# Examples of third noise problems for action evolutions with infinite past

Yu Ito (Kyoto Sangyo University) Toru Sera (Kyoto University) Kouji Yano (Kyoto University)

## 1 Introduction

An action evolution is a pair (X, N) of processes  $X = (X_k)_{k \in \mathbb{Z}}$  and  $N = (N_k)_{k \in \mathbb{Z}}$  defined on a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$  satisfying the stochastic recursive equation

$$X_k = N_k X_{k-1}$$
 P-a.s. for  $k \in \mathbb{Z}$ , (1.1)

where the observation  $X = (X_k)_{k \in \mathbb{Z}}$  takes values in a measurable space V which evolves at each time being acted by the driving process  $N = (N_k)_{k \in \mathbb{Z}}$  which is an iid random mappings of V into itself. Here  $N_k X_{k-1}$  means the evaluation of a random mapping  $N_k$  at  $X_{k-1}$ ; we always write fv simply for the evaluation f(v). We may call X a two-sided random orbit of the random dynamical system generated by the iid random mappings N.

Let us give a precise definition. Let  $\Sigma$  be a measurable space consisting of mappings from V to itself and let  $\mathcal{P}(\Sigma)$  denote the set of probability measures on  $\Sigma$ . For  $\mu \in \mathcal{P}(\Sigma)$ , we call (X, N) a  $\mu$ -evolution if it satisfies (1.1) and  $N_k$  at each time k has common law  $\mu$  and is independent of the past  $\mathcal{F}_{k-1}^{X,N}$  defined as

$$\mathcal{F}_{k-1}^{X,N} := \sigma(X_j, N_j : j \le k - 1). \tag{1.2}$$

It is obvious that (X, N) is a  $\mu$ -evolution if and only if the Markov property

$$\mathbb{P}\left((X_k, N_k) \in \cdot \mid \mathcal{F}_{k-1}^{X,N}\right) = Q\left((X_{k-1}, N_{k-1}); \cdot\right) \quad \text{a.s. for } k \in \mathbb{Z}$$
(1.3)

holds with the joint transition probability being given as

$$Q((x,g);\cdot) = \mu\{f \in \Sigma : (fx,f) \in \cdot\}.$$
(1.4)

Consider a  $\mu$ -evolution (X, N). Since for j < k we know that  $\sigma(N_k, N_{k-1}, \ldots, N_{j+1})$  is independent of  $\mathcal{F}_j^X := \sigma(X_j, X_{j-1}, \ldots)$ , the driving noise  $\mathcal{F}_k^N := \sigma(N_k, N_{k-1}, \ldots)$  is independent of the remote past noise  $\mathcal{F}_{-\infty}^X := \bigcap_j \mathcal{F}_j^X$ . We sometimes encounter a third noise, which we define as a sequence of random variables  $(U_k)_{k \in \mathbb{Z}}$  such that

$$\mathcal{F}_k^X \subset \mathcal{F}_k^N \vee \mathcal{F}_{-\infty}^X \vee \sigma(U_k)$$
 a.s. and  $\sigma(U_k) \subset \mathcal{F}_k^{X,N}$  a.s. for  $k \in \mathbb{Z}$  (1.5)

holds with the three  $\sigma$ -fields  $\mathcal{F}_k^N$ ,  $\mathcal{F}_{-\infty}^X$  and  $\sigma(U_k)$  being independent. Here, for  $\sigma$ -fields  $\mathcal{F}_1, \mathcal{F}_2, \ldots$  we always write  $\mathcal{F}_1 \vee \mathcal{F}_2 \vee \cdots$  for  $\sigma(\mathcal{F}_1 \cup \mathcal{F}_2 \cup \cdots)$ . In addition, we can sometimes find a reduced driving noise, which we define as a sequence of  $\sigma$ -fields  $(\mathcal{G}_k^N)_{k \in \mathbb{Z}}$  such that

$$\mathcal{F}_k^X = \mathcal{G}_k^N \vee \mathcal{F}_{-\infty}^X \vee \sigma(U_k)$$
 a.s. and  $\mathcal{G}_k^N \subset \mathcal{F}_k^N$  a.s. for  $k \in \mathbb{Z}$  (1.6)

holds. The former identity of (1.6) will be called the resolution of the observation.

