

TRANS-SASAKIAN MANIFOLD ADMITTING QUARTER-SYMMETRIC NON-METRIC CONNECTION

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ABSTRACT. In this paper we shall introduce a quarter-symmetric non-metric connection in a trans-Sasakian manifold and prove its existence. We shall discuss some properties of quarter-symmetric non-metric connection on trans-Sasakian manifold. Also we shall compare the quarter-symmetric non-metric connection with the Levi-Civita connection in trans-Sasakian manifold.

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1. INTRODUCTION

In 1985, J.A. Oubina introduced a new class of almost contact manifold namely trans-Sasakian manifold [6]. Many geometers in [1], [4], [8] have studied the structure of trans-Sasakian manifold and obtained many results on it. In 1975, Golab introduced quarter-symmetric metric connection in Riemannian manifold [3] and S. Mukhopadhyay et. al. studied some properties on quarter-symmetric metric connection on Riemannian manifold [5].

Let M be an almost contact metric manifold of dimension $n(= 2m + 1)$ with an almost contact metric structure (ϕ, ξ, η, g) where ϕ is $(1, 1)$ tensor field, ξ is contravariant vector field, η is a 1-form and g is a associated Riemannian metric such that,

$$\phi^2 = -I + \eta \otimes \xi, \quad (1)$$

$$\eta(\xi) = 1, \quad \phi\xi = 0, \quad \eta \circ \phi = 0, \quad (2)$$

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y), \quad (3)$$

$$g(X, \phi Y) = -g(\phi X, Y), \quad (4)$$

and

$$g(X, \xi) = \eta(X), \quad (5)$$

$\forall X, Y \in \chi(M)$, then M is called a *trans-Sasakian manifold of type* (α, β) provided,

$$(\nabla_X \phi)(Y) = \alpha\{g(X, Y)\xi - \eta(Y)X\} + \beta\{g(\phi X, Y)\xi - \eta(Y)\phi X\}, \quad (6)$$

holds, for smooth functions α and β on M [8].

On a trans-Sasakian manifold, it can be shown that [8],

$$\nabla_X \xi = -\alpha\phi X + \beta(X - \eta(X)\xi), \quad (7)$$

$$(\nabla_X \eta)Y = -\alpha g(\phi X, Y) + \beta g(\phi X, \phi Y), \quad (8)$$

$$F(X, Y) = -F(Y, X), \quad (9)$$

where $F(X, Y) = g(\phi X, Y)$, is fundamental 2-form.

Now we shall prove the following property:

Property 1. Let M be a trans-Sasakian manifold with the structure (ϕ, ξ, η, g) , then

$$(\nabla_X F)(\xi, Y) = (\nabla_X \eta)\phi Y, \quad (10)$$

$$(\nabla_X F)(\phi Y, \phi Z) = 0, \quad (11)$$

$$(\nabla_X F)(Y, \phi Z) = -\eta(Y)(\nabla_X \eta)(Z), \quad (12)$$

$$\begin{aligned} (\nabla_X F)(Y, Z) &= -\{\alpha\{g(X, Y)\eta(Z) - \eta(Y)g(X, Z)\} \\ &\quad + \beta\{g(\phi X, Y)\eta(Z) - \eta(Y)g(\phi X, Z)\}\}, \end{aligned} \quad (13)$$

$$(\nabla_X F)(\phi Y, Z) = -\eta(Z)(\nabla_X \eta)(Y), \quad (14)$$

$$\begin{aligned} (\nabla_X F)(Y, Z) + (\nabla_Y F)(Z, X) + (\nabla_Z F)(X, Y) \\ = 2\beta\{g(\phi X, Y)\eta(Z) + g(\phi Y, Z)\eta(X) + g(\phi Z, X)\eta(Y)\}. \end{aligned} \quad (15)$$

Proof. From the definition of $F(X, Y)$,

it is clear that $F(\xi, Y) = 0$.

$$\begin{aligned} \text{Here, } (\nabla_X F)(\xi, Y) &= \nabla_X F(\xi, Y) - F(\nabla_X \xi, Y) - F(\xi, \nabla_X Y), \\ &= -F(-\alpha\phi X + \beta(X - \eta(X)\xi), Y), \text{ using (7)} \\ &= -\{\alpha g(\phi X, \phi Y) + \beta g(\phi X, Y)\}. \end{aligned}$$

Replacing Y by ϕY in (8) we get,

$$\begin{aligned} (\nabla_X \eta)\phi Y &= -\alpha g(\phi X, \phi Y) + \beta g(\phi X, \phi^2 Y), \\ &= -\{\alpha g(\phi X, \phi Y) + \beta g(\phi X, Y)\}, \text{ using (1)}. \end{aligned}$$

It proves (10).

