Electronic Journal of Differential Equations, Vol. 2006(2006), No. 68, pp. 1–11. ISSN: 1072-6691. URL: http://ejde.math.txstate.edu or http://ejde.math.unt.edu ftp ejde.math.txstate.edu (login: ftp)

EXISTENCE OF POSITIVE SOLUTIONS FOR BOUNDARY-VALUE PROBLEMS FOR SINGULAR HIGHER-ORDER FUNCTIONAL DIFFERENTIAL EQUATIONS

CHUANZHI BAI, QING YANG, JING GE

ABSTRACT. We study the existence of positive solutions for the boundary-value problem of the singular higher-order functional differential equation

 $(Ly^{(n-2)})(t) + h(t)f(t, y_t) = 0, \text{ for } t \in [0, 1],$

$$\begin{split} y^{(i)}(0) &= 0, \quad 0 \leq i \leq n-3, \\ \alpha y^{(n-2)}(t) - \beta y^{(n-1)}(t) &= \eta(t), \quad \text{for } t \in [-\tau, 0], \\ \gamma y^{(n-2)}(t) + \delta y^{(n-1)}(t) &= \xi(t), \quad \text{for } t \in [1, 1+a], \end{split}$$

where Ly := -(py')' + qy, $p \in C([0, 1], (0, +\infty))$, and $q \in C([0, 1], [0, +\infty))$. Our main tool is the fixed point theorem on a cone.

1. INTRODUCTION

As pointed out in [5], boundary-value problems associated with functional differential equations arise from problems in physics, from variational problems in control theory, and from applied mathematics; see for example [6, 8]. Many authors have investigated the existence of solutions for boundary-value problems of functional differential equations; see [3, 9, 15, 18]. Recently an increasing interest in studying the existence of positive solutions for such problems has been observed. Among others publication, we refer to [1, 2, 10, 11, 13, 19].

In this paper, we investigate the existence of positive solutions for singular boundary-value problems (BVP) of an *n*-th order $(n \ge 3)$ functional differential equation (FDE) of the form

$$(Ly^{(n-2)})(t) + h(t)f(t, y_t) = 0, \text{ for } t \in [0, 1],$$
 (1.1)

$$y^{(i)}(0) = 0, \quad 0 \le i \le n - 3,$$
 (1.2)

$$\alpha y^{(n-2)}(t) - \beta y^{(n-1)}(t) = \eta(t), \quad \text{for } t \in [-\tau, 0], \tag{1.3}$$

$$\gamma y^{(n-2)}(t) + \delta y^{(n-1)}(t) = \xi(t), \quad \text{for } t \in [1, 1+a], \tag{1.4}$$

2000 Mathematics Subject Classification. 34K10, 34B16.

Key words and phrases. Boundary value problem; higher-order; positive solution; functional differential equation; fixed point.

^{©2006} Texas State University - San Marcos.

Submitted April 21, 2006. Published July 6, 2006.

Supported by the Natural Science Foundation of Jiangsu Education Office and by Jiangsu Planned Projects for Postdoctoral Research Funds.

where Ly := -(py')' + qy, $p \in C([0,1], (0, +\infty))$, and $q \in C([0,1], [0, +\infty))$; $\alpha, \beta, \gamma, \delta \ge 0$, and $\alpha\delta + \alpha\gamma + \beta\gamma > 0$; $\eta \in C([-\tau, 0], \mathbb{R})$, $\xi \in C([1, b], \mathbb{R})$ (b = 1 + a), and $\eta(0) = \xi(1) = 0$; $h \in C((0, 1), \mathbb{R})$ (h(t) is allowed to have singularity at t = 0or 1); $f \in C([0, 1] \times D, \mathbb{R})$, $D = C([-\tau, a], \mathbb{R})$, for every $t \in [0, 1]$, $y_t \in D$ is defined by $y_t(\theta) = y(t + \theta), \theta \in [-\tau, a]$.

The study of higher-order functional differential equation has received also some attention; see for example [3, 10, 17]. Recently, Hong et al. [12] imposed conditions on $f(t, y^t)$ to yield at least one positive solution to (1.1)-(1.4) for the special case $h(t) \equiv 1$, $p(t) \equiv 1$, and $q(t) \equiv 0$. They applied the Krasnosel'skii fixed-point theorem.

The purpose of this paper is to establish the existence of positive solutions of the singular higher-order functional differential equation (1.1) with boundary conditions (1.2)-(1.4) under suitable conditions on f.

2. Preliminaries

To abbreviate our discussion, we assume the following hypotheses: (H1) G(t, s) is the Green's function of the differential equation

$$(Ly^{(n-2)})(t) = 0, \quad 0 < t < 1$$

subject to the boundary condition (1.2)-(1.4) with $\tau = a = 0$. (H2) g(t, s) is the Green's function of the differential equation

$$Ly(t) = 0 \quad t \in (0,1)$$

subject to the boundary conditions

$$\alpha y(0) - \beta y'(0) = 0, \quad \gamma y(1) + \delta y'(1) = 0,$$

where α, β, γ and δ are as in (1.3) and (1.4).

(H3) $h \in C((0, 1), [0, +\infty))$ and satisfies

$$0 < \int_0^1 g(s,s)h(s)ds < +\infty.$$

(H4) $f \in C([0,1] \times D^+, [0,\infty))$, where $D^+ = C([-\tau, a], [0, +\infty))$.

