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# OSCILLATION OF HIGH ORDER LINEAR FUNCTIONAL DIFFERENTIAL EQUATION WITH IMPULSES 

HAIHUA LIANG, WEIZHEN FENG


#### Abstract

We study the solutions to high-order linear functional differential equations with impulses. We improve previous results in the oscillation theory for ordinary differential equations and obtain new criteria on the oscillation of solutions.


## 1. Introduction

In the past years, the theory of the oscillatory behavior of impulsive ordinary differential equation (IODE) and impulsive functional differential equation (IFDE) has been investigated by many authors; see for example [1, 2, 4, 5, 6, 8, 10, 11, 12, 13. However, most of these articles concern first-order or second-order IODE and IFDE [1, 2, 5, 6, 8, 11, 13. Just a few of them have studied third and the fourthorder IODE [4, 10, 12]. Recently, in [3, the authors studied oscillatory criteria for even order IODE

$$
\begin{gather*}
x^{(2 n)}(t)+p(t) x(t)=0, \quad t \geq t_{0}, \quad t \neq t_{k}, \\
x^{(i)}\left(t_{k}^{+}\right)=a_{k}^{(i)} x^{(i)}\left(t_{k}\right), \quad i=0,1, \ldots, 2 n-1 ; k=1,2, \ldots \tag{1.1}
\end{gather*}
$$

and obtained some important results. To the best of our knowledge, paper [3] is probably the first publication on the high order IODE. However, there are somethings worth further consideration. Firstly, the results of [3] is invalid for odd order IODE and IFDE; Secondly, in order to assure the oscillatory behavior of (1.1), the following condition is required:

$$
\begin{align*}
& \int_{t_{0}}^{t_{1}} p(s) d s+\frac{a_{1}^{(0)}}{a_{1}^{(2 n-1)}} \int_{t_{1}}^{t_{2}} p(s) d s+\frac{a_{1}^{(0)} a_{2}^{(0)}}{a_{1}^{(2 n-1)} a_{2}^{(2 n-1)}} \int_{t_{2}}^{t_{3}} p(s) d s \\
& +\cdots+\frac{a_{1}^{(0)} a_{2}^{(0)} \ldots a_{k}^{(0)}}{a_{1}^{(2 n-1)} a_{2}^{(2 n-1)} \ldots a_{k}^{(2 n-1)}} \int_{t_{k}}^{t_{k+1}} p(s) d s+\cdots=+\infty \tag{1.2}
\end{align*}
$$

[^0]which is parallel assumption to
\[

$$
\begin{equation*}
\int^{+\infty} p(s) d s=+\infty \tag{1.3}
\end{equation*}
$$

\]

in ODE. We know, however, in the corresponding oscillation theory of ODE, it is sufficient to assume that

$$
\begin{equation*}
\int^{+\infty} s^{n-2} p(s) d s=+\infty \tag{1.4}
\end{equation*}
$$

So it is natural to ask if it is possible to improved (1.2) to a better form? Moreover, what is the result about the odd order differential equations with impulses? In the present article, we deal with a more general linear IFDE and establish several useful criteria for it. We believe our approach is simple and is also helpful to be used in other systems.

Consider the impulsive delay differential equation

$$
\begin{gather*}
x^{(n)}(t)+p(t) x(t-\tau)=0, \quad t \geq t_{0}, t \neq t_{k} \\
x^{(i)}\left(t_{k}^{+}\right)=a_{k}^{(i)} x^{(i)}\left(t_{k}\right), \quad i=0,1, \ldots, n-1 ; k=1,2, \ldots, \tag{1.5}
\end{gather*}
$$

where $n$ is a natural number with $n \geq 2,0 \leq t_{0}<t_{1}<t_{2}<\cdots<t_{k}<\ldots$, $\lim _{k \rightarrow \infty} t_{k}=+\infty, t_{k+1}-t_{k}>3 \tau, x^{(0)}(t)=x(t)$,

$$
\begin{aligned}
x^{(i)}\left(t_{k}\right) & =\lim _{h \rightarrow-0} \frac{x^{(i-1)}\left(t_{k}+h\right)-x^{(i-1)}\left(t_{k}\right)}{h} \\
x^{(i)}\left(t_{k}^{+}\right) & =\lim _{h \rightarrow+0} \frac{x^{(i-1)}\left(t_{k}+h\right)-x^{(i-1)}\left(t_{k}^{+}\right)}{h}
\end{aligned}
$$

where $i=1,2, \ldots, n$ and $x^{(0)}\left(t_{k}^{+}\right)=x\left(t_{k}^{+}\right)$.
For the rest of this paper, assume the following conditions:

- $a_{k}^{(i)}>0, i=0,1, \ldots, n-1 ; k=1,2, \ldots$.
- $p(t)$ is continuous in $\left[t_{0}-\tau, \infty\right) ; p(t) \geq 0$ and for any $T \geq t_{0}, p(t)$ is not identically zero in $[T,+\infty)$.

Definition. A function $x:\left[t_{0}-\tau, a\right) \rightarrow R\left(a>t_{0}\right)$ is said to be a solution of (1.5) on $\left[t_{0}-\tau, a\right)$ satisfying the initial-value condition $x^{(i)}(t)=\phi^{(i)}(t)$ for $i=0,1, \ldots, n-1$ and $t \in\left[t_{0}-\tau, t_{0}\right)$, if
(i) $x^{(i)}(t)$ is continuous for $t \in\left[t_{0}, a\right)$ and $t \neq t_{k}, i=0,1, \ldots n-1 ; k=1,2, \ldots$
(ii) $x(t)$ satisfies $x^{(n)}(t)+p(t) x(t-\tau)=0$ for $t \in\left[t_{0}, a\right), t \neq t_{k}, k=1,2, \ldots$
(iii) $x^{(i)}(t)=\phi^{(i)}(t), t \in\left[t_{0}-\tau, t_{0}\right], i=0,1, \ldots, n-1$
(iv) $x^{(i)}\left(t_{k}^{+}\right)=a_{k}^{(i)} x\left(t_{k}\right)$, for $t_{k} \in\left[t_{0}, a\right), i=0,1, \ldots, n-1$.

It is clear that 1.5 can be transformed into a first-order linear impulsive differential systems. Theorems on existence of solutions, on uniqueness, and on existence of global solutions of the first order linear differential equation with impulses can be found in [7, 9]. There, we can find the existence of global solutions under some simple conditions.

In the following, we assume that the solutions of (1.5) exist on $\left[t_{0}-\tau,+\infty\right)$.
Definition. A solution of 1.5 is said to be non-oscillatory if this solution is eventually positive or eventually negative. Otherwise, this solution is said to be oscillatory.

