Electronic Journal of Differential Equations, Vol. 2005(2005), No. 76, pp. 1-13. ISSN: 1072-6691. URL: http://ejde.math.txstate.edu or http://ejde.math.unt.edu ftp ejde.math.txstate.edu (login: ftp)

# OSCILLATION OF SECOND-ORDER NONLINEAR DIFFERENTIAL EQUATIONS WITH A DAMPING TERM 

ELMETWALLY M. ELABBASY, TAHER S. HASSAN, SAMIR H. SAKER


#### Abstract

This paper concerns the oscillation of solutions to the differential equation $$
\left(r(t) x^{\prime}(t)\right)^{\prime}+p(t) x^{\prime}(t)+q(t) g(x(t))=0,
$$ where $x g(x)>0$ for all $x \neq 0, r(t)>0$ for $t \geq t_{0}>0$. No sign conditions are imposed on $p(t)$ and $q(t)$. Our results solve the open problem posed by Rogovchenko [27], complement the results in Sun [29], and improve a number of existing oscillation criteria. Our main results are illustrated with examples.


## 1. Introduction

This paper concerned with oscillation of the solutions to the second-order nonlinear differential equation with damping term:

$$
\begin{equation*}
\left(r(t) x^{\prime}(t)\right)^{\prime}+p(t) x^{\prime}(t)+q(t) g(x(t))=0, \quad t \geq t_{0} \tag{1.1}
\end{equation*}
$$

where $q$ and $p$ are continuous functions defined on the interval $\left[t_{0}, \infty\right), t_{0}>0$ and $r(t)>0$ for $t \geq t_{0}>0, g$ is a continuous function for $x \in(-\infty, \infty)$, continuously differentiable and satisfies

$$
\begin{equation*}
x g(x)>0, \quad g^{\prime}(x) \geq k>0 \quad \text { for all } x \neq 0 \tag{1.2}
\end{equation*}
$$

Equation (1.1) is said to be superlinear if

$$
\begin{equation*}
\int_{ \pm \epsilon}^{ \pm \infty} \frac{1}{g(u)} d u<\infty \quad \text { for } \epsilon>0 \tag{1.3}
\end{equation*}
$$

and sublinear if

$$
\begin{equation*}
\int_{0}^{ \pm \epsilon} \frac{1}{g(u)} d u<\infty \quad \text { for } \epsilon>0 \tag{1.4}
\end{equation*}
$$

We restrict our attention to those solutions of 1.1 which exist on some half line $\left[t_{x}, \infty\right)$ and satisfy $\sup \{|x(t)|: t>T\}>0$ for any $T \geq t_{x}$. We make a standing hypothesis that (1.1) does possess such solutions. A solution of 1.1 is said to be oscillatory if it has arbitrarily large zeros; otherwise it is non-oscillatory. The equation itself is called oscillatory if all its solutions are oscillatory.

[^0]In the previous two decades, there has been increasing interest in obtaining sufficient conditions for the oscillation and non-oscillation of solutions of different classes of second order differential equations, see for example 4, 5, 6, 7, 8, 11, 12, 14, $15,16,17,19,23,24,25,26,27,28,29$ and the references therein.
a lot of work has been done on the following particular cases of (1.1):

$$
\begin{gather*}
x^{\prime \prime}(t)+q(t) x(t)=0  \tag{1.5}\\
\left(r(t) x^{\prime}(t)\right)^{\prime}+q(t) x(t)=0  \tag{1.6}\\
\left(r(t) x^{\prime}(t)\right)^{\prime}+q(t) g(x(t))=0 \tag{1.7}
\end{gather*}
$$

An important tool in the study of oscillatory behavior of solutions of these equations is the averaging technique which goes back as far as the classical result of Wintner $[32$ which proved that 1.5 is oscillatory if

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \frac{1}{t} \int_{t_{0}}^{t} \int_{t_{0}}^{t} q(v) d v d s=\infty \tag{1.8}
\end{equation*}
$$

Hartman [14] proved that that the limit in 1.8) cannot be replaced by the limit supremum and proved that the condition

$$
\begin{equation*}
-\infty<\lim _{t \rightarrow \infty} \inf \frac{1}{t} \int_{t_{0}}^{t} \int_{t_{0}}^{s} q(v) d v d s<\lim _{t \rightarrow \infty} \sup \frac{1}{t} \int_{t_{0}}^{t} \int_{t_{0}}^{s} q(v) d v d s \leq \infty \tag{1.9}
\end{equation*}
$$

implies that every solution of 1.5 oscillates.
Kamenev [15] improved Wintner's result by proving that the condition

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \frac{1}{t^{n}} \int_{t_{0}}^{t}(t-s)^{n} q(s) d s=\infty \tag{1.10}
\end{equation*}
$$

for some integer $n>1$ is sufficient for the oscillation of 1.5 .
Yan 36] proved that if

$$
\limsup _{t \rightarrow \infty} \frac{1}{t^{n}} \int_{t_{0}}^{t}(t-s)^{n} q(s) d s<\infty
$$

for some integer $n>1$ and there exists a function $\phi$ on $\left[t_{0}, \infty\right)$ satisfying

$$
\int t_{0}^{\infty} \phi_{+}^{2}(t) d t=\infty
$$

where $\phi_{+}(t)=\max \{\phi(t), 0\}$ such that

$$
\limsup _{t \rightarrow \infty} \frac{1}{t^{n}} \int_{t_{0}}^{t}(t-s)^{n} q(s) d s>\sup _{u \geq t_{0}} \phi(u)
$$

then every solution of equation (1.5) oscillates.
Philos [24] further improved Kamenev's result by proving the following: Suppose there exist continuous functions $H, h: D \equiv\left\{(t, s): t \geq s \geq t_{0}\right\} \rightarrow \mathbb{R}$ such that

$$
\begin{gather*}
H(t, t)=0, \quad t \geq t_{0} \\
H(t, s)>0, \quad t>s \geq t_{0} \tag{1.11}
\end{gather*}
$$

and $H$ has a continuous and nonpositive partial derivative on $D$ with respect to the second variable and satisfies

$$
\begin{equation*}
-\frac{\partial H(t, s)}{\partial s}=h(t, s) \sqrt{H(t, s)} \geq 0 \tag{1.12}
\end{equation*}
$$