From (1), (2), (5) and (6) we get

$$(\nabla_X F)(\phi Y, \phi Z) = -\nabla_X g(Y, \phi Z) + \alpha \eta(Y)g(\phi X, \phi Z) - \beta \eta(Y)g(X, \phi Z) \\ + g(\nabla_X Y, \phi Z) + g(Y, \nabla_X(\phi Z)) - g(\eta(Y)\xi, \nabla_X(\phi Z)).$$

Again using (3) and (8) in above equation we find,

$$(\nabla_X F)(\phi Y, \phi Z) = 0.$$

Using (2) and (6), we can find

$$(\nabla_X F)(Y, \phi Z) = (\nabla_X g)(\phi X, \phi Y) - \alpha \eta(Y)g(X, \phi Z) - \beta \eta(Y)g(\phi X, \phi Z) \\ = -\eta(Y)(\nabla_X \eta)Z.$$

Using (3) and (6) we get

$$(\nabla_X F)(Y, Z) = -\{\alpha\{g(X, Y)\eta(Z) - \eta(Y)g(X, Z)\} \\ + \beta\{g(\phi X, Y)\eta(Z) - \eta(Y)g(\phi X, Z)\}\}.$$

Also replacing Y by ϕY in (13) it can be easily shown

$$(\nabla_X F)(\phi Y, Z) = -\eta(Z)(\nabla_X \eta)(Y).$$

Replacing X, Y and Z in cyclic order in (13) and then adding three equations we can show equation (15).

2. QUARTER-SYMMETRIC NON-METRIC CONNECTION ON TRANS-SASAKIAN MANIFOLD

Let M be a trans-sasakian manifold with Levi-Civita connection ∇ and $X, Y \in \chi(M)$. We define a linear connection D on M by

$$D_X Y = \nabla_X Y + \eta(Y)\phi(X) \tag{16}$$

where η is 1-form and ϕ is a tensor field of type $(1, 1)$. D is said to be quarter symmetric connection if \bar{T} , the torsion tensor with respect to the connection D , satisfies

$$\bar{T}(X, Y) = \eta(Y)\phi X - \eta(X)\phi Y. \tag{17}$$

D is said to be non-metric connection if $(Dg) \neq 0$. Using (16) we have

$$(D_X g)(Y, Z) = -\{\eta(Y)g(\phi X, Z) + \eta(Z)g(\phi X, Y)\}. \tag{18}$$

A linear connection D is said to be quarter-symmetric non-metric connection if it satisfies (16), (17) and (18).

3. EXISTENCE OF A QUARTER-SYMMETRIC NON-METRIC CONNECTION D IN A TRANS-SASAKIAN MANIFOLD

In this setion we shall show the existance of the quarter-symmetric non-metric connection D on a trans-Sasakian manifold M . Next we shall prove some theorems on quarter-symmetric non-metric connection on trans-Sasakian manifold.

Theorem 2. Let X, Y, Z be any vectors fields on a trans-Sasakian manifold M with an almost structure (ϕ, ξ, η, g) . Let us define a connection D by

$$\begin{aligned} 2g(D_X Y, Z) = & Xg(Y, Z) + Yg(Z, X) - Zg(X, Y) \\ & + g([X, Y], Z) - g([Y, Z], X) + g([Z, X], Y) \\ & + g(\eta(Y)\phi X - \eta(X)\phi Y, Z) + g(\eta(X)\phi Z \\ & - \eta(Z)\phi X, Y) + g(\eta(Y)\phi Z + \eta(Z)\phi Y, X). \end{aligned} \quad (19)$$

Then D is a quarter-symmetric non-metric connection on M .

Proof. It can be verified that $D : (X, Y) \rightarrow D_X Y$ satisfies the following equations:

$$D_X(Y + Z) = D_X Y + D_X Z, \quad (20)$$

$$D_{X+Y} Z = D_X Z + D_Y Z, \quad (21)$$

$$D_{fX} Y = f D_X Y, \quad (22)$$

$$D_X(fY) = f(D_X Y) + (Xf)Y, \quad (23)$$

for all $X, Y, Z \in \chi(M)$ and for all f , all differentiable function on M .

