

How to construct your own directional wavelet frame ?

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Outline

- Introduction: well-known wavelet constructions
- Wanted properties of a directional wavelet system
- What can be learned from the one-dimensional case ?
- How to construct curvelets ?
- What are α -molecules ?
- References

Many wavelet (frame) constructions for image analysis

- 1) Tensor product wavelets
- 2) steerable wavelets [Freeman and Adelson '91]
- 3) curvelets [Candes, Donoho '03]
- 4) shearlets [Labate, Lim, Kutyniok, Weiss '05]
- 5) contourlets [Do, Vetterli '05]
- 6) Gabor wavelets [Lee '08]
- 7) α -molecules [Grohs, Keiper, Kutyniok, Schäfer '14]

Wanted properties of a new wavelet system

What is the purpose of the wavelet system?

We want a representation system $(\psi_\lambda)_{\lambda \in \Lambda}$ for images $f \in L^2(\mathbb{R}^2)$

$$f = \sum_{\lambda \in \Lambda} c_\lambda \psi_\lambda$$

that allows a “sparse representation” of the image f .

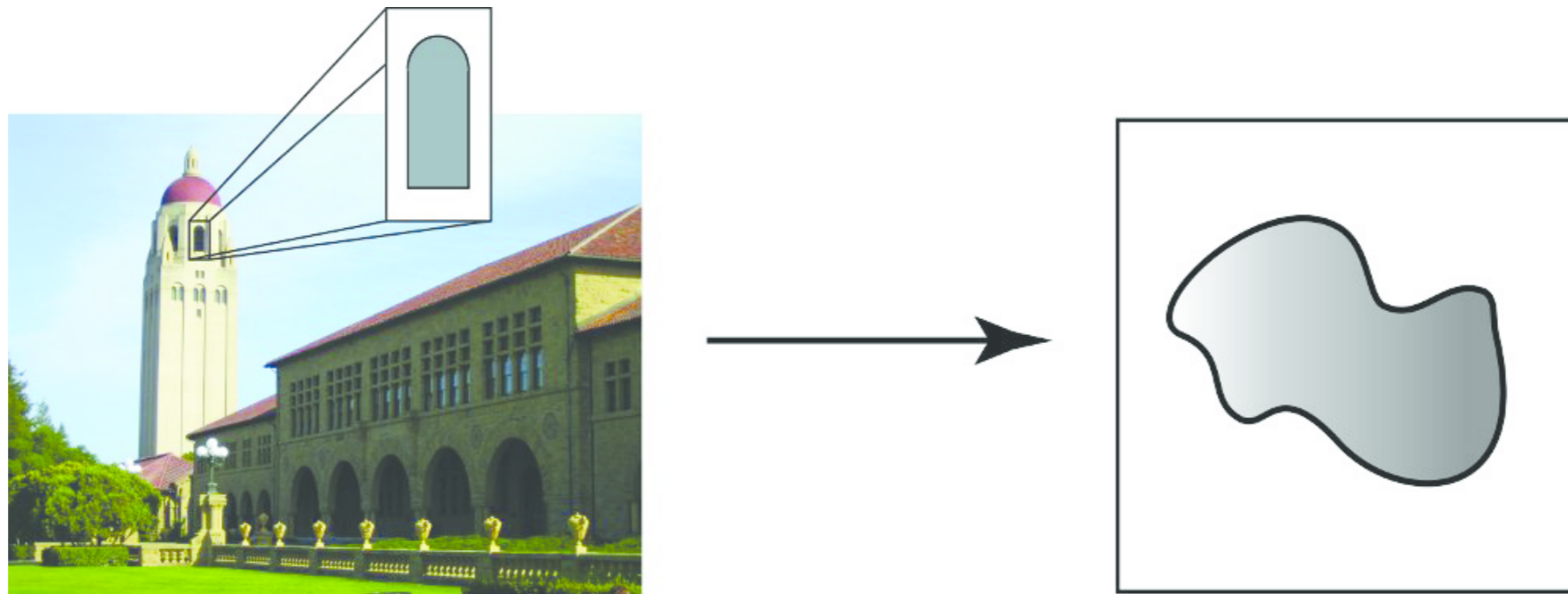
Best N -term approximation $f_N \approx f$

$$f_N = \operatorname{argmin} \left\| f - \sum_{\lambda \in \Lambda_N} c_\lambda \psi_\lambda \right\| \quad \text{where} \quad \Lambda_N \subset \Lambda, \quad |\Lambda_N| = N.$$

How to model the image data?

How to model the image data ?

Image model: Cartoon-like functions $\mathcal{E}^\beta(\mathbb{R}^2)$ [Donoho '01 ($\beta = 2$)]



Grohs et al '14: The class of cartoon-like functions $\mathcal{E}^\beta(\mathbb{R}^2)$, $\beta \in (1, 2]$, is defined by

$$\mathcal{E}^\beta(\mathbb{R}^2) = \{f \in L^2(\mathbb{R}^2) : f = f_0 + f_1 \cdot \chi_B\},$$

where $B \subset [0, 1]^2$, ∂B a closed C^β -curve, $f_0, f_1 \in C_0^\beta([0, 1]^2)$.

