# GLOBAL SOLVABILITY AND MANN ITERATION METHOD WITH ERROR FOR A THIRD ORDER NONLINEAR NEUTRAL DELAY DIFFERENTIAL EQUATION 

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#### Abstract

This paper intends to investigate the existence of uncountably many bounded positive solutions of a third order nonlinear neutral delay differential equation $$
\begin{aligned} & \frac{d}{d t}\left\{r_{1}(t) \frac{d}{d t}\left[r_{2}(t) \frac{d}{d t}(x(t)-f(t, x(t-\sigma)))\right]\right\} \\ & \quad+\frac{d}{d t}\left[r_{1}(t) \frac{d}{d t} g(t, x(p(t)))\right]+\frac{d}{d t} h(t, x(q(t)))=l(t, x(\eta(t))), \quad t \geq t_{0} \end{aligned}
$$ in the following bounded closed and convex set $$
\Omega(a, b)=\left\{x(t) \in C\left(\left[t_{0},+\infty\right), \mathbb{R}\right): a(t) \leq x(t) \leq b(t), \forall t \geq t_{0}\right\}
$$ where $\sigma>0, r_{1}, r_{2}, a, b \in C\left(\left[t_{0},+\infty\right), \mathbb{R}^{+}\right), f, g, h, l \in C\left(\left[t_{0},+\infty\right) \times \mathbb{R}, \mathbb{R}\right), p, q, \eta \in$ $C\left(\left[t_{0},+\infty\right),\left[t_{0},+\infty\right)\right)$. By using the Krasnoselskii fixed point theorem, the Schauder fixed point theorem, the Sadovskii fixed point theorem and the Banach contraction principle, four existence results of uncountably many bounded positive solutions of the differential equation are established. Moreover, a perturbed Mann iteration method with error is constructed for approximating the solution of the third order differential equation, and the convergence and stability of the iterative sequence generated by the algorithm are discussed.


## 1. Introduction and preliminaries

In recent years, it undergoes a rapid development for the theory of neutral delay differential equations and systems, especially for the existence of nonoscillatory solutions of second-order and higher order neutral delay differential equations, refer to $[1,3-5,9-11,13-16]$ and the references therein.

In 2005, Zhang, Feng, Yan and Song [15] studied the existence of nonoscillatory solutions of the first-order neutral delay differential equations with variable

[^0]coefficients and delays
\[

$$
\begin{equation*}
\frac{d}{d t}[x(t)+p(t) x(t-\tau)]+Q_{1}(t) x\left(t-\sigma_{1}\right)-Q_{2}(t) x\left(t-\sigma_{2}\right)=0, \quad t \geq t_{0} \tag{1.1}
\end{equation*}
$$

\]

where $p \in C\left(\left[t_{0},+\infty\right), \mathbb{R}\right), \tau>0, \sigma_{1}, \sigma_{2} \geq 0$ and $Q_{1}, Q_{2} \in C\left(\left[t_{0},+\infty\right), \mathbb{R}^{+}\right)$with $\int_{t_{0}}^{+\infty} Q_{i}(s) d s<+\infty$ for $i \in\{1,2\}$, and

$$
\begin{gather*}
\frac{d}{d t}[x(t)+p(t) x(t-\tau)]+\sum_{i=1}^{m} A_{i}(t) x\left(t-\sigma_{i}\right)-\sum_{i=m+1}^{n} A_{i}(t) x\left(t-\sigma_{i}\right)=0, \quad t \geq t_{0}  \tag{1.2}\\
\frac{d}{d t}[x(t)+p(t) x(t-\tau)]+\sum_{i=1}^{n} B_{i}(t) x\left(t-\sigma_{i}\right)=0, \quad t \geq t_{0} \tag{1.3}
\end{gather*}
$$

where $p, B_{i} \in C\left(\left[t_{0},+\infty\right), \mathbb{R}\right), \tau>0, \sigma_{i} \geq 0, A_{i} \in C\left(\left[t_{0},+\infty\right), \mathbb{R}^{+}\right)$with $\int_{t_{0}}^{+\infty} A_{i}(s) d s<$ $+\infty$ and $\int_{t_{0}}^{+\infty}\left|B_{i}(s)\right| d s<+\infty$ for $i \in\{1,2, \ldots, n\}$.

In 2005, Lin [10] got some sufficient conditions for oscillation and nonoscillation for the second-order nonlinear neutral differential equation

$$
\begin{equation*}
\frac{d^{2}}{d t^{2}}[x(t)-p(t) x(t-\tau)]+q(t) f(x(t-\sigma))=0, \quad t \geq 0 \tag{1.4}
\end{equation*}
$$

where $\tau, \sigma>0, p, q \in C([0,+\infty), \mathbb{R}), f \in C(\mathbb{R}, \mathbb{R})$ with $q(t) \geq 0$ and $x f(x)>0$ for $t \in \mathbb{R}, x \in \mathbb{R} /\{0\}$.

In 2007, Islam and Raffoul [5] employed Krasnoselskii fixed point theorem and the Banach contraction principle to discuss the existence of periodic solutions of the nonlinear neutral system of differential equations of the form

$$
\begin{equation*}
\frac{d}{d t} x(t)=A(t) x(t)+\frac{d}{d t} Q(t, x(t-g(t)))+G(t, x(t), x(t-g(t))) \tag{1.5}
\end{equation*}
$$

where $A(t)$ is a nonsingular $n \times n$ matrix, $Q \in C\left(\mathbb{R} \times \mathbb{R}^{n}, \mathbb{R}^{n}\right), G \in C\left(\mathbb{R} \times \mathbb{R}^{n} \times\right.$ $\left.\mathbb{R}^{n}, \mathbb{R}^{n}\right)$.

In 2007, Zhou [14] used Krasnoselskii fixed point theorem to study the existence of nonoscillatory soluions of the following second-order nonlinear neutral differential equation

$$
\begin{equation*}
\frac{d}{d t}\left[r(t) \frac{d}{d t}(x(t)+p(t) x(t-\tau))\right]+\sum_{i=1}^{m} Q_{i}(t) f_{i}\left(x\left(t-\sigma_{i}\right)\right)=0, \quad t \geq t_{0} \tag{1.6}
\end{equation*}
$$

where $m \geq 1$ is an integer, $\tau>0, \sigma_{i} \geq 0, r, p, Q_{i} \in C\left(\left[t_{0},+\infty\right), \mathbb{R}\right)$ and $f_{i} \in C(\mathbb{R}, \mathbb{R})$ for $i \in\{1,2, \ldots, m\}$.

However, the works on Eqs.(1.1)-(1.6) listed above and others are all concerning the existence of single nonoscillatory solution or at most infinitely many nonoscillatory solutions. As far as we are concerned, the existence of uncountably many nonoscillatory solutions of Eqs.(1.1)-(1.6) and other differential equations or systems has received much less attention until now.

In this paper, we are concerned with the following third order nonlinear neutral delay differential equation:

$$
\begin{align*}
& \frac{d}{d t}\left\{r_{1}(t) \frac{d}{d t}\left[r_{2}(t) \frac{d}{d t}(x(t)-f(t, x(t-\sigma)))\right]\right\}  \tag{1.7}\\
& \quad+\frac{d}{d t}\left[r_{1}(t) \frac{d}{d t} g(t, x(p(t)))\right]+\frac{d}{d t} h(t, x(q(t)))=l(t, x(\eta(t))), \quad t \geq t_{0}
\end{align*}
$$

where $\sigma>0, r_{1}, r_{2} \in C\left(\left[t_{0},+\infty\right), \mathbb{R}^{+}\right), f, g, h, l \in C\left(\left[t_{0},+\infty\right) \times \mathbb{R}, \mathbb{R}\right), p, q, \eta \in$ $C\left(\left[t_{0},+\infty\right),\left[t_{0},+\infty\right)\right)$ with

$$
\lim _{t \rightarrow+\infty} p(t)=\lim _{t \rightarrow+\infty} q(t)=\lim _{t \rightarrow+\infty} \eta(t)=+\infty
$$

By applying the Krasnoselskii fixed point theorem, the Schauder fixed point theorem, the Sadovskii fixed point theorem and the Banach contraction principle, we obtain four existence results of uncountably many bounded positive solutions of Eq.(1.7). Furthermore, we construct a perturbed Mann iteration algorithm for approximating the solution of Eq.(1.7) and discuss the convergence and stability of the iterative sequence.

