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# POSITIVE SOLUTIONS FOR A NONLOCAL BOUNDARY-VALUE PROBLEM WITH INCREASING RESPONSE 

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#### Abstract

We study a nonlocal boundary-value problem for a second order ordinary differential equation. Under a monotonicity condition on the response function, we prove the existence of positive solutions.


## 1. Introduction

When looking for positive solutions of the equation

$$
u^{\prime \prime}(t)+a(t) f(u(t))=0, \quad t \in[0,1],
$$

associated with various boundary conditions the main assumption on the response function $f$ is the existence of the limits of $f(u) / u$, as $u$ approaches 0 and $+\infty$. Existence of solutions under these conditions has been shown, for instance, in [1, $4,5,6,7,11,18]$. Such conditions distinguish two cases: The sublinear case when the limits are $+\infty$ and 0 , and the superlinear case when the limits are 0 and $+\infty$, respectively. In [16] the authors present a detailed investigation of a twwo-point boundary-value problem under similar limiting conditions and they introduce the meaning of the index of convergence.

In this paper, we discuss a general problem with non-local boundary conditions. We avoid the limits above, and therefore weaken the restriction of the function $f$. Instead, we assume that there exist real positive numbers $u, v$ such that $f(u) \geq \rho u$ and $f(v)<\theta v$, where $\rho, \theta$ are prescribed positive numbers. This is a rather weak condition, but we have to pay for it. Indeed, we assume that the function $f$ is increasing (not necessarily strictly increasing). More precisely, we consider the ordinary differential equation

$$
\begin{equation*}
\left(p(t) x^{\prime}\right)^{\prime}+q(t) f(x)=0, \text { a.e. } t \in[0,1] \tag{1.1}
\end{equation*}
$$

with the initial condition

$$
\begin{equation*}
x(0)=0 \tag{1.2}
\end{equation*}
$$

and the non-local boundary condition

$$
\begin{equation*}
x^{\prime}(1)=\int_{\eta}^{1} x^{\prime}(s) d g(s) \tag{1.3}
\end{equation*}
$$

[^0]Here $f: \mathbb{R} \rightarrow \mathbb{R}$ is an increasing function, the real valued functions $p, q, g$ are defined at least on the interval $[0,1]$ and $\eta$ is a real number in the open interval $(0,1)$. Also the integral in (1.3) is meant in the sense of Riemann-Stieljes.

When (1.1) is an equation of Sturm-Liouville type, Il'in and Moiseev [12], motivated by a work of Bitsadze [2] and Bitsadze and Samarskii [3], investigated the existence of solutions of the problem (1.1), (1.2) with the multi-point condition

$$
\begin{equation*}
x^{\prime}(1)=\sum_{i=1}^{m} \alpha_{i} x^{\prime}\left(\xi_{i}\right), \tag{1.4}
\end{equation*}
$$

where the real numbers $\alpha_{1}, \alpha_{2}, \ldots, \alpha_{m}$ have the same sign. The formed boundaryvalue problem (1.1), (1.2), (1.4) was the subject of some recent papers (see, e.g. [9, $10]$ ). Condition (1.3) is the continuous version of (1.4) which happens when $g$ is a piece-wise constant function that is increasing and has a finitely many jumps.

The question of existence of positive solutions of the boundary-value problem (1.1)-(1.3) is justified by the large number of papers. For example one can consult the papers $[1,4,5,6,7,11,18]$ which were motivated by Krasnoselskii [17], who presented a complete theory for positive solutions of operator equations. One of the more powerful tools exhibited in [17] is the following general fixed point theorem. This theorem is an extension of the classical Bolzano-Weierstrass sign theorem for continuous real valued functions to Banach spaces, when the usual order is replaced by the order generated by a cone.
Theorem 1.1. Let $\mathcal{B}$ be a Banach space and let $\mathbb{K}$ be a cone in $\mathcal{B}$. Assume that $\Omega_{1}$ and $\Omega_{2}$ are open subsets of $\mathcal{B}$, with $0 \in \Omega_{1} \subset \overline{\Omega_{1}} \subset \Omega_{2}$, and let

$$
A: \mathbb{K} \cap\left(\Omega_{2} \backslash \overline{\Omega_{1}}\right) \rightarrow \mathbb{K}
$$

be a completely continuous operator such that either

$$
\|A u\| \leq\|u\|, \quad u \in \mathbb{K} \cap \partial \Omega_{1}, \quad\|A u\| \geq\|u\|, \quad u \in \mathbb{K} \cap \partial \Omega_{2}
$$

or

$$
\|A u\| \geq\|u\|, \quad u \in \mathbb{K} \cap \partial \Omega_{1}, \quad\|A u\| \leq\|u\|, \quad u \in \mathbb{K} \cap \partial \Omega_{2} .
$$