[Reprinted figure with permission of G. Kutyniok]

Wanted properties of a new wavelet system

- Good space-frequency localization
- “Simple structure” of the wavelet system $\{\psi_\lambda\}_{\lambda \in \Lambda}$ (multiscale approach)
- Orthonormal basis or Parseval frame of $L^2(\mathbb{R}^2)$, i.e.,

$$f = \sum_{\lambda \in \Lambda} \langle f, \psi_\lambda \rangle \psi_\lambda$$

and

$$\sum_{\lambda \in \Lambda} |\langle f, \psi_\lambda \rangle|^2 = \|f\|_{L^2(\mathbb{R}^2)}^2 \quad \text{for all } f \in L^2(\mathbb{R}^2)$$

(Parseval equation)

- Good approximation properties: If f is in a certain smoothness class, then f can be well approximated by a sparse wavelet frame expansion, such that e.g.

$$\|f - f_N\|_2^2 \leq C N^{-\beta}$$

for (piecewise) Hölder smooth functions of order β .

Sparse approximation benchmark

Theorem (Donoho '01)

Allowing only polynomial depth search in a dictionary, the approximation rate of the best N -term approximation for $\mathcal{E}^\beta(\mathbb{R}^2)$, $\beta \in (1, 2]$, cannot exceed

$$\|f - f_N\|_2^2 \sim N^{-\beta}.$$

Question: Can this bound be reached?

- Classical wavelet systems achieve $\|f - f_N\|_2^2 \sim N^{-1}$.
- Specifically designed directional representation systems can reach this bound up to log-factors.
- Adaptive wavelet frames can reach this bound.

What can be learned from \mathbb{R}^1 ?

- “Simple structure” of the wavelet system:
use translations and dilations of only on “mother-wavelet” ψ .

$$\psi_{j,k} = 2^{j/2} \psi(2^j \cdot -k), \quad j, k \in \mathbb{Z}.$$

- Good space-frequency localization:
 ψ should have compact support or fast decay outside in space and frequency domain.
- How to ensure that $\{\psi_{j,k} : j, k \in \mathbb{Z}\}$ is an orthonormal basis or a (Parseval) frame in $L^2(\mathbb{R})$?

Try to achieve that

$$\sum_{j=-\infty}^{\infty} |\hat{\psi}(2^j \omega)|^2 = 1 \quad \omega \in \mathbb{R} \text{ a.e.}$$

(or $0 < A \leq \sum_{j=-\infty}^{\infty} |\hat{\psi}(2^j \omega)|^2 \leq B < \infty$)
and has a good frequency localization.

Example: Meyer wavelets

Choose $\hat{\psi}$ with $\text{supp } \hat{\psi} \subset [-2, -1/2] \cup [1/2, 2]$ Hence $\text{supp } \hat{\psi}(2^{-j}\omega)$ has support $[-2^{j+1}, -2^{j-1}] \cup [2^{j-1}, 2^{j+1}]$.

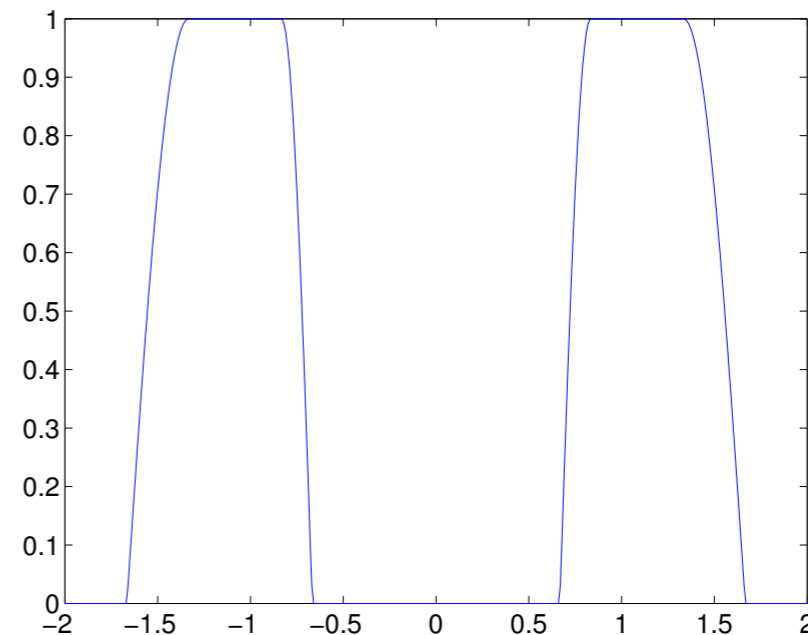
Choose e.g. for $\omega > 0$

$$\hat{\psi}(\omega) = \begin{cases} \cos\left[\frac{\pi}{2}\nu(5 - 6\omega)\right] & \frac{2}{3} \leq \omega \leq \frac{5}{6} \\ 1 & \frac{5}{6} \leq \omega \leq \frac{4}{3} \\ \cos\left[\frac{\pi}{2}\nu(3\omega - 4)\right] & \frac{4}{3} \leq \omega \leq \frac{5}{3} \\ 0 & \text{else} \end{cases}$$

where ν is smooth and $\nu(x) = 0$ for $x \leq 0$, $\nu(x) = 1$ for $x \geq 1$ and $\nu(x) + \nu(1 - x) = 1$ for $x \in [0, 1]$.