Iterating the equation (1.1), we have  $X_k = N_{k,j}X_j$  with

$$N_{k,j} := N_k N_{k-1} \cdots N_{j+1} \tag{1.7}$$

for j < k, and thus we may expect in general that

$$\mathcal{F}_k^X \subset \bigcap_{j < k} \left( \mathcal{F}_k^N \vee \mathcal{F}_j^X \right) \stackrel{?}{\subset} \mathcal{F}_k^N \vee \left( \bigcap_{j < k} \mathcal{F}_j^X \right) = \mathcal{F}_k^N \vee \mathcal{F}_{-\infty}^X. \tag{1.8}$$

This inclusion  $\stackrel{?}{\subset}$ , however, is false in general, or in other words, there may exist a non-trivial third noise; see [6, (1) of Remark 1.4] for the famous errors by Kolmogorov and Wiener. See also [2, Section 2.5] for related discussions.

In many results, the third noise is always a random variable with a uniform law on a certain set which is not given a priori. We discuss several examples with proofs, for better understanding the third noise problems.

#### 2 Random translations on a torus

Let us consider the one-dimensional torus  $\mathbb{T} = \mathbb{R}/\mathbb{Z} \simeq [0,1)$ , which is a compact commutative group with respect to addition in  $\mathbb{T}$ , or addition in  $\mathbb{R}$  mod 1. For a probability measure  $\mu$  on  $\mathbb{T}$ , we consider a  $\mu$ -evolution

$$X_k = N_k + X_{k-1} \quad \text{a.s. for } k \in \mathbb{Z}, \tag{2.1}$$

where X and N take values in  $\mathbb{T}$  and we understand  $N_k + X_{k-1}$  as addition in  $\mathbb{T}$ . Note that  $\mathcal{F}_k^N \subset \mathcal{F}_k^X$  for all  $k \in \mathbb{Z}$ , since  $N_k = X_k - X_{k-1}$  in  $\mathbb{T}$  (or in  $\mathbb{R}$  mod 1).

The resolution problem itself originates from Yor [9] who did a thorough study about this action evolution on a torus with inhomogeneous noise. His results were generalized to action evolutions on general compact groups by Akahori–Uenishi–Yano [1] and Hirayama–Yano [3]; see also [8] for a survey of this topic.

Let us write  $\mu\nu \in \mathcal{P}(\mathbb{T})$  for the convolution of  $\mu$  and  $\nu \in \mathcal{P}(\mathbb{T})$ :

$$(\mu\nu)(A) = \iint_{\mathbb{T}\times\mathbb{T}} 1_A(x+y)\mu(\mathrm{d}x)\nu(\mathrm{d}y). \tag{2.2}$$

We equip  $\mathcal{P}(\mathbb{T})$  with the topology of weak convergence;  $\mu_n \to \mu$  if and only if  $\int \varphi d\mu_n \to \int \varphi d\mu$  for all continuous function  $\varphi$  on  $\mathbb{T}$ . We write  $\omega_G$  for the normalized Haar measure on G if G is a compact group. We write  $\omega_V$  for the uniform law on V if V is a finite set. There is no confusion for finite groups.

Let us present some examples of Yor [9].

**Example 2.1 (deterministic translation).** Consider a  $\mu$ -evolution (X, N) with  $\mu = \delta_a$  for  $a \in \mathbb{T}$ :

$$X_k = a + X_{k-1}$$
 a.s. for  $k \in \mathbb{Z}$ . (2.3)

Then the driving noise is trivial, i.e.,  $\mathcal{F}_k^N = \{\emptyset, \Omega\}$  a.s. for  $k \in \mathbb{Z}$ , and we have

$$\mathcal{F}_k^X = \mathcal{F}_{-\infty}^X$$
 a.s. for  $k \in \mathbb{Z}$ , (2.4)

which gives the resolution of the observation and shows no third noise. In fact, since  $X_k - ka = X_{k-1} - (k-1)a$  a.s., we have  $X_k = X_0 + ka$  a.s. for  $k \in \mathbb{Z}$ , which shows that  $\mathcal{F}_k^X = \mathcal{F}_{-\infty}^X = \sigma(X_0)$  a.s.