Then $A$ has a fixed point in $\mathbb{K} \cap\left(\Omega_{2} \backslash \overline{\Omega_{1}}\right)$.
In the literature, boundary-value problems of the form (1.1)-(1.3) are often solved by using the well known Leray-Schauder Continuation Theorem (see, e.g. [9, 10, 13, 19]), or the Nonlinear Alternative (see, e.g. [8, 15] and the references therein. For another approach see, also, [14]). On the other hand Krasnoselskii's fixed point theorem, when it is applied, it provides some additional properties of the solutions, for instance, positivity (see, e.g. $[1,4,5,6,7,11,14]$ ). However, the more information on the solutions the more restrictions on the coefficients are needed.

## 2. Preliminaries and assumptions

In the sequel we shall denote by $\mathbb{R}$ the real line and by $I$ the interval $[0,1]$. Then $C(I)$ will denote the space of all continuous functions $x: I \rightarrow \mathbb{R}$. Let $C_{0}^{1}(I)$ be the space of all functions $x: I \rightarrow \mathbb{R}$, whose the first derivative $x^{\prime}$ is absolutely
continuous on $I$ and $x(0)=0$. This is a Banach space when it is furnished with the norm defined by

$$
\|x\|:=\sup \left\{\left|x^{\prime}(t)\right|: t \in I\right\}, \quad x \in C_{0}^{1}(I) .
$$

We denote by $L_{1}^{+}(I)$ the space of functions $x: I \rightarrow \mathbb{R}^{+}:=[0,+\infty)$ which are Lebesgue integrable on I.

Consider the system (1.1), (1.2) and the nonlocal-value condition (1.3). By a solution of the problem (1.1)-(1.3) we mean a function $x \in C_{0}^{1}(I)$ satisfying equation (1.1) for almost all $t \in I$ and condition (1.3).

Before presenting our results we give our basic assumptions:
(H1) $f: \mathbb{R} \rightarrow \mathbb{R}$ is an increasing continuous function, with $f(x) \geq 0$, when $x>0$
(H2) The functions $p, q$ belong to $C(I)$ and they are such that $p>0, q \geq 0$ and $\sup \{q(s): \eta \leq s \leq 1\}>0$. Without loss of generality we can assume that $p(1)=1$.
(H3) The function $g: I \rightarrow \mathbb{R}$ is increasing and such that $g(\eta)=0<g(\eta+)$.
(H4) $\int_{\eta}^{1} \frac{1}{p(s)} d g(s)<1$
To search for solutions to problem (1.1)-(1.3), we first re-formulate the problem as an operator equation of the form $x=A x$, for an appropriate operator $A$. To find this operator consider the equation (1.1) and integrate it from $t$ to 1 . Then we derive

$$
\begin{equation*}
x^{\prime}(t)=\frac{1}{p(t)} x^{\prime}(1)+\frac{1}{p(t)} \int_{t}^{1} q(s) f(x(s)) d s . \tag{2.1}
\end{equation*}
$$

Taking into account the condition (1.3) we obtain

$$
x^{\prime}(1)=\int_{\eta}^{1} x^{\prime}(s) d g(s)=x^{\prime}(1) \int_{\eta}^{1} \frac{1}{p(s)} d g(s)+\int_{\eta}^{1} \frac{1}{p(s)} \int_{s}^{1} q(\theta) f(x(\theta)) d \theta d g(s)
$$

and so

$$
x^{\prime}(1)=\alpha \int_{\eta}^{1} \frac{1}{p(s)} \int_{s}^{1} q(\theta) f(x(\theta)) d \theta d g(s),
$$

where

$$
\alpha:=\left(1-\int_{\eta}^{1} \frac{1}{p(s)} d g(s)\right)^{-1} .
$$

Then, from (2.1), we get
$x(t)=\alpha \int_{\eta}^{1} \frac{1}{p(s)} \int_{s}^{1} q(\theta) f(x(\theta)) d \theta d g(s) \int_{0}^{t} \frac{1}{p(s)} d s+\int_{0}^{t} \frac{1}{p(s)} \int_{s}^{1} q(\theta) f(x(\theta)) d \theta d s$.
(Notice that $x(0)=0$.)
This process shows that solving the boundary-value problem (1.1)-(1.3) is equivalent to solve the operator equation $x=A x$ in $C_{0}^{1}(I)$, where $A$ is the operator defined by