## 2. Main Results

The following conditions are assumed in this paper:
(H1) For $i=1,2, \ldots, n-1$,

$$
\begin{aligned}
& \left(t_{1}-t_{0}\right)+\frac{a_{1}^{(i)}}{a_{1}^{(i-1)}}\left(t_{2}-t_{1}\right)+\frac{a_{1}^{(i)} a_{2}^{(i)}}{a_{1}^{(i-1)} a_{2}^{(i-1)}}\left(t_{3}-t_{2}\right)+\ldots \\
& +\frac{a_{1}^{(i)} a_{2}^{(i)} \ldots a_{m}^{(i)}}{a_{1}^{(i-1)} a_{2}^{(i-1)} \ldots a_{m}^{(i-1)}}\left(t_{m+1}-t_{m}\right)+\cdots=+\infty
\end{aligned}
$$

(H2) $\liminf _{k \rightarrow+\infty}\left(a_{k}^{(i)} a_{k-1}^{(i)} \ldots a_{2}^{(i)} a_{1}^{(i)}\right)=\delta_{i}>0, i=0,1, \ldots, n-1$
(H3) If $n \geq 3$, then $w_{m}^{L}(k) \geq W$ holds for $k$ large enough, where $W$ is a constant, and

$$
\begin{aligned}
w_{m}^{L}(k)= & \left(a_{k}^{(L-m-1)}-1\right)\left(t_{k}^{m}-t_{k-1}^{m}\right)+\left(a_{k}^{(L-m-1)} a_{k-1}^{(L-m-1)}-1\right)\left(t_{k-1}^{m}-t_{k-2}^{m}\right) \\
& +\cdots+\left(a_{k}^{(L-m-1)} a_{k-1}^{(L-m-1)} \ldots a_{1}^{(L-m-1)}-1\right)\left(t_{1}^{m}-t_{0}^{m}\right)
\end{aligned}
$$

where $L=2,3, \ldots, n-1$ and $m=1,2, \ldots L-1$.
We remark that if $a_{k}^{(i)} \geq 1$, then (H2) and (H3) are satisfied.
Lemma 2.1. Let $x(t)$ be a solution of (1.5). Suppose (H1) holds and for some $i \in\{1,2, \ldots, n-1\}$, there exists a constant $T \geq t_{0}$ such that $x^{(i)}(t)>0(<0)$, $x^{(i+1)}(t) \geq 0(\leq 0)$ for $t \geq T$. Then $x^{(i-1)}(t)>0(<0)$ holds for sufficiently large $t$.
Proof. We prove only the conclusion under the assumptions that $x^{(i)}(t)>0$, $x^{(i+1)}(t) \geq 0$. The case that $x^{(i)}(t)<0, x^{(i+1)}(t) \leq 0$ can be proved similarly. Without loss of generality, suppose $T=t_{0}$. By $x^{(i)}(t)>0, x^{(i+1)}(t) \geq 0$, we know that $x^{(i)}(t)$ is monotonically nondecreasing in each interval $\left(t_{k}, t_{k+1}\right)$, $k=0,1,2, \ldots$ Hence

$$
x^{(i)}(t) \geq x^{(i)}\left(t_{k}^{+}\right), \quad \text { for } t \in\left(t_{k}, t_{k+1}\right] .
$$

Integrating the above inequality, we have

$$
x^{(i-1)}\left(t_{k+1}\right) \geq x^{(i-1)}\left(t_{k}^{+}\right)+x^{(i)}\left(t_{k}^{+}\right)\left(t_{k+1}-t_{k}\right)
$$

Then

$$
x^{(i-1)}\left(t_{2}\right) \geq x^{(i-1)}\left(t_{1}^{+}\right)+x^{(i)}\left(t_{1}^{+}\right)\left(t_{2}-t_{1}\right)
$$

and thus

$$
\begin{aligned}
x^{(i-1)}\left(t_{3}\right) & \geq x^{(i-1)}\left(t_{2}^{+}\right)+x^{(i)}\left(t_{2}^{+}\right)\left(t_{3}-t_{2}\right) \\
& =a_{2}^{(i-1)} x^{(i-1)}\left(t_{2}\right)+a_{2}^{(i)} x^{(i)}\left(t_{2}\right)\left(t_{3}-t_{2}\right) \\
& \geq a_{2}^{(i-1)}\left[x^{(i-1)}\left(t_{1}^{+}\right)+x^{(i)}\left(t_{1}^{+}\right)\left(t_{2}-t_{1}\right)\right]+a_{2}^{(i)} x^{(i)}\left(t_{2}\right)\left(t_{3}-t_{2}\right) \\
& \geq a_{2}^{(i-1)}\left[x^{(i-1)}\left(t_{1}^{+}\right)+x^{(i)}\left(t_{1}^{+}\right)\left(t_{2}-t_{1}\right)+\frac{a_{2}^{(i)}}{a_{2}^{(i-1)}} x^{(i)}\left(t_{1}^{+}\right)\left(t_{3}-t_{2}\right)\right] .
\end{aligned}
$$

By induction, we find that

$$
\begin{aligned}
x^{(i-1)}\left(t_{k}\right) \geq & a_{k-1}^{(i-1)} \ldots a_{3}^{(i-1)} a_{2}^{(i-1)}\left\{x^{(i-1)}\left(t_{1}^{+}\right)+x^{(i)}\left(t_{1}^{+}\right)\left[\left(t_{2}-t_{1}\right)\right.\right. \\
& \left.\left.+\frac{a_{2}^{(i)}}{a_{2}^{(i-1)}}\left(t_{3}-t_{2}\right)+\cdots+\frac{a_{2}^{(i)} a_{3}^{(i)} \ldots a_{k-1}^{(i)}}{a_{2}^{(i-1)} a_{3}^{(i-1)} \ldots a_{k-1}^{(i-1)}}\left(t_{k}-t_{k-1}\right)\right]\right\} .
\end{aligned}
$$

Since $a_{k}^{(i)}>0$, it follows from (H1) that for sufficiently large $k, x^{(i-1)}\left(t_{k}\right)>0$. i.e., there exists some $N$ such that $x^{(i-1)}\left(t_{k}\right)>0$ for $k \geq N$. Since $x^{(i)}(t)>0$, we have

$$
x^{(i-1)}(t)>x^{(i-1)}\left(t_{k}^{+}\right)>0, \quad \text { for } t \in\left(t_{k}, t_{k+1}\right], t_{k} \geq t_{N}
$$

Thus, for sufficiently large $t, x^{(i-1)}(t)>0$, which completes the proof.
Lemma 2.2. Let $x(t)$ be a solution of (1.5). Suppose (H1) holds, and for some $i \in\{1,2, \ldots, n\}$, there exists a constant $T\left(T \geq t_{0}\right)$ such that $x(t)>0, x^{(i)}(t) \leq$ $0(t \geq T)$. Furthermore, $x^{(i)}(t)$ is not identically zero in any interval $\left[t^{\prime},+\infty\right)$. Then $x^{(i-1)}(t)>0$ holds for sufficiently large $t$.

