

PERIODIC SOLUTIONS FOR NON-AUTONOMOUS SECOND-ORDER DIFFERENTIAL SYSTEMS WITH (q, p) -LAPLACIAN

CHUN LI, ZENG-QI OU, CHUN-LEI TANG

ABSTRACT. Some existence theorems are obtained for periodic solutions of nonautonomous second-order differential systems with (q, p) -Laplacian by using the least action principle and the saddle point theorem.

1. INTRODUCTION

Consider the second-order system

$$\begin{aligned} \frac{d}{dt}(|\dot{u}_1(t)|^{q-2}\dot{u}_1(t)) &= \nabla_{u_1}F(t, u_1(t), u_2(t)), \\ \frac{d}{dt}(|\dot{u}_2(t)|^{p-2}\dot{u}_2(t)) &= \nabla_{u_2}F(t, u_1(t), u_2(t)), \quad \text{a.e. } t \in [0, T], \\ u_1(0) - u_1(T) &= \dot{u}_1(0) - \dot{u}_1(T) = 0, \\ u_2(0) - u_2(T) &= \dot{u}_2(0) - \dot{u}_2(T) = 0, \end{aligned} \tag{1.1}$$

where $1 < p, q < \infty$, $T > 0$ and $|\cdot|$ denotes the Euclidean norm in \mathbb{R}^N . $F : [0, T] \times \mathbb{R}^N \times \mathbb{R}^N \rightarrow \mathbb{R}$ satisfies the following assumption

- (A1) – F is measurable in t for each $(x_1, x_2) \in \mathbb{R}^N \times \mathbb{R}^N$;
- F is continuously differentiable in (x_1, x_2) for a.e. $t \in [0, T]$;
- there exist $a_1, a_2 \in C(\mathbb{R}_+, \mathbb{R}_+)$ and $b \in L^1(0, T; \mathbb{R}_+)$ such that

$$|F(t, x_1, x_2)|, |\nabla_{x_1}F(t, x_1, x_2)|, |\nabla_{x_2}F(t, x_1, x_2)| \leq [a_1(|x_1|) + a_2(|x_2|)]b(t)$$

for all $(x_1, x_2) \in \mathbb{R}^N \times \mathbb{R}^N$ and a.e. $t \in [0, T]$.

We denote by $W_T^{1,p}$ the Sobolev space of functions $u \in L^p(0, T; \mathbb{R}^N)$ having a weak derivative $\dot{u} \in L^p(0, T; \mathbb{R}^N)$. The norm in $W_T^{1,p}$ is defined by

$$\|u\|_{W_T^{1,p}} = \left(\int_0^T (|u(t)|^p + |\dot{u}(t)|^p) dt \right)^{1/p}.$$

The corresponding functional $\varphi : W \rightarrow \mathbb{R}$ given is

$$\varphi(u_1, u_2) = \frac{1}{q} \int_0^T |\dot{u}_1(t)|^q dt + \frac{1}{p} \int_0^T |\dot{u}_2(t)|^p dt + \int_0^T F(t, u_1(t), u_2(t)) dt,$$

2000 Mathematics Subject Classification. 34C25, 35B38, 47J30.

Key words and phrases. Periodic solution; differential systems; (q, p) -Laplacian; least action principle; saddle point theorem.

©2014 Texas State University - San Marcos.

Submitted March 18, 2012. Published March 5, 2014.

where $W = W_T^{1,q} \times W_T^{1,p}$ is a reflexive Banach space and endowed with the norm

$$\|(u_1, u_2)\|_W = \|u_1\|_{W_T^{1,q}} + \|u_2\|_{W_T^{1,p}}.$$

It follows from assumption (A1) that the functional φ is continuously differentiable and weakly lower semicontinuous on W . Moreover,

$$\begin{aligned} & \langle \varphi'(u_1, u_2), (v_1, v_2) \rangle \\ &= \int_0^T [(|\dot{u}_1(t)|^{q-2}\dot{u}_1(t), \dot{v}_1(t)) + (\nabla_{u_1} F(t, u_1(t), u_2(t)), v_1(t))] dt \\ &+ \int_0^T [(|\dot{u}_2(t)|^{p-2}\dot{u}_2(t), \dot{v}_2(t)) + (\nabla_{u_2} F(t, u_1(t), u_2(t)), v_2(t))] dt \end{aligned}$$

for all $(u_1, u_2), (v_1, v_2) \in W$.

For each $u \in W_T^{1,p}$ can be written as $u(t) = \bar{u} + \tilde{u}(t)$ with

$$\bar{u} = \frac{1}{T} \int_0^T u(t) dt, \quad \int_0^T \tilde{u}(t) dt = 0.$$

We have the Sobolev's inequality (for a proof and details see [4])

$$\|\tilde{u}\|_\infty \leq C_1 \|\dot{u}\|_p, \quad \|\tilde{v}\|_\infty \leq C_1 \|\dot{v}\|_q \quad \text{for each } u \in W_T^{1,p}, \quad v \in W_T^{1,q},$$

and Wirtinger's inequality (see [4])

$$\|\tilde{u}\|_p \leq C_2 \|\dot{u}\|_p, \quad \|\tilde{v}\|_q \leq C_2 \|\dot{v}\|_q \quad \text{for each } u \in W_T^{1,p}, \quad v \in W_T^{1,q},$$

where

$$\|u\|_p = \left(\int_0^T |u(t)|^p dt \right)^{1/p}, \quad \|u\|_\infty = \max_{t \in [0, T]} |u(t)|.$$

A function $G : \mathbb{R}^N \rightarrow \mathbb{R}$ is called to be (λ, μ) -subconvex if

$$G(\lambda(x+y)) \leq \mu(G(x) + G(y))$$

for some $\lambda, \mu > 0$ and all $x, y \in \mathbb{R}^N$ (see [19]).

The existence of periodic solutions for the second-order Hamiltonian system

$$\begin{aligned} \ddot{u}(t) &= \nabla F(t, u), \quad \text{a.e. } t \in [0, T], \\ u(0) - u(T) &= \dot{u}(0) - \dot{u}(T) = 0, \end{aligned} \tag{1.2}$$

has been extensively investigated in papers, such as [1, 2, 3, 4, 12, 13, 14, 15, 16, 18, 19] and the reference therein. Many solvability conditions are given, such as the coercive condition (see [1]), the periodicity condition (see [18]), the convexity condition (see [3]), the boundedness condition (see [4]), the subadditive condition (see [12]), and the sublinear condition (see [14]). When the gradient $\nabla F(t, x)$ is bounded; that is, there exists $g \in L^1(0, T; \mathbb{R}_+)$ such that

$$|\nabla F(t, x)| \leq g(t)$$

for all $x \in \mathbb{R}^N$ and a.e. $t \in [0, T]$. Mawhin and Willem [4] obtained the existence of solutions for problem (1.2) under the condition

$$\int_0^T F(t, x) dt \rightarrow +\infty \text{(or } -\infty\text{)}, \quad \text{as } |x| \rightarrow \infty.$$

