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# PERIODIC BOUNDARY-VALUE PROBLEMS FOR FOURTH-ORDER DIFFERENTIAL EQUATIONS WITH DELAY 

SAMUEL A. IYASE

$$
\begin{aligned}
& \text { ABSTRACT. We study the periodic boundary-value problem } \\
& \qquad \begin{aligned}
x^{(i v)}(t)+f(\ddot{x}) \dddot{x}(t)+b \ddot{x}(t)+g(t, \dot{x}(t-\tau))+d x=p(t) \\
x(0)=x(2 \pi), \quad \dot{x}(0)=\dot{x}(2 \pi), \quad \ddot{x}(0)=\ddot{x}(2 \pi), \quad \dddot{x}(0)=\dddot{x}(2 \pi),
\end{aligned}
\end{aligned}
$$

Under some resonant conditions on the asymptotic behaviour of the ratio $g(t, y) /(b y)$ for $|y| \rightarrow \infty$. Uniqueness of periodic solutions is also examined.

## 1. Introduction

In this article we study the periodic boundary-value problem

$$
\begin{gather*}
x^{(i v)}(t)+f(\ddot{x}) \dddot{x}(t)+b \ddot{x}+g(t, \dot{x}(t-\tau))+d x=p(t) \\
x(0)=x(2 \pi), \quad \dot{x}(0)=\dot{x}(2 \pi), \quad \ddot{x}(0)=\ddot{x}(2 \pi), \quad \dddot{x}(0)=\dddot{x}(2 \pi), \tag{1.1}
\end{gather*}
$$

with fixed delay $\tau \in[0,2 \pi), f: \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function, $P:[0,2 \pi] \rightarrow \mathbb{R}$ and $g:[0,2 \pi] \times \mathbb{R} \rightarrow \mathbb{R}$ are $2 \pi-$ periodic in $t$ and $g$ satisfies Caratheodory conditions with $b$ and $d$ real constants. The unknown function $x:[0,2 \pi] \rightarrow \mathbb{R}$ is defined for $0<t \leq \tau$ by $x(t-\tau)=[2 \pi-(t-\tau)]$. We are concerned with the existence and uniqueness of periodic solution of equation (1.1) under some resonant conditions on $g$.

It is pertinent to note that fourth-order differential equations with time delay are used to model problems in engineering and biological or physiological systems. For instance, the oscillatory movements of muscles that occur as a result of the interaction of a muscle with its load (see [5]). For other papers dealing with the study of fourth order differential equations with time delay see [2, 3] and references therein.

In what follows, we shall use the spaces $C([0,2 \pi]), C^{k}([0,2 \pi])$ and $L^{k}([0,2 \pi])$ of continuous, $k$ times continuously differentiable or measurable real functions whose $k t h$ power of the absolute value are lebesgue integrable. We shall use the following

[^0]Sobolev spaces:

$$
\begin{aligned}
W_{2 \pi}^{4,2}= & \{x:[0,2 \pi] \rightarrow \mathbb{R}: x, \dot{x}, \ddot{x}, \dddot{x} \text { are absolutely continuous on }[0,2 \pi] \text { and } \\
& x(0)=x(2 \pi), \dot{x}(0)=\dot{x}(2 \pi), \ddot{x}(0)=\ddot{x}(2 \pi), \dddot{x}(0)=\dddot{x}(2 \pi)\}
\end{aligned}
$$

with the norm

$$
|x|_{W_{2 \pi}^{4,2}}^{2}=\sum_{i=0}^{4} \frac{1}{2 \pi} \int_{0}^{2 \pi}\left|x^{i}(t)\right|^{2} d t
$$

and

$$
H_{2 \pi}^{1}=\left\{x:[0,2 \pi] \rightarrow \mathbb{R}: x \text { is absolutely continuous on }[0,2 \pi] \text { and } \dot{x} \in L_{2 \pi}^{2}\right\}
$$

with the norm

$$
|x|_{W_{2 \pi}^{4,2}}^{2}=\left(\frac{1}{2 \pi} \int_{0}^{2 \pi} x(t) d t\right)^{2}+\frac{1}{2 \pi} \int_{0}^{2 \pi}|\dot{x}|^{2} d t
$$