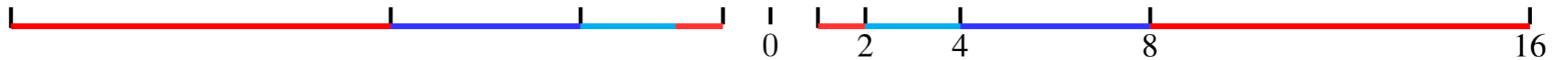
Choose e.g. $\nu(x) = x \cdot \chi_{[0,1]}(x)$

or $\nu(x) = (3x^2 - 2x^3) \cdot \chi_{[0,1]}$ etc.



Corresponding tiling of the frequency domain

one-dimensional case:



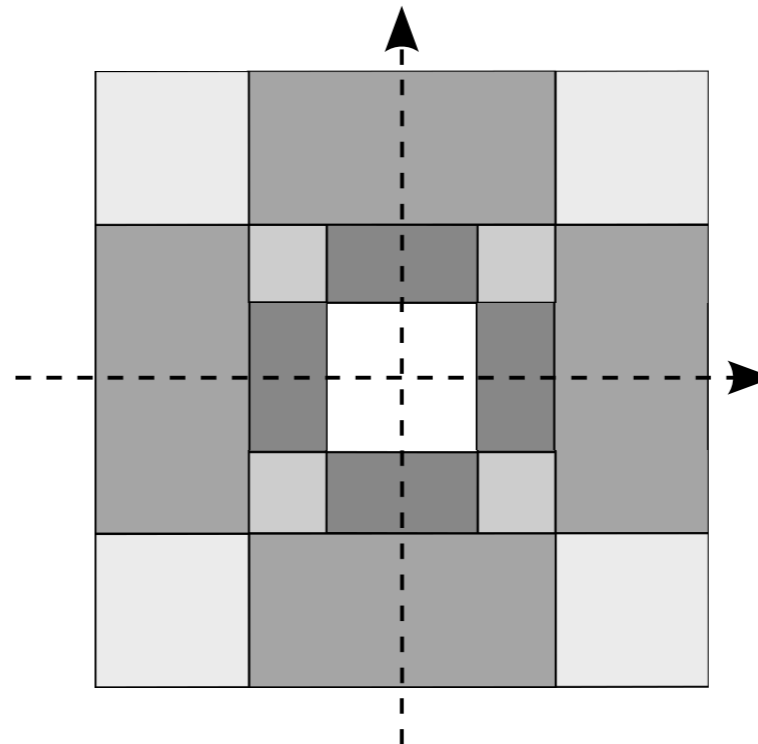
two-dimensional case: tensor-product wavelets

three types of wavelet functions

$$\hat{\phi}(\omega_1)\hat{\psi}(\omega_2)$$

$$\hat{\psi}(\omega_1)\hat{\phi}(\omega_2)$$

$$\hat{\psi}(\omega_1)\hat{\psi}(\omega_2)$$

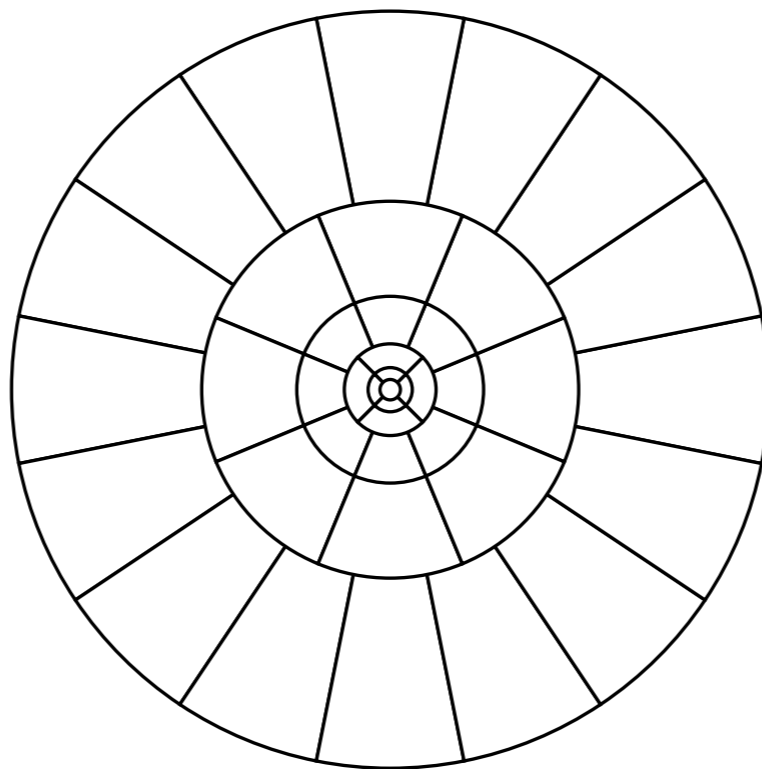


How to construct directional wavelet frames ?