Tang [14] proved the existence of solutions for problem (1.2) when

$$|\nabla F(t, x)| \leq f(t)|x|^\alpha + g(t) \tag{1.3}$$

for all $x \in \mathbb{R}^N$ and a.e. $t \in [0, T]$, where $f, g \in L^1(0, T; \mathbb{R}_+)$ and $\alpha \in [0, 1]$. And, F satisfies the condition

$$|x|^{-2\alpha} \int_0^T F(t, x) dt \rightarrow +\infty \text{ (or } -\infty\text{), as } |x| \rightarrow \infty.$$

Tang and Meng [16] studied the existence of solutions for problem (1.2) under the conditions (1.3) or

$$|\nabla F(t, x)| \leq f(t)|x| + g(t)$$

for all $x \in \mathbb{R}^N$ and a.e. $t \in [0, T]$, where $f, g \in L^1(0, T; \mathbb{R}_+)$. The results in [16] complement those in [14, Theorem 1 and 2].

Recently, Paşa and Tang [9] established the existence results for problem (1.1) which extend [14, Theorems 1 and 2]. By applying the least action principle, Paşa [7] proved some existence theorems for problem (1.1) which generalize the corresponding Theorems of [19]. Using the Saddle Point Theorem, Paşa and Tang [10] obtained some existence results for problem (1.1). Paşa [8] studied the existence of periodic solutions for nonautonomous second-order differential inclusions systems with (q, p) -Laplacian which extend the results of [5, 6, 9, 14].

In this paper, motivated by references [7, 9, 14, 16], we consider the existence of periodic solutions for problem (1.1) by using the least action principle and the Saddle Point Theorem. Our main results are the following theorems.

Theorem 1.1. *Suppose that $F = F_1 + F_2$, where F_1 and F_2 satisfy assumption (A1) and the following conditions:*

- (H0) $F_1(t, \cdot, \cdot)$ is (λ, μ) -subconvex with $\lambda > 1/2$ and $1/2 < \mu < 2^{r-1}\lambda^r$ for a.e. $t \in [0, T]$, where $r = \min\{p, q\}$;
- (H1) there exist $f_i, g_i, h_i \in L^1(0, T; \mathbb{R}_+)$, $i = 1, 2$, $\alpha_1 \in [0, q-1]$, $\alpha_2 \in [0, p-1]$, $\beta_1 \in [0, p/q']$, $\beta_2 \in [0, q/p']$, $q' = q/(q-1)$ and $p' = p/(p-1)$

$$|\nabla_{x_1} F_2(t, x_1, x_2)| \leq f_1(t)|x_1|^{\alpha_1} + g_1(t)|x_2|^{\beta_1} + h_1(t)$$

$$|\nabla_{x_2} F_2(t, x_1, x_2)| \leq f_2(t)|x_2|^{\alpha_2} + g_2(t)|x_1|^{\beta_2} + h_2(t)$$

for all $(x_1, x_2) \in \mathbb{R}^N \times \mathbb{R}^N$ and a.e. $t \in [0, T]$;

- (H2)

$$\lim_{|x| \rightarrow \infty} \frac{1}{|x_1|^{\gamma_1} + |x_2|^{\gamma_2}} \left(\frac{1}{\mu} \int_0^T F_1(t, \lambda x_1, \lambda x_2) dt + \int_0^T F_2(t, x_1, x_2) dt \right) > 2K,$$

where $|x| = \sqrt{|x_1|^2 + |x_2|^2}$, $\gamma_1 = \max\{q'\alpha_1, \beta_2 p'\}$, $\gamma_2 = \max\{p'\alpha_2, \beta_1 q'\}$ and

$$K = \max \left\{ \frac{4^{q'/q}(2^{q-1}\|f_1\|_{L^1}C_1)^{q'}}{q'}, \frac{4^{p'/p}(2^{p-1}\|f_2\|_{L^1}C_1)^{p'}}{p'}, \right. \\ \left. \frac{4^{q'/q}(2^{\beta_1}\|g_1\|_{L^1}C_1)^{q'}}{q'}, \frac{4^{p'/p}(2^{\beta_2}\|g_2\|_{L^1}C_1)^{p'}}{p'} \right\}.$$

Then problem (1.1) has at least one solution in W .

Corollary 1.2. *Suppose that $F = F_1 + F_2$, satisfies (H0), (H1) and*

- (H2')

$$\frac{1}{|x_1|^{\gamma_1} + |x_2|^{\gamma_2}} \left(\frac{1}{\mu} \int_0^T F_1(t, \lambda x_1, \lambda x_2) dt + \int_0^T F_2(t, x_1, x_2) dt \right) \rightarrow \infty$$

as $|x| \rightarrow +\infty$. Then problem (1.1) has at least one solution in W .

Remark 1.3. Corollary 1.2 generalizes Theorem 1 of [7]. In fact, it follows from Corollary 1.2 by letting $\beta_1 = \beta_2 = 0$. There are functions satisfying the assumptions of our Corollary 1.2 and not satisfying the assumptions in [7, 9]. For example, Let $\alpha_1 = \alpha_2 = 15/4$, $\beta_1 = \beta_2 = 11/4$, $p = q = 5$, $p' = q' = 5/4$, and

$$\begin{aligned} F_1(t, x_1) &= 5 + \sin(|x_1|^6 + |x_2|^6), \\ F_2(t, x_1, x_2) &= \left(\frac{2T}{3} - t\right)(|x_1|^{19/4} + |x_2|^{19/4} + |x_1|^{5/4}|x_2|^{5/4}). \end{aligned}$$

Theorem 1.4. Suppose that $F(t, x_1, x_2)$ satisfies (H1) and

(H3)

$$\lim_{|x| \rightarrow \infty} \frac{1}{|x_1|^{\gamma_1} + |x_2|^{\gamma_2}} \int_0^T F(t, x_1, x_2) dt < -(2q' + 2p' + 1)2K.$$

Then problem (1.1) has at least one solution in W .

Corollary 1.5. Suppose that $F(t, x_1, x_2)$ satisfies (H1) and

(H3')

$$\frac{1}{|x_1|^{\gamma_1} + |x_2|^{\gamma_2}} \int_0^T F(t, x_1, x_2) dt \rightarrow -\infty$$

as $|x| \rightarrow \infty$. Then problem (1.1) has at least one solution in W .

Remark 1.6. Corollary 1.5 extends [9, Theorem 2]. In fact, it follows from Corollary 1.5 by letting $\beta_1 = \beta_2 = 0$. There are functions satisfying the assumptions of our Corollary 1.5 and not satisfying the assumptions in [9]. For example, Let $\alpha_1 = \alpha_2 = 15/4$, $\beta_1 = \beta_2 = 11/4$, $p = q = 5$, $p' = q' = 5/4$, and

$$F(t, x_1, x_2) = \left(\frac{T}{3} - t\right)(|x_1|^{19/4} + |x_2|^{19/4} + |x_1|^{5/4}|x_2|^{5/4}).$$

2. PROOFS OF MAIN RESULTS

Tian and Ge [17] proved the following result which generalizes a very well known result proved by Jean Mawhin and Michel Willem [4, Theorem 1.4].