(H5) $\eta \in C([-\tau, 0], [0, +\infty)), \xi \in C([1, 1 + a], [0, +\infty))$, and $\eta(0) = \xi(1) = 0$. It is easy to see that

$$\frac{\partial^{n-2}}{\partial t^{n-2}}G(t,s) = g(t,s), \quad t,s \in [0,1].$$

It is also well known that the Green's function g(t,s) is

$$g(t,s) = \frac{1}{c} \begin{cases} \phi(s)\psi(t), & \text{if } 0 \le s \le t \le 1, \\ \phi(t)\psi(s), & \text{if } 0 \le t \le s \le 1, \end{cases}$$

where ϕ and ψ are solutions, respectively, of

$$L\phi = 0, \quad \phi(0) = \beta, \quad \phi'(0) = \alpha,$$
 (2.1)

$$L\psi = 0, \quad \psi(1) = \delta, \quad \psi'(1) = -\gamma.$$
 (2.2)

One can show that $c = -p(t)(\phi(t)\psi'(t) - \phi'(t)\psi(t)) > 0$ and $\phi'(t) > 0$ on (0, 1] and $\psi'(t) < 0$ on [0, 1). Clearly

$$g(t,s) \le g(s,s), \quad 0 \le t, s \le 1.$$
 (2.3)

$$\frac{g(t,s)}{g(s,s)} \ge \min\left\{\frac{\psi(1-\varepsilon)}{\psi(s)}, \frac{\phi(\varepsilon)}{\phi(s)}\right\} \ge \min\left\{\frac{\psi(1-\varepsilon)}{\psi(0)}, \frac{\phi(\varepsilon)}{\phi(1)}\right\} := \sigma.$$
(2.4)

Let $E = C^{(n-2)}([-\tau, b]; \mathbb{R})$ with a norm $||u||_{[-\tau, b]} = \sup_{-\tau \le t \le b} |u^{(n-2)}(t)|$ for $u \in E$. Obviously, E is a Banach space. And let $C = C^{(n-2)}([-\tau, a], \mathbb{R})$ be a space with norm $||\psi||_{[-\tau, a]} = \sup_{-\tau \le t \le a} |\psi^{(n-2)}(x)|$ for $\psi \in C$. Let

$$C^{+} = \{ \psi \in C : \psi(x) \ge 0, x \in [-\tau, a] \}.$$

It is easy to see that C^+ is a subspace of C.

Define a cone $K \subset E$ as follows:

$$K = \{ y \in E : y(t) \ge 0, \ \min_{t \in [\varepsilon, 1-\varepsilon]} y^{(n-2)}(t) \ge \overline{\sigma} \|y\|_{[-\tau, b]} \},$$
(2.5)

where $\overline{\sigma} = \frac{1}{b} \min\{\varepsilon, \sigma\}, \sigma$ is as in (2.4).

For each $\rho > 0$, we define $K_{\rho} = \{y \in K : ||y||_{[-\tau,b]} < \rho\}$. Furthermore, we define a set Ω_{ρ} as follows:

$$\Omega_{\rho} = \big\{ y \in K : \min_{\varepsilon \le t \le 1 - \varepsilon} y^{(n-2)}(t) < \overline{\sigma}\rho \big\}.$$

Similar to the [14, Lemma 2.5], we have

Lemma 2.1. Ω_{ρ} defined above has the following properties:

- (a) Ω_{ρ} is open relative to K.
- (b) $K_{\overline{\sigma}\rho} \subset \Omega_{\rho} \subset K_{\rho}$.
- (c) $y \in \partial \Omega_{\rho}$ if and only if $\min_{\varepsilon < t < 1-\varepsilon} y^{(n-2)}(t) = \overline{\sigma}\rho$.
- (d) If $y \in \partial \Omega_{\rho}$, then $\overline{\sigma}\rho \leq y^{(n-2)}(t) \leq \rho$ for $t \in [\varepsilon, 1-\varepsilon]$.

To obtain the positive solutions of (1.1)-(1.4), the following fixed point theorem in cones will be fundamental.

Lemma 2.2. Let K be a cone in a Banach space E. Let D be an open bounded subset of E with $D_K = D \cap K \neq \emptyset$ and $\overline{D}_K \neq K$. Assume that $A : \overline{D}_K \to K$ is a compact map such that $x \neq Ax$ for $x \in \partial D_K$. Then the following results hold.

- (1) $||Ax|| \le ||x||, x \in \partial D_K$, then $i_K(A, D_K) = 1$.
- (2) If there exists $e \in K \setminus \{0\}$ such that $x \neq Ax + \lambda e$ for all $x \in \partial D_K$ and all $\lambda > 0$, then $i_K(A, D_K) = 0$.
- (3) Let U be an open set in E such that $\overline{U} \subset D_K$. If $i_K(A, D_K) = 1$ and $i_K(A, U_K) = 0$, then A has a fixed point in $D_K \setminus \overline{U}_K$. The same results holds if $i_K(A, D_K) = 0$ and $i_K(A, U_K) = 1$.