## 2. The Linear Problem

We consider here the linear delay equation

$$
\begin{gather*}
\left.x^{(i v)}(t)+a \dddot{x}(t)+b \ddot{x}(t)+c \dot{x}(t-\tau)\right)+d x=0  \tag{2.1}\\
x(0)=x(2 \pi), \quad \dot{x}(0)=\dot{x}(2 \pi), \quad \ddot{x}(0)=\ddot{x}(2 \pi), \quad \dddot{x}(0)=\dddot{x}(2 \pi),
\end{gather*}
$$

where $c$ is a real constant.
Lemma 2.1. Let $b<0, d>0$ and

$$
\begin{equation*}
0<\frac{c}{b}<n \tag{2.2}
\end{equation*}
$$

where $n$ is an integer $n \geq 1$. Then (2.1) has no non-trivial periodic solution for any fixed $\tau \in[0,2 \pi)$.

Proof. We consider a solution of the form $x(t)=e^{\lambda t}$ where $\lambda=i n$ with $i^{2}=-1$. Then Lemma 2.1 will follow if

$$
\psi(n, \tau)=n^{4}-b n^{2}+c n \sin n \tau+d \neq 0
$$

for all $n \geq 1$ and $\tau \in[0,2 \pi)$. By 2.2 , we obtain

$$
\begin{aligned}
b_{-1} \psi(n, \tau) & =\frac{n^{4}}{b}-n^{2}+\frac{c}{b} n \sin n \tau+\frac{d}{b} \\
& \leq \frac{n^{4}}{b}-n^{2}+\frac{c}{b} n+\frac{d}{b} \\
& <\frac{n^{4}}{b}+\frac{d}{b}<0 .
\end{aligned}
$$

Therefore, $\psi(n, \tau) \neq 0$ and the result follows. If $x \in L_{2 \pi}^{1}$ we shall write

$$
\bar{x}=\frac{1}{2 \pi} \int_{0}^{2 \pi} x(t) d t, \quad \tilde{x}(t)=x(t)-\bar{x}
$$

such that $\int_{0}^{2 \pi} \tilde{x}(t) d t=0$.
We consider next the delay equation

$$
\begin{gather*}
\left.x^{(i v)}(t)+a \dddot{x}(t)+b \ddot{x}(t)+c(t) \dot{x}(t-\tau)\right)+d x=0 \\
x(0)=x(2 \pi), \quad \dot{x}(0)=\dot{x}(2 \pi), \quad \ddot{x}(0)=\ddot{x}(2 \pi), \quad \dddot{x}(0)=\dddot{x}(2 \pi), \tag{2.3}
\end{gather*}
$$

where $a, b$ are constants and $c(t) \in L_{2 \pi}^{2}$.

Theorem 2.2. Let $b<0, d>0$ and $\Gamma(t)=b^{-1} c(t) \in L_{2 \pi}^{2}$. Suppose that

$$
\begin{equation*}
0<\Gamma(t)<1 \tag{2.4}
\end{equation*}
$$

Then 2.3 has no non-trivial periodic solution for every fixed $\tau \in[0,2 \pi)$.
Proof. Let $x(t)$ be any solution of 2.3 . Then

