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# EXISTENCE OF CONTINUOUS POSITIVE SOLUTIONS FOR SOME NONLINEAR POLYHARMONIC SYSTEMS OUTSIDE THE UNIT BALL 

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#### Abstract

We study the existence of continuous positive solutions of the mpolyharmonic nonlinear elliptic system $$
\begin{gathered} (-\Delta)^{m} u+\lambda p(x) g(v)=0 \\ (-\Delta)^{m} v+\mu q(x) f(u)=0 \end{gathered}
$$ in the complement of the unit closed ball in $\mathbb{R}^{n}(n>2 m$ and $m \geq 1)$. Here the constants $\lambda, \mu$ are nonnegative, the functions $f, g$ are nonnegative, continuous and monotone. We prove two existence results for the above system subject to some boundary conditions, where the nonnegative functions $p, q$ satisfy some appropriate conditions related to a Kato class of functions.


## 1. Introduction

In this article, we discuss the existence of positive continuous solutions (in the sense of distributions) for the $m$-polyharmonic nonlinear elliptic system

$$
\begin{gather*}
(-\Delta)^{m} u+\lambda p(x) g(v)=0, \quad x \in D \\
(-\Delta)^{m} v+\mu q(x) f(u)=0, \quad x \in D \\
\lim _{x \rightarrow \xi \in \partial D} \frac{u(x)}{\left(|x|^{2}-1\right)^{m-1}}=a \varphi(\xi), \quad \lim _{x \rightarrow \xi \in \partial D} \frac{v(x)}{\left(|x|^{2}-1\right)^{m-1}}=b \psi(\xi),  \tag{1.1}\\
\lim _{|x| \rightarrow \infty} \frac{u(x)}{\left(|x|^{2}-1\right)^{m-1}}=\alpha, \quad \lim _{|x| \rightarrow \infty} \frac{v(x)}{\left(|x|^{2}-1\right)^{m-1}}=\beta
\end{gather*}
$$

where $D$ is the complementary of the unit ball in $\mathbb{R}^{n}(n>2 m)$ and $m$ is a positive integer. The constants $\lambda, \mu$ are nonnegative, $f, g:(0, \infty) \rightarrow[0, \infty)$ are monotone and continuous and $p, q: D \rightarrow[0, \infty)$ are measurable functions. Also we fix two nontrivial nonnegative continuous functions $\varphi$ and $\psi$ on $\partial D$ and the constants $a, b, \alpha, \beta$ are nonnegative and satisfy $a+\alpha>0, b+\beta>0$.

Since our tools are based on potential theory approach, we denote by $G_{m, n}^{B}$ the Green function of $(-\Delta)^{m}$ on the unit ball $B$ in $\mathbb{R}^{n}(n \geq 2)$ with Dirichlet boundary conditions $\left(\frac{\partial}{\partial \nu}\right)^{j} u=0,0 \leq j \leq m-1$ and where $\frac{\partial}{\partial \nu}$ is the outward normal derivative.

[^0]Boggio [5] obtained an explicit expression for $G_{m, n}^{B}$ given by

$$
\begin{equation*}
G_{m, n}^{B}(x, y)=k_{m, n}|x-y|^{2 m-n} \int_{1}^{\frac{[x, y]}{[x-y \mid}} \frac{\left(r^{2}-1\right)^{m-1}}{r^{n-1}} d r \tag{1.2}
\end{equation*}
$$

where $k_{m, n}$ is a positive constant and $[x, y]^{2}=|x-y|^{2}+\left(1-|x|^{2}\right)\left(1-|y|^{2}\right)$, for $x, y \in B$.

It is obvious that the positivity of $G_{m, n}^{B}$ holds in $B$ but this does not hold in an arbitrary bounded domain (see for example [8]). For $m=1$, we do not have this restriction. Putting

$$
[x, y]^{2}=|x-y|^{2}+\left(|x|^{2}-1\right)\left(|y|^{2}-1\right)
$$

for $x, y \in D$ and denote by $G_{m, n}^{D}$ the Green function of $(-\Delta)^{m}$ in $D$ with Dirichlet boundary conditions $\left(\frac{\partial}{\partial \nu}\right)^{j} u=0,0 \leq j \leq m-1$, then $G_{m, n}^{D}$ has the same expression defined by (1.2). That is,

$$
G_{m, n}^{D}(x, y)=k_{m, n}|x-y|^{2 m-n} \int_{1}^{\frac{[x, y]}{|x-y|}} \frac{\left(r^{2}-1\right)^{m-1}}{r^{n-1}} d r, \quad \text { for } x, y \in D
$$

In [4], the authors proved some estimates for $G_{m, n}^{D}$. In particular, they showed that there exists $C_{0}>0$ such that for each $x, y, z \in D$, we have

$$
\frac{G_{m, n}^{D}(x, z) G_{m, n}^{D}(z, y)}{G_{m, n}^{D}(x, y)} \leq C_{0}\left[\left(\frac{\rho(z)}{\rho(x)}\right)^{m} G_{m, n}^{D}(x, z)+\left(\frac{\rho(z)}{\rho(y)}\right)^{m} G_{m, n}^{D}(y, z)\right]
$$

where throughout this paper, $\rho(x)=1-\frac{1}{|x|}$, for all $x \in D$. This form is called the $3 G$-inequality and has been exploited to introduce the polyharmonic Kato class $K_{m, n}^{\infty}(D)$ which is defined as follows

Definition 1.1 ([4). A Borel measurable function $q$ in $D$ belongs to the Kato class $K_{m, n}^{\infty}(D)$ if $q$ satisfies

$$
\begin{aligned}
& \lim _{\alpha \rightarrow 0}\left(\sup _{x \in D} \int_{D \cap B(x, \alpha)}\left(\frac{\rho(y)}{\rho(x)}\right)^{m} G_{m, n}^{D}(x, y)|q(y)| d y\right)=0 \\
& \lim _{M \rightarrow \infty}\left(\sup _{x \in D} \int_{(|y| \geq M)}\left(\frac{\rho(y)}{\rho(x)}\right)^{m} G_{m, n}^{D}(x, y)|q(y)| d y\right)=0
\end{aligned}
$$