Throughout this paper, put $I=\left[t_{0},+\infty\right)$ and $C(I, \mathbb{R})$ denote the Banach space of all continuous and bounded functions $x(t)$ on $I$ with norm $\|x\|=\sup _{t \in I}|x(t)|$. For any $a, b \in C\left(I, \mathbb{R}^{+}\right)$, set $\bar{a}=\sup _{t \in I} a(t), \underline{a}=\inf _{t \in I} a(t), \bar{b}=\sup _{t \in I} b(t), \underline{b}=$ $\inf _{t \in I} b(t)$ and

$$
\Omega(a, b)=\{x(t) \in C(I, \mathbb{R}): a(t) \leq x(t) \leq b(t), \forall t \in I\}
$$

Obviously, $\Omega(a, b)$ is a bounded closed and convex subset of $C(I, \mathbb{R})$. For any $D \subseteq \Omega(a, b)$ and $t \in I$, let

$$
\begin{aligned}
& D(t)=\sup \{|x(t)-y(t)|: x(t), y(t) \in D\} \\
& \quad \operatorname{diam} D=\sup \{\|x-y\|: x, y \in D\}
\end{aligned}
$$

It's assumed in the sequel that there exist functions $a, b, c, d, \alpha, \beta, \gamma, \lambda, \tau, \zeta \in$ $C\left(I, \mathbb{R}^{+}\right)$with $a(t)<b(t)$ for $t \in I$ and $\varphi: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$satisfying
(i) $\int_{t_{0}}^{+\infty} \max \left\{\frac{\alpha(s)}{r_{2}(s)}, \frac{\beta(s)}{r_{1}(s)}, \gamma(s), \frac{1}{r_{1}(s)}, \frac{1}{r_{2}(s)}\right\} d s<+\infty$;
(ii) $|f(t, u)| \leq c(t), \quad \forall t \in I, u \in[\underline{a}, \bar{b}]$;
(iii) $|f(t, u)-f(t, v)| \leq d(t)|u-v|, \quad \forall t \in I, u, v \in[\underline{a}, \bar{b}]$;
(iv) $|g(t, u)| \leq \alpha(t),|h(t, u)| \leq \beta(t),|l(t, u)| \leq \gamma(t), \quad \forall t \in I, u \in[\underline{a}, \bar{b}]$;
(v) $\int_{t_{0}}^{+\infty} \max \left\{\frac{s \alpha(s)}{r_{2}(s)}, \frac{\beta(s)}{r_{1}(s)}, \gamma(s), \frac{1}{r_{1}(s)}, \frac{s}{r_{2}(s)}\right\} d s<+\infty$;
(vi)

$$
\begin{aligned}
& |f(t, x(t-\sigma))-f(t, y(t-\sigma))| \\
& +\int_{t}^{+\infty} \frac{|g(s, x(p(s)))-g(s, y(p(s)))|}{r_{2}(s)} d s \\
& +\int_{t}^{+\infty} \int_{s}^{+\infty} \frac{|h(u, x(q(u)))-h(u, y(q(u)))|}{r_{2}(s) r_{1}(u)} d u d s \\
& +\int_{t}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{|l(v, x(\eta(v)))-l(v, y(\eta(v)))|}{r_{2}(s) r_{1}(u)} d v d u d s \\
& \leq \varphi(D(t)), \quad \forall D \subseteq \Omega(a, b), x, y \in D, t \in I
\end{aligned}
$$

(vii) $|g(t, u)-g(t, v)| \leq \lambda(t)|u-v|, \quad|h(t, u)-h(t, v)| \leq \tau(t)|u-v|$, $|l(t, u)-l(t, v)| \leq \zeta(t)|u-v|, \quad \forall t \in I, u, v \in[\underline{a}, \bar{b}] ;$
(viii) $\int_{t_{0}}^{+\infty} \max \left\{\frac{\lambda(s)}{r_{2}(s)}, \frac{\tau(s)}{r_{1}(s)}, \zeta(s), \frac{1}{r_{1}(s)}, \frac{1}{r_{2}(s)}\right\} d s<+\infty$.

By a solution of Eq.(1.7), we mean a function $x$ such that for some $t_{1} \geq t_{0}$, $x \in C\left(\left[t_{1}-\sigma,+\infty\right), \mathbb{R}\right), x(t)-f(t, x(t-\sigma))$ is 3 times continuously differentiable on $\left[t_{1},+\infty\right), g(t, x(p(t)))$ is 2 times continuously differentiable on $\left[t_{1},+\infty\right), h(t, x(q(t)))$ is continuously differentiable on $\left[t_{1},+\infty\right)$ and Eq.(1.7) holds for $t \geq t_{1}$.

The following four lemmas play significant roles in this paper.

Lemma 1.1. (Krasnoselskii Fixed Point Theorem [2]) Let $D$ be a nonempty bounded closed convex subset of a Banach space $X$ and $S, Q: D \rightarrow X$ satisfy $S x+Q y \in D$ for each $x, y \in D$. If $Q$ is a contraction mapping and $S$ is a completely continuous mapping, then the equation $S x+Q x=x$ has at least one solution in $D$.

Lemma 1.2. (Schauder Fixed Point Theorem [2]) Let $D$ be a nonempty closed convex subset of a Banach space $X$. Let $S: D \rightarrow D$ be a continuous mapping such that $S D$ is a relatively compact subset of $X$. Then $S$ has at least one fixed point in D.

Lemma 1.3. (Sadovskii Fixed Point Theorem [12]) Let $D$ be a nonempty bounded closed convex subset of a Banach space $X$ and $S: D \rightarrow D$ be a continuous condensing mapping. Then $S$ has at least one fixed point in $D$.

Lemma 1.4. (Banach contraction principle) Let $D$ be a closed subset of a completely metric space $X$ and $S: D \rightarrow D$ be a contraction on $D$. Then $S$ has at least one fixed point in $D$.

## 2. Existence of uncountably many bounded positive solutions

In this section, we demonstrate the existence of uncountably many bounded positive solutions of Eq.(1.7). Let

$$
c=\sup _{t \in I} c(t) \text { and } d=\sup _{t \in I} d(t) .
$$

Theorem 2.1. Let $a, b \in C\left(I, \mathbb{R}^{+}\right)$with $\bar{a}<\underline{b}$ and (i)-(iv) hold. If $d \in(0,1)$ and $c<\frac{b-\bar{a}}{2}$, then Eq.(1.7) possesses uncountably many bounded positive solutions in $\Omega(a, b)$.

Proof. Set $L \in(\bar{a}+c, \underline{b}-c)$. According to (i), we deduce that there exists $T \geq t_{0}+\sigma$ large enough satisfying

$$
\begin{gather*}
\int_{T}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s+\int_{T}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s \\
\quad<\min \{\underline{b}-c-L, L-c-\bar{a}\} \tag{2.1}
\end{gather*}
$$

Define two mappings $Q_{L}, S_{L}: \Omega(a, b) \rightarrow C(I, \mathbb{R})$ by

$$
\begin{align*}
& \left(Q_{L} x\right)(t)=\left\{\begin{array}{lc}
L+f(t, x(t-\sigma)), & t \geq T \\
\left(Q_{L} x\right)(T), & t_{0} \leq t<T
\end{array}\right. \\
& \left(S_{L} x\right)(t)= \begin{cases}\int_{t}^{+\infty} \frac{g(s, x(p(s)))}{r_{2}(s)} d s-\int_{t}^{+\infty} \int_{s}^{+\infty} \frac{h(u, x(q(u)))}{r_{2}(s) r_{1}(u)} d u d s \\
-\int_{t}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{l(v, x(\eta(v)))}{r_{2}(s) r_{1}(u)} d v d u d s, & t \geq T \\
\left(S_{L} x\right)(T), & t_{0} \leq t<T\end{cases} \tag{2.2}
\end{align*}
$$

for $x \in \Omega(a, b)$ and $t \in I$.