$$
\begin{aligned}
0= & \frac{1}{2 \pi} \int_{0}^{2 \pi} \ddot{\tilde{x}}(t)\left[\frac{b^{-1}}{2 \pi}\left\{x^{(i v)}+a \dddot{x}+d x+\{\ddot{x}+\Gamma(t) \dot{x}(t-\tau)\}\right\}\right] d t \\
= & -\frac{b^{-1}}{2 \pi} \int_{0}^{2 \pi} \ddot{\tilde{x}}^{2}(t) d t-\frac{d b^{-1}}{2 \pi} \int_{0}^{2 \pi} \dot{\tilde{x}}^{2}(t) d t+\frac{1}{2 \pi} \int_{0}^{2 \pi} \ddot{\tilde{x}}(t)[\dddot{x}(t)+\Gamma(t) \dot{x}(t-\tau)] d t \\
\geq & \frac{1}{2 \pi} \int_{0}^{2 \pi} \ddot{\tilde{x}}(t)[\ddot{x}(t)+\Gamma(t) \dot{x}(t-\tau)] d t \\
= & \int_{0}^{2 \pi}\left[\ddot{\tilde{x}}^{2}(t)+\Gamma(t) \ddot{\tilde{x}}(t) \dot{x}(t-\tau)\right] d t \\
= & \frac{1}{2 \pi} \int_{0}^{2 \pi}\left[\ddot{\tilde{x}}^{2}(t)-\frac{\Gamma(t)}{2} \ddot{\tilde{x}}^{2}(t)-\frac{\Gamma(t)}{2} \dot{\tilde{x}}^{2}(t-\tau)\right] d t \\
& +\frac{1}{2 \pi} \int_{0}^{2 \pi} \frac{\Gamma(t)}{2}[\ddot{\tilde{x}}(t)+\dot{x}(t-\tau)]^{2} d t .
\end{aligned}
$$

In the above expression we used the equality

$$
a b=\left(\frac{a+b}{2}\right)^{2}-\frac{a^{2}}{2}-\frac{b^{2}}{2}
$$

From the periodicity of $\dot{x}(t)$, it follows that

$$
\frac{1}{2 \pi} \int_{0}^{2 \pi} \ddot{\tilde{x}}^{2}(t) d t=\frac{1}{2 \pi} \int_{0}^{2 \pi} \ddot{\tilde{x}}^{2}(t-\tau) d t
$$

Hence,

$$
\begin{aligned}
0 & \geq \frac{1}{2}\left[\frac{1}{2 \pi} \int_{0}^{2 \pi}\left[\ddot{\tilde{x}}^{2}(t)-\Gamma(t) \ddot{\tilde{x}}^{2}(t)\right] d t\right] \\
& =\frac{1}{2}\left[\frac{1}{2 \pi} \int_{0}^{2 \pi}\left[\ddot{\tilde{x}}^{2}(t-\tau)-\Gamma(t) \dot{\tilde{x}}^{2}(t-\tau)\right] d t\right. \\
& \geq \delta|\dot{\tilde{x}}|_{H_{2 \pi}^{1}}^{2}=\delta|\dot{x}|_{H_{2 \pi}^{1}} .
\end{aligned}
$$

By [4, Lemma 1] where $\delta>0$ is a constant. This implies that $x$ is constant a.e. But since $d \neq 0$ we must have $x=0$, a. e.

## 3. The non-Linear problem

We shall consider here a preliminary Lemma which will enable us obtain a priori estimates required for our results.
Lemma 3.1. Let all the conditions of Lemma 2.1 hold and let $\delta$ be related to $\Gamma(t)$ by Theorem 2.2. Suppose that $v \in L_{2 \pi}^{2}$ and

$$
0<v(t)<\Gamma(t)+\epsilon \quad \text { a.e. } t \in[0,2 \pi]
$$

holds for any $v \in L_{2 \pi}^{2}$, where $\epsilon>0$. Then

$$
\frac{1}{2 \pi} \int_{0}^{2 \pi} \ddot{\tilde{x}}(t)\left[b^{-1}\left\{x^{(i v)}+a \dddot{x}+d x\right\}+\ddot{x}+\Gamma(t) \dot{x}(t-\tau)\right] d t \geq(\delta-\epsilon)|\dot{x}|_{H_{2 \pi}^{1}}^{2}
$$

