental group of a Type 2 ribbon 2-knot with ribbon crossing number up to four is isomorphic to the free product $\mathbb{Z}_3 * \mathbb{Z}_3$ (Proposition 3.2 in [6]).

Proposition 5. *The fundamental group of the 2-fold cover of S^4 branched over a ribbon 2-knot of 1-fusion K is the finite cyclic group whose order is the determinant of K , $|\Delta_K(-1)|$.*

Table 2 lists the ribbon 2-knots with ribbon crossing number up to three given by [13], and Table 3 lists the ribbon 2-knots with ribbon crossing four given by Yasuda [15]. Each column in Tables 2 and 3 shows as follows:

- The first column, Name, shows the names of the ribbon 2-knots:
 - (i) The names Ym_n , Ym_n^* ($m = 2, 3$) in Table 2 denote the knots m_n , m_n^* with ribbon crossing number m in [13]; Ym_n^* is the mirror image of Ym_n .
 - (ii) The name Yn ($1 \leq n \leq 111$) in Table 3 denotes the ribbon 2-knot K_n^2 with ribbon crossing number four in [15].

- The column, C, shows the chirality of the ribbon 2-knots:
 - (i) The symbol “a” means that the ribbon 2-knot is positive-amphicheiral.
 - (ii) In Table 3 the mirror image knot is listed.
- The column, Presentation, shows a ribbon handlebody presentation of the ribbon 2-knot: P_i is one of the ribbon handlebody presentations (15)–(20), and the symbols j and \bar{j} ($j = 1, 2, 3, 4, 5$) denote the letters x_j and x_j^{-1} , respectively. For example, $P_2(21, 32)$ for the knot Y43 in Table 3 means the presentation Eq. (11) in Example 3.
- The column, Type, shows the type of the ribbon 2-knot:
 - (i) A Type 1 ribbon 2-knot is presented by a 1-fusion notation $R(p_1, q_1, \dots, p_m, q_m)$.
 - (ii) A Type 2 ribbon 2-knot is presented by a composition $R(\epsilon_1, \epsilon_2) \# R(\epsilon_3, \epsilon_4)$, $\epsilon_i = \pm 1$.
- The column, $\Delta(t)$, shows the normalized Alexander polynomial of the ribbon 2-knot in the abbreviated form: $(c_{-m} c_{-m+1} \dots c_{-1} [c_0] c_1 \dots c_{n-1} c_n) = \sum_{i=-m}^n c_i t^i$, $c_i \in \mathbb{Z}$. We normalize the Alexander polynomial of a ribbon 2-knot $\Delta(t) \in \mathbb{Z}[t^{\pm 1}]$, so that $\Delta(1) = 1$ and $(d/dt)\Delta(1) = 0$; cf. [1].
- The column, Det, shows the determinant of the ribbon 2-knot, which is given by $|\Delta(-1)|$.
- The column, Set, shows the name of the set of the ribbon 2-knots sharing the same Alexander polynomial; $\mathcal{A}_i!$ denotes the set of the mirror images of the knots in \mathcal{A}_i . For example, $\mathcal{A}_2 = \{Y3.1^*, Y27\}$, $\mathcal{A}_2! = \{Y3.1, Y34\}$, and the knots in the sets \mathcal{A}_i , $i = 1, 5, 6, 9, 13, 15, 17$, have reciprocal Alexander polynomials, and so we do not consider the set of mirror images. The sets \mathcal{A}_i with $i \leq 13$ are the same sets as in [6].

The knot Y112 is missed in [15], which has the same Alexander polynomial as Y109; the ribbon handlebodies are shown as in Fig. 1.

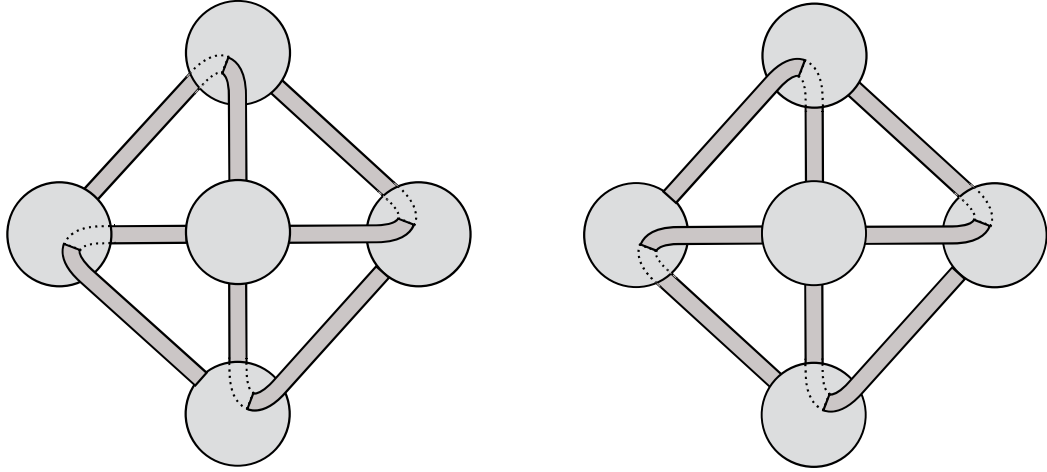


Figure 1: Ribbon handlebodies presenting Y109 and Y112.