Firstly, we prove $Q_{L} x+S_{L} y \in \Omega(a, b)$ for all $x, y \in \Omega(a, b)$. Due to (ii), (iv), (2.1) and (2.2), we get that for each $x, y \in \Omega(a, b)$ and $t \geq T$,

$$
\begin{align*}
& \left(Q_{L} x+S_{L} y\right)(t) \\
& \leq L+c(t)+\int_{T}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s \\
& \quad+\int_{T}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s  \tag{2.3}\\
& \leq L+c+(\underline{b}-c-L) \\
& \leq b(t)
\end{align*}
$$

and

$$
\begin{align*}
& \left(Q_{L} x+S_{L} y\right)(t) \\
& \geq L-c(t)-\left[\int_{T}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.\quad+\int_{T}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right]  \tag{2.4}\\
& \geq L-c-(L-c-\bar{a}) \\
& \geq a(t)
\end{align*}
$$

It follows from (2.3) and (2.4) that $Q_{L} \Omega(a, b)+S_{L} \Omega(a, b) \subseteq \Omega(a, b)$.
Secondly, we demonstrate that $Q_{L}$ is a contraction mapping. According to (2.2) and (iii), we derive that

$$
\begin{aligned}
\left|\left(Q_{L} x\right)(t)-\left(Q_{L} y\right)(t)\right| & =|f(t, x(t-\sigma))-f(t, y(t-\sigma))| \\
& \leq d(t)|x(t-\sigma)-y(t-\sigma)| \\
& \leq d\|x-y\|, \quad \forall x, y \in \Omega(a, b), t \geq T
\end{aligned}
$$

which infers that

$$
\left\|Q_{L} x-Q_{L} y\right\| \leq d\|x-y\|, \quad \forall x, y \in \Omega(a, b)
$$

That is, $Q_{L}$ is a contraction mapping by $d \in(0,1)$.
Thirdly, we show that $S_{L}$ is completely continuous. Now we demonstrate $S_{L}$ is continuous in $\Omega(a, b)$. Let $x_{0} \in \Omega(a, b)$ and $\left\{x_{k}\right\}_{k \geq 0} \subset \Omega(a, b)$ with $x_{k} \rightarrow x_{0}$ as
$k \rightarrow+\infty$. (2.2) yields that

$$
\begin{align*}
\| S_{L} x_{k} & -S_{L} x_{0} \| \\
= & \sup _{t \in I}\left|\left(S_{L} x_{k}\right)(t)-\left(S_{L} x_{0}\right)(t)\right| \\
\leq & \sup _{t \geq T}\left\{\int_{t}^{+\infty} \frac{\left|g\left(s, x_{k}(p(s))\right)-g\left(s, x_{0}(p(s))\right)\right|}{r_{2}(s)} d s\right. \\
& +\int_{t}^{+\infty} \int_{s}^{+\infty} \frac{\left|h\left(u, x_{k}(q(u))\right)-h\left(u, x_{0}(q(u))\right)\right|}{r_{2}(s) r_{1}(u)} d u d s \\
& \left.+\int_{t}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\left|l\left(v, x_{k}(\eta(v))\right)-l\left(v, x_{0}(\eta(v))\right)\right|}{r_{2}(s) r_{1}(u)} d v d u d s\right\}  \tag{2.5}\\
\leq & \int_{T}^{+\infty} \frac{\left|g\left(s, x_{k}(p(s))\right)-g\left(s, x_{0}(p(s))\right)\right|}{r_{2}(s)} d s \\
& +\int_{T}^{+\infty} \int_{s}^{+\infty} \frac{\left|h\left(u, x_{k}(q(u))\right)-h\left(u, x_{0}(q(u))\right)\right|}{r_{2}(s) r_{1}(u)} d u d s \\
& +\int_{T}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\left|l\left(v, x_{k}(\eta(v))\right)-l\left(v, x_{0}(\eta(v))\right)\right|}{r_{2}(s) r_{1}(u)} d v d u d s
\end{align*}
$$

Note that

$$
\begin{align*}
& \left|g\left(s, x_{k}(p(s))\right)-g\left(s, x_{0}(p(s))\right)\right| \leq 2 \alpha(s), \\
& \left|h\left(u, x_{k}(q(u))\right)-h\left(u, x_{0}(q(u))\right)\right| \leq 2 \beta(u),  \tag{2.6}\\
& \left|l\left(v, x_{k}(\eta(v))\right)-l\left(v, x_{0}(\eta(v))\right)\right| \leq 2 \gamma(v) \\
& \quad\left|g\left(s, x_{k}(p(s))\right)-g\left(s, x_{0}(p(s))\right)\right| \rightarrow 0 \\
& \quad\left|h\left(u, x_{k}(q(u))\right)-h\left(u, x_{0}(q(u))\right)\right| \rightarrow 0  \tag{2.7}\\
& \quad\left|l\left(v, x_{k}(\eta(v))\right)-l\left(v, x_{0}(\eta(v))\right)\right| \rightarrow 0
\end{align*}
$$

as $k \rightarrow+\infty$ and $s, u, v \in[T,+\infty)$. It follows from (2.5), (2.6), (2.7) and Lebesgue dominated convergence theorem that $\left\|S_{L} x_{k}-S_{L} x_{0}\right\| \rightarrow 0$ as $k \rightarrow+\infty$. Hence $S_{L}$ is continuous in $\Omega(a, b)$. Now we prove that $S_{L} \Omega(a, b)$ is relatively compact. In view of (i), (iv) and (2.2), we deduce that

$$
\begin{aligned}
\left\|S_{L} x\right\|= & \sup _{t \in I}\left|\left(S_{L} x\right)(t)\right| \\
\leq & \int_{T}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s \\
& +\int_{T}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s, \quad \forall x \in \Omega(a, b) .
\end{aligned}
$$

That is, $S_{L} \Omega(a, b)$ is uniformly bounded. For the equicontinuity of $S_{L} \Omega(a, b)$ on $I$, according to Levitans result [6], it suffices to prove that for any given $\epsilon>0, I$ can be decomposed into finite subintervals in such a way that on each subinterval all functions of the family have change of amplitude less than $\epsilon$. Let $\epsilon>0$. By (i), there exists $T_{*}>T$ such that

$$
\begin{align*}
\int_{T_{*}}^{+\infty} & \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T_{*}}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s \\
& \quad+\int_{T_{*}}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s<\frac{\epsilon}{2} \tag{2.8}
\end{align*}
$$

It follows from (iv), (2.2) and (2.8) that for all $x \in \Omega(a, b)$ and $t_{2} \geq t_{1} \geq T_{*}$,

$$
\begin{aligned}
\left|\left(S_{L} x\right)\left(t_{1}\right)-\left(S_{L} x\right)\left(t_{2}\right)\right| \leq & \left|\left(S_{L} x\right)\left(t_{1}\right)\right|+\left|\left(S_{L} x\right)\left(t_{2}\right)\right| \\
\leq & \int_{t_{1}}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{t_{1}}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s \\
& +\int_{t_{1}}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s \\
& +\int_{t_{2}}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{t_{2}}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s \\
& +\int_{t_{2}}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s \\
\leq & 2\left[\int_{T_{*}}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T_{*}}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.+\int_{T_{*}}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right] \\
< & \epsilon ;
\end{aligned}
$$

For each $x \in \Omega(a, b)$ and $T \leq t_{1} \leq t_{2} \leq T_{*}$, by (iv) and (2.2), we infer that

$$
\begin{align*}
\mid & \left(S_{L} x\right)\left(t_{1}\right)-\left(S_{L} x\right)\left(t_{2}\right) \mid \\
\leq & \int_{t_{1}}^{t_{2}} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{t_{1}}^{t_{2}} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s \\
& +\int_{t_{1}}^{t_{2}} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s  \tag{2.9}\\
\leq & M\left|t_{1}-t_{2}\right|
\end{align*}
$$

where

$$
M=\max _{T \leq s \leq T_{*}}\left\{\frac{\alpha(s)}{r_{2}(s)}+\int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u+\int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u\right\}
$$

(2.9) implies that there exists $\delta=\frac{\epsilon}{1+M}>0$ such that $\left|\left(S_{L} x\right)\left(t_{1}\right)-\left(S_{L} x\right)\left(t_{2}\right)\right|<\epsilon$ for any $t_{1}, t_{2} \in\left[T, T_{*}\right]$ with $\left|t_{1}-t_{2}\right|<\delta$ and $x \in \Omega(a, b)$;

For $x \in \Omega(a, b), t_{0} \leq t_{1} \leq t_{2} \leq T$, due to (2.2), we achieve that

$$
\left|\left(S_{L} x\right)\left(t_{1}\right)-\left(S_{L} x\right)\left(t_{2}\right)\right|=0
$$

Hence Lemma 1.1 ensures that there exists $x \in \Omega(a, b)$ with $Q_{L} x+S_{L} x=x$. It is easy to see that $x$ is a bounded positive solution of Eq.(1.7).

