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# EXISTENCE OF POSITIVE SOLUTIONS FOR DIRICHLET PROBLEMS OF SOME SINGULAR ELLIPTIC EQUATIONS 

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#### Abstract

When an unbounded domain is inside a slab, existence of a positive solution is proved for the Dirichlet problem of a class of semilinear elliptic equations similar to the singular Emden-Fowler equation. The proof is based on a super and sub-solution method. A super solution is constructed by Perron's method together with a family of auxiliary functions.


## 1. Introduction and Main Results

Let $\Omega$ be an unbounded domain in $\mathbb{R}^{n}(n \geq 3)$ with $C^{2, \alpha}(0<\alpha<1)$ boundary. We assume that $\Omega$ is inside a slab of width $2 M$ :

$$
\Omega \subset S_{M}=\left\{(\mathbf{x}, y) \in \mathbb{R}^{n}:|y|<M\right\}
$$

where $\mathbf{x}=\left(x_{1}, x_{2}, \ldots, x_{n-1}\right)$ and throughout the paper, $y$ will be identified with $x_{n}$.

We consider the existence of positive solutions for the Dirichlet problem

$$
\begin{equation*}
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} u=p(\mathbf{x}, y) u^{-\gamma} \quad \text { on } \Omega ; \quad u=0 \quad \text { on } \partial \Omega \tag{1.1}
\end{equation*}
$$

where $\left(a_{i j}\right)$ is a positive definite matrix in which each entry is a local Hölder continuous function on $\bar{\Omega}, p(\mathbf{x}, y)$ is a also local Hölder continuous on $\bar{\Omega}, \gamma>0$ is a constant.

The main result of the paper is as follows.
Theorem 1.1. Assume
(1) $p\left(\mathbf{x}_{0}, y_{0}\right)>0$ for some $\left(\mathbf{x}_{0}, y_{0}\right) \in \Omega$;
(2) there is a positive constant $C$ such that

$$
\begin{equation*}
0 \leq p(\mathbf{x}, y) \leq C(|\mathbf{x}|+1)^{\gamma} \quad \text { for } \quad(\mathbf{x}, \mathrm{y}) \in \Omega ; \tag{1.2}
\end{equation*}
$$

(3) Trace $\left(a_{i j}\right)=1$ and there is a constant $c_{1}>0$, such that

$$
\begin{equation*}
a_{n n}(\mathbf{x}, y) \geq c_{1} \quad \text { on } \bar{\Omega} . \tag{1.3}
\end{equation*}
$$

Then (1.1) has a positive solution $u \in C^{2}(\Omega) \cap C^{0}(\bar{\Omega})$.

[^0]When the principal part in (1.1) is the Laplace operator, (1.1) becomes a boundary value problem for the singular Emden-Fowler equation

$$
\begin{equation*}
-\Delta u=p(\mathbf{x}, y) u^{-\gamma} \quad \text { on } \Omega ; \quad u=0 \quad \text { on } \partial \Omega \tag{1.4}
\end{equation*}
$$

The singular Emden-Fowler is related to the theory of heat conduction in electrical conduction materials and in the studies of boundary layer phenomena for viscous fluids $[2,16]$. The existence of positive solutions of the equation on exterior domains (including $\mathbb{R}^{n}$ ) has been considered by quite a number of authors (for example, see $[4,5,8,11,12,15]$, and references therein). The main approach used to prove existence is to construct super and sub- solutions. To construct super solutions, one needs to assume that $p(\mathbf{x}, y)$ decays near infinity in an appropriate rate. A super solution is usually found in the class of radial symmetric functions. If $\Omega$ is an exterior domain (not inside a slab), $\gamma>0$ and there is $C$ such that $p(\mathbf{x}, y) \geq \frac{C}{\left(1+|\mathbf{x}|^{2}+y^{2}\right)}$ for $|\mathbf{x}|^{2}+y^{2}$ large, then (1.4) has no positive solutions ([11]). On the other hand, if there are constants $\sigma>1$ and $C$, such that $0 \leq p(\mathbf{x}, y) \leq \frac{C}{\left(1+|\mathbf{x}|^{2}+y^{2}\right)^{\sigma}}$ for $|\mathbf{x}|^{2}+y^{2}$ large, (1.4) has a positive solution ([8]). When $\Omega$ is an unbounded domain inside a slab, the situation is quite different. The traditional way to construct a super solution by finding an appropriate radial symmetric function is no longer valid since the domain now is inside a slab (the generality of the coefficient matrix $\left(a_{i j}\right)$ also makes finding a radial symmetric super solution impossible). In this paper, we combine an idea from [13] and a family of auxiliary functions constructed in [10] to construct a super solution which is then used to prove the existence of a positive solution of (1.1).

Actually the procedure in the paper can be applied to prove the existence of a positive solution for the Dirichlet problem of more general elliptic equations. A statement for the general case will be given in the last section of the paper. Here we just state a special case of the general result.

Theorem 1.2. Assume
(1) $p\left(\mathbf{x}_{0}, y_{0}\right)>0$ for some $\left(\mathbf{x}_{0}, y_{0}\right) \in \Omega$;
(2) there is a positive constant $C$ such that

$$
\begin{equation*}
0 \leq p(\mathbf{x}, y) \leq C e^{|\mathbf{x}|} \quad \text { for } \quad(\mathbf{x}, \mathrm{y}) \in \Omega \tag{1.5}
\end{equation*}
$$

(3) Trace $\left(a_{i j}\right)=1$, and there is a constant $c_{1}>0$, such that

$$
\begin{equation*}
a_{n n}(\mathbf{x}, y) \geq c_{1} \quad \text { on } \quad \bar{\Omega} \tag{1.6}
\end{equation*}
$$

Then the problem

$$
\begin{equation*}
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} u=p(\mathbf{x}, y) e^{-u} \quad \text { on } \Omega ; \quad u=0 \quad \text { on } \partial \Omega \tag{1.7}
\end{equation*}
$$

has a positive solution $u \in C^{2}(\Omega) \cap C^{0}(\bar{\Omega})$.
This paper is organized as follows. In Section 2, we construct a family of auxiliary functions that are defined on a family of subdomains of $\Omega$. In Section 3 , we combine the family of auxiliary functions constructed in Section 2 and an idea from [13] to prove that (1.1) has a positive supper solution. In Section 4, we prove that (1.1) has a positive solution by the procedure used in [8]. In Section 5, we discuss the general case.

## 2. A Family of Auxiliary Functions

In this section, we will construct families of sub-domains $\Omega_{\mathbf{x}_{0}}$ of $\Omega$ and functions $T_{\mathbf{x}_{0}}+z$ (see definitions below) so that

$$
\begin{equation*}
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j}\left(T_{\mathbf{x}_{0}}+z\right) \geq p(\mathbf{x}, y)\left(T_{\mathbf{x}_{0}}+z\right)^{-\gamma} \quad \text { on } \Omega_{\mathbf{x}_{0}} \tag{2.1}
\end{equation*}
$$

and the graphs of the functions $T_{\mathbf{x}_{0}}+z$ have special relative positions (see below).
Our construction is based on the construction of a family of auxiliary functions used in [10] (the construction in [10] was adapted from [9] which in turn was inspired from [6] and [14]). We consider the operator

$$
Q u=\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} u
$$

We first extend $a_{i j}(1 \leq i, j \leq n)$ to be continuous functions on $\overline{S_{M}}$ in such a way that we still have $\operatorname{Trace}\left(a_{i j}\right)=1$ and

$$
\begin{equation*}
a_{n n}(\mathbf{x}, y) \geq c_{1} \quad \text { on } S_{M} \tag{2.2}
\end{equation*}
$$

In the rest of the paper, we will use $c_{m}$ (for some integer $m \geq 2$ ) to denote a constant depending only on $c_{1}$ and $M$. Once a constant $c_{m}$ is used in a formula, it will represent the same constant if the same notation appears again in the paper.

