# A $q$-analogue of Graham, Hoffman and Hosoya's Theorem 

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#### Abstract

Graham, Hoffman and Hosoya gave a very nice formula about the determinant of the distance matrix $D_{G}$ of a graph $G$ in terms of the distance matrix of its blocks. We generalize this result to a $q$-analogue of $D_{G}$. Our generalization yields results about the equality of the determinant of the mod-2 (and in general mod- $k$ ) distance matrix (i.e. each entry of the distance matrix is taken modulo 2 or $k$ ) of some graphs. The mod- 2 case can be interpreted as a determinant equality result for the adjacency matrix of some graphs.


## 1 Introduction

Graham and Pollak (see [3]) considered the distance matrix $D_{T}=\left(d_{u, v}\right)$ of a tree $T=(V, E)$. For $u, v \in V$, its distance $d_{u, v}$ is the length of a shortest (in this case unique) path between $u$ and $v$ in $T$ and since any tree is connected, all entries $d_{u, v}$ are finite. Let $D_{T}$ be the distance matrix of $T$ with $|V|=n$. They showed a surprising result that $\operatorname{det}\left(D_{T}\right)=(-1)^{n-1}(n-1) 2^{n-2}$. Thus, the determinant of $D_{T}$ only depends on $n$, the number of vertices of $T$ and is independent of $T$ 's structure.

Graham, Hoffman and Hosoya [2] proved a very attractive theorem about the determinant of the distance matrix $D_{G}$ of a strongly connected digraph $G$ as a function of the distance matrix of its 2 -connected blocks (also called blocks). Denote the sum of the cofactors of a matrix $A$ as cofsum $(A)$. Graham, Hoffman and Hosoya (see [2]) showed the following.

Theorem 1 If $G$ is a strongly connected digraph with 2-connected blocks $G_{1}, G_{2}, \ldots, G_{r}$, then $\operatorname{cofsum}\left(D_{G}\right)=\prod_{i=1}^{r} \operatorname{cofsum}\left(D_{G_{i}}\right)$ and $\operatorname{det}\left(D_{G}\right)=\sum_{i=1}^{r} \operatorname{det}\left(D_{G_{i}}\right) \prod_{j \neq i} \operatorname{cofsum}\left(D_{G_{j}}\right)$.

Since all the $(n-1)$ blocks of any tree $T$ on $n$ vertices are $K_{2}$ 's, we can recover Graham and Pollak's result from Theorem 1 Yan and Yeh [5] showed a similar "tree structure independent"
result for the problem of counting the number of signed permutations with a fixed number $k$ as the Spearman measure where distances are induced from an underlying tree $T$.

Bapat et al [1] obtained a $q$-analogue of Graham and Pollak's result and Sivasubramanian [4] obtained a $q$-analogue of Theorem 1 for the case when all the blocks of a graph are triangles. In this present work, we show a $q$-analogue of Theorem 1

### 1.1 The $q$-analogue

For a strongly connected digraph $G=(V, E)$, the $q$-analogue of its distance matrix $q D_{G}$ is obtained from its distance matrix $D_{G}$ by replacing all positive entries $i$ by $[i]_{q}=1+q+\cdots+q^{i-1}$ where $q$ is an indeterminate and $[0]_{q}=0$. Let the distance between vertices $u$ and $v$ in $G$ be denoted as $d_{u, v}$ and let the cofactor matrix (see Section 2 for definitions) of $q D_{G}$ be $\mathrm{qCOF}_{G}=$ $\left(c_{u, v}\right)$. Let the rowsum of $\mathrm{qCOF}_{G}$ corresponding to row $v$ be rsum ${ }_{v}$. Given $\mathbf{w} \in V$, consider the weighted cofactor sum defined as qcofsum ${ }_{G}^{\mathrm{w}}=\sum_{v \in G} q^{d_{v, w}}{ }^{\mathrm{r}}$ rsum $_{v}$. We note that setting $q=1$ gives qcofsum ${ }_{G}^{\mathrm{w}}=\sum_{u, v} c_{u, v}$ which is the sum of the cofactors as used in [2] and that this sum is independent of $\mathbf{w}$. In Lemma3, we show that qcofsum ${ }_{G}^{\mathrm{w}}$ is independent of $\mathbf{w}$ (and hence can be denoted as qcofsum ${ }_{G}$ ). In Subsection 3.1 we prove the following $q$-analogue of Graham, Hoffman and Hosoya's result.