This class is well studied when $m=1$ in [3]. As a typical example of functions belonging to the class $K_{m, n}^{\infty}(D)$, we quote an example from [4]: Let $\gamma, \nu \in \mathbb{R}$ and $q$ be the function defined in $D$ by $q(x)=\frac{1}{|y|^{\nu-\gamma}(|y|-1)^{\gamma}}$. Then

$$
q \in K_{m, n}^{\infty}(D) \Leftrightarrow \gamma<2 m<\nu
$$

Our main purpose in this paper is to study problem (1.1) when $p$ and $q$ satisfy an appropriate condition related to the Kato class $K_{m, n}^{\infty}(D)$ and to investigate the existence and the asymptotic behavior of such positive solutions. For this aim we shall refer to the bounded continuous solution $H_{D} \varphi$ of the Dirichlet problem (see [1])

$$
\begin{gathered}
\Delta u=0 \quad \text { in } D \\
\lim _{x \rightarrow \xi \in \partial D} u(x)=\varphi(\xi), \quad \lim _{|x| \rightarrow \infty} u(x)=0
\end{gathered}
$$

where $\varphi$ is a nonnegative nontrivial continuous function on $\partial D$. Also, we refer to the potential of a measurable nonnegative function $f$, defined in $D$ by

$$
V_{m, n} f(x)=\int_{D} G_{m, n}^{D}(x, y) f(y) d y
$$

The outline of our article is as follows. In Section 2, we recapitulate some properties of functions belonging to $K_{m, n}^{\infty}(D)$ developed in 4 and adopted to our interest. In Section 3, we aim at proving a first existence result for 1.1). In fact, let $a, b, \alpha, \beta$ be nonnegative real numbers with $a+\alpha>0, b+\beta>0$ and $\varphi, \psi$ are nontrivial nonnegative continuous functions on $\partial D$. Let $h$ be the harmonic function defined in $D$ by $h(x)=1-\frac{1}{|x|^{n-2}}$. Let $\theta$ and $\omega$ be the functions defined in $D$ by

$$
\begin{aligned}
& \theta(x)=\gamma(x)\left(\alpha h(x)+a H_{D} \varphi(x)\right), \\
& \omega(x)=\gamma(x)\left(\beta h(x)+b H_{D} \psi(x)\right),
\end{aligned}
$$

where $\gamma(x)=\left(|x|^{2}-1\right)^{m-1}$.
The functions $f, g, p$ and $q$ are required to satisfy the following hypotheses.
(H1) $f, g:(0, \infty) \rightarrow[0, \infty)$ are nondecreasing and continuous;
(H2)

$$
\begin{aligned}
\lambda_{0} & :=\inf _{x \in D} \frac{\theta(x)}{V_{m, n}(p g(\omega))(x)}>0 \\
\mu_{0} & :=\inf _{x \in D} \frac{\omega(x)}{V_{m, n}(q f(\theta))(x)}>0
\end{aligned}
$$

(H3) The functions $p$ and $q$ are measurable nonnegative and satisfy

$$
x \rightarrow \tilde{p}(x)=\frac{p(x) g(\omega(x))}{\gamma(x)} \quad \text { and } \quad x \rightarrow \tilde{q}(x)=\frac{q(x) f(\theta(x))}{\gamma(x)}
$$

belong to the Kato class $K_{m, n}^{\infty}(D)$.
Then we prove the following result.
Theorem 1.2. Assume (H1)-(H3). Then for each $\lambda \in\left[0, \lambda_{0}\right)$ and each $\mu \in\left[0, \mu_{0}\right)$, problem (1.1) has a positive continuous solution $(u, v)$ that for each $x \in D$ satisfies

$$
\begin{aligned}
\left(1-\frac{\lambda}{\lambda_{0}}\right) \theta(x) & \leq u(x) \leq \theta(x) \\
\left(1-\frac{\mu}{\mu_{0}}\right) \omega(x) & \leq v(x) \leq \omega(x)
\end{aligned}
$$

Next, we establish a second existence result for problem (1.1) where $a=b=\lambda=$ $\mu=1$. Namely, we study the system

$$
\begin{gather*}
(-\Delta)^{m} u+p(x) g(v)=0, \quad x \in D \quad \text { (in the sense of distributions), } \\
(-\Delta)^{m} v+q(x) f(u)=0, \quad x \in D \\
\lim _{x \rightarrow \xi \in \partial D} \frac{u(x)}{\left(|x|^{2}-1\right)^{m-1}}=\varphi(\xi), \quad \lim _{x \rightarrow \xi \in \partial D} \frac{v(x)}{\left(|x|^{2}-1\right)^{m-1}}=\psi(\xi),  \tag{1.3}\\
\lim _{|x| \rightarrow \infty} \frac{u(x)}{\left(|x|^{2}-1\right)^{m-1}}=\alpha, \quad \lim _{|x| \rightarrow \infty} \frac{v(x)}{\left(|x|^{2}-1\right)^{m-1}}=\beta .
\end{gather*}
$$

To study this problem, we fix a positive continuous function $\phi$ on $\partial D$. We put $\rho_{0}=\gamma h_{0}$, where $h_{0}=H_{D} \phi$ and we assume the following hypotheses:
(H4) The functions $f, g:(0, \infty) \rightarrow[0, \infty)$ are nonincreasing and continuous;
(H5) The functions $p_{1}:=p \frac{g\left(\rho_{0}\right)}{\rho_{0}}$ and $q_{1}:=q \frac{f\left(\rho_{0}\right)}{\rho_{0}}$ belong to the Kato class $K_{m, n}^{\infty}(D)$.
Here, we mention that the method used to prove Theorem 1.3 stated below is different from that in Theorem 1.2. In fact, with loss of $\lambda$ and $\mu$, the boundary $\partial D$ will play a capital role to construct a positive and continuous solution for 1.3 by means of a fixed point argument.