It was proved in [10] (also see Appendix I) that there are positive decreasing functions $\chi(t), h_{a}(t)$ and a positive increasing function $A(t)\left(\chi(t)\right.$ depending on $c_{1}$ only, $h_{a}(t)$ and $A(t)$ depending on $c_{1}$ and $M$ only), such that for any number $K$, there is a number $H_{0}$, depending only on $K, M$ and $c_{1}$, such that for $H \geq H_{0}$, we have (for $0<t<2 M$ )

$$
\begin{gather*}
A(H) \leq h_{a}^{-1}(t) \leq A(H) e^{\chi(H)}, \quad 22 M H \leq c_{1} A(H) e^{\chi(H)} \leq 66 M H  \tag{2.3}\\
8 K \leq A(H) e^{\chi(H)}, \quad 0<\chi(H)<1 \tag{2.4}
\end{gather*}
$$

and the non-negative function

$$
\begin{equation*}
z=z_{\mathbf{x}_{0}}=A(H) e^{\chi(H)}-\left\{\left(h_{a}^{-1}(y+M)\right)^{2}-\left|\mathbf{x}-\mathbf{x}_{0}\right|^{2}\right\}^{1 / 2} \tag{2.5}
\end{equation*}
$$

satisfies

$$
\begin{gather*}
Q z \leq \frac{-3 c_{1}}{22 e M H} \quad \text { in } \Omega_{\mathbf{x}_{0}, H, K}  \tag{2.6}\\
z \geq K \quad \text { on } \partial \Omega_{\mathbf{x}_{0}, H, K} \cap\{|y|<M\}, \quad z\left(\mathbf{x}_{0}, y\right) \leq \frac{2 M}{H} \quad \text { for }|y| \leq M \tag{2.7}
\end{gather*}
$$

where

$$
\begin{equation*}
\Omega_{\mathbf{x}_{0}, H, K}=\left\{(\mathbf{x}, y):|y|<M,\left|\mathbf{x}-\mathbf{x}_{0}\right|<\sqrt{\frac{2 K}{A(H) e^{\chi(H)}}} h_{a}^{-1}(y+M)\right\} . \tag{2.8}
\end{equation*}
$$

(For verifications of (2.3)-(2.4) and (2.6)-(2.7), see Appendix I.)
Now we set

$$
\begin{equation*}
K=100, \quad H=H_{0}+4 M, \quad \Omega_{\mathbf{x}_{0}}=\Omega_{\mathbf{x}_{0}, H, K} \tag{2.9}
\end{equation*}
$$

Then (2.6)-(2.7) becomes

$$
\begin{gather*}
Q z \leq-c_{2} \quad \text { in } \Omega_{\mathbf{x}_{0}}  \tag{2.10}\\
z \geq 100 \quad \text { on } \partial \Omega_{\mathbf{x}_{0}} \cap\{|y|<M\}, \quad z\left(\mathbf{x}_{0}, y\right) \leq 1 \quad \text { for }|y| \leq M . \tag{2.11}
\end{gather*}
$$

Now we construct a family of auxiliary functions as follows.
If $(\mathbf{x}, y) \in \Omega_{\mathbf{x}_{0}}$, from (2.3) and (2.8), we have

$$
\left|\mathbf{x}-\mathbf{x}_{0}\right|<\sqrt{200 A(H) e^{\chi(H)}} \leq \sqrt{13200 M H / c_{1}}=c_{4}
$$

For $C$ defined in (1.2), we set

$$
\begin{equation*}
T_{\mathbf{x}_{0}}=\left(\frac{C}{c_{2}}\right)^{1 / \gamma}\left(\left|\mathbf{x}_{0}\right|+c_{4}+1\right) \tag{2.12}
\end{equation*}
$$

Then we have that on $\Omega_{\mathbf{x}_{0}}$,

$$
p(\mathbf{x}, y)\left(T_{\mathbf{x}_{0}}+z\right)^{-\gamma} \leq C(|\mathbf{x}|+1)^{\gamma} T_{\mathbf{x}_{0}}^{-\gamma} \leq \frac{C\left(\left|\mathbf{x}_{0}\right|+c_{4}+1\right)^{\gamma}}{T_{\mathbf{x}_{0}}^{\gamma}}=c_{2}
$$

Thus

$$
\begin{equation*}
-Q\left(T_{\mathbf{x}_{0}}+z\right) \geq c_{2} \geq p(\mathbf{x}, y)\left(T_{\mathbf{x}_{0}}+z\right)^{-\gamma} \quad \text { on } \Omega_{\mathbf{x}_{0}} \tag{2.13}
\end{equation*}
$$

When $\mathbf{x}_{0}$ changes, we obtain families of auxiliary functions $T_{\mathbf{x}_{0}}+z$ and domains $\Omega_{\mathbf{x}_{0}}$ satisfying (2.1).

To be able to use the family of auxiliary functions, we need to investigate relative positions of the graphs of these auxiliary functions.

For two points $\mathbf{x}_{0}$ and $\mathbf{x}_{1}$ in $R^{n-1}$, when $\Omega_{\mathbf{x}_{1}}$ either covers the whole segment of the set $\left\{\left(\mathbf{x}_{0}, y\right)||y| \leq M\}\right.$ or does not intersect with the set, from (2.3) and (2.8), we have either

$$
\begin{equation*}
\left|\mathbf{x}_{1}-\mathbf{x}_{0}\right| \leq \sqrt{200 A(H) e^{-\chi(H)}} \quad \text { or } \quad\left|\mathbf{x}_{1}-\mathbf{x}_{0}\right| \geq \sqrt{200 A(H) e^{\chi(H)}} \tag{2.14}
\end{equation*}
$$

Then when $\Omega_{\mathbf{x}_{1}}$ covers part of some neighborhood of $\left\{\left(\mathbf{x}_{0}, y\right):|y| \leq M\right\}$, we have

$$
\begin{equation*}
\sqrt{195 A(H) e^{-\chi(H)}} \leq\left|\mathbf{x}_{1}-\mathbf{x}_{0}\right| \leq \sqrt{205 A(H) e^{\chi(H)}} \tag{2.15}
\end{equation*}
$$

Let $\mathbf{x}_{1}$ and $\mathbf{x}_{0}$ satisfy (2.15) and $\delta_{0}$ be a small positive number such that $2 \delta_{0}<$ $\sqrt{195 A(H) e^{-\chi(H)}}$. If $(\mathbf{x}, y) \in \Omega_{\mathbf{x}_{1}}$ for some $y$ and $\left|\mathbf{x}-\mathbf{x}_{0}\right| \leq \delta_{0}$, by (2.3), (2.5) and (2.15), we have

$$
\begin{aligned}
& T_{\mathbf{x}_{1}}+z_{\mathbf{x}_{1}}(\mathbf{x}, y) \\
& \geq T_{\mathbf{x}_{1}}+A(H) e^{\chi(H)}-\left\{A(H)^{2} e^{2 \chi(H)}-\left|\mathbf{x}-\mathbf{x}_{1}\right|\right\}^{1 / 2} \\
& \geq T_{\mathbf{x}_{1}}+A(H) e^{\chi(H)}-\left\{A(H)^{2} e^{2 \chi(H)}-\left(\sqrt{195 A(H) e^{-\chi(H)}}-\delta_{0}\right)^{2}\right\}^{1 / 2} \\
& \geq T_{\mathbf{x}_{1}}+A(H) e^{\chi(H)} \\
& \quad-\left\{A(H)^{2} e^{2 \chi(H)}-195 A(H) e^{-\chi(H)}+2 \delta_{0} \sqrt{195 A(H) e^{-\chi(H)}}\right\}^{1 / 2} \\
& \geq T_{\mathbf{x}_{1}}+A(H) e^{\chi(H)}\left(1-\left(1-\frac{195}{A(H) e^{3 \chi(H)}}+\frac{2 \delta_{0} \sqrt{195 A(H) e^{-\chi(H)}}}{A(H)^{2} e^{2 \chi(H)}}\right)^{1 / 2}\right)
\end{aligned}
$$

(by the inequality $\sqrt{1-t} \leq 1-\frac{1}{2} t$ for $0<t<1$ and (2.4))

$$
\begin{aligned}
& \geq T_{\mathbf{x}_{1}}+A(H) e^{\chi(H)}\left(\frac{195}{2 A(H) e^{3 \chi(H)}}-\frac{2 \delta_{0} \sqrt{195 A(H) e^{-\chi(H)}}}{2 A(H)^{2} e^{2 \chi(H)}}\right) \\
& =T_{\mathbf{x}_{1}}+\frac{195}{2 e^{2 \chi(H)}}-\frac{\delta_{0} \sqrt{195 A(H) e^{-\chi(H)}}}{A(H) e^{\chi(H)}}>T_{\mathbf{x}_{1}}+10-\frac{\delta_{0} \sqrt{195 A(H) e^{-\chi(H)}}}{A(H) e^{\chi(H)}} .
\end{aligned}
$$

Thus there is a $\delta_{0}$ small such that for all $\left|\mathbf{x}-\mathbf{x}_{0}\right| \leq \delta_{0}$ with $(\mathbf{x}, y) \in \Omega_{\mathbf{x}_{1}}$, if $\mathbf{x}_{1}$ and $\mathrm{x}_{0}$ satisfy (2.15), we have

$$
\begin{equation*}
T_{\mathbf{x}_{1}}+z_{\mathbf{x}_{1}}(\mathbf{x}, y) \geq T_{\mathbf{x}_{1}}+8 . \tag{2.16}
\end{equation*}
$$