Further, suppose that

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \frac{1}{H\left(t, t_{0}\right)} \int_{t_{0}}^{t}\left[H(t, s) q(s)-\frac{1}{4} h^{2}(t, s)\right] d s=\infty \tag{1.13}
\end{equation*}
$$

Then every solution of equation 1.5 oscillates.
We note, however, that when $q(t)=\frac{\gamma}{t^{2}}, 1.5$ reduces to the well known Euler equation

$$
\begin{equation*}
u^{\prime \prime}(t)+\frac{\gamma}{t^{2}} u(t)=0, \quad t \geq 1 \tag{1.14}
\end{equation*}
$$

to which none of the above mentioned oscillation criteria is applicable. In fact, the Euler equation 1.14 is oscillatory if $\gamma>\frac{1}{4}$, and non-oscillatory if $\gamma \leq \frac{1}{4}$, see [17. For further results on the oscillation of superlinear and sublinear equations, we refer the reader to [6, $7,8,31$.

For the oscillation of 1.6 ), Leighton (19] proved that if:

$$
\begin{equation*}
\int_{t_{0}}^{\infty} \frac{d t}{r(t)}=\infty \quad \text { and } \quad \int_{t_{0}}^{\infty} q(t) d t=\infty \tag{1.15}
\end{equation*}
$$

then every solution of 1.6 oscillates.
Willett [30] used the transformation

$$
\tau=\left(\int_{t}^{\infty} \frac{d s}{r(s)}\right)^{-1}, \quad u(t)=\tau^{-1} y(t)
$$

to establish a new version of Leighton's criterion and obtained the following oscillation criteria: If

$$
\begin{equation*}
\int_{t_{0}}^{\infty} \frac{d t}{r(t)}=\infty \quad \text { and } \quad \int_{t_{0}}^{\infty} q(t)\left(t \int_{t}^{\infty} \frac{d s}{r(s)}\right)^{2} d t=\infty \tag{1.16}
\end{equation*}
$$

then every solution of 1.6 oscillates.
We note, however, that the oscillation criteria of Leighton and Willett are not applicable to the equation

$$
\begin{equation*}
\left(t^{2} u^{\prime}(t)\right)^{\prime}+\gamma u(t)=0, \quad t>0 \tag{1.17}
\end{equation*}
$$

where $\gamma$ is a positive constant. Kong [17], Li [21, Li and Yeh [22, Rogovechenkov [25], and Yu [38] used the generalized Riccati technique and have given several sufficient conditions for oscillation of (1.6) which can be applied to (1.17); in fact every solution of 1.17 ) oscillates if $\gamma>\frac{1}{4}$; see [22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38.

In the study of the differential equation (1.7), many criteria for oscillation exist which involve the behavior of the integral of $q$ however the common restrictions that

$$
q(t)>0, \quad g^{\prime}(u)>0 \quad \text { for } u \neq 0, \quad \int_{t_{0}}^{\infty} \frac{d t}{r(t)}=\infty
$$

on the functions $q, g$ and $r$ are required; see for example [4, [5, 11, 12 .
The presence of the damping term in (1.1) calls for a modified approach to the study of the oscillatory properties of solutions, see for example the paper by Saker, Peng and Agarwal [28, Li, Wang and Yan [23] and the references therein. They cited most of the oscillation results for 1.1 when $p(t)$ and $q(t)$ are positive functions.

Recently, Rogovechenko et al. [27] considered (1.1) and established some sufficient conditions for oscillations. They posed the following open problem: It would
be very important to obtain general oscillation criteria for nonlinear differential equations with damping term without requiring additional sign conditions on the coefficients $p(t)$ and $q(t)$.

In this paper, we consider 1.1) and by using a Riccati transformation technique, we establish some oscillation criteria of Kamanev and Philos type with no sign conditions on $p(t)$ and $q(t)$. Our results in this paper are the affirmative answer to the question posed by Rogovechenko et al. [27] and improve and complement the results established by Sun [29].

## 2. Main Results

In this section, we will use the Riccati technique to establish sufficient conditions for oscillation of (1.1). Comparisons between our results and the previously known are presented and some examples illustrate the main results.

Theorem 2.1. Assume that (1.2) and (1.3) hold. Furthermore, suppose that there exists a function $\rho:\left[t_{0}, \infty\right) \rightarrow(0, \infty)$ such that:

$$
\begin{gather*}
\rho^{\prime}(t) \geq 0, \quad(r(t) \rho(t))^{\prime} \geq 0, \quad(r(t) \rho(t))^{\prime \prime} \leq 0, \quad\left[r(t) \rho^{\prime}(t)-\rho(t) p(t)\right]^{\prime} \leq 0  \tag{2.1}\\
\liminf _{t \rightarrow \infty} \int_{t_{0}}^{t} \rho(s) q(s) d s>-\infty  \tag{2.2}\\
\limsup _{t \rightarrow \infty} \frac{1}{t} \int_{t_{0}}^{t}\left[\int_{t_{0}}^{s} \rho(u) q(u) d u\right]^{2} d s=\infty \tag{2.3}
\end{gather*}
$$

Then 1.1 is oscillatory.
Proof. Suppose to the contrary that (1.1) possesses a non-oscillatory solution $x$ on an interval $[T, \infty), T \geq t_{0}$. Without loss of generality, we shall assume that $x(t)>0$ for all $t \geq T$ (the case $x(t)<0$ can be treated similarly and will be omitted). Let $w(t)$ be defined by the Riccati transformation

$$
w(t)=\frac{\rho(t) r(t) x^{\prime}(t)}{g(x(t))}
$$

This and (1.1) imply for $t \geq T$ that

$$
\begin{equation*}
w^{\prime}(t)=-\rho(t) q(t)+\frac{x^{\prime}(t)}{g(x(t))}\left[r(t) \rho^{\prime}(t)-\rho(t) p(t)\right]-\frac{g^{\prime}(x(t)) w^{2}(t)}{\rho(t) r(t)} \tag{2.4}
\end{equation*}
$$