From (20), (21), (22) and (23) we can conclude that D is a linear connection on M . From (19) we have,

$$D_X Y - D_Y X - [X, Y] = \eta(Y)\phi X - \eta(X)\phi Y$$

or,

$$\bar{T}(X, Y) = \eta(Y)\phi X - \eta(X)\phi Y. \quad (24)$$

Again from (19) we get,

$$\begin{aligned} 2g(D_X Y, Z) + 2g(D_X Z, Y) \\ = 2Xg(Y, Z) + 2\eta(Y)g(\phi X, Z) + 2\eta(Z)g(\phi X, Y). \\ (D_X g)(Y, Z) = -\{\eta(Y)g(\phi X, Z) + \eta(Z)g(\phi X, Y)\}. \end{aligned} \quad (25)$$

This shows that D is a quarter-symmetric non-metric connection on M .

Theorem 3. Let D be a linear connection on a trans-Sasakian manifold M , given by

$$D_X Y = \nabla_X Y + H(X, Y), \quad (26)$$

where $H(X, Y)$ is a $(1, 2)$ tensor field and ∇ is Levi-Civita connection, satisfying (18). Then $H(X, Y) = \eta(Y)\phi(X)$.

Proof. Using (26) in the definition of torsion tensor, we get

$$\bar{T}(X, Y) = H(X, Y) - H(Y, X). \quad (27)$$

From (26), we have

$$g(H(X, Y), Z) + g(H(X, Z), Y) = -(D_X g)(Y, Z). \quad (28)$$

From (18), (26), (27) and (28) we have

$$\begin{aligned} & g(\bar{T}(X, Y), Z) + g(\bar{T}(Z, Y), X) + g(\bar{T}(Z, X), Y) \\ &= 2g(H(X, Y), Z) - (D_Z g)(X, Y) + (D_Y g)(X, Z) + (D_X g)(Y, Z). \end{aligned}$$

We get from above equation,

$$\begin{aligned} g(H(X, Y), Z) &= \frac{1}{2}[g(\bar{T}(X, Y), Z) + g(\bar{T}(Z, Y), X) \\ &\quad + g(\bar{T}(Z, X), Y)] + [\eta(Y)g(\phi X, Z) + \eta(X)g(\phi Y, Z)]. \end{aligned}$$

Thus, we get

$$\begin{aligned} H(X, Y) &= \frac{1}{2}[\bar{T}(X, Y) + \tilde{T}(X, Y) + \tilde{T}(Y, X)] \\ &\quad + [\eta(Y)\phi X + \eta(X)\phi Y], \end{aligned}$$

where \tilde{T} is a tensor field of type (1,2) defined by

$$g(\tilde{T}(X, Y), Z) = g(\bar{T}(Z, X), Y).$$

Thus $H(X, Y) = \eta(Y)\phi X$.

Hence $D_X Y = \nabla_X Y + \eta(Y)\phi X$.

Theorem 4. *Under the quarter-symmetric non-metric connection,*

$$(D_X g)(Y, Z) + (D_Y g)(Z, X) + (D_Z g)(X, Y) = 0, \quad (29)$$

$$\begin{aligned} & g(\bar{T}(X, Y), Z) + g(\bar{T}(Y, Z), X) + g(\bar{T}(Z, X), Y) \\ &= 2[\eta(Y)g(\phi X, Z) + \eta(Z)g(\phi Y, X) + \eta(X)g(\phi Z, Y)], \end{aligned} \quad (30)$$

Proof. By (4) and (18), we have

$$\begin{aligned} & (D_X g)(Y, Z) + (D_Y g)(Z, X) + (D_Z g)(X, Y) \\ &= -[\eta(Y)\{g(\phi X, Z) + g(X, \phi Z)\} + \eta(X)\{g(\phi Y, Z) \\ &\quad + g(Y, \phi Z)\} + \eta(Z)\{g(\phi X, Y) + g(X, \phi Y)\}] = 0. \end{aligned}$$

From (17) we have

$$\begin{aligned} & g(\bar{T}(X, Y), Z) + g(\bar{T}(Y, Z), X) + g(\bar{T}(Z, X), Y) \\ &= \eta(Y)g(\phi X, Z) - \eta(X)g(\phi Y, Z) + \eta(Z)g(\phi Y, X) \\ &\quad - \eta(Y)g(\phi Z, X) + \eta(X)g(\phi Z, Y) - \eta(Z)g(\phi X, Y) \\ &= 2[\eta(Y)g(\phi X, Z) + \eta(Z)g(\phi Y, X) + \eta(X)g(\phi Z, Y)]. \end{aligned}$$