**Example 2.2 (lazy irrational translation).** Consider a  $\mu$ -evolution (X, N) with  $\mu = \omega_{\{0,a\}}$ . We call it a *lazy translation*, because it sometimes stays  $(X_k = X_{k-1})$  or translates  $(X_k = a + X_{k-1})$  according as  $N_k = 0$  or a. Suppose  $a \notin \mathbb{Q}$ . It then holds that the remote past noise is trivial, i.e.,  $\mathcal{F}_{-\infty}^X = \{\emptyset, \Omega\}$  a.s. for  $k \in \mathbb{Z}$ , and that

$$\mathcal{F}_k^X = \mathcal{F}_k^N \vee \sigma(X_k)$$
 a.s. for  $k \in \mathbb{Z}$ , (2.5)

where, for each  $k \in \mathbb{Z}$ , the  $X_k$  is independent of  $\mathcal{F}_k^N$  and has uniform law on  $\mathbb{T}$ ; this gives the resolution of the observation and shows that  $(X_k)_{k \in \mathbb{Z}}$  is a third noise.

Let us prove this claim. Set  $N_{k,j} = N_k + N_{k-1} + \cdots + N_{j+1}$  for j < k. Since  $X_j = X_k - N_{k,j}$  and  $N_j = X_j - X_{j-1}$  for j < k, the identity (2.5) is obvious. Let us prove the independence. We utilize the characters:  $\chi_m(z) = \mathrm{e}^{2\pi i m z}$  for  $z \in \mathbb{T}$  and  $m \in \mathbb{Z}$ . By the irrationality of a, we have  $\left|\frac{1+\chi_m(a)}{2}\right| < 1$  for all  $m \neq 0$ , and hence we have

$$\int_{\mathbb{T}} \chi_m(z) \mu^n(\mathrm{d}z) = \left(\int_{\mathbb{T}} \chi_m(z) \mu(\mathrm{d}z)\right)^n = \left(\frac{1 + \chi_m(a)}{2}\right)^n \xrightarrow[n \to \infty]{} 0 \quad \text{for any } m \neq 0.$$
 (2.6)

This shows  $\mu^n \to \omega_{\mathbb{T}}$  by the theory of Fourier series. For  $B \in \mathcal{F}^X_{-\infty}$ , for any continuous function  $\varphi$  on  $\mathbb{T}$ , for k > j > l and for  $A \in \sigma(N_k, N_{k-1}, \ldots, N_{j+1})$ , we have

$$\mathbb{E}[1_A 1_B \varphi(X_k)] = \mathbb{E}[1_A 1_B \varphi(N_{k,j} + N_{j,l} + X_l)]$$
(2.7)

$$= \mathbb{E}\left[1_A 1_B \int_{\mathbb{T}} \varphi(N_{k,j} + z + X_l) \mu^{j-l}(\mathrm{d}z)\right]$$
 (2.8)

$$\underset{l \to -\infty}{\longrightarrow} \mathbb{E} \left[ 1_A 1_B \int_{\mathbb{T}} \varphi(z) \omega_{\mathbb{T}}(\mathrm{d}z) \right]$$
 (2.9)

$$= \mathbb{P}(A)\mathbb{P}(B) \int_{\mathbb{T}} \varphi(z)\omega_{\mathbb{T}}(\mathrm{d}z), \qquad (2.10)$$

since for any sequences  $\{x_n\}, \{x_n'\} \subset \mathbb{T}$  we have  $\delta_{x_n} \mu^{j+n} \delta_{x_n'} \to \omega_{\mathbb{T}}$  as  $n \to \infty$ . This shows that, for each  $k \in \mathbb{Z}$ , the  $X_k$  has uniform law on  $\mathbb{T}$  and that the three  $\sigma$ -fields  $\mathcal{F}_k^N$ ,  $\mathcal{F}_{-\infty}^X$  and  $\sigma(X_k)$  are independent. By the identity (2.5), we have  $\mathcal{F}_{-\infty}^X \subset \mathcal{F}_k^N \vee \sigma(X_k)$  a.s. Since the remote past noise  $\mathcal{F}_{-\infty}^X$  is independent of  $\mathcal{F}_k^N \vee \sigma(X_k)$ , we see that it is independent of itself, which shows its triviality. The proof is now complete.