We consider the following two cases:
Case 1. the integral $\int_{T}^{\infty} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s$ is finite. Then there exists a positive constant $N$ such that

$$
\begin{equation*}
\int_{T}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s \leq N \quad \text { for all } t \geq T \tag{2.5}
\end{equation*}
$$

Now, from 2.4,

$$
\begin{align*}
& \int_{t_{0}}^{t} \rho(s) q(s) d s \\
& =\int_{t_{0}}^{T} \rho(s) q(s) d s+\int_{T}^{t} \rho(s) q(s) d s  \tag{2.6}\\
& =-w(t)+c_{1}+\int_{T}^{t}\left[r(s) \rho^{\prime}(s)-\rho(s) p(s)\right] \frac{x^{\prime}(s)}{g(x(s))} d s-\int_{T}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s
\end{align*}
$$

where $c_{1}=w(T)+\int_{t_{0}}^{T} \rho(s) q(s) d s$. By Bonnet's theorem since $r(t) \rho^{\prime}(t)-\rho(t) p(t)$ is non-increasing, for a fixed $t \geq T$, there exists $\xi \in[T, t]$ such that

$$
\begin{aligned}
\int_{T}^{t}\left[r(s) \rho^{\prime}(s)-\rho(s) p(s)\right] \frac{x^{\prime}(s)}{g(x(s))} d s & =\left[r(T) \rho^{\prime}(T)-\rho(T) p(T)\right] \int_{T}^{\xi} \frac{x^{\prime}(s)}{g(x(s))} d s \\
& =\left[r(T) \rho^{\prime}(T)-\rho(T) p(T)\right] \inf _{x(T)} \frac{1}{g(u)} d u
\end{aligned}
$$

Since $\left[r(T) \rho^{\prime}(T)-\rho(T) p(T)\right] \geq 0$ and

$$
\int_{x(T)}^{x(\xi)} \frac{1}{g(u)} d u< \begin{cases}0 & \text { if } x(\xi) \leq x(T) \\ \int_{x(T)}^{\infty} \frac{1}{g(u)} d u & \text { if } x(\xi) \geq x(T)\end{cases}
$$

we have

$$
\begin{equation*}
-\infty<\int_{T}^{t}\left[r(s) \rho^{\prime}(s)-\rho(s) p(s)\right] \frac{x^{\prime}(s)}{g(x(s))} d s \leq k_{1} \tag{2.7}
\end{equation*}
$$

where

$$
k_{1}=\left[r(T) \rho^{\prime}(T)-\rho(T) p(T)\right] \int_{x(T)}^{\infty} \frac{1}{g(u)} d u
$$

Thus, for $t \geq T$,

$$
\begin{aligned}
& {\left[\int_{t_{0}}^{t} \rho(s) q(s) d s\right]^{2}} \\
& =\left\{c_{1}-w(t)+\int_{T}^{t}\left[r(s) \rho^{\prime}(s)-\rho(s) p(s)\right] \frac{x^{\prime}(s)}{g(x(s))} d s-\int_{T}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s\right\}^{2} \\
& \leq 4 c_{1}^{2}+4(w(t))^{2}+4\left[\int_{T}^{t}\left[r(s) \rho^{\prime}(s)-\rho(s) p(s)\right] \frac{x^{\prime}(s)}{g(x(s))} d s\right]^{2} \\
& \quad+4\left[\int_{T}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s\right]^{2} .
\end{aligned}
$$

Therefore, taking into account 2.5 and 2.7, we conclude that

$$
\left[\int_{t_{0}}^{t} \rho(s) q(s) d s\right]^{2} \leq c_{2}+4(w(t))^{2}
$$

where

$$
c_{2}=4 c_{1}^{2}+4\left[\int_{T}^{t}\left[r(s) \rho^{\prime}(s)-\rho(s) p(s)\right] \frac{x^{\prime}(s)}{g(x(s))} d s\right]^{2}+4\left[\int_{T}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s\right]^{2} .
$$

Thus, for every $t \geq T$,

$$
\begin{aligned}
\int_{t_{0}}^{t}\left[\int_{t_{0}}^{s} \rho(u) q(u) d u\right]^{2} d s & =\int_{t_{0}}^{T}\left[\int_{t_{0}}^{s} \rho(u) q(u) d u\right]^{2} d s+\int_{T}^{t}\left[\int_{t_{0}}^{s} \rho(u) q(u) d u\right]^{2} d s \\
& =c_{3}+\int_{T}^{t}\left[\int_{t_{0}}^{s} \rho(u) q(u) d u\right] d s \\
& \leq c_{3}+c_{2}(t-T)+4 \int_{T}^{t} w^{2}(s) d s \\
& \leq c_{3}+c_{2}(t-T)+\frac{4}{k} \int_{T}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} r(s) \rho(s) d s
\end{aligned}
$$

since $r(t) \rho(t)$ is positive and nondecreasing for $t \in\left[t_{0}, \infty\right)$, Bonnet's theorem ensures the existence of $T_{1} \in[T, t]$ such that

$$
\int_{T}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} r(s) \rho(s) d s=r(t) \rho(t) \int_{T_{1}}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s
$$

Also, since $r(t) \rho(t)$ is positive on $\left[t_{0}, \infty\right)$ and $(r(t) \rho(t))^{\prime}$ is nonnegative and bounded above, it follows that $r(t) \rho(t) \leq \beta t$ for all large $t$ where $\beta>0$ is a constant and this implies that

$$
\int_{t_{0}}^{\infty} \frac{1}{\rho(s) r(s)} d s=\infty
$$

Thus, we conclude that

$$
\int_{t_{0}}^{t}\left[\int_{t_{0}}^{s} \rho(u) q(u) d u\right]^{2} d s \leq c_{3}+c_{2}(t-T)+\frac{4 \beta}{k} t \int_{T_{1}}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s
$$