Idea. use translations, dilations and rotations of one “basic function” ψ .

Curvelet construction.

1. Consider polar coordinates in frequency domain
2. Construct curvelet element being locally supported near a wedge.



Curvelet construction

Let $\omega = (\omega_1, \omega_2)^T$, $r := \sqrt{\omega_1^2 + \omega_2^2}$ and $\sigma := \arctan(\omega_1/\omega_2)$.

Ansatz for the dilated basic curvelet:

$$\hat{\psi}_{j,0,0}(r, \sigma) = 2^{-3j/4} W(2^{-j}r) V_{N_j}(\sigma), \quad r \geq 0, \sigma \in [0, 2\pi), j \in \mathbb{N}_0$$

with suitable window functions W and V_{N_j} , where $N_j = 4 \cdot 2^{\lceil j/2 \rceil}$ indicates the number of wedges in the circular ring at scale 2^{-j} .

We need:

a) $W(r)$ and $V_{N_j}(\sigma) = V_{per}(2^{-\lceil j/2 \rceil} \sigma)$ should have compact support or exponential decay.

b) Partition of frequency domain:

$$\sum_{j=-\infty}^{\infty} |W(2^j r)|^2 = 1$$

$$\sum_{l=0}^{N_j-1} V_{N_j}^2\left(\sigma - \frac{2\pi l}{N_j}\right) = 1 \quad \text{for all } \sigma \in [0, 2\pi).$$

Indeed we then have

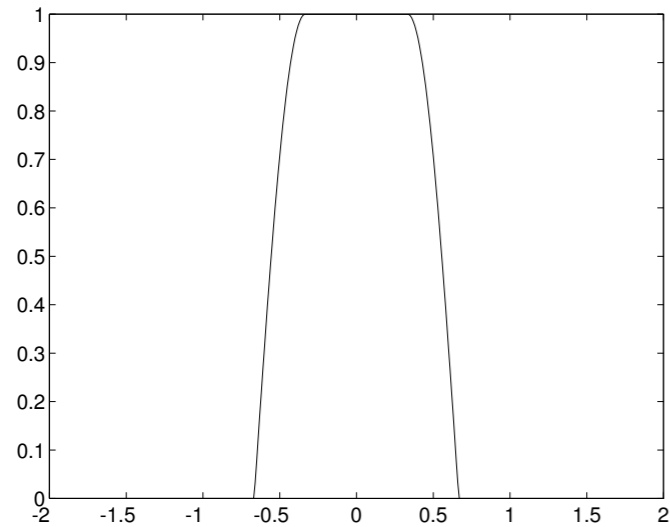
$$\begin{aligned} \sum_{l=0}^{N_j-1} \left| 2^{3j/4} \hat{\psi}_{j,0,0}(r, \sigma - \frac{2\pi l}{N_j}) \right|^2 &= |W(2^{-j}r)|^2 \sum_{l=0}^{N_j-1} V_{N_j}^2(\omega - \frac{2\pi l}{N_j}) \\ &= |W(2^{-j}r)|^2 \end{aligned}$$

Examples for Window functions.

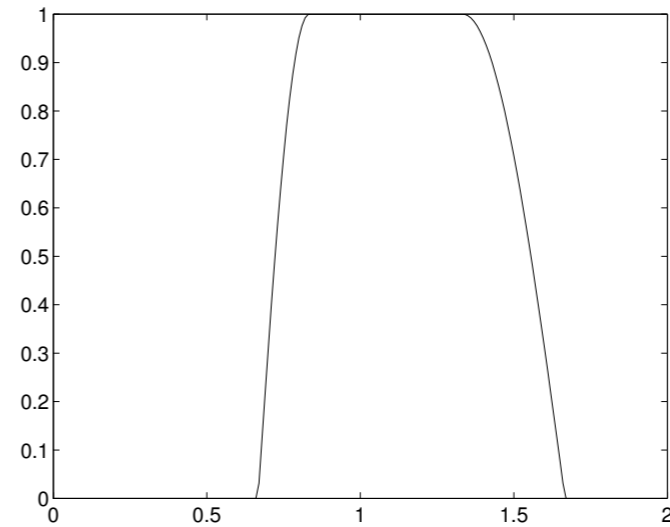
$$V(\sigma) = \begin{cases} 1 & |\sigma| \leq \frac{1}{3} \\ \cos(\frac{\pi}{2}\nu(3|\sigma| - 1)) & \frac{1}{3} \leq |\sigma| \leq \frac{2}{3}, \\ 0 & \text{else} \end{cases}$$

$$W(r) = \begin{cases} \cos[\frac{\pi}{2}\nu(5 - 6r)] & \frac{2}{3} \leq r \leq \frac{5}{6} \\ 1 & \frac{5}{6} \leq r \leq \frac{4}{3} \\ \cos[\frac{\pi}{2}\nu(3r - 4)] & \frac{4}{3} \leq r \leq \frac{5}{3} \\ 0 & \text{else} \end{cases}$$