$$
\begin{equation*}
A x(t):=\alpha P(t) \int_{\eta}^{1} \Phi(f(x))(s) d g(s)+\int_{0}^{t} \Phi(f(x))(s) d s \tag{2.2}
\end{equation*}
$$

where we have set

$$
P(t):=\int_{0}^{t} \frac{1}{p(s)} d s, t \in I
$$

and

$$
(\Phi y)(t):=\frac{1}{p(t)} \int_{t}^{1} q(s) y(s) d s, \quad t \in I, \quad y \in C(I)
$$

It is clear that $A$ is a completely continuous operator. We set

$$
b_{0}=g(\eta+)(>0) .
$$

The following lemma is the basic tool in the proof of our main result.
Lemma 2.1. If $y \in C(I)$ is a nonnegative and increasing function, then it holds

$$
\int_{\eta}^{1} \Phi(y)(s) d g(s) \geq \lambda b \int_{0}^{1} q(s) y(s) d s, \quad b \in\left[0, b_{0}\right]
$$

where

$$
\lambda:=\frac{\int_{\eta}^{1} q(s) d s}{\int_{0}^{1} q(s) d s}\left(\sup _{s \in I} p(s)\right)^{-1} .
$$

Proof. Since the function $g$ is increasing, for every $b \in\left(0, b_{0}\right]$ we have

$$
\begin{equation*}
g(s) \geq b, \quad s \in(\eta, 1] . \tag{2.3}
\end{equation*}
$$

Hence it follows that

$$
\begin{aligned}
\int_{0}^{1} q(s) y(s) d s & =\int_{0}^{\eta} q(s) y(s) d s+\int_{\eta}^{1} q(s) y(s) d s \\
& \leq y(\eta) \int_{0}^{\eta} q(s) d s+\int_{\eta}^{1} q(s) y(s) d s \\
& \leq \frac{\int_{0}^{\eta} q(s) d s}{\int_{\eta}^{1} q(s) d s} \int_{\eta}^{1} q(s) y(s) d s+\int_{\eta}^{1} q(s) y(s) d s \\
& =\frac{\int_{0}^{1} q(s) d s}{\int_{\eta}^{1} q(s) d s} \int_{\eta}^{1} q(s) y(s) d s
\end{aligned}
$$

Now we use assumption $\left(H_{3}\right)$ and relation (2.3) to obtain that

$$
\begin{aligned}
\int_{0}^{1} q(s) y(s) d s & \leq b^{-1} \frac{\int_{0}^{1} q(s) d s}{\int_{\eta}^{1} q(s) d s} \int_{\eta}^{1} q(s) y(s) g(s) d s \\
& =-b^{-1} \frac{\int_{0}^{1} q(s) d s}{\int_{\eta}^{1} q(s) d s} \int_{\eta}^{1} d\left(\int_{s}^{1} q(\theta) y(\theta) d \theta\right) g(s) \\
& =b^{-1} \frac{\int_{0}^{1} q(s) d s}{\int_{\eta}^{1} q(s) d s} \int_{\eta}^{1} \int_{s}^{1} q(\theta) y(\theta) d \theta d g(s) \\
& \leq(\lambda b)^{-1} \int_{\eta}^{1} \frac{1}{p(s)} \int_{s}^{1} q(\theta) y(\theta) d \theta d g(s) .
\end{aligned}
$$

The proof is complete.
For convenience we set

$$
D:=\int_{\eta}^{1} \Phi(P)(s) d g(s), \quad H:=\int_{\eta}^{1} \Phi(1)(s) d g(s)
$$

and we observe the following:
Lemma 2.2. Let b be a fixed real number such that

$$
0<b \leq \min \left\{\frac{H}{\alpha \lambda|D \eta p(0)-H|}, b_{0}\right\} .
$$

Then $\sigma \eta \leq H$, where $\sigma:=\frac{\alpha \lambda b p(0)}{\alpha \lambda b+1} D$.
Proof. Obviously $b \leq \frac{H}{\alpha \lambda|D \eta p(0)-H|}$. If $D \eta p(0)-H>0$, by a simple calculation we have the result. Also, if $\operatorname{Dqp}(0)-H<0$, then

$$
\sigma \eta=\frac{\alpha \lambda b p(0) \eta}{\alpha \lambda b+1} D<\frac{\alpha \lambda b H}{\alpha \lambda b+1} \leq H .
$$

## 3. Main results

Before presenting our main theorem we set $\rho:=\frac{1}{\alpha \sigma \eta}$ and let $\theta:=\frac{p(0)}{\alpha H+\int_{0}^{1} q(s) d s}$ where $\sigma$ and $H$ are the constants defined in Lemma 2.2.