Further for all $\mathbf{x}_{0}$ and $\mathbf{x}_{1}$ satisfying (2.15),

$$
\begin{aligned}
T_{\mathbf{x}_{0}}+2 & \leq T_{\mathbf{x}_{1}}+T_{\mathbf{x}_{0}}-T_{\mathbf{x}_{1}}+2 \\
& \leq T_{\mathbf{x}_{1}}+\left(\frac{C}{c_{2}}\right)^{\frac{1}{\gamma}}\left(\left|\mathbf{x}_{0}\right|-\left|\mathbf{x}_{1}\right|\right)+2 \\
& \leq T_{\mathbf{x}_{1}}+\left(\frac{C}{c_{2}}\right)^{\frac{1}{\gamma}}\left|\mathbf{x}_{1}-\mathbf{x}_{0}\right|+2 \\
& \leq T_{\mathbf{x}_{1}}+\left(\frac{C}{c_{2}}\right)^{\frac{1}{\gamma}} \sqrt{205 A(H) e^{\chi(H)}}+2 \\
& \leq T_{\mathbf{x}_{1}}+\left(\frac{C}{c_{2}}\right)^{\frac{1}{\gamma}} c_{5}+2
\end{aligned}
$$

where $c_{5}=\sqrt{205 A(H) e^{\chi(H)}}$. Thus if we assume that $C$ in (1.2) satisfies

$$
\begin{equation*}
C \leq 6^{\gamma} c_{5}^{-\gamma} c_{2} \tag{2.17}
\end{equation*}
$$

we have that for all $\mathbf{x}_{0}$ and $\mathbf{x}_{1}$ satisfying (2.15),

$$
\begin{equation*}
T_{\mathbf{x}_{0}}+2 \leq T_{\mathbf{x}_{1}}+8 \tag{2.18}
\end{equation*}
$$

From (2.8) and (2.11), we can choose a number $\delta_{2}\left(\mathbf{x}_{0}\right)>0$ such that for all $\mathbf{x} \in R^{n-1}$ with $\left|\mathbf{x}_{0}-\mathbf{x}\right| \leq \delta_{2}\left(\mathbf{x}_{0}\right)$, we have $(\mathbf{x}, y) \in \Omega_{\mathbf{x}_{0}}$ for all $|y|<M$, and

$$
\begin{equation*}
T_{\mathbf{x}_{0}}+z_{\mathbf{x}_{0}}(\mathbf{x}, y) \leq T_{\mathbf{x}_{0}}+2 \tag{2.19}
\end{equation*}
$$

Now if we set $\delta_{\mathbf{x}_{0}}=\min \left\{\delta_{0}, \delta_{2}\left(\mathbf{x}_{0}\right)\right\}$, from (2.16), (2.18) and (2.19), we have

$$
\begin{equation*}
T_{\mathbf{x}_{0}}+z_{\mathbf{x}_{0}}(\mathbf{x}, y) \leq T_{\mathbf{x}_{1}}+z_{\mathbf{x}_{1}}(\mathbf{x}, y) \tag{2.20}
\end{equation*}
$$

for all $\mathbf{x}_{0}$ and $\mathbf{x}_{1}$ satisfying (2.15), $\left|\mathbf{x}_{0}-\mathbf{x}\right| \leq \delta_{\mathbf{x}_{0}}$ and $(\mathbf{x}, y) \in \Omega_{\mathbf{x}_{1}}$.
Finally we define a family of open subsets of $\Omega$ that will be needed in next section.

For each point $\left(\mathbf{x}_{0}, y_{0}\right) \in \bar{\Omega}$, we define an open set $O\left(\mathbf{x}_{0}, y_{0}\right)$ as follows:
(1) If $\left(\mathbf{x}_{0}, y_{0}\right) \in \Omega$, we choose a ball $B$ with center $\left(\mathbf{x}_{0}, y_{0}\right)$ and a radius less than $\delta_{\mathbf{x}_{0}}$ so that $B \subset \Omega$. We then set $O\left(\mathbf{x}_{0}, y_{0}\right)=B$;
(2) If $\left(\mathbf{x}_{0}, y_{0}\right) \in \partial \Omega$, since $\Omega$ has $C^{2, \alpha}$ boundary, there is a ball $B$ with center $\left(\mathbf{x}_{0}, y_{0}\right)$ and a radius less than $\delta_{\mathbf{x}_{0}}$, such that there is a $C^{2, \alpha}$ diffeomorphism $\Phi$ satisfying

$$
\Phi(B \cap \Omega) \subset \mathbb{R}_{+}^{n}, \quad \Phi(B \cap \partial \Omega) \subset \partial \mathbb{R}_{+}^{n} ; \quad \Phi\left(\mathbf{x}_{0}, y_{0}\right)=\mathbf{0}
$$

Now we choose a domain $J$ with $C^{3}$ boundary with following properties: (a) $J \subset$ $\Phi(B \cap \Omega) ;(\mathrm{b}) \partial J \cap \partial \mathbb{R}_{+}^{n}$ is a neighborhood of $\mathbf{0}$ in $\partial \mathbb{R}_{+}^{n}$. Certainly there are many different $J$ 's having those properties. One example is given in the Appendix II at the end of paper to illustrate how to construct such a domain $J$.

Now we set $O\left(\mathbf{x}_{0}, y_{0}\right)=\Phi^{-1}(J)$. It is easy to see that $O\left(\mathbf{x}_{0}, y_{0}\right) \subset B \cap \Omega$, $O\left(\mathbf{x}_{0}, y_{0}\right)$ has a $C^{2, \alpha}$ boundary and $\partial O\left(\mathbf{x}_{0}, y_{0}\right) \cap \partial \Omega$ is a neighborhood of $\left(\mathbf{x}_{0}, y_{0}\right)$ in $\partial \Omega$. Let $\Pi$ be the collection of all such open sets $O\left(\mathbf{x}_{0}, y_{0}\right)$ defined in (1) and (2).

## 3. A Super Solution of (1.1)

In this section, using the family of auxiliary functions $T_{\mathbf{x}_{0}}+z$ constructed in Section 2 and an idea from [13] (that basically says that the Perron's method still works if we can find a family of appropriate auxiliary functions that works like a super solution), we will show that there is a positive function $u \in C^{2}(\Omega) \cap C^{0}(\bar{\Omega})$, satisfies

$$
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} u=p(\mathbf{x}, y) u^{-\gamma} \quad \text { on } \Omega, \quad u=\tau \quad \text { on } \partial \Omega .
$$

for some constant $\tau>0$. Then $u$ will be a super solution of (1.1).
If $u=c_{0} v$ for some constant $c_{0}, v$ will satisfy

$$
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} v=c_{0}^{-\gamma-1} p(\mathbf{x}, y) v^{-\gamma} \quad \text { on } \Omega, \quad v=\tau / c_{0} \quad \text { on } \partial \Omega
$$

Thus without loss of generality, we may assume $C$ in (1.2) satisfying (2.17). Then all constructions in Section 2 are valid.

Let $v>0$ be a function on $\bar{\Omega}$, for a point $\left(\mathbf{x}_{0}, y_{0}\right) \in \bar{\Omega}$, we define a new function $M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v)$, called the lift of $v$ over $O\left(\mathbf{x}_{0}, y_{0}\right)$ as follows:

$$
\begin{gathered}
M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v)(\mathbf{x}, y)=v(\mathbf{x}, y) \quad \text { if } \quad(\mathbf{x}, y) \in \Omega \backslash O\left(\mathbf{x}_{0}, y_{0}\right) \\
M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v)(\mathbf{x}, y)=w(\mathbf{x}, y) \quad \text { if } \quad(\mathbf{x}, y) \in O\left(\mathbf{x}_{0}, y_{0}\right)
\end{gathered}
$$

where $w(\mathbf{x}, y)$ is the positive solution of the boundary-value problem

$$
\begin{equation*}
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} w=p(\mathbf{x}, y) w^{-\gamma} \quad \text { in } O\left(\mathbf{x}_{0}, y_{0}\right), \quad w=v \quad \text { on } \partial O\left(\mathbf{x}_{0}, y_{0}\right) \tag{3.1}
\end{equation*}
$$

It is easy to see (3.1) has a unique positive solution in $C^{2}\left(O\left(\mathbf{x}_{0}, y_{0}\right)\right) \cap C^{0}\left(\overline{O\left(\mathbf{x}_{0}, y_{0}\right)}\right)$. Indeed $m_{1}=\min \left\{v(\mathbf{x}, y):(\mathbf{x}, y) \in \partial O\left(\mathbf{x}_{0}, y_{0}\right)\right\}$ is a sub-solution since $p(\mathbf{x}, y)$ is non-negative, $m_{2}+T_{\mathbf{x}_{0}}+z_{\mathbf{x}_{0}}$ is a super solution by (2.1), where $m_{2}=\max \{v(\mathbf{x}, y)$ : $\left.(\mathbf{x}, y) \in \partial O\left(\mathbf{x}_{0}, y_{0}\right)\right\}$. Then we can conclude the existence of a desired solution (for example, see [1] or [3]). Uniqueness of positive solutions of (3.1) follows from a standard argument.

Set $\tau=\left(C / c_{2}\right)^{1 / \gamma} c_{4}$ (see (2.12) for the source of the constants).
We define a class $\Xi$ of functions as follows: a function $v$ is in $\Xi$ if
(1) $v \in C^{0}(\bar{\Omega}), v>0$ on $\bar{\Omega}$ and $v \leq \tau$ on $\partial \Omega$;
(2) For any $\left(\mathbf{x}_{0}, y_{0}\right) \in \bar{\Omega}, v \leq M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v)$;
(3) $v \leq T_{\mathbf{x}_{0}}+z_{\mathbf{x}_{0}}$ on $\Omega_{\mathbf{x}_{0}} \cap \Omega$ for any $\left(\mathbf{x}_{0}, y_{0}\right) \in \bar{\Omega}$.