So, we have

$$
\limsup _{t \rightarrow \infty} \frac{1}{t} \int_{t_{0}}^{t}\left[\int_{t_{0}}^{s} \rho(u) q(u) d u\right]^{2} d s \leq c_{2}+\frac{4 \beta}{k} N<\infty
$$

which contradicts 2.3).
Case 2. The integral $\int_{T}^{\infty} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s$ is infinite. From (2.4), taking into account (2.6) and 2.7), for every $t \geq T$ we obtain

$$
\begin{equation*}
\int_{t_{0}}^{t} \rho(s) q(s) d s \leq-w(t)+A-\int_{T}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s \tag{2.8}
\end{equation*}
$$

where $A=c_{1}+k_{1}$. By the condition 2.2, from 2.8), it follows that for some constant $B$,

$$
\begin{equation*}
-w(t) \geq B+\int_{T}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s \quad \text { for every } t \geq T \tag{2.9}
\end{equation*}
$$

We can consider a $T_{2} \geq T$ such that

$$
C=B+\int_{T}^{T_{2}} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s>0
$$

Then 2.9) ensures that $w(t)$ is negative on $\left[T_{2}, \infty\right)$. Now, 2.9) gives

$$
\frac{g^{\prime}(x(t)) w^{2}(t)}{\rho(t) r(t)}\left(B+\int_{T}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s\right)^{-1} \geq \frac{g^{\prime}(x(t)) x^{\prime}(t)}{g(x(t))}, \quad t \geq T_{2}
$$

and consequently for all $t \geq T_{2}$,

$$
\log \frac{B+\int_{T}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s}{C} \geq \log \frac{g\left(x\left(T_{2}\right)\right)}{g(x(t))}
$$

Hence,

$$
B+\int_{T}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s \geq C \frac{g\left(x\left(T_{2}\right)\right)}{g(x(t))}, \quad t \geq T_{2}
$$

So, 2.9) yields

$$
x^{\prime}(t) \leq \frac{-C^{\prime}}{\rho(t) r(t)}, \quad t \geq T_{2}
$$

where $C^{\prime}=C g\left(x\left(T_{2}\right)\right)>0$. Thus, we have

$$
x(t) \leq x\left(T_{2}\right)-C^{\prime} \int_{T}^{t} \frac{1}{\rho(s) r(s)} d s \quad \text { for all } t \geq T_{2}
$$

which leads to $\lim _{t \rightarrow \infty} x(t)=-\infty$, which is a contradiction. This completes the proof.

Example 2.2. Consider the differential equation

$$
\begin{equation*}
\left(t^{\frac{1}{2}} x^{\prime}(t)\right)^{\prime}-\frac{1}{t} x^{\prime}(t)+t^{\frac{-3}{2}}\left(x^{2}(t) \operatorname{sgn} x(t)+x(t)\right)=0, \quad t \geq 1 \tag{2.10}
\end{equation*}
$$

Here $p(t)=\frac{-1}{t}, q(t)=t^{-3 / 2}$ and $g(x)=x^{2} \operatorname{sgn} x+x$. We see that $p, q$ and $g$ satisfy conditions (1.2), (1.3) and 2.1. To apply Theorem 2.1. It remains to prove that (2.2) and 2.3 hold. By choosing $\rho(t)=t^{1 / 2}$ we see that

$$
\begin{gathered}
\liminf _{t \rightarrow \infty} \int_{1}^{t} \rho(s) q(s) d s=\liminf _{t \rightarrow \infty} \int_{1}^{t} s^{-1} d s>-\infty \\
\limsup _{t \rightarrow \infty} \frac{1}{t} \int_{1}^{t}\left[\int_{1}^{s} q(u) d u\right]^{2} d s=\limsup _{t \rightarrow \infty} \frac{2}{t} \int_{1}^{t}\left[1-\frac{1}{\sqrt{s 2}}\right]^{2} d s<\infty \\
\limsup _{t \rightarrow \infty} \frac{1}{t} \int_{1}^{t}\left[\int_{1}^{s} \rho(u) q(u) d u\right]^{2} d s=\infty
\end{gathered}
$$

Thus Theorem 2.1 ensures that every solution of 2.10 oscillates. Note that that the results from Wong [33, 34, and Bhatia [4] can not be applied to 2.10.

Example 2.3. Consider the differential equation

$$
\begin{equation*}
\left(\frac{1}{t} x^{\prime}(t)\right)^{\prime}+\left(\frac{1}{2}+\sin t\right) x^{\prime}(t)+\left(\frac{1}{2}+\cos t\right) x(t)=0, \quad t \geq 1 \tag{2.11}
\end{equation*}
$$

Here $p(t)=\frac{1}{2}+\sin t, q(t)=\frac{1}{2}+\cos t$ and $g(x)=x$. Note that 1.2 and 1.3 are satisfied. By choosing $\rho(t)=t$ we have

$$
\begin{gathered}
\liminf _{t \rightarrow \infty} \int_{1}^{t} \rho(s) q(s) d s=\infty \\
\limsup _{t \rightarrow \infty} \frac{1}{t} \int_{1}^{t}\left[\int_{1}^{s} \rho(u) q(u) d u\right]^{2} d s=\infty
\end{gathered}
$$