Theorem 3.1. Assume that $f, p, q$ and $g$ satisfy (H1)-(H4). If
(H5) There exist $u>0$ and $v>0$ such that $f(u) \geq \rho u$ and $f(v)<\theta v$,
then the boundary-value problem (1.1)-(1.3) admits at least one positive solution.
Proof. Our main purpose is to make the appropriate arrangements so that Theorem 1.1 to be applicable. Define the set
$\mathbb{K}:=\left\{x \in C_{0}^{1}(I): x \geq 0, x^{\prime} \geq 0, x\right.$ is concave and $\left.\int_{\eta}^{1} \Phi(x)(s) d g(s) \geq \sigma\|x\|\right\}$,
which is a cone in $C_{0}^{1}(I)$.
First we claim that the operator $A$ maps $\mathbb{K}$ into $\mathbb{K}$. To this end take a point $x \in \mathbb{K}$. Then observe that it holds $A x \geq 0,(A x)^{\prime} \geq 0$ and $(A x)^{\prime \prime} \leq 0$. Moreover, we observe that

$$
\begin{aligned}
\int_{\eta}^{1} \Phi(A x)(s) d g(s) \geq & \geq \int_{\eta}^{1} \Phi(P)(s) d g(s) \int_{\eta}^{1} \Phi(f(x))(s) d g(s) \\
= & \alpha D \int_{\eta}^{1} \frac{1}{p(s)} \int_{s}^{1} q(\theta) f(x(\theta)) d \theta d g(s) \\
= & \frac{\sigma(\alpha \lambda b+1)}{\lambda b p(0)} \int_{\eta}^{1} \frac{1}{p(s)} \int_{s}^{1} q(\theta) f(x(\theta)) d \theta d g(s) \\
= & \frac{\sigma}{p(0)}\left(\alpha+\frac{1}{\lambda b}\right) \int_{\eta}^{1} \frac{1}{p(s)} \int_{s}^{1} q(\theta) f(x(\theta)) d \theta d g(s) \\
= & \sigma\left[\frac{\alpha}{p(0)} \int_{\eta}^{1} \frac{1}{p(s)} \int_{s}^{1} q(\theta) f(x(\theta)) d \theta d g(s)\right. \\
& \left.+\frac{1}{p(0)} \frac{1}{\lambda b} \int_{\eta}^{1} \frac{1}{p(s)} \int_{s}^{1} q(\theta) f(x(\theta)) d \theta d g(s)\right] .
\end{aligned}
$$

Now we use Lemma 2.1 and get

$$
\begin{aligned}
\int_{\eta}^{1} \Phi(A x)(s) d g(s) \geq & \sigma\left[\frac{\alpha}{p(0)} \int_{\eta}^{1} \frac{1}{p(s)} \int_{s}^{1} q(\theta) f(x(\theta)) d \theta d g(s)\right. \\
& \left.+\frac{1}{p(0)} \int_{0}^{1} q(\theta) f(x(\theta)) d \theta\right] \\
= & \sigma(A x)^{\prime}(0) \\
= & \sigma\|(A x)\| .
\end{aligned}
$$

This proves our first claim.
Now consider an arbitrary $x \in \mathbb{K}$. The fact that the function $x$ is concave implies that

$$
\eta x(1) \leq x(\eta) \leq x(r) \leq x(1) \leq\|x\|, \text { for every } r \in[\eta, 1] .
$$

So,

$$
\begin{aligned}
\sigma\|x\| & \leq \int_{\eta}^{1} \Phi(x)(s) d g(s) \\
& =\int_{\eta}^{1} \frac{1}{p(s)} \int_{s}^{1} q(\theta) x(\theta) d \theta d g(s) \\
& \leq x(1) \int_{\eta}^{1} \frac{1}{p(s)} \int_{s}^{1} q(\theta) d \theta d g(s) \\
& =x(1) \int_{\eta}^{1} \Phi(1)(s) d g(s) \\
& =x(1) H .
\end{aligned}
$$

Thus we have $x(1) \geq \frac{\sigma\|x\|}{H}$, which implies that

$$
x(r) \geq \frac{\eta \sigma}{H}\|x\|, \quad r \in[\eta, 1] .
$$

Hence, for every $r \in[\eta, 1]$ we have

$$
\frac{\eta \sigma}{H}\|x\| \leq x(r) \leq\|x\|,
$$

where, notice that, by Lemma 2.2, $\frac{\eta \sigma}{H} \leq 1$. Then, by assumption (H5), there exists $u>0$ such that $f(u) \geq \rho u$.