Suppose that y(t) is a solution of (1.1)-(1.4), then it can be written as

$$y(t) = \begin{cases} y(-\tau; t), & -\tau \le t \le 0, \\ \int_0^1 G(t, s) h(s) f(s, y_s) ds, & 0 \le t \le 1, \\ y(b; t), & 1 \le t \le b, \end{cases}$$

where $y(-\tau; t)$ and y(b; t) satisfy

$$y^{(n-2)}(-\tau;t) = \begin{cases} e^{\frac{\alpha}{\beta}t} \left(\frac{1}{\beta} \int_{t}^{0} e^{-\frac{\alpha}{\beta}s} \eta(s) ds + y^{(n-2)}(0) \right), & t \in [-\tau,0], \ \beta \neq 0, \\ \frac{1}{\alpha} \eta(t), & t \in [-\tau,0], \ \beta = 0, \end{cases}$$

and

4

$$y^{(n-2)}(b;t) = \begin{cases} e^{-\frac{\gamma}{\delta}t} \left(\frac{1}{\delta} \int_1^t e^{\frac{\gamma}{\delta}s} \xi(s) ds + e^{\frac{\gamma}{\delta}} y^{(n-2)}(1)\right), & t \in [1,b], \ \delta \neq 0, \\ \frac{1}{\gamma} \xi(t), & t \in [1,b], \ \delta = 0. \end{cases}$$

Throughout this paper, we assume that $u_0(t)$ is the solution of (1.1)-(1.4) with $f \equiv 0$, and $||u_0||_{[-\tau,b]} =: M_0$. Clearly, $u_0^{(n-2)}(t)$ can be expressed as follows:

$$u_0^{(n-2)}(t) = \begin{cases} u_0^{(n-2)}(-\tau;t), & -\tau \le t \le 0, \\ 0, & 0 \le t \le 1, \\ u_0^{(n-2)}(b;t), & 1 \le t \le b. \end{cases}$$

where

$$u_0^{(n-2)}(-\tau;t) = \begin{cases} \frac{1}{\beta} e^{\frac{\alpha}{\beta}t} \int_t^0 e^{-\frac{\alpha}{\beta}s} \eta(s) ds, & t \in [-\tau,0], \ \beta \neq 0, \\ \frac{1}{\alpha} \eta(t), & t \in [-\tau,0], \ \beta = 0, \end{cases}$$

and

$$u_0^{(n-2)}(b;t) = \begin{cases} \frac{1}{\delta} e^{-\frac{\gamma}{\delta}t} \int_1^t e^{\frac{\gamma}{\delta}s} \xi(s) ds, & t \in [1,b], \ \delta \neq 0, \\ \frac{1}{\gamma} \xi(t), & t \in [1,b], \ \delta = 0. \end{cases}$$

Let y(t) be a solution of BVP (1.1)-(1.4) and $u(t) = y(t) - u_0(t)$. Noting that $u(t) \equiv y(t)$ for $0 \le t \le 1$, we have

$$u^{(n-2)}(t) = \begin{cases} u^{(n-2)}(-\tau;t), & -\tau \le t \le 0, \\ \int_0^1 g(t,s)h(s)f(s,u_s+(u_0)_s)ds, & 0 \le t \le 1, \\ u^{(n-2)}(b;t), & 1 \le t \le b, \end{cases}$$

where

$$u^{(n-2)}(-\tau;t) = \begin{cases} e^{\frac{\alpha}{\beta}t} \int_0^1 g(0,s)h(s)f(s,u_s+(u_0)_s)ds, & t \in [-\tau,0], \ \beta \neq 0, \\ 0, & t \in [-\tau,0], \ \beta = 0, \end{cases}$$

and

$$u^{(n-2)}(b;t) = \begin{cases} e^{-\frac{\gamma}{\delta}(t-1)} \int_0^1 g(1,s)h(s)f(s,u_s+(u_0)_s)ds, & t \in [1,b], \ \delta \neq 0, \\ 0, & t \in [1,b], \ \delta = 0. \end{cases}$$

It is easy to see that y(t) is a solution of BVP (1.1)-(1.4) if and only if $u(t) = y(t) - u_0(t)$ is a solution of the operator equation

$$u(t) = Au(t) \quad \text{for } t \in [-\tau, b].$$

$$(2.6)$$

Here, operator $A: E \to E$ is defined by

$$Au(t) := \begin{cases} B_1u(t), & -\tau \le t \le 0, \\ \int_0^1 G(t,s)h(s)f(s,u_s + (u_0)_s)ds, & 0 \le t \le 1, \\ B_2u(t), & 1 \le t \le b, \end{cases}$$

where

$$B_1 u(t) := \begin{cases} \left(\frac{\beta}{\alpha}\right)^{n-2} e^{\frac{\alpha}{\beta}t} \int_0^1 g(0,s)h(s)f(s,u_s+(u_0)_s)ds, & \beta \neq 0, \ \alpha \neq 0, \\ \frac{t^{n-2}}{(n-2)!} \int_0^1 g(0,s)h(s)f(s,u_s+(u_0)_s)ds, & \beta \neq 0, \ \alpha = 0, \\ 0, & \beta = 0 \end{cases}$$

for each $t \in [-\tau, 0]$, and

$$B_2u(t) := \begin{cases} \left(-\frac{\delta}{\gamma}\right)^{n-2} e^{-\frac{\gamma}{\delta}(t-1)} \int_0^1 g(1,s)h(s)f(s,u_s+(u_0)_s)ds, & \delta \neq 0, \ \gamma \neq 0, \\ \frac{t^{n-2}}{(n-2)!} \int_0^1 g(1,s)h(s)f(s,u_s+(u_0)_s)ds, & \delta \neq 0, \ \gamma = 0, \\ 0, & \delta = 0 \end{cases}$$

for any $t \in [1, b]$. Obviously,

$$(Au)^{(n-2)}(t) := \begin{cases} (B_1u)^{(n-2)}(t), & -\tau \le t \le 0, \\ \int_0^1 g(t,s)h(s)f(s,u_s+(u_0)_s)ds, & 0 \le t \le 1, \\ (B_2u)^{(n-2)}(t), & 1 \le t \le b, \end{cases}$$

where

$$(B_1 u)^{(n-2)}(t) := \begin{cases} e^{\frac{\alpha}{\beta}t} \int_0^1 g(0,s)h(s)f(s,u_s+(u_0)_s)ds, & t \in [-\tau,0], \ \beta \neq 0, \\ 0, & t \in [-\tau,0], \ \beta = 0, \end{cases}$$

and

$$(B_2 u)^{(n-2)}(t) := \begin{cases} e^{-\frac{\gamma}{\delta}(t-1)} \int_0^1 g(1,s)h(s)f(s,u_s+(u_0)_s)ds, & t \in [1,b], \ \delta \neq 0, \\ 0, & t \in [1,b], \ \delta = 0. \end{cases}$$

Lemma 2.3. With the above notation, $A(K) \subset K$.