**Example 2.3 (lazy rational translation).** Consider a  $\mu$ -evolution (X, N) with  $\mu = \omega_{\{0,a\}}$  for  $a = 1/3 \in \mathbb{T}$ . Set  $H = \{0, a, 2a\}$  and C = [0, a). Note that H is a subgroup of  $\mathbb{T}$  and C is isomorphic to the quotient set  $\mathbb{T}/H$ . Define a mapping  $\mathbb{T} \ni z \mapsto (z^H, z^C) \in H \times C$  so that  $z = z^H + z^C$ , or in other words, if z = (n + t)a for n = 0, 1, 2 and  $t \in [0, 1)$ , then

 $z^H = na$  and  $z^C = ta$ . Let (X, N) be a  $\mu$ -evolution. It then holds that there exists a C-valued random variable  $Z_C$  such that  $X_k^C = Z_C$  a.s. for  $k \in \mathbb{Z}$ . Moreover, we have the decomposition

$$X_j = -N_{k,j} + X_k^H + Z_C$$
 a.s. for  $j < k$  (2.11)

and the resolution of the observation

$$\mathcal{F}_k^X = \mathcal{F}_k^N \vee \mathcal{F}_{-\infty}^X \vee \sigma(X_k^H)$$
 a.s. for  $k \in \mathbb{Z}$ , (2.12)

where  $\mathcal{F}_{-\infty}^X = \sigma(Z_C)$  a.s. and, for each  $k \in \mathbb{Z}$ , the  $X_k^H$  is independent of  $\mathcal{F}_k^N \vee \mathcal{F}_{-\infty}^X$  and has uniform law on H; as a consequence  $(X_k^H)_{k \in \mathbb{Z}}$  is a third noise.

Let us prove this claim. Since  $X_k = N_k + X_{k-1}$  and  $N_k \in \{0, a\} \subset H$ , we have

$$X_k^H = N_k + X_{k-1}^H, \quad X_k^C = X_{k-1}^C \quad \text{a.s.},$$
 (2.13)

which shows existence of  $Z_C(=X_0^C)$  such that  $X_k^C=Z_C$  a.s. for  $k\in\mathbb{Z}$ . Identity (2.11) is now obvious. Since

$$\int_{\mathbb{T}} \chi_m(z) \mu^n(\mathrm{d}z) = \left(\frac{1 + \chi_m(a)}{2}\right)^n \underset{n \to \infty}{\longrightarrow} \begin{cases} 1 & (m \in 3\mathbb{Z}) \\ 0 & (m \notin 3\mathbb{Z}), \end{cases}$$
(2.14)

we obtain  $\mu^n \to \omega_H$  by the theory of Fourier series. For  $B \in \mathcal{F}_{-\infty}^X$ , for any continuous function  $\varphi$  on H, for l < j < k and for  $A \in \sigma(N_k, N_{k-1}, \dots, N_{j+1})$ , we have

$$\mathbb{E}[1_A 1_B \varphi(X_k^H)] = \mathbb{E}[1_A 1_B \varphi(N_{k,j} + N_{j,l} + X_l^H)] \xrightarrow[l \to -\infty]{} \mathbb{P}(A) \mathbb{P}(B) \int_H \varphi(z) \omega_H(\mathrm{d}z), \quad (2.15)$$

in the same way as the previous example. This shows that, for each  $k \in \mathbb{Z}$ , the  $X_k^H$  has uniform law on H and that the three  $\sigma$ -fields  $\mathcal{F}_k^N$ ,  $\mathcal{F}_{-\infty}^X$  and  $\sigma(X_k^H)$  are independent. By (2.11), we obtain

$$\mathcal{F}_k^X = \mathcal{F}_k^N \vee \sigma(Z_C) \vee \sigma(X_k^H)$$
 a.s. for  $k \in \mathbb{Z}$ . (2.16)

From this identity we obtain  $\mathcal{F}_{-\infty}^X \subset \sigma(Z_C) \vee (\mathcal{F}_k^N \vee \sigma(X_k^H))$  a.s. By the independence of  $\mathcal{F}_{-\infty}^X$  and  $\mathcal{F}_k^N \vee \sigma(X_k^H)$ , we can deduce that  $\mathcal{F}_{-\infty}^X \subset \sigma(Z_C)$  a.s. (see [2, Section 2.2]). We now obtain  $\mathcal{F}_{-\infty}^X = \sigma(Z_C)$  a.s. and thus the proof is complete.