Set

$$
M:=\frac{H}{\eta \sigma} u
$$

and fix a function $x \in \mathbb{K}$ with $\|x\|=M$. Then

$$
\frac{\eta \sigma}{H} M \leq x(r) \leq M, \text { for every } r \in[\eta, 1]
$$

and therefore

$$
\begin{aligned}
(A x)^{\prime}(1) & \geq \alpha \int_{\eta}^{1} \frac{1}{p(s)} \int_{s}^{1} q(\theta) f(x(\theta)) d \theta d g(s) \\
& \geq \alpha f(x(\eta)) \int_{\eta}^{1} \Phi(1)(s) d g(s)=\alpha H f(x(\eta)) \\
& \geq \alpha H f\left(\frac{\eta \sigma M}{H}\right)=\alpha H f(u) \geq \alpha H \rho u \\
& =\alpha \rho \eta \sigma M \geq M=\|x\| .
\end{aligned}
$$

Thus we proved that, if $\|x\|=M$, then $\|A x\| \geq\|x\|$.
Now, again, from assumption (H5), it follows that there exists $v>0$ such that $0 \leq f(v)<\theta v$. Fix any function $x \in \mathbb{K}$ with $\|x\|=v$. Then $0 \leq x(r) \leq v, r \in I$. Therefore

$$
\begin{aligned}
\|A x\|=(A x)^{\prime}(0) & =\frac{\alpha}{p(0)} \int_{\eta}^{1} \Phi(f(x))(s) d g(s)+\frac{1}{p(0)} \int_{0}^{1} q(s) f(x(s)) d s \\
& =\frac{\alpha}{p(0)} \int_{\eta}^{1} \frac{1}{p(s)} \int_{0}^{1} q(r) f(x(r)) d r d g(s)+\frac{1}{p(0)} \int_{0}^{1} q(s) f(x(s)) d s \\
& \leq f(v)\left[\frac{\alpha H}{p(0)}+\frac{1}{p(0)} \int_{0}^{1} q(s) d s\right] \\
& \leq \theta v\left[\frac{\alpha H}{p(0)}+\frac{1}{p(0)} \int_{0}^{1} q(s) d s\right] \\
& =v=\|x\|
\end{aligned}
$$

So we proved that, if $\|x\|=v$, then $\|A x\| \leq\|x\|$.
Finally, we set $\Omega_{1}:=\left\{x \in C_{0}^{1}(I):\|x\|<r_{1}\right\}$ and $\Omega_{2}:=\left\{x \in C_{0}^{1}(I):\|x\|<r_{2}\right\}$, where $r_{1}=\min \{M, v\}$ and $r_{2}=\max \{M, v\}$. Without loss of generality we can assume that $M \neq v$ and hence $r_{1}<r_{2}$. Then taking into account the fact that $A$ is a completely continuous operator, by Theorem 1.1, the result follows.

Next we show that some information on the lower and upper limits of the quantity $f(u) / u$ at the points 0 and $+\infty$, are enough to guarrantee existence of a positive solution of the problem (1.1)-(1.3).

Corollary 3.2. Consider the functions $f, p, q$ and $g$ satisfying the assumptions (H1)-(H4). Moreover assume that
(H6) $\lim \sup _{x \rightarrow+\infty} \frac{f(x)}{x}=+\infty$ and $\lim \inf _{x \rightarrow 0+} \frac{f(x)}{x}=0$.
or
(H7) $\lim \sup _{x \rightarrow 0+} \frac{f(x)}{x}=+\infty$ and $\liminf _{x \rightarrow+\infty} \frac{f(x)}{x}=0$.
Then the boundary-value problem (1.1)-(1.3) admits at least one positive solution.
Proof. It is easy to see that each of assumptions (H6), (H7) imply the validity of (H5). Hence the result follows from Theorem 3.1.

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