Our second existence result is the following.
Theorem 1.3. Assume (H4)-(H5). Then there exists a constant $c>1$ such that if $\varphi \geq c \phi$ and $\psi \geq c \phi$ on $\partial D$, then problem 1.3 has a positive continuous solution $(u, v)$ that for each $x \in D$ satisfies

$$
\begin{aligned}
& \left(|x|^{2}-1\right)^{m-1}\left(\alpha h(x)+h_{0}(x)\right) \leq u(x) \leq\left(|x|^{2}-1\right)^{m-1}\left(\alpha h(x)+H_{D} \varphi(x)\right) \\
& \left(|x|^{2}-1\right)^{m-1}\left(\beta h(x)+h_{0}(x)\right) \leq v(x) \leq\left(|x|^{2}-1\right)^{m-1}\left(\beta h(x)+H_{D} \psi(x)\right)
\end{aligned}
$$

This result is a follow up to the one obtained by Athreya [2].
For $m=1$, the existence of solutions for nonlinear elliptic systems has been extensively studied for both bounded and unbounded $C^{1,1}$-domains in $\mathbb{R}^{n}(n \geq 3)$ (see for example [6, 7, 9, 10, 11, 12, 13, 14, 15]). The motivation for our study comes from the results proved in [10] and which correspond to the case $m=1$ in this article. Section 4 gives some examples where hypotheses (H2) and (H3) are satisfied and to illustrate Theorem 1.3.

In the sequel and in order to simplify our statements we denote by $C$ a generic positive constant which may vary from line to line and for two nonnegative functions $f$ and $g$ on a set $S$, we write $f(x) \asymp g(x)$, for $x \in S$, if there exists a constant $C>0$ such that $g(x) / C \leq f(x) \leq C g(x)$ for all $x \in S$. Let

$$
C_{0}(D):=\left\{f \in C(D): \lim _{|x| \rightarrow 1} f(x)=\lim _{|x| \rightarrow \infty} f(x)=0\right\}
$$

## 2. Preliminary results

In this section, we are concerned with some results related to the Kato class $K_{m, n}^{\infty}(D)$ which are useful for the proof of our main results stated in Theorems 1.2 and 1.3 .

Proposition 2.1 ([4]). Let $q$ be a function in $K_{m, n}^{\infty}(D)$, then

$$
\|q\|_{D}:=\sup _{x \in D} \int_{D}\left(\frac{\rho(y)}{\rho(x)}\right)^{m} G_{m, n}^{D}(x, y)|q(y)| d y<\infty .
$$

To present the following Proposition, we need to denote by $\mathcal{H}$ the set of nonnegative harmonic functions $h$ defined in $D$ by

$$
h(x)=\int_{\partial D} P(x, \xi) \nu(d \xi),
$$

where $\nu$ is a nonnegative measure on $\partial D$ and $P(x, \xi)=\frac{|x|^{2}-1}{|x-\xi|^{n}}$ is the Poisson kernel in $D$. From the 3G-inequality, we derive the following result.

Proposition 2.2. Let $q$ be a nonnegative function in $K_{m, n}^{\infty}(D)$. Then we have

$$
\begin{equation*}
\alpha_{q}:=\sup _{x, y \in D} \int_{D} \frac{G_{m, n}^{D}(x, z) G_{m, n}^{D}(z, y)}{G_{m, n}^{D}(x, y)} q(z) d z<\infty \tag{i}
\end{equation*}
$$

(ii) For any function $h \in \mathcal{H}$ and each $x \in D$, we have

$$
\int_{D} G_{m, n}^{D}(x, z)\left(|z|^{2}-1\right)^{m-1} h(z) q(z) d z \leq \alpha_{q}\left(|x|^{2}-1\right)^{m-1} h(x)
$$

Proof. From the 3G-inequality, there exists $C_{0}>0$ such that for each $x, y, z \in D$, we have

$$
\frac{G_{m, n}^{D}(x, z) G_{m, n}^{D}(z, y)}{G_{m, n}^{D}(x, y)} \leq C_{0}\left[\left(\frac{\rho(z)}{\rho(x)}\right)^{m} G_{m, n}^{D}(x, z)+\left(\frac{\rho(z)}{\rho(y)}\right)^{m} G_{m, n}^{D}(y, z)\right]
$$

This implies that $\alpha_{q} \leq 2 C_{0}\|q\|_{D}$. Then the assertion (i) holds from Proposition 2.1 .

Now, we shall prove (ii). Let $h \in \mathcal{H}$, then there exists a nonnegative measure $\nu$ on $\partial D$ such that

$$
\begin{equation*}
h(x)=\int_{\partial D} P(x, \xi) \nu(d \xi) \tag{2.1}
\end{equation*}
$$

On the other hand, by using the transformation $r^{2}=1+\frac{\varrho(x, y)}{|x-y|^{2}}(1-t)$ in 1.2 , where $\varrho(x, y)=[x, y]^{2}-|x-y|^{2}=\left(|x|^{2}-1\right)\left(|y|^{2}-1\right)$, we obtain

$$
G_{m, n}^{D}(x, y)=\frac{k_{m, n}}{2} \frac{(\varrho(x, y))^{m}}{[x, y]^{n}} \int_{0}^{1} \frac{(1-t)^{m-1}}{\left(1-t \frac{\varrho(x, y)}{[x, y]^{2}}\right)^{n / 2}} d t
$$

This implies for each $x, z \in D$ and $\xi \in \partial D$ that

$$
\lim _{y \rightarrow \xi} \frac{G_{m, n}^{D}(z, y)}{G_{m, n}^{D}(x, y)}=\frac{\left(|z|^{2}-1\right)^{m-1} P(z, \xi)}{\left(|x|^{2}-1\right)^{m-1} P(x, \xi)}
$$

So, it follows from Fatou's lemma that

$$
\begin{aligned}
& \int_{D} G_{m, n}^{D}(x, z) \frac{\left(|z|^{2}-1\right)^{m-1} P(z, \xi)}{\left(|x|^{2}-1\right)^{m-1} P(x, \xi)} q(z) d z \\
& \leq \liminf _{y \rightarrow \xi} \int_{D} \frac{G_{m, n}^{D}(x, z) G_{m, n}^{D}(z, y)}{G_{m, n}^{D}(x, y)} q(z) d z \leq \alpha_{q}
\end{aligned}
$$