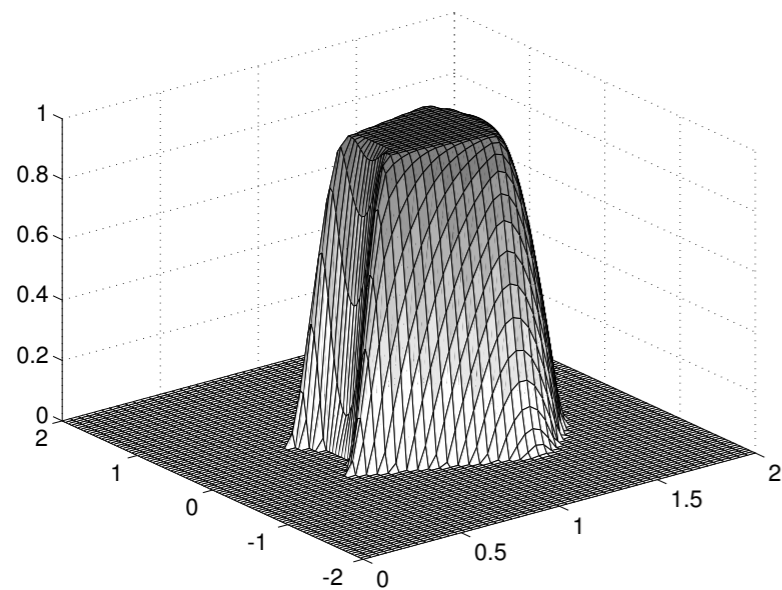
with ν as before.