Proof. By the assumptions of (H1)-(H5), it is easy to know that $Au \in E$ and $Au \ge 0$ for any $u \in K$. Moreover, it follows from

$$0 \le (Au)^{(n-2)}(t) \le (Au)^{(n-2)}(0) \quad \text{for } -\tau \le t \le 0$$

$$0 \le (Au)^{(n-2)}(t) \le (Au)^{(n-2)}(1) \quad \text{for } 1 \le t \le b$$

that $||Au||_{[-\tau,b]} = ||Au||_{[0,1]}$. By (2.3) we have, for any $u \in K$ and $t \in [0,1]$ that

$$||Au||_{[-\tau,b]} = ||Au||_{[0,1]} \le \int_0^1 g(s,s)h(s)f(s,u_s+(u_0)_s)ds.$$
(2.7)

From (2.4), we get

$$\min_{\varepsilon \le t \le 1-\varepsilon} (Au)^{(n-2)}(t) = \min_{\varepsilon \le t \le 1-\varepsilon} \int_0^1 g(t,s)h(s)f(s,u_s+(u_0)_s)ds$$
$$\ge \sigma \int_0^1 g(s,s)h(s)f(s,u_s+(u_0)_s)ds$$
$$\ge \overline{\sigma} \int_0^1 g(s,s)h(s)f(s,u_s+(u_0)_s)ds.$$
(2.8)

In view of (2.7) and (2.8), we obtain

$$\min_{\varepsilon \le t \le 1-\varepsilon} (Au)^{(n-2)}(t) \ge \overline{\sigma} \|Au\|_{[-\tau,b]}, \quad u \in K,$$

which implies $A(K) \subset K$.

Let

$$C^{+}_{[k,r]} = \{ \varphi \in C^{+} : k \le \|\varphi\|_{[-\tau,a]} \le r \},\$$

$$C^{+}_{[k,\infty)} = \{ \varphi \in C^{+} : k \le \|\varphi\|_{[-\tau,a]} < \infty \},\$$

where $0 \le k < r$.

Lemma 2.4. $A: K \to K$ is completely continuous.

Proof. We apply a truncation technique (cf. [16]). We define the function h_m for $m \ge 2$, by

$$h_m(t) = \begin{cases} \min\left\{h(t), h(\frac{1}{m})\right\}, & 0 < t \le \frac{1}{m}, \\ h(t), & \frac{1}{m} < t < 1 - \frac{1}{m}, \\ \min\left\{h(t), h(\frac{m-1}{m})\right\}, & \frac{m-1}{m} \le t < 1. \end{cases}$$

It is clear that $h_m(t)$ is nonnegative and continuous on [0, 1]. We define the operator A_m by

$$A_m u(t) := \begin{cases} B_{1m} u(t), & -\tau \le t \le 0, \\ \int_0^1 G(t,s) h_m(s) f(s, u_s + (u_0)_s) ds, & 0 \le t \le 1, \\ B_{2m} u(t), & 1 \le t \le b, \end{cases}$$

where

$$B_{1m}u(t) := \begin{cases} \left(\frac{\beta}{\alpha}\right)^{n-2} e^{\frac{\alpha}{\beta}t} \int_0^1 g(0,s)h_m(s)f(s,u_s+(u_0)_s)ds, & \beta \neq 0, \ \alpha \neq 0, \\ \frac{t^{n-2}}{(n-2)!} \int_0^1 g(0,s)h_m(s)f(s,u_s+(u_0)_s)ds, & \beta \neq 0, \ \alpha = 0, \\ 0, & \beta = 0 \end{cases}$$

for each $t \in [-\tau, 0]$, and

$$B_{2m}u(t) := \begin{cases} \left(-\frac{\delta}{\delta}\right)^{n-2} e^{-\frac{\gamma}{\delta}(t-1)} \int_0^1 g(1,s)h_m(s)f(s,u_s+(u_0)_s)ds, & \delta \neq 0, \ \gamma \neq 0, \\ \frac{t^{n-2}}{(n-2)!} \int_0^1 g(1,s)h_m(s)f(s,u_s+(u_0)_s)ds, & \delta \neq 0, \ \gamma = 0, \\ 0, & \delta = 0 \end{cases}$$

for any $t \in [1, b]$. By Lemma 2.3, it is easy to check that $A_m : K \to K$. And, A_m is continuous, the proof is similar to that of [11, Theorem 2.1].