This, together with 2.1, completes the proof.
Proposition 2.3 ([4]). Let $q \in K_{m, n}^{\infty}(D)$. Then the function $z \rightarrow \frac{(|z|-1)^{2 m-1}}{|z|^{n-1}} q(z)$ is in $L^{1}(D)$.
Proposition 2.4. 4] Let $q \in K_{m, n}^{\infty}(D)$ and $h$ be a bounded function in $\mathcal{H}$. Then the function

$$
x \rightarrow \int_{D}\left(\frac{|y|^{2}-1}{|x|^{2}-1}\right)^{m-1} G_{m, n}^{D}(x, y) h(y)|q(y)| d y
$$

lies in $C_{0}(D)$.
For a nonnegative function $q \in K_{m, n}^{\infty}(D)$, we denote

$$
\mathcal{F}_{q}=\left\{p \in K_{m, n}^{\infty}(D):|p| \leq q \text { in } D\right\}
$$

Proposition 2.5 ([4]). For any nonnegative function $q \in K_{m, n}^{\infty}(D)$, the family of functions

$$
\left\{\int_{D}\left(\frac{|y|^{2}-1}{|x|^{2}-1}\right)^{m-1} G_{m, n}^{D}(x, y) h_{0}(y) p(y) d y, p \in \mathcal{F}_{q}\right\}
$$

is uniformly bounded and equicontinuous in $\bar{D} \cup\{\infty\}$. Consequently it is relatively compact in $C(\bar{D} \cup\{\infty\})$.

## 3. Proofs of main results

Proof of Theorem 1.2. Let $\lambda \in\left[0, \lambda_{0}\right)$ and $\mu \in\left[0, \mu_{0}\right)$. We define the sequences $\left(u_{k}\right)_{k \geq 0}$ and $\left(v_{k}\right)_{k \geq 0}$ by

$$
\begin{gathered}
v_{0}=\omega \\
u_{k}=\theta-\lambda V_{m, n}\left(p g\left(v_{k}\right)\right) \\
v_{k+1}=\omega-\mu V_{m, n}\left(q f\left(u_{k}\right)\right)
\end{gathered}
$$

We intend to prove that for all $k \in \mathbb{N}$,

$$
\begin{align*}
& 0<\left(1-\frac{\lambda}{\lambda_{0}}\right) \theta \leq u_{k} \leq u_{k+1} \leq \theta  \tag{3.1}\\
& 0<\left(1-\frac{\mu}{\mu_{0}}\right) \omega \leq v_{k+1} \leq v_{k} \leq \omega \tag{3.2}
\end{align*}
$$

Note that from the definition of $\lambda_{0}$ and $\mu_{0}$ we have

$$
\begin{align*}
& \lambda_{0} V_{m, n}(p g(\omega)) \leq \theta,  \tag{3.3}\\
& \mu_{0} V_{m, n}(q f(\theta)) \leq \omega \tag{3.4}
\end{align*}
$$

From (3.3) we have

$$
u_{0}=\theta-\lambda V_{m, n}\left(p g\left(v_{0}\right)\right) \geq\left(1-\frac{\lambda}{\lambda_{0}}\right) \theta>0
$$

Then $v_{1}-v_{0}=-\mu V_{m, n}\left(q f\left(u_{0}\right)\right) \leq 0$. Since $g$ is nondecreasing we obtain

$$
u_{1}-u_{0}=\lambda V_{m, n}\left(p\left(g\left(v_{0}\right)-g\left(v_{1}\right)\right)\right) \geq 0
$$

Now, since $v_{0}$ is positive and $f$ is nondecreasing,

$$
v_{1} \geq \omega-\mu V_{m, n}(q f(\theta))
$$

We deduce from (3.4) that

$$
v_{1} \geq\left(1-\frac{\mu}{\mu_{0}}\right) \omega>0
$$

This implies that $u_{1} \leq \theta$. Finally, we obtain that

$$
\begin{aligned}
& 0<\left(1-\frac{\lambda}{\lambda_{0}}\right) \theta \leq u_{0} \leq u_{1} \leq \theta \\
& 0<\left(1-\frac{\mu}{\mu_{0}}\right) \omega \leq v_{1} \leq v_{0} \leq \omega
\end{aligned}
$$

By induction, we suppose that (3.1) and (3.2) hold for $k$. Since $f$ is nondecreasing and $u_{k+1} \leq \theta$, we have

$$
v_{k+2}-v_{k+1}=\mu V_{m, n}\left(q\left(f\left(u_{k}\right)-f\left(u_{k+1}\right)\right)\right) \leq 0
$$

and

$$
\begin{aligned}
v_{k+2} & =\omega-\mu V_{m, n}\left(q f\left(u_{k+1}\right)\right) \\
& \geq \omega-\mu V_{m, n}(q f(\theta)) \\
& \geq\left(1-\frac{\mu}{\mu_{0}}\right) \omega
\end{aligned}
$$

To reach the last inequality, we use (3.4). Then

$$
0<\left(1-\frac{\mu}{\mu_{0}}\right) \omega \leq v_{k+2} \leq v_{k+1} \leq \omega
$$

Now, using that $g$ is nondecreasing we have

$$
u_{k+2}-u_{k+1}=\lambda V_{m, n}\left(p\left(g\left(v_{k+1}\right)-g\left(v_{k+2}\right)\right) \geq 0\right.
$$

Since $v_{k+2}>0$, we obtain

$$
0<\left(1-\frac{\lambda}{\lambda_{0}}\right) \theta \leq u_{k+1} \leq u_{k+2} \leq \theta
$$

Therefore, the sequences $\left(u_{k}\right)_{k \geq 0}$ and $\left(v_{k}\right)_{k \geq 0}$ converge respectively to two functions $u$ and $v$ satisfying

$$
\begin{aligned}
& \left(1-\frac{\lambda}{\lambda_{0}}\right) \theta \leq u \leq \theta, \\
& \left(1-\frac{\mu}{\mu_{0}}\right) \omega \leq v \leq \omega .
\end{aligned}
$$