Theorem 5. *Let M be a trans-Sasakian manifold with the quarter-symmetric non-metric connection, then*

$$(D_X\phi)Y = (\nabla_X\phi)Y - X\eta(Y) + \eta(X)\eta(Y)\xi, \quad (31)$$

$$D_X\xi = \nabla_X\xi + \phi X, \quad (32)$$

$$(D_X\eta)Y = (\nabla_X\eta)Y, \quad (33)$$

$$(D_XF)(Y, Z) = (\nabla_XF)(Y, Z). \quad (34)$$

Proof. Using (16), we have

$$\begin{aligned} (D_X\phi)Y &= (\nabla_X\phi)Y - \phi(\nabla_XY) - \phi(\eta(Y)\phi X) \\ &= (\nabla_X\phi)Y - X\eta(Y) + \eta(X)\eta(Y)\xi. \end{aligned}$$

Putting ξ in place of Y in (16), we get

$$D_X\xi = \nabla_X\xi + \phi X.$$

Using (2) and (16), we get

$$(D_X\eta)Y = \nabla_X\eta(Y) - \eta(\nabla_XY) = (\nabla_X\eta)Y.$$

4. CURVATURE TENSOR AND RICCI TENSOR ON A TRANS-SASAKIAN MANIFOLD WITH RESPECT TO QUARTER-SYMMETRIC NON-METRIC CONNECTION

Let \bar{R} and R be the curvature tensors with respect to the quarter-symmetric non-metric connection D and the Levi-Civita connection ∇ respectively on a trans-Sasakian manifold M . In this section we shall find the relation between \bar{R} and R . Also we shall find the relation between \bar{S} and S , \bar{r} and r , where \bar{S} and \bar{r} are the Ricci tensor and scalar curvature with respect to quarter-symmetric non-metric connection D on M respectively, S and r are Ricci tensor and scalar curvature with respect to Levi-Civita connection ∇ on M respectively. After this we shall prove some theorems on curvature tensor, Ricci tensor and Einstein manifold.

Theorem 6. *Let X, Y and Z be vector fields on a trans-Sasakian manifold M and \bar{R} and R be the curvature tensors with respect to the quarter-symmetric non-metric connection D and with respect to the Levi-Civita connection ∇ on M respectively. Then*

$$\begin{aligned} \bar{R}(X, Y)Z &= R(X, Y)Z + \alpha[\eta(X)Y - \eta(Y)X]\eta(Z) + 2\beta\eta(Z)g(\phi X, Y)\xi \\ &\quad + \alpha\{g(\phi Y, Z)\phi X - g(\phi X, Z)\phi Y\} + \beta\{g(X, Z)\phi Y - g(Y, Z)\phi X\}. \end{aligned}$$

Proof. We define the curvature tensor \bar{R} with respect to quarter-symmetric non-metric connection on M by

$$\bar{R}(X, Y)Z = D_X D_Y Z - D_Y D_X Z - D_{[X, Y]}Z.$$

Using (8) and (16) we get

$$\begin{aligned} \bar{R}(X, Y)Z &= R(X, Y)Z + \eta(Z)[(\nabla_X \phi)(Y) - (\nabla_Y \phi)(X)] + \{\alpha g(\phi Y, Z) \\ &\quad - \beta g(\phi Y, \phi Z)\}\phi X - \{\alpha g(\phi X, Z) - \beta g(\phi X, \phi Z)\}\phi Y. \end{aligned}$$

Then using (3), (4) and (6) we get

$$\begin{aligned} \bar{R}(X, Y)Z &= R(X, Y)Z + \alpha[\eta(X)Y - \eta(Y)X]\eta(Z) \\ &\quad + 2\beta\eta(Z)g(\phi X, Y)\xi + \alpha\{g(\phi Y, Z)\phi X - g(\phi X, Z)\phi Y\} \\ &\quad + \beta\{g(X, Z)\phi Y - g(Y, Z)\phi X\}. \end{aligned} \tag{35}$$

Theorem 7. *If \bar{S} and \bar{r} are the Ricci tensor and scalar curvature with respect to quarter-symmetric non-metric connection D on M respectively, S and r are Ricci tensor and scalar curvature with respect to Levi-Civita connection ∇ on M respectively, then*

$$\begin{aligned} \bar{S}(X, Y) &= S(X, Y) - (n - 1)\alpha\eta(Y)\eta(X) + \alpha g(\phi X, \phi Y) + \beta g(\phi Y, X) \\ \text{and } \bar{r} &= r. \end{aligned}$$