Theorem 2 Let $G$ be a strongly connected digraph with distance matrix $D_{G}$. Let the $q$-analogue of $D_{G}$ be $q D_{G}$ and let $G$ have blocks $G_{1}, G_{2}, \ldots, G_{r}$. For each $1 \leqslant i \leqslant r$, let the distance matrix of $G_{i}$ and its $q$-analogue be $D_{G_{i}}$ and $q D_{G_{i}}$ respectively. Then,

1. qcofsum $_{G}=\prod_{i=1}^{r}$ qcofsum $_{G_{i}}$
2. $\operatorname{det}\left(q D_{G}\right)=\sum_{i=1}^{r} \operatorname{det}\left(q D_{G_{i}}\right) \prod_{j \neq i} q_{\operatorname{cofsum}}^{G_{j}}$.

Thus, we show a polynomial generalisation of Graham, Hoffman and Hosoya's Theorem. We also prove a similar polynomial generalisation - when two $n \times n$ matrices $M_{1}, M_{2}$ have the same determinant, then replacing all the entries of both matrices by twice (or any scalar times) its original value clearly still gives two different matrices (say $M_{1}^{\prime}, M_{2}^{\prime}$ ) also with the same determinant value. For distance matrices, we show in Subsection 3.3 that replacing each entry by a "two-times" polynomial (and more generally by a " $k$-times" polynomial, where $k$ is a positive integer) again gives identical determinant values as polynomials.

Consider the mod-2 distance matrix of a graph, where only the parity of each entry of the distance matrix is used. We show that if two graphs $G_{1}, G_{2}$ have an identical multiset of isomorphic blocks, then the mod-2 distance matrices of $G_{1}$ and $G_{2}$ have the same determinant value, independent of the tree-like connection of their blocks. This shows that the adjacency matrix of several graphs have the same determinant value.

More generally for a positive integer $k \geqslant 3$, we first replace all the distance matrix entries by its mod- $k$ values. In the resulting matrix, if we change all entries $i$ (for $0 \leqslant i<k$ ) to $1+\zeta+\zeta^{2}+\cdots+\zeta^{i-1}$, where $\zeta$ is a primitive $k$-th root of unity, then the determinant of this (complex) matrix is again independent of the tree structure on the blocks of $G$. Subsection 3.2 contains these results.

## 2 Preliminaries

In this section, we note a few linear algebraic preliminaries that we will need for the proof of Theorem 2 All our vectors will be column vectors and given an $n \times p$ matrix $A$, we denote its transpose by $A^{t}$. For a square matrix $A$, $\operatorname{det}(A)$ denotes its determinant.

Given an $n \times n$ matrix $A$, its row and column indices begin with 1 and we denote its $i$-th row (for $1 \leqslant i \leqslant n$ ) by $\operatorname{Row}_{i}$ and its $j$-th column (for $1 \leqslant j \leqslant n$ ) by $\mathrm{Col}_{j}$. It is convenient for determinant calculations to represent some combinations of elementary row and column operations on $A$ by multiplications of the following $n \times n$ matrices:

$$
R=\left(\begin{array}{cccc}
1 & 0 & \cdots & 0 \\
\alpha_{2} & 1 & \cdots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
\alpha_{n} & 0 & \cdots & 1
\end{array}\right) \text { and } C=\left(\begin{array}{cccc}
1 & \beta_{2} & \cdots & \beta_{n} \\
0 & 1 & \cdots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
0 & 0 & \cdots & 1
\end{array}\right)
$$

It follows that $R A C$ is the result of the following elementary row and column operations on $A$ performed in any order: $\operatorname{Row}_{i}:=\operatorname{Row}_{i}+\alpha_{i} \operatorname{Row}_{1}$ and $\operatorname{Col}_{i}:=\operatorname{Col}_{i}+\beta_{i} \operatorname{Col}_{1}$ for $2 \leqslant i \leqslant n$.

