

**POSITIVE NONDECREASING SOLUTIONS FOR A
MULTI-TERM FRACTIONAL-ORDER FUNCTIONAL
DIFFERENTIAL EQUATION WITH INTEGRAL CONDITIONS**

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ABSTRACT. In this article, we prove the existence of positive nondecreasing solutions for a multi-term fractional-order functional differential equations. We consider Cauchy boundary problems with: nonlocal conditions, two-point boundary conditions, integral conditions, and deviated arguments.

1. INTRODUCTION

Problems with non-local conditions have been extensively studied by several authors in the previous two decades; see for example [1]-[6], [9]-[17] and references therein. In this work we study the existence of nondecreasing solutions for the fractional differential equation

$$x'(t) = f(t, D^{\alpha_1}x(m_1(t)), D^{\alpha_2}x(m_2(t)), \dots, D^{\alpha_n}x(m_n(t))), \quad \alpha_i \in (0, 1), \quad (1.1)$$

a.e. $t \in (0, 1)$, with the nonlocal condition

$$\sum_{k=1}^m a_k x(\tau_k) = \beta \sum_{j=1}^p b_j x(\eta_j), \quad (1.2)$$

where $a_k, b_j > 0$, $\tau_k \in (a, c)$, $\eta_j \in (d, b)$, $0 < a < c \leq d < b < 1$, $\sum_{k=1}^m a_k \neq \beta \sum_{j=1}^p b_j$ and β is parameter.

As applications, we prove the existence of at least one nondecreasing solution for the Cauchy problem of (1.1) with the nonlocal integral condition

$$\int_a^c x(s) d\phi(s) = \beta \int_d^b x(s) d\psi(s), \quad 0 < a < c \leq d < b < 1, \quad (1.3)$$

where ϕ and ψ are nondecreasing functions. Also we prove the existence of at least one positive nondecreasing solution for the Cauchy problems of (1.1) with the nonlocal condition

$$\sum_{k=1}^m a_k x(\tau_k) = 0, \quad \tau_k \in (a, c) \subset (0, 1), \quad (1.4)$$

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and with the integral condition

$$\int_a^c x(s)d\phi(s) = 0, (a, c) \subset (0, 1). \quad (1.5)$$

As another applicatin, we problems with deviated arguments $m_i(t) \leq t$, $i = 1, 2, \dots, n$).

2. PRELIMINARIES

Let $L^1 = L^1(I)$ denote the class of Lebesgue integrable functions on the interval $I = [0, 1]$ and $\Gamma(\cdot)$ denote the usual gamma function.

Definition 2.1. The fractional-order integral of the function $f \in L^1[a, b]$, of order $\beta > 0$, is defined by (see [19])

$$I_a^\beta f(t) = \int_a^t \frac{(t-s)^{\beta-1}}{\Gamma(\beta)} f(s) ds.$$

The Caputo fractional-order derivative of $f(t)$ of order $\alpha \in (0, 1]$ is defined as (see [18, 19])

$$D_a^\alpha f(t) = I_a^{1-\alpha} \frac{d}{dt} f(t) = \int_a^t \frac{(t-s)^{-\alpha}}{\Gamma(1-\alpha)} \frac{d}{ds} f(s) ds.$$

Theorem 2.2 (Schauder fixed point theorem [7]). *Let E be a Banach space and Q be a convex subset of E , and $T : Q \rightarrow Q$ is compact, continuous map, Then T has at least one fixed point in Q .*

Theorem 2.3 (Kolmogorov compactness criterion [8]). *Let $\Omega \subseteq L^p[0, 1]$, $1 \leq p < \infty$. If*

- (i) Ω is bounded in $L^p[0, 1]$, and
- (ii) $u_h \rightarrow u$ as $h \rightarrow 0$ uniformly with respect to $u \in \Omega$,

then Ω is relatively compact in $L^p[0, 1]$, where

$$u_h(t) = \frac{1}{h} \int_t^{t+h} u(s) ds.$$

3. MAIN RESULTS

We consider firstly the fractional-order functional integral equation

$$y(t) = f(t, I^{1-\alpha_1} m_1'(t)y(m_1(t)), \dots, I^{1-\alpha_n} m_n'(t)y(m_n(t))). \quad (3.1)$$

A function y is called a solution of the fractional-order functional integral equation (3.1) if $y \in L^1[0, 1]$ and satisfies (3.1).