Table 2: Ribbon 2-knots with up to three crossings.

| Name | C | Presentation | Type | $\Delta(t)$ | Det | Set |
|-------|---|----------------------------------|---------------------------|-----------------------|-----|------------------|
| Y0 | a | | Trivial knot | $([1])$ | 1 | \mathcal{A}_1 |
| Y2.1 | a | $P_1(21)$ | $R(1, 1)$ | $(1 \ [-1] \ 1)$ | 3 | |
| Y2.2 | | $P_1(2\bar{1})$ | $R(1, -1)$ | $([0] \ 2 \ -1)$ | 3 | $\mathcal{A}_3!$ |
| Y2.2* | | $P_1(\bar{2}1)$ | $R(-1, 1)$ | $(-1 \ 2 \ [0])$ | 3 | \mathcal{A}_3 |
| Y3.1 | | $P_1(211)$ | $R(1, 2)$ | $(1 \ -1 \ [0] \ 1)$ | 1 | $\mathcal{A}_2!$ |
| Y3.1* | | $P_1(221)$ | $R(-1, -2)$ | $(1 \ [0] \ -1 \ 1)$ | 1 | \mathcal{A}_2 |
| Y3.2 | | $P_1(2\bar{1}\bar{1})$ | $R(1, -2)$ | $([0] \ 1 \ 1 \ -1)$ | 1 | |
| Y3.2* | | $P_1(\bar{2}11)$ | $R(-1, 2)$ | $(-1 \ 1 \ 1 \ [0])$ | 1 | |
| Y3.3 | | $P_2(31, 2)$ | $R(-1, 1, 1, 1)$ | $(-1 \ 2 \ -1 \ [1])$ | 5 | |
| Y3.3* | | $P_2(\bar{3}\bar{1}, \bar{2})$ | $R(1, -1, -1, -1)$ | $([1] \ -1 \ 2 \ -1)$ | 5 | |
| Y3.4 | | $P_2(31, \bar{2})$ | $R(1, 1, -1, 1)$ | $(1 \ -2 \ [2])$ | 5 | |
| Y3.4* | | $P_2(3\bar{1}, \bar{2})$ | $R(-1, -1, 1, -1)$ | $([2] \ -2 \ 1)$ | 5 | |
| Y3.5 | a | $P_2(3\bar{1}, \bar{2})$ | $R(1, -1, -1, 1)$ | $(-1 \ [3] \ -1)$ | 5 | |
| Y3.6 | | $P_3(3, 4, 2)$ | $R(-1, 1, -1, -1, 1, 1)$ | $(1 \ -3 \ 3 \ [0])$ | 5 | |
| Y3.6* | | $P_3(\bar{3}, \bar{4}, \bar{2})$ | $R(1, -1, 1, 1, -1, -1)$ | $([0] \ 3 \ -3 \ 1)$ | 5 | |
| Y3.7 | | $P_3(3, 4, \bar{2})$ | $R(-1, 1, 1, -1, 1, 1)$ | $(-1 \ 3 \ [-2] \ 1)$ | 5 | |
| Y3.7* | | $P_3(3, \bar{4}, \bar{2})$ | $R(1, -1, -1, 1, -1, -1)$ | $(1 \ [-2] \ 3 \ -1)$ | 5 | |

Table 3: Ribbon 2-knots with four crossings.