Finally, we investigate that Eq.(1.7) possesses uncountably many bounded positive solutions. Let $L_{1}, L_{2} \in(\bar{a}+c, \underline{b}-c)$ and $L_{1} \neq L_{2}$. For each $j \in\{1,2\}$, we choose a constant $T_{j}>t_{0}+\sigma$ and two mappings $Q_{L_{j}}$ and $S_{L_{j}}$ satisfying (2.1) and (2.2), where $L$ and $T$ are replaced by $L_{j}$ and $T_{j}$, respectively, and

$$
\begin{align*}
\int_{T_{3}}^{+\infty} & \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T_{3}}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s  \tag{2.10}\\
& +\int_{T_{3}}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s<\frac{\left|L_{1}-L_{2}\right|}{2}
\end{align*}
$$

for some $T_{3}>\max \left\{T_{1}, T_{2}\right\}$. Obviously, the mappings $Q_{L_{1}}+S_{L_{1}}$ and $Q_{L_{2}}+S_{L_{2}}$ have the fixed points $x, y \in \Omega(a, b)$, respectively. That is, $x$ and $y$ are bounded positive solutions of Eq.(1.7) in $\Omega(a, b)$. In order to show that Eq.(1.7) possesses uncountably many bounded positive solutions in $\Omega(a, b)$, we need only to prove that $x \neq y$. Indeed, by (2.2) we gain that for $t \geq T_{3}$,

$$
\begin{aligned}
x(t)= & L_{1}+f(t, x(t-\sigma))+\int_{t}^{+\infty} \frac{g(s, x(p(s)))}{r_{2}(s)} d s \\
& -\int_{t}^{+\infty} \int_{s}^{+\infty} \frac{h(u, x(q(u)))}{r_{2}(s) r_{1}(u)} d u d s-\int_{t}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{l(v, x(\eta(v)))}{r_{2}(s) r_{1}(u)} d v d u d s
\end{aligned}
$$

and

$$
\begin{aligned}
y(t)= & L_{2}+f(t, y(t-\sigma))+\int_{t}^{+\infty} \frac{g(s, y(p(s)))}{r_{2}(s)} d s \\
& -\int_{t}^{+\infty} \int_{s}^{+\infty} \frac{h(u, y(q(u)))}{r_{2}(s) r_{1}(u)} d u d s-\int_{t}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{l(v, y(\eta(v)))}{r_{2}(s) r_{1}(u)} d v d u d s
\end{aligned}
$$

which together with (iv) and (2.10) yield that

$$
\begin{aligned}
& |x(t)-y(t)-(f(t, x(t-\sigma))-f(t, y(t-\sigma)))| \\
& \quad \geq\left|L_{1}-L_{2}\right|-2\left[\int_{T_{3}}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T_{3}}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.\quad+\int_{T_{3}}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right] \\
& >0, \quad \forall t \geq T_{3},
\end{aligned}
$$

that is, $x \neq y$. This completes the proof.

Theorem 2.2. Let $a, b \in C\left(I, \mathbb{R}^{+}\right)$with $\bar{a}<\underline{b}$ and (iv) and (v) hold. Then Eq.(1.7) with $f(t, u)=u$ possesses uncountably many bounded positive solutions in $\Omega(a, b)$.

Proof. Due to (v), there exists $M_{0}>0$ such that

$$
\max \left\{\int_{t_{0}}^{+\infty} \frac{\beta(u)}{r_{1}(u)} d u, \int_{t_{0}}^{+\infty} \int_{t_{0}}^{+\infty} \frac{\gamma(v)}{r_{1}(u)} d v d u\right\}<M_{0}
$$

By the known result([2]), we gain that

$$
\int_{t_{0}}^{+\infty} \frac{s \alpha(s)}{r_{2}(s)} d s<+\infty, \quad \int_{t_{0}}^{+\infty} \frac{s}{r_{2}(s)} d s<+\infty
$$

are equivalent to

$$
\sum_{j=0}^{+\infty} \int_{t_{0}+j \sigma}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s<+\infty, \quad \sum_{j=0}^{+\infty} \int_{t_{0}+j \sigma}^{+\infty} \frac{1}{r_{2}(s)} d s<+\infty
$$

respectively. Hence

$$
\begin{aligned}
& \sum_{j=0}^{+\infty}\left[\int_{t_{0}+j \sigma}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{t_{0}+j \sigma}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.\quad+\int_{t_{0}+j \sigma}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right] \\
& <\sum_{j=0}^{+\infty}\left[\int_{t_{0}+j \sigma}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{t_{0}+j \sigma}^{+\infty} \int_{t_{0}}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.\quad+\int_{t_{0}+j \sigma}^{+\infty} \int_{t_{0}}^{+\infty} \int_{t_{0}}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right] \\
& <\sum_{j=0}^{+\infty}\left[\int_{t_{0}+j \sigma}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+2 M_{0} \int_{t_{0}+j \sigma}^{+\infty} \frac{1}{r_{2}(s)} d s\right] \\
& <+\infty
\end{aligned}
$$

Let $L \in(\bar{a}, \underline{b})$. According to the above inequalities, we deduce that there exists $T \geq t_{0}+\sigma$ sufficiently large satisfying

$$
\begin{align*}
& \sum_{j=1}^{+\infty}\left[\int_{T+j \sigma}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T+j \sigma}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.\quad+\int_{T+j \sigma}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right]  \tag{2.11}\\
& <\min \{\underline{b}-L, L-\bar{a}\}
\end{align*}
$$

Define a mapping $Q_{L}: \Omega(a, b) \rightarrow C(I, \mathbb{R})$ by

$$
\left(Q_{L} x\right)(t)=\left\{\begin{array}{c}
L-\sum_{j=1}^{+\infty}\left[\int_{t+j \sigma}^{+\infty} \frac{g(s, x(p(s)))}{r_{2}(s)} d s-\int_{t+j \sigma}^{+\infty} \int_{s}^{+\infty} \frac{h(u, x(q(u)))}{r_{2}(s) r_{1}(u)} d u d s\right.  \tag{2.12}\\
\left.-\int_{t+j \sigma}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{l(v, x(\eta(v)))}{r_{2}(s) r_{1}(u)} d v d u d s\right], \\
t \geq T \\
\left(Q_{L} x\right)(T), \quad t_{0} \leq t<T
\end{array}\right.
$$

First of all, we prove $Q_{L} x \in \Omega(a, b)$ for all $x \in \Omega(a, b)$. Due to (iv) and (2.12), we derive that for each $x \in \Omega(a, b)$,

$$
\begin{aligned}
& \left(Q_{L} x\right)(t) \\
& \leq L+\sum_{j=1}^{+\infty}\left[\int_{T+j \sigma}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T+j \sigma}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.+\int_{T+j \sigma}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right] \\
& \begin{array}{l}
\leq L+(\underline{b}-L) \\
\leq b(t), \\
\begin{array}{l}
\left(Q_{L} x\right)(t)
\end{array} \\
\begin{array}{l}
\geq L-\sum_{j=1}^{+\infty}\left[\int_{T+j \sigma}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T+j \sigma}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
\left.\quad+\int_{T+j \sigma}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right] \\
\geq L-(L-\bar{a}) \\
\geq a(t),
\end{array} t \geq T .
\end{array}
\end{aligned}
$$

Therefore, $Q_{L} \Omega(a, b) \subseteq \Omega(a, b)$.
Next, we demonstrate that $Q_{L}$ is completely continuous. It's claimed that $Q_{L}$ is continuous. Indeed, let $x_{0} \in \Omega(a, b)$ and $\left\{x_{k}\right\}_{k \geq 0} \subset \Omega(a, b)$ with $x_{k} \rightarrow x_{0}$ as $k \rightarrow+\infty$. (2.12) yields that

$$
\begin{align*}
& \| Q_{L} x_{k}-Q_{L} x_{0} \| \\
&=\sup _{t \in I}\left|\left(Q_{L} x_{k}\right)(t)-\left(Q_{L} x_{0}\right)(t)\right| \\
& \leq \sup _{t \in I}\left\{\sum _ { j = 1 } ^ { + \infty } \left[\int_{t+j \sigma}^{+\infty} \frac{\left|g\left(s, x_{k}(p(s))\right)-g\left(s, x_{0}(p(s))\right)\right|}{r_{2}(s)} d s\right.\right. \\
&+\int_{t+j \sigma}^{+\infty} \int_{s}^{+\infty} \frac{\left|h\left(u, x_{k}(q(u))\right)-h\left(u, x_{0}(q(u))\right)\right|}{r_{2}(s) r_{1}(u)} d u d s \\
&\left.\left.+\int_{t+j \sigma}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\left|l\left(v, x_{k}(\eta(v))\right)-l\left(v, x_{0}(\eta(v))\right)\right|}{r_{2}(s) r_{1}(u)} d v d u d s\right]\right\}  \tag{2.13}\\
& \leq \sum_{j=1}^{+\infty}[ \int_{T+j \sigma}^{+\infty} \frac{\left|g\left(s, x_{k}(p(s))\right)-g\left(s, x_{0}(p(s))\right)\right|}{r_{2}(s)} d s \\
&+\int_{T+j \sigma}^{+\infty} \int_{s}^{+\infty} \frac{\left|h\left(u, x_{k}(q(u))\right)-h\left(u, x_{0}(q(u))\right)\right|}{r_{2}(s) r_{1}(u)} d u d s \\
&\left.+\int_{T+j \sigma}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\left|l\left(v, x_{k}(\eta(v))\right)-l\left(v, x_{0}(\eta(v))\right)\right|}{r_{2}(s) r_{1}(u)} d v d u d s\right] .
\end{align*}
$$