In this article, we use the following assumption:

- (i) $f : [0, 1] \times R_+^n \rightarrow R_+$ is a function with the following properties:
 - (a) for each $t \in [0, 1]$, $f(t, \cdot)$ is continuous,
 - (b) for each $x \in R_+^n$, $f(\cdot, x)$ is measurable;
- (ii) there exists an integral function $a \in L^1[0, 1]$ and constants $q_i > 0$, $i = 1, 2$, such that

$$|f(t, x)| \leq a(t) + \sum_{i=1}^n q_i |x_i|, \text{ for each } t \in [0, 1], x \in R_n;$$

- (iii) $m_i : [0, 1] \rightarrow [0, 1]$ are absolutely continuous functions;

(iv)

$$\sum_{i=1}^n \frac{q_i}{\Gamma(2-\alpha_i)} < 1.$$

Theorem 3.1. *Assume (i)-(iv). Then (3.1) has at least one positive solution $y \in L^1[0, 1]$.*

Proof. Define the operator T associated with (3.1) by

$$Ty(t) = f(t, I^{1-\alpha_1} m_1'(t)y(m_1(t)), \dots, I^{1-\alpha_n} m_n'(t)y(m_n(t))).$$

Let $B_r^+ = \{y \in R^+ : \|y\|_{L^1} \leq r\} \subset L^1$,

$$r = \frac{\|a\|}{1 - \sum_{i=1}^n \frac{q_i}{\Gamma(2-\alpha_i)}}.$$

Let y be an arbitrary element in B_r^+ . Then from the assumptions (i) and (ii), we obtain

$$\begin{aligned} \|Ty\|_{L^1} &= \int_0^1 |Ty(t)| dt \\ &= \int_0^1 |f(t, I^{1-\alpha_1} m_1'(t)y(m_1(t)), \dots, I^{1-\alpha_n} m_n'(t)y(m_n(t)))| dt \\ &\leq \int_0^1 |a(t)| dt + \sum_{i=1}^n q_i \int_0^1 \int_0^t \frac{(t-s)^{-\alpha_i}}{\Gamma(1-\alpha_i)} |y(m_i(s))| dm_i(s) dt \\ &\leq \|a\|_{L^1} + \sum_{i=1}^n q_i \int_0^1 \left(\int_s^1 \frac{(t-s)^{-\alpha_i}}{\Gamma(1-\alpha_i)} dt \right) |y(m_i(s))| dm_i(s) \\ &\leq \|a\|_{L^1} + \sum_{i=1}^n q_i \int_{m_i(0)}^{m_i(1)} \frac{1}{\Gamma(2-\alpha_i)} |y(m_i(s))| dm_i(s) \\ &\leq \|a\|_{L^1} + \sum_{i=1}^n q_i \int_0^1 \frac{1}{\Gamma(2-\alpha_i)} |y(u)| du \\ &\leq \|a\|_{L^1} + \sum_{i=1}^n \frac{q_i}{\Gamma(2-\alpha_i)} \|y\|_{L^1} \leq r, \end{aligned}$$

which implies that the operator T maps B_r^+ into itself.