By the following well-known lemma, it is easy to check the function $v=\tau$ is in $\Xi$. Thus $\Xi$ is not empty.

Lemma 3.1. Let $D$ be a bounded domain, $f(\mathbf{x}, y, t)$ be a $C^{1}$ function that is decreasing in $t$. If $w_{1}, w_{2}$ are in $C^{2}(D) \cap C^{0}(\bar{D}), w_{1} \leq w_{2}$ on $\partial D$, and

$$
\begin{aligned}
& -\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} w_{1} \leq f\left(\mathbf{x}, y, w_{1}\right) \quad \text { in } D \\
& -\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} w_{2} \geq f\left(\mathbf{x}, y, w_{2}\right) \quad \text { in } D
\end{aligned}
$$

then $w_{1} \leq w_{2}$ on $D$.
Now we set

$$
u(\mathbf{x}, y)=\sup _{v \in \Xi} v(\mathbf{x}, y), \quad(\mathbf{x}, y) \in \bar{\Omega}
$$

We will show that $u$ is in $C^{2}(\Omega) \cap C^{0}(\bar{\Omega})$ and satisfies

$$
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} u=p(\mathbf{x}, y) u^{-\gamma} \quad \text { on } \Omega ; \quad u=\tau \quad \text { on } \partial \Omega .
$$

First we need some lemmas.
Lemma 3.2. If $0<v_{1} \leq v_{2}$, then $M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(v_{1}\right) \leq M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(v_{2}\right)$ for any $\left(\mathbf{x}_{0}, y_{0}\right) \in \bar{\Omega}$.
Proof. Let $w_{1}, w_{2}$ be the positive solutions for the following problems

$$
\begin{gathered}
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} w_{k}=p(\mathbf{x}, y) w_{k}^{-\gamma} \quad \text { in } O\left(\mathbf{x}_{0}, y_{0}\right), \\
w_{k}=v_{k} \quad \text { on } \partial O\left(\mathbf{x}_{0}, y_{0}\right), \quad k=1,2
\end{gathered}
$$

Since $w_{1}=v_{1} \leq v_{2}=w_{2}$ on $\partial O\left(\mathbf{x}_{0}, y_{0}\right), p(\mathbf{x}, y) t^{-\gamma}$ is decreasing on $t$, from lemma 1, we see $w_{1} \leq w_{2}$ on $O\left(\mathbf{x}_{0}, y_{0}\right)$. On $\Omega \backslash O\left(\mathbf{x}_{0}, y_{0}\right), M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(v_{1}\right)=v_{1}, M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(v_{2}\right)=v_{2}$. Thus $M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(v_{1}\right) \leq M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(v_{2}\right)$.

Lemma 3.3. If $v_{1} \in \Xi, v_{2} \in \Xi$, then $\max \left\{v_{1}, v_{2}\right\} \in \Xi$.
Proof. If $v_{1} \in \Xi, v_{2} \in \Xi$, it is clear that $\max \left\{v_{1}, v_{2}\right\} \in C^{0}(\bar{\Omega}), \max \left\{v_{1}, v_{2}\right\}>0$ on $\bar{\Omega}$ and $\max \left\{v_{1}, v_{2}\right\} \leq \tau$ on $\partial \Omega$. It is also clear that $\max \left\{v_{1}, v_{2}\right\} \leq T_{\mathbf{x}_{0}}+z_{\mathbf{x}_{0}}$ on $\Omega_{\mathbf{x}_{0}} \cap \Omega$ for any $\left(\mathbf{x}_{0}, y_{0}\right) \in \bar{\Omega}$. Since

$$
v_{1} \leq \max \left\{v_{1}, v_{2}\right\}, \quad v_{2} \leq \max \left\{v_{1}, v_{2}\right\}
$$

we have (by lemma 2) that for any $\left(\mathbf{x}_{0}, y_{0}\right) \in \bar{\Omega}$,

$$
M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(v_{1}\right) \leq M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(\max \left\{v_{1}, v_{2}\right\}\right), \quad M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(v_{2}\right) \leq M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(\max \left\{v_{1}, v_{2}\right\}\right) .
$$

Since $v_{1} \in \Xi$ and $v_{2} \in \Xi$ imply

$$
v_{1} \leq M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(v_{1}\right), \quad v_{2} \leq M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(v_{2}\right),
$$

we have

$$
\max \left\{v_{1}, v_{2}\right\} \leq M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(\max \left\{v_{1}, v_{2}\right\}\right) .
$$

Thus $\max \left\{v_{1}, v_{2}\right\} \in \Xi$.
Lemma 3.4. If $v \in \Xi$, then $M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v) \in \Xi$ for any $\left(\mathbf{x}_{0}, y_{0}\right) \in \bar{\Omega}$.
Proof. By the definition of $M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v)$, it is clear that $M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v)>0$ on $\bar{\Omega}$, $M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v) \in C^{0}(\bar{\Omega})$ and $M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v) \leq \tau$ on $\partial \Omega$.

For any $\left(\mathbf{x}^{*}, y^{*}\right) \in \bar{\Omega}$, we first show that

$$
\begin{equation*}
M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v)(\mathbf{x}, y) \leq M_{\left(\mathbf{x}^{*}, y^{*}\right)}\left(M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v)\right)(\mathbf{x}, y) . \tag{3.2}
\end{equation*}
$$

We only need to prove that (3.2) is true for $(\mathbf{x}, y) \in O\left(\mathbf{x}^{*}, y^{*}\right)$. Since

$$
v \leq M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v),
$$

we have (by lemma 2)

$$
M_{\left(\mathbf{x}^{*}, y^{*}\right)}(v) \leq M_{\left(\mathbf{x}^{*}, y^{*}\right)}\left(M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v)\right) .
$$

Then from $v \leq M_{\left(\mathbf{x}^{*}, y^{*}\right)}(v)$ (by lemma 2 again), we have

$$
v \leq M_{\left(\mathbf{x}^{*}, y^{*}\right)}\left(M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v)\right)
$$

Thus for $(\mathbf{x}, y) \in O\left(\mathbf{x}^{*}, y^{*}\right) \backslash O\left(\mathbf{x}_{0}, y_{0}\right)$,

$$
\begin{equation*}
M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v)(\mathbf{x}, y)=v(\mathbf{x}, y) \leq M_{\left(\mathbf{x}^{*}, y^{*}\right)}\left(M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v)\right)(\mathbf{x}, y) \tag{3.3}
\end{equation*}
$$

That is, (3.2) is true on $O\left(\mathbf{x}^{*}, y^{*}\right) \backslash O\left(\mathbf{x}_{0}, y_{0}\right)$, Now for $\Omega_{1}=O\left(\mathbf{x}^{*}, y^{*}\right) \cap O\left(\mathbf{x}_{0}, y_{0}\right)$, if we set

$$
M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v)=w_{1}, \quad M_{\left(\mathbf{x}^{*}, y^{*}\right)}\left(M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v)\right)=w_{2}
$$

we have

$$
\begin{aligned}
& -\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} w_{1}=p(\mathbf{x}, y) w_{1}^{-\gamma} \quad \text { on } \Omega_{1} \\
& -\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} w_{2}=p(\mathbf{x}, y) w_{2}^{-\gamma} \quad \text { on } \Omega_{1}
\end{aligned}
$$

On $\partial \Omega_{1}, w_{1} \leq w_{2}$ on $O\left(\mathbf{x}^{*}, y^{*}\right) \cap \partial O\left(\mathbf{x}_{0}, y_{0}\right)$ by (3.3) and $w_{1} \leq w_{2}$ on $\partial O\left(\mathbf{x}^{*}, y^{*}\right) \cap$ $O\left(\mathbf{x}_{0}, y_{0}\right)$ since (3.2) is true on $\Omega \backslash O\left(\mathbf{x}^{*}, y^{*}\right)$. Then lemma 1 implies $w_{1} \leq w_{2}$ on $\Omega_{1}$. Thus (3.2) is true on $O\left(\mathbf{x}^{*}, y^{*}\right) \cap O\left(\mathbf{x}_{0}, y_{0}\right)$ and on $O\left(\mathbf{x}^{*}, y^{*}\right)$.