In light of (2.6), (2.7), (2.13) and Lebesgue dominated convergence theorem, we infer that $\left\|Q_{L} x_{k}-Q_{L} x_{0}\right\| \rightarrow 0$ as $k \rightarrow+\infty$, which means that $Q_{L}$ is continuous. Now we show $Q_{L} \Omega(a, b)$ is relatively compact. On account of $Q_{L} \Omega(a, b) \subseteq \Omega(a, b)$,
$Q_{L}$ is uniformly bounded. Because of (v) and for any $\epsilon>0$, choose $T_{*}>T$ large enough such that

$$
\begin{align*}
& \sum_{j=1}^{+\infty}\left[\int_{T_{*}+j \sigma}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T_{*}+j \sigma}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right.  \tag{2.14}\\
&\left.\quad+\int_{T_{*}+j \sigma}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right]<\frac{\epsilon}{2}
\end{align*}
$$

By (2.12) and (2.14), for $x \in \Omega(a, b), t_{2} \geq t_{1} \geq T_{*}$, we have

$$
\begin{aligned}
\mid & \left(Q_{L} x\right)\left(t_{1}\right)-\left(Q_{L} x\right)\left(t_{2}\right) \mid \\
\leq & \sum_{j=1}^{+\infty}\left[\int_{t_{1}+j \sigma}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{t_{1}+j \sigma}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.+\int_{t_{1}+j \sigma}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right] \\
& +\sum_{j=1}^{+\infty}\left[\int_{t_{2}+j \sigma}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{t_{2}+j \sigma}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.+\int_{t_{2}+j \sigma}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right] \\
< & \epsilon
\end{aligned}
$$

For $T \leq t_{1} \leq t_{2} \leq T_{*}$, choose a sufficiently large integer $w \geq 1$ satisfying $T+j \sigma \geq T_{*}$ with $j \geq w$. For $x \in \Omega(a, b)$, we get that

$$
\begin{aligned}
& \left|\left(Q_{L} x\right)\left(t_{1}\right)-\left(Q_{L} x\right)\left(t_{2}\right)\right| \\
& \leq \sum_{j=1}^{+\infty}\left[\int_{t_{1}+j \sigma}^{t_{2}+j \sigma} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{t_{1}+j \sigma}^{t_{2}+j \sigma} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.+\int_{t_{1}+j \sigma}^{t_{2}+j \sigma} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right] \\
& =\sum_{j=1}^{w}\left[\int_{t_{1}+j \sigma}^{t_{2}+j \sigma} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{t_{1}+j \sigma}^{t_{2}+j \sigma} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.+\int_{t_{1}+j \sigma}^{t_{2}+j \sigma} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right] \\
& +\sum_{j=w+1}^{+\infty}\left[\int_{t_{1}+j \sigma}^{t_{2}+j \sigma} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{t_{1}+j \sigma}^{t_{2}+j \sigma} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.+\int_{t_{1}+j \sigma}^{t_{2}+j \sigma} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right] \\
& \leq \sum_{j=1}^{w}\left[\int_{t_{1}+j \sigma}^{t_{2}+j \sigma} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{t_{1}+j \sigma}^{t_{2}+j \sigma} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.+\int_{t_{1}+j \sigma}^{t_{2}+j \sigma} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right] \\
& +\sum_{j=1}^{+\infty}\left[\int_{T_{*}+j \sigma}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T_{*}+j \sigma}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.+\int_{T_{*}+j \sigma}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right] \\
& <W\left|t_{1}-t_{2}\right|+\frac{\epsilon}{2},
\end{aligned}
$$

where

$$
\begin{aligned}
& W=\max _{T+\sigma \leq s \leq T_{*}+w \sigma}\left\{\sum _ { j = 1 } ^ { w } \left[\frac{\alpha(s)}{r_{2}(s)}+\int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u\right.\right. \\
&\left.\left.+\int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u\right]\right\}
\end{aligned}
$$

which implies that there exists $\delta=\frac{\epsilon}{2(1+W)}>0$ such that $\left|\left(Q_{L} x\right)\left(t_{1}\right)-\left(Q_{L} x\right)\left(t_{2}\right)\right|<$ $\epsilon$ for any $t_{1}, t_{2} \in\left[T, T_{*}\right]$ with $\left|t_{1}-t_{2}\right|<\delta$ and $x \in \Omega(a, b)$;

For $x \in \Omega(a, b), t_{0} \leq t_{1} \leq t_{2} \leq T$, it follows from (2.12) that

$$
\left|\left(Q_{L} x\right)\left(t_{1}\right)-\left(Q_{L} x\right)\left(t_{2}\right)\right|=0
$$

Thus Lemma 1.2 ensures that there exists $x \in \Omega(a, b)$ with $Q_{L} x=x$. That is,

$$
x(t)=\left\{\begin{array}{c}
L-\sum_{j=1}^{+\infty}\left[\int_{t+j \sigma}^{+\infty} \frac{g(s, x(p(s)))}{r_{2}(s)} d s-\int_{t+j \sigma}^{+\infty} \int_{s}^{+\infty} \frac{h(u, x(q(u)))}{r_{2}(s) r_{1}(u)} d u d s\right. \\
\left.-\int_{t+j \sigma}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{l(v, x(\eta(v)))}{r_{2}(s) r_{1}(u)} d v d u d s\right], \quad t \geq T \\
x(T), \quad t_{0} \leq t<T
\end{array}\right.
$$

It follows that for $t \geq T$,

$$
\begin{aligned}
x(t)-x(t-\sigma)=\int_{t}^{+\infty} & \frac{g(s, x(p(s)))}{r_{2}(s)} d s-\int_{t}^{+\infty} \int_{s}^{+\infty} \frac{h(u, x(q(u)))}{r_{2}(s) r_{1}(u)} d u d s \\
& -\int_{t}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{l(v, x(\eta(v)))}{r_{2}(s) r_{1}(u)} d v d u d s
\end{aligned}
$$

It's easy to verify that $x$ is a bounded positive solution of Eq.(1.7).
Finally, we investigate that Eq.(1.7) possesses uncountably many bounded positive solutions. Let $L_{1}, L_{2} \in(\bar{a}+c, \underline{b}-c)$ with $L_{1} \neq L_{2}$. For each $j \in\{1,2\}$, choose a constant $T_{j}>t_{0}+\sigma$ and a mapping $Q_{L_{j}}$ to satisfy (2.11) and (2.12), where $L$ and $T$ are replaced by $L_{j}$ and $T_{j}$, respectively, and

$$
\begin{align*}
& \sum_{j=1}^{+\infty}\left[\int_{T_{3}+j \sigma}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T_{3}+j \sigma}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right.  \tag{2.15}\\
& \left.\quad+\int_{T_{3}+j \sigma}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right]<\frac{\left|L_{1}-L_{2}\right|}{2}
\end{align*}
$$

for some $T_{3}>\max \left\{T_{1}, T_{2}\right\}$. Obviously, the mappings $Q_{L_{1}}$ and $Q_{L_{2}}$ have the fixed points $x, y \in \Omega(a, b)$, respectively. That is, $x$ and $y$ are bounded positive solutions of Eq.(1.7). Next we need only to prove that $x \neq y$. As a matter of fact, by (2.12) we get that for $t \geq T_{3}$,

$$
\begin{aligned}
x(t)=L_{1}-\sum_{j=1}^{+\infty}[ & \int_{t+j \sigma}^{+\infty} \frac{g(s, x(p(s)))}{r_{2}(s)} d s-\int_{t+j \sigma}^{+\infty} \int_{s}^{+\infty} \frac{h(u, x(q(u)))}{r_{2}(s) r_{1}(u)} d u d s \\
& \left.-\int_{t+j \sigma}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{l(v, x(\eta(v)))}{r_{2}(s) r_{1}(u)} d v d u d s\right] \\
y(t)=L_{2}-\sum_{j=1}^{+\infty}[ & \int_{t+j \sigma}^{+\infty} \frac{g(s, y(p(s)))}{r_{2}(s)} d s-\int_{t+j \sigma}^{+\infty} \int_{s}^{+\infty} \frac{h(u, y(q(u)))}{r_{2}(s) r_{1}(u)} d u d s \\
& \left.-\int_{t+j \sigma}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{l(v, y(\eta(v)))}{r_{2}(s) r_{1}(u)} d v d u d s\right]
\end{aligned}
$$

which together with (iv) and (2.15) yield that

$$
\begin{aligned}
|x(t)-y(t)| \geq\left|L_{1}-L_{2}\right|-2 \sum_{j=1}^{+\infty}[ & \int_{T_{3}+j \sigma}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T_{3}+j \sigma}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s \\
& \left.+\int_{T_{3}+j \sigma}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right]
\end{aligned}
$$

$>0, \quad \forall t \geq T_{3}$,
that is, $x \neq y$. This completes the proof.