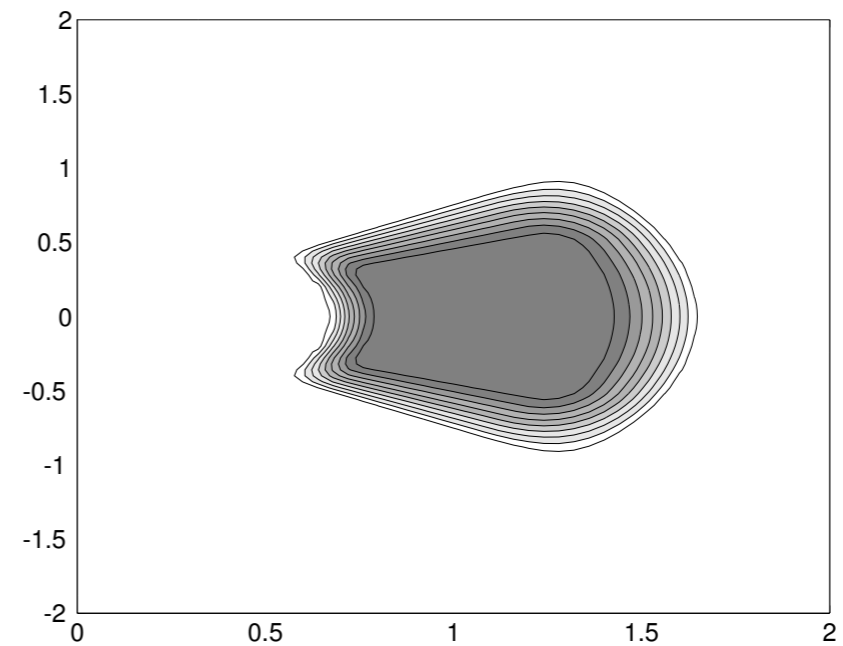
window V



window W



*basic curvelet $\hat{\psi}_{0,0,0}$ in
frequency domain*

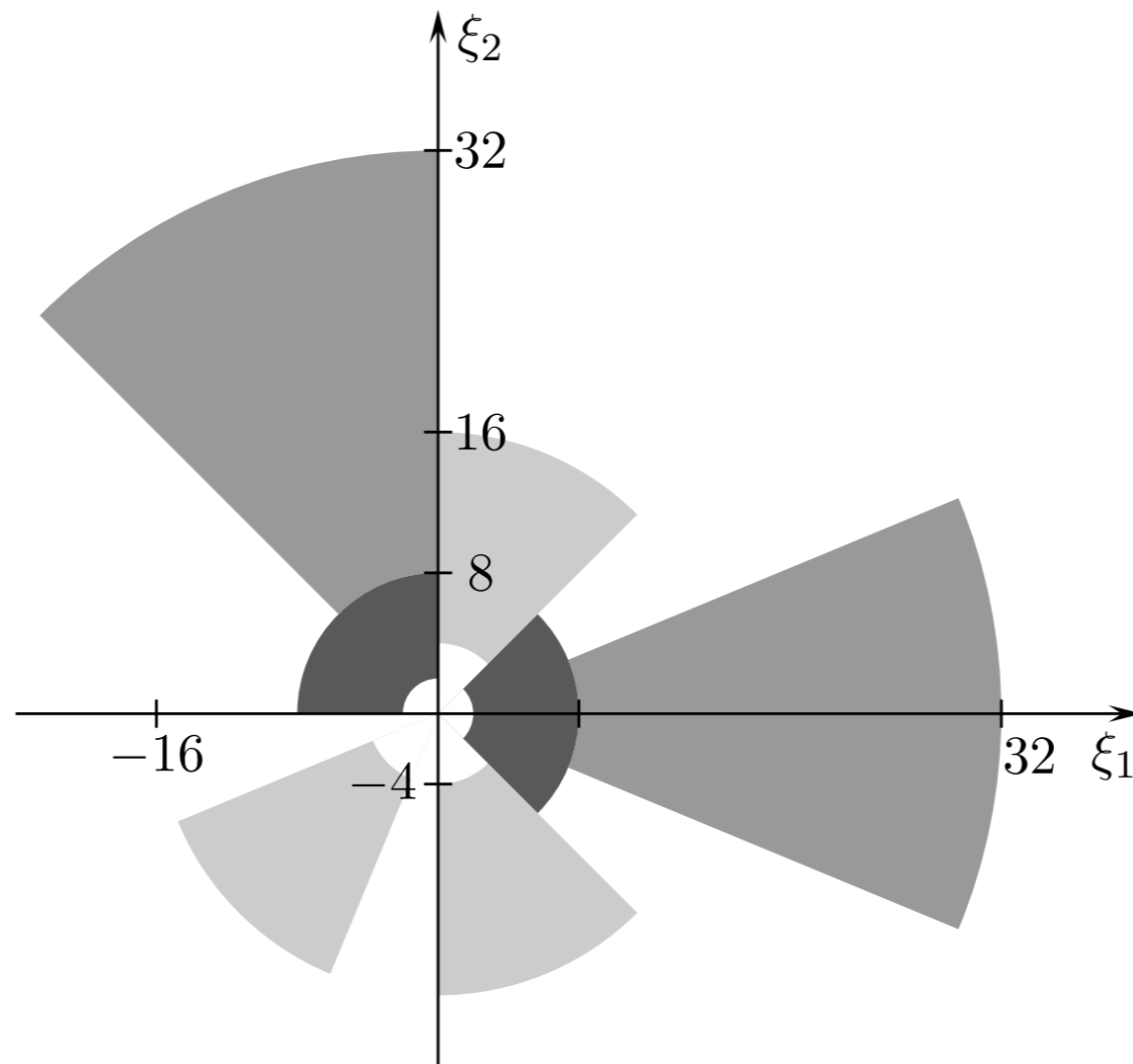


support of $\hat{\psi}_{0,0,0}$

The window V_N is obtained by 2π -periodization of $V(N\sigma/2\pi)$.

With the windows taken above, we have only a small overlap of supports.

Maximal supports of $\hat{\psi}_{2,k,0}$ and $\hat{\psi}_{2,k,5}$ (dark grey); of $\hat{\psi}_{3,k,6}$ and $\hat{\psi}_{3,k,13}$ (light grey); and of $\hat{\psi}_{4,k,0}$ and $\hat{\psi}_{4,k,11}$ (grey). The translation $k \in Z^2$ does not influence the support of the curve let elements.