Given an $n \times n$ matrix $A$ and $n \times 1$ vectors $\rho$ and $\tau$, we will need to find $\operatorname{det}\left(A+x \rho \tau^{t}\right)$ where $x$ is a fresh variable, not occurring in $A, \tau$ or $\rho$. We will restrict attention to vectors $\rho, \tau$ where both $\rho_{1} \neq 0$ and $\tau_{1} \neq 0$. Let $\mathrm{cA}=\left(A_{i, j}\right)$ be the cofactor matrix of $A$ with $A_{i, j}$ for $1 \leqslant i, j \leqslant n$ denoting the cofactor at position $(i, j)$. Specifically, $A_{i, j}$ is $(-1)^{i+j}$ times the determinant of the submatrix of $A$ obtained by deleting $\mathrm{Row}_{i}$ and $\mathrm{Col}_{j}$. Lastly, define $C_{\rho, \tau}(\mathrm{cA})=\rho^{t} \mathrm{cA} \tau$.
Lemma 1 The coefficient of $x$ in $\operatorname{det}\left(A+x \rho \tau^{t}\right)$ is $C_{\rho, \tau}(\mathrm{cA})$
Proof: The coefficient of $x$ in $\operatorname{det}\left(A+x \rho \tau^{t}\right)$ is $\sum_{i, j} \rho_{i} \tau_{j} A_{i, j}$. (This follows by observing that the only way to get an $x$ in the determinant expansion is to choose $x \rho_{i} \tau_{j}$ from the $i$-th row and $j$-th column and non- $x$ terms from other rows and columns.)

Let $\tilde{A}$ be obtained from an $n \times n$ matrix $A$ by performing $\operatorname{Row}_{i}:=\operatorname{Row}_{i}-\frac{\rho_{i}}{\rho_{1}} \operatorname{Row}_{1}$ for $2 \leqslant i \leqslant n$ and then performing $\operatorname{Col}_{i}:=\operatorname{Col}_{i}-\frac{\tau_{i}}{\tau_{1}} \operatorname{Col}_{1}$. Let

$$
R=\left(\begin{array}{cccc}
1 & 0 & \cdots & 0 \\
-\frac{\rho_{2}}{\rho_{1}} & 1 & \cdots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
-\frac{\rho_{n}}{\rho_{1}} & 0 & \cdots & 1
\end{array}\right) \text { and } C=\left(\begin{array}{cccc}
1 & -\frac{\tau_{2}}{\tau_{1}} & \cdots & -\frac{\tau_{n}}{\tau_{1}} \\
0 & 1 & \cdots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
0 & 0 & \cdots & 1
\end{array}\right)
$$

Celarly, $\tilde{A}=R A C$. We will use the matrices $R$ and $C$ again in this work and though they depend on the vectors $\rho$ and $\tau$, instead of using a more correct subscripted notation $R_{\rho}$ and $C_{\tau}$, we will define vectors $\rho$ and $\tau$ and only then use $R, C$. In our proof of Theorem 2 we will apply this notation to cases with $A=q D_{G}$ and with $A$ being each of two principal submatrices of $q D_{G}$ with only index 1 in common; vertex 1 will be the separator between one block and the rest of the graph $G$. In each of these three cases, the vertices of the appropriate subgraph of $G$ will be labelled by the indices of $A, R, C, c \mathrm{~A}, \rho$ and $\tau$ and these indices are used in the multiplications defining $C_{\rho, \tau}(\mathrm{cA})=\rho^{t} \mathrm{c} \mathrm{A} \tau$ and $\tilde{M}=R M C$ (for $M=A$ and others). The common vertex has index 1 . In all cases, the cofactor of $\tilde{A}$ at position $(1,1)$ is denoted by $\tilde{A}_{1,1}$.

Lemma $2 \rho_{1} \tau_{1} \widetilde{A}_{1,1}=C_{\rho, \tau}(\mathrm{cA})$.
Proof: $\quad$ Since $R$ and $C$ have determinant 1 , $\operatorname{det}\left(A+x \rho \tau^{t}\right)=\operatorname{det}\left(R\left(A+x \rho \tau^{t}\right) C\right)=$ $\operatorname{det}(R A C+M)=\operatorname{det}(\tilde{A}+M)$, where

$$
M=\left(\begin{array}{ccc}
x \rho_{1} \tau_{1} & \cdots & 0 \\
0 & \cdots & 0 \\
\vdots & \ddots & \vdots \\
0 & \cdots & 0
\end{array}\right)
$$

Therefore, the coefficient of $x$ in $\operatorname{det}\left(A+x \rho \tau^{t}\right)$ is $\rho_{1} \tau_{1} \widetilde{A}_{1,1}$. The proof is complete by combining with Lemma

