

EXISTENCE OF GLOBAL SOLUTIONS FOR A SYSTEM OF REACTION-DIFFUSION EQUATIONS HAVING A TRIANGULAR MATRIX

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ABSTRACT. We consider the system of reaction-diffusion equations

$$\begin{aligned}u_t - a\Delta u &= \beta - f(u, v) - \alpha u, \\v_t - c\Delta u - d\Delta v &= g(u, v) - \sigma v.\end{aligned}$$

Our aim is to establish the existence of global classical solutions using the method used by Melkemi, Mokrane, and Youkana [19].

1. INTRODUCTION

In this manuscript, we consider a reaction-diffusion system that arises in the study of physical, chemistry, and various biological processes including population dynamics [3, 6, 7, 9, 14, 23, 24]. The system of equations is

$$\frac{\partial u}{\partial t} - a\Delta u = \beta - f(u, v) - \alpha u \quad (x, t) \in \Omega \times R_+ \quad (1.1)$$

$$\frac{\partial v}{\partial t} - c\Delta u - d\Delta v = g(u, v) - \sigma v \quad (x, t) \in \Omega \times R_+, \quad (1.2)$$

with the boundary conditions

$$\frac{\partial u}{\partial \eta} = \frac{\partial v}{\partial \eta} = 0 \quad \text{on } \partial\Omega \times R_+. \quad (1.3)$$

and the initial data

$$0 \leq u(0, x) = u_0(x); \quad 0 \leq v(0, x) = v_0(x) \quad \text{in } \Omega. \quad (1.4)$$

where Ω is a smooth open bounded domain in R^n , with boundary $\partial\Omega$ of class C^1 and η is the outer normal to $\partial\Omega$. The constants of diffusion a, c, d are such that $a > 0$, $d > 0$, $c > 0$ and $a > d$, $c^2 < 4ad$ which is the parabolic condition, and α, σ are positive constants, $\beta \geq 0$, and f, g are nonnegative functions of class $C(R_+ \times R_+)$, such that

- (H1) For all $\tau \geq 0$, $f(0, \tau) = 0$;
- (H2) For all $\xi \geq 0$ and all $\tau \geq 0$, $0 \leq f(\xi, \tau) \leq \varphi(\xi)(\mu + \tau)^r$;
- (H3) For all $\xi \geq 0$ and all $\tau \geq 0$, $g(\xi, \tau) \leq \psi(\tau)f(\xi, \tau) + \phi(\tau)$,

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where r, μ are positive constants such that $r \geq 1, \mu \geq 1, \varphi, \psi$ and ϕ are nonnegative functions of class $C(R^+)$, such that

$$\lim_{\tau \rightarrow +\infty} \frac{\psi(\tau)}{\tau} = \lim_{\tau \rightarrow +\infty} \frac{\phi(\tau)}{\tau} = 0. \quad (1.5)$$

$$\phi(0) > \beta \frac{c}{a-d}. \quad (1.6)$$

In addition we suppose that

$$g(\xi, \frac{c}{a-d}\xi) + \frac{c}{a-d}f(\xi, \frac{c}{a-d}\xi) \geq \frac{c}{a-d}[(\sigma - \alpha)\xi + \beta], \quad \forall \xi \geq 0. \quad (1.7)$$

Melkemi et al [19] established the existence of global solutions, (eventually uniformly bounded in time) using a novel approach that involved the use of a Lyapunov function for system (1.1)–(1.4) when $c = 0$. Here, we apply the same method to the study of system (1.1)–(1.4) when $c > 0$; that is, for a model that involves a triangular matrix.