| Name | C | Presentation | Type | $\Delta(t)$ | Det | Set |
|------|-----|---------------------------------------|--------------------------|---------------------------|-----|------------------|
| Y1 | Y7 | $P_1(2111)$ | $R(1, 3)$ | $(1 \ -1 \ 0 \ [0] \ 1)$ | 3 | |
| Y2 | a | $P_1(2121)$ | $R(1, 1, 1, 1)$ | $(1 \ -1 \ [1] \ -1 \ 1)$ | 5 | |
| Y3 | Y8 | $P_1(2\bar{1}\bar{1}\bar{1})$ | $R(3, -1)$ | $([0] \ 1 \ 0 \ 1 \ -1)$ | 3 | $\mathcal{A}_4!$ |
| Y4 | Y9 | $P_1(2\bar{1}2\bar{1})$ | $R(1, -1, 1, -1)$ | $([0] \ 0 \ 3 \ -2)$ | 5 | |
| Y5 | a | $P_1(2211)$ | $R(2, 2)$ | $(1 \ 0 \ [-1] \ 0 \ 1)$ | 1 | |
| Y6 | Y10 | $P_1(22\bar{1}\bar{1})$ | $R(2, -2)$ | $([0] \ 0 \ 2 \ 0 \ -1)$ | 1 | |
| Y7 | Y1 | $P_1(2221)$ | $R(3, 1)$ | $(1 \ [0] \ 0 \ -1 \ 1)$ | 3 | |
| Y8 | Y3 | $P_1(\bar{2}111)$ | $R(-1, 3)$ | $(-1 \ 1 \ 0 \ 1 \ [0])$ | 3 | \mathcal{A}_4 |
| Y9 | Y4 | $P_1(\bar{2}\bar{1}\bar{2}1)$ | $R(-1, 1, -1, 1)$ | $(-2 \ 3 \ 0 \ [0])$ | 5 | |
| Y10 | Y6 | $P_1(\bar{2}\bar{2}11)$ | $R(-2, 2)$ | $(-1 \ 0 \ 2 \ 0 \ [0])$ | 1 | |
| Y11 | Y18 | $P_2(231, \bar{2})$ | $R(2, 1, -1, 1)$ | $(1 \ 0 \ [-2] \ 2)$ | 3 | |
| Y12 | Y17 | $P_2(23\bar{1}, \bar{2})$ | $R(2, 1, -1, -1)$ | $([1] \ 1 \ -2 \ 1)$ | 3 | |
| Y13 | Y16 | $P_2(2\bar{3}\bar{1}, \bar{2})$ | $R(2, -1, -1, 1)$ | $([0] \ 2 \ -1)$ | 3 | $\mathcal{A}_3!$ |
| Y14 | Y15 | $P_2(2\bar{3}\bar{1}, \bar{2})$ | $R(2, -1, -1, -1)$ | $([0] \ 1 \ 0 \ 1 \ -1)$ | 3 | $\mathcal{A}_4!$ |
| Y15 | Y14 | $P_2(\bar{2}31, 2)$ | $R(-2, 1, 1, 1)$ | $(-1 \ 1 \ 0 \ 1 \ [0])$ | 3 | \mathcal{A}_4 |
| Y16 | Y13 | $P_2(\bar{2}\bar{3}\bar{1}, 2)$ | $R(1, -1, -1, 2)$ | $(-1 \ 2 \ [0])$ | 3 | \mathcal{A}_3 |
| Y17 | Y12 | $P_2(\bar{2}\bar{3}\bar{1}, 2)$ | $R(-2, -1, 1, 1)$ | $(1 \ -2 \ 1 \ [1])$ | 3 | |
| Y18 | Y11 | $P_2(\bar{2}\bar{3}\bar{1}, 2)$ | $R(-2, -1, 1, -1)$ | $(2 \ [-2] \ 0 \ 1)$ | 3 | |
| Y19 | Y31 | $P_2(311, 2)$ | $R(-1, 1, 1, 2)$ | $(-1 \ 2 \ -1 \ 0 \ [1])$ | 3 | |
| Y20 | Y33 | $P_2(313, 2)$ | $R(-1, 1, 1, 1, -1, 1)$ | $(-1 \ 2 \ -2 \ 2 \ [0])$ | 7 | |
| Y21 | Y32 | $P_2(313, \bar{2})$ | $R(1, 1, -1, 1, 1, 1)$ | $(1 \ -2 \ 2 \ [-1] \ 1)$ | 7 | |
| Y22 | Y30 | $P_2(3\bar{1}\bar{3}, 2)$ | $R(1, -1, -1, 1, -1, 1)$ | $(-2 \ 4 \ [-1])$ | 7 | |
| Y23 | a | $P_2(3\bar{1}\bar{3}, \bar{2})$ | $R(1, 1, -1, -1, 1, 1)$ | $(2 \ [-3] \ 2)$ | 7 | \mathcal{A}_5 |
| Y24 | Y37 | $P_2(321, 2)$ | $R(-1, 1, 2, 1)$ | $(-1 \ 2 \ 0 \ [-1] \ 1)$ | 1 | |
| Y25 | Y36 | $P_2(3\bar{2}\bar{1}, 2)$ | $R(1, -2, -1, 1)$ | $(-1 \ [2] \ 1 \ -1)$ | 1 | |
| Y26 | Y35 | $P_2(3\bar{2}\bar{1}, \bar{2})$ | $R(1, 1, -2, 1)$ | $([1])$ | 1 | \mathcal{A}_1 |
| Y27 | Y34 | $P_2(3\bar{2}\bar{1}, \bar{2})$ | $R(1, 2, -1, -1)$ | $(1 \ [0] \ -1 \ 1)$ | 1 | \mathcal{A}_2 |
| Y28 | Y39 | $P_2(331, 2)$ | $R(-1, 2, 1, 1)$ | $(-1 \ 1 \ 1 \ -1 \ [1])$ | 1 | |
| Y29 | Y38 | $P_2(331, \bar{2})$ | $R(1, 2, -1, 1)$ | $(1 \ -1 \ -1 \ [2])$ | 1 | |
| Y30 | Y22 | $P_2(\bar{3}\bar{1}\bar{3}, \bar{2})$ | $R(1, -1, -1, 1, 1, -1)$ | $([-1] \ 4 \ -2)$ | 7 | |
| Y31 | Y19 | $P_2(\bar{3}\bar{1}\bar{1}, \bar{2})$ | $R(2, 1, 1, -1)$ | $([1] \ 0 \ -1 \ 2 \ -1)$ | 3 | |
| Y32 | Y21 | $P_2(\bar{3}\bar{1}\bar{3}, 2)$ | $R(1, 1, 1, -1, 1, 1)$ | $(1 \ [-1] \ 2 \ -2 \ 1)$ | 7 | |
| Y33 | Y20 | $P_2(\bar{3}\bar{1}\bar{3}, \bar{2})$ | $R(1, -1, 1, 1, 1, -1)$ | $([0] \ 2 \ -2 \ 2 \ -1)$ | 7 | |
| Y34 | Y27 | $P_2(\bar{3}\bar{2}\bar{1}, 2)$ | $R(-1, -1, 2, 1)$ | $(1 \ -1 \ [0] \ 1)$ | 1 | $\mathcal{A}_2!$ |
| Y35 | Y26 | $P_2(\bar{3}\bar{2}\bar{1}, 2)$ | $R(1, -2, 1, 1)$ | $([1])$ | 1 | \mathcal{A}_1 |
| Y36 | Y25 | $P_2(\bar{3}\bar{2}\bar{1}, \bar{2})$ | $R(1, -1, -2, 1)$ | $(-1 \ 1 \ [2] \ -1)$ | 1 | |
| Y37 | Y24 | $P_2(\bar{3}\bar{2}\bar{1}, \bar{2})$ | $R(1, 2, 1, -1)$ | $(1 \ [-1] \ 0 \ 2 \ -1)$ | 1 | |
| Y38 | Y29 | $P_2(\bar{3}\bar{3}\bar{1}, 2)$ | $R(-1, -2, 1, -1)$ | $([2] \ -1 \ -1 \ 1)$ | 1 | |
| Y39 | Y28 | $P_2(\bar{3}\bar{3}\bar{1}, \bar{2})$ | $R(1, -2, -1, -1)$ | $([1] \ -1 \ 1 \ 1 \ -1)$ | 1 | |