Proof. Without loss of generality, assume $T=t_{0}$. We will show that for any $t_{k} \geq t_{0}, x^{(i-1)}\left(t_{k}\right)>0$ holds. Suppose that there exists some $t_{j} \geq t_{0}$ such that $x^{(i-1)}\left(t_{j}\right) \leq 0$. Since $x^{(i)}(t) \leq 0$, it is obvious that $x^{(i-1)}(t)$ is monotonically nonincreasing in any interval $\left(t_{k}, t_{k+1}\right.$ ] If $k \geq j$. By the condition that $x^{(i)}(t)$ is not identically zero in any interval $\left[t^{\prime},+\infty\right)$, we obtain that there exists some $t_{l} \geq t_{j}$ such that $x^{(i)}(t)$ is not identically zero $\operatorname{in}\left(t_{l}, t_{l+1}\right]$. For convenient, assume $l=j$. So

$$
x^{(i-1)}\left(t_{j+1}\right)<x^{(i-1)}\left(t_{j}^{+}\right)=a_{j}^{(i-1)} x^{(i-1)}\left(t_{j}\right) \leq 0
$$

and

$$
x^{(i-1)}(t) \leq x^{(i-1)}\left(t_{j+1}^{+}\right)=a_{j+1}^{(i-1)} x^{(i-1)}\left(t_{j+1}\right)<0, \quad \text { for } t \in\left(t_{j+1}, t_{j+2}\right]
$$

By induction, $x^{(i-1)}(t)<0$ holds for $t \in\left(t_{j+m}, t_{j+m+1}\right]$, where $m$ is a natural number. Then $x^{(i-1)}(t)<0, x^{(i)}(t) \leq 0, t \in\left(t_{j+1}, \infty\right)$. Thus, by Lemma 2.1. we obtain $x^{(i-2)}(t)<0$ for all sufficiently large $t$.

Making use of Lemma 2.1 repeatedly, we eventually obtain that $x(t)<0$ for $t$ large enough, which contradicts $x(t)>0(t \geq T)$. Therefore, $x^{(i-1)}\left(t_{k}\right)>0$ for any $t_{k}$. Since $a_{k}^{(i-1)}>0$ and that $x^{(i-1)}(t)$ is monotonically non-increasing in $\left(t_{k}, t_{k+1}\right]$, we have $x^{(i-1)}(t)>0$ for sufficiently large $t$. Thus the proof is complete.

Lemma 2.3. Let $x(t)$ be a solution of (1.5). Suppose that (H1) holds and that there exists a constant $T \geq t_{0}$ such that $x(t)>0$ for $t \geq T$. Then, there exists a $T^{\prime}$ and an integer $L, 0 \leq L \leq n$, with $n+L$ odd, such that

$$
\begin{gather*}
x^{(i)}(t)>0, \quad i=0,1, \ldots L \\
(-1)^{i+L} x^{(i)}(t)>0, \quad i=L+1, \ldots, n-1, t \geq T^{\prime} . \tag{2.1}
\end{gather*}
$$

Proof. By the assumption that $x(t)>0(t \geq T)$, we have $x^{(n)}(t)=-p(t) x(t-\tau) \leq 0$ for $t \geq T+\tau$ and that $x^{(n)}(t)$ is not identically zero in any interval $\left[t^{\prime},+\infty\right)$. According to Lemma 2.2, there exists some $T_{0} \geq T+\tau$ such that $x^{(n-1)}(t)>0$ holds for $t \geq T_{0}$.

Therefore, $x^{(n-2)}(t)$ is monotonically nondecreasing in $\left(t_{k}, t_{k+1}\right]\left(t_{k} \geq T_{0}\right)$. If $x^{(n-2)}\left(t_{k}\right)<0$ holds for all $t_{k} \geq T_{0}$, then it is obvious that $x^{(n-2)}(t)<0\left(t \geq T_{0}\right)$. If there is some $j$ such that $x^{(n-2)}\left(t_{j}\right) \geq 0$, then, by the monotonicity of $x^{(n-2)}(t)$ and $a_{k}^{(n-2)}>0$, we obtain $x^{(n-2)}(t)>0$ for sufficiently large $t$. So, in any case, there exists a $T_{1}$ such that one of the following statements is true:
(A1) $x^{(n-1)}(t)>0, x^{(n-2)}(t)>0, t \geq T_{1}$
(B1) $x^{(n-1)}(t)>0, x^{(n-2)}(t)<0, t \geq T_{1}$.

If (A1) is true, Lemma 2.1 shows that $x^{(n-3)}(t)>0$ holds for sufficiently large $t$. By using Lemma 2.1 repeatedly, we finally arrive at that

$$
x^{(n-1)}(t)>0, \quad x^{(n-2)}(t)>0, \quad \ldots, \quad x^{\prime}(t)>0, \quad x(t)>0 .
$$

If (B1) holds, Lemma 2.2 suggests that $x^{(n-3)}(t)>0$ for sufficiently large $t$. So, there exists a $T_{2} \geq T_{1}$ such that one of the following statements is true:
(A2) $x^{(n-3)}(t)>0, x^{(n-4)}(t)>0, t \geq T_{2}$
(B2) $x^{(n-3)}(t)>0, x^{(n-4)}(t)<0, t \geq T_{2}$.
Proceeding as in the above argument, we obtain that there exists a $T^{\prime} \geq T$ and $L: 0 \leq L \leq n-1$, with $n+L$ odd, such that (2.1) holds.

Lemma 2.4. Let $x(t)$ be a solution of (1.5). Assume that (H2) and (H3) are satisfied and there exist a natural number $L \geq 1$ and a $T^{\prime} \geq t_{0}$, such that $x^{(i)}(t)>0$ holds for $t \geq T^{\prime}$ and $i=0,1, \ldots L$. Then there exist constants $M$ and $T$ such that

$$
\begin{equation*}
x(t) \geq M t^{L-1}, \quad t \geq T \tag{2.2}
\end{equation*}
$$

Proof. Without loss of generality, let $T^{\prime}=t_{0}$. At first, we claim that there exists a constant $a>0$ such that

$$
\begin{equation*}
x^{(L-1)}(t) \geq a . \tag{2.3}
\end{equation*}
$$

holds for sufficiently large $t$. Suppose it is not true, then $\liminf _{t \rightarrow+\infty} x^{(L-1)}(t)=0$. Since $x^{(L)}(t)>0$, this implies $\liminf _{k \rightarrow+\infty} x^{(L-1)}\left(t_{k}^{+}\right)=0$. Note that

$$
\begin{aligned}
x^{(L-1)}\left(t_{k}^{+}\right) & =a_{k}^{(L-1)} x^{(L-1)}\left(t_{k}\right) \geq a_{k}^{(L-1)} x^{(L-1)}\left(t_{k-1}^{+}\right) \\
& =a_{k}^{(L-1)} a_{k-1}^{(L-1)} x^{(L-1)}\left(t_{k-1}\right) \geq \cdots \geq a_{k}^{(L-1)} a_{k-1}^{(L-1)} \ldots a_{1}^{(L-1)} x^{(L-1)}\left(t_{0}^{+}\right)
\end{aligned}
$$

hence $\liminf _{t \rightarrow+\infty}\left(a_{k}^{(L-1)} a_{k-1}^{(L-1)} \ldots a_{1}^{(L-1)}\right)=0$, which contradicts condition (H2). The claim is proved.