## 3 The $q$-analogue

### 3.1 Proofs of results

With the notation of Section we begin with the Lemma below.
Lemma 3 For vertices $u_{1}, u_{2} \in G, u_{1} \neq u_{2}$, qcofsum ${ }_{G}^{u_{1}}=\operatorname{qcofsum}_{G}^{u_{2}}$. Thus, qcofsum ${ }_{G}^{v}$ is independent of the vertex $v$. Further, for all $u \in G$, qcofsum ${ }_{G}^{u}=(q-1) \operatorname{det}\left(q D_{G}\right)+\operatorname{cofsum}\left(q D_{G}\right)$, where cofsum $\left(q D_{G}\right)=\sum_{u, v} c_{u, v}$ is the sum of the cofactors of $q D_{G}$.

Proof: We recall that $q D_{G}$ is the $q$-analogue of the distance matrix $D_{G}=\left(d_{u, v}\right)$ of $G$ and $\mathrm{qCOF}_{G}=\left(c_{u, v}\right)$ is the cofactor matrix of $q D_{G}$. For two vertices $u, v \in G, d_{u, v}$ is the distance between them and $\left[d_{u, v}\right]_{q}=1+q+q^{2}+\cdots+q^{d_{u, v}-1}$. Let rsum ${ }_{v}$ be the row-sum of $\mathrm{qCOF}_{G}$ corresponding to row $v$ and for a vertex $u$, qcofsum ${ }_{G}^{u}=\sum_{v} q^{d_{v, u}}$ rsum $_{v}$

Elementary properties of the determinant and the adjugate imply for all vertices $u \in G$, $\operatorname{det}\left(q D_{G}\right)=\sum_{v \in G}\left[d_{v, u}\right]_{q} \cdot c_{v, u}=\sum_{v \in G}\left[d_{v, u}\right]_{q} \cdot$ rsum $_{v}$. Thus,

$$
\begin{aligned}
(q-1) \operatorname{det}\left(q D_{G}\right) & =\sum_{v \in G}(q-1)\left[d_{v, u}\right]_{q} \cdot \operatorname{rsum}_{v} \\
& =\sum_{v \in G}\left(q^{d_{v, u}}-1\right) \cdot \operatorname{rsum}_{v} \\
& =\operatorname{qcofsum}{ }_{G}^{u}-\operatorname{cofsum}\left(q D_{G}\right)
\end{aligned}
$$

This completes the proof.
For simplicity, $d_{i, j}$ denotes $d_{v_{i}, v_{j}}$ for vertices $v_{i}, v_{j}$ in any graph and sometimes, the index $i$ will be identified with vertex $v_{i}$. Lemma 3 can be stated in the following alternate way. For a strongly connected digraph $G$, let $\mathrm{ED}_{G}=\left(e_{u, v}\right)$ be its exponential distance matrix defined as $e_{u, v}=q^{d_{u, v}}$ where $d_{u, v}$ is the distance between $u$ and $v, q$ is an indeterminate and $q^{0}=1$.

Corollary 1 Consider the matrix $M_{G}=\mathrm{ED}_{G}^{t} \cdot \mathrm{qCOF}_{G}$. The all-ones vector $\mathbb{1}$, of dimension $|V(G)| \times 1$ is an eigenvector of $M_{G}$ corresponding to eigenvalue qcofsum ${ }_{G}$.

Proof: Let RS be the $|V(G)| \times 1$ vector with $\mathrm{RS}_{v}=\operatorname{rsum}_{v}$. Clearly, $\mathrm{qCOF}_{G} \cdot \mathbb{1}=\mathrm{RS}$ and $\left(\mathrm{ED}_{G}^{t} \cdot \mathrm{RS}\right)_{v}=\sum_{u} q^{d_{u, v}} \mathrm{rsum}_{u}=$ qcofsum $_{G}$. The proof follows.