Next let $B \subset K$ be a bounded subset of K, and $M_1 > 0$ be a constant such that $||u||_{[-\tau,b]} \leq M_1$ for $u \in B$. Noting that if $x_t \in C = C^{n-2}([-\tau,a],\mathbb{R})$, then $x_t^{(n-2)} \in C([-\tau,a],\mathbb{R})$, and $x_t^{(n-2)}(\theta) = x^{(n-2)}(t+\theta)$, $\theta \in [-\theta,a]$. Thus

$$\begin{aligned} \|u_{s} + (u_{0})_{s}\|_{[-\tau,a]} &= \sup_{-\tau \leq \theta \leq a} |(u^{s} + u_{0}^{s})^{(n-2)}(\theta)| \\ &\leq \sup_{-\tau \leq \theta \leq a} |(u^{(n-2)}(s+\theta)| + \sup_{-\tau \leq \theta \leq a} |u_{0}^{(n-2)}(s+\theta)| \\ &\leq \sup_{-\tau \leq t \leq b} |u^{(n-2)}(t)| + \sup_{-\tau \leq t \leq b} |u_{0}^{(n-2)}(t)| = \|u\|_{[-\tau,b]} + \|u_{0}\|_{[-\tau,b]} \\ &\leq M_{1} + M_{0} := M_{2} \end{aligned}$$

$$(2.9)$$

for $u \in B$ and $s \in [0,1]$. Hence, there exists a constant $M_3 > 0$ such that

$$|f(s, u_s + (u_0)_s)| \le M_3, \text{ on } [0, 1] \times C^+_{[0, M_3]},$$
 (2.10)

since f is continuous on $[0,1] \times C^+$. For $u \in B$ we have

$$(A_m u)^{(n-2)}(t) := \begin{cases} (B_{1m} u)^{(n-2)}(t), & -\tau \le t \le 0, \\ \int_0^1 g(t,s)h_m(s)f(s,u_s + (u_0)_s)ds, & 0 \le t \le 1, \\ (B_{2m} u)^{(n-2)}(t), & 1 \le t \le b, \end{cases}$$

where

$$(B_{1m}u)^{(n-2)}(t) := \begin{cases} e^{\frac{\alpha}{\beta}t} \int_0^1 g(0,s)h_m(s)f(s,u_s+(u_0)_s)ds, & t \in [-\tau,0], \ \beta \neq 0, \\ 0, & t \in [-\tau,0], \ \beta = 0, \end{cases}$$

and

$$(B_{2m}u)^{(n-2)}(t) := \begin{cases} e^{-\frac{\gamma}{\delta}(t-1)} \int_0^1 g(1,s)h_m(s)f(s,u_s+(u_0)_s)ds, & t \in [1,b], \ \delta \neq 0, \\ 0, & t \in [1,b], \ \delta = 0. \end{cases}$$

These and (2.10) imply $(A_m u)^{(n-2)}(t)$ is continuous and uniformly bounded for $u \in B$. So $(A_m u)'(t)$ is continuous and uniformly bounded for $u \in B$ also. The Ascoli-Arzela Theorem implies that A_m is a completely continuous operator on K for any $m \geq 2$.

Moreover, A_m converges uniformly to A as $m \to \infty$ on any bounded subset of K. To see this, note that if $u \in K$ with $||u||_{[-\tau,b]} \leq M$, then from (H3) and $0 \leq h_n(s) \leq h(s)$,

$$\begin{split} |(A_m u)^{(n-2)}(t) - (Au)^{(n-2)}(t)| &= \left| \int_0^{\frac{1}{m}} g(t,s)[h(s) - h_m(s)]f(s, u_s + (u_0)_s)ds \right. \\ &+ \int_{\frac{m-1}{m}}^1 g(t,s)[h(s) - h_m(s)]f(s, u_s + (u_0)_s)ds \\ &\leq \int_0^{\frac{1}{m}} g(s,s)|h(s) - h_m(s)|f(s, u_s + (u_0)_s)ds \\ &+ \int_{\frac{m-1}{m}}^1 g(s,s)|h(s) - h_m(s)|f(s, u_s + (u_0)_s)ds \\ &\leq 2\overline{M} \Big[\int_0^{\frac{1}{m}} g(s,s)h(s)ds + \int_{\frac{m-1}{m}}^1 g(s,s)h(s)ds \Big] \\ &\to 0 \quad \text{as } m \to \infty, \end{split}$$

where $\overline{M} := \max_{t \in [0,1], \varphi \in C^+_{[0,M+M_0]}} f(t,\varphi)$. Thus, we have

$$||A_m u - Au||_{[-\tau,b]} = ||A_m u - Au||_{[0,1]} \to 0, \quad n \to \infty,$$

for each $u \in K$ with $||u||_{[-\tau,b]} \leq M$. Hence, A_m converges uniformly to A as $m \to \infty$ and therefore A is completely continuous also. This completes the proof of Lemma 2.4.

3. Main results

For convenience, we introduce the following notation. Let

$$\begin{split} \omega &= \left(\int_{0}^{1} g(s,s)h(s)ds\right)^{-1}; \quad N = \left(\min_{\varepsilon \leq t \leq 1-\varepsilon} \int_{\varepsilon}^{1-\varepsilon} g(t,s)h(s)ds\right)^{-1}; \\ f_{\overline{\sigma}\rho}^{\rho} &= \inf\left\{\min_{t \in [\varepsilon, 1-\varepsilon]} \frac{f(t,\varphi)}{\rho} : \varphi \in C^{+}_{[\overline{\sigma}\rho, \rho+M_{0}]}\right\}; \\ f_{0}^{\rho} &= \sup\left\{\max_{t \in [0,1]} \frac{f(t,\varphi)}{\rho} : \varphi \in C^{+}_{[0,\rho+M_{0}]}\right\}; \\ f^{\mu} &= \lim_{\|\varphi\|_{[-\tau,a]} \to \mu} \sup\max_{t \in [0,1]} \frac{f(t,\varphi)}{\|\varphi\|_{[-\tau,a]}}; \\ f_{\mu} &= \lim_{\|\varphi\|_{[-\tau,a]} \to \mu} \inf\min_{t \in [\varepsilon, 1-\varepsilon]} \frac{f(t,\varphi)}{\|\varphi\|_{[-\tau,a]}}, \quad (\mu := \infty \text{ or } 0^{+}). \end{split}$$

Now, we impose conditions on f which we assure that $i_K(A, K_{\rho}) = 1$.