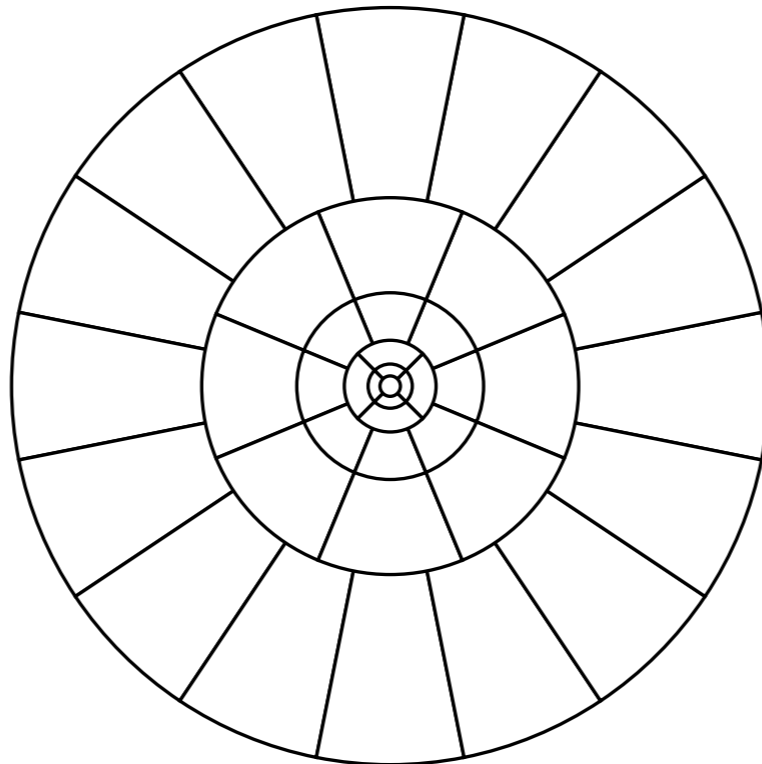


Can we do something else ?

- The window V_N is a low-pass-filter. Any one-dimensional scaling function ϕ (being suitable localized in time and frequency) can serve as the window V and leads to V_{N_j} by 2π -periodization of $\phi(N_j\sigma/2\pi)$.
- The window W is a high-pass filter. Any one-dimensional wavelet function ψ (being suitable localized in time and frequency) can serve as the window W .

How many wedges should be taken in one circular ring ?

- For curvelet construction, choose $N_j = 4 \cdot 2^{\lceil j/2 \rceil}$ wedges in the circular ring with $2^{j-1/2} \leq r \leq 2^{j+1/2}$ (scale 2^{-j}).
- If the number of wedges in a fixed way leads to steerable wavelets.
- If the number of wedges increases like $1/\text{scale}$ (like 2^j), we obtain ridgelets.
- If the number of wedges increases like $\sqrt{1/\text{scale}}$, we obtain curvelets.



The complete set of curvelet elements

We employ rotations and translations of the dilated basic curvelet $\psi_{j,0,0}$. We choose

a) $N_j = 4 \cdot 2^{\lceil j/2 \rceil}$ equidistant rotation angles at level j

$$\theta_{j,l} := \frac{2\pi l}{N_j}, \quad l = 0, \dots, N_j - 1.$$

b) the positions

$$\mathbf{b}_{\mathbf{k}}^{j,l} = \mathbf{b}_{k_1, k_2}^{j,l} := \mathbf{R}_{\theta_{j,l}}^{-1} \left(\frac{k_1}{2^j}, \frac{k_2}{2^{j/2}} \right)^T$$

with $k_1, k_2 \in \mathbb{Z}$, \mathbf{R}_{θ} rotation matrix with angle θ . Then the family of curvelet functions is given by

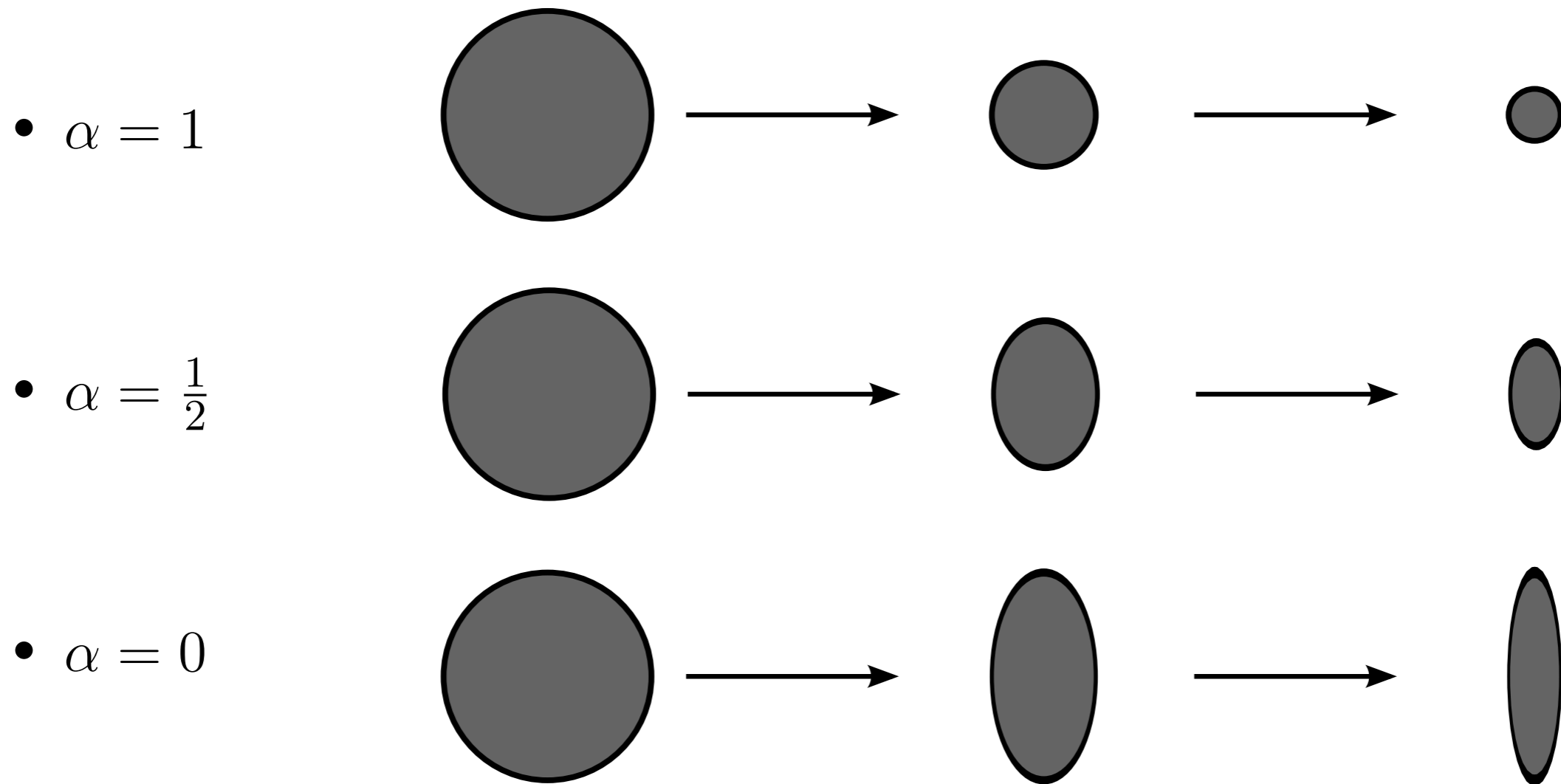
$$\psi_{j,k,l}(\mathbf{x}) := \psi_{j,0,0}(\mathbf{R}_{\theta_{j,l}}(\mathbf{x} - \mathbf{b}_{\mathbf{k}}^{j,l})) = \psi_{0,0,0}(\mathbf{A}_{2,2}^j \mathbf{R}_{\theta_{j,l}} \mathbf{x} - \mathbf{k})$$