Assumption (i) implies that T is continuous. Now, we will show that T is compact. Let Ω be a bounded subset of B_r^+ . Then $T(\Omega)$ is bounded in $L^1[0, 1]$; i.e., condition (i) of Theorem 2.3 is satisfied. It remains to show that $(Ty)_h \rightarrow Ty$ in $L^1[0, 1]$ as $h \rightarrow 0$, uniformly with respect to $Ty \in T\Omega$. Now

$$\begin{aligned} &\|(Ty)_h - Ty\|_{L^1} \\ &= \int_0^1 |(Ty)_h(t) - (Ty)(t)| dt \\ &= \int_0^1 \left| \frac{1}{h} \int_t^{t+h} (Ty)(s) ds - (Ty)(t) \right| dt \\ &= \int_0^1 \left(\frac{1}{h} \int_t^{t+h} |(Ty)(s) - (Ty)(t)| ds \right) dt \end{aligned}$$

$$\leq \int_0^1 \frac{1}{h} \int_t^{t+h} \left| f(s, I^{1-\alpha_1} m'_1(s)y(m_1(s)), \dots, I^{1-\alpha_n} m'_n(s)y(m_n(s))) \right. \\ \left. - f(t, I^{1-\alpha_1} m'_1(t)y(m_1(t)), \dots, I^{1-\alpha_n} m'_n(t)y(m_n(t))) \right| ds dt.$$

Now, by assumption (ii), $y \in \Omega$ implies $f \in L^1[0, 1]$; then

$$\frac{1}{h} \int_t^{t+h} |f(s, I^{1-\alpha_1} m'_1(s)y(m_1(s)), \dots) - f(t, I^{1-\alpha_1} m'_1(t)y(m_1(t)), \dots)| ds dt \rightarrow 0.$$

Therefore, by Theorem 2.3, $T(\Omega)$ is relatively compact; that is, T is compact, then the operator T has a fixed point in B_r^+ , which proves the existence of positive solution $y \in B_r^+ \subset L^1[0, 1]$ of equation (3.1). \square

Let $AC[0, 1]$ be the class of absolutely continuous functions defined on $[0, 1]$. For the existence of solution for the nonlocal problem (1.1)-(1.2), we have the following result.

Theorem 3.2. *Under the assumptions of Theorem 3.1, problem (1.1)-(1.2) has at least one solution $x \in AC[0, 1]$.*

Proof. Let $y(t) = x'(t)$, then

$$x(t) = x(0) + Iy(t), \quad (3.2)$$

$$x'(m_i(t)) = m'_i(t)y(m_i(t)), \quad (3.3)$$

and y is the solution of the fractional-order functional integral equation (3.1). Let $t = \tau_k$ in equation (3.2). We obtain

$$x(\tau_k) = \int_0^{\tau_k} y(s) ds + x(0), \\ \sum_{k=1}^m a_k x(\tau_k) = \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds + x(0) \sum_{k=1}^m a_k.$$

Let $t = \eta_j$ in equation (3.2). We obtain

$$x(\eta_j) = \int_0^{\eta_j} y(s) ds + x(0), \\ \sum_{j=1}^p b_j x(\eta_j) = \sum_{j=1}^p b_j \int_0^{\eta_j} y(s) ds + x(0) \sum_{j=1}^p b_j.$$

From (1.2), we obtain

$$\sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds + x(0) \sum_{k=1}^m a_k = \beta \sum_{j=1}^p b_j \int_0^{\eta_j} y(s) ds + x(0) \beta \sum_{j=1}^p b_j.$$

Then

$$x(0) = A \left(\sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds - \beta \sum_{j=1}^p b_j \int_0^{\eta_j} y(s) ds \right), \\ A = \left(\beta \sum_{j=1}^p b_j - \sum_{k=1}^m a_k \right)^{-1},$$

and

$$x(t) = A \left(\sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds - \beta \sum_{j=1}^p b_j \int_0^{\eta_j} y(s) ds \right) + \int_0^t y(s) ds, \quad (3.4)$$

which, by Theorem 3.1, has at least one solution $x \in AC(0, 1)$.

Now, from equation (3.4), we have

$$x(0) = \lim_{t \rightarrow 0^+} x(t) = A \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds - A\beta \sum_{j=1}^p b_j \int_0^{\eta_j} y(s) ds$$

and

$$x(1) = \lim_{t \rightarrow 1^-} x(t) = A \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds - A\beta \sum_{j=1}^p b_j \int_0^{\eta_j} y(s) ds + \int_0^1 y(s) ds,$$

from which we deduce that (3.4) has at least one solution $x \in AC[0, 1]$.