If $L=1$, by 2.3 we find the Lemma 2.4 has been proved. Now, suppose $L \geq 2$. We will show that

$$
\begin{equation*}
x^{(L-2)}(t) \geq \frac{a}{2} t \tag{2.4}
\end{equation*}
$$

holds for sufficiently large $t$.
In order to simplify the sign, we assume that 2.3) holds for $t \geq t_{0}$. Consequently, for $t \in\left(t_{0}, t_{1}\right]$, we have

$$
x^{(L-2)}(t)=x^{(L-2)}\left(t_{0}^{+}\right)+\int_{t_{0}}^{t} x^{(L-1)}(s) d s \geq a\left(t-t_{0}\right)
$$

Particularly, $x^{(L-2)}\left(t_{1}\right) \geq a\left(t_{1}-t_{0}\right)$. For $t \in\left(t_{1}, t_{2}\right]$, we have

$$
\begin{aligned}
x^{(L-2)}(t) & =x^{(L-2)}\left(t_{1}^{+}\right)+\int_{t_{1}}^{t} x^{(L-1)}(s) d s \\
& \geq x^{(L-2)}\left(t_{1}^{+}\right)+a\left(t-t_{1}\right) \\
& =a_{1}^{(L-2)} x^{(L-2)}\left(t_{1}\right)+a\left(t-t_{1}\right) \\
& \geq a_{1}^{(L-2)} a\left(t_{1}-t_{0}\right)+a t-a t_{1} \\
& =a\left[t+\left(a_{1}^{(L-2)}-1\right) t_{1}-a_{1}^{(L-2)} t_{0}\right] .
\end{aligned}
$$

In particular, $x^{(L-2)}\left(t_{2}\right) \geq a\left[t_{2}+\left(a_{1}^{(L-2)}-1\right) t_{1}-a_{1}^{(L-2)} t_{0}\right]$. For $t \in\left(t_{2}, t_{3}\right]$, we obtain

$$
\begin{aligned}
x^{(L-2)}(t) & \geq x^{(L-2)}\left(t_{2}^{+}\right)+a\left(t-t_{2}\right) \\
& =a_{2}^{(L-2)} x^{(L-2)}\left(t_{2}\right)+a\left(t-t_{2}\right) \\
& \geq a_{2}^{(L-2)} a\left[t_{2}+\left(a_{1}^{(L-2)}-1\right) t_{1}-a_{1}^{(L-2)} t_{0}\right]+a t-a t_{2} \\
& =a\left[t+\left(a_{2}^{(L-2)}-1\right) t_{2}+a_{2}^{(L-2)}\left(a_{1}^{(L-2)}-1\right) t_{1}-a_{2}^{(L-2)} a_{1}^{(L-2)} t_{0}\right] .
\end{aligned}
$$

By induction, for $t \in\left(t_{k}, t_{k+1}\right]$, we get

$$
\begin{aligned}
& x^{(L-2)}(t) \\
& \geq a\left[t+\left(a_{k}^{(L-2)}-1\right) t_{k}+a_{k}^{(L-2)}\left(a_{k-1}^{(L-2)}-1\right) t_{k-1}+\ldots\right. \\
& \left.\quad+a_{k}^{(L-2)} a_{k-1}^{(L-2)} \ldots a_{2}^{(L-2)}\left(a_{1}^{(L-2)}-1\right) t_{1}-a_{k}^{(L-2)} a_{k-1}^{(L-2)} \ldots a_{2}^{(L-2)} a_{1}^{(L-2)} t_{0}\right] \\
& =a\left[t+\left(a_{k}^{(L-2)}-1\right)\left(t_{k}-t_{k-1}\right)+\left(a_{k}^{(L-2)} a_{k-1}^{(L-2)}-1\right)\left(t_{k-1}-t_{k-2}\right)\right. \\
& \left.\quad+\cdots+\left(a_{k}^{(L-2)} a_{k-1}^{(L-2)} \ldots a_{1}^{(L-2)}-1\right)\left(t_{1}-t_{0}\right)-t_{0}\right] \\
& =a\left[t+w_{1}^{L}(k)-t_{0}\right] .
\end{aligned}
$$

From (H3), we find $x^{(L-2)}(t) \geq \frac{a}{2} t$ holds for sufficiently large $t$. To complete the proof, we prove the inequality

$$
\begin{equation*}
x^{(L-j)}(t) \geq \frac{a}{p_{j}} t^{j-1}, \quad j=1,2, \ldots L \tag{2.5}
\end{equation*}
$$

where $p_{j}=2^{j-1}(j-1)$ ! and that $t$ is sufficiently large. From the above argument, it is clear that 2.5 holds for $j=1,2$. We suppose 2.5 holds for $j(j<L)$ and $t>t_{0}$. Then for $t \in\left(t_{0}, t_{1}\right]$,

$$
x^{(L-j-1)}(t) \geq x^{(L-j-1)}\left(t_{0}^{+}\right)+\int_{t_{0}}^{t} \frac{a}{p_{j}} s^{j-1} d s \geq \frac{a}{p_{j}} \int_{t_{0}}^{t} s^{j-1} d s=\frac{a}{j p_{j}}\left(t^{j}-t_{0}^{j}\right)
$$

In particular, $x^{(L-j-1)}\left(t_{1}\right) \geq \frac{a}{j p_{j}}\left(t_{1}^{j}-t_{0}^{j}\right)$. For $t \in\left(t_{1}, t_{2}\right]$, we get

$$
\begin{aligned}
x^{(L-j-1)}(t) & \geq x^{(L-j-1)}\left(t_{1}^{+}\right)+\int_{t_{1}}^{t} \frac{a}{p_{j}} s^{j-1} d s \\
& \geq a_{1}^{(L-j-1)} \frac{a}{j p_{j}}\left(t_{1}^{j}-t_{0}^{j}\right)+\frac{a}{j p_{j}}\left(t^{j}-t_{1}^{j}\right) \\
& =\frac{a}{j p_{j}}\left[t^{j}+\left(a_{1}^{(L-j-1)}-1\right) t_{1}^{j}-a_{1}^{(L-j-1)} t_{0}^{j}\right] .
\end{aligned}
$$

In particular, $x^{(L-j-1)}\left(t_{2}\right) \geq \frac{a}{j p_{j}}\left[t_{2}^{j}+\left(a_{1}^{(L-j-1)}-1\right) t_{1}^{j}-a_{1}^{(L-j-1)} t_{0}^{j}\right]$. By induction, we find that for $t \in\left(t_{k}, t_{k}+1\right]$,

$$
\begin{aligned}
& x^{(L-j-1)}(t) \\
& \geq \frac{a}{j p_{j}}\left[t^{j}+\left(a_{k}^{(L-j-1)}-1\right) t_{k}^{j}+a_{k}^{(L-j-1)}\left(a_{k-1}^{(L-j-1)}-1\right) t_{k-1}^{j}+\ldots\right. \\
& \quad+a_{k}^{(L-j-1)} a_{k-1}^{(L-j-1)} \ldots a_{2}^{(L-j-1)}\left(a_{1}^{(L-j-1)}-1\right) t_{1}^{j}-a_{k}^{(L-j-1)} a_{k-1}^{(L-j-1)} \\
& \left.\quad \ldots a_{2}^{(L-j-1)} a_{1}^{(L-2)} t_{0}^{j}\right] \\
& =\frac{a}{j p_{j}}\left[t^{j}+\left(a_{k}^{(L-j-1)}-1\right)\left(t_{k}^{j}-t_{k-1}^{j}\right)+\left(a_{k}^{(L-j-1)} a_{k-1}^{(L-j-1)}-1\right)\left(t_{k-1}^{j}-t_{k-2}^{j}\right)\right.
\end{aligned}
$$

$$
\begin{aligned}
& \left.+\cdots+\left(a_{k}^{(L-j-1)} a_{k-1}^{(L-j-1)} \ldots a_{1}^{(L-j-1)}-1\right)\left(t_{1}^{j}-t_{0}^{j}\right)-t_{0}^{j}\right] \\
= & \frac{a}{j p_{j}}\left[t^{j}+w_{j}^{L}(k)-t_{o}^{j}\right] .
\end{aligned}
$$

Using (H3) again, we obtain that

$$
x^{(L-j-1)}(t) \geq \frac{a}{2 j p_{j}} t^{j}=\frac{a}{p_{j+1}} t^{j}
$$

holds for sufficiently large $t$. Therefore, 2.5 is as well satisfied for $j+1$. Thus the proof is complete.