Proof. By (35) we get

$$\begin{aligned} g(\bar{R}(X, Y)Z, W) &= g(R(X, Y)Z, W) + \alpha\eta(Z)[\eta(X)g(Y, W) \\ &\quad - \eta(Y)g(X, W)] + 2\beta\eta(Z)g(\phi X, Y)g(\xi, W) + \alpha\{g(\phi Y, Z)g(\phi X, W) \\ &\quad - g(\phi X, Z)g(\phi Y, W)\} + \beta\{g(X, Z)g(\phi Y, W) - g(Y, Z)g(\phi X, W)\}. \end{aligned}$$

By contraction we get

$$\bar{S}(X, Y) = S(X, Y) - (n - 1)\alpha\eta(Y)\eta(X) + \alpha g(\phi X, \phi Y) + \beta g(\phi Y, X). \tag{36}$$

Again by contraction, from (36) we get

$$\bar{r} = r. \tag{37}$$

Theorem 8. *In a trans-Sasakian manifold with the quarter-symmetric non-metric connection*

$$\begin{aligned} \bar{R}(X, Y)Z + \bar{R}(Y, Z)X + \bar{R}(Z, X)Y \\ &= 2\alpha\{g(\phi X, Y)\phi Z + g(\phi Y, Z)\phi X + g(\phi Z, X)\phi Y\} \\ &\quad + 2\beta\{g(\phi X, Y)\eta(Z) + g(\phi Y, Z)\eta(X) + g(\phi Z, X)\eta(Y)\}\xi. \end{aligned}$$

Proof. Using first Binachi identity with respect to Levi-Civita connection ∇ and (35) we get the result.

Theorem 9. *In a trans-Sasakian manifold with quarter-symmetric non-metric connection D the Ricci tensor is symmetric if and only if $\beta = 0$, i.e., M is α -Sasakian manifold.*

Proof. By (36) and using (4) we get,

$$\bar{S}(X, Y) - \bar{S}(Y, X) = 2\beta g(X, \phi Y).$$

Clearly, $\bar{S}(X, Y)$ is symmetric if and only if $2\beta g(X, \phi Y) = 0$, i.e., $\beta = 0$.

Theorem 10. *In a trans-Sasakian manifold with a quarter-symmetric non-metric connection D , the Ricci tensor \bar{S} is skew-symmetric if and only if the Ricci tensor of the Levi-Civita connection ∇ is $S(X, Y) = (n - 1)\alpha\eta(Y)\eta(X) - \alpha g(\phi X, \phi Y)$.*

Proof. From (36) we get,

$$\begin{aligned} \bar{S}(X, Y) + \bar{S}(Y, X) &= 2S(X, Y) - 2(n - 1)\alpha\eta(Y)\eta(X) \\ &\quad + 2\alpha g(\phi X, \phi Y) + \beta\{g(\phi Y, X) + g(\phi X, Y)\}. \end{aligned}$$

Using (4), we have,

$$\bar{S}(X, Y) + \bar{S}(Y, X) = 2S(X, Y) - 2(n - 1)\alpha\eta(Y)\eta(X) + 2\alpha g(\phi X, \phi Y). \quad (38)$$

If $\bar{S}(X, Y)$ is skew-symmetric then the L.H.S. of above equation vanishes and we get

$$S(X, Y) = (n - 1)\alpha\eta(Y)\eta(X) - \alpha g(\phi X, \phi Y). \quad (39)$$

Using (39) in (38) we get,

$$\bar{S}(X, Y) + \bar{S}(Y, X) = 0.$$

Thus Ricci tensor of D is skew-symmetric.

Theorem 11. *In a trans-Sasakian manifold with the quarter-symmetric non-metric connection D , if $\alpha\{n\eta(X)\eta(Y) - g(X, Y)\} = \beta g(X, \phi Y)$ then the Einstein manifold for quarter-symmetric non-metric connection D is equal to the Einstein manifold for the Riemannian connection.*

Proof. We define Einstein manifold with respect to quarter-symmetric non-metric connection D by

$$\bar{S}(X, Y) = \frac{\bar{r}}{n}g(X, Y), \quad (40)$$

$X, Y \in \chi(M)$. From (36), (37) and (40) we get,

$$\bar{S}(X, Y) - \frac{\bar{r}}{n}g(X, Y) = S(X, Y) - \frac{r}{n}g(X, Y) - \alpha\{n\eta(X)\eta(Y) - g(X, Y)\} + \beta g(X, \phi Y).$$

If $\alpha\{n\eta(X)\eta(Y) - g(X, Y)\} - \beta g(X, \phi Y) = 0$, then $\bar{S}(X, Y) - \frac{\bar{r}}{n}g(X, Y) = S(X, Y) - \frac{r}{n}g(X, Y)$.