Lemma 2.1 ([17]). *Let $L : [0, T] \times \mathbb{R}^N \times \mathbb{R}^N \times \mathbb{R}^N \times \mathbb{R}^N \rightarrow \mathbb{R}$, $(t, x_1, x_2, y_1, y_2) \rightarrow L(t, x_1, x_2, y_1, y_2)$ be measurable in t for each (x_1, x_2, y_1, y_2) , and continuously differentiable in (x_1, x_2, y_1, y_2) for a.e. $t \in [0, T]$. If there exist $a_i \in C(\mathbb{R}_+, \mathbb{R}_+)$, $i = 1, 2$, $b \in L^1(0, T; \mathbb{R}_+)$, and $c_1 \in L^p(0, T; \mathbb{R}_+)$, $c_2 \in L^q(0, T; \mathbb{R}_+)$, $1 < p, q < \infty$, such that for a.e. $t \in [0, T]$ and every $(x_1, x_2, y_1, y_2) \in \mathbb{R}^N \times \mathbb{R}^N \times \mathbb{R}^N \times \mathbb{R}^N$, one has*

$$\begin{aligned} |L(t, x_1, x_2, y_1, y_2)| &\leq (a_1(|x_1|) + a_2(|x_2|))(b(t) + |y_1|^q + |y_2|^p), \\ |D_{x_1}L(t, x_1, x_2, y_1, y_2)| &\leq (a_1(|x_1|) + a_2(|x_2|))(b(t) + |y_2|^p), \\ |D_{x_2}L(t, x_1, x_2, y_1, y_2)| &\leq (a_1(|x_1|) + a_2(|x_2|))(b(t) + |y_1|^q), \\ |D_{y_1}L(t, x_1, x_2, y_1, y_2)| &\leq (a_1(|x_1|) + a_2(|x_2|))(c_1(t) + |y_1|^{q-1}), \\ |D_{y_2}L(t, x_1, x_2, y_1, y_2)| &\leq (a_1(|x_1|) + a_2(|x_2|))(c_2(t) + |y_2|^{p-1}), \end{aligned}$$

then the function $\varphi : W_T^{1,q} \times W_T^{1,p} \rightarrow \mathbb{R}$ defined by

$$\varphi(u_1, u_2) = \int_0^T L(t, u_1(t), u_2(t), \dot{u}_1(t), \dot{u}_2(t)) dt$$

is continuously differentiable on $W_T^{1,q} \times W_T^{1,p}$ and

$$\begin{aligned} \langle \varphi'(u_1, u_2), (v_1, v_2) \rangle &= \int_0^T ((D_{x_1} L(t, u_1(t), u_2(t), \dot{u}_1(t), \dot{u}_2(t)), v_1(t)) \\ &\quad + (D_{y_1} L(t, u_1(t), u_2(t), \dot{u}_1(t), \dot{u}_2(t)), \dot{v}_1(t)) \\ &\quad + (D_{x_2} L(t, u_1(t), u_2(t), \dot{u}_1(t), \dot{u}_2(t)), v_2(t)) \\ &\quad + (D_{y_2} L(t, u_1(t), u_2(t), \dot{u}_1(t), \dot{u}_2(t)), \dot{v}_2(t))) dt. \end{aligned}$$

Corollary 2.2. *Let $L : [0, T] \times \mathbb{R}^N \times \mathbb{R}^N \times \mathbb{R}^N \times \mathbb{R}^N \rightarrow \mathbb{R}$ be defined by*

$$L(t, x_1, x_2, y_1, y_2) = \frac{1}{q}|y_1|^q + \frac{1}{p}|y_2|^p + F(t, x_1, x_2)$$

where $F : [0, T] \times \mathbb{R}^N \times \mathbb{R}^N \rightarrow \mathbb{R}$ satisfies condition (A1). If $(u_1, u_2) \in W_T^{1,q} \times W_T^{1,p}$ is a solution of the corresponding Euler equation $\varphi'(u_1, u_2) = 0$, then (u_1, u_2) is a solution of problem (1.1).

Remark 2.3. The function φ is weakly lower semi-continuous (w.l.s.c.) on W as the sum of two convex continuous functions and of a weakly continuous one.

We will prove Theorem 1.1 by using the least action principle [4, Theorem 1.1], and Theorem 1.4 by using the saddle point theorem [11, Theorem 4.6].

Proof of Theorem 1.1. Let $\beta = \log_{2\lambda}(2\mu)$. Then $0 < \beta < r$. For $|x| > 1$, there exists a positive integer n such that

$$n - 1 < \log_{2\lambda} |x| \leq n.$$

So, we have $|x|^\beta > (2\lambda)^{(n-1)\beta} = (2\mu)^{n-1}$ and $|x| \leq (2\lambda)^n$. Then, by (A1) and (H0), one has

$$\begin{aligned} F_1(t, x_1, x_2) &\leq 2\mu F_1(t, x_1/(2\lambda), x_2/(2\lambda)) \leq \dots \\ &\leq (2\mu)^n F_1(t, x_1/(2\lambda), x_2/(2\lambda)) \\ &\leq 2\mu|x|^\beta(a_{10} + a_{20})b(t) \end{aligned}$$

for a.e. $t \in [0, T]$ and all $|x| > 1$, where $a_{i0} = \max_{0 \leq s \leq 1} a_i(s)$, $i = 1, 2$. Therefore,

$$F_1(t, x_1, x_2) \leq (2^{\beta/2+1}\mu(|x_1|^\beta + |x_2|^\beta) + 1)(a_{10} + a_{20})b(t) \quad (2.1)$$

for a.e. $t \in [0, T]$ and all $(x_1, x_2) \in \mathbb{R}^N \times \mathbb{R}^N$.