Table 3: Ribbon 2-knots with four crossings (cont'd).

| Name | C | Presentation | Type | $\Delta(t)$ | Det | Set |
|------|-----|-----------------------------------|---|----------------------------|-----|---------------------|
| Y40 | a | $P_2(21, 31)$ | $R(1, 1)\#R(1, 1)$ | $(1 \ -2 \ [3] \ -2 \ 1)$ | 9 | \mathcal{A}_6 |
| Y41 | Y42 | $P_2(21, 3\bar{1})$ | $R(1, 1)\#R(1, -1)$ | $([2] \ -3 \ 3 \ -1)$ | 9 | \mathcal{A}_7 |
| Y42 | Y41 | $P_2(21, \bar{3}1)$ | $R(1, 1)\#R(-1, 1)$ | $(-1 \ 3 \ -3 \ [2])$ | 9 | $\mathcal{A}_7!$ |
| Y43 | a | $P_2(21, 32)$ | $R(-1, -1, 1, 1, 1, 1, -1, -1)$ | $(1 \ -2 \ [3] \ -2 \ 1)$ | 9 | \mathcal{A}_6 |
| Y44 | Y45 | $P_2(21, 3\bar{2})$ | $R(1, -1, 1, 1, -1, 1, 1, -1)$ | $([2] \ -3 \ 3 \ -1)$ | 9 | \mathcal{A}_7 |
| Y45 | Y44 | $P_2(21, \bar{3}2)$ | $R(-1, 1, 1, -1, 1, 1, -1, 1)$ | $(-1 \ 3 \ -3 \ [2])$ | 9 | $\mathcal{A}_7!$ |
| Y46 | a | $P_2(21, \bar{3}\bar{2})$ | $R(1, 1, 1, -1, -1, 1, 1, 1)$ | $(1 \ -2 \ [3] \ -2 \ 1)$ | 9 | \mathcal{A}_6 |
| Y47 | Y52 | $P_2(2\bar{1}, 3\bar{1})$ | $R(1, -1)\#R(1, -1)$ | $([0] \ 0 \ 4 \ -4 \ 1)$ | 9 | \mathcal{A}_8 |
| Y48 | a | $P_2(2\bar{1}, \bar{3}1)$ | $R(1, -1)\#R(-1, 1)$ | $(-2 \ [5] \ -2)$ | 9 | \mathcal{A}_9 |
| Y49 | Y53 | $P_2(2\bar{1}, 32)$ | $R(-1, -1, 1, 1, 1, 1, -1, -1, -1)$ | $([2] \ -3 \ 3 \ -1)$ | 9 | \mathcal{A}_7 |
| Y50 | Y55 | $P_2(2\bar{1}, 3\bar{2})$ | $R(1, -1, 1, 1, -1, -1, 1, -1)$ | $([0] \ 0 \ 4 \ -4 \ 1)$ | 9 | \mathcal{A}_8 |
| Y51 | Y54 | $P_2(2\bar{1}, \bar{3}2)$ | $R(-1, 1, 1, -1, 1, -1, -1, 1)$ | $(-2 \ [5] \ -2)$ | 9 | \mathcal{A}_9 |
| Y52 | Y47 | $P_2(\bar{2}1, 31)$ | $R(-1, 1)\#R(-1, 1)$ | $(1 \ -4 \ 4 \ 0 \ [0])$ | 9 | $\mathcal{A}_8!$ |
| Y53 | Y49 | $P_2(\bar{2}1, 32)$ | $R(-1, -1, -1, 1, 1, 1, -1, -1)$ | $(-1 \ 3 \ -3 \ [2])$ | 9 | $\mathcal{A}_7!$ |
| Y54 | Y51 | $P_2(\bar{2}1, 3\bar{2})$ | $R(1, -1, -1, 1, -1, 1, 1, -1)$ | $(-2 \ [5] \ -2)$ | 9 | \mathcal{A}_9 |
| Y55 | Y50 | $P_2(\bar{2}1, \bar{3}2)$ | $R(-1, 1, -1, -1, 1, 1, -1, 1)$ | $(1 \ -4 \ 4 \ 0 \ [0])$ | 9 | $\mathcal{A}_8!$ |
| Y56 | Y58 | $P_3(3, \bar{1}4, \bar{2})$ | $R(1, 1, -1, 1, -1, -1)$ | $(2 \ [-3] \ 2)$ | 7 | \mathcal{A}_5 |
| Y57 | a | $P_3(3, \bar{1}\bar{4}, 2)$ | $R(1, -1, -1, -1, -1, 1)$ | $(-1 \ 2 \ [-1] \ 2 \ -1)$ | 7 | |
| Y58 | Y56 | $P_3(\bar{3}, \bar{1}4, 2)$ | $R(-1, -1, 1, -1, 1, 1)$ | $(2 \ [-3] \ 2)$ | 7 | \mathcal{A}_5 |
| Y59 | Y66 | $P_4(31, 4, 2)$ | $R(-1, -1, 1, 1, -1, 1, 1, 1)$ | $(1 \ -3 \ 3 \ -1 \ [1])$ | 9 | |
| Y60 | Y64 | $P_4(31, 4, \bar{2})$ | $R(1, -1, -1, 1, 1, 1, -1, 1)$ | $(-1 \ 3 \ -3 \ [2])$ | 9 | $\mathcal{A}_7!$ |
| Y61 | Y63 | $P_4(31, \bar{4}, \bar{2})$ | $R(1, 1, -1, 1, 1, -1, -1, 1)$ | $(1 \ -3 \ [4] \ -1)$ | 9 | $\mathcal{A}_{10}!$ |