We note the following lemma similar to the lemma in [2]. We recall the $q$-weighted cofactor
 is independent of $j$, we fix $j=1$ and write $\operatorname{cofsum}_{G}=\operatorname{cofsum}_{G}^{j}$. We will use Lemma2 with

$$
\begin{equation*}
A=q D_{G}, \rho^{t}=\left[1, q^{d_{2,1}}, q^{d_{3,1}}, \ldots, q^{d_{n, 1}}\right] \text { and } \tau^{t}=\mathbb{1} \tag{1}
\end{equation*}
$$

These values for the $\rho_{i}$ 's and the $\tau_{i}$ 's define the matrices $R, C$ and thus $\widetilde{q D_{G}}$. It is simple to see from the definition that qcofsum ${ }_{G}=\mathrm{qcofsum}_{G}^{1}=C_{\rho, \tau}\left(\mathrm{qCOF}_{G}\right)$, where we recall $C_{\rho, \tau}\left(\mathrm{qCOF}_{G}\right)=\rho^{t}\left(\mathrm{qCOF}_{G}\right) \tau$. The following lemma gives the cofactor of $q \tilde{D}_{G}$ at position $(1,1)$.
Lemma 4 With the above notation, $C_{\rho, \tau}\left(\mathrm{qCOF}_{G}\right)=\widetilde{\left(q D_{G}\right)_{1,1}}$.
Proof: Follows from Lemma 2 by noting $\rho_{1}=\tau_{1}=1$.
Proof: (Of Theorem 2) Pairs of distinct blocks have at most one vertex in common; the common vertex joining two adjacent blocks is called a cut-vertex. Among the blocks of $G$, let $H$ be a block which has only one cut-vertex. We call such blocks as leaf-blocks. Clearly, leaf-blocks exist and let $H$ be a leaf block connected to the rest of $G$ along a cut-vertex. Let us label the vertices so that this cut-vertex is labelled by 1 , so when $v_{i}$ denotes a vertex of $H$ and $u_{j}$ denotes a vertex of $G^{\prime}, v_{1}=u_{1}=1$ denotes this cut-vertex in $G$. We recall the cofactor matrix $\mathrm{qCOF}_{H}=\left(c_{u, v}^{H}\right)$ of $q D_{H}$, and the $q$-weighted cofactor sum qcofsum ${ }_{H}$ defined above.

Let $|H|=k$ and $V(H)=\left\{1, v_{2}, \ldots, v_{k}\right\}$. We recall $G^{\prime}=G-(H-\{1\})$, and if $\left|G^{\prime}\right|=r$, let $V\left(G^{\prime}\right)=\left\{1, u_{2}, \ldots, u_{r}\right\}$. Let us introduce the following notation. Row vector $\overline{[a]_{q}}=$ $\left(\left[a_{2}\right]_{q}, \ldots,\left[a_{k}\right]_{q}\right)$, row vector $\overline{[f]_{q}}=\left(\left[f_{2}\right]_{q}, \ldots,\left[f_{r}\right]_{q}\right)$, column vector $\overline{[b]_{q}}=\left(\left[b_{2}\right]_{q}, \ldots,\left[b_{k}\right]_{q}\right)^{t}$ and column vector $\overline{[g]_{q}}=\left(\left[g_{2}\right]_{q}, \ldots,\left[g_{r}\right]_{q}\right)^{t}$. We also use $(M(i, j))$ to denote the matrix with entries $M(i, j)$ and various ranges of indices. We now verify that given the following block decompositions

$$
q D_{H}=\left(\begin{array}{cc}
0 & \overline{[a]_{q}} \\
\overline{[b]_{q}} & P
\end{array}\right) \text { and } q D_{G^{\prime}}=\left(\begin{array}{cc}
0 & \overline{[f]_{q}} \\
\overline{[g]_{q}} & Q
\end{array}\right)
$$

we can express

$$
q D(G)=\left(\begin{array}{c|c|c}
0 & \overline{[a]_{q}} & \overline{[f]_{q}} \\
\overline{[b]_{q}} & P & \left(\left[b_{i}\right]_{q}+q^{b_{i}}\left[f_{j}\right]_{q}\right) \\
\hline[g]_{q} & \left(\left[g_{i}\right]_{q}+q^{g_{i}}\left[a_{j}\right]_{q}\right) & Q
\end{array}\right)
$$