Now we prove that $M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v) \leq T_{\mathbf{x}_{1}}+z_{\mathbf{x}_{1}}$ on $\Omega_{\mathbf{x}_{1}} \cap \Omega$ for all $\left(\mathbf{x}_{1}, y_{1}\right) \in \bar{\Omega}$.
By the definition of $M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v)$, we only need to consider the graph of the function $M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v)$ over $O\left(\mathbf{x}_{0}, y_{0}\right)$. If $O\left(\mathbf{x}_{0}, y_{0}\right)$ is covered completely by $\Omega_{\mathbf{x}_{1}}$, since $v \leq T_{\mathbf{x}_{1}}+z_{\mathbf{x}_{1}}$ and $T_{\mathbf{x}_{1}}+z_{\mathbf{x}_{1}}$ satisfies (2.1), $T_{\mathbf{x}_{1}}+z_{\mathbf{x}_{1}}$ is a super solution of (3.1) on $O\left(\mathbf{x}_{0}, y_{0}\right)$. Then Lemma 3.1 implies $M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v) \leq T_{\mathbf{x}_{1}}+z_{\mathbf{x}_{1}}$ on $O\left(\mathbf{x}_{0}, y_{0}\right)$. In the case that $O\left(\mathbf{x}_{0}, y_{0}\right)$ does not intersect with $\Omega_{\mathbf{x}_{1}}$, the conclusion is trivial. Now we consider the case that $O\left(\mathbf{x}_{0}, y_{0}\right)$ is partially covered by $\Omega_{\mathbf{x}_{1}}$. Since $O\left(\mathbf{x}_{0}, y_{0}\right)$ is covered by $\Omega_{\mathbf{x}_{0}}$, we always have

$$
\begin{equation*}
M_{\left(\mathbf{x}_{0}, y_{0}\right)}(v) \leq T_{\mathbf{x}_{0}}+z_{\mathbf{x}_{0}} \quad \text { on } O\left(\mathbf{x}_{0}, y_{0}\right) \tag{3.4}
\end{equation*}
$$

Then by the choice of $\delta_{\mathbf{x}_{0}}, O\left(\mathbf{x}_{0}, y_{0}\right)$, and the fact that $O\left(\mathbf{x}_{0}, y_{0}\right) \cap T_{\mathbf{x}_{1}}$ is not empty, we have that $\mathbf{x}_{0}$ and $\mathbf{x}_{1}$ satisfy (2.15), and for all $(\mathbf{x}, y) \in O\left(\mathbf{x}_{0}, y_{0}\right) \cap \Omega_{\mathbf{x}_{1}}$, $\left|\mathbf{x}_{0}-\mathbf{x}\right| \leq \delta_{\mathbf{x}_{0}}$. Then by (2.20), the graph of $T_{\mathbf{x}_{0}}+z_{\mathbf{x}_{0}}$ over $O\left(\mathbf{x}_{0}, y_{0}\right) \cap \Omega_{\mathbf{x}_{1}}$ is under the graph of $T_{\mathbf{x}_{1}}+z_{\mathbf{x}_{1}}$. Thus the conclusion follows from (3.4).

Now we are ready to prove that $u$ has the desired properties.
Let $\left(\mathbf{x}_{0}, y_{0}\right) \in \bar{\Omega}$. By the definition of $u\left(\mathbf{x}_{0}, y_{0}\right)$, there is a sequence of functions $v_{k}$ in $\Xi$ such that

$$
u\left(\mathbf{x}_{0}, y_{0}\right)=\lim _{k \rightarrow \infty} v_{k}\left(\mathbf{x}_{0}, y_{0}\right)
$$

By lemma 3 and the fact that $v=\tau$ is in $\Xi$, replacing $v_{k}$ by $\max \left\{v_{k}, \tau\right\}$ if it is necessary, we may assume that $v_{k} \geq \tau$ on $\Omega$. We replace $v_{k}$ by $M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(v_{k}\right)$. Then we have a sequence of functions $w_{k}$ satisfying

$$
\begin{aligned}
u\left(\mathbf{x}_{0}, y_{0}\right) & =\lim _{k \rightarrow \infty} w_{k}\left(\mathbf{x}_{0}, y_{0}\right), \\
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} w_{k} & =p(\mathbf{x}, y) w_{k}^{-\gamma} \quad \text { on } \quad O\left(\mathbf{x}_{0}, y_{0}\right), \\
w_{k}=v_{k} & \text { on } \quad \partial O\left(\mathbf{x}_{0}, y_{0}\right) .
\end{aligned}
$$

Since for all $k$,

$$
\tau \leq v_{k} \leq w_{k} \leq T_{\mathbf{x}_{0}}+z_{\mathbf{x}_{0}} \quad \text { on } O\left(\mathbf{x}_{0}, y_{0}\right)
$$

By [7, Theorem 9.11] and an approximation of the boundary value by smooth functions, we see that there is a subsequence of $w_{k}$, for convenience still denoted by $w_{k}$, converges to a $C^{2}\left(O\left(\mathbf{x}_{0}, y_{0}\right)\right) \cap C^{0}\left(\overline{O\left(\mathbf{x}_{0}, y_{0}\right)}\right)$ function $w(x)$ in $C^{2}\left(O\left(\mathbf{x}_{0}, y_{0}\right)\right) \cap$ $C^{0}\left(\overline{O\left(\mathbf{x}_{0}, y_{0}\right)}\right)$. Thus $w(x)$ satisfies

$$
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} w=p(\mathbf{x}, y) w^{-\gamma} \quad \text { on } \quad O\left(\mathbf{x}_{0}, y_{0}\right)
$$

and $u\left(\mathbf{x}_{0}, y_{0}\right)=w\left(\mathbf{x}_{0}, y_{0}\right)$. We claim that $u=w$ on $O\left(\mathbf{x}_{0}, y_{0}\right)$. Indeed, if there is another point $\left(\mathbf{x}_{2}, y_{2}\right) \in O\left(\mathbf{x}_{0}, y_{0}\right)$ such that $u\left(\mathbf{x}_{2}, y_{2}\right)$ is not equal to $w\left(\mathbf{x}_{2}, y_{2}\right)$, then $u\left(\mathbf{x}_{2}, y_{2}\right)>w\left(\mathbf{x}_{2}, y_{2}\right)$. Then there is a function $u_{0} \in \Xi$, such that

$$
w\left(\mathbf{x}_{2}, y_{2}\right)<u_{0}\left(\mathbf{x}_{2}, y_{2}\right) \leq u\left(\mathbf{x}_{2}, y_{2}\right) .
$$

Now the sequence $\max \left\{u_{0}, M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(v_{k}\right)\right\}$ satisfying

$$
v_{k} \leq \max \left\{u_{0}, M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(v_{k}\right)\right\} \leq u
$$

Then similar to the way we obtain $w, M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(\max \left\{u_{0}, M_{\left(\mathbf{x}_{0}, y_{0}\right)}\left(v_{k}\right)\right\}\right)$ will produce a function $w_{1}$ satisfying

$$
\begin{gathered}
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} w_{1}=p(\mathbf{x}, y) w_{1}^{-\gamma} \quad \text { on } O\left(\mathbf{x}_{0}, y_{0}\right) \\
w \leq w_{1} \quad \text { on } \quad O\left(\mathbf{x}_{0}, y_{0}\right), \quad w\left(\mathbf{x}_{2}, y_{2}\right)<u_{0}\left(\mathbf{x}_{2}, y_{2}\right) \leq w_{1}\left(\mathbf{x}_{2}, y_{2}\right), \\
w\left(\mathbf{x}_{0}, y_{0}\right)=w_{1}\left(\mathbf{x}_{0}, y_{0}\right)=u\left(\mathbf{x}_{0}, y_{0}\right) .
\end{gathered}
$$

That is, $w_{1}(\mathbf{x}, y)-w(\mathbf{x}, y)$ is non-negative, not identically zero on $O\left(\mathbf{x}_{0}, y_{0}\right)$ and achieves its minimum value zero inside $O\left(\mathbf{x}_{0}, y_{0}\right)$. However, from the equations satisfied by $w$ and $w_{1}$, we have that on $O\left(\mathbf{x}_{0}, y_{0}\right)$,

$$
-\sum_{i, j=1}^{n} a_{i, j}(\mathbf{x}, y) D_{i j}\left(w_{1}-w\right)+\gamma p(\mathbf{x}, y)\left(w+\theta\left(w_{1}-w\right)\right)^{-\gamma-1}\left(w_{1}-w\right)=0
$$

for some continuous function $\theta$. Then by the standard maximum principle (for example, see $\left[7\right.$, Theorem 3.5]), we get a contradiction. Thus $u=w$ on $O\left(\mathbf{x}_{0}, y_{0}\right)$. Therefore $u \in C^{2}(\Omega)$ and

$$
-\sum_{i, j=1}^{n} a_{i, j}(\mathbf{x}, y) D_{i j} u=p(\mathbf{x}, y) u^{-\gamma} \quad \text { on } \Omega
$$

When $\left(\mathbf{x}_{0}, y_{0}\right) \in \partial \Omega, \partial O\left(\mathbf{x}_{0}, y_{0}\right) \cap \partial \Omega$ is a neighborhood of $\left(\mathbf{x}_{0}, y_{0}\right)$ in $\partial \Omega$. Since $\max \left\{\tau, v_{k}\right\}=\tau$ on $\partial \Omega, u=\tau$ on $\partial \Omega$ and $w=\tau$ on $\partial O\left(\mathbf{x}_{0}, y_{0}\right) \cap \partial \Omega$. Since $w$ is continuous up to the boundary of $O\left(\mathbf{x}_{0}, y_{0}\right), u$ is continuous on $\partial O\left(\mathbf{x}_{0}, y_{0}\right) \cap \partial \Omega$ from inside $O\left(\mathbf{x}_{0}, y_{0}\right)$. Thus $u \in C^{0}(\bar{\Omega})$ and $u=\tau$ on $\partial \Omega$.