2. EXISTENCE OF LOCAL AND POSITIVE SOLUTIONS

First we convert system (1.1)–(1.4) into an abstract first order system in $X = C(\overline{\Omega}) \times C(\overline{\Omega})$ of the form

$$U'(t) = AU(t) + F(U(t)), \quad t > 0, \quad (2.1)$$

$$U(0) = U_0 \in X, \quad (2.2)$$

where

$$\begin{aligned} AU(t) &= (a\Delta u, c\Delta u + d\Delta v), \\ F(U(t)) &= (\beta - f(u, v) - \alpha u, g(u, v) - \sigma v). \end{aligned}$$

Since F is locally Lipschitz in U and X , for every initial data $U_0 \in X$, system (2.1)–(2.2) admits a unique strong local solution on $]0, T^*[$, where T^* is the eventual blowing-up time, (see Kirane [14], Friedman [8], Henry [12], Pazy [20]).

Multiplying (1.1) by $\frac{c}{a-d}$, and subtracting the resulting equation from (1.2) leads to the system

$$\frac{\partial u}{\partial t} - a\Delta u = \Lambda(u, z), \quad (x, t) \in \Omega \times R_+ \quad (2.3)$$

$$\frac{\partial z}{\partial t} - d\Delta z = \Upsilon(u, z), \quad (x, t) \in \Omega \times R_+. \quad (2.4)$$

where

$$\begin{aligned} \Lambda(u, z) &= \beta - f(u, v) - \alpha u \\ \Upsilon(u, z) &= g(u, v) + \frac{c}{a-d}f(u, v) + \frac{c}{a-d}(\alpha u - \beta) - \sigma v, \\ z &= v - \frac{c}{a-d}u, \end{aligned}$$

with the boundary conditions

$$\frac{\partial u}{\partial \eta} = \frac{\partial z}{\partial \eta} = 0, \quad \text{on } \partial\Omega \times R_+ \quad (2.5)$$

and initial data

$$u(0, x) = u_0(x) \quad \text{in } \Omega, \quad (2.6)$$

$$z(0, x) = z_0(x) = v_0(x) - \frac{c}{a-d}u_0(x) \quad \text{in } \Omega. \quad (2.7)$$

If we assume (1.7) and (H1) then a simple application of a comparison theorem to system (2.3)-(2.4) implies (see [14]) that for positive initial data $u_0 \geq 0$ and $z_0 \geq 0$ we have that

$$u(t, x) \geq 0, \quad v(t, x) \geq \frac{c}{a-d}u(t, x) \quad \forall (x, t) \in \Omega \times]0, T^*[.$$

3. EXISTENCE OF GLOBAL SOLUTIONS

Before we establish the existence of a global solution, we introduce some notation. Here, we let

$$\|u\|_p^p = \frac{1}{|\Omega|} \int_{\Omega} |u(x)|^p dx \quad \text{and} \quad \|u\|_{\infty} = \max_{x \in \Omega} |u(x)|.$$

denote the usual norms in spaces $L^p(\Omega)$, $L^{\infty}(\Omega)$ and $C(\bar{\Omega})$. Applying the comparison principle we get that

$$u(t, x) \leq \max(\|u_0\|_{\infty}, \frac{\beta}{\alpha}) = K. \quad (3.1)$$

To establish the uniform boundedness of v , it is sufficient to show the uniform boundedness of z . This task is carried out using a result found in Henry [12, pp. 35-62], from which it sufficient to derive a uniform estimate for $\|\Upsilon(u, z)\|_p$; that is, finding a constant C such that

$$\|\Upsilon(u, z)\|_p \leq C. \quad (3.2)$$

Here C is a nonnegative constant independent of t , for some $p > n/2$. The key is to establish the uniform boundedness of $\|v\|_p$ on $]0, T^*[$, taking into account assumptions (H2) and (H3). When $p \geq 2$, we put

$$\begin{aligned} \Gamma(p) &= \frac{p\Gamma + 1}{p-1}, \quad \Gamma = (a-d)^2 \left[1 + \frac{1}{4ad}\right], \\ l &= \frac{2\beta\rho}{\Gamma(p)\sigma}, \quad \omega = \left[\frac{S^2}{4adR^2} + \frac{p}{R^2} + \mu\right](p-1) \end{aligned} \quad (3.3)$$

where $\rho > 0$,

$$S = \frac{\rho}{\Gamma(p)l}, \quad R = \frac{(a-d)\rho}{\Gamma(p)(l + \rho K)}.$$