Hence the theorem is proved.

5. EXAMPLE OF A TRANS-SASAKIAN MANIFOLD WITH QUARTER-SYMMETRIC NON-METRIC CONNECTION

In this section we shall show a three dimensional trans-Sasakian manifold with quarter-symmetric non-metric connection.

Example 1. We consider the three-dimensional real manifold

$M = \{(x, y, z) \in R^3, z \neq 0, \}$ with the basis $\{e_1, e_2, e_3\}$, where $e_1 = z \frac{\partial}{\partial x}$, $e_2 = z \frac{\partial}{\partial y}$, $e_3 = z \frac{\partial}{\partial z}$ [2].

Let g be the Riemannian metric defined by

$$g(e_i, e_j) = 1, \text{ if } i = j, \\ = 0, \text{ if } i \neq j.$$

The 1-form η can be defined by $\eta(X) = g(X, e_3)$, where $X \in \chi(M)$. Then clearly $\eta(e_1) = \eta(e_2) = 0$ and $\eta(e_3) = 1$. Let ϕ be the (1, 1) tensor field defined by $\phi(e_1) = -e_2$, $\phi(e_2) = e_1$ and $\phi(e_3) = 0$. Let the contravariant vector field $\xi = e_3$.

Then $\eta(\xi) = 1$, $\phi^2(X) = -X + \eta(X)\xi$, $g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y)$, where $X, Y \in \chi(M)$.

Also $\eta(\phi(e_i)) = 0$, for all $i = 1, 2, 3$, $\phi\xi = 0$. Thus (ϕ, ξ, η, g) is an almost contact metric structure on M . Also we obtain

$$[e_1, e_2] = 0, [e_2, e_3] = -e_2 \text{ and } [e_1, e_3] = -e_1.$$

By Koszul's formula we get

$$\begin{aligned} \nabla_{e_1} e_1 &= e_3, & \nabla_{e_2} e_1 &= 0, & \nabla_{e_3} e_1 &= 0, \\ \nabla_{e_1} e_2 &= 0, & \nabla_{e_2} e_2 &= e_3, & \nabla_{e_3} e_2 &= 0, \\ \nabla_{e_1} e_3 &= -e_1, & \nabla_{e_2} e_3 &= -e_2, & \nabla_{e_3} e_3 &= 0. \end{aligned}$$

It can be shown that M is a trans-Sasakian manifold of type $(0, -1)$ [2].

Now using (16) we find D , the quarter-symmetric connection on M

$$\begin{aligned} D_{e_1} e_1 &= e_3, & D_{e_2} e_1 &= 0, & D_{e_3} e_1 &= 0, \\ D_{e_1} e_2 &= 0, & D_{e_2} e_2 &= e_3, & D_{e_3} e_2 &= 0, \\ D_{e_1} e_3 &= -e_1 - e_2, & D_{e_2} e_3 &= e_1 - e_2, & D_{e_3} e_3 &= 0. \end{aligned}$$

Using (17), the torsion tensor \bar{T} , with respect to quarter-symmetric connection D is given by $\bar{T}(e_i, e_i) = 0$, for all $i = 1, 2, 3$, $\bar{T}(e_1, e_2) = 0$, $\bar{T}(e_2, e_3) = -e_1$, $\bar{T}(e_3, e_1) = -e_2$.

Now using (18), we calculate the metric g with respect to the quarter-symmetric connection D as follows:

$$(D_{e_1}g)(e_2, e_3) = -\{\eta(e_2)g(\phi e_1, e_3) + \eta(e_3)g(\phi e_1, e_2)\} = 1,$$

$$(D_{e_2}g)(e_3, e_1) = -\{\eta(e_3)g(\phi e_2, e_1) + \eta(e_1)g(\phi e_2, e_3)\} = -1,$$

$$(D_{e_3}g)(e_1, e_2) = -\{\eta(e_1)g(\phi e_3, e_2) + \eta(e_2)g(\phi e_3, e_1)\} = 0.$$

From these we can conclude that $(D_Xg)(Y, Z) \neq 0$, where X, Y, Z are any vector field in $\chi(M)$.

Hence D is a quarter-symmetric non-metric connection on a trans-Sasakian manifold M .

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