Thus Theorem 2.1 ensures that every solution of 2.11 oscillates.
Theorem 2.4. Assume that (1.2, (1.3), 2.1, and 2.2 hold. Furthermore, Suppose that

$$
\begin{align*}
& \int_{ \pm \epsilon}^{ \pm \infty} \frac{\sqrt{g^{\prime}(x)}}{g(x)} d x<\infty, \quad \epsilon>0  \tag{2.12}\\
& \sqrt{g^{\prime}(x)} G(x)>0 \quad \text { for all } x \neq 0 \tag{2.13}
\end{align*}
$$

where $G(x)=\int_{x}^{\infty} \frac{\sqrt{g^{\prime}(u)}}{g(u)} d u$,

$$
\begin{align*}
& \limsup _{t \rightarrow \infty} \frac{1}{t^{\alpha}} \int_{T}^{t}\left\{(t-s)^{\alpha} \rho(s) q(s)\right. \\
& \left.-\frac{1}{4 c} \int_{T}^{t}\left[\alpha-(t-s) \frac{\lambda(s)}{r(s) \rho(s)}\right]^{2}(t-s)^{\alpha-2} \frac{V(s)}{V^{\prime}(s)}\right\} d s=\infty \tag{2.14}
\end{align*}
$$

for some integer $\alpha>1$, where

$$
V(t)=\int_{t_{0}}^{t} \frac{1}{r(s) \rho(s)} d s, \quad \lim _{t \rightarrow \infty} V(t)=\infty, \quad \lambda(t)=\left[r(t) \rho^{\prime}(t)-\rho(t) p(t)\right]
$$

Then 1.1 is oscillatory.
Proof. Suppose to the contrary that (1.1) possesses a non-oscillatory solution $x$ on an interval $[T, \infty), T \geq t_{0}$. Without loss of generality, we shall assume that $x(t)>0$ for all $t \geq T \geq t_{0}$ (the case $x(t)<0$ treated similarly and will be omitted). Again we define $w(t)$ as in Theorem 2.1. and prove that (1.1) holds then we have equation (2.4). First, we claim that

$$
I=\int_{T}^{\infty} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s
$$

is infinite. Otherwise, if $I<\infty$, there exists a positive constant $N$ such that

$$
\int_{T}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{\rho(s) r(s)} d s \leq N, \quad \text { for all } t \geq T
$$

Now, by the Schwarz's inequality, we have

$$
\begin{aligned}
\left|\int_{T}^{t} \frac{w(s)}{\rho(s) r(s)} \sqrt{g^{\prime}(x(s))} d s\right|^{2} & \leq\left(\int_{T}^{t} \frac{d s}{\rho(s) r(s)}\right)\left(\int_{T}^{t} \frac{w^{2}(s) g^{\prime}(x(s))}{\rho(s) r(s)} d s\right) \\
& \leq N\left(\int_{T}^{t} \frac{d s}{\rho(s) r(s)}\right)
\end{aligned}
$$

Set

$$
\begin{equation*}
M_{1}=\int_{x(T)}^{\infty} \frac{\sqrt{g^{\prime}(u)}}{g(u)} d u>0, \quad \sqrt{g^{\prime}(x)} \int_{x(t)}^{\infty} \frac{\sqrt{g^{\prime}(u)}}{g(u)} d u \geq M_{2}>0 \tag{2.15}
\end{equation*}
$$

Then, we have

$$
\begin{aligned}
g^{\prime}(x(t)) & \geq M_{2}^{2}\left[\int_{x(t)}^{\infty} \frac{\sqrt{g^{\prime}(u)}}{g(u)} d u\right]^{-2} \\
& =M_{2}^{2}\left[M_{1}-\int_{x(T)}^{x(t)} \frac{\sqrt{g^{\prime}(u)}}{g(u)} d u\right]^{-2} \\
& =M_{2}^{2}\left[M_{1}-\int_{T}^{t} \frac{x^{\prime}(s) \sqrt{g^{\prime}(x(s))}}{g(x(s))} d s\right]^{-2} \\
& \geq M_{2}^{2}\left[M_{1}+\left|\int_{T}^{t} \frac{w(s)}{\rho(s) r(s)} \sqrt{g^{\prime}(x(s))} d s\right|\right]^{-2} \\
& \geq M_{2}^{2}\left[M_{1}+\sqrt{N V(t)}\right]^{-2} .
\end{aligned}
$$

Condition (2.1) ensures (as in Theorem 2.1) that $\lim _{t \rightarrow \infty} V(t)=\infty$. Hence,

$$
\begin{equation*}
g^{\prime}(x) \geq M_{2}^{2}\left\{\left[M_{1}+\sqrt{N}\right] \sqrt{V(t)}\right\}^{-2}=\frac{c}{V(t)} \tag{2.16}
\end{equation*}
$$

where $c=M_{2}^{2}\left[M_{1}+\sqrt{N}\right]^{-2}$. Therefore, by (2.4), taking into account 2.16), we have

$$
\begin{equation*}
\rho(t) q(t) \leq-w^{\prime}(t)+\frac{\lambda(t)}{r(t) \rho(t)} w(t)-c \frac{V^{\prime}(t)}{V(t)} w^{2}(t) \tag{2.17}
\end{equation*}
$$

where $\lambda(t)=\left[r(t) \rho^{\prime}(t)-\rho(t) p(t)\right]$. Hence, for all $t \geq T$, we have

$$
\begin{aligned}
& \int_{T}^{t}(t-s)^{\alpha} \rho(s) q(s) d s \\
& \leq-\int_{T}^{t}(t-s)^{\alpha} w^{\prime}(s) d s+\int_{T}^{t} \frac{(t-s)^{\alpha} \lambda(s) w(s)}{r(s) \rho(s)} d s-c \int_{T}^{t} \frac{(t-s)^{\alpha} V^{\prime}(s) w^{2}(s)}{V(s)} d s \\
& =(t-T)^{\alpha} w(T)-\alpha \int_{T}^{t}(t-s)^{\alpha-1} w(s) d s+\int_{T}^{t} \frac{(t-s)^{\alpha} \lambda(s) w(s)}{r(s) \rho(s)} d s \\
& \quad-c \int_{T}^{t} \frac{(t-s)^{\alpha} V^{\prime}(s) w^{2}(s)}{V(s)} d s \\
& =(t-T)^{\alpha} w(T) \\
& \quad-\int_{T}^{t}\left\{\sqrt{\frac{c V^{\prime}(s)}{V(s)}}(t-s)^{\frac{\alpha}{2}} w(s)+\frac{\left[\alpha-(t-s) \frac{\lambda(s)}{r(s) \rho(s)}\right](t-s)^{\frac{\alpha}{2}-1}}{\sqrt{\frac{c V^{\prime}(s)}{V(s)}}}\right\}^{2} d s \\
& \quad+\frac{1}{4 c} \int_{T}^{t}\left[\alpha-(t-s) \frac{\lambda(s)}{r(s) \rho(s)}\right]^{2}(t-s)^{\alpha-2} \frac{V(s)}{V^{\prime}(s)} d s .
\end{aligned}
$$