It follows from (H1), Sobolev's inequality and Young's inequality that

$$\begin{aligned} &\left| \int_0^T (F_2(t, u_1(t), \bar{u}_2) - F_2(t, \bar{u}_1, \bar{u}_2)) dt \right| \\ &= \left| \int_0^T \int_0^1 (\nabla_{x_1} F_2(t, \bar{u}_1 + s\tilde{u}_1(t), \bar{u}_2), \tilde{u}_1(t)) ds dt \right| \\ &\leq \int_0^T \int_0^1 f_1(t)|\bar{u}_1 + s\tilde{u}_1(t)|^{\alpha_1}|\tilde{u}_1(t)| ds dt + \int_0^T \int_0^1 g_1(t)|\bar{u}_2|^{\beta_1}|\tilde{u}_1(t)| ds dt \\ &\quad + \int_0^T \int_0^1 h_1(t)|\tilde{u}_1(t)| ds dt \\ &\leq 2^{q-1}(|\bar{u}_1|^{\alpha_1} + \|\tilde{u}_1\|_\infty^{\alpha_1})\|\tilde{u}_1\|_\infty\|f_1\|_{L^1} + |\bar{u}_2|^{\beta_1}\|\tilde{u}_1\|_\infty\|g_1\|_{L^1} + \|\tilde{u}_1\|_\infty\|h_1\|_{L^1} \\ &\leq 2^{q-1}C_1^{\alpha_1+1}\|f_1\|_{L^1}\|\dot{u}_1\|_q^{\alpha_1+1} + 2^{q-1}\|f_1\|_{L^1}C_1|\bar{u}_1|^{\alpha_1}\|\dot{u}_1\|_q \end{aligned}$$

$$\begin{aligned}
& + C_1 \|g_1\|_{L^1} |\bar{u}_2|^{\beta_1} \|\dot{u}_1\|_q + C_1 \|h_1\|_{L^1} \|\dot{u}_1\|_q \\
& \leq 2^{q-1} C_1^{\alpha_1+1} \|f_1\|_{L^1} \|\dot{u}_1\|_q^{\alpha_1+1} + \frac{1}{4q} \|\dot{u}_1\|_q^q + \frac{4^{q'/q} (2^{q-1} \|f_1\|_{L^1} C_1)^{q'}}{q'} |\bar{u}_1|^{q'\alpha_1} \\
& \quad + \frac{1}{4q} \|\dot{u}_1\|_q^q + \frac{4^{q'/q} (\|g_1\|_{L^1} C_1)^{q'}}{q'} |\bar{u}_2|^{q'\beta_1} + C_1 \|h_1\|_{L^1} \|\dot{u}_1\|_q \\
& = \frac{1}{2q} \|\dot{u}_1\|_q^q + 2^{q-1} C_1^{\alpha_1+1} \|f_1\|_{L^1} \|\dot{u}_1\|_q^{\alpha_1+1} + \frac{4^{q'/q} (2^{q-1} \|f_1\|_{L^1} C_1)^{q'}}{q'} |\bar{u}_1|^{q'\alpha_1} \\
& \quad + \frac{4^{q'/q} (\|g_1\|_{L^1} C_1)^{q'}}{q'} |\bar{u}_2|^{q'\beta_1} + C_1 \|h_1\|_{L^1} \|\dot{u}_1\|_q
\end{aligned}$$

and

$$\begin{aligned}
& \left| \int_0^T (F_2(t, u_1(t), u_2(t)) - F_2(t, u_1(t), \bar{u}_2)) dt \right| \\
& = \left| \int_0^T \int_0^1 (\nabla_{x_2} F_2(t, u_1(t), \bar{u}_2 + s\tilde{u}_2(t)), \tilde{u}_2(t)) ds dt \right| \\
& \leq \int_0^T \int_0^1 f_2(t) |\bar{u}_2 + s\tilde{u}_2(t)|^{\alpha_2} |\tilde{u}_2(t)| ds dt + \int_0^T \int_0^1 g_2(t) |u_1|^{\beta_2} |\tilde{u}_2(t)| ds dt \\
& \quad + \int_0^T \int_0^1 h_2(t) |\tilde{u}_2(t)| ds dt \\
& \leq 2^{p-1} (|\bar{u}_2|^{\alpha_2} + \|\tilde{u}_2\|_\infty^{\alpha_2}) \|\tilde{u}_2\|_\infty \|f_2\|_{L^1} + 2^{\beta_2} (|\bar{u}_1|^{\beta_2} + \|\tilde{u}_1\|_\infty^{\beta_2}) \|\tilde{u}_2\|_\infty \|g_2\|_{L^1} \\
& \quad + \|\tilde{u}_2\|_\infty \|h_2\|_{L^1} \\
& \leq 2^{p-1} C_1^{\alpha_2+1} \|f_2\|_{L^1} \|\dot{u}_2\|_p^{\alpha_2+1} + 2^{p-1} C_1 \|f_2\|_{L^1} |\bar{u}_2|^{\alpha_2} \|\dot{u}_2\|_p + C_1 \|h_2\|_{L^1} \|\dot{u}_2\|_p \\
& \quad + 2^{\beta_2} \|g_2\|_{L^1} C_1^{\beta_2+1} \|\dot{u}_2\|_p \|\dot{u}_1\|_q^{\beta_2} + 2^{\beta_2} \|g_2\|_{L^1} C_1 \|\dot{u}_2\|_p |\bar{u}_1|^{\beta_2} \\
& \leq 2^{p-1} C_1^{\alpha_2+1} \|f_2\|_{L^1} \|\dot{u}_2\|_p^{\alpha_2+1} + \frac{1}{4p} \|\dot{u}_2\|_p^p + \frac{4^{p'/p} (2^{p-1} \|f_2\|_{L^1} C_1)^{p'}}{p'} |\bar{u}_2|^{p'\alpha_2} \\
& \quad + \frac{1}{4p} \|\dot{u}_2\|_p^p + \frac{4^{p'/p} (2^{\beta_2} \|g_2\|_{L^1} C_1^{\beta_2+1})^{p'}}{p'} \|\dot{u}_1\|_q^{\beta_2 p'} + \frac{1}{4p} \|\dot{u}_2\|_p^p \\
& \quad + \frac{4^{p'/p} (2^{\beta_2} \|g_2\|_{L^1} C_1)^{p'}}{p'} |\bar{u}_1|^{\beta_2 p'} + C_1 \|h_2\|_{L^1} \|\dot{u}_2\|_p \\
& = \frac{3}{4p} \|\dot{u}_2\|_p^p + 2^{p-1} C_1^{\alpha_2+1} \|f_2\|_{L^1} \|\dot{u}_2\|_p^{\alpha_2+1} + \frac{4^{p'/p} (2^{p-1} \|f_2\|_{L^1} C_1)^{p'}}{p'} |\bar{u}_2|^{p'\alpha_2} \\
& \quad + \frac{4^{p'/p} (2^{\beta_2} \|g_2\|_{L^1} C_1^{\beta_2+1})^{p'}}{p'} \|\dot{u}_1\|_q^{\beta_2 p'} + \frac{4^{p'/p} (2^{\beta_2} \|g_2\|_{L^1} C_1)^{p'}}{p'} |\bar{u}_1|^{\beta_2 p'} \\
& \quad + C_1 \|h_2\|_{L^1} \|\dot{u}_2\|_p
\end{aligned}$$

for all $(u_1, u_2) \in W$. So, one has

$$\begin{aligned}
& \left| \int_0^T (F_2(t, u_1(t), u_2(t)) - F_2(t, \bar{u}_1, \bar{u}_2)) dt \right| \\
& \leq \left| \int_0^T (F_2(t, u_1(t), \bar{u}_2) - F_2(t, \bar{u}_1, \bar{u}_2)) dt \right|
\end{aligned}$$