We are now able to state and show the main results, using the assumption

$$
\begin{align*}
\int_{t_{0}}^{t_{1}} p(s) s^{n-2} d s & +\frac{1}{b_{1}} \int_{t_{1}}^{t_{2}} p(s) s^{n-2} d s+\frac{1}{b_{1} b_{2} \ldots b_{k}} \int_{t_{k}}^{t_{k+1}} p(s) s^{n-2} d s+\cdots=+\infty  \tag{H4}\\
\text { where } b_{i} & =\max \left\{a_{i}, a_{i}^{1.5}, \ldots a_{i}^{(n-1)}\right\}
\end{align*}
$$

Theorem 2.5. Assuming (H1)-(H4) and that $n$ is even, then all solutions of 1.5 are oscillatory.
Proof. Suppose 1.5 has a non-oscillatory solution $x(t)$. We may assume $x(t)>0$ $\left(t \geq t_{0}\right)$ (the case when $x(t)<0\left(t \geq t_{0}\right)$ can be proved similarly and will not be included here). Lemma 2.3 shows that there exist constants $L \in\{1,3, \ldots, n-1\}$ such that 2.1 holds. Moreover, from Lemma 2.4 there exists a $T \geq t_{0}$ such that $t \geq T$ implies

$$
x(t-\tau) \geq M(t-\tau)^{L-1} \geq \frac{M}{2} t^{L-1}=N t^{L-1}
$$

where $N=\frac{M}{2}$. For convenience, let $T=t_{0}$. Thus

$$
x^{(n)}(t)=-p(t) x(t-\tau) \leq-N p(t) t^{L-1}, \quad\left(t \geq t_{0}\right)
$$

Multiplying both sides of the above inequality by $t^{n-L-1}$ and integrating both sides of it from $t_{k}$ to $t$, we obtain

$$
\int_{t_{k}}^{t} x^{(n)}(s) s^{n-L-1} d s \leq-N \int_{t_{k}}^{t} p(s) s^{n-2} d s, \quad t \in\left(t_{k}, t_{k+1}\right]
$$

Integrating by parts,

$$
\begin{equation*}
Q(t)-Q\left(t_{k}^{+}\right) \leq-N \int_{t_{k}}^{t} p(s) s^{n-2} d s \tag{2.6}
\end{equation*}
$$

where

$$
\begin{aligned}
Q(t)= & t^{n-L-1} x^{(n-1)}(t)-(n-L-1) t^{n-L-2} x^{(n-2)}(t) \\
& +(n-L-1)(n-L-2) t^{n-L-3} x^{(n-3)}(t)+\ldots \\
& +(-1)^{n-L-1}(n-L-1)!x^{(L)}(t)
\end{aligned}
$$

Lemma 2.3 suggests that $Q(t) \geq 0$. In view of 2.6, we obtain

$$
Q\left(t_{k}^{+}\right)-N \int_{t_{k}}^{t_{k+1}} p(s) s^{n-2} d s \geq 0
$$

Since

$$
Q\left(t_{i}^{+}\right)=a_{i}^{(n-1)} t_{i}^{n-L-1} x^{(n-1)}\left(t_{i}\right)-(n-L-1) a_{i}^{(n-2)} t_{i}^{n-L-2} x^{(n-2)}\left(t_{i}\right)
$$

$$
\begin{aligned}
& +(n-L-1)(n-L-2) a_{i}^{(n-3)} t_{i}^{n-L-3} x^{(n-3)}\left(t_{i}\right) \\
& +\cdots+(-1)^{n-L-1}(n-L-1)!a_{i}^{(L)} x^{(L)}\left(t_{i}\right) \\
\leq & b_{i} Q\left(t_{i}\right)
\end{aligned}
$$

then

$$
\begin{aligned}
Q\left(t_{1}\right) & \leq Q\left(t_{0}^{+}\right)-N \int_{t_{0}}^{t_{1}} p(s) s^{n-2} d s \\
Q\left(t_{2}\right) & <Q\left(t_{1}^{+}\right)-N \int_{t_{1}}^{t_{2}} p(s) s^{n-2} d s \\
& \leq b_{1} Q\left(t_{1}\right)-N \int_{t_{1}}^{t_{2}} p(s) s^{n-2} d s \\
& \leq b_{1}\left[Q\left(t_{0}^{+}\right)-N \int_{t_{0}}^{t_{1}} p(s) s^{n-2} d s\right]-N \int_{t_{1}}^{t_{2}} p(s) s^{n-2} d s \\
& =b_{1} N\left[\frac{Q\left(t_{0}^{+}\right)}{N}-\int_{t_{0}}^{t_{1}} p(s) s^{n-2} d s-\frac{1}{b_{1}} \int_{t_{1}}^{t_{2}} p(s) s^{n-2} d s\right] .
\end{aligned}
$$

Similarly

$$
\begin{aligned}
& Q\left(t_{3}\right) \\
& <Q\left(t_{2}^{+}\right)-N \int_{t_{2}}^{t_{3}} p(s) s^{n-2} d s \\
& \leq b_{2} Q\left(t_{2}\right)-N \int_{t_{2}}^{t_{3}} p(s) s^{n-2} d s \\
& \leq b_{2} b_{1} N\left[\frac{Q\left(t_{0}^{+}\right)}{N}-\int_{t_{0}}^{t_{1}} p(s) s^{n-2} d s-\frac{1}{b_{1}} \int_{t_{1}}^{t_{2}} p(s) s^{n-2} d s-\frac{1}{b_{1} b_{2}} \int_{t_{2}}^{t_{3}} p(s) s^{n-2} d s\right]
\end{aligned}
$$

Applying induction, we get

$$
\begin{aligned}
Q\left(t_{k}\right) \leq & b_{k-1} \ldots b_{2} b_{1} N\left[\frac{Q\left(t_{0}^{+}\right)}{N}-\left(\int_{t_{0}}^{t_{1}} p(s) s^{n-2} d s+\frac{1}{b_{1}} \int_{t_{1}}^{t_{2}} p(s) s^{n-2} d s\right.\right. \\
& \left.\left.+\cdots+\frac{1}{b_{k-1} \ldots b_{2} b_{1}} \int_{t_{k-1}}^{t_{k}} p(s) s^{n-2} d s\right)\right]
\end{aligned}
$$

According to (H4), $Q\left(t_{k}\right)<0$ holds for sufficiently large $k$. This contradicts that $Q\left(t_{k}\right) \geq 0$. Hence every solution of equation 1.5 is oscillatory.

Note that in Theorem 2.5. we use a method different from that of [3], and that our result and [3, Theorem 1] are independent. In particular, if $0<\prod_{k=1}^{+\infty} a_{k}^{(i)} \leq$ $\prod_{k=1}^{+\infty} b_{k}<+\infty, i=0,1, \ldots, n-1$, then condition (1.2) turns out to be (1.3). But in this theorem, we only need condition (1.4) to be satisfied.