Thus

$$
\begin{aligned}
& \frac{1}{t^{\alpha}} \int_{T}^{t}\left\{(t-s)^{\alpha} \rho(s) q(s)-\frac{1}{4 c}\left[\alpha-(t-s) \frac{\lambda(s)}{r(s) \rho(s)}\right]^{2}(t-s)^{\alpha-2} \frac{V(s)}{V^{\prime}(s)}\right\} d s \\
& \leq\left(1-\frac{T}{t}\right)^{\alpha} w(T)
\end{aligned}
$$

Then, taking a limit superior on both sides, we obtain a contradiction to the condition 2.14. Thus it must be the case $I=\infty$. As in the proof of Theorem 2.1 (Case 2) we arrive at the contradiction $\lim _{t \rightarrow \infty} x(t)=-\infty$. This completes the proof.

Theorem 2.5. Assume that (1.2), 2.12, and 2.13 hold. Furthermore, Suppose that

$$
\begin{gather*}
\lim _{t \rightarrow \infty} R(t)=\lim _{t \rightarrow \infty} \int_{t_{0}}^{t} \frac{d s}{r(s)}=\infty  \tag{2.18}\\
\lim _{t \rightarrow \infty} \inf \int_{t_{0}}^{t} q(s) d s>-\infty \tag{2.19}
\end{gather*}
$$

there exist a function $\phi \in C^{1}\left(\left[t_{0}, \infty\right),(0, \infty)\right), H, h: D \equiv\left\{(t, s): t \geq s \geq t_{0}\right\} \rightarrow \mathbb{R}$ such that

$$
\begin{gathered}
H(t, t)=0, \quad t \geq t_{0} \\
H(t, s)>0, \quad t>s \geq t_{0}
\end{gathered}
$$

and $H$ has a continuous and nonpositive partial derivative on $D$ with respect to the second variable and satisfies

$$
\begin{align*}
& -\frac{\partial}{\partial u}(H(t, u) \phi(u))+H(t, u) \phi(u) \frac{p(u)}{r(u) \xi}=h(t, u) \sqrt{H(t, u) \phi(u) D R^{\prime}(u)} \\
& \lim _{t \rightarrow \infty} \inf \frac{1}{H(t, s)} \int_{s}^{t}\left[H(t, u) \phi(u) q(u)-\frac{1}{4} R(u) h^{2}(t, u)\right] d u \geq f(s) \tag{2.20}
\end{align*}
$$

for some constant $D>0$, and

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \int_{t_{0}}^{t} \frac{\left[f_{+}(s)\right]^{2} R^{\prime}(s)}{[\phi(s)]^{2} R(s)} d s=\infty \tag{2.21}
\end{equation*}
$$

where $f_{+}(t)=\max \{f(t), 0\}$. Then 1.1 is oscillatory.
Proof. Suppose to the contrary that (1.1) possesses a non-oscillatory solution $x$ on an interval $[T, \infty), T \geq t_{0}$. Without loss of generality, we shall assume that $x(t)>0$ for all $t \geq T$ (the case $x(t)<0$ can be treated similarly). Let

$$
w(t)=\frac{r(t) x^{\prime}(t)}{g(x(t))}
$$

From this definition and 1.1 it follows that

$$
\begin{gather*}
w^{\prime}(t)=-q(t)-\frac{p(t)}{r(t)} w(t)-\frac{g^{\prime}(x(t))}{r(t)} w^{2}(t), \quad t \geq t_{0}  \tag{2.22}\\
\int_{t_{0}}^{t} q(s) d s=-w(t)+w\left(t_{0}\right)-\int_{t_{0}}^{t} \frac{p(s) w(s)}{r(s)} d s-\int_{t_{0}}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{r(s)} d s \tag{2.23}
\end{gather*}
$$

We distinguish two cases:
Case 1. The integral $\int_{t_{0}}^{\infty} \frac{g^{\prime}(x(s)) w^{2}(s)}{r(s)} d s$ is finite. Then there exists a positive constant $N$ such that

$$
\begin{equation*}
\int_{T}^{t} \frac{g^{\prime}(x(s)) w^{2}(s)}{r(s)} d s \leq M \quad \text { for all } t \geq t_{0} \tag{2.24}
\end{equation*}
$$

By the Schwarz's inequality, we have

$$
\begin{align*}
\left|\int_{T}^{t} \frac{w(s)}{r(s)} \sqrt{g^{\prime}(x(s))} d s\right|^{2} & \leq\left(\int_{T}^{t} \frac{d s}{r(s)}\right)\left(\int_{T}^{t} \frac{w^{2}(s) g^{\prime}(x(s))}{r(s)} d s\right) \\
& \leq M\left(\int_{T}^{t} \frac{d s}{r(s)}\right)=M R(t) \tag{2.25}
\end{align*}
$$

Taking into account $2.15,2.25$ and 2.19 , the procedure in Theorem 2.4 implies

$$
\begin{equation*}
g^{\prime}(x(t)) \geq \frac{D}{R(t)}, \quad t \geq t_{0} \tag{2.26}
\end{equation*}
$$

where $D=M_{2}^{2}\left[M_{1}+\sqrt{M}\right]^{-2}$. Hence, for every $t \geq t_{0}, 2.18$ and 2.22 imply

$$
q(t) \leq-w^{\prime}(t)-\frac{p(t)}{r(t)} w(t)-\frac{D R^{\prime}(t)}{R(t)} w^{2}(t)
$$