Example 2.4 (lazy rational-irrational translation on a two-dimensional torus). Let us consider the two-dimensional torus  $\mathbb{T}^2 = \mathbb{T} \times \mathbb{T}$ , which is also a compact commutative group under componentwise addition. Consider a  $\mu$ -evolution with  $\mu = \omega_{\{(0,0),(a,b)\}}$  for a = 1/3 and  $b \notin \mathbb{Q}$ . Set  $H = \{(0,x), (a,x), (2a,x) : x \in \mathbb{T}\}$  and  $C = \{(ta,x) : t \in [0,1), x \in \mathbb{T}\} = [0,1/3) \times \mathbb{T}$ . Note that H is a subgroup of  $\mathbb{T}$  and C is isomorphic to the quotient set  $\mathbb{T}^2/H$ . We can then deduce the same resolution of the observation by the same argument as the previous example.

## 3 Finite-state action evolutions

For a finite set V and for the set  $\Sigma$  of mappings of V into itself, we may consider the action evolution

$$X_k = N_k X_{k-1}$$
 P-a.s. for  $k \in \mathbb{Z}$ , (3.1)

where X takes values in V and N does in  $\Sigma$ . As we have some difficulty in obtaining resolution of the observation, we would like to consider a multiparticle evolution. For  $m \in \mathbb{N}$ , we understand that any mapping  $f: V \to V$  operates  $\mathbf{x} = (x^1, \dots, x^m) \in V^m$  componentwise, i.e.,  $f\mathbf{x} = (fx^1, \dots, fx^m)$ . We call  $(\mathbb{X}, N)$  an m-particle  $\mu$ -evolution if it satisfies

$$X_k = N_k X_{k-1}$$
 P-a.s. for  $k \in \mathbb{Z}$ , (3.2)

or in other words

$$X_k^i = N_k X_{k-1}^i$$
 P-a.s. for  $k \in \mathbb{Z}$  and  $i = 1, \dots, m$ , (3.3)

where  $\mathbb{X} = (\mathbb{X}_k)_{k \in \mathbb{Z}}$  with  $\mathbb{X}_k = (X_k^1, \dots, X_k^m)$  takes values in  $V^m$  and  $N = (N_k)_{k \in \mathbb{Z}}$  takes values in  $\Sigma$  with  $N_k$  at each time k having common law  $\mu$  and being independent of  $\mathcal{F}_{k-1}^{\mathbb{X},N}$ .

Write  $S(\mu) = \{f : \mu\{f\} > 0\}$  for the support of  $\mu$  and write  $\langle S(\mu) \rangle = \bigcup_{n=1}^{\infty} S(\mu)^n$  for the semigroup generated by  $S(\mu)$ . For monoparticle action evolutions, Yano [7] has proved that there is no third noise if and only if  $S(\mu)$  is sync, i.e., there exists  $g \in \langle S(\mu) \rangle$  such that #g(V) = 1. Recently Ito–Sera–Yano [4] has obtained the resolution of the observation for  $m_{\mu}$ -particle action evolution where  $m_{\mu} = \min\{\#g(V) : g \in \langle S(\mu) \rangle\}$ .

For  $\mu, \nu \in \mathcal{P}(\Sigma)$  and for  $\lambda \in \mathcal{P}(V)$ , we define

$$(\mu\nu)(A) = \int_{\Sigma} \int_{\Sigma} 1_A(fg)\mu(\mathrm{d}f)\nu(\mathrm{d}g), \quad A \subset \Sigma, \tag{3.4}$$

$$(\mu\lambda)(B) = \int_{\Sigma} \int_{V} 1_{B}(fx)\mu(\mathrm{d}f)\lambda(\mathrm{d}x), \quad B \subset V.$$
 (3.5)

We sometimes write  $\mu f$  simply for  $\mu \delta_f$ , etc. Let us present an example of the main theorem of Ito–Sera–Yano [4].

**Example 3.1.** Let  $V = \{1, 2, 3, 4\}$ . We write  $[y^1, y^2, y^3, y^4]$  for the mapping f of V into itself such that  $fi = y^i$  for i = 1, 2, 3, 4. Consider the three mappings:

$$f = [2, 2, 4, 4], \quad g = [3, 3, 1, 1], \quad h = [1, 3, 3, 1].$$
 (3.6)

Consider  $\mu = \omega_{\{id,f,g,h\}}$ , where id denotes the identity mapping of V. It is obvious that  $S(\mu) = \{id, f, g, h\}$  and that  $m_{\mu} = 2$ .