Using these definitions and notation we can state the following key proposition

Proposition 3.1. *Assume that $p \geq 2$ and let*

$$G_N(t) = N \int_{\Omega} u dx + \int_{\Omega} (v + \omega)^p \exp\left(-\frac{1}{\Gamma(p)} \ln(\Gamma(p)[l + \rho(K - u)])\right) dx, \quad (3.4)$$

where (u, v) is the solution of (1.1)-(1.4) on $]0, T^*[$. Then under the assumptions (H3) and (1.5) there exist two positive constants N and s such that

$$\frac{dG_N}{dt} \leq -(p-1)\sigma G_N + s. \quad (3.5)$$

The proof of the above proposition requires some lemmas.

Lemma 3.2. *If (u, v) be a solution of (1.1) – (1.4) then*

$$\int_{\Omega} f(u, v) dx \leq \beta |\Omega| - \frac{d}{dt} \int_{\Omega} u(t, x) dx. \quad (3.6)$$

Proof. We integrate both sides of (1.1),

$$f(u, v) = \beta - \alpha u - \frac{d}{dt} u(t, x)$$

satisfied by u , which is positive and then we find (3.6). \square

Lemma 3.3. *Assume that $p \geq 2$, then under the assumptions (H1)–(H3), and (1.5) there exists N_1 , such that*

$$[p(g(\xi, \tau) - \phi(\tau))(\tau + \omega)^{p-1} - \theta f(\xi, \tau)(\tau + \omega)^p] \leq N_1 f(\xi, \tau) \quad (3.7)$$

for all $0 \leq \xi \leq K$ and $\tau \geq 0$, $\theta > 0$.

Proof. from the assumption (H3) and (1.5), we conclude that there exists $\tau_0 > 0$, such that for all $0 \leq \xi \leq K$, $\tau \geq \tau_0$, one finds

$$[p \frac{\psi(\tau)}{\tau + \omega} - \theta](\tau + \omega)^p f(\xi, \tau) \leq 0$$

now if τ is in the compact interval $[0, \tau_0]$, then the continuous function

$$\chi(\xi, \tau) = p\psi(\tau)(\tau + \omega)^{p-1} - \theta(\tau + \omega)^p$$

is bounded. \square

Lemma 3.4. *For all $\tau \geq 0$ and $\omega \geq 1$, we have*

$$\frac{\beta\rho}{\Gamma(p)l}(\tau + \omega)^p - \sigma p(\tau + \omega)^{p-1}\tau + p\phi(\tau)(\tau + \omega)^{p-1} \leq -(p-1)\sigma(\tau + \omega)^p + M_1 \quad (3.8)$$

where M_1 is positive constant.

Proof. Let us put

$$\begin{aligned} \Pi &= \frac{\beta\rho}{\Gamma(p)l}(\tau + \omega)^p - \sigma p(\tau + \omega)^{p-1}\tau \\ &\leq [2\frac{\beta\rho}{\Gamma(p)l} - \sigma p]\tau(\tau + \omega)^{p-1} + [2\frac{\beta\rho}{\Gamma(p)l}\frac{\omega}{\tau + \omega} - \frac{\beta\rho}{\Gamma(p)l}](\tau + \omega)^p \end{aligned}$$

since $l = \frac{2\beta\rho}{\Gamma(p)\sigma}$, then

$$\Pi + p\phi(\tau)(\tau + \omega)^{p-1} \leq -(p-1)\sigma(\tau + \omega)^p + [\frac{p(\sigma\omega + \phi(\tau))}{\sigma(\tau + \omega)} - \frac{1}{2}]\sigma(\tau + \omega)^p$$