We claim that

$$
\begin{align*}
u & =\theta-\lambda V_{m, n}(p g(v)),  \tag{3.5}\\
v & =\omega-\mu V_{m, n}(q f(u)) . \tag{3.6}
\end{align*}
$$

Since $v_{k} \leq \omega$ for all $k \in \mathbb{N}$, using hypothesis $\left(\mathrm{H}_{3}\right)$ and the fact that $g$ is nondecreasing, there exists $\tilde{p} \in K_{m, n}^{\infty}(D)$ such that

$$
\begin{equation*}
p g(v) \leq p g(\omega) \leq \tilde{p} \gamma \tag{3.7}
\end{equation*}
$$

and so $p\left|g\left(v_{k}\right)-g(v)\right| \leq 2 \tilde{p} \gamma$ for all $k \in \mathbb{N}$. From Proposition 2.4 we obtain

$$
\begin{equation*}
V_{m, n}(\tilde{p} \gamma) \in C(\bar{D}) \tag{3.8}
\end{equation*}
$$

and by Lebesgue's theorem we deduce that

$$
\lim _{k \rightarrow \infty} V_{m, n}\left(p g\left(v_{k}\right)\right)=V_{m, n}(p g(v))
$$

So, letting $k \rightarrow \infty$ in the equation $u_{k}=\theta-\lambda V_{m, n}\left(p g\left(v_{k}\right)\right)$, we obtain (3.5). Similarly, we obtain (3.6).

Next, we claim that $(u, v)$ satisfies

$$
\begin{align*}
& (-\Delta)^{m} u+\lambda p g(v)=0 \\
& (-\Delta)^{m} v+\mu q f(u)=0 \tag{3.9}
\end{align*}
$$

Indeed, using (3.7) and Proposition 2.3 we obtain $p g(v) \in L_{\text {loc }}^{1}(D)$. Using again (3.7), it follows from (3.8) that

$$
V_{m, n}(p g(v)) \in C(\bar{D})
$$

Which implies that

$$
V_{m, n}(p g(v)) \in L_{\mathrm{loc}}^{1}(D)
$$

Similarly

$$
q f(u), V_{m, n}(q f(u)) \in L_{\mathrm{loc}}^{1}(D)
$$

Now, applying the operator $(-\Delta)^{m}$ in both (3.5) and (3.6), we deduce that $(u, v)$ is a positive solution (in the sense of distributions) of (3.9).

On the other hand, using Proposition 2.4 and (3.7), we deduce that

$$
x \rightarrow \frac{V_{m, n}(p g(v))(x)}{\left(|x|^{2}-1\right)^{m-1}} \in \overline{C_{0}}(D)
$$

and

$$
x \rightarrow \frac{V_{m, n}(q f(u))(x)}{\left(|x|^{2}-1\right)^{m-1}} \in C_{0}(D)
$$

Thus, we deduce from $(3.5$ and $(3.6$ that

$$
\begin{gathered}
\lim _{x \rightarrow \xi \in \partial D} \frac{u(x)}{\left(|x|^{2}-1\right)^{m-1}}=a \varphi(\xi), \quad \lim _{x \rightarrow \xi \in \partial D} \frac{v(x)}{\left(|x|^{2}-1\right)^{m-1}}=b \psi(\xi) \\
\lim _{|x| \rightarrow \infty} \frac{u(x)}{\left(|x|^{2}-1\right)^{m-1}}=\alpha, \quad \lim _{|x| \rightarrow \infty} \frac{v(x)}{\left(|x|^{2}-1\right)^{m-1}}=\beta
\end{gathered}
$$

Furthermore, the continuity of $\theta, \omega, V_{m, n}(p g(v))$ and $V_{m, n}(q f(u))$ imply that $(u, v) \in$ $(C(D))^{2}$. This completes the proof.
Proof of Theorem 1.3. Put $c=1+\alpha_{p_{1}}+\alpha_{q_{1}}$, where $\alpha_{p_{1}}$ and $\alpha_{q_{1}}$ are the constants given in Proposition 2.2 and associated respectively to the functions $p_{1}$ and $q_{1}$ given in hypothesis $\left(H_{5}\right)$. Suppose that $\varphi \geq c \phi$ and $\psi \geq c \phi$. Then it follows from the maximum principle that for each $x \in D$, we have

$$
\begin{align*}
& H_{D} \varphi(x) \geq c h_{0}(x)  \tag{3.10}\\
& H_{D} \psi(x) \geq c h_{0}(x) \tag{3.11}
\end{align*}
$$

We consider the non-empty closed convex set

$$
\Lambda=\left\{w \in C(\bar{D} \cup\{\infty\}): h_{0} \leq w \leq H_{D} \varphi\right\}
$$

We define the operator $T$ defined on $\Lambda$ as

$$
T w=H_{D} \varphi-\frac{V_{m, n}\left(p g\left[\gamma\left(\beta h+H_{D} \psi\right)-V_{m, n}(q f(\tilde{w}))\right]\right)}{\gamma}
$$

where $\tilde{w}(x)=\gamma(x)(w(x)+\alpha h(x))=\left(|x|^{2}-1\right)^{m-1}(w(x)+\alpha h(x))$. We need to check that the operator $T$ has a fixed point $w$ in $\Lambda$.