Proof. From the proof of Theorem 2.2. we have

$$
\begin{aligned}
& \frac{1}{2 \pi} \int_{0}^{2 \pi} \ddot{\tilde{x}}(t)\left[b^{-1}\left\{x^{(i v)}+a \dddot{x}+d x\right\}+\ddot{x}+v(t) \dot{x}(t-\tau)\right] d t \\
& \geq \frac{1}{2}\left[\frac{1}{2 \pi} \int_{0}^{2 \pi}\left[\ddot{\tilde{x}}^{2}(t)-\Gamma(t) \ddot{\tilde{x}}^{2}(t)\right] d t\right]+\frac{1}{2}\left[\frac{1}{2 \pi} \int_{0}^{2 \pi}\left[\ddot{\tilde{x}}^{2}(t-\tau)-\Gamma(t) \dot{\tilde{x}}^{2}(t-\tau)\right] d t\right] \\
& \quad-\epsilon \frac{1}{2 \pi} \int_{0}^{2 \pi}\left(\dot{\tilde{x}}^{2}(t-\tau)+\ddot{\tilde{x}}^{2}(t)\right) d t \\
& \geq \frac{1}{2}\left[\frac{1}{2 \pi} \int_{0}^{2 \pi}\left[\ddot{\tilde{x}}^{2}(t-\tau)-\Gamma(t) \dot{\tilde{x}}^{2}(t-\tau)\right] d t\right]-\frac{\epsilon}{2 \pi} \int_{0}^{2 \pi} \dot{x}^{2}(t-\tau) \\
& \quad-\frac{\epsilon}{2 \pi} \int_{0}^{2 \pi} \ddot{\tilde{x}}^{2}(t-\tau) d t \\
& \geq \delta|\dot{\tilde{x}}|_{H_{2 \pi}^{1}}^{2}-\epsilon \mid \ddot{\tilde{x}}_{H_{H 2 \pi}^{1}}^{2} \\
& \geq(\delta-\epsilon)|\dot{\tilde{x}}|_{H_{2 \pi}^{1}}^{2} .
\end{aligned}
$$

We shall consider the non-linear delay equation

$$
\begin{equation*}
x^{(i v)}+f(\ddot{x}) \dddot{x}+b \ddot{x}+g(t, \dot{x}(t-\tau))+d x=p(t) \tag{3.1}
\end{equation*}
$$

where $f: \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function and $g:[0,2 \pi] \times \mathbb{R} \rightarrow \mathbb{R}$ are $2 \pi$ periodic in $t$ and $g$ satisfies Caratheodory condition; that is, $g(\cdot, x)$ is measurable on $[0,2 \pi]$ for each $x \in \mathbb{R}$ and $g(t, \cdot)$ is continuous on $\mathbb{R}$ for almost each $t \in[0,2 \pi]$. We assume moreover that for $r>0$ there exists $Y_{r} \in L_{2 \pi}^{2}$ such that $|g(t, y)| \leq Y_{r}(t)$ for a.e. $t \in[0,2 \pi]$ and $x \in[-r, r]$.

Theorem 3.2. Let $b<0$ and $d>0$. Suppose that $g$ is Caratheodory function satisfying the inequality

$$
\begin{gather*}
g(t, y) \geq 0, \quad|y| \leq r  \tag{3.2}\\
\lim _{|y| \rightarrow \infty} \sup \frac{g(t, y)}{b y} \leq \Gamma(t) \tag{3.3}
\end{gather*}
$$

uniformly a.e., $t \in[0,2 \pi]$ where $r>0$ is a constant and $\Gamma(t) \in L_{2 \pi}^{2}$ is such that

$$
\begin{equation*}
0<\Gamma(t)<1 \tag{3.4}
\end{equation*}
$$

Then for arbitrary continuous function $f$, the boundary-value problem 3.1 has at least one $2 \pi$-periodic solution.