Theorem 2.6. Suppose (H1)-(H4) hold, and that $n$ is odd. If

$$
\begin{equation*}
\sum_{k=1}^{\infty}\left|a_{k}^{(0)}-1\right|<+\infty \tag{2.7}
\end{equation*}
$$

then all the non-oscillatory solutions of (1.5 tend to zero.

Proof. Assume that $x(t)$ is a non-oscillatory solution of (1.5). Without loss of generality, we may assume $x(t)>0$ for $t \geq t_{0}-\tau$. By Lemma 2.3. one of the following two statements holds:
(i) $x(t)>0, x^{\prime}(t)>0, \ldots, x^{(L)}(t)>0, x^{(L+1)}(t)<0 \ldots, x^{(n-1)}(t)>0$, $x^{(n)}(t) \leq 0, L \in\{2,4, \ldots, n-1\}$,
(ii) $x(t)>0, x^{\prime}(t)<0, x^{\prime \prime}(t)>0, \ldots x^{(n-1)}(t)>0, x^{(n)}(t) \leq 0$.

If (i) is true, then employing the conditions (H1)-(H4) and by a similar way of the proof of Theorem 2.5, we find $x(t)$ is oscillatory, which contradicts the assumption that $x(t)$ is a non-oscillatory solution. Thus, only (ii) can be true. Therefore, $x(t)$ is monotonically decreasing in each interval $\left(t_{k}, t_{k+1}\right]$.

We claim that $\lim _{t \rightarrow \infty} x(t)=\alpha \geq 0$ exists and is finite. First, we show that

$$
\sum_{k=1}^{+\infty}\left|x\left(t_{k}^{+}\right)-x\left(t_{k}\right)\right|<+\infty
$$

It is an easy exercise to prove that condition 2.7 implies

$$
\begin{equation*}
\prod_{k=1}^{+\infty} a_{k}^{(0)}<+\infty \tag{2.8}
\end{equation*}
$$

Since

$$
\begin{aligned}
x\left(t_{k}^{+}\right) & =a_{k}^{(0)} x\left(t_{k}\right) \leq a_{k}^{(0)} x\left(t_{k-1}^{+}\right) \\
& =a_{k}^{(0)} a_{k-1}^{(0)} x\left(t_{k-1}\right) \leq \cdots \leq a_{k}^{(0)} a_{k-1}^{(0)} \ldots a_{1}^{(0)} x\left(t_{0}^{+}\right)
\end{aligned}
$$

by (2.8), we know that $\left\{x\left(t_{k}^{+}\right)\right\}$is bounded for $k \in N$. Furthermore, $x(t)$ is nonincreasing in every interval $\left(t_{k}, t_{k+1}\right]$, i.e. $x(t) \leq x\left(t_{k}^{+}\right) t \in\left(t_{k}, t_{k+1}\right]$. Thus, $x(t)$ is bounded on $\left[t_{0},+\infty\right)$. Now, from (2.7) and the bounded nature of $x(t)$, we find

$$
\sum_{k=1}^{+\infty}\left|x\left(t_{k}^{+}\right)-x\left(t_{k}\right)\right|<+\infty
$$

Next, to complete the claim, we let

$$
\begin{equation*}
c_{l}=\sum_{k=1}^{l}\left[x\left(t_{k}^{+}\right)-x\left(t_{k}\right)\right], \quad \lim _{l \rightarrow \infty} c_{l}=c \tag{2.9}
\end{equation*}
$$

and define a function

$$
y(t)=-c_{k}+x(t), t \in\left(t_{k}, t_{k+1}\right], \quad k \in N
$$

We will prove that $y(t)$ is non-increasing and bounded on $\left[t_{0},+\infty\right)$. From the definition of $y(t)$, we have

$$
\begin{aligned}
y\left(t_{k}\right) & =-c_{k-1}+x\left(t_{k}\right)=-c_{k-1}-\left[x\left(t_{k}^{+}\right)-x\left(t_{k}\right)\right]+x\left(t_{k}^{+}\right) \\
& =-c_{k}+x\left(t_{k}^{+}\right) \geq-c_{k}+x\left(t_{k+1}\right)=y\left(t_{k+1}\right), \quad k \in N .
\end{aligned}
$$

Now, for any $t_{0}<a<b<+\infty$, if there is some $k$ such that $a, b \in\left(t_{k}, t_{k+1}\right]$, then

$$
y(a)=-c_{k}+x(a) \geq-c_{k}+x(b)=y(b)
$$

If there exist $m, k \in N$ such that $0<m<k$ and $a \in\left(t_{m}, t_{m+1}\right], b \in\left(t_{k}, t_{k+1}\right]$, then from the non-increasing nature of $x(t)$ on $\left(t_{k}, t_{k+1}\right]$ and that $y\left(t_{k}\right) \geq y\left(t_{k+1}\right)$ we have

$$
y(a)=-c_{m}+x(a) \geq-c_{m}+x\left(t_{m+1}\right)=y\left(t_{m+1}\right)
$$

$$
\begin{aligned}
& \geq y\left(t_{k}\right)=-c_{k-1}+x\left(t_{k}\right)=-c_{k-1}-\left[x\left(t_{k}^{+}\right)-x\left(t_{k}\right)\right]+x\left(t_{k}^{+}\right) \\
& =-c_{k}+x\left(t_{k}^{+}\right) \geq-c_{k}+x(b)=y(b)
\end{aligned}
$$

Hence, $y(t)$ is non-increasing on $\left[t_{0},+\infty\right)$. On the other hand, 2.9) and the bounded nature of $x(t)$ imply that $y(t)$ is bounded on $\left[t_{0},+\infty\right)$. Therefore, the $\lim _{t \rightarrow \infty} y(t)=$ $A$ exists and hence the $\lim _{t \rightarrow \infty} x(t)=\alpha$ exists and $\alpha=A+c \geq 0$.

Finally, we prove that $\alpha=0$. If $\alpha>0$, then there exists $T>t_{0}$ such that $x(t-\tau) \geq \frac{\alpha}{2}$ for $t \geq T$. Thus

$$
x^{(n)}(t)=-p(t) x(t-\tau) \leq-\frac{\alpha}{2} p(t)
$$

and therefore,

$$
\int_{t_{k}}^{t} x^{(n)}(s) s^{n-2} d s \leq-\frac{\alpha}{2} \int_{t_{k}}^{t} p(s) s^{n-2} d s
$$

where $t \in\left(t_{k}, t_{k+1}\right]$.
The remainder of the proof is similar to that of Theorem 2.5 with $L=1$ and is omitted. The proof is completed.

We remark that the Theorem 2.6 is an extension of the result in [8.
For the next theorem we assume
(H5) There exists a sequence $\left\{t_{k_{m}}\right\}_{m=1}^{\infty}$ such that

$$
\int_{t_{k_{m}}-\tau}^{t_{k_{m}}}\left(t_{k_{m}}-s\right)^{n-1} p(s) d s>(n-1)!
$$

Theorem 2.7. Suppose that (H1)-(H5) hold and that $n$ is odd. Then all solutions of (1.5) are oscillatory.