We must verify that $\left[d_{i, j}\right]_{q}=\left[b_{i}\right]_{q}+q^{b_{i}}\left[f_{j}\right]_{q}$ when $v_{i}, i \neq 1$ is a vertex of $H$ and $v_{j}, j \neq 1$ is a vertex of $G^{\prime}$. Consider such a pair of vertices. Since $v_{1}$ is a cut-vertex separating $H$ and $G^{\prime}$,
the distances satisfy $d_{i, j}=d_{i, 1}+d_{1, j}$ It follows from the fact that $[n+m]_{q}=[n]_{q}+q^{n}[m]_{q}$ that $\left[d_{i, j}\right]_{q}=\left[d_{i, 1}\right]_{q}+q^{d_{i, 1}}\left[d_{1, j}\right]_{q}$. However, by the block decomposition of $q D_{H},\left[d_{i, 1}\right]_{q}=\left[b_{i}\right]_{q}$; and by the block decomposition of $q D_{G^{\prime}},\left[d_{1, j}\right]_{q}=\left[f_{j}\right]_{q}$. We verify in the same manner that $\left[d_{i, j}\right]_{q}=\left[d_{i, 1}\right]_{q}+q^{g_{i}}\left[a_{j}\right]_{q}$ when $i \neq 1$ labels a vertex of $G^{\prime}$ and $j \neq 1$ labels a vertex of $H$.

As operation ${ }^{\sim}$ preserves determinant, and by definition of $\widetilde{\left(q D_{G^{\prime}}\right)_{1,1}}$ and $\widetilde{\left(q D_{H}\right)_{1,1}}$, we have

$$
\begin{aligned}
& \operatorname{det}\left(q D_{G}\right)=\operatorname{det}\left(R \cdot q D_{G} \cdot C\right)=\operatorname{det}\left(\begin{array}{c|c|c}
\frac{0}{[b]_{q}} & P-\left(\left[b_{i}\right]_{q}+q^{b_{i}}\left[a_{j}\right]_{q}\right) & \overline{[f]_{q}} \\
\overline{[g]_{q}} & 0 & 0 \\
Q-\left(\left[g_{i}\right]_{q}+q^{g_{i}}\left[f_{j}\right]_{q}\right)
\end{array}\right) \\
& =\operatorname{det}\left(\begin{array}{c|c}
0 \\
{[b]_{q}} & \overline{[a]_{q}} \\
P-\left(\left[b_{i}\right]_{q}+q^{b_{i}}\left[a_{j}\right]_{q}\right)
\end{array}\right) \cdot \operatorname{det}\left(Q-\left(\left[g_{i}\right]_{q}+q^{g_{i}}\left[f_{j}\right]_{q}\right)\right) \\
& +\operatorname{det}\left(\begin{array}{c|c}
0 & \overline{[f]_{q}} \\
{[g]_{q}} & Q-\left(\left[g_{i}\right]_{q}+q^{g_{i}}\left[f_{j}\right]_{q}\right)
\end{array}\right) \cdot \operatorname{det}\left(P-\left(\left[b_{i}\right]_{q}+q^{b_{i}}\left[a_{j}\right]_{q}\right)\right) \\
& =\operatorname{det}\left(\widetilde{q D_{H}}\right) \cdot \widetilde{\left(q D_{G^{\prime}}\right)_{1,1}}+\operatorname{det}\left(\widetilde{q D_{G^{\prime}}}\right) \cdot \widetilde{\left(q D_{H}\right)_{1,1}} \\
& =\operatorname{det}\left(q D_{H}\right) \cdot \operatorname{qcofsum}_{q D_{G^{\prime}}}+\operatorname{det}\left(q D_{G^{\prime}}\right) \cdot \operatorname{qcofsum}_{q D_{H}}
\end{aligned}
$$

where the last line follows from Lemma 4 with the observation that $\rho, \tau$ restricted to the vertices of $H, G^{\prime}$ are as in Equation with the dimensions of the restrictions of $\rho, \tau$ matching that of either $A=q D_{H}$ or $A=q D_{G^{\prime}}$. Using Lemma 4 again, we note that

$$
\begin{aligned}
\operatorname{qcofsum~}_{q D_{G}} & =\operatorname{det}\left(\begin{array}{c}
P-\left(\left[b_{i}\right]_{q}+q^{b_{i}}\left[a_{j}\right]_{q}\right) \\
0
\end{array} \left\lvert\, \begin{array}{c}
0 \\
\\
\\
=\operatorname{det}\left(P-\left(\left[\left[g_{i}\right]_{q}+q^{g_{i}}\left[f_{j}\right]_{q}\right)\right.\right.
\end{array}\right.\right) \\
& \left.\left.=\widetilde{\left(q D_{H}\right]_{q}+q^{b_{i}}}\left[a_{j}\right]_{q}\right)\right) \cdot \operatorname{det}\left(Q-\left(\left[g_{i}\right]_{q}+q^{g_{i}}\left[f_{j}\right]_{q}\right)\right) \\
& =\operatorname{qcofsum}_{q D_{H}} \cdot \text { qcofsum }_{q D_{G^{\prime}}}
\end{aligned}
$$