## 4. Proof of Existence

Using the super solution $u$ constructed in Section 3, we can prove the existence of a positive solution of (1.1) exactly in the same way as that in [8] (the generality of the principal term of the elliptic operator will not cause any extra difficulty). We just sketch the proof here.

Since $\Omega$ is an unbounded domain with $C^{2, \alpha}$ boundary, we can choose a sequence of subdomains of $\Omega$, denoted by $\Omega_{m}, m=1,2,3, \ldots$, such that
(1) $\Omega_{m} \subset \Omega_{m+1} \subset \Omega$ for all $m$;
(2) $\cup \Omega_{m}=\Omega$;
(3) each $\Omega_{m}$ is a bounded domain with $C^{2, \alpha}$ boundary;
(4) $\operatorname{dist}\left(0, \partial \Omega \backslash \partial \Omega_{m}\right) \rightarrow \infty$ as $m \rightarrow \infty$.

We can find a number $\mu$, such that for each large $m$, the eigenvalue problem

$$
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} w=\lambda(\mu p(\mathbf{x}, y)) w \quad \text { on } \Omega_{m}, \quad w=0 \quad \text { on } \partial \Omega_{m}
$$

has a first eigenvalue $\lambda_{1}<1$ with its first eigenfunction $\phi_{m}$. We can assume $\max \phi_{m}=1$. Choose $\delta_{m}$ such that $\delta_{m} \leq \frac{1}{2} \tau$ and

$$
\mu p(\mathbf{x}, y) t \leq p(\mathbf{x}, y) t^{-\gamma} \quad \text { for }(\mathbf{x}, y) \in \Omega_{m}, \quad 0<t<\delta_{m}
$$

Then

$$
\begin{equation*}
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} w=p(\mathbf{x}, y) w^{-\gamma} \quad \text { on } \Omega_{m}, \quad w=0 \quad \text { on } \partial \Omega_{m} \tag{4.1}
\end{equation*}
$$

has a pair of super and sub solutions $u(\mathbf{x}, y), \delta_{m} \phi_{m}$. Thus (4.1) has a solution $w_{m}$ that can be proved to satisfy

$$
\begin{array}{ll}
0<w_{m}<u & \text { on } \Omega_{m} \\
\frac{1}{2} \delta_{s} \phi_{s} \leq w_{m} & \text { on } \Omega_{m}
\end{array}
$$

for all $m>s$. Finally we take limit of $w_{m}$ to get a desired solution.

## 5. The General Case

Now we consider the boundary-value problem

$$
\begin{equation*}
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} u=g(\mathbf{x}, y, u) \quad \text { on } \Omega, \quad u=0 \quad \text { on } \partial \Omega . \tag{5.1}
\end{equation*}
$$

In addition to the assumptions on $\left(a_{i j}\right)$ and $\Omega$ given at the beginning of the paper, we assume the following conditions.
(1) Trace $\left.a_{i j}\right)=1$;
(2) There is a constant $c_{1}>0$ such that $a_{n n} \geq c_{1}$ on $\bar{\Omega}$;
(3) There is a family of increasing positive functions $T=T(t)$ satisfying (with $\left.T_{\mathbf{x}}=T(|\mathbf{x}|)\right)$
(a) $\left|T_{\mathbf{x}_{0}}-T_{\mathbf{x}}\right| \leq\left|\mathbf{x}_{0}-\mathbf{x}\right| / c_{5}$;
(b) $g\left(\mathbf{x}, y, T_{\mathbf{x}_{0}}+z_{\mathbf{x}_{0}}\right) \leq c_{2}$ on $\Omega_{\mathbf{x}_{0}}\left(\Omega_{\mathbf{x}_{0}}, z_{\mathbf{x}_{0}}\right.$ and $c_{2}$ are defined in Section 2);
(4) $g(\mathbf{x}, y, t)$ is non-negative, in $C^{1}\left(\bar{\Omega} \times \mathbb{R}_{+}^{n}\right)$ and decreasing on $t$.
(5) $\lim _{t \rightarrow 0^{+}} \frac{g(\mathbf{x}, y, t)}{t} \geq v_{0}(\mathbf{x}, y)$ uniformly for $(\mathbf{x}, y)$ in any bounded subset on $\bar{\Omega}$, where $v_{0}(\mathbf{x}, y)$ is a non-negative function satisfying that when $m$ is large, the eigenvalue problem

$$
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} w=\lambda v_{0}(\mathbf{x}, y) w \text { on } \Omega_{m}, \quad u=0 \text { on } \partial \Omega_{m}
$$

has a first eigenvalue $\lambda_{1}<1$.
Then we have the following conclusion.
Theorem 5.1. Under the assumptions (1)-(5), (5.1) has a positive solution.

Proof. We just sketch the proof here. Assumptions (1)-(3) assure that $T_{\mathbf{x}_{0}}+z_{\mathbf{x}_{0}}$ is a family of auxiliary functions satisfying (2.1) on $\Omega_{\mathbf{x}_{0}}$ and the graphs of these function have the desired relative positions as discussed in Section 2.

Assumption (4) assures that lemma 1 can be applied and the boundary value problem

$$
\begin{equation*}
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} w=g(\mathbf{x}, y, w) \quad \text { in } O\left(\mathbf{x}_{0}, y_{0}\right), \quad w=\operatorname{von} \partial O\left(\mathbf{x}_{0}, y_{0}\right) \tag{5.2}
\end{equation*}
$$

has a unique positive solution for each positive function $v$ on $\bar{\Omega}$. Thus the lift $M_{\left(\mathbf{x}_{0}, y_{0}\right)}$ and the class $\Xi$ of functions are well defined. The proofs of lemmas 2-4 and the existence of the super solution $u$ are the same.

Finally the assumption (5) assures that the proof in Section 4 still works out like that in [8].

Now we apply theorem 3 to the case that $g(\mathbf{x}, y, u)=p(\mathbf{x}, y) e^{-u}$. We consider a modified problem:

$$
\begin{equation*}
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} u=\frac{p(\mathbf{x}, y) e^{-c_{5} u}}{c_{5}} \quad \text { on } \Omega, \quad u=0 \quad \text { on } \partial \Omega \tag{5.3}
\end{equation*}
$$

If we can find a positive solution $u$ of (5.3), then $c_{5} u$ is a positive solution of (1.7).
For (5.3), we set

$$
T(t)=\frac{1}{c_{5}}\left(t+c_{4}\right)+\frac{1}{c_{5}} \ln \frac{C}{c_{2} c_{5}}+A
$$

where $A$ is a positive constant such that $\frac{1}{c_{5}} \ln \frac{C}{c_{5}}+A>1, C$ is defined in (1.5) and $c_{2}, c_{4}, c_{5}$ are defined in Section 2. Then $T(t)$ is increasing and the assumption (3)(a) is obviously satisfied for $T_{\mathbf{x}}=T(|\mathbf{x}|)$. For (3)(b), on $\Omega_{\mathbf{x}_{0}}$,

$$
\begin{aligned}
\frac{1}{c_{5}} p(\mathbf{x}, y) e^{-c_{5}\left(T_{\mathbf{x}_{0}}+z_{\mathbf{x}_{0}}\right)} & \leq \frac{C}{c_{5}} e^{|\mathbf{x}|} e^{-c_{5} T_{\mathbf{x}_{0}}} \\
& \leq \frac{C}{c_{5}} e^{\left|\mathbf{x}_{0}\right|+c_{4}} e^{-c_{5} T_{\mathbf{x}_{0}}} \\
& =\frac{C}{c_{5}} e^{\left|\mathbf{x}_{0}\right|+c_{4}} e^{-\left|\mathbf{x}_{0}\right|-c_{4}-\ln \frac{C}{c_{2} c_{5}}-c_{5} A} \\
& =c_{2} e^{-c_{5} A}<c_{2}
\end{aligned}
$$

Assumption (4) is obvious. For assumption (5), let $\lambda_{1}$ be the first eigenvalue of the eigenvalue problem ( $\Omega_{1}$ is defined in Section 4)

$$
-\sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} w=\lambda p(\mathbf{x}, y) w \quad \text { on } \Omega_{1}, \quad w=0 \quad \text { on } \partial \Omega_{1} .
$$

Set $v_{0}=2 \lambda_{1} p(\mathbf{x}, y)$, then it is easy to see that

$$
\lim _{t \rightarrow 0^{+}} \frac{p(\mathbf{x}, y) e^{-t}}{t} \geq v_{0}(\mathbf{x}, y) \quad \text { uniformly on } \bar{\Omega}
$$

It is also easy to see that $v_{0}$ has the desired property. Thus assumption (5) is satisfied. Therefore we can conclude that Theorem 1.22 is true.
6. Appendix I: Verifications of (2.3), (2.4), (2.6),(2.7)

In this appendix, we verify (2.3)-(2.4) and (2.6)-(2.7) used in Section 2. All the computations here are copied from [10].