| Y62 | Y65 | $P_4(3\bar{1}, 4, 2)$ | $R(-1, -1, 1, 1, -1, 1, 1, -1)$ | $(1 \ -3 \ [4] \ -1)$ | 9 | $\mathcal{A}_{10}!$ |
| Y63 | Y61 | $P_4(3\bar{1}, 4, \bar{2})$ | $R(1, -1, -1, 1, 1, 1, -1, -1)$ | $(-1 \ [4] \ -3 \ 1)$ | 9 | \mathcal{A}_{10} |
| Y64 | Y60 | $P_4(3\bar{1}, \bar{4}, \bar{2})$ | $R(1, 1, -1, 1, 1, -1, -1, -1)$ | $([2] \ -3 \ 3 \ -1)$ | 9 | \mathcal{A}_7 |
| Y65 | Y62 | $P_4(\bar{3}1, \bar{4}, \bar{2})$ | $R(1, 1, -1, -1, 1, -1, -1, 1)$ | $(-1 \ [4] \ -3 \ 1)$ | 9 | \mathcal{A}_{10} |
| Y66 | Y59 | $P_4(\bar{3}1, \bar{4}, 2)$ | $R(1, 1, -1, -1, 1, -1, -1, -1)$ | $([1] \ -1 \ 3 \ -3 \ 1)$ | 9 | |
| Y67 | Y82 | $P_3(23, 4, 1)$ | $R(1, -1, -1, -1, 1, 1, 1, 1, -1, -1)$ | $(1 \ [-2] \ 4 \ -3 \ 1)$ | 11 | $\mathcal{A}_{11}!$ |
| Y68 | Y81 | $P_3(23, 4, \bar{1})$ | $R(1, 1, -1, -1, 1, 1, 1, -1, -1, -1)$ | $([0] \ 3 \ -4 \ 3 \ -1)$ | 11 | |
| Y69 | Y80 | $P_3(23, \bar{4}, 1)$ | $R(1, -1, -1, -1, -1, 1, 1, 1, -1, -1)$ | $(-1 \ 3 \ [-3] \ 3 \ -1)$ | 11 | \mathcal{A}_{13} |
| Y70 | Y79 | $P_3(23, \bar{4}, \bar{1})$ | $R(1, 1, -1, -1, -1, 1, 1, -1, -1, -1)$ | $(1 \ [-2] \ 4 \ -3 \ 1)$ | 11 | $\mathcal{A}_{11}!$ |
| Y71 | Y78 | $P_3(2\bar{3}, 4, 1)$ | $R(-1, -1, 1, -1, 1, 1, -1, 1, 1, -1)$ | $(2 \ [-4] \ 4 \ -1)$ | 11 | \mathcal{A}_{12} |
| Y72 | Y77 | $P_3(2\bar{3}, 4, \bar{1})$ | $R(-1, 1, 1, -1, 1, 1, -1, -1, 1, -1)$ | $([-1] \ 5 \ -4 \ 1)$ | 11 | |
| Y73 | Y76 | $P_3(2\bar{3}, \bar{4}, 1)$ | $R(-1, -1, 1, -1, -1, 1, -1, 1, 1, -1)$ | $(-2 \ 5 \ [-3] \ 1)$ | 11 | |
| Y74 | Y75 | $P_3(2\bar{3}, \bar{4}, \bar{1})$ | $R(-1, 1, 1, -1, -1, 1, -1, -1, 1, -1)$ | $(2 \ [-4] \ 4 \ -1)$ | 11 | \mathcal{A}_{12} |
| Y75 | Y74 | $P_3(\bar{2}3, 4, 1)$ | $R(1, -1, -1, 1, 1, -1, 1, 1, -1, 1)$ | $(-1 \ 4 \ [-4] \ 2)$ | 11 | $\mathcal{A}_{12}!$ |
| Y76 | Y73 | $P_3(\bar{2}3, 4, \bar{1})$ | $R(1, 1, -1, 1, 1, -1, 1, -1, -1, 1)$ | $(1 \ [-3] \ 5 \ -2)$ | 11 | |
| Y77 | Y72 | $P_3(\bar{2}3, \bar{4}, 1)$ | $R(1, -1, -1, 1, -1, -1, 1, 1, -1, 1)$ | $(1 \ -4 \ 5 \ [-1])$ | 11 | |
| Y78 | Y71 | $P_3(\bar{2}3, \bar{4}, \bar{1})$ | $R(1, 1, -1, 1, -1, -1, 1, -1, -1, 1)$ | $(-1 \ 4 \ [-4] \ 2)$ | 11 | $\mathcal{A}_{12}!$ |
| Y79 | Y70 | $P_3(2\bar{3}, 4, 1)$ | $R(-1, -1, 1, 1, 1, -1, -1, 1, 1, 1)$ | $(1 \ -3 \ 4 \ [-2] \ 1)$ | 11 | \mathcal{A}_{11} |
| Y80 | Y69 | $P_3(2\bar{3}, 4, \bar{1})$ | $R(-1, 1, 1, 1, 1, -1, -1, -1, 1, 1)$ | $(-1 \ 3 \ [-3] \ 3 \ -1)$ | 11 | \mathcal{A}_{13} |
| Y81 | Y68 | $P_3(2\bar{3}, \bar{4}, 1)$ | $R(-1, -1, 1, 1, -1, -1, -1, 1, 1, 1)$ | $(-1 \ 3 \ -4 \ 3 \ [0])$ | 11 | |
| Y82 | Y67 | $P_3(2\bar{3}, \bar{4}, \bar{1})$ | $R(-1, 1, 1, 1, -1, -1, -1, -1, 1, 1)$ | $(1 \ -3 \ 4 \ [-2] \ 1)$ | 11 | \mathcal{A}_{11} |