The proof is complete.
We apply Theorem 2 to obtain a few known corollaries and some new ones as well. When $G=T$ is a tree, each block $G_{i}$ is an edge (i.e. a $K_{2}$ ). It is simple to note that qcofsum $G_{G_{i}}=$ $-(1+q)$ and $\operatorname{det}\left(D_{G_{i}}\right)=-1$. Thus, we get a $q$-analogue of Graham, Hoffman and Hosoya's result first observed by Bapat et. al [1] Corollary 5.2].

Corollary 2 (Corollary 5.2, [1]) When $G$ is a tree on $n$ vertices, then $\operatorname{det}\left(q D_{G}\right)=(-1)^{n-1}(n-$ 1) $(1+q)^{n-2}$.

When each block of $G$, is a 3 -clique(i.e. a $K_{3}$ ), we get

$$
D_{G_{i}}=\left(\begin{array}{lll}
0 & 1 & 1 \\
1 & 0 & 1 \\
1 & 1 & 0
\end{array}\right)
$$

thus qcofsum $G_{i}=(1+2 q)$ and $\operatorname{det}\left(D_{G_{i}}\right)=2$. From this, we recover the following result of Sivasubramanian [4]. More generally, when each block of $G$ is an $r$-clique (ie $K_{r}$ ), then $D_{G_{i}}=$ $J-I$, where $J$ is the matrix of all ones and $I$ is the identity matrix, both of dimension $r \times r$. It is simple to check that qcofsum $G_{G_{i}}=(-1)^{r-1}[1+(r-1) q]$ and $\operatorname{det}\left(D_{G_{i}}\right)=(-1)^{r-1}(r-1)$.

Corollary 3 Let $G$ have $k$ blocks all of which are $r$-cliques (thus, $G$ has $n=(r-1) k+1$ vertices).

- When $r=3$, $\operatorname{det}\left(q D_{G}\right)=2 k(1+2 q)^{k-1}$. ( 4 Corollary 3].)
- More generally for any $r, \operatorname{det}\left(q D_{G}\right)=(-1)^{n-1}[(r-1) \cdot k][1+(r-1) q]^{k-1}$.


### 3.2 Mod $k$ distances, setting values to $q$

In this subsection, by setting values to $q$, we get a few pleasing corollaries about some modifications of the distance matrix of graphs, some of which seem non obvious.

If we set $q=-1$, then it is easy to check that for odd $i,[i]_{q}=1$ and for even $i,[i]_{q}=0$. Let $G$ be a connected graph with distance matrix $D_{G}$ and let $q D_{G}$ be the $q$-analogue of $D_{G}$. If we set $q=-1$ in all entries of $q D_{G}$, this operation corresponds to considering the distance matrix $D_{G}$ with all entries modulo 2.

Theorem 3 Let $G$ and $H$ be graphs with an identical multiset of isomorphic blocks (they may differ in the tree structure of the connection among these blocks). Let $D_{G}^{\prime}$ and $D_{H}^{\prime}$ be the mod-2 distance matrices (where all distances are all considered modulo 2) of $G$ and $H$ respectively. Then $\operatorname{det}\left(D_{G}^{\prime}\right)=\operatorname{det}\left(D_{H}^{\prime}\right)$.

Proof: Follows from Theorem 2 by setting $q=-1$.
Corollary 4 Let $G$ be a tree and let $D_{G}^{\prime}$ be its mod-2 distance matrix where all distances are all considered modulo 2. Then $D_{G}^{\prime}$ is singular (ie $\left.\operatorname{det}\left(D_{G}^{\prime}\right)=0\right)$.

We get the following pleasant mod-2 analogue of Corollary 3 for which simple proofs would be interesting.

Corollary 5 Let $G$ be a graph with $k$ blocks, all of which are $r$-cliques (ie $K_{r}$ 's), and let $D_{G}^{\prime}$ be its mod-2 distance matrix (i.e. where each entry is considered modulo 2 ).