Next we differentiate (3.4), to obtain

$$\begin{aligned} \frac{dx}{dt} &= y(t), \\ D^{\alpha_i} x(m_i(t)) &= I^{1-\alpha_i} \frac{d}{dt} x(m_i(t)) = I^{1-\alpha_i} m'_i(t) y(m_i(t)), \\ x'(t) &= f(t, D^{\alpha_1} x(t), D^{\alpha_2} x(t), \dots, D^{\alpha_n} x(t)). \end{aligned}$$

By direct calculation, we can prove that (3.4) satisfies the nonlocal condition (1.2). This completes the proof. \square

From the above theorem we have the following corollaries.

Corollary 3.3. *Under the assumptions of Theorem 3.1, the solution of (1.1)-(1.2) is nondecreasing.*

Proof. Let $t_1, t_2 \in (0, 1)$ and $t_1 < t_2$, then from (3.4) we have

$$\begin{aligned} x(t_1) &= A \left(\sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds - \beta \sum_{j=1}^p b_j \int_0^{\eta_j} y(s) ds \right) + \int_0^{t_1} y(s) ds \\ &\leq A \left(\sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds - \beta \sum_{j=1}^p b_j \int_0^{\eta_j} y(s) ds \right) + \int_0^{t_2} y(s) ds \\ &= x(t_2) \end{aligned}$$

and the solution of the nonlocal problem (1.1)-(1.2) is nondecreasing. \square

Corollary 3.4. *Under the assumptions of Theorem 3.1, problem (1.1) with the nonlocal condition*

$$\sum_{k=1}^m a_k x(\tau_k) = 0, \quad \tau_k \in (a, c) \subset (0, 1). \quad (3.5)$$

has at least one nondecreasing solution $x \in AC[0, 1]$, represented by

$$x(t) = \int_0^t y(s) ds - A^* \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds, \quad A^* = \left(\sum_{k=1}^m a_k \right)^{-1}. \quad (3.6)$$

This solution is positive in the interval $[c, 1]$.

Proof. Letting $\beta = 0$ in (1.2) and (3.4), then from Theorem 3.2 we deduce that the nonlocal problem (1.1) and (3.5) has at least one nondecreasing solution given by (3.6). Let $t \in [c, 1]$, then $\tau_k < t$ and

$$A^* \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds \leq A^* \sum_{k=1}^m a_k \int_0^t y(s) ds = \int_0^t y(s) ds,$$

which proves that the solution (3.6) is positive in $[c, 1]$. \square

Corollary 3.5. *Under the assumptions of Theorem 3.1, the two point problem*

$$\begin{aligned} x'(t) &= f(t, D^{\alpha_1} x(m_1(t)), D^{\alpha_2} x(m_2(t)), \dots, D^{\alpha_n} x(m_n(t))), \alpha_i \in (0, 1), \\ &\text{a.e. } t \in (0, 1), \\ x(\tau) &= \beta x(\eta), \quad \tau, \eta \in (a, c) \subset (0, 1). \end{aligned}$$

has at least one nondecreasing solution $x \in AC[0, 1]$ represented by

$$x(t) = A \left(\int_0^\tau y(s) ds - \beta \int_0^\eta y(s) ds \right) + \int_0^t y(s) ds, \quad A = (\beta - 1)^{-1}. \quad (3.7)$$

This solution is positive in the interval $[c, 1]$.

4. INTEGRAL CONDITION

Let $x \in AC[0, 1]$ be the solution of the nonlocal problem (1.1)-(1.2). Let $a_k = \phi(\tau_k) - \phi(\tau_{k-1})$, $t_k \in (\tau_{k-1}, \tau_k)$, $a = \tau_0 < \tau_1 < \tau_2, \dots < \tau_m = c$ and $b_j = \psi(\eta_j) - \psi(\eta_{j-1})$, $t_j \in (\eta_{j-1}, \eta_j)$, $d = \eta_0 < \eta_1 < \eta_2, \dots < \eta_p = b$ then the nonlocal condition (1.2) will be

$$\sum_{k=1}^m (\phi(\tau_k) - \phi(\tau_{k-1})) x(t_k) = \beta \sum_{j=1}^p (\psi(\eta_j) - \psi(\eta_{j-1})) x(t_j).$$