Table 3: Ribbon 2-knots with four crossings (cont'd).

| Name | C | Presentation | Type | $\Delta(t)$ | Det | Set |
|------|------|-----------------------------|--|----------------------|-----|---------------------|
| Y83 | Y90 | $P_3(43, 1, 2)$ | $R(1, 1, 1, 1, -1, -1, -1, 1)$ | $(1 - 2 [3] - 2 1)$ | 9 | \mathcal{A}_6 |
| Y84 | Y89 | $P_3(43, 1, 2)$ | $R(1, -1, 1, 1, -1, 1, -1, -1)$ | $(3] - 4 2)$ | 9 | |
| Y85 | Y88 | $P_3(43, \bar{1}, 2)$ | $R(1, 1, 1, -1, -1, -1, -1, 1)$ | $(-1 [3] - 2 2 - 1)$ | 9 | |
| Y86 | Y87 | $P_3(43, \bar{1}, 2)$ | $R(1, -1, 1, -1, -1, 1, -1, -1)$ | $(1] - 2 4 - 2)$ | 9 | |
| Y87 | Y86 | $P_3(4\bar{3}, 1, 2)$ | $R(-1, 1, -1, 1, 1, -1, 1, 1)$ | $(-2 4 - 2 [1])$ | 9 | |
| Y88 | Y85 | $P_3(4\bar{3}, 1, 2)$ | $R(-1, -1, -1, 1, 1, 1, 1, -1)$ | $(-1 2 - 2 [3] - 1)$ | 9 | |
| Y89 | Y84 | $P_3(4\bar{3}, \bar{1}, 2)$ | $R(-1, 1, -1, -1, 1, -1, 1, 1)$ | $(2 - 4 [3])$ | 9 | |
| Y90 | Y83 | $P_3(4\bar{3}, \bar{1}, 2)$ | $R(-1, -1, -1, -1, 1, 1, 1, -1)$ | $(1 - 2 [3] - 2 1)$ | 9 | \mathcal{A}_6 |
| Y91 | Y106 | $P_5(5, 2, 3, 4)$ | $R(-1, -1, 1, -1, -1, 1, 1, -1, 1, 1, 1, -1, 1)$ | $(-1 4 - 5 [3])$ | 13 | \mathcal{A}_{14} |
| Y92 | Y105 | $P_5(5, 2, 3, 4)$ | $R(-1, -1, 1, 1, -1, 1, 1, -1, -1, -1, 1, 1)$ | $(1 - 4 [6] - 2)$ | 13 | |
| Y93 | Y104 | $P_5(5, 2, 3, 4)$ | $R(-1, 1, 1, -1, -1, -1, 1, 1, 1, -1, -1, 1)$ | $(1 - 3 [5] - 3 1)$ | 13 | \mathcal{A}_{15} |
| Y94 | Y103 | $P_5(5, 2, 3, 4)$ | $R(-1, 1, 1, 1, -1, -1, 1, 1, 1, -1, -1, 1)$ | $(-1 [4] - 4 3 - 1)$ | 13 | \mathcal{A}_{16} |
| Y95 | Y102 | $P_5(5, \bar{2}, 3, 4)$ | $R(1, -1, -1, -1, 1, 1, 1, -1, -1, 1, 1, 1)$ | $(1 - 3 [5] - 3 1)$ | 13 | \mathcal{A}_{15} |
| Y96 | Y101 | $P_5(5, \bar{2}, 3, 4)$ | $R(1, -1, -1, 1, 1, 1, 1, -1, -1, -1, 1, 1)$ | $(-1 [4] - 4 3 - 1)$ | 13 | \mathcal{A}_{16} |
| Y97 | Y100 | $P_5(5, \bar{2}, 3, 4)$ | $R(1, 1, -1, -1, 1, -1, 1, 1, -1, 1, 1, -1)$ | $(3] - 5 4 - 1)$ | 13 | $\mathcal{A}_{14}!$ |
| Y98 | Y99 | $P_5(5, \bar{2}, 3, 4)$ | $R(1, 1, -1, 1, 1, -1, 1, 1, -1, -1, 1, -1)$ | $(1] - 2 5 - 4 1)$ | 13 | |
| Y99 | Y98 | $P_5(5, 2, 3, 4)$ | $R(-1, -1, 1, -1, -1, 1, -1, -1, 1, 1, -1, 1)$ | $(1 - 4 5 - 2 [1])$ | 13 | |
| Y100 | Y97 | $P_5(5, 2, 3, 4)$ | $R(-1, -1, 1, 1, -1, 1, -1, -1, -1, -1, 1, 1)$ | $(-1 4 - 5 [3])$ | 13 | \mathcal{A}_{14} |
| Y101 | Y96 | $P_5(5, 2, 3, 4)$ | $R(-1, 1, 1, -1, -1, -1, -1, 1, 1, -1, -1, 1)$ | $(-1 3 - 4 [4] - 1)$ | 13 | $\mathcal{A}_{16}!$ |
| Y102 | Y95 | $P_5(5, 2, 3, 4)$ | $R(-1, 1, 1, 1, -1, -1, -1, 1, 1, -1, -1, 1)$ | $(1 - 3 [5] - 3 1)$ | 13 | \mathcal{A}_{15} |
| Y103 | Y94 | $P_5(5, \bar{2}, 3, 4)$ | $R(1, -1, -1, -1, 1, 1, -1, -1, -1, 1, 1, 1)$ | $(-1 3 - 4 [4] - 1)$ | 13 | $\mathcal{A}_{16}!$ |
| Y104 | Y93 | $P_5(5, \bar{2}, 3, 4)$ | $R(1, -1, -1, 1, 1, 1, -1, -1, -1, -1, 1, 1)$ | $(1 - 3 [5] - 3 1)$ | 13 | \mathcal{A}_{15} |
| Y105 | Y92 | $P_5(5, \bar{2}, 3, 4)$ | $R(1, 1, -1, -1, 1, -1, -1, -1, -1, -1, 1, -1)$ | $(-2 [6] - 4 1)$ | 13 | |
| Y106 | Y91 | $P_5(5, \bar{2}, 3, 4)$ | $R(1, 1, -1, 1, 1, -1, -1, 1, -1, -1, 1, -1)$ | $(3] - 5 4 - 1)$ | 13 | $\mathcal{A}_{14}!$ |
| Y107 | Y111 | $P_6(3, 4, 5, 2)$ | $R(-1, -1, 1, -1, -1, 1, 1, 1, -1, -1, 1, -1, 1)$ | $(-1 4 - 6 4 [0])$ | 15 | |
| Y108 | Y110 | $P_6(3, 4, 5, 2)$ | $R(1, -1, -1, -1, 1, 1, -1, 1, -1, -1, 1, 1, 1)$ | $(1 - 4 6 [-3] 1)$ | 15 | |
| Y109 | a | $P_6(3, 4, 5, 2)$ | $R(1, 1, -1, -1, 1, -1, -1, 1, 1, -1, 1, -1, 1)$ | $(-1 4 [-5] 4 - 1)$ | 15 | \mathcal{A}_{17} |
| Y110 | Y108 | $P_6(3, \bar{4}, 5, 2)$ | $R(-1, 1, 1, 1, -1, -1, -1, 1, -1, -1, 1, -1, -1)$ | $(1 [-3] 6 - 4 1)$ | 15 | |
| Y111 | Y107 | $P_6(3, \bar{4}, 5, 2)$ | $R(1, 1, -1, 1, 1, -1, -1, -1, 1, -1, -1, 1, -1)$ | $(0] 4 - 6 4 - 1)$ | 15 | |
| Y112 | a | $P_6(3, \bar{4}, 5, 2)$ | $R(1, -1, -1, 1, 1, -1, -1, 1, -1, -1, -1, 1, 1)$ | $(-1 4 [-5] 4 - 1)$ | 15 | \mathcal{A}_{17} |