(i) The unique minimal two-sided ideal K of  $\langle S(\mu) \rangle$ , which is called the *kernel* of  $\langle S(\mu) \rangle$ , admits the *Rees decomposition* given as

$$K = \langle \{f, g, h\} \rangle = LGR, \quad L = \{e, f\}, \quad G = \{e, g\}, \quad R = \{e, h\},$$
 (3.7)

where  $e := g^2 = [1, 1, 3, 3]$  and the product mapping  $L \times G \times R \ni (a, b, c) \mapsto abc \in K$  is bijective. We denote its inverse by  $K \ni k \mapsto (k^L, k^G, k^R) \in L \times G \times R$ .

(ii) The convolution product of  $\mu$  satisfies

$$\mu^n \to \eta^L \omega_G \eta^R, \quad \eta^L = \frac{2}{3} \delta_e + \frac{1}{3} \delta_f, \quad \eta^R = \frac{2}{3} \delta_e + \frac{1}{3} \delta_h.$$
 (3.8)

(iii) It is easy to see that the measure

$$\Lambda = \frac{1}{3}\delta_{(1,3)} + \frac{1}{3}\delta_{(3,1)} + \frac{1}{6}\delta_{(2,4)} + \frac{1}{6}\delta_{(4,2)}$$
(3.9)

is a unique  $\mu$ -invariant probability (i.e.,  $\mu\Lambda=\Lambda$ ) on  $V_{\times}^2=\{(x^1,x^2)\in V^2:x^1\neq x^2\}$ . Set

$$W_{\mu} = S(\Lambda) = \{(1,3), (3,1), (2,4), (4,2)\} \subset V_{\times}^{2}, \tag{3.10}$$

then we easily have the representations

$$W_{\mu} = LG(1,3) \text{ and } \Lambda = \eta^{L} \omega_{G}(1,3).$$
 (3.11)

We now obtain that the product mapping  $L \times G \ni (a, b) \mapsto ab(1, 3) \in W_{\mu}$  is bijective. We denote its inverse by  $W_{\mu} \ni \boldsymbol{x} \mapsto (\boldsymbol{x}^{L}, \boldsymbol{x}^{G}) \in L \times G$ .

(iv) Let us consider a stationary biparticle  $\mu$ -evolution ( $\mathbb{X}$ , N) such that  $\mathbb{X}$  has a common law  $\Lambda$ . Then we have the factorization

$$X_j = X_j^L(M_{k,j}^G)^{-1}U_k^G(1,3)$$
 a.s. for  $j < k$  (3.12)

with  $U_k^G = \mathbb{X}_k^G \stackrel{\mathrm{d}}{=} \omega_G$ ,  $M_j^G = \mathbb{X}_j^G (\mathbb{X}_{j-1}^G)^{-1}$  and  $M_{k,j}^G = M_k^G M_{k-1}^G \cdots M_{j+1}^G$ . Consequently, we obtain the resolution of the observation

$$\mathcal{F}_k^{\mathbb{X}} = \mathcal{G}_k^N \vee \sigma(U_k^G) \quad \text{a.s. with } \mathcal{G}_k^N = \sigma(\mathbb{X}_i^L, M_i^G : j \le k), \tag{3.13}$$

where  $\mathcal{F}_{-\infty}^X$  is trivial and the two  $\sigma$ -fields  $\mathcal{F}_k^N(\supset \mathcal{G}_k^N)$  and  $\sigma(U_k^G)$  are independent.

Let us prove these claims.

(i) Let us write  $S = \langle S(\mu) \rangle$ . Since  $g^2 = e^2 = e$  and ge = eg = g, the set  $G = \{e, g\}$  is a group with e the unit element. Noting that

$$ef = he = e, \quad f^2 = fe = f, \quad gf = hg = hf = g, \quad h^2 = eh = h,$$
 (3.14)

we have so that LGR is a two-sided ideal of S. For any  $k \in LGR$ , we have  $e \in SkS$  so that LGR is a minimal ideal. Uniqueness of a minimal ideal is a known fact (see, e.g., [5, Theorem 2.12]). The injectivity of the product mapping  $L \times G \times R \ni (a, b, c) \mapsto abc \in K$  is obvious because ef = he = e and G is a group.