Then

$$
\begin{aligned}
\int_{s}^{t} H(t, u) \phi(u) q(u) d u \leq & -\int_{s}^{t} H(t, u) \phi(u) w^{\prime}(u) d u-\int_{s}^{t} H(t, u) \phi(u) \frac{p(u)}{r(u)} w(u) d u \\
- & D \int_{s}^{t} H(t, u) \phi(u) \frac{R^{\prime}(u)}{R(u)} w^{2}(u) d u, \quad\left(s \geq t_{0}\right) \\
= & H(t, s) \phi(s) w(s)-D \int_{s}^{t} H(t, u) \phi(u) \frac{R^{\prime}(u)}{R(u)} w^{2}(u) d u \\
& -\int_{s}^{t}\left[-\frac{\partial}{\partial u}(H(t, u) \phi(u))+H(t, u) \phi(u) \frac{p(u)}{r(u)}\right] w(u) d u \\
= & H(t, s) \phi(s) w(s)+\frac{1}{4} R(u) h^{2}(t, u) \\
& -\int_{s}^{t}\left[\sqrt{\frac{H(t, u) \phi(u) D R^{\prime}(u)}{R(u)}} w(u)+\frac{1}{2} \sqrt{R(u)} h(t, u)\right]^{2} d u
\end{aligned}
$$

Thus for all $t \geq s \geq t_{0}$, we have

$$
\begin{aligned}
& \int_{s}^{t}\left[H(t, u) \phi(u) q(u)-\frac{1}{4} R(u) h^{2}(t, u)\right] d u \\
& \leq H(t, s) \phi(s) w(s)-\int_{s}^{t}\left[\sqrt{\frac{H(t, u) \phi(u) D R^{\prime}(u)}{R(u)}} w(u)+\frac{1}{2} \sqrt{R(u)} h(t, u)\right]^{2} d u
\end{aligned}
$$

Hence,

$$
\begin{equation*}
\int_{s}^{t}\left[H(t, u) \phi(u) q(u)-\frac{1}{4} R(u) h^{2}(t, u)\right] d u \leq H(t, s) \phi(s) w(s) \tag{2.27}
\end{equation*}
$$

Dividing 2.27) by $H(t, s)$ and then taking the lower limit as $t \rightarrow \infty$, we have

$$
f(s) \leq \phi(s) w(s), \quad s \geq t_{0}
$$

and hence

$$
\left[f_{+}(s)\right]^{2} \leq[\phi(s)]^{2}[w(s)]^{2}, \quad s \geq t_{0}
$$

In view of 2.24 and 2.26 we have

$$
\begin{aligned}
\lim _{t \rightarrow \infty} \int_{t_{0}}^{t} \frac{D\left[f_{+}(s)\right]^{2} R^{\prime}(s)}{[\phi(s)]^{2} R(s)} d s & \leq \lim _{t \rightarrow \infty} \int_{t_{0}}^{t} \frac{D[w(s)]^{2} R^{\prime}(s)}{R(s)} d s \\
& \leq \lim _{t \rightarrow \infty} \int_{t_{0}}^{t} \frac{[w(s)]^{2} g^{\prime}(x(s))}{r(s)} d s \leq M<\infty
\end{aligned}
$$

This contradicts 2.21.
Case 2. The integral $\int_{t_{0}}^{\infty} \frac{g^{\prime}(x(s)) w^{2}(s)}{r(s)} d s$ is infinite. In this case, by 2.19) and 2.23, the procedure of Theorem 2.1 (Case 2) leads to the contradiction $\lim _{t \rightarrow \infty} x(t)=$ $-\infty$. This completes the proof.

Corollary 2.6. Replace 2.20 and 2.21 by

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \sup \frac{1}{H(t, s)} \int_{s}^{t}\left[H(t, u) \phi(u) q(u)-\frac{1}{4} R(u) h^{2}(t, u)\right] d u=\infty \tag{2.28}
\end{equation*}
$$

Then the conclusion of Theorem 2.5 still holds.

Proof. Divide 2.27 by $H(t, s)$ and then take the upper limit as $t \rightarrow \infty$. This way, we get a contradiction to 2.28 . Them the rest of the proof is similar to the proof of Theorem 2.5 (Case 2).