Theorem 2.3. Let $a, b \in C\left(I, \mathbb{R}^{+}\right)$with $\bar{a}<\underline{b}$ and (i), (ii), (iv) and (vi) hold. If $c<\frac{b-\bar{a}}{2}$ and $\varphi$ is nondecreasing with $\varphi(t+)<t$ for each $t>0$, then Eq.(1.7) possesses uncountably many bounded positive solutions in $\Omega(a, b)$.

Proof. Put $L \in(\bar{a}+c, \underline{b}-c)$. In view of (i), there exists $T \geq t_{0}+\sigma$ sufficiently large satisfying (2.1). Define a mapping $Q_{L}: \Omega(a, b) \rightarrow C(I, \mathbb{R})$ by

$$
\left(Q_{L} x\right)(t)=\left\{\begin{array}{l}
L+f(t, x(t-\sigma))+\int_{t}^{+\infty} \frac{g(s, x(p(s)))}{r_{2}(s)} d s-\int_{t}^{+\infty} \int_{s}^{+\infty} \frac{h(u, x(q(u)))}{r_{2}(s) r_{1}(u)} d u d s  \tag{2.16}\\
\quad-\int_{t}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{l(v, x(\eta(v)))}{r_{2}(s) r_{1}(u)} d v d u d s, \quad t \geq T \\
\left(Q_{L} x\right)(T), \quad t_{0} \leq t<T .
\end{array}\right.
$$

Firstly, we assure that $Q_{L} x \in \Omega(a, b)$ for all $x \in \Omega(a, b)$. In terms of (ii), (iv), (2.1) and (2.16), we infer that for each $x \in \Omega(a, b)$,

$$
\begin{align*}
& \left(Q_{L} x\right)(t) \\
& \leq L+c(t)+\left(\int_{T}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.+\int_{T}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right)  \tag{2.17}\\
& \leq L+c+(\underline{b}-c-L) \\
& \leq b(t), \quad t \geq T, \\
& \left(Q_{L} x\right)(t) \\
& \geq L-c(t)-\left(\int_{T}^{+\infty} \frac{\alpha(s)}{r_{2}(s)} d s+\int_{T}^{+\infty} \int_{s}^{+\infty} \frac{\beta(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.+\int_{T}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\gamma(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right)  \tag{2.18}\\
& \geq L-c-(L-c-\bar{a}) \\
& \geq a(t), \quad t \geq T .
\end{align*}
$$

Thus $Q_{L} \Omega(a, b) \subseteq \Omega(a, b)$.
Secondly, we claim that

$$
\begin{equation*}
\lim _{t \rightarrow 0^{+}} \varphi(t)=0=\varphi(0) \tag{2.19}
\end{equation*}
$$

Because $\varphi: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$is nondecreasing and nonnegative, we deduce that

$$
0 \leq \varphi(0) \leq \varphi(t) \leq \varphi(s), \quad \forall s>t>0
$$

which together with $\varphi(t+)<t$ for each $t>0$ ensures that

$$
0 \leq \varphi(0) \leq \varphi(t) \leq \lim _{s \rightarrow t^{+}} \varphi(s)=\varphi(t+)<t, \quad \forall t>0
$$

Letting $t \rightarrow 0^{+}$in the above inequalities, we get that (2.19) holds.
Thirdly, we prove that $Q_{L}$ is continuous. Let $x_{0} \in \Omega(a, b)$ and $\left\{x_{k}\right\}_{k \geq 0} \subset \Omega(a, b)$ with $x_{k} \rightarrow x_{0}$ as $k \rightarrow+\infty$. Let $D_{k}=\left\{x_{k}, x_{0}\right\}$ for $k \geq 1$. It follows from (vi), (2.16)
and (2.19) that

$$
\begin{aligned}
\left\|Q_{L} x_{k}-Q_{L} x_{0}\right\|= & \sup _{t \in I}\left|\left(Q_{L} x_{k}\right)(t)-\left(Q_{L} x_{0}\right)(t)\right| \\
\leq & \sup _{t \geq T}\left[\left|f\left(t, x_{k}(t-\sigma)\right)-f\left(t, x_{0}(t-\sigma)\right)\right|\right. \\
& +\int_{t}^{+\infty} \frac{\left|g\left(s, x_{k}(p(s))\right)-g\left(s, x_{0}(p(s))\right)\right|}{r_{2}(s)} d s \\
& +\int_{t}^{+\infty} \int_{s}^{+\infty} \frac{\left|h\left(u, x_{k}(q(u))\right)-h\left(u, x_{0}(q(u))\right)\right|}{r_{2}(s) r_{1}(u)} d u d s \\
& \left.+\int_{t}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\left|l\left(v, x_{k}(\eta(v))\right)-l\left(v, x_{0}(\eta(v))\right)\right|}{r_{2}(s) r_{1}(u)} d v d u d s\right] \\
\leq & \sup _{t \geq T} \varphi\left(D_{k}(t)\right) \\
= & \sup _{t \geq T} \varphi\left(\left|x_{k}(t)-x_{0}(t)\right|\right) \\
\leq & \varphi\left(\left\|x_{k}-x_{0}\right\|\right) \\
\rightarrow & 0 \text { as } k \rightarrow+\infty .
\end{aligned}
$$

Thereupon, $Q_{L}$ is continuous in $\Omega(a, b)$.
Lastly, we demonstrate that $Q_{L}$ is a condensing mapping. Let $\epsilon>0$. For any nonempty subset $D$ of $\Omega(a, b)$ with $\alpha(D)>0$, where $\alpha$ denotes the Kuratowski measure of noncompactness, there exist finitely many subsets $D_{1}, D_{2}, \ldots, D_{n}$ of $\Omega(a, b)$ such that

$$
\begin{equation*}
D \subseteq \bigcup_{m=1}^{n} D_{m}, \operatorname{diam} D_{m} \leq \alpha(D)+\epsilon, \quad \forall m \in\{1,2, \ldots, n\} \tag{2.20}
\end{equation*}
$$

It follows from (vi) and (2.16) that for any $x, y \in D_{m}, m \in\{1,2, \ldots, n\}$,

$$
\begin{aligned}
\left\|Q_{L} x-Q_{L} y\right\|= & \sup _{t \in I}\left|\left(Q_{L} x\right)(t)-\left(Q_{L} y\right)(t)\right| \\
\leq & \sup _{t \geq T}[|f(t, x(t-\sigma))-f(t, y(t-\sigma))| \\
& +\int_{t}^{+\infty} \frac{|g(s, x(p(s)))-g(s, y(p(s)))|}{r_{2}(s)} d s \\
& +\int_{t}^{+\infty} \int_{s}^{+\infty} \frac{|h(u, x(q(u)))-h(u, y(q(u)))|}{r_{2}(s) r_{1}(u)} d u d s \\
& \left.+\int_{t}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{|l(v, x(\eta(v)))-l(v, y(\eta(v)))|}{r_{2}(s) r_{1}(u)} d v d u d s\right] \\
\leq & \sup _{t \geq T} \varphi\left(D_{m}(t)\right) \\
\leq & \varphi\left(\operatorname{diam} D_{m}\right)
\end{aligned}
$$

which means that

$$
\begin{equation*}
\operatorname{diam}\left(Q_{L} D_{m}\right) \leq \varphi\left(\operatorname{diam} D_{m}\right), \quad \forall m \in\{1,2, \ldots, n\} \tag{2.21}
\end{equation*}
$$

According to (2.20) and (2.21), we derive that

$$
\begin{aligned}
\alpha\left(Q_{L} D\right) & \leq \alpha\left(\bigcup_{m=1}^{n} Q_{L} D_{m}\right)=\max _{1 \leq m \leq n}\left\{\alpha\left(Q_{L} D_{m}\right)\right\} \\
& \leq \max _{1 \leq m \leq n} \operatorname{diam}\left(Q_{L} D_{m}\right) \leq \max _{1 \leq m \leq n} \varphi\left(\operatorname{diam} D_{m}\right) \\
& \leq \varphi(\alpha(D)+\epsilon) .
\end{aligned}
$$

Setting $\epsilon \rightarrow 0$ in the above inequality, we gain that

$$
\alpha\left(Q_{L} D\right) \leq \varphi(\alpha(D)+0)<\alpha(D)
$$

which implies that $Q_{L}$ is condensing. Lemma 1.3 ensures that there exists $x \in$ $\Omega(a, b)$ with $Q_{L} x=x$, which is also a solution of Eq.(1.7). The rest of the proof is similar to that of Theorem 2.1. This completes the proof.