Proof. Suppose on the contrary that (1.5) has a non-oscillatory solution $x(t)$. Without loss of generality, we may assume that $x(t)>0$ for $t \geq t_{0}-\tau$ and $\left\{t_{k_{m}}\right\}=\left\{t_{k}\right\}$.

Lemma 2.3 suggests that, for sufficiently large $t$, one of the statements (i) or (ii) in Theorem 2.6 is true. If (i) is true, then one can prove the required conclusion in a similar way as the proof of Theorem 2.5. So only the case (ii) need to be considered.

Since $t_{k}-t_{k-1}>3 \tau$, for $s \in\left[t_{k}-\tau, t_{k}\right)$, we have $s-\tau \in\left(t_{k-1}+\tau, t_{k}-\tau\right)$. Using the Taylor formula and (ii), we obtain

$$
\begin{aligned}
x^{(n)}(s)= & -p(s) x(s-\tau) \\
= & -p(s)\left[x\left(t_{k}-\tau\right)+x^{\prime}\left(t_{k}-\tau\right)\left(s-t_{k}\right)+\frac{1}{2} x^{\prime \prime}\left(t_{k}-\tau\right)\left(s-t_{k}\right)^{2}\right. \\
& \left.+\ldots \frac{x^{(n-1)}\left(t_{k}-\tau\right)}{(n-1)!}\left(s-t_{k}\right)^{n-1}+\frac{x^{(n)}(\xi)}{n!}\left(s-t_{k}\right)^{n}\right] \\
= & -p(s)\left[x\left(t_{k}-\tau\right)-x^{\prime}\left(t_{k}-\tau\right)\left(t_{k}-s\right)+\frac{1}{2} x^{\prime \prime}\left(t_{k}-\tau\right)\left(t_{k}-s\right)^{2} \ldots\right. \\
& \left.+\frac{x^{(n-1)}\left(t_{k}-\tau\right)}{(n-1)!}\left(t_{k}-s\right)^{n-1}-\frac{x^{(n)}(\xi)}{n!}\left(t_{k}-s\right)^{n}\right] \\
\leq & -p(s) \frac{x^{(n-1)}\left(t_{k}-\tau\right)}{(n-1)!}\left(t_{k}-s\right)^{n-1},
\end{aligned}
$$

where $\xi \in\left(s-\tau, t_{k}-\tau\right)$. Integrating both sides of the above inequality from $t_{k}-\tau$ to $t_{k}$,

$$
x^{(n-1)}\left(t_{k}\right)-x^{(n-1)}\left(t_{k}-\tau\right) \leq-\frac{x^{(n-1)}\left(t_{k}-\tau\right)}{(n-1)!} \int_{t_{k}-\tau}^{t_{k}}\left(t_{k}-s\right)^{n-1} p(s) d s
$$

Since $x^{(n-1)}\left(t_{k}\right)>0$,

$$
-x^{(n-1)}\left(t_{k}-\tau\right) \leq-\frac{x^{(n-1)}\left(t_{k}-\tau\right)}{(n-1)!} \int_{t_{k}-\tau}^{t_{k}}\left(t_{k}-s\right)^{n-1} p(s) d s
$$

or

$$
\begin{gathered}
1 \geq \frac{1}{(n-1)!} \int_{t_{k}-\tau}^{t_{k}}\left(t_{k}-s\right)^{n-1} p(s) d s \\
\int_{t_{k}-\tau}^{t_{k}}\left(t_{k}-s\right)^{n-1} p(s) d s \leq(n-1)!
\end{gathered}
$$

which contradicts (H5). So every solution of 1.5 is oscillatory.
Corollary 2.8. Assume that
(i) (H1) holds;
(ii) $a_{k}^{(i)} \geq 1, \prod_{k=1}^{+\infty} b_{k}<+\infty, i=0,1,2, \ldots, n-1$;
(iii) $\int^{+\infty} t^{n-2} p(t) d t=+\infty$.

Then the following statements are true: (a) If $n$ is even, then every solution of 1.5 is oscillatory. (b) If $n$ is odd, then every non-oscillatory solution of 1.5 converges to zero.
Proof. It is clear that condition $a_{k}^{(i)} \geq 1$ implies that (H2) and (H3), and that $\prod_{k=1}^{+\infty} b_{k}<+\infty$ yields that 2.7). (ii) and (iii) yield (H4). Thus, the required conclusion comes out immediately.

Corollary 2.9. Assume that (H1), (H2), (H3) hold and there exist an integer $K \geq 0$ and a constant $\alpha \geq 0$ such that $\frac{1}{b_{k}} \geq\left(\frac{t_{k+1}}{t_{k}}\right)^{\alpha}$ for $k \geq K$, where $b_{i}=$ $\max \left\{a_{i}^{1.5}, a_{i}^{(2)}, \ldots a_{i}^{(n-1)}\right\}$. If $\int^{+\infty} t^{n-2+\alpha} p(t) d t=+\infty$, then the following statements are true: (a) If $n$ is even, then every solution of 1.5 is oscillatory. (b) If $n$ is odd and (2.7) is satisfied,then every non-oscillatory solution of (1.5) converges to zero.

Proof. Without loss of generality, assume that $K=0$. By the assumption of Corollary 2.9, we have

$$
\begin{aligned}
\frac{1}{b_{1} b_{2} \ldots b_{k}} \int_{t_{k}}^{t_{k+1}} t^{n-2} p(t) d t & \geq\left(\frac{t_{2}}{t_{1}}\right)^{\alpha}\left(\frac{t_{3}}{t_{2}}\right)^{\alpha} \ldots\left(\frac{t_{k+1}}{t_{k}}\right)^{\alpha} \int_{t_{k}}^{t_{k+1}} t^{n-2} p(t) d t \\
& =\left(\frac{t_{k+1}}{t_{1}}\right)^{\alpha} \int_{t_{k}}^{t_{k+1}} t^{n-2} p(t) d t \\
& \geq \frac{1}{t_{1}^{\alpha}} \int_{t_{k}}^{t_{k+1}} t^{n-2+\alpha} p(t) d t
\end{aligned}
$$

and

$$
\int_{t_{0}}^{t_{1}} t^{n-2} p(t) d t+\frac{1}{b_{1}} \int_{t_{0}}^{t_{1}} t^{n-2} p(t) d t+\cdots+\frac{1}{b_{1} b_{2} \ldots b_{k}} \int_{t_{k}}^{t_{k+1}} t^{n-2} p(t) d t
$$

$$
\begin{aligned}
& \geq \frac{1}{t_{1}^{\alpha}} \int_{t_{0}}^{t_{1}} t^{n-2+\alpha} p(t) d t+\frac{1}{t_{1}^{\alpha}} \int_{t_{1}}^{t_{2}} t^{n-2+\alpha} p(t) d t+\cdots+\frac{1}{t_{1}^{\alpha}} \int_{t_{k}}^{t_{k+1}} t^{n-2+\alpha} p(t) d t \\
& =\frac{1}{t_{1}^{\alpha}} \int_{t_{0}}^{t_{k+1}} t^{n-2+\alpha} p(t) d t \rightarrow+\infty \quad \text { as } k \rightarrow+\infty
\end{aligned}
$$

This implies that (H4) holds and the required conclusion thus comes from Theorem 2.5 and Theorem 2.6 .