$$\begin{aligned}
& + \left| \int_0^T (F_2(t, u_1(t), u_2(t)) - F_2(t, u_1(t), \bar{u}_2)) dt \right| \\
& \leq \frac{1}{2q} \|\dot{u}_1\|_q^q + \frac{3}{4p} \|\dot{u}_2\|_p^p + C_1 \|h_1\|_{L^1} \|\dot{u}_1\|_q + C_1 \|h_2\|_{L^1} \|\dot{u}_2\|_p \\
& + 2^{q-1} C_1^{\alpha_1+1} \|f_1\|_{L^1} \|\dot{u}_1\|_q^{\alpha_1+1} + 2^{p-1} C_1^{\alpha_2+1} \|f_2\|_{L^1} \|\dot{u}_2\|_p^{\alpha_2+1} \\
& + \frac{4^{q'/q} (2^{q-1} \|f_1\|_{L^1} C_1)^{q'}}{q'} |\bar{u}_1|^{q'\alpha_1} + \frac{4^{q'/q} (\|g_1\|_{L^1} C_1)^{q'}}{q'} |\bar{u}_2|^{q'\beta_1} \\
& + \frac{4^{p'/p} (2^{p-1} \|f_2\|_{L^1} C_1)^{p'}}{p'} |\bar{u}_2|^{p'\alpha_2} + \frac{4^{p'/p} (2^{\beta_2} \|g_2\|_{L^1} C_1)^{p'}}{p'} |\bar{u}_1|^{p'\beta_2} \\
& + \frac{4^{p'/p} (2^{\beta_2} \|g_2\|_{L^1} C_1^{\beta_2+1})^{p'}}{p'} \|\dot{u}_1\|_q^{\beta_2 p'}
\end{aligned}$$

for all $(u_1, u_2) \in W$. Hence, we obtain from (H0), (2.1) and the above expression that

$$\begin{aligned}
\varphi(u_1, u_2) &= \frac{1}{q} \int_0^T |\dot{u}_1(t)|^q dt + \frac{1}{p} \int_0^T |\dot{u}_2(t)|^p dt + \int_0^T F_1(t, u_1(t), u_2(t)) dt \\
& + \int_0^T (F_2(t, u_1(t), u_2(t)) - F_2(t, \bar{u}_1, \bar{u}_2)) dt + \int_0^T F_2(t, \bar{u}_1, \bar{u}_2) dt \\
& \geq \frac{1}{2q} \|\dot{u}_1\|_q^q + \frac{1}{4p} \|\dot{u}_2\|_p^p - C_1 \|h_1\|_{L^1} \|\dot{u}_1\|_q - C_1 \|h_2\|_{L^1} \|\dot{u}_2\|_p \\
& - 2^{q-1} C_1^{\alpha_1+1} \|f_1\|_{L^1} \|\dot{u}_1\|_q^{\alpha_1+1} - 2^{p-1} C_1^{\alpha_2+1} \|f_2\|_{L^1} \|\dot{u}_2\|_p^{\alpha_2+1} \\
& - \frac{4^{p'/p} (2^{\beta_2} \|g_2\|_{L^1} C_1^{\beta_2+1})^{p'}}{p'} \|\dot{u}_1\|_q^{p'\beta_2} - \frac{4^{q'/q} (2^{q-1} \|f_1\|_{L^1} C_1)^{q'}}{q'} |\bar{u}_1|^{q'\alpha_1} \\
& - \frac{4^{q'/q} (\|g_1\|_{L^1} C_1)^{q'}}{q'} |\bar{u}_2|^{q'\beta_1} - \frac{4^{p'/p} (2^{p-1} \|f_2\|_{L^1} C_1)^{p'}}{p'} |\bar{u}_2|^{p'\alpha_2} \\
& - \frac{4^{p'/p} (2^{\beta_2} \|g_2\|_{L^1} C_1)^{p'}}{p'} |\bar{u}_1|^{\beta_2 p'} + \int_0^T F_2(t, \bar{u}_1, \bar{u}_2) dt \\
& + \frac{1}{\mu} \int_0^T F_1(t, \lambda \bar{u}_1, \lambda \bar{u}_2) dt - \int_0^T F_1(t, -\bar{u}_1, -\bar{u}_2) dt \\
& \geq \frac{1}{2q} \|\dot{u}_1\|_q^q + \frac{1}{4p} \|\dot{u}_2\|_p^p - \frac{4^{p'/p} (2^{\beta_2} \|g_2\|_{L^1} C_1^{\beta_2+1})^{p'}}{p'} \|\dot{u}_1\|_q^{p'\beta_2} \\
& - 2^{q-1} C_1^{\alpha_1+1} \|f_1\|_{L^1} \|\dot{u}_1\|_q^{\alpha_1+1} - 2^{p-1} C_1^{\alpha_2+1} \|f_2\|_{L^1} \|\dot{u}_2\|_p^{\alpha_2+1} \\
& - C_1 \|h_1\|_{L^1} \|\dot{u}_1\|_q - C_1 \|h_2\|_{L^1} \|\dot{u}_2\|_p \\
& - (2^{\beta/2+1} C_1^\beta \mu (\|\dot{u}_1\|_q^\beta + \|\dot{u}_2\|_p^\beta) + 1)(a_{10} + a_{20}) \int_0^T b(t) dt \\
& + (|\bar{u}_1|^{\gamma_1} + |\bar{u}_2|^{\gamma_2}) \left(\frac{1}{|\bar{u}_1|^{\gamma_1} + |\bar{u}_2|^{\gamma_2}} \left(\frac{1}{\mu} \int_0^T F_1(t, \lambda \bar{u}_1, \lambda \bar{u}_2) dt \right) \right. \\
& \left. + \int_0^T F_2(t, \bar{u}_1, \bar{u}_2) dt \right) - 2K - K_0
\end{aligned}$$

for all $(u_1, u_2) \in W$ and some positive constants K and K_0 . It follows that $\varphi(u_1, u_2) \rightarrow +\infty$ as $\|(u_1, u_2)\|_W \rightarrow \infty$ due to (H2). By [4, Theorem 1.1] and Corollary 2.2, The proof is complete. \square