using (1.5) and Lemma 3.3, we can establish Proposition 3.1. \square

Proof of Proposition 3.1. Let

$$h(u) = -\frac{1}{\Gamma(p)} \ln(\Gamma(p)[l + \rho(K - u)])$$

so that

$$G_N(t) = N \int_{\Omega} u dx + L(t)$$

where

$$L(t) = \int_{\Omega} e^{h(u)}(v + \omega)^p dx.$$

Differentiating L with respect to t and using Greens formula, we obtain that

$$L'(t) = I + J$$

where

$$\begin{aligned} I = & - \int_{\Omega} [a(h''(u) + h'^2(u))(v + \omega)^p + pch'(u)(v + \omega)^{p-1}] e^{h(u)} \nabla u^2 dx \\ & - \int_{\Omega} [p(a + d)h'(u)(v + \omega)^{p-1} + p(p-1)c(v + \omega)^{p-2}] e^{h(u)} \nabla u \nabla v dx \\ & - \int_{\Omega} p(p-1)d(v + \omega)^{p-2} e^{h(u)} \nabla v^2 dx \end{aligned}$$

and

$$\begin{aligned} J = & \int_{\Omega} \beta h'(u)(v + \omega)^p e^{h(u)} dx \\ & + \int_{\Omega} [pg(u, v)(v + \omega)^{p-1} - h'(u)f(u, v)(v + \omega)^p] e^{h(u)} dx \\ & - \int_{\Omega} \alpha h'(u)u(v + \omega)^p e^{h(u)} dx - \int_{\Omega} \sigma p(v + \omega)^{p-1} v e^{h(u)} dx. \end{aligned}$$

We see that I involves a quadratic form with respect to $\nabla u, \nabla v$.

$$\begin{aligned} D = & [a(h''(u) + h'^2(u))(v + \omega)^p + pch'(u)(v + \omega)^{p-1}] \nabla u^2 \\ & + [p(a + d)h'(u)(v + \omega)^{p-1} + p(p-1)c(v + \omega)^{p-2}] \nabla u \nabla v \\ & + p(p-1)d(v + \omega)^{p-2} \nabla v^2 \end{aligned}$$

which is nonnegative if

$$\begin{aligned} \delta = & [p(a + d)h'(u)(v + \omega)^{p-1} + p(p-1)(v + \omega)^{p-2}]^2 \\ & - 4p(p-1)d(v + \omega)^{p-2} [a(h''(u) + h'^2(u))(v + \omega)^p \\ & + pch'(u)(v + \omega)^{p-1}] \leq 0. \end{aligned}$$

Indeed,

$$\begin{aligned} \delta = & p^2(a + d)^2 h'^2(u)(v + \omega)^{2p-2} + 2(a + d)cp^2(p-1)h'(u)(v + \omega)^{2p-3} \\ & + c^2 p^2 (p-1)^2 (v + \omega)^{2p-4} - 4p(p-1)ad(h''(u) + h'^2(u))(v + \omega)^{2p-2} \\ & - 4cdp^2(p-1)h'(u)(v + \omega)^{2p-3} \end{aligned}$$

and from (3.3) we have that $v + \omega \geq 1$. It follows that

$$\begin{aligned} \delta \leq & [p^2(a + d)^2 h'^2(u) - 4p(p-1)ad(h''(u) + h'^2(u))](v + \omega)^{2p-2} \\ & + [2(a + d)cp^2(p-1)h'(u) + c^2 p^2 (p-1)^2 \\ & - 4cdp^2(p-1)h'(u)](v + \omega)^{2p-3}. \end{aligned}$$

Let us try

$$T = p^2(a + d)^2 h'^2(u) - 4p(p-1)ad(h''(u) + h'^2(u))$$

the choice of $h(u)$ implies

$$\frac{\rho}{\Gamma(p)[l + \rho K]} \leq h'(u) \leq \frac{\rho}{\Gamma(p)l}, \quad (3.9)$$

and, consequently,

$$T = -\frac{\rho^2 4ad(a-d)^2 p^2}{[\Gamma(p)(l + \rho(K-u))]^2} \leq -4adp^2 R^2 \leq 0.$$