Proof. Let $\delta>0$ be associated to the function $\Gamma$ by Theorem 2.2. Then by (3.2), (3.3) there exists a constant $R_{1}>0$ such that

$$
\begin{equation*}
0 \leq \frac{g(t, y)}{b y}<\Gamma(t)+\frac{\delta}{2} \tag{3.5}
\end{equation*}
$$

if $|y| \geq R_{1}$ for a. e., $t \in[0,2 \pi]$ and all $y \in \mathbb{R}$. Define $\bar{Y}:[0,2 \pi] \times \mathbb{R} \rightarrow \mathbb{R}$ by

$$
\bar{Y}= \begin{cases}y^{-1} g(t, y), & |y| \geq R_{1}  \tag{3.6}\\ R^{-1} g(t, R), & 0<y<R_{1} \\ -R_{1}^{-1} g\left(t,-R_{1}\right), & -R_{1}<y<0 \\ \Gamma(t), & y=0\end{cases}
$$

Then by 3.5, we have

$$
\begin{equation*}
0 \leq \bar{Y}(t, y)<\Gamma(t)+\frac{\delta}{2} \tag{3.7}
\end{equation*}
$$

for a. e. $t \in[0,2 \pi]$ for all $y \in \mathbb{R}$. Moreover the function $\bar{Y}(t, y)$ satisfies Caratheodory conditions and

$$
\tilde{g}(t, \dot{x}(t-\tau))=b^{-1} g(t, \dot{x}(t-\tau))-\bar{Y}(t, \dot{x}(t-\tau)) \dot{x}(t-\tau)
$$

is such that a. e. $t \in[0,2 \pi]$ and all $x \in \mathbb{R}$, we have

$$
\begin{equation*}
|\tilde{g}(t, \dot{x}(t-\tau))| \leq \alpha(t) \tag{3.8}
\end{equation*}
$$

for some $\alpha(t) \in L_{2 \pi}^{2}$. To prove that (3.1) has at least one periodic solution, it suffices to show that the possible solution of the family of equations

$$
\begin{align*}
& b^{-1}\left[x^{(i v)}+\lambda f(\ddot{x}) \dddot{x}\right]+\ddot{x}+(1-\lambda) \Gamma(t) \dot{x}(t-\tau)+\lambda Y(t, \dot{x}(t-\tau)) \\
& +b^{-1} d x+\lambda \tilde{g}(t, \dot{x}(t-\tau))+\bar{Y}(t, \dot{x}(t-\tau))=\lambda b^{-1} p(t) \tag{3.9}
\end{align*}
$$

are a-priori bounded in $W_{2 \pi}^{4,2}$ independently of $\lambda \in[0,1]$. By inequality (3.7) one has

$$
\begin{equation*}
0 \leq(1-\lambda) \Gamma(t)+\lambda \bar{Y}(t, \dot{x}(t-\tau)) \leq \Gamma(t)+\frac{\delta}{2} \tag{3.10}
\end{equation*}
$$

for a. e. $t \in[0,2 \pi]$ and all $x \in \mathbb{R}$. From Theorem 2.2, we can derive that for $\lambda=0$ equation 3.9 has only the trivial solution. Then using Lemma 3.1 and Cauchy Schwarz inequality we obtain