Proof of Theorem 1.4. Firstly, we prove that φ satisfies the (PS) condition. Suppose that $\{(u_{1n}, u_{2n})\}$ is a (PS) sequence for φ , that is, $\varphi'(u_{1n}, u_{2n}) \rightarrow 0$ as $n \rightarrow \infty$ and $\{\varphi(u_{1n}, u_{2n})\}$ is bounded. In a way similar to the proof of Theorem 1.1, we have

$$\begin{aligned} & \left| \int_0^T (\nabla_{x_1} F(t, u_{1n}(t), u_{2n}(t)), \tilde{u}_{1n}(t)) dt \right| \\ & \leq 2^{q-1} C_1^{\alpha_1+1} \|f_1\|_{L^1} \|\dot{u}_{1n}\|_q^{\alpha_1+1} + \frac{3}{4q} \|\dot{u}_{1n}\|_q^q + \frac{4^{q'/q} (2^{q-1} \|f_1\|_{L^1} C_1)^{q'}}{q'} |\bar{u}_{1n}|^{q'\alpha_1} \\ & \quad + \frac{4^{q'/q} (2^{\beta_1} \|g_1\|_{L^1} C_1^{\beta_1+1})^{q'}}{q'} \|\dot{u}_{2n}\|_p^{\beta_1 q'} + \frac{4^{q'/q} (2^{\beta_1} \|g_1\|_{L^1} C_1)^{q'}}{q'} |\bar{u}_{2n}|^{q'\beta_1} \\ & \quad + C_1 \|h_1\|_{L^1} \|\dot{u}_{1n}\|_q \end{aligned}$$

and

$$\begin{aligned} & \left| \int_0^T (\nabla_{x_2} F(t, u_{1n}(t), u_{2n}(t)), \tilde{u}_{2n}(t)) dt \right| \\ & \leq 2^{p-1} C_1^{\alpha_2+1} \|f_2\|_{L^1} \|\dot{u}_{2n}\|_p^{\alpha_2+1} + \frac{3}{4p} \|\dot{u}_{2n}\|_p^p + \frac{4^{p'/p} (2^{p-1} \|f_2\|_{L^1} C_1)^{p'}}{p'} |\bar{u}_{2n}|^{p'\alpha_2} \\ & \quad + \frac{4^{p'/p} (2^{\beta_2} \|g_2\|_{L^1} C_1^{\beta_2+1})^{p'}}{p'} \|\dot{u}_{1n}\|_q^{\beta_2 p'} + \frac{4^{p'/p} (2^{\beta_2} \|g_2\|_{L^1} C_1)^{p'}}{p'} |\bar{u}_{1n}|^{p'\beta_2} \\ & \quad + C_1 \|h_2\|_{L^1} \|\dot{u}_{2n}\|_p \end{aligned}$$

for all n . Hence, one has

$$\begin{aligned} & \|(\tilde{u}_{1n}, \tilde{u}_{2n})\|_W \\ & \geq \langle \varphi'(u_{1n}, u_{2n}), (\tilde{u}_{1n}, \tilde{u}_{2n}) \rangle \\ & = \int_0^T ((\nabla_{x_1} F(t, u_{1n}(t), u_{2n}(t)), \tilde{u}_{1n}(t)) + (|\dot{u}_{1n}(t)|^{q-2} \dot{u}_{1n}(t), \dot{u}_{1n}(t))) \\ & \quad + (\nabla_{x_2} F(t, u_{1n}(t), u_{2n}(t)), \tilde{u}_{2n}(t)) + (|\dot{u}_{2n}(t)|^{p-2} \dot{u}_{2n}(t), \dot{u}_{2n}(t)) dt \\ & \geq \frac{4q-3}{4q} \|\dot{u}_{1n}\|_q^q + \frac{4p-3}{4p} \|\dot{u}_{2n}\|_p^p - 2^{q-1} C_1^{\alpha_1+1} \|f_1\|_{L^1} \|\dot{u}_{1n}\|_q^{\alpha_1+1} \\ & \quad - \frac{4^{q'/q} (2^{\beta_1} \|g_1\|_{L^1} C_1^{\beta_1+1})^{q'}}{q'} \|\dot{u}_{2n}\|_p^{\beta_1 q'} - \frac{4^{q'/q} (2^{q-1} \|f_1\|_{L^1} C_1)^{q'}}{q'} |\bar{u}_{1n}|^{q'\alpha_1} \quad (2.2) \\ & \quad - \frac{4^{q'/q} (2^{\beta_1} \|g_1\|_{L^1} C_1)^{q'}}{q'} |\bar{u}_{2n}|^{q'\beta_1} - 2^{p-1} C_1^{\alpha_2+1} \|f_2\|_{L^1} \|\dot{u}_{2n}\|_p^{\alpha_2+1} \\ & \quad - \frac{4^{p'/p} (2^{\beta_2} \|g_2\|_{L^1} C_1^{\beta_2+1})^{p'}}{p'} \|\dot{u}_{1n}\|_q^{\beta_2 p'} - \frac{4^{p'/p} (2^{p-1} \|f_2\|_{L^1} C_1)^{p'}}{p'} |\bar{u}_{2n}|^{p'\alpha_2} \\ & \quad - \frac{4^{p'/p} (2^{\beta_2} \|g_2\|_{L^1} C_1)^{p'}}{p'} |\bar{u}_{1n}|^{p'\beta_2} - C_1 \|h_2\|_{L^1} \|\dot{u}_{2n}\|_p - C_1 \|h_1\|_{L^1} \|\dot{u}_{1n}\|_q \end{aligned}$$

for large n . It follows from Wirtinger's inequality that

$$\begin{aligned} \|(\tilde{u}_{1n}, \tilde{u}_{2n})\|_W &= \|\tilde{u}_{1n}\|_{W_T^{1,q}} + \|\tilde{u}_{2n}\|_{W_T^{1,p}} \\ &\leq (1 + C_2^q)^{1/q} \|\dot{u}_{1n}\|_q + (1 + C_2^p)^{1/p} \|\dot{u}_{2n}\|_p \\ &\leq \max \{(1 + C_2^q)^{1/q}, (1 + C_2^p)^{1/p}\} (\|\dot{u}_{1n}\|_q + \|\dot{u}_{2n}\|_p) \end{aligned} \quad (2.3)$$