with

$$\mathbf{A}_{2,2}^j = \begin{pmatrix} 2^j & 0 \\ 0 & 2^{\lceil j/2 \rceil} \end{pmatrix}.$$

General directional representation systems (Grohs et al. '14)

- α -scaling matrix: $\mathbf{A}_{\alpha,s} = \begin{pmatrix} s & 0 \\ 0 & s^\alpha \end{pmatrix}$, $s \in \mathbb{R}_+$, $\alpha \in [0, 1]$



Directional Representation Systems

Basic ingredients. Take a “mother wavelet” $g \in L^2(\mathbb{R}^2)$ and consider

- **Translation**

$$g \rightarrow g(\cdot - p), \quad p \in \Lambda \subset \mathbb{R}^2$$

- **Scaling**

$$g \rightarrow g(\mathbf{A}_{\alpha,s}\cdot), \quad \mathbf{A}_{\alpha,s} = \begin{pmatrix} s & 0 \\ 0 & s^\alpha \end{pmatrix}, \quad s \in \mathbb{R}_+$$

- **Orientation**

Rotation: $g \rightarrow g(\mathbf{R}_\theta\cdot), \quad \mathbf{R}_\theta = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}, \quad \theta \in [0, 2\pi).$

Shears: $g \rightarrow g(\mathbf{S}_a\cdot), \quad \mathbf{S}_a = \begin{pmatrix} 1 & a \\ 0 & 1 \end{pmatrix} \text{ or } \mathbf{S}_a = \begin{pmatrix} 1 & 0 \\ a & 1 \end{pmatrix} \quad a \in \mathbb{R}.$

We obtain

$$\psi_{s,\theta,p}(x) = s^{(1+\alpha)/2} g(\mathbf{A}_{\alpha,s}\mathbf{R}_\theta(x - p)).$$

Directional Representation Systems

- Ridgelets (Candes, Donoho '99): Rotations, $s = 2$, $\alpha = 0$
- Curvelets (Candes, Donoho '03): Rotations, $s = 2$, $\alpha = 1/2$
- Shearlets (Kutyniok, Labate '06): Shearings, $s = 2$, $\alpha = 1/2$
- α -Shearlets (Kutyniok et al. '12): Shearings $s > 0$, $\alpha \in [0, 1]$
- α -Curvelets (Grohs et al. '14): Rotations $s > 0$, $\alpha \in [0, 1]$

Common framework \rightarrow α -Molecules (Grohs et al. '14)

Our publications

- Jianwei Ma, Gerlind Plonka.
The curvelet transform: A review of recent applications.
IEEE Signal Processing Magazine 27(2) (March 2010), 118-133.
- Jianwei Ma, Gerlind Plonka.
Computing with Curvelets: From Image Processing to Turbulent Flows.
Computing in Science and Engineering 11(2) (2009), 72-80.

\thankyou