$$
\begin{aligned}
0= & \frac{1}{2 \pi} \int_{0}^{2 \pi} \ddot{x}\left\{b^{-1}\left[x^{(i v)}+f(\ddot{x}) \dddot{x}\right]+\ddot{x}+(1-\lambda) \Gamma(t) \dot{x}(t-\tau)\right. \\
& \left.+\lambda \bar{Y}(t, \dot{x}(t-\tau)) \dot{x}(t-\tau)+\lambda \tilde{g}(t, \dot{x}(t-\tau))+b^{-1} d x-\lambda p(t)\right\} d t \\
\geq & \frac{\delta}{2}|\dot{x}|_{H_{2 \pi}^{1}}^{2}-\left(|\alpha|_{2}+\left|b^{-1}\right||p|_{2}\right)|\dot{\tilde{x}}|_{2}+\left|b^{-1}\right| d|\dot{\tilde{x}}|_{2} \\
\geq & \frac{\delta}{2}|\dot{x}|_{H_{2 \pi}^{1}}^{2}-\beta|\dot{x}|_{H_{2 \pi}^{2}}-b^{-1}|\dddot{x}|_{2 \pi}^{2} \\
\geq & \frac{\delta}{2}|\dot{x}|_{H_{2 \pi}^{1}}^{2}-\beta|\dot{x}|_{H_{2 \pi}^{1}}
\end{aligned}
$$

for some $\beta>0$. Hence,

$$
\begin{equation*}
|\dot{x}|_{H_{2 \pi}^{1}} \leq \frac{2 \beta}{\delta}=c_{1} \tag{3.11}
\end{equation*}
$$

with $c_{1}>0$. This implies

$$
\begin{align*}
|\ddot{x}|_{2} & \leq c_{2}  \tag{3.12}\\
|\ddot{x}|_{\infty} & \leq c_{3} \tag{3.13}
\end{align*}
$$

where $c_{2}>0$ and $c_{3}>0$. Using Wirtinger's inequality in (3.12), we obtain

$$
\begin{equation*}
|\dot{x}|_{2} \leq c_{4} \tag{3.14}
\end{equation*}
$$

with $c_{4}>0$. Multiplying $\sqrt{3.9}$ by $-\ddot{x}(t)$ and integrating over [ $\left.0,2 \pi\right]$, we obtain

$$
|\dddot{x}|_{2}^{2} \leq\left.|\ddot{x}|_{2}^{2}\left|1+\frac{\delta}{2}\right| \ddot{x}\right|_{2}+|\alpha|_{2}+d|\dot{x}|_{2}+|p|_{2}|\ddot{x}|_{2}
$$

Applying Wirtingers inequality we obtain

$$
\begin{equation*}
|\dddot{x}|_{2}^{2} \leq c_{5} \tag{3.15}
\end{equation*}
$$

with $c_{5}>0$ and hence

$$
|\ddot{x}|_{\infty} \leq c_{6}
$$

with $c_{6}>0$. We multiply 3.9 by $x^{(i v)}(t)$ and integrate over $[0,2 \pi]$ to get

$$
\begin{aligned}
-b^{-1}\left|x^{(i v)}\right|_{2}^{2} \leq & |f(\ddot{x})|_{\infty}|\ddot{x}|_{2}\left|x^{(i v)}\right|_{2}\left|b^{-1}\right|+|\ddot{x}|_{2}\left|x^{(i v)}\right|_{2}+\left|1+\frac{\delta}{2}\right||\dot{x}|_{2}\left|x^{i(i v)}\right|_{2} \\
& +\left|b^{-1}\right||d||\ddot{x}|_{2}+|\alpha|_{2}\left|x^{(i v)}\right|_{2}+|p|_{2}\left|x^{i(i v)}\right|_{2} \\
\leq & |f(\ddot{x})|_{\infty}|\ddot{x}|_{2}\left|x^{(i v)}\right|_{2}\left|b^{-1}\right|+|\ddot{x}|_{2}\left|x^{(i v)}\right|_{2} \\
& +\left|1+\frac{\delta}{2}\right||\dot{x}|_{2}\left|x^{(i v)}\right|_{2}\left|b^{-1}\right| d\left|x^{(i v)}\right|_{2}+|\alpha|_{2}\left|x^{(i v)}\right|_{2}+|p|_{2}\left|x^{i(i v)}\right|_{2}\left|b^{-1}\right|,
\end{aligned}
$$