- If $r=3, \operatorname{det}\left(D_{G}^{\prime}\right)=2 k(-1)^{k-1}$.
- For a general $r, \operatorname{det}\left(D_{G}^{\prime}\right)=(r-1) k(-r)^{n+k-2}$.

Remark 1 Theorem 3 answers the following question. Akin to determinant of the distance matrices of some graphs being equal, are there graphs such that the determinant of their adjacency matrices are identical? Since a mod-2 distance matrix has 0-1 entries, Theorem 3 gives families of graphs whose adjacency matrices have the same determinant. It would be interesting to see if there is some structure or some description of all or even a subset of the graphs which arise in this mod-2 manner from the distance matrix of graphs having an identical multiset of isomorphic blocks.

Just as we set the value $q=-1$, we set other values to $q$ and get further corollaries. The following corollary was suggested by the referee. For a positive integer $k$, let $\zeta$ be a primitive $k$-th root of unity. Clearly setting $q=\zeta$ corresponds to the following operation: replace each positive entry $i$ in the distance matrix of $G$ by $1+\zeta+\cdots+\zeta^{(i \bmod k)-1}$. Setting $q=-1$ corresponds to this operation with $k=2$. Thus, we get the following.
Corollary 6 Let $G$ and $H$ be graphs with an identical multiset of isomorphic blocks (they may differ in the tree structure of the connection among these blocks). For any fixed positive integer $k$, let $\zeta$ be a primitive $k$-th root of unity. Let $D_{G}^{\prime}$ and $D_{H}^{\prime}$ be the mod- $k$ distance matrices of $G$ and $H$ respectively, where all positive distances $i$ are replaced by $1+\zeta+\cdots+\zeta^{i-1}$. Then $\operatorname{det}\left(D_{G}^{\prime}\right)=\operatorname{det}\left(D_{H}^{\prime}\right)$.

## $3.3[k d]_{q}$-analogues

In this subsection, for any positive integer $k$, we consider $k D_{q}$ analogues of $D$, where we replace positive integers $i$ in $D$ by $[k i]_{q}=1+q+q^{2}+\cdots+q^{k i-1}$. Thus, we replace all entries $[i]_{q}$ in $q D_{G}$ by $[k i]_{q}$ to get $k D_{q}$. It is easy to see that $[k i]_{q}=\left(1+q^{i}+q^{2 i}+\cdots+q^{(k-1) i}\right)[i]_{q}$. Thus, if we define $[k]_{q^{i}}$ analogously as $1+q^{i}+q^{2 i}+\cdots+q^{(k-1) i}$, we get $[k i]_{q}=[k]_{q^{i}}[i]_{q}$. It can be checked that with weights $q^{k \cdot d_{u, v}}$ multiplying rsum ${ }_{v}$, we get qcofsum ${ }_{k G}^{u}$, independent of vertex $u$. The proofs of all Lemmata and Theorem 2 in Subsection 3.1 go through as before. We omit the details and state the following result for trees in the case $k=2$.

Corollary 7 Let $T$ be a tree on $n$ vertices and let $D$ be its distance matrix. Let $2 D_{q}$ be the polynomial matrix obtained from $D$ by replacing all entries $i$ by $[2 i]_{q}=1+q+q^{2}+\cdots+q^{2 i-1}$. Then, $\operatorname{det}\left(2 D_{q}\right)=(-1)^{n-1}(n-1)(1+q)^{n}\left(1+q^{2}\right)^{n-2}$.
Proof: Follows by observing that for $H=K_{2}$, $\operatorname{det}\left(2 H_{q}\right)=-(1+q)^{2}$ and that qcofsum ${ }_{2 H_{q}}=$ $-\left(1+q^{2}\right)(1+q)$

We end with a question. Just as multiplying all entries of an $n \times n$ matrix by a factor $\alpha$ results in multiplication of its determinant by $\alpha^{n}$, multiplying just the elements of a subset $S$ with $|S|=k$ of the rows by $\alpha$ results in multiplication of its determinant by $\alpha^{k}$. It would be interesting to see if for some distinct trees $T_{1}, T_{2}$, some subsets $S_{1}, S_{2}$ with $\left|S_{1}\right|=\left|S_{2}\right|$ exist such that the $q$-analogue of just the rows of $S_{i}$ in $T_{i}$ can be multiplied to get identical polynomials for the determinant of the distance matrix.

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