(ii) From a known fact (see, e.g., [5, Theorem 2.2]), the set  $\mathcal{K}$  of subsequential limits of  $\{\mu^n\}$  is given either as  $[\mathcal{K} = \{\eta, \mu\eta\}]$  with  $\eta = \eta^L \eta^R$  and  $\mu \eta = \eta^L g \eta^R$ ] or as  $[\mathcal{K} = \{\eta\}]$  with

 $\eta = \eta^L \omega_G \eta^R$ ], where  $\eta^L = \eta\{k^L : k \in K\}$  and  $\eta^R = \eta\{k^R : k \in K\}$ . If  $\mathcal{K} = \{\eta, \mu\eta\}$  were the case, then it would follow that  $f = ff \in S(\mu)S(\eta) = S(\mu\eta) = LgR$ , which would contradict the fact that  $f^G = e$ . Hence we see that  $\mathcal{K} = \{\eta\}$ , which shows  $\mu^n \to \eta$ . Let  $\eta^L = p\delta_e + q\delta_f$  with  $p = 1 - q \in [0, 1]$ . Since  $\eta^R e = \delta_e$ , we have  $\mu\eta^L\omega_G = \eta^L\omega_G$ . We have

$$\mu \eta^L \omega_G = \frac{1}{4} \{ 2p\delta_e + (1+q)\delta_f + (1+q)\delta_g \} \, \omega_G = \frac{1}{4} \{ (2+p)\delta_e + (1+q)\delta_f \} \, \omega_G, \quad (3.15)$$

which shows that  $\eta^L = \frac{2}{3}\delta_e + \frac{1}{3}\delta_f$ . By the same way we obtain  $\eta^R = \frac{2}{3}\delta_e + \frac{1}{3}\delta_h$ .

- (iii) Since e(1,3) = (1,3) and g(1,3) = (3,1), the group G acts on the two-point set  $\{1,3\}$  as permutations. Noting that f(1,3) = (2,4) and f(3,1) = (4,2), we have obtained the injectivity of the product mapping  $L \times G \ni (a,b) \mapsto ab(1,3) \in W_{\mu}$ .
- (iv) Let  $k \in \mathbb{Z}$  be fixed. Since  $\mathbb{X}_k \in S(\Lambda) = W_{\mu}$ , we can decompose it as  $\mathbb{X}_k = \mathbb{X}_k^L \mathbb{X}_k^G(1,3)$ . Since  $\mathbb{X}_k \stackrel{\mathrm{d}}{=} \Lambda = \eta^L \omega_G(1,3)$ , we see that  $\mathbb{X}_k^L$  and  $\mathbb{X}_k^G$  are independent and  $\mathbb{X}_k^G \stackrel{\mathrm{d}}{=} \omega_G$ .

For j < k, since  $M_{k,j}^G = \mathbb{X}_k^G(\mathbb{X}_j^G)^{-1}$ , we have

$$X_{j} = X_{j}^{L}X_{j}^{G}(1,3) = X_{j}^{L}(M_{k,j}^{G})^{-1}X_{k}^{G}(1,3) \quad \text{a.s.},$$
(3.16)

which shows (3.12) and (3.13). We here omit the proof of the fact  $\mathcal{G}_k^N \subset \mathcal{F}_k^N$ ; see [4] for the details.

Let us prove the independence of the two  $\sigma$ -fields  $\mathcal{F}_k^N$  and  $\sigma(\mathbb{X}_k^G)$ . For j < k, let  $A \in \sigma(N_k, N_{k-1}, \ldots, N_{j+1})$  and let  $\varphi$  be a function on G. We now have

$$\mathbb{E}\left[1_A \varphi(\mathbb{X}_k^G)\right] = \mathbb{E}\left[1_A \varphi(M_{k,j}^G \mathbb{X}_j^G)\right] = \mathbb{P}(A) \int_G \varphi(a) \omega_G(\mathrm{d}a), \tag{3.17}$$

since  $\mathbb{X}_{j}^{G}$  is independent of  $\sigma(N_{k}, N_{k-1}, \dots, N_{j+1})$  and has uniform distribution on G. This shows the desired independence.

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