for all n . So, it follows from (2.2) and (2.3) that

$$\begin{aligned} &K(|\bar{u}_{1n}|^{p'\beta_2} + |\bar{u}_{2n}|^{p'\alpha_2} + |\bar{u}_{1n}|^{q'\alpha_1} + |\bar{u}_{2n}|^{q'\beta_1}) \\ &\geq \frac{4^{q'/q}(2^{q-1}\|f_1\|_{L^1}C_1)^{q'}}{q'} |\bar{u}_{1n}|^{q'\alpha_1} + \frac{4^{q'/q}(2^{\beta_1}\|g_1\|_{L^1}C_1)^{q'}}{q'} |\bar{u}_{2n}|^{q'\beta_1} \\ &\quad + \frac{4^{p'/p}(2^{p-1}\|f_2\|_{L^1}C_1)^{p'}}{p'} |\bar{u}_{2n}|^{p'\alpha_2} + \frac{4^{p'/p}(2^{\beta_2}\|g_2\|_{L^1}C_1)^{p'}}{p'} |\bar{u}_{1n}|^{p'\beta_2} \\ &\geq \frac{4q-3}{4q} \|\dot{u}_{1n}\|_q^q + \frac{4p-3}{4p} \|\dot{u}_{2n}\|_p^p \\ &\quad - 2^{q-1} C_1^{\alpha_1+1} \|f_1\|_{L^1} \|\dot{u}_{1n}\|_q^{\alpha_1+1} - \frac{4^{q'/q}(2^{\beta_1}\|g_1\|_{L^1}C_1^{\beta_1+1})^{q'}}{q'} \|\dot{u}_{2n}\|_p^{\beta_1 q'} \\ &\quad - 2^{p-1} C_1^{\alpha_2+1} \|f_2\|_{L^1} \|\dot{u}_{2n}\|_p^{\alpha_2+1} - \frac{4^{p'/p}(2^{\beta_2}\|g_2\|_{L^1}C_1^{\beta_2+1})^{p'}}{p'} \|\dot{u}_{1n}\|_q^{\beta_2 p'} \\ &\quad - C_1 \|h_2\|_{L^1} \|\dot{u}_{2n}\|_p - C_1 \|h_1\|_{L^1} \|\dot{u}_{1n}\|_q - \|(\tilde{u}_{1n}, \tilde{u}_{2n})\|_W \\ &\geq \frac{4q-3}{4q} \|\dot{u}_{1n}\|_q^q + \frac{4p-3}{4p} \|\dot{u}_{2n}\|_p^p - C_1 \|h_2\|_{L^1} \|\dot{u}_{2n}\|_p - C_1 \|h_1\|_{L^1} \|\dot{u}_{1n}\|_q \\ &\quad - 2^{q-1} C_1^{\alpha_1+1} \|f_1\|_{L^1} \|\dot{u}_{1n}\|_q^{\alpha_1+1} - \frac{4^{q'/q}(2^{\beta_1}\|g_1\|_{L^1}C_1^{\beta_1+1})^{q'}}{q'} \|\dot{u}_{2n}\|_p^{\beta_1 q'} \\ &\quad - 2^{p-1} C_1^{\alpha_2+1} \|f_2\|_{L^1} \|\dot{u}_{2n}\|_p^{\alpha_2+1} - \frac{4^{p'/p}(2^{\beta_2}\|g_2\|_{L^1}C_1^{\beta_2+1})^{p'}}{p'} \|\dot{u}_{1n}\|_q^{\beta_2 p'} \\ &\quad - (1 + C_2^p)^{1/p} \|\dot{u}_{2n}\|_p - (1 + C_2^q)^{1/q} \|\dot{u}_{1n}\|_q \\ &\geq \frac{q-1}{q} \|\dot{u}_{1n}\|_q^q + \frac{p-1}{p} \|\dot{u}_{2n}\|_p^p - K_1 \\ &= \frac{1}{q'} \|\dot{u}_{1n}\|_q^q + \frac{1}{p'} \|\dot{u}_{2n}\|_p^p - K_1 \end{aligned}$$

for large n and some positive constant K_1 . Hence, by the above expression, we obtain

$$2K(|\bar{u}_{1n}|^{\gamma_1} + |\bar{u}_{2n}|^{\gamma_2}) \geq \min \left\{ \frac{1}{q'}, \frac{1}{p'} \right\} (\|\dot{u}_{1n}\|_q^q + \|\dot{u}_{2n}\|_p^p) - K_2 \quad (2.4)$$

for large n and some positive constant K_2 . By the proof of Theorem 1.1, we have

$$\begin{aligned} &\left| \int_0^T (F(t, u_{1n}(t), u_{2n}(t)) - F(t, \bar{u}_{1n}, \bar{u}_{2n})) dt \right| \\ &\leq \frac{1}{2q} \|\dot{u}_{1n}\|_q^q + \frac{3}{4p} \|\dot{u}_{2n}\|_p^p + C_1 \|h_1\|_{L^1} \|\dot{u}_{1n}\|_q + C_1 \|h_2\|_{L^1} \|\dot{u}_{2n}\|_p \\ &\quad + 2^{q-1} C_1^{\alpha_1+1} \|f_1\|_{L^1} \|\dot{u}_{1n}\|_q^{\alpha_1+1} + 2^{p-1} C_1^{\alpha_2+1} \|f_2\|_{L^1} \|\dot{u}_{2n}\|_p^{\alpha_2+1} \\ &\quad + \frac{4^{q'/q}(2^{q-1}\|f_1\|_{L^1}C_1)^{q'}}{q'} |\bar{u}_{1n}|^{q'\alpha_1} + \frac{4^{q'/q}(\|g_1\|_{L^1}C_1)^{q'}}{q'} |\bar{u}_{2n}|^{q'\beta_1} \end{aligned}$$

$$\begin{aligned}
& + \frac{4^{p'/p}(2^{p-1}\|f_2\|_{L^1}C_1)^{p'}}{p'}|\bar{u}_{2n}|^{p'\alpha_2} + \frac{4^{p'/p}(2^{\beta_2}\|g_2\|_{L^1}C_1)^{p'}}{p'}|\bar{u}_{1n}|^{p'\beta_2} \\
& + \frac{4^{p'/p}(2^{\beta_2}\|g_2\|_{L^1}C_1^{\beta_2+1})^{p'}}{p'}\|\dot{u}_{1n}\|_q^{\beta_2 p'}
\end{aligned}$$

for all n . It follows from the boundedness of $\{\varphi(u_{1n}, u_{2n})\}$, (2.4) and the above inequality that