where we used the Wirtinger's inequality. Thus

$$
\begin{equation*}
\left|x^{(i v)}\right|_{2} \leq c_{7} \tag{3.16}
\end{equation*}
$$

with $c_{7}>0$. Finally multiplying (3.9) by $x(t)$ and integrating over $[0,2 \pi]$ we obtain

$$
\begin{equation*}
|x|_{2} \leq c_{8} \tag{3.17}
\end{equation*}
$$

with $c_{8}>0$. Hence,

$$
|x|_{W_{2 \pi}^{4,2}}=|x|_{2}+|\dot{x}|_{2}+|\ddot{x}|_{2}+|\dddot{x}|_{2}+\left|x^{(i v)}\right|_{2} \leq c_{8}+c_{4}+c_{2}+c_{5}+c_{7}=C_{9}
$$

Taking $R>C_{9}>0$, the required a priori bound in $W_{2 \pi}^{4,2}$ is obtained independently of $x$ and $\lambda$.

## 4. Uniqueness Result

For $f(x)=a, a$ constant, in 1.1), we have the following uniqueness result.
Theorem 4.1. Let $a, b, d$ be constants with $b<0$ and $d>0$. Suppose $g$ is $a$ Caratheodory function satisfying

$$
\begin{equation*}
0<\frac{g\left(t, \dot{x}_{1}\right)-g\left(t, \dot{x}_{2}\right)}{b\left(\dot{x}_{1}-\dot{x}_{2}\right)}<\Gamma(t) \tag{4.1}
\end{equation*}
$$

for all $x_{1}, x_{2} \in \mathbb{R}$ with $x_{1} \neq x_{2}$ where $\Gamma(t) \in L_{2 \pi}^{2}$ is such that $0<\Gamma(t)<1$. Then for all arbitrary constant a and every $\tau \in[0,2 \pi)$ the boundary-value problem

$$
\begin{gather*}
x^{(i v)}(t)+a \dddot{x}+b \ddot{x}+g(t, \dot{x}(t-\tau))+d x=p(t) \\
x(0)=x(2 \pi), \dot{x}(0)=\dot{x}(2 \pi), \ddot{x}(0)=\ddot{x}(2 \pi), \dddot{x}(0)=\dddot{x}(2 \pi), \tag{4.2}
\end{gather*}
$$

has at most one solution.
Proof. Let $x_{1}, x_{2}$ be any two solutions of (4.2). Set $x=x_{1}-x_{2}$. Then $x$ satisfies the boundary value problem

$$
\begin{gathered}
b^{-1} x^{(i v)}(t)+a \dddot{x}+\Gamma(t) \dot{x}(t-\tau)+b^{-1} d x=0 \\
x(0)=x(2 \pi), \quad \dot{x}(0)=\dot{x}(2 \pi), \quad \ddot{x}(0)=\ddot{x}(2 \pi), \quad \dddot{x}(0)=\dddot{x}(2 \pi),
\end{gathered}
$$

where the function $\Gamma(t) \in L_{2 \pi}^{2}$ is defined by

$$
\Gamma(t)= \begin{cases}\frac{g\left(t, \dot{x}_{1}(t-\tau)\right)-g\left(t, \dot{x}_{2}(t-\tau)\right)}{\dot{x}(t)} & \text { if } \ddot{x}(t) \neq 0 \\ \frac{1}{2} & \text { if } \ddot{x}(t)=0\end{cases}
$$

if $\dot{x}(t)$ on every subset of $[0,2 \pi]$ of positive measure, then $x$ is constant Since $d \neq 0$ we must have $x=0$ and hence $x_{1}=x_{2}$ a.e. Suppose on the other hand that
$\dot{x}(t) \neq 0$ on a certain subset of $[0,2 \pi]$ of positive measure, then using the arguments of Theorem 2.2 we obtain that $x=0$ and hence $x_{1}=x_{2}$ a .e.

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