In addition

$$\begin{aligned} \delta &\leq [2(a+d)cp^2(p-1)h'(u) + c^2p^2(p-1)^2 - 4cdp^2(p-1)h'(u)](v+\omega)^{2p-3} \\ &\quad + T(v+\omega)(v+\omega)^{2p-3} \\ &\leq [(p-1)c^2 + 2(a-d)c\frac{\rho}{\Gamma(p)l} - \frac{4adR^2\omega}{(p-1)}]p^2(p-1)(v+\omega)^{2p-3} + Tv(v+\omega)^{2p-3}. \end{aligned}$$

If we replace w by its value (3.3) and use the parabolic condition $c^2 - 4ad < 0$, we deduce that

$$\begin{aligned} \delta &\leq [p(c^2 - 4ad) - (c - S)^2 - 4adR^2\mu]p^2(p-1)(v+\omega)^{2p-3} \\ &\quad + Tv(v+\omega)^{2p-3} \leq 0, \end{aligned}$$

that is, $I \leq 0$.

We can control the second term by observing that

$$\begin{aligned} J &\leq \int_{\Omega} [\beta h'(u)(v+\omega)^p - \sigma p(v+\omega)^{p-1}v + p\phi(v)(v+\omega)^{p-1}]e^{h(u)} dx \\ &\quad + \int_{\Omega} [p(g(u,v) - \phi(v))(v+\omega)^{p-1} - h'(u)f(u,v)(v+\omega)^p]e^{h(u)} dx. \end{aligned}$$

Using (3.9),

$$\begin{aligned} J &\leq \int_{\Omega} [\frac{\beta\rho}{\Gamma(p)l}(v+\omega)^p - \sigma p(v+\omega)^{p-1}v + p\phi(v)(v+\omega)^{p-1}]e^{h(u)} dx \\ &\quad + \int_{\Omega} [p(g(u,v) - \phi(v))(v+\omega)^{p-1} - \frac{\rho}{\Gamma(p)[l + \rho k]}f(u,v)(v+\omega)^p]e^{h(u)} dx. \end{aligned}$$

Applying Lemmas 3.3 and 3.4, one finds that

$$J \leq -(p-1)\sigma \int_{\Omega} (v+\omega)^p e^{h(u)} dx + M_1 \int_{\Omega} e^{h(u)} dx + N_1 \int_{\Omega} f(u,v) e^{h(u)} dx.$$

In addition we see that

$$h(u) \leq -\frac{1}{\Gamma(p)} \ln \frac{2\beta\rho}{\sigma},$$

and, consequently,

$$J \leq -(p-1)\sigma L + M_1 |\Omega| e^{-\frac{1}{\Gamma(p)} \ln \frac{2\beta\rho}{\sigma}} + N_1 e^{-\frac{1}{\Gamma(p)} \ln \frac{2\beta\rho}{\sigma}} \int_{\Omega} f(u,v) dx.$$

Letting

$$M = M_1 |\Omega| e^{-\frac{1}{\Gamma(p)} \ln \frac{2\beta\rho}{\sigma}}, \quad N = N_1 e^{-\frac{1}{\Gamma(p)} \ln \frac{2\beta\rho}{\sigma}}$$

and using Lemma 3.2 we conclude that

$$\begin{aligned} J &\leq -(p-1)\sigma L + M + N[\beta|\Omega| - \frac{d}{dt} \int_{\Omega} u(t,x) dx] \\ &\leq -(p-1)\sigma G_N + (p-1)\sigma N \int_{\Omega} u dx + M + N\beta|\Omega| - N \frac{d}{dt} \int_{\Omega} u(t,x) dx \\ &\leq -(p-1)\sigma G_N + |\Omega| N [(p-1)K\sigma + \beta] + M - N \frac{d}{dt} \int_{\Omega} u(t,x) dx. \end{aligned}$$

It follows that

$$\frac{dG_N}{dt} \leq -(p-1)\sigma G_N + s$$

where $s = |\Omega|N[(p-1)K\sigma + \beta] + M$. □

We can now establish the main result of this manuscript.