Corollary 2.10. Assume that (H1) holds and $a_{k}^{(i)} \geq 1, i=1,2, \ldots, n-1, k=$ $1,2, \ldots$ Furthermore, there exist an integer $K \geq 0$ and a constant $\alpha<0$ such that $\frac{1}{b_{k}} \geq\left(\frac{t_{k+1}}{t_{k}}\right)^{\alpha}$ for $k \geq K$. If

$$
\sum_{k=1}^{+\infty} t_{k+1}^{\alpha} \int_{t_{k}}^{t_{k+1}} t^{n-2} p(t) d t=+\infty
$$

then the following statements are true: (a) If $n$ is even, then every solution of (1.5) is oscillatory. (b) If $n$ is odd and (2.7) is satisfied, then every non-oscillatory solution of 1.5 converges to zero.

Proof. We proceed as in the proof of Corollary 2.9 and obtain that

$$
\frac{1}{b_{1} b_{2} \ldots b_{k}} \int_{t_{k}}^{t_{k+1}} t^{n-2} p(t) d t \geq\left(\frac{t_{k+1}}{t_{1}}\right)^{\alpha} \int_{t_{k}}^{t_{k+1}} t^{n-2} p(t) d t
$$

Then

$$
\begin{aligned}
& \int_{t_{0}}^{t_{1}} t^{n-2} p(t) d t+\frac{1}{b_{1}} \int_{t_{1}}^{t_{2}} t^{n-2} p(t) d t+\cdots+\frac{1}{b_{1} b_{2} \ldots b_{k}} \int_{t_{k}}^{t_{k+1}} t^{n-2} p(t) d t \\
& \geq \frac{1}{t_{1}^{\alpha}} \sum_{k=1}^{+\infty} t_{k+1}^{\alpha} \int_{t_{k}}^{t_{k+1}} t^{n-2} p(t) d t=+\infty
\end{aligned}
$$

By Theorem 2.5 and Theorem 2.6. the required result follows.

## 3. Examples

The following examples illustrate how the results can be applied in practice.
Example 3.1. Consider the impulsive delay differential equation

$$
\begin{align*}
& x^{(6)}(t)+\frac{2 t+1}{t^{6}} x\left(t-\frac{1}{5}\right)=0, \quad t \neq k, \quad k=1,2, \ldots  \tag{3.1}\\
& x^{(i)}\left(k^{+}\right)=\sqrt[2^{k}]{2} x^{(i)}(k), \quad i=0,1, \ldots, 5 ; \quad k=1,2, \ldots
\end{align*}
$$

where $a_{k}^{(i)}=\sqrt[2^{k}]{2}=b_{k}, i=0,1, \ldots 5, k=1,2, \ldots ; p(t)=\frac{2 t+1}{t^{6}}$. One can show easily that $\prod_{k=1}^{+\infty} b_{k}=2$ and $\int^{+\infty} t^{4} p(t) d t=+\infty$. By Corollary 2.8 . every solution of equation (3.1) is oscillatory.
Example 3.2. Consider the impulsive delay differential equation

$$
\begin{gather*}
x^{(5)}(t)+\frac{1}{t^{4}} x\left(t-\frac{1}{4}\right)=0, \quad t \neq k, k=1,2, \ldots  \tag{3.2}\\
x^{(i)}\left(k^{+}\right)=\left(1+c^{2^{k}}\right) x^{(i)}(k), \quad i=0,1,2, \ldots, 4 ; k=1,2, \ldots
\end{gather*}
$$

where $c$ is a constant, $0<c<1 . \quad b_{k}=a_{k}^{(i)}=1+c^{2^{k}}, i=0,1,2,3,4 ; k=$ $1,2, \ldots$ and $p(t)=\frac{1}{t^{4}}$. By simple calculation, we obtain $\lim _{k \rightarrow+\infty} b_{1} b_{2} \ldots b_{k}=$
$\frac{1}{1-c}, \int^{+\infty} t^{3} p(t) d t=+\infty$. It follows from Corollary 2.8 that every non-oscillatory solution of equation (3.2) tends to zero.

Example 3.3. Consider the impulsive delay differential equation

$$
\begin{gather*}
x^{(10)}(t)+\left(1 / t^{\frac{17}{2}}\right) x(t-0.5)=0, \quad t \neq k^{2}, k=1,2, \ldots \\
x^{(i)}\left(k^{+}\right)=((k+1) / k) x^{(i)}(k), \quad i=0,1, \ldots, 9 ; k=1,2, \ldots \tag{3.3}
\end{gather*}
$$

where $b_{k}=a_{k}^{(i)}=\frac{k+1}{k}, i=0,1, \ldots, 9 ; k=1,2, \ldots ; p(t)=1 / t^{\frac{17}{2}}$. Let $\alpha=-\frac{1}{2}$, then

$$
\frac{1}{b_{k}}=\frac{k+1}{k}=\left(\frac{t_{k+1}}{t_{k}}\right)^{\alpha} .
$$

Furthermore,

$$
\sum_{k=1}^{+\infty} t_{k+1}^{\alpha} \int_{t_{k}}^{t_{k+1}} t^{8} p(t) d t=\frac{1}{2} \sum_{k=1}^{+\infty} \frac{1}{k+1}=+\infty
$$

Thus, by Corollary 2.10, all the solutions of equation $\left(E_{3}\right)$ are oscillatory.
Example 3.4. Consider the impulsive delay differential equation

$$
\begin{gather*}
x^{(3)}(t)+\left(2+\frac{1}{t^{2}}\right) x\left(t-\frac{1}{4}\right)=0, \quad t \neq k, k=1,2, \ldots \\
x^{(i)}\left(k^{+}\right)=((k+1) / k) x^{(i)}(k),  \tag{3.4}\\
x^{(0)}\left(k^{+}\right)=x^{(0)}(k), i=1,2 ; k=1,2, \ldots
\end{gather*}
$$

where $a_{k}^{(0)}=1, b_{k}=a_{k}^{(i)}=\frac{k+1}{k}, i=1,2, k=1,2, \ldots, p(t)=2+\frac{1}{t^{2}}$. A simple calculation leads to

$$
\begin{gathered}
\sum_{k=1}^{+\infty} \frac{1}{b_{1} b_{2} \ldots b_{k}} \int_{k}^{k+1} s p(s) d s=\sum_{k=1}^{+\infty} \frac{1}{k+1} \int_{k}^{k+1}\left(2 s+\frac{1}{s}\right) d s \geq \sum_{k=1}^{+\infty} \frac{2 k+1}{k+1}=+\infty \\
\int_{t-\frac{1}{3}}^{t}(t-s)^{2} p(s) d s \geq 2 \int_{t-\frac{1}{3}}^{t}(t-s)^{2} d s=\frac{4}{3} t^{2}-\frac{8}{9}+\frac{2}{27} \rightarrow+\infty(t \rightarrow+\infty)
\end{gathered}
$$

Thus, (H1)-(H5) hold. By Theorem 2.7. every solution of equation (3.4) is oscillatory.

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Haihua Liang
School of Mathematical Sciences, South China Normal University, Guangzhou 510631, China

E-mail address: haiihuaa@tom.com
Weizhen Feng
School of Mathematical Sciences, South China Normal University, Guangzhou 510631, China


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