5 Classification of the knots

The ribbon 2-knots in the sets \mathcal{A}_i , $i = 1, 2, \dots, 13$, have been classified in [6] except for the pair Y43 and Y46 in \mathcal{A}_6 , which have isomorphic knot group; see Sect. 7 in [6], where $Y43 = R_{8,6}^8$ and $Y46 = R_{8,1}^8$. In this section we classify the ribbon 2-knots in each of the sets \mathcal{A}_i , $i = 14, 15, 16, 17$.

5.1 Classification of the knots in \mathcal{A}_{14}

The set \mathcal{A}_{14} consists of the two knots Y91 and Y100, which share the same Alexander polynomial $-t^{-3} + 4t^{-2} - 5t^{-1} + 3$. Since they have different trace sets as shown in Table 4, we obtain $Y91 \not\approx Y100$.

Table 4: Trace sets of the knots in \mathcal{A}_{14} , \mathcal{A}_{16} , and \mathcal{A}_{17} .

| Set | Knot | Trace set |
|--------------------|------|---|
| \mathcal{A}_{14} | Y91 | $\{0, 0, 0, 0, 0, 0, (\delta + \epsilon\sqrt{5})/2 \mid \delta, \epsilon = \pm 1\}$ |
| | Y100 | $\left\{0, 0, 0, 0, 0, 0, \delta\sqrt{5(3 + \epsilon\sqrt{3})}/6 \mid \delta, \epsilon = \pm 1\right\}$ |
| \mathcal{A}_{16} | Y94 | $\{0, 0, 0, 0, 0, 0\}$ |
| | Y96 | $\{0, 0, 0, 0, 0, 0, \pm\alpha_1, \pm\alpha_2, \pm\alpha_3\}$ |
| \mathcal{A}_{17} | Y109 | $\left\{\begin{array}{l} \mathbb{C} - \{\pm\sqrt{3}\}, \pm\sqrt{2}, 0, 0, 0, 0, 0, 0, 0, \\ \mathbb{C} - \{\pm\sqrt{5}\}, \mathbb{C} - \{\pm\sqrt{5}\}, \pm 1, \\ (\delta + \epsilon\sqrt{13})/2, (\delta + \epsilon\sqrt{13})/2 \ (\delta, \epsilon = \pm 1), \\ \pm\beta_1, \pm\beta_2, \pm\beta_3, \pm\beta_4 \end{array}\right\}$ |
| | Y112 | $\left\{\begin{array}{l} \mathbb{C} - \{\pm\sqrt{3}\}, \pm\sqrt{2}, 0, 0, 0, 0, 0, 0, 0, \\ \gamma_1, \gamma_2, \gamma_3, \gamma_4 \end{array}\right\}$ |

- The numbers α_k , $k = 1, 2, 3$, are the roots of the cubic equation $1 - x - 2x^2 + x^3 = 0$ with $-1 < \alpha_1 < 0 < \alpha_2 < 1, 2 < \alpha_3 < 3$.
- The complex numbers β_k , $k = 1, 2, 3, 4$, are the roots of the quartic equation $5 - 2x - 4x^2 + x^3 + x^4 = 0$; $\beta_1, \beta_2 \doteq 1.25 \pm 0.27i$, $\beta_3, \beta_4 \doteq -1.75 \pm 0.17i$.
- The complex numbers γ_k , $k = 1, 2, 3, 4$, are the roots of the quartic equation $5 - 4x^2 + x^4 = 0$; $\gamma_k \doteq \pm 1.46 \pm 0.34i$.