First, we prove that $T \Lambda$ is relatively compact in $C(\bar{D} \cup\{\infty\})$. Let $w \in \Lambda$, then we have $w+\alpha h \geq h_{0}$.
Since $f$ is nonincreasing, it follows from Proposition 2.2 that

$$
V_{m, n}(q f(\tilde{w})) \leq V_{m, n}\left(q f\left(\gamma h_{0}\right)\right)=V_{m, n}\left(q f\left(\rho_{0}\right)\right) \leq \alpha_{q_{1}} \rho_{0}
$$

Which implies

$$
\begin{equation*}
\gamma\left(\beta h+H_{D} \psi\right)-V_{m, n}(q f(\tilde{w})) \geq \gamma\left(\beta h+H_{D} \psi-\alpha_{q_{1}} h_{0}\right) \tag{3.12}
\end{equation*}
$$

According to 3.11, we obtain

$$
\begin{equation*}
\gamma\left(\beta h+H_{D} \psi\right)-V_{m, n}(q f(\tilde{w})) \geq \gamma\left(\beta h+h_{0}\right) \geq \rho_{0} \tag{3.13}
\end{equation*}
$$

Hence

$$
\begin{equation*}
T w \leq H_{D} \varphi \tag{3.14}
\end{equation*}
$$

Also, since $g$ is nonincreasing, we obtain

$$
\begin{equation*}
p g\left(\gamma\left(\beta h+H_{D} \psi\right)-V_{m, n}(q f(\tilde{w}))\right) \leq p g\left(\rho_{0}\right) \tag{3.15}
\end{equation*}
$$

So it follows that for each $y \in D$, we have

$$
\begin{equation*}
\frac{p(y) g\left[\gamma(y)\left(\beta h(y)+H_{D} \psi(y)\right)-V_{m, n}(q f(\tilde{w}))(y)\right]}{\gamma(y)} \leq p_{1}(y) h_{0}(y) \tag{3.16}
\end{equation*}
$$

Therefore, we deduce from (H5) and Proposition 2.5 that the family of functions

$$
\left\{x \rightarrow \frac{V_{m, n}\left(p g\left[\gamma\left(\beta h+H_{D} \psi\right)-V_{m, n}(q f(\tilde{w}))\right]\right)(x)}{\gamma(x)}, w \in \Lambda\right\}
$$

is relatively compact in $C(\bar{D} \cup\{\infty\})$. Moreover, since $H_{D} \varphi \in C(\bar{D} \cup\{\infty\})$, we have the set $T \Lambda$ is relatively compact in $C(\bar{D} \cup\{\infty\})$.

Next, we claim that $T \Lambda \subset \Lambda$. Indeed, let $\omega \in \Lambda$, by using (3.15), ( $H_{5}$ ) and Proposition 2.2, we have

$$
\frac{V_{m, n}\left(p g\left[\gamma\left(\beta h+H_{D} \psi\right)-V_{m, n}(q f(\tilde{w}))\right]\right)(x)}{\gamma(x)} \leq \alpha_{p_{1}} h_{0}(x)
$$

for each $x \in D$. According to 3.10 , we obtain

$$
T w(x) \geq\left(1+\alpha_{q_{1}}\right) h_{0}(x) \geq h_{0}(x), \quad \text { for each } x \in D .
$$

This, together with $(3.14)$, proves that $T \omega \in \Lambda$.
Now, we prove the continuity of the operator $T$ in $\Lambda$ with respect to the supremum norm. Let $\left(w_{k}\right)_{k \in \mathbb{N}}$ be a sequence in $\Lambda$ which converges uniformly to a function $w \in \Lambda$. Then, for each $x \in D$, we have

$$
\begin{equation*}
\left|T w_{k}(x)-T w(x)\right| \leq \frac{V_{m, n}\left(p\left|g\left(s_{k}\right)-g(s)\right|\right)(x)}{\gamma(x)} \tag{3.17}
\end{equation*}
$$

where $s_{k}=\gamma\left(\beta h+H_{D} \psi\right)-V_{m, n}\left(q f\left(\gamma\left(w_{k}+\alpha h\right)\right)\right)$ and $s=\gamma\left(\beta h+H_{D} \psi\right)-$ $V_{m, n}(q f(\gamma(w+\alpha h)))$. Using the fact that $g$ is nonincreasing and 3.12, we have

$$
\begin{aligned}
p\left(g\left(s_{k}\right)+g(s)\right) & \leq 2 p g\left(\gamma\left(\beta h+H_{D} \psi-\alpha_{q_{1}} h_{0}\right)\right) \\
& \leq 2 p g\left(\rho_{0}\right)=2 p_{1} \rho_{0} .
\end{aligned}
$$

To reach the last inequality we use 3.11.
Since from (H5) and Proposition 2.4 the function

$$
x \rightarrow \int_{D}\left(\frac{|y|^{2}-1}{|x|^{2}-1}\right)^{m-1} G_{m, n}^{D}(x, y) h_{0}(y) p_{1}(y) d y
$$

is in $C_{0}(D)$, also using the fact that

$$
p\left|g\left(s_{k}\right)-g(s)\right| \leq p\left(g\left(s_{k}\right)+g(s)\right)
$$

it follows from (3.17) and the dominated convergence theorem that for each $x \in D$, the sequence $\left(T w_{k}(x)\right)$ converges to $T w(x)$ as $k \rightarrow \infty$. Since $T \Lambda$ is relatively compact in $C(\bar{D} \cup\{\infty\})$, we deduce that the pointwise convergence implies the uniform convergence; that is,

$$
\left\|T w_{k}-T w\right\|_{\infty} \rightarrow 0 \quad \text { as } k \rightarrow \infty
$$

This shows that $T$ is a continuous mapping from $\Lambda$ into itself. Then by using Schauder fixed point theorem, there exists $w \in \Lambda$ such that $T w=w$. Now, for each $x \in D$, put

$$
\begin{gather*}
u(x)=\left(|x|^{2}-1\right)^{m-1}(w(x)+\alpha h(x)),  \tag{3.18}\\
v(x)=\left(|x|^{2}-1\right)^{m-1}\left(\beta h(x)+H_{D} \psi(x)\right)-V_{m, n}(q f(u))(x) \tag{3.19}
\end{gather*}
$$

Then

$$
\begin{equation*}
u(x)-\alpha\left(|x|^{2}-1\right)^{m-1} h(x)=\left(|x|^{2}-1\right)^{m-1} H_{D} \varphi(x)-V_{m, n}(p g(v))(x) \tag{3.20}
\end{equation*}
$$