Theorem 2.4. Let $a, b \in C\left(I, \mathbb{R}^{+}\right)$with $\bar{a}<\underline{b}$ and (i)-(iv), (vii) and (viii) hold. If $c<\frac{b-\bar{a}}{2}$ and $d \in(0,1)$, then Eq.(1.7) possesses uncountably many bounded positive solutions in $\Omega(a, b)$.

Proof. Put $L \in(\bar{a}+c, \underline{b}-c)$. Due to (i) and (viii), we derive that there exists $T \geq t_{0}+\sigma$ large enough satisfying (2.1) and
$\int_{T}^{+\infty} \frac{\lambda(s)}{r_{2}(s)} d s+\int_{T}^{+\infty} \int_{s}^{+\infty} \frac{\tau(u)}{r_{2}(s) r_{1}(u)} d u d s+\int_{T}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\zeta(v)}{r_{2}(s) r_{1}(u)} d v d u d s$ $<\frac{1-d}{2}$.

Define a mapping $Q_{L}: \Omega(a, b) \rightarrow C(I, \mathbb{R})$ by (2.16). Just as (2.17) and (2.18), we can demonstrate that $Q_{L}$ is a self-mapping on $\Omega(a, b)$ by (ii), (iv) and (2.1).

We now investigate that $Q_{L}$ is a contraction mapping. According to (iii), (vii) and (2.22), we get that

$$
\begin{aligned}
& \left|\left(Q_{L} x\right)(t)-\left(Q_{L} y\right)(t)\right| \\
& \leq|f(t, x(t-\sigma))-f(t, y(t-\sigma))|+\int_{t}^{+\infty} \frac{|g(s, x(p(s)))-g(s, y(p(s)))|}{r_{2}(s)} d s \\
& \quad+\int_{t}^{+\infty} \int_{s}^{+\infty} \frac{|h(u, x(q(u)))-h(u, y(q(u)))|}{r_{2}(s) r_{1}(u)} d u d s \\
& \quad+\int_{t}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{|l(v, x(\eta(v)))-l(v, y(\eta(v)))|}{r_{2}(s) r_{1}(u)} d v d u d s \\
& \leq d(t)|x(t-\sigma)-y(t-\sigma)|+\int_{t}^{+\infty} \frac{\lambda(s)|x(p(s))-y(p(s))|}{r_{2}(s)} d s \\
& \quad+\int_{t}^{+\infty} \int_{s}^{+\infty} \frac{\tau(u)|x(q(u))-y(q(u))|}{r_{2}(s) r_{1}(u)} d u d s \\
& \quad+\int_{t}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\zeta(v)|x(\eta(v))-y(\eta(v))|}{r_{2}(s) r_{1}(u)} d v d u d s \\
& \leq\left(d+\int_{T}^{+\infty} \frac{\lambda(s)}{r_{2}(s)} d s+\int_{T}^{+\infty} \int_{s}^{+\infty} \frac{\tau(u)}{r_{2}(s) r_{1}(u)} d u d s\right. \\
& \left.\quad \quad+\int_{T}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\zeta(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right)\|x-y\| \\
& <\frac{1+d}{2}\|x-y\|, \quad t \geq T,
\end{aligned}
$$

which infers that $\left\|Q_{L} x-Q_{L} y\right\|<\frac{1+d}{2}\|x-y\|$ for any $x, y \in \Omega(a, b)$. Clearly, $Q_{L}$ is a contraction mapping by $d \in(0,1)$. Consequently, $Q_{L}$ has a unique fixed point $x \in \Omega(a, b)$, which is a bounded positive solution of Eq.(1.7). The rest of the proof is similar to that of Theorem 2.1 and is omitted. This completes the proof.

## 3. Algorithm and convergence

In this section, a perturbed Mann iteration method with error is constructed for approximating the solution of the third order nonlinear neutral delay differential equation (1.7), and the convergence and stability of the iterative sequence generated by the algorithm are discussed.

Lemma 3.1. ([7]) Let $\left\{a_{n}\right\}_{n \geq 0},\left\{b_{n}\right\}_{n \geq 0},\left\{c_{n}\right\}_{n \geq 0}$ be nonnegative sequences satisfying

$$
a_{n+1} \leq\left(1-\lambda_{n}\right) a_{n}+\lambda_{n} b_{n}+c_{n}, \quad \forall n \geq 0
$$

where

$$
\left\{\lambda_{n}\right\}_{n=0}^{\infty} \subset[0,1], \sum_{n=0}^{\infty} \lambda_{n}=+\infty, \sum_{n=0}^{\infty} c_{n}<+\infty, \lim _{n \rightarrow \infty} b_{n}=0
$$

Then $\lim _{n \rightarrow \infty} a_{n}=0$.
Definition 3.2. ([8])??Let $n \geq 0, T$ be a self-mapping of $H, x_{0} \in H, x_{n+1}=$ $f\left(T, x_{n}\right)$ be an iteration procedure which yields a sequence of points $\left\{x_{n}\right\}_{n \geq 0} \subset H$, where $f$ is a continuous mapping. Suppose that $\{x \in H: T x=x\} \neq \varnothing$ and $\left\{x_{n}\right\}_{n \geq 0}$ converges to a fixed point $x^{*}$ of $T$. Let $\left\{u_{n}\right\}_{n \geq 0} \subset H, E_{n}=\left\|u_{n+1}-f\left(T, u_{n}\right)\right\|$. If
$\lim _{n \rightarrow \infty} E_{n}=0$ implies that $\lim _{n \rightarrow \infty} u_{n}=x^{*}$, then the iteration procedure defined by $x_{n+1}=f\left(T, x_{n}\right)$ is said to be $T$-stable or stable with respect to $T$.

Algorithm 3.3. Let $\sigma, r_{1}, r_{2}, f, g, h, l, p, q, \eta$ be same as those in Theorem 2.4. For any $x_{0}(t) \in C(I, \mathbb{R})$, define an iterative sequence $\left\{x_{n}(t)\right\}_{n \geq 0}$ on $I$ by

$$
\begin{equation*}
x_{n+1}(t)=\left(1-a_{n}\right) x_{n}(t)+a_{n}\left(Q_{L} x_{n}\right)(t)+a_{n} e_{n}(t), \forall n \geq 0 \tag{3.1}
\end{equation*}
$$

where $Q_{L}$ is the same as in (2.16), $\left\{e_{n}(t)\right\}_{n \geq 0} \subset C(I, \mathbb{R})$ is a sequence introduced to take into account possible inexact computation which satisfies

$$
\lim _{n \rightarrow \infty}\left\|e_{n}\right\|=0
$$

and the sequence $\left\{a_{n}\right\}_{n \geq 0}$ satisfies the following condition

$$
0<a \leq a_{n} \leq 1, \quad \forall n \geq 0
$$

where $a$ is a constant. Let $\left\{z_{n}(t)\right\}_{n \geq 0} \subset C(I, \mathbb{R})$ be any sequence and define $\varepsilon_{n}$ for $n \geq 0$ by

$$
\begin{equation*}
\varepsilon_{n}=\left\|z_{n+1}-\left[\left(1-a_{n}\right) z_{n}+a_{n}\left(Q_{L} z_{n}\right)+a_{n} e_{n}\right]\right\| \tag{3.2}
\end{equation*}
$$

Theorem 3.4. Let all conditions of Theorem 2.4 hold. Then
(1) the iterative sequence $\left\{x_{n}(t)\right\}_{n \geq 0}$ generated by Algorithm 3.3 converges to a solution $x(t)$ relative to $L$ of Eq.(1.7),
(2) for any sequence $\left\{z_{n}(t)\right\}_{n \geq 0} \subset C(I, \mathbb{R}), \lim _{n \rightarrow \infty} z_{n}(t)=x(t)$ if and only if $\lim _{n \rightarrow \infty} \varepsilon_{n}=0$, where $\varepsilon_{n}$ is defined by Algorithm 3.3.