Lemma 3.1. Assume that

$$f_0^{\rho} \le \omega \quad and \quad u \ne Au \quad for \ u \in \partial K_{\rho}.$$
 (3.1)

Then $i_K(A, K_{\rho}) = 1$.

Proof. For $u \in \partial K_{\rho}$, we have $||u_s + (u_0)_s||_{[-\tau,a]} \leq \rho + M_0$, for all $s \in [0,1]$, i.e., $u_s + (u_0)_s \in C_{[0,\rho+M_0]}$ for any $s \in [0,1]$. It follows from (3.1) that for $t \in [0,1]$,

$$(Au)^{(n-2)}(t) = \int_0^1 g(t,s)h(s)f(s,u_s + (u_0)_s)ds$$

$$\leq \int_0^1 g(s,s)h(s)f(s,u_s + (u_0)_s)ds$$

$$< \rho\omega \int_0^1 g(s,s)h(s)ds$$

$$= \rho = ||u||_{[-\tau,b]}.$$

This implies that $||Au||_{[-\tau,b]} < ||u||_{[-\tau,b]}$ for $u \in \partial K_{\rho}$. By Lemma 2.2 (1), we have $i_K(A, K_{\rho}) = 1$.

Let
$$u \in \partial \Omega_{\rho}$$
, then for any $s \in [\varepsilon, 1 - \varepsilon]$, we have by Lemma 2.1(c) that
 $\|u_s + (u_0)_s\|_{[-\tau,a]} = \sup_{\theta \in [-\tau,a]} (u^{(n-2)}(s+\theta) + (u_0)^{(n-2)}(s+\theta))$
 $\geq \sup_{\theta \in [-\tau,a]} u^{(n-2)}(s+\theta) \text{ (since } (u_0)^{(n-2)}(t) \geq 0 \text{ for } t \in [-\tau,b])$
 $\geq u^{(n-2)}(s)$
 $\geq \min_{t \in [\varepsilon,1-\varepsilon]} u^{(n-2)}(t) = \overline{\sigma}\rho.$

By Lemma 2.1(b), we have $\overline{\Omega}_{\rho} \subset \overline{K}_{\rho}$, that is $||u||_{[-\tau,b]} \leq \rho$. Thus, from (2.9) we get $||u_s + (u_0)_s||_{[-\tau,b]} \leq ||u||_{[-\tau,b]} + ||u_0||_{[-\tau,b]} \leq \rho + M_0, \quad \forall s \in [0,1].$

$$||u_s + (u_0)_s||_{[-\tau,a]} \le ||u||_{[-\tau,b]} + ||u_0||_{[-\tau,b]} \le \rho + M_0, \quad \forall s \in [0,1]$$

Hence

$$u_s + (u_0)_s \in C^+_{[\overline{\sigma}\rho, \rho+M_0]}, \quad \text{for } u \in \partial\Omega_\rho, \ s \in [\varepsilon, 1-\varepsilon].$$

$$(3.2)$$

Next, we impose conditions on f which assure that $i_K(A, \Omega_{\rho}) = 0$.

Lemma 3.2. If f satisfies the condition

$$f^{\rho}_{\overline{\sigma}\rho} \ge N\overline{\sigma} \quad and \quad u \neq Au \quad for \ u \in \partial\Omega_{\rho}.$$
 (3.3)

Then $i_K(A, \Omega_{\rho}) = 0.$

Proof. Let

$$e(t) = \begin{cases} -\frac{t^{n-1}}{(1+\tau)(n-1)!}, & n \text{ is odd}, \ -\tau \le t \le 0, \\ \frac{t^n}{(1+\tau)^2 n!}, & n \text{ is even }, \ -\tau \le t \le 0, \\ \frac{t^{n-1}}{b(n-1)!}, & 0 \le t \le b. \end{cases}$$

It is easy to verify that $e \in C^{(n-2)}([-\tau, b], \mathbb{R}), e(t) \ge 0$ for $t \in [-\tau, b]$, and

$$e^{(n-2)}(t) = \begin{cases} -\frac{t}{1+\tau}, & n \text{ is odd, } -\tau \le t \le 0, \\ \frac{t^2}{2(1+\tau)^2}, & n \text{ is even, } -\tau \le t \le 0, \\ \frac{t}{b}, & 0 \le t \le b, \end{cases}$$

which implies that $e \in K$ and $||e||_{[-\tau,b]} = 1$, that is $e \in \partial K_1$. We claim that

$$u \neq Au + \lambda e, \quad u \in \partial \Omega_{\rho}, \quad \lambda > 0.$$