As the remainder of the proof, we aim to show that $(u, v)$ is the desired solution of problem (1.3). By using respectively (3.18), 3.19) and 3.13), clearly (u,v) satisfies for each $x \in D$,

$$
\begin{equation*}
h_{0}(x)+\alpha h(x) \leq \frac{u(x)}{\left(|x|^{2}-1\right)^{m-1}} \leq H_{D} \varphi(x)+\alpha h(x) \tag{3.21}
\end{equation*}
$$

and

$$
h_{0}(x)+\beta h(x) \leq \frac{v(x)}{\left(|x|^{2}-1\right)^{m-1}} \leq H_{D} \psi(x)+\beta h(x)
$$

On the other hand, from 3.18, we have $u(x) \geq \rho_{0}(x)$ for each $x \in D$. Since $f$ is nonincreasing, this implies

$$
q f(u) \leq q f\left(\rho_{0}\right)=q_{1} \rho_{0} .
$$

Note that from (H5) we have $q_{1}$ is in the Kato class $K_{m, n}^{\infty}(D)$, so it follows from Proposition 2.3 that $q f(u) \in L_{\mathrm{loc}}^{1}(D)$ and from Proposition 2.2 that $V_{m, n}(q f(u)) \in$ $L_{\text {loc }}^{1}(D)$.

Similarly, we obtain $p g(v) \in L_{\mathrm{loc}}^{1}(D)$ and $V_{m, n}(p g(v)) \in L_{\mathrm{loc}}^{1}(D)$. Then applying the elliptic operator $(-\Delta)^{m}$ in both (3.18) and 3.19), we obtain clearly that $(u, v)$ is a positive continuous solution (in the distributional sense) of

$$
\begin{array}{ll}
(-\Delta)^{m} u+p(x) g(v)=0, & x \in D \\
(-\Delta)^{m} v+q(x) f(u)=0, & x \in D
\end{array}
$$

Finally, from (3.20), 3.16), Proposition 2.4 and the fact that $H_{D} \varphi=\varphi$ on $\partial D$, we conclude that

$$
\lim _{x \rightarrow \xi \in \partial D} \frac{u(x)}{\left(|x|^{2}-1\right)^{m-1}}=\varphi(\xi)
$$

Also, since $\lim _{|x| \rightarrow \infty} H_{D} \varphi(x)=\lim _{|x| \rightarrow \infty} h_{0}(x)=0$, it follows from 3.21 that

$$
\lim _{|x| \rightarrow \infty} \frac{u(x)}{\left(|x|^{2}-1\right)^{m-1}}=\alpha
$$

The proof is complete by using the same arguments for $v$.

## 4. Examples

In this Section, we give some examples where hypotheses (H2) and (H3) are satisfied.

Example 4.1. Let $\alpha=1, a=0, \beta=1$ and $b=0$. Let $f$ and $g$ be two nonnegative nondecreasing bounded continuous functions on $(0, \infty)$. Assume that $p$ and $q$ are two nonnegative measurable functions on $D$ satisfying

$$
p(x) \leq \frac{1}{|x|^{\nu-\kappa}(|x|-1)^{\kappa}}, \quad q(x) \leq \frac{1}{|x|^{\nu-\kappa}(|x|-1)^{\kappa}}
$$

with $\kappa<m$ and $\nu>2$.
Since $|x|+1 \asymp|x|$, for each $x \in D$, then we have

$$
\begin{aligned}
& \frac{p(x) g(\omega(x))}{\left(|x|^{2}-1\right)^{m-1}} \leq \frac{C}{|x|^{\nu-\kappa+m-1}(|x|-1)^{m-1+\kappa}} \\
& \frac{q(x) f(\theta(x))}{\left(|x|^{2}-1\right)^{m-1}} \leq \frac{C}{|x|^{\nu-\kappa+m-1}(|x|-1)^{m-1+\kappa}}
\end{aligned}
$$

Using the fact that $\kappa<m$ and $\nu>2$, it follows that the functions

$$
x \rightarrow \frac{p(x) g(\omega(x))}{\left(|x|^{2}-1\right)^{m-1}} \quad \text { and } \quad x \rightarrow \frac{q(x) f(\theta(x))}{\left(|x|^{2}-1\right)^{m-1}}
$$

are in $K_{m, n}^{\infty}(D)$. Now, since for each $x \in D$, we have

$$
\begin{gather*}
h(x)=1-\frac{1}{|x|^{n-2}} \asymp \frac{|x|-1}{|x|}  \tag{4.1}\\
\theta(x)=\left(|x|^{2}-1\right)^{m-1} h(x)=\omega(x)
\end{gather*}
$$

then there exists $C>0$ such that

$$
p(x) g(\omega(x)) \leq \frac{C}{|x|^{\nu-\kappa+m-2}(|x|-1)^{m+\kappa}} \omega(x), \quad \text { for each } x \in D .
$$

So, we deduce from the choice of $\nu, \kappa$ that there exists $p_{0} \in K_{m, n}^{\infty}(D)$ such that

$$
p(x) g(\omega(x)) \leq p_{0}(x) \omega(x)
$$

Which implies from Proposition 2.2 that $V_{m, n}(p g(\omega)) \leq C \omega$. Hence $\lambda_{0}>0$. Similarly, we have $\mu_{0}>0$.

Example 4.2. Let $\alpha=1, a=0, \beta=0$ and $b=1$. Assume that $\psi \geq c_{0}>0$ on $\partial D$. Let $f$ and $g$ be two continuous and nondecreasing functions on $(0, \infty)$ satisfying for $t \in(0, \infty)$

$$
\begin{equation*}
0 \leq g(t) \leq \eta t \text { and } 0 \leq f(t) \leq \xi t \tag{4.2}
\end{equation*}
$$

where $\eta$ and $\xi$ are positive constants. Suppose furthermore that $p$ and $q$ are nonnegative measurable functions on $D$ such that

$$
p(x) \leq \frac{1}{|x|^{\delta-\sigma}(|x|-1)^{\sigma}}, \quad q(x) \leq \frac{1}{|x|^{s-r}(|x|-1)^{r}}
$$

where

$$
\begin{align*}
& \sigma+1<2 m<\delta+n-2  \tag{4.3}\\
& r-1<2 m<2-n+s \tag{4.4}
\end{align*}
$$