## References

[1] R. P. Agarwal, S, R. Grace and D. O'Regan; Oscillation Theory for Difference and functional Differential Equations, Kluwer Academic Publ., Drdrechet, 2000.
[2] R. P. Agarwal, S, R. Grace and D. O'Regan; Oscillation Theory for Second order Dynamic Equations, to appear.
[3] D. D. Bainov and D. P. Mishev; Oscillation Theory for Neutral Differential Equations with Delay, Adam Hilger, New York, 1991.
[4] N. P. Bhatia; Some oscillation theorems for second order differential equations, J. Math. Anal. Appl. 15 (1966), 442-446.
[5] R. Blasko, J. R. Graef, M. Hacik and P. W. Spikes; Oscillatory behavior of solutions of nonlinear differential equations of the second order, J. Math. Anal. Appl. 151 (1990), 330343.
[6] G. J. Butler; Integral averages and the oscillation of second order ordinary differential equations, SIAM J. Math. Anal. 11 (1980), 190-200.
[7] W. J. Coles; An oscillation criterion for the second order differential equations, Proc. Amer. Math. Soc. 19 (1968), 755-759.
[8] W. J. Coles; Oscillation criteria for nonlinear second order equations, Ann. Mat. Pura Appl. 82 (1969), 132-134.
[9] L. H. Erbe, Q. King and B. Z. Zhang; Oscillation Theory for Functional Differential Equations, Marcel Dekker, New York, 1995.
[10] E. M. Elabbasy; On the Oscillation of Nonlinear Second Order Differential Equations, PanAmerican Mathematical Journal 4 (1996), 69-84.
[11] J. R. Graef and P. W. Spikes; On the oscillatory behavior of solutions of second order nonlinear differential equations, Czech. Math. J. 36 (1986), 275-284.
[12] J. R. Graef, S. M. Rankin and P. W. Spikes; Oscillation theorems for perturbed nonlinear differential equations, J. Math. Anal. Appl. 65 (1978), 375-390.
[13] I. Gyori and G. Ladas; Oscillation Theory of Delay Differential Equations With Applications, Clarendon Press, Oxford, 1991.
[14] P. Hartman; On nonoscillatory linear differential equations of second order, Amer. J. Math. 74 (1952), 389-400.
[15] I. V. Kamenev; Integral criterion for oscillation of linear differential equations of second order, Math. Zemetki (1978), 249-251 (in Russian).
[16] M. Kirane and Yuri. V. Rogovechenko; On oscillation of nonlinear second order equations with damping, Appl. Math. Comp. (to appear).
[17] Q. Kong; Interval criteria for oscillation of second-order linear ordinary differential equations, J. Math. Anal. Appl. 229 (1999), 258-270.
[18] G. S. Ladde, V. Lakshmikantham and B. Z. Zhang; Oscillation Theory of Differential Equations with deviating arguments, Marcel Dekker, New York, 1987.
[19] W. Leighton; The detection of the oscillation of solutions of a second order linear differential equation, Duke J. Math. 17 (1950), 57-62.
[20] B. Li; Oscillation of delay differential equations with variable coefficients, J. Math. Anal. Appl., 192 (1995), 217-234.
[21] H. J. Li; Oscillation criteria for second order linear differential equations, J. Math. Anal. Appl. 194 (1995), 312-321.
[22] H. J. Li and C. C. Yeh; On the nonoscillatory behavior of solutions of a second order linear differential equations, Math. Nach. 182 (1996), 295-315.
[23] M. Li, M. Wang and J. Yan; On oscillation of nonlinear second order differential equations with damping term, J. Appl. Math. and Computing, 13 (2003), 223-232.
[24] Ch. G. Philos; Oscillation theorems for linear differential equation of second order, Arch. Math. 53 (1989), 483-492.
[25] Yuri. V. Rogovechenko; Note on oscillation criteria for second-order linear differential equations, J. Math. Anal. Appl. 203 (1996), 560-563.
[26] Yuri. V. Rogovechenko; Oscillation theorems for second-order equations with damping, Nonlinear Anal. 42 (2000), 1005-1028.
[27] Svitlana P. Rogovechenko and Yuri. V. Rogovechenko; Oscillation of second-order Differential equations with damping, Mathematical Analysis 10 (2003), 447-461.
[28] S. H. Saker, P. Y. H. Pang and Ravi P. Agarwal; Oscillation theorems for second order nonlinear functional differential equations with damping, Dynamic Systems and Applications 12 (2003), 307-322.
[29] Y. G. Sun; New Kamenev-type oscillation criteria for second-order nonlinear differential equations with damping, J. Math. Anal. Appl. 291 (2004), 341-351.
[30] D. W. Willett; On the oscillatory behavior of the solutions of second order linear differential equations, Ann. Polon. Math. 21 (1969), 175-191.
[31] D. W. Willett; Classification of second order linear differential equations with respect to oscillations, Adv. in. Math. 3 (1969), 494-623.
[32] A. Wintner; A cireterion of oscillatory stability, Quart. Appl. Math. 7 (1949), 115-117.
[33] J. S. W. Wong; An Oscillation theorem for second order sublinear differential equations Proc. Amer. Math. Soc. 110 (1990), 633-637.
[34] J. S. W. Wong; On Kamenev-type oscillation theorems for second order differential equations with damping, J. Math. Anal. Appl. 258 (2001), 244-257.
[35] J. Yan; A note on an oscillation criterion for an equation with damping term, Proc. Amer. Math. Soc. 90 (1984), 277-280.
[36] J. Yan; Oscillation theorems for second order linear differential equations with damping, Proc. Amer. Math. Soc. 98 (1986), 276-282.
[37] C. C. Yeh; Oscillation theorems for nonlinear second order differential equations with damped term, Proc. Amer. Math. Soc. 84 (1982), 397-402.
[38] Y. H. Yu; Leighton type oscillation criteria and Sturm comparison theorem, Math. Nachr. 153 (1991), 485-496.
Elmetwally M. Elabbasy
Department of Mathematics, Faculty of Science, Mansoura University, Mansoura, 35516, Egypt
Email: emelabbasy@mans.edu.eg
Taher S. Hassan
Department of Mathematics, Faculty of Science, Mansoura University, Mansoura, 35516, Egypt
Email: tshassan@mans.edu.eg
Samir H. Saker
Department of Mathematics, Faculty of Science, Mansoura University, Mansoura, 35516, Egypt
Email: shsaker@mans.edu.eg
Corrigendum posted on January 2, 2008
Page 4. To the assumptions in Theorem 2.1, add

$$
r(t) \rho^{\prime}(t)-\rho(t) p(t) \geq 0
$$

Page 7. The same assumption needs to added to Theorem 2.4
Page 7. In Example 2.3 replace 2.11 with

$$
\left(\frac{1}{t} x^{\prime}(t)\right)^{\prime}-\frac{1}{t^{2}} x^{\prime}(t)+(2+\cos t) x(t)=0, \quad t \geq 1
$$

The authors are grateful to Mr. Başak Karpuz, whose remarks prompted the posting of this corrigendum.


[^0]:    2000 Mathematics Subject Classification. 34K15, 34C10.
    Key words and phrases. Oscillation; second order nonlinear differential equation;
    damping term.
    (C) 2005 Texas State University - San Marcos.

    Submitted April 5, 2005. Published July 8, 2005.