Theorem 3.5. *Under the assumptions (H1)-(H3) and (1.5), the solutions of (1.1)–(1.4) are global and uniformly bounded in $[0, +\infty[$.*

Proof. Multiplying (3.5) by $e^{(p-1)\sigma t}$ and integrating, implies the existence of a positive constant $C > 0$ independent of t such that

$$G_N(t) \leq C.$$

Since

$$e^{h(u)} \geq e^{-\frac{1}{\Gamma(p)} \ln(\Gamma(p)[l+\rho k])},$$

for all $p \geq 2$, we have

$$\int_{\Omega} (v + \omega)^p dx \leq e^{\frac{1}{\Gamma(p)} \ln(\Gamma(p)[l+\rho k])} G_N(t) \leq C e^{\frac{1}{\Gamma(p)} \ln \Gamma(p)[l+\rho k]} = C(p).$$

Consequently,

$$\int_{\Omega} (v + \mu)^p dx \leq C(p), \quad \int_{\Omega} v^p dx \leq C(p).$$

Now we chose $p > n/2$ and we search for a bound for $\|\Upsilon(u, v)\|_p$. We put

$$A_1 = \max_{0 \leq \tau \leq \tau_0} \psi(\tau), \quad A_2 = \max_{0 \leq \xi \leq K} \varphi(\xi), \quad A_3 = \max_{0 \leq \tau \leq \tau_0} \phi(\tau)$$

where $\tau_0 = \max(\tau_1, \tau_2)$ such that

$$\tau \geq \tau_1 \Rightarrow \psi(\tau) \leq \tau, \quad \tau \geq \tau_2 \Rightarrow \phi(\tau) \leq \tau.$$

Using (H1)–(H3) implies

$$g(u, v) \leq \psi(v)f(u, v) + \phi(v) \leq \psi(v)\varphi(u)(\mu + v)^r + \phi(v) \leq A_2\psi(v)(\mu + v)^r + \phi(v).$$

Since $0 \leq u \leq K$, we have

$$\int_{\Omega} g(u, v)^p dx \leq \int_{\Omega} [A_2\psi(v)(\mu + v)^r + \phi(v)]^p dx.$$

Now we use the inequality

$$(x + y)^q \leq 2^{q-1}(x^q + y^q)$$

all $x, y \geq 0$ and $q \geq 1$, to obtain the following sequence of estimates

$$\begin{aligned} & \int_{\Omega} g(u, v)^p dx \\ & \leq \int_{\Omega} 2^{p-1} [A_2^p \psi(v)^p (\mu + v)^{rp} + \phi(v)^p] dx \\ & \leq 2^{p-1} \left[A_2^p \left(\int_{v \leq \tau_0} A_1^p (\mu + \tau_0)^{rp} dx + \int_{v \geq \tau_0} v^p (\mu + v)^{rp} dx \right) + |\Omega| A_3^p + \int_{v \geq \tau_0} v^p dx \right] \\ & \leq 2^{p-1} \left[\left(A_2 A_1 (\mu + \tau_0)^r \right)^p |\Omega| + A_2^p \int_{v \geq \tau_0} (\mu + v)^{(r+1)p} dx + |\Omega| A_3^p + \int_{v \geq \tau_0} v^p dx \right] \\ & \leq 2^{p-1} [(A_2 A_1 (\mu + \tau_0)^r)^p |\Omega| + A_2^p C((r+1)p) + |\Omega| A_3^p + C(p)] = E_g^p \end{aligned}$$

and

$$\int_{\Omega} f(u, v)^p dx \leq A_2^p C(rp) = E_f^p.$$

We conclude that

$$\begin{aligned} \|\Upsilon(u, v)\|_p &\leq \|g(u, v)\|_p + \frac{c}{a-d} [\|f(u, v)\|_p + \alpha\|u\|_p + \beta|\Omega|] + \sigma\|v\|_p \\ &\leq E_g + \frac{c}{a-d} [E_f + (\alpha K + \beta)|\Omega|] + \sigma\sqrt[p]{C(p)}. \end{aligned}$$

We conclude that the unique solution of (1.1)–(1.4) is globally and uniformly bounded in $[0, +\infty[\times\Omega$. \square

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