Set $\Phi_{1}(\rho)=\rho^{-2}$ if $0<\rho<1$ and $\Phi_{1}(\rho)=\frac{11}{c_{1}}$ if $\rho \geq 1$, and define a function $\chi$ by

$$
\chi(\alpha)=\int_{\alpha}^{\infty} \frac{d \rho}{\rho^{3} \Phi_{1}(\rho)} \quad \text { for } \alpha>0
$$

It is clear that $\chi(\alpha)$ is a decreasing function with range $(0, \infty)$. Let $\eta$ be the inverse of $\chi$. Then $\eta$ is a positive, decreasing function with range $(0, \infty)$. Let $c^{*}=11 / c_{1}$. For $\alpha>1$, we have

$$
\begin{equation*}
\chi(\alpha)=\int_{\alpha}^{\infty} \frac{d \rho}{\rho^{3} \Phi_{1}(\rho)}=\int_{\alpha}^{\infty} \frac{d \rho}{c^{*} \rho^{3}}=\frac{1}{2 c^{*}} \alpha^{-2} \tag{6.1}
\end{equation*}
$$

Thus

$$
\begin{equation*}
\eta(\beta)=\left(2 c^{*} \beta\right)^{-\frac{1}{2}} \quad \text { for } \quad 0<\beta<\left(2 c^{*}\right)^{-1} \tag{6.2}
\end{equation*}
$$

Let $H \geq 2$. Since $\eta(\chi(H))=H$ and $\eta$ is decreasing, we have $\eta(\beta)>H$ for $0<\beta<\chi(H)$. We define a function $A(H)$ by

$$
\begin{equation*}
A(H)=2 M\left(\int_{1}^{e^{\chi(H)}} \eta(\ln t) d t\right)^{-1} \tag{6.3}
\end{equation*}
$$

For the rest of this article, we set $a=A(H)$ and define

$$
\begin{equation*}
h_{a}(r)=\int_{r}^{a e^{\chi(H)}} \eta\left(\ln \frac{t}{a}\right) d t \quad \text { for } a \leq r \leq a e^{\chi(H)} \tag{6.4}
\end{equation*}
$$

Then

$$
\begin{equation*}
h_{a}\left(a e^{\chi(H)}\right)=0, \quad h_{a}(a)=h_{A(H)}(A(H))=2 M \tag{6.5}
\end{equation*}
$$

For $a<r \leq a e^{\chi(H)}$,

$$
\begin{equation*}
h_{a}^{\prime}(r)=-\eta\left(\ln \frac{r}{a}\right)<0,\left|h_{a}^{\prime}(r)\right|>H, \quad h_{a}^{\prime \prime}(r)=\frac{1}{r}\left(\eta\left(\ln \frac{r}{a}\right)\right)^{3} \Phi_{1}\left(\eta\left(\ln \frac{r}{a}\right)\right) \tag{6.6}
\end{equation*}
$$

Thus for $a<r \leq a e^{\chi(H)}$,

$$
\begin{equation*}
\frac{h_{a}^{\prime \prime}(r)}{\left(h_{a}^{\prime}(r)\right)^{2}}=-\frac{h_{a}^{\prime}(r)}{r} \Phi_{1}\left(-h_{a}^{\prime}(r)\right) . \tag{6.7}
\end{equation*}
$$

Let $h_{a}^{-1}$ be the inverse of $h_{a}$. Then $h_{a}^{-1}$ is decreasing and

$$
\begin{equation*}
h_{a}^{-1}(0)=A(H) e^{\chi(H)}, \quad h_{a}^{-1}(2 M)=A(H) \tag{6.8}
\end{equation*}
$$

Thus we have the first half of (2.3). Further for $-M \leq y \leq M$,

$$
\left(h_{a}^{-1}\right)^{\prime}(y+M)=\frac{1}{h_{a}^{\prime}\left(h_{a}^{-1}(y+M)\right)}
$$

$$
\begin{aligned}
\left(h_{a}^{-1}\right)^{\prime \prime}(y+M) & =\left(\frac{1}{h_{a}^{\prime}\left(h_{a}^{-1}(y+M)\right)}\right)^{\prime} \\
& =-\frac{h_{a}^{\prime \prime}\left(h_{a}^{-1}(y+M)\right)\left(h_{a}^{-1}\right)^{\prime}(y+M)}{\left(h_{a}^{\prime}\left(h_{a}^{-1}(y+M)\right)\right)^{2}} \\
& =-\frac{h_{a}^{\prime \prime}\left(h_{a}^{-1}(y+M)\right)}{\left(h_{a}^{\prime}\left(h_{a}^{-1}(y+M)\right)\right)^{3}} \\
& =\frac{1}{h_{a}^{-1}(y+M)} \Phi_{1}\left(-h_{a}^{\prime}\left(h_{a}^{-1}(y+M)\right)\right)
\end{aligned}
$$

Thus

$$
\begin{equation*}
\left(h_{a}^{-1}\right)^{\prime \prime}(y+M) h_{a}^{-1}(y+M)=\Phi_{1}\left(-h_{a}^{\prime}\left(h_{a}^{-1}(y+M)\right)\right) . \tag{6.9}
\end{equation*}
$$

Now we choose an $H_{0}>2$ such that for $H \geq H_{0}$,

$$
\begin{equation*}
H_{0}>\frac{1}{\sqrt{2 c^{*}}}+3 M+4+\frac{24 n c_{1} K}{M}, \quad \sqrt{\frac{4 K}{A(H) e^{\chi(H)}}} \leq \frac{1}{\sqrt{2}} \tag{6.10}
\end{equation*}
$$

Then we have (2.4). For $H>H_{0}$, by (6.1), (6.2), we have

$$
\begin{aligned}
A(H)^{-1} & =(2 M)^{-1} \int_{1}^{e^{\chi(H)}} \eta(\ln t) d t \\
& =(2 M)^{-1} \int_{0}^{\chi(H)} \eta(m) e^{m} d m \\
& =(2 M)^{-1} \int_{0}^{\chi(H)} \frac{e^{m}}{\sqrt{2 c^{*} m}} d m
\end{aligned}
$$

From

$$
\frac{1}{\sqrt{2 c^{*}}} \int_{0}^{\chi(H)} \frac{1}{\sqrt{m}} d m \leq \int_{0}^{\chi(H)} \frac{e^{m}}{\sqrt{2 c^{*} m}} d m \leq \frac{e^{\chi(H)}}{\sqrt{2 c^{*}}} \int_{0}^{\chi(H)} \frac{1}{\sqrt{m}} d m
$$

we have

$$
\frac{1}{c^{*} H}=\frac{2 \sqrt{\chi(H)}}{\sqrt{2 c^{*}}} \leq \int_{0}^{\chi(H)} \frac{e^{m}}{\sqrt{2 c^{*} m}} d m \leq \frac{2 e^{\chi(H)} \sqrt{\chi(H)}}{\sqrt{2 c^{*}}}=\frac{e^{\frac{1}{2 c^{*} H^{2}}}}{c^{*} H}
$$

Thus

$$
\begin{equation*}
2 M c^{*} H \geq A(H) \geq 2 M c^{*} H e^{-\chi(H)}=2 M c^{*} H e^{-\frac{1}{2 c^{*} H^{2}}} \tag{6.11}
\end{equation*}
$$

Thus we have the second half of (2.3) since $c^{*}=11 / c_{1}$.
For $\mathbf{x}_{0} \in \mathbb{R}^{n-1}$, and a fixed constant $K$, we define a domain $\Omega_{\mathbf{x}_{0}, H, K}$ in $(\mathbf{x}, y)$ space by (2.8) and define a function $z=z(\mathbf{x}, y)$ by (2.5). Since $h_{a}^{-1}(y+M) \geq 0$ for $|y| \leq M,\left(\mathbf{x}_{0}, y\right) \in \Omega_{\mathbf{x}_{0}, H, K}$ for $|y|<M$. Further it is clear that the function $z=z(\mathbf{x}, y)$ is well defined on $\Omega_{\mathbf{x}_{0}, H, K}$.

Now we verify the first half of (2.7), on $\partial \Omega_{\mathbf{x}_{0}, H, K} \cap\{(\mathbf{x}, y):|y|<M\}$,

$$
\left|\mathbf{x}-\mathbf{x}_{0}\right|=\sqrt{\frac{2 K}{A(H) e^{\chi(H)}}} h^{-1}(y+M)
$$

then from (6.8), we have

$$
\begin{aligned}
z & =A(H) e^{\chi(H)}-\left\{\left(h_{a}^{-1}(y+M)\right)^{2}-\left|\mathbf{x}-\mathbf{x}_{0}\right|^{2}\right\}^{1 / 2} \\
& =A(H) e^{\chi(H)}-h_{a}^{-1}(y+M)\left(1-\frac{2 K}{A(H) e^{\chi(H)}}\right)^{1 / 2} \\
& \geq A(H) e^{\chi(H)}-A(H) e^{\chi(H)}\left(1-\frac{2 K}{A(H) e^{\chi(H)}}\right)^{1 / 2} \\
& \geq A(H) e^{\chi(H)}\left(1-\left(1-\frac{2 K}{2 A(H) e^{\chi(H)}}\right)\right)=K .
\end{aligned}
$$