In fact, if not, there exist $u \in \partial \Omega_{\rho}$ and $\lambda_0 > 0$ such that $u = Au + \lambda_0 e$. Then by (3.2) for $t \in [\varepsilon, 1 - \varepsilon]$, we get

$$\begin{split} u^{(n-2)}(t) &= (Au)^{(n-2)}(t) + \lambda_0 e^{(n-2)}(t) \\ &= \int_0^1 g(t,s)h(s)f(s,u_s + (u_0)_s)ds + \lambda_0 e^{(n-2)}(t) \\ &\geq \int_{\varepsilon}^{1-\varepsilon} g(t,s)h(s)f(s,u_s + (u_0)_s)ds + \lambda_0 \frac{\varepsilon}{b} \\ &\geq \min_{\varepsilon \le t \le 1-\varepsilon} \int_{\varepsilon}^{1-\varepsilon} g(t,s)h(s)f(s,u_s + (u_0)^s)ds + \lambda_0 \overline{\sigma} \\ &\geq \rho N\overline{\sigma} \min_{\varepsilon \le t \le 1-\varepsilon} \int_{\varepsilon}^{1-\varepsilon} g(t,s)h(s)ds + \lambda_0 \overline{\sigma} \\ &\geq \overline{\sigma}\rho + \lambda_0 \overline{\sigma}. \end{split}$$

This implies that $\overline{\sigma}\rho \geq \overline{\sigma}\rho + \lambda_0\overline{\sigma}$, a contradiction. Moreover, it is easy to check that $u \neq Au$ for $u \in \partial\Omega_\rho$ from (3.3). Hence, by Lemma 2.2 (2), it follows that $i_K(A, \Omega_\rho) = 0.$

Theorem 3.3. If one of the following conditions holds:

(H7) There exist $\rho_1, \rho_2, \rho_3 \in (0, \infty)$ with $\rho_1 < \overline{\sigma} \rho_2$ and $\rho_2 < \rho_3$ such that

 $f_0^{\rho_1} \leq \omega, \quad f_{\overline{\sigma}\rho_2}^{\rho_2} \geq N\overline{\sigma}, \quad u \neq Au \quad for \ u \in \partial\Omega_{\rho_2} \quad and \quad f_0^{\rho_3} \leq \omega.$

(H8) There exist $\rho_1, \ \rho_2, \ \rho_3 \in (0,\infty)$ with $\rho_1 < \rho_2 < \overline{\sigma}\rho_3$ such that

$$f_{\overline{\sigma}\rho_1}^{\rho_1} \ge N\overline{\sigma}, \quad f_0^{\rho_2} \le \omega, \quad u \ne Au \quad for \ u \in \partial K_{\rho_2} \quad and \quad f_{\overline{\sigma}\rho_3}^{\rho_3} \ge N\overline{\sigma}.$$

Then BVP (1.1)-(1.4) has two positive solutions. Moreover, if in (H7), $f_0^{\rho_1} \leq \omega$ is replaced by $f_0^{\rho_1} < \omega$, then (1.1)-(1.4) has a third positive solution $u_3 \in K_{\rho_1}$.

Proof. Suppose that (H7) holds. We show that either A has a fixed point u_1 in ∂K_{ρ_1} or in $\Omega_{\rho_2} \setminus \overline{K_{\rho_1}}$. If $u \neq Au$ for $u \in \partial K_{\rho_1} \cup \partial K_{\rho_3}$, by Lemmas 3.1-3.2, we have $i_K(A, K_{\rho_1}) = 1$, $i_K(A, \Omega_{\rho_2}) = 0$ and $i_K(A, K_{\rho_3}) = 1$. Since $\rho_1 < \overline{\sigma}\rho_2$, we have $\overline{K_{\rho_1}} \subset K_{\overline{\sigma}\rho_2} \subset \Omega_{\rho_2}$ by Lemma 2.1 (b). It follows from Lemma 2.2 that A has a fixed point $u_1 \in \Omega_{\rho_2} \setminus \overline{K_{\rho_1}}$. Similarly, A has a fixed point $u_2 \in K_{\rho_3} \setminus \overline{\Omega_{\rho_2}}$. The proof is similar when (H8) holds.

As a special case of Theorem 3.3 we obtain the following result.

Corollary 3.4. Let $\xi(t) \equiv 0$, $\eta(t) \equiv 0$. If there exists $\rho > 0$ such that one of the following conditions holds:

(H9) $0 \leq f^0 < \omega, \ f^{\rho}_{\overline{\sigma}\rho} \geq N\overline{\sigma}, \ u \neq Au \ for \ u \in \partial\Omega_{\rho} \ and \ 0 \leq f^{\infty} < \omega.$ (H10) $N < f_0 \leq \infty, \ f_0^{\rho} \leq \omega, \ u \neq Au \ for \ u \in \partial K_{\rho} \ and \ N < f_{\infty} \leq \infty.$

Then BVP (1.1)-(1.4) has two positive solutions.

Proof. From $\xi(t) \equiv 0, \eta(t) \equiv 0$, it is clear that $u_0(t) \equiv 0$ for $t \in [-\tau, b]$, thus $M_0 = 0$. We now show that (H₉) implies (H₇). It is easy to verify that $0 \leq f^0 < \omega$ implies that there exists $\rho_1 \in (0, \overline{\sigma}\rho)$ such that $f_0^{\rho_1} < \omega$. Let $k \in (f^{\infty}, \omega)$. Then there exists $r > \rho$ such that $\max_{t \in [0,1]} f(t, \varphi) \leq k \|\varphi\|_{[-\tau,a]}$ for $\varphi \in C^+_{[r,\infty)}$ since $0 \leq f^{\infty} < \omega$. Let

$$l = \max\{\max_{t \in [0,1]} f(t,\varphi) : \varphi \in C^+_{[0,r]}\}, \text{ and } \rho_3 > \max\{\frac{l}{\omega-k}, \rho\}.$$

Then we have

$$\max_{t \in [0,1]} f(t,\varphi) \le k \|\varphi\|_{[-\tau,a]} + l \le k\rho_3 + l < \omega\rho_3 \quad \text{for } \varphi \in C^+_{[0,\rho_3]}.$$

This implies that $f_0^{\rho_3} < \omega$ and (H7) holds. Similarly, (H10) implies (H8).