5.2 Classification of the knots in \mathcal{A}_{15}

The set \mathcal{A}_{15} consists of the four knots Y93, Y95, Y102(= Y95!), and Y104(= Y93!), which share the same Alexander polynomial $t^{-2} - 3t^{-1} + 5 - 3t + t^2$. Table 5 lists the trace sets of the irreducible representations to $SL(2, \mathbb{C})$ of the knot groups of Y93 and Y95, and the associated twisted Alexander polynomials, which show these four knots are mutually non-isotopic. In fact, since the twisted Alexander polynomials are not reciprocal, the knots Y93 and Y95 are not positive-amhicheiral.

Table 5: Twisted Alexander polynomials of Y93 and Y95 in \mathcal{A}_{15} .

| Set | Knot | $(s + s^{-1}, u)$ | Twisted Alexander polynomial |
|--------------------|------|--|---|
| \mathcal{A}_{15} | Y93 | $\left(\frac{\epsilon}{\sqrt{2}}, \frac{3}{2}\right)$ ($\epsilon = \pm 1$) | $1 - \epsilon\sqrt{2}t + \frac{5}{2}t^2 - \epsilon\frac{3}{\sqrt{2}}t^3 + \frac{5}{2}t^4 - \epsilon\sqrt{2}t^5 + t^6$ |
| | | $(0, \alpha_1)$ | $1 + \beta_1t^2 + \gamma_2t^4 + t^6$ |
| | | $(0, \alpha_2)$ | $1 + \beta_5t^2 + \gamma_1t^4 + t^6$ |
| | | $(0, \alpha_3)$ | $1 + \beta_4t^2 + \gamma_1t^4 + t^6$ |
| | | $(0, \alpha_4)$ | $1 + \beta_2t^2 + \gamma_3t^4 + t^6$ |
| | | $(0, \alpha_5)$ | $1 + \beta_3t^2 + \gamma_2t^4 + t^6$ |
| | Y95 | $(0, \alpha_6)$ | $1 + \beta_6t^2 + \gamma_3t^4 + t^6$ |
| | | $(0, \alpha_1)$ | $1 + \beta_1t^2 + \beta_3t^4 + t^6$ |
| | | $(0, \alpha_2)$ | $1 + \beta_2t^2 + \beta_1t^4 + t^6$ |
| | | $(0, \alpha_3)$ | $1 + \beta_5t^2 + \beta_4t^4 + t^6$ |
| | | $(0, \alpha_4)$ | $1 + \beta_6t^2 + \beta_2t^4 + t^6$ |
| | | $(0, \alpha_5)$ | $1 + \beta_6t^2 + \beta_4t^4 + t^6$ |
| | | $(0, \alpha_6)$ | $1 + \beta_5t^2 + \beta_3t^4 + t^6$ |

- The numbers α_k , $k = 1, \dots, 6$, are the roots of the 6th order equation $13 - 91x + 182x^2 - 156x^3 + 65x^4 - 13x^5 + x^6 = 0$ with $0 < \alpha_1 < 0.5 < \alpha_2 < 1 < \alpha_3 < 2 < \alpha_4 < 3 < \alpha_5 < 3.5 < \alpha_6 < 4$.
- The numbers β_k , $k = 1, \dots, 6$, are the roots of the 6th order equation $-1 - 81x + 201x^2 - 178x^3 + 73x^4 - 14x^5 + x^6 = 0$ with $-1 < \beta_1 < 0 < \beta_2 < 1$, $2 < \beta_3 < 2.4 < \beta_4 < 2.8 < \beta_5 < 3$, $5 < \beta_6 < 6$.
- The numbers γ_k , $k = 1, 2, 3$, are the roots of the cubic equation $-5 + 12x - 7x^2 + x^3 = 0$ with $0 < \gamma_1 < 1 < \gamma_2 < 2$, $4 < \gamma_3 < 5$.

5.3 Classification of the knots in \mathcal{A}_{16}

The set \mathcal{A}_{16} consists of the two knots Y94 and Y96, which share the same Alexander polynomial $-t^{-1} + 4 - 4t + 3t^2 - t^3$. Since they have different trace sets as shown in Table 4, we obtain $Y94 \not\approx Y96$.

5.4 Classification of the knots in \mathcal{A}_{17}

The set \mathcal{A}_{17} consists of the two knots Y109 and Y112, which share the same Alexander polynomial $-t^{-2} + 4t^{-1} - 5 + 4t - t^2$. Since they have different trace sets as shown in Table 4, we obtain $Y109 \not\approx Y112$.

Remark 6. According to Toshio Sumi [9], we can also distinguish the knots Y109 and Y112 in the following ways:

- They have distinct twisted Alexander polynomials associated to the nonabelian representations to $SL(2, 2)$ as listed in Table 6.
- They have distinct numbers of the irreducible representations to $SL(2, 7)$.

Table 6: Twisted Alexander polynomials of the knots in \mathcal{A}_{17} .

| Set | Knot | $\rho : \pi K \rightarrow \mathrm{SL}(2, 2)$ | $\Delta_{K, \rho}$ |
|--------------------|------|--|-----------------------|
| \mathcal{A}_{17} | Y109 | $x \mapsto \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, y \mapsto \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}$ | $1 + t^6$ |
| | Y112 | $x \mapsto \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, y \mapsto \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}$ | $1 + t^2 + t^4 + t^6$ |

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