Here we have used (6.10) and the fact that $\sqrt{1-t} \leq 1-\frac{1}{2} t$ for $0<t<1$. For the second half of (2.7), since $h_{a}^{-1}(r)$ and $\eta$ are decreasing functions, we have

$$
\begin{align*}
\frac{-1}{h_{a}^{\prime}\left(h_{a}^{-1}(y+M)\right)} & =\frac{1}{\eta\left(\ln \left(\frac{1}{a} h_{a}^{-1}(y+M)\right)\right)} \\
& \leq \frac{1}{\eta\left(\ln e^{\chi(H)}\right)}  \tag{6.12}\\
& =\frac{1}{\eta(\chi(H))}=\frac{1}{H}, \quad \text { for }|y| \leq-M
\end{align*}
$$

Then by (2.5), we have

$$
\frac{\partial z}{\partial y}\left(\mathbf{x}_{0}, y\right)=\frac{-1}{h_{a}^{\prime}\left(h_{a}^{-1}(y+M)\right)} \leq \frac{1}{H}, \quad \text { for }|y| \leq-M
$$

Now the second half of (2.7) follows from this and

$$
z\left(\mathbf{x}_{0},-M\right)=A(H) e^{\chi(H)}-h_{a}^{-1}(0)=A(H) e^{\chi(H)}-A(H) e^{\chi(H)}=0
$$

For (2.6), we set $S=\left\{\left(h_{a}^{-1}(y+M)\right)^{2}-\left|\mathbf{x}-\mathbf{x}_{0}\right|^{2}\right\}^{1 / 2}$. Then we have that for $1 \leq i \leq n-1$,

$$
\frac{\partial z}{\partial x_{i}}=\frac{1}{S}\left(x_{i}-x_{0 i}\right), \quad \frac{\partial z}{\partial y}=-\frac{1}{S} h_{a}^{-1}\left(h_{a}^{-1}\right)^{\prime}
$$

By (6.10) and (6.11), on $\Omega_{\mathbf{x}_{0}, H, K}$, we have

$$
\frac{1}{2} h_{a}^{-1}(y+M) \leq S \leq h_{a}^{-1}(y+M)
$$

and

$$
\frac{\left|\mathbf{x}-\mathbf{x}_{0}\right|}{S} \leq 2\left(\frac{2 K}{A(H) e^{\chi(H)}}\right)^{1 / 2} \leq 2\left(\frac{2 K}{2 M c^{*} H}\right)^{1 / 2}
$$

Thus, by (6.12), we have

$$
\begin{equation*}
\left|\frac{\partial z}{\partial x_{i}}\right| \leq 2\left(\frac{c_{1} K}{M H}\right)^{1 / 2}, \quad\left|\frac{\partial z}{\partial y}\right| \leq \frac{h_{a}^{-1}(y+M)}{S \mid h_{a}^{\prime}\left(h_{a}^{-1}(y+M) \mid\right.} \leq \frac{2}{H} . \tag{6.13}
\end{equation*}
$$

Hence from (6.10), and the assumption that Trace $a_{i j}$ ) $=1$ (hence all eigenvalues of $\left(a_{i j}\right)$ are less than or equal to 1$)$, we have

$$
\begin{equation*}
\left|\sum_{i, j=1}^{n} a_{i j} \frac{\partial z}{\partial x_{i}} \frac{\partial z}{\partial x_{j}}\right| \leq|D z|^{2} \leq 1 \tag{6.14}
\end{equation*}
$$

Now we have

$$
\begin{aligned}
Q z= & \sum_{i, j=1}^{n} a_{i j}(\mathbf{x}, y) D_{i j} z \\
= & \frac{1}{S} \sum_{i=1}^{n-1} a_{i i}+\frac{1}{S^{3}} \sum_{i, j=1}^{n-1} a_{i j}\left(x_{i}-x_{i}^{0}\right)\left(x_{j}-x_{j}^{0}\right)-\frac{1}{S^{3}} \sum_{i=1}^{n-1} a_{i n}\left(x_{i}-x_{i}^{0}\right) h_{a}^{-1}\left(h_{a}^{-1}\right)^{\prime} \\
& -\frac{1}{S} a_{n n}\left(\left(h_{a}^{-1}\right)^{2}+h_{a}^{-1}\left(h_{a}^{-1}\right)^{\prime \prime}\right)+\frac{1}{S^{3}} a_{n n}\left(h_{a}^{-1}\right)^{2}\left(\left(h_{a}^{-1}\right)^{\prime}\right)^{2} \\
= & \frac{1}{S}\left\{1-a_{n n}+\sum_{i, j=1}^{n} a_{i j} \frac{\partial z}{\partial x_{i}} \frac{\partial z}{\partial x_{j}}-a_{n n}\left(\left(h_{a}^{-1}\right)^{2}+h_{a}^{-1}\left(h_{a}^{-1}\right)^{\prime \prime}\right)\right\} \quad\left(\text { since } a_{n n}>0\right) \\
\leq & \frac{1}{S}\left\{1+\sum_{i, j=1}^{n} a_{i j} \frac{\partial z}{\partial x_{i}} \frac{\partial z}{\partial x_{j}}-a_{n n} h_{a}^{-1}\left(h_{a}^{-1}\right)^{\prime \prime}\right\} .
\end{aligned}
$$

By (2.2), (6.9)), (6.11) and (6.14)) the above expression is bounded by

$$
\frac{-9}{S} \leq \frac{-9}{h_{a}^{-1}(y+M)} \leq \frac{-9}{A(H) e^{\chi(H)}} \leq \frac{-9}{2 M c^{*} H e^{\frac{1}{2 c^{*} H^{2}}}} \leq \frac{-3 c_{1}}{22 e M H}
$$

This shows (2.6).

## 7. Appendix II: A Construction of the Domain $J$

In this part, we give a construction of the domain $J$ used at the end of Section 2 in the definition of $\Pi$. Let

$$
\begin{gathered}
\mathbb{R}_{+}^{n}=\left\{\left(y_{1}, y_{2}, \ldots, y_{n}\right) \mid y_{n}>0\right\} \\
J_{1}=\left\{\left(y_{1}, y_{n}\right): y_{1}= \pm 1,\left|y_{n}\right| \leq 1 \text { or } y_{n}= \pm 1,\left|y_{1}\right| \leq 1\right\}
\end{gathered}
$$

That is, $J_{1}$ is a square with side length 2 and center $(0,0)$ in $\left(y_{1}, y_{n}\right)$ plane. In polar coordinate we can write $\partial J_{1}$ as

$$
\left(y_{1}, y_{n}\right)=(k(\theta) \cos \theta, k(\theta) \sin \theta), \quad 0 \leq \theta \leq 2 \pi,
$$

where $k(\theta)$ is a positive, continuous, periodic function of period $2 \pi, k(\theta)$ is $C^{\infty}$ except at $\theta= \pm \frac{\pi}{4}, \pm \frac{3 \pi}{4}$. Then we can smooth out $k(\theta)$ near those points to get a function $k_{1}(\theta)$ such that $k_{1}(\theta)$ is a positive, $C^{\infty}$, periodic function of period $2 \pi$, $k_{1}(\theta)=k(\theta)$ except in some small neighborhoods of $\theta= \pm \frac{\pi}{4}, \pm \frac{3 \pi}{4}$, and $k_{1}(\theta) \leq k(\theta)$ for all $\theta$. Indeed we can modify $k(\theta)$ as follows:

Let $s(t)$ be a $C^{\infty}$ function satisfying
(1) $s(t)=0$ if $t \leq 1$;
(2) $0<s(t) \leq \frac{1}{8}$ if $1<t \leq 2$;
(3) $s(t) \geq 0$ for all $t$;
(4) $s(t)=1$ if $t \geq 4$.

Fixed a positive constant $\epsilon<\frac{\pi}{100}$. Near $\theta=\frac{\pi}{4}$, we define

$$
k_{1}(\theta)=k(\theta) s\left(\frac{1}{\epsilon}\left|\theta-\frac{\pi}{4}\right|\right)+\frac{1}{8}\left(1-s\left(\frac{2}{\epsilon}\left|\theta-\frac{\pi}{4}\right|\right)\right)
$$

Then using the fact that $\max k(\theta)=\sqrt{2}, \min k(\theta)=1$, we can verify that $k_{1}(\theta)$ is positive, smooth and

$$
k_{1}(\theta)=k(\theta) \quad \text { if } \quad\left|\theta-\frac{\pi}{4}\right| \geq 4 \epsilon ; \quad 0<k_{1}(\theta) \leq k(\theta)
$$

In a similar way, we can modify $k(\theta)$ near other points $-\pi / 4$ and $\pm 3 \pi / 4$. Now let $J_{2}$ be the domain in $\left(y_{1}, y_{n}\right)$ plane bounded by the curve

$$
\left(y_{1}, y_{n}\right)=\left(k_{1}(\theta) \cos \theta, k_{1}(\theta) \sin \theta\right), \quad 0 \leq \theta \leq 2 \pi
$$

We then rotate the set

$$
\left\{\left(y_{1}, 0, \cdot, \cdot, \cdot, 0, y_{n}\right):\left(y_{1}, y_{n}\right) \in J_{2}\right\}
$$

with respect to $y_{n}$ axis to get a domain $J_{3}$. Finally, $J$ is obtained from $J_{3}$ by appropriate translation and scaling.

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