From the continuity of the solution x of (1.1)-(1.2) we can obtain

$$\lim_{m \rightarrow \infty} \sum_{k=1}^m (\phi(\tau_k) - \phi(\tau_{k-1})) x(t_k) = \beta \lim_{p \rightarrow \infty} \sum_{j=1}^p (\psi(\eta_j) - \psi(\eta_{j-1})) x(t_j).$$

and the nonlocal condition (1.2) transformed to the integral condition

$$\int_a^c x(s) d\phi(s) = \beta \int_d^b x(s) d\psi(s). \quad (4.1)$$

Also from the continuity of the function $Iy(t)$, where y is the solution of (3.1), we deduce that the solution (3.4) will be

$$\begin{aligned} x(t) &= (\beta(b-d) - (c-a))^{-1} \left(\int_a^c \int_0^s y(\theta) d\phi(\theta) ds - \beta \int_d^b \int_0^s y(\theta) d\psi(\theta) ds \right) \\ &\quad + \int_0^t y(s) ds. \end{aligned}$$

Theorem 4.1. *Under the assumptions of Theorem 3.2, there exists at least one nondecreasing solution $x \in AC[0, 1]$ of the nonlocal problem with integral condition,*

$$\begin{aligned} x'(t) &= f(t, D^{\alpha_1} x(m_1(t)), D^{\alpha_2} x(m_2(t)), \dots, D^{\alpha_n} x(m_n(t))), \alpha_i \in (0, 1), \\ &\text{a.e. } t \in (0, 1), \end{aligned}$$

$$\int_a^c x(s) ds = \beta \int_d^b y(s) ds, \quad \beta(b-d) \neq (c-a).$$

Letting $\beta = 0$ in (4.1), then we can easily prove the following corollary.

Corollary 4.2. *Under the assumptions of Theorem 3.2, the nonlocal problem*

$$x'(t) = f(t, D^{\alpha_1}x(m_1(t)), D^{\alpha_2}x(m_2(t)), \dots, D^{\alpha_n}x(m_n(t))),$$

$$\alpha_i \in (0, 1), \text{ a.e. } t \in (0, 1),$$

$$\int_a^c x(s) ds = 0, \quad (a, c) \subset (0, 1)$$

has at least one nondecreasing solution $x \in AC[0, 1]$ represented by

$$x(t) = \int_0^t y(s) ds - (c-a)^{-1} \int_a^c \int_0^s y(\theta) d\theta ds.$$

This solution is positive in the interval $[c, 1]$.

5. EQUATIONS WITH DEVIATED ARGUMENTS

As a first example, let $m_i(t) = \beta_i t$, $\beta_i \in (0, 1)$, then $m_i : [0, 1] \rightarrow [0, 1]$ is absolutely continuous deviated functions and all our results here can be applied to the multi-term fractional-order functional differential equation with deviated arguments

$$x'(t) = f(t, D^{\alpha_1}x(\beta_1 t), D^{\alpha_2}x(\beta_2 t), \dots, D^{\alpha_n}x(\beta_n t)), \alpha_i \in (0, 1), \text{ a.e. } t \in (0, 1). \quad (5.1)$$

As a second example, let $m_i(t) = t^{\gamma_i}$, $\gamma_i \geq 1$, then $m_i : [0, 1] \rightarrow [0, 1]$ is absolutely continuous deviated functions and all our results here can be applied to the multi-term fractional-order functional differential equation with deviated arguments

$$x'(t) = f(t, D^{\alpha_1}x(t^{\gamma_1}), D^{\alpha_2}x(t^{\gamma_2}), \dots, D^{\alpha_n}x(t^{\gamma_n})), \alpha_i \in (0, 1), \text{ a.e. } t \in (0, 1). \quad (5.2)$$

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