By a similar argument to that of Theorem 3.3, we obtain the following results on existence of at least one positive solution of (1.1)-(1.4).

Theorem 3.5. If one of the following conditions holds:

(H11) There exist $\rho_1, \rho_2 \in (0, \infty)$ with $\rho_1 < \overline{\sigma} \rho_2$ such that

$$f_0^{\rho_1} \leq \omega \quad and \quad f_{\overline{\sigma}\rho_2}^{\rho_2} \geq N\overline{\sigma}.$$

(H12) There exist $\rho_1, \rho_2 \in (0, \infty)$ with $\rho_1 < \rho_2$ such that

$$f^{\rho_1}_{\overline{\sigma}\rho_1} \ge N\overline{\sigma} \quad and \quad f^{\rho_2}_0 \le \omega.$$

Then BVP (1.1)-(1.4) has a positive solution.

As a special case of Theorem 3.5, we obtain the following result.

Corollary 3.6. Let $\xi(t) \equiv 0, \eta(t) \equiv 0$. If one of the following conditions holds:

(H13) $0 \le f^0 < \omega$ and $N < f_\infty \le \infty$.

(H14) $0 \le f^{\infty} < \omega$ and $N < f_0 \le \infty$.

Then BVP (1.1)-(1.4) has a positive solution.

References

- C. Bai, J. Ma; Eigenvalue criteria for existence of multiple positive solutions to boundaryvalue problems of second-order delay differential equations, J. Math. Anal. Appl. 301 (2005) 457-476.
- C. Bai, J. Fang; Existence of multiple positive solutions for functional differential equations, Comput. Math. Appl. 45(2003) 1797-1806.
- [3] J.M. Davis, K.R. Prasad, W.K.C. Yin; Nonlinear eigenvalue problems involving two classa of functional differential equations, Houston J. Math. 26(2000) 597-608.
- [4] K. Deimling; Nonlinear Functional Analysis, Springer-Verlag, New York, 1985.
- [5] L.H. Erbe, Q.K. Kong; Boundary value problems for singular second order functional differential equations, J. Comput. Appl. Math. 53 (1994) 640-648.
- [6] L.J. Grimm, K. Schmitt; Boundary value problem problems for differential equations with deviating arguments, Aequationes Math. 4 (1970) 176-190.
- [7] D. Guo, V. Lakshmikantham; Nonlinear Problems in Abstract Cones, Academic Press, New York, 1988.
- [8] G.B. Gustafson, K. Schmitt; Nonzero solutions of boundary-value problems for second order ordinary and delay-differential equations, J. Differential Equations 12 (1972) 129-147.
- [9] J. Henderson, Boundary Value Problems for Functional Differential Equations, World Scientific, 1995.
- [10] J. Henderson, W.K.C. Yin; Positive solutions and nonlinear eigenvalue problems for functional differential equations, Appl. Math. Lett. 12 (1999) 63-68.
- [11] C.H. Hong, C.C. Yeh, C.F. Lee, F. Hsiang, F.H. Wong; Existence of positive solutions for functional differential equations, Comput. Math. Appl. 40 (2000) 783-792.
- [12] C.H. Hong, F.H. Wong, C.C. Yeh; Existence of positive solutions for higher-order functional differential equations, J. Math Anal. Appl. 297(2004) 14-23.
- [13] G. L. Karakostas, K. G. Mavridis, P. Ch. Tsamotos; Multiple positive solutions for a functional second-order boundary-value problem, J. Math. Anal. Appl. 282 (2003) 567-577.
- K.Q. Lan; Multiple positive solutions of semilinear differential equations with singularities, J. London. Math. Soc. 63(2001) 690-704.
- [15] S.K. Ntouyas, Y. Sficas, P.Ch. Tsamatos; An existence principle for boundary-value problems for second order functional differential equations, Nonlinear Anal. 20 (1993) 215-222.
- [16] Y. Shi, S. Chen; Multiple positive solutions of singular boundary value problems, Indian J. Pure Appl. Math. 30 (1999) 847-855.
- [17] D. Taunton, W.K.C. Yin; Existence of some functional differential equations, Comm. Appl. Nonlinear Anal. 4 (1997) 31-43.
- [18] P.Ch. Tsamatos; On a boundary-value problem for a system for functional differential equations with nonlinear boundary conditions, Funkcial. Ekvac. 42 (1999) 105-114.
- [19] P. Weng, D. Jiang; Existence of some positive solutions for boundary-value problem of secondorder FDE, J. Comput. Math. Appl. 37(1999) 1-9.

Chuanzhi Bai

Department of Mathematics, Huaiyin Teachers College, Huaian, Jiangsi 223001, China; and Department of Mathematics, Nanjing University, Nanjing 210093, China

E-mail address: czbai8@sohu.com

QING YANG

DEPARTMENT OF MATHEMATICS, HUAIYIN TEACHERS COLLEGE, HUAIAN, JIANGSI 223001, CHINA *E-mail address:* yangqing3511115@163.com

Jing Ge

DEPARTMENT OF MATHEMATICS, HUAIYIN TEACHERS COLLEGE, HUAIAN, JIANGSI 223001, CHINA *E-mail address:* gejing0512@163.com