Proof. First to prove (1). It follows from Theorem 2.4 that Eq.(1.7) has a solution $x(t) \subset C(I, \mathbb{R})$ relative to $L$. Consequently,

$$
\begin{equation*}
x(t)=\left(1-a_{n}\right) x(t)+a_{n}\left(Q_{L} x\right)(t) \tag{3.3}
\end{equation*}
$$

By (2.22) and for $t \in I$,

$$
\begin{align*}
\| x_{n+1} & -x \| \\
\leq & \left(1-a_{n}\right)\left\|x_{n}-x\right\|+a_{n}\left\{d(t)\left\|x_{n}-x\right\|\right. \\
& +\int_{T}^{+\infty} \frac{\lambda(s)\left\|x_{n}-x\right\|}{r_{2}(s)} d s+\int_{T}^{+\infty} \int_{s}^{+\infty} \frac{\tau(u)\left\|x_{n}-x\right\|}{r_{2}(s) r_{1}(u)} d u d s \\
& \left.+\int_{T}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\zeta(v)\left\|x_{n}-x\right\|}{r_{2}(s) r_{1}(u)} d v d u d s\right\}+a_{n}\left\|e_{n}\right\|  \tag{3.4}\\
\leq & \left\{1-a_{n}\left[1-\left(d+\int_{T}^{+\infty} \frac{\lambda(s)}{r_{2}(s)} d s+\int_{T}^{+\infty} \int_{s}^{+\infty} \frac{\tau(u)}{r_{2}(s) r_{1}(u)} d u d s\right.\right.\right. \\
& \left.\left.\left.+\int_{T}^{+\infty} \int_{s}^{+\infty} \int_{u}^{+\infty} \frac{\zeta(v)}{r_{2}(s) r_{1}(u)} d v d u d s\right)\right]\right\}\left\|x_{n}-x\right\|+a_{n}\left\|e_{n}\right\| \\
\leq & \left(1-\frac{1-d}{2} a_{n}\right)\left\|x_{n}-x\right\|+\frac{1-d}{2} a_{n} \frac{\left\|e_{n}\right\|}{\frac{1-d}{2}}, \quad \forall n \geq 0,
\end{align*}
$$

which means that $x_{n}(t) \rightarrow x(t)$ as $n \rightarrow \infty$ by Algorithm 3.3 and Lemma 3.1.

Now to prove (2). Using (3.2) and (3.3), similar to the proof of (3.4), we deduce that

$$
\begin{align*}
\left\|z_{n+1}-x\right\| \leq & \left\|z_{n+1}-\left[\left(1-a_{n}\right) z_{n}+a_{n}\left(Q_{L} z_{n}\right)+a_{n} e_{n}\right]\right\| \\
& +\left\|\left(1-a_{n}\right) z_{n}+a_{n}\left(Q_{L} z_{n}\right)+a_{n} e_{n}-x\right\|  \tag{3.5}\\
\leq & \left(1-\frac{1-d}{2} a_{n}\right)\left\|z_{n}-x\right\|+\frac{1-d}{2} a_{n} \frac{\left\|e_{n}\right\|+\frac{\epsilon_{n}}{a}}{\frac{1-d}{2}}, \quad \forall n \geq 0
\end{align*}
$$

Suppose that $\lim _{n \rightarrow \infty} \varepsilon_{n}=0$. By (3.5), Algorithm 3.3 and Lemma 3.1, we get that $z_{n}(t) \rightarrow x(t)$ as $n \rightarrow \infty$. Conversely, suppose that $z_{n}(t) \rightarrow x(t)$ as $n \rightarrow \infty$. In view of (3.2), we infer that

$$
\begin{aligned}
\varepsilon_{n} & \leq\left\|z_{n+1}-x\right\|+\left\|\left(1-a_{n}\right) z_{n}+a_{n}\left(Q_{L} z_{n}\right)+a_{n} e_{n}-x\right\| \\
& \leq\left\|z_{n+1}-x\right\|+\left(1-\frac{1-d}{2} a_{n}\right)\left\|z_{n}-x\right\|+a_{n}\left\|e_{n}\right\| \\
& \leq\left\|z_{n+1}-x\right\|+\left\|z_{n}-x\right\|+\left\|e_{n}\right\|, \quad \forall n \geq 0 .
\end{aligned}
$$

Hence, $\lim _{n \rightarrow \infty} \varepsilon_{n}=0$. This completes the proof.

## 4. Examples

In this section, two examples are given to illustrate how to apply the above results.

Example 4.1. Consider the following third order nonlinear neutral delay differential equation:

$$
\begin{align*}
& \frac{d}{d t}\left\{t^{3} \frac{d}{d t}\left[t^{2} \frac{d}{d t}\left(x(t)-\frac{\sin ^{2} t}{x(t-\sigma)+1}\right)\right]\right\}  \tag{4.1}\\
& \quad+\frac{d}{d t}\left[t^{3} \frac{d}{d t} \frac{x\left(e^{t}\right)}{t}\right]+\frac{d}{d t}\left[t x\left(t^{2}\right)\right]=\frac{1}{t^{2}+x(\sqrt{t})}, \quad t \geq t_{0}=1
\end{align*}
$$

where

$$
\begin{align*}
& \sigma>0, r_{1}(t)=t^{3}, r_{2}(t)=t^{2}, f(t, u)=\frac{\sin ^{2} t}{u+1}, g(t, u)=\frac{u}{t}  \tag{4.2}\\
& h(t, u)=t u, l(t, u)=\frac{1}{t^{2}+u}, p(t)=e^{t}, q(t)=t^{2}, \eta(t)=\sqrt{t}
\end{align*}
$$

Choose $a(t)=2+\sin t, b(t)=6+\cos t$. Then, $\underline{a}=1, \bar{a}=3, \underline{b}=5, \bar{b}=7$. We can take

$$
\begin{equation*}
c(t)=\frac{\sin ^{2} t}{2}, d(t)=\frac{\sin ^{2} t}{4}, \alpha(t)=\frac{7}{t}, \beta(t)=7 t, \gamma(t)=\frac{1}{t^{2}+1} \tag{4.3}
\end{equation*}
$$

It is easy to verify that the conditions of Theorem 2.1 are satisfied. Therefore Theorem 2.1 ensures that (4.1) has uncountably many bounded positive solutions in $\Omega(2+\sin t, 6+\cos t)$.

Example 4.2. Consider the following third order nonlinear neutral delay differential equation:

$$
\begin{align*}
& \frac{d}{d t}\left\{t^{4} \frac{d}{d t}\left[t^{3} \frac{d}{d t}(x(t)-x(t-\sigma))\right]\right\}+\frac{d}{d t}\left[t^{4} \frac{d}{d t} \frac{\sqrt{x\left(2^{t}\right)}}{t}\right]  \tag{4.4}\\
& \quad+\frac{d}{d t}\left[t^{2} \cos x(2+\ln t)\right]=\frac{\sin x(1+\arctan t)}{t^{3}}, \quad t \geq t_{0}=2
\end{align*}
$$

where

$$
\begin{align*}
& \sigma>0, r_{1}(t)=t^{4}, r_{2}(t)=t^{3}, g(t, u)=\frac{\sqrt{u}}{t}, h(t, u)=t^{2} \cos u  \tag{4.5}\\
& l(t, u)=\frac{\sin u}{t^{3}}, p(t)=2^{t}, q(t)=2+\ln t, \eta(t)=1+\arctan t
\end{align*}
$$

Choose $a(t) \equiv 1, b(t) \equiv 4$. We can take

$$
\begin{equation*}
\alpha(t)=\frac{2}{t}, \beta(t)=t^{2}, \gamma(t)=\frac{1}{t^{3}} \tag{4.6}
\end{equation*}
$$

It can be verified that the assumptions of Theorem 2.2 are fulfilled. It follows from Theorem 2.2 that (4.3) has uncountably many bounded positive solutions in $\Omega(1,4)$.

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