Here $\theta(x)=\left(|x|^{2}-1\right)^{m-1} h(x)$ and $\omega(x)=\left(|x|^{2}-1\right)^{m-1} H_{D} \psi(x)$.
Since $\psi \geq c_{0}>0$, it follows that

$$
\begin{equation*}
H_{D} \psi(x) \asymp H_{D} 1(x)=\frac{1}{|x|^{n-2}}, \quad \text { for each } x \in D \tag{4.5}
\end{equation*}
$$

Then, from 4.2, we have

$$
\begin{equation*}
\frac{p(x) g(\omega(x))}{\left(|x|^{2}-1\right)^{m-1}} \leq \eta p(x) H_{D} \psi(x) \leq \frac{C}{|x|^{n-2+\delta-\sigma}(|x|-1)^{\sigma}} . \tag{4.6}
\end{equation*}
$$

Also, using 4.1, we have

$$
\frac{q(x) f(\theta(x))}{\left(|x|^{2}-1\right)^{m-1}} \leq \xi q(x) h(x) \leq \frac{C}{|x|^{1+s-r}(|x|-1)^{r-1}} .
$$

This, together with 4.3, 4.4 and 4.6), implies that (H3) is satisfied.
Now, using 4.1, 4.2 and 4.5, for each $x \in D$, we have

$$
p(x) g(\omega(x)) \leq \eta p(x) \omega(x) \leq C p(x)\left(|x|^{2}-1\right)^{m-1} H_{D} 1(x) \leq \frac{C\left(|x|^{2}-1\right)^{m-1} h(x)}{|x|^{n-3+\delta-\sigma}(|x|-1)^{\sigma+1}} .
$$

So it follows from (4.3) that there exists $p_{2} \in K_{m, n}^{\infty}(D)$ such that $p g(\omega) \leq p_{2} \theta$. Hence, it follows from Proposition 2.2 that $V_{m, n}(\operatorname{pg}(\omega)) \leq C \theta$, which implies that $\lambda_{0}>0$.

Using again 4.1, we obtain, for each $x \in D$,

$$
q(x) h(x) \leq \frac{C}{|x|^{1+s-r}(|x|-1)^{r-1}}
$$

According to 4.2 and 4.4, there exists $q_{2} \in K_{m, n}^{\infty}(D)$ satisfying

$$
q f(\theta) \leq C \gamma q_{2} H_{D} 1
$$

Finally, we deduce from 4.5 and Proposition 2.2 that $V_{m, n}(q f(\theta)) \leq C \omega$. This implies that $\mu_{0}>0$.

We end this section by giving an example as an application of Theorem 1.3 .
Example 4.3. Let $\tau>0, \varepsilon>0, g(t)=t^{-\tau}$ and $f(t)=t^{-\varepsilon}$. Let $p$ and $q$ be two nonnegative measurable functions in $D$ satisfying

$$
\begin{aligned}
& p(x) \leq \frac{1}{(|x|-1)^{l-(1+\tau) m}|x|^{\vartheta-l+(1+\tau)(n-m)}} \\
& q(x) \leq \frac{1}{(|x|-1)^{k-(1+\varepsilon) m}|x|^{\zeta-k+(1+\varepsilon)(n-m)}}
\end{aligned}
$$

where $l<2 m<\vartheta$ and $k<2 m<\zeta$. Let $\phi$ be a nonnegative nontrivial continuous function on $\partial D$ and put $\rho_{0}(x)=\left(|x|^{2}-1\right)^{m-1} H_{D} \phi(x)$ for $x \in D$.

Since for $x \in D$, we have

$$
H_{D} \phi(x) \geq C \frac{|x|-1}{(|x|+1)^{n-1}}
$$

Then we obtain for each $x \in D$ that

$$
p_{1}(x)=p(x) \rho_{0}^{-\tau-1}(x) \leq \frac{C}{(|x|-1)^{l}|x|^{\vartheta-l}}
$$

Similarly, we have

$$
q_{1}(x) \leq \frac{C}{(|x|-1)^{k}|x|^{\zeta-k}}, \quad x \in D .
$$

Hence, hypothesis (H5) is satisfied. So there exists $c>1$ such that if $\varphi$ and $\psi$ are two nonnegative nontrivial continuous functions on $\partial D$ satisfying $\varphi \geq c \phi$ and $\psi \geq c \phi$ on $\partial D$, then for each $\alpha \geq 0$ and $\beta \geq 0$, problem

$$
\begin{array}{r}
(-\Delta)^{m} u+p(x) v^{-\tau}=0, \quad x \in D, \quad \text { (in the sense of distributions) } \\
(-\Delta)^{m} v+q(x) u^{-\varepsilon}=0, \quad x \in D \\
\lim _{x \rightarrow s \in \partial D} \frac{u(x)}{\left(|x|^{2}-1\right)^{m-1}}=\varphi(s), \quad \lim _{x \rightarrow s \in \partial D} \frac{v(x)}{\left(|x|^{2}-1\right)^{m-1}}=\psi(s) \\
\lim _{|x| \rightarrow \infty} \frac{u(x)}{\left(|x|^{2}-1\right)^{m-1}}=\alpha, \quad \lim _{|x| \rightarrow \infty} \frac{v(x)}{\left(|x|^{2}-1\right)^{m-1}}=\beta
\end{array}
$$

has a positive continuous solution $(u, v)$ satisfying for each $x \in D$,

$$
\begin{aligned}
& \left(|x|^{2}-1\right)^{m-1}\left(\alpha h(x)+h_{0}(x)\right) \leq u(x) \leq\left(|x|^{2}-1\right)^{m-1}\left(\alpha h(x)+H_{D} \varphi(x)\right) \\
& \left(|x|^{2}-1\right)^{m-1}\left(\beta h(x)+h_{0}(x)\right) \leq v(x) \leq\left(|x|^{2}-1\right)^{m-1}\left(\beta h(x)+H_{D} \psi(x)\right)
\end{aligned}
$$

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