$$\begin{aligned}
K_3 & \leq \varphi(u_{1n}, u_{2n}) \\
& = \frac{1}{q} \int_0^T |\dot{u}_{1n}(t)|^q dt + \frac{1}{p} \int_0^T |\dot{u}_{2n}(t)|^p dt \\
& \quad + \int_0^T [F(t, u_{1n}(t), u_{2n}(t)) - F(t, \bar{u}_{1n}, \bar{u}_{2n})] dt + \int_0^T F(t, \bar{u}_{1n}, \bar{u}_{2n}) dt \\
& \leq \frac{3}{2q} \|\dot{u}_{1n}\|_q^q + \frac{7}{4p} \|\dot{u}_{2n}\|_p^p + C_1 \|h_1\|_{L^1} \|\dot{u}_{1n}\|_q + C_1 \|h_2\|_{L^1} \|\dot{u}_{2n}\|_p \\
& \quad + 2^{q-1} C_1^{\alpha_1+1} \|f_1\|_{L^1} \|\dot{u}_{1n}\|_q^{\alpha_1+1} + 2^{p-1} C_1^{\alpha_2+1} \|f_2\|_{L^1} \|\dot{u}_{2n}\|_p^{\alpha_2+1} \\
& \quad + \frac{4^{q'/q}(2^{q-1}\|f_1\|_{L^1}C_1)^{q'}}{q'} |\bar{u}_{1n}|^{q'\alpha_1} + \frac{4^{q'/q}(\|g_1\|_{L^1}C_1)^{q'}}{q'} |\bar{u}_{2n}|^{q'\beta_1} \\
& \quad + \frac{4^{p'/p}(2^{p-1}\|f_2\|_{L^1}C_1)^{p'}}{p'} |\bar{u}_{2n}|^{p'\alpha_2} + \frac{4^{p'/p}(2^{\beta_2}\|g_2\|_{L^1}C_1)^{p'}}{p'} |\bar{u}_{1n}|^{p'\beta_2} \\
& \quad + \frac{4^{p'/p}(2^{\beta_2}\|g_2\|_{L^1}C_1^{\beta_2+1})^{p'}}{p'} \|\dot{u}_{1n}\|_q^{\beta_2 p'} + \int_0^T F(t, \bar{u}_{1n}, \bar{u}_{2n}) dt \\
& \leq 2(\|\dot{u}_{1n}\|_q^q + \|\dot{u}_{2n}\|_p^p) + 2K(|\bar{u}_{1n}|^{\gamma_1} + |\bar{u}_{2n}|^{\gamma_2}) + \int_0^T F(t, \bar{u}_{1n}, \bar{u}_{2n}) dt + K_4 \\
& \leq (2 \max\{q', p'\} + 1)2K(|\bar{u}_{1n}|^{\gamma_1} + |\bar{u}_{2n}|^{\gamma_2}) + \int_0^T F(t, \bar{u}_{1n}, \bar{u}_{2n}) dt + K_5 \\
& \leq (2q' + 2p' + 1)2K(|\bar{u}_{1n}|^{\gamma_1} + |\bar{u}_{2n}|^{\gamma_2}) + \int_0^T F(t, \bar{u}_{1n}, \bar{u}_{2n}) dt + K_5 \\
& \leq (|\bar{u}_{1n}|^{\gamma_1} + |\bar{u}_{2n}|^{\gamma_2}) \left(\frac{1}{|\bar{u}_{1n}|^{\gamma_1} + |\bar{u}_{2n}|^{\gamma_2}} \int_0^T F(t, \bar{u}_{1n}, \bar{u}_{2n}) dt \right. \\
& \quad \left. + (2q' + 2p' + 1)2K \right) + K_5
\end{aligned}$$

for large n and some real constants K_3 , K_4 and K_5 . The above inequality and (H3) imply that $(|\bar{u}_{1n}|^{\gamma_1} + |\bar{u}_{2n}|^{\gamma_2})$ is bounded. Hence, (u_{1n}, u_{2n}) is bounded by (2.3) and (2.4). By the compactness of the embedding $W_T^{1,p}$ (or $W_T^{1,q}$) $\subset C(0, T; \mathbb{R}^N)$, the sequence $\{u_{1n}\}$ (or $\{u_{2n}\}$) has a subsequence, still denoted by $\{u_{1n}\}$ (or $\{u_{2n}\}$), such that

$$u_{1n} \text{ (or } u_{2n}) \rightharpoonup u_1 \text{ (or } u_2) \quad \text{weakly in } W_T^{1,p} \text{ (or in } W_T^{1,q}), \quad (2.5)$$

$$u_{1n} \text{ (or } u_{2n}) \rightarrow u_1 \text{ (or } u_2) \quad \text{strongly in } C(0, T; \mathbb{R}^N). \quad (2.6)$$

Note that

$$\begin{aligned} & \langle \varphi'(u_{1n}, u_{2n}), (u_1 - u_{1n}, 0) \rangle \\ &= \int_0^T |\dot{u}_{1n}(t)|^{p-2} (\dot{u}_{1n}(t), \dot{u}_1 - \dot{u}_{1n}(t)) dt \\ &\quad - \int_0^T (\nabla_{x_1} F(t, u_{1n}(t), u_{2n}(t)), u_1(t) - u_{1n}(t)) dt \rightarrow 0 \end{aligned} \tag{2.7}$$

as $n \rightarrow \infty$. From (2.6), $\{u_{1n}\}$ is bounded in $C(0, T; \mathbb{R}^N)$. Then we have

$$\begin{aligned} & \left| \int_0^T (\nabla_{x_1} F(t, u_{1n}(t), u_{2n}(t)), u_1(t) - u_{1n}(t)) dt \right| \\ & \leq \int_0^T |\nabla_{x_1} F(t, u_{1n}(t), u_{2n}(t))| \cdot |u_1(t) - u_{1n}(t)| dt \\ & \leq K_6 \int_0^T b(t) |u_1(t) - u_{1n}(t)| dt \\ & \leq K_6 \|b\|_{L^1} \|u_1 - u_{1n}\|_\infty \end{aligned}$$

for some positive constant K_6 , which combines with (2.6) implies that

$$\int_0^T (\nabla_{x_1} F(t, u_{1n}(t), u_{2n}(t)), u_1(t) - u_{1n}(t)) dt \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

Hence, by (2.7), one has

$$\int_0^T |\dot{u}_{1n}(t)|^{p-2} (\dot{u}_{1n}(t), \dot{u}_1(t) - \dot{u}_{1n}(t)) dt \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

Moreover, from (2.6) we obtain

$$\int_0^T |u_{1n}(t)|^{p-2} (u_{1n}(t), u_1(t) - u_{1n}(t)) dt \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

Setting

$$\psi(u_1, u_2) = \frac{1}{p} \int_0^T (|u_1(t)|^p + |\dot{u}_1(t)|^p) dt + \frac{1}{q} \int_0^T (|u_2(t)|^q + |\dot{u}_2(t)|^q) dt,$$

one obtains

$$\begin{aligned} \langle \psi'(u_{1n}, u_{2n}), (u_1 - u_{1n}, 0) \rangle &= \int_0^T |u_{1n}(t)|^{p-2} (u_{1n}(t), u_1(t) - u_{1n}(t)) dt \\ &\quad + \int_0^T |\dot{u}_{1n}(t)|^{p-2} (\dot{u}_{1n}(t), \dot{u}_1(t) - \dot{u}_{1n}(t)) dt \end{aligned}$$

and

$$\langle \psi'(u_{1n}, u_{2n}), (u_1 - u_{1n}, 0) \rangle \rightarrow 0 \quad \text{as } n \rightarrow \infty. \tag{2.8}$$

By the Hölder's inequality, we have

$$0 \leq (\|u_{1n}\|^{p-1} - \|u_1\|^{p-1})(\|u_{1n}\| - \|u_1\|) \leq \langle \psi'(u_{1n}, u_{2n}) - \psi'(u_1, u_2), (u_1 - u_{1n}, 0) \rangle,$$

which together with (2.8) yields $\|u_{1n}\| \rightarrow \|u_1\|$. It follows that $u_{1n} \rightarrow u_1$ strongly in $W_T^{1,p}$ by the uniform convexity of $W_T^{1,p}$. Similarly, we have $u_{2n} \rightarrow u_2$ strongly in $W_T^{1,q}$. Hence, the (PS) condition is satisfied.

Let $\widetilde{W} = \widetilde{W}_T^{1,q} \times \widetilde{W}_T^{1,p}$ be the subspace of W given by

$$\widetilde{W} = \{(u_1, u_2) \in W \mid (\bar{u}_1, \bar{u}_2) = (0, 0)\}.$$

Then

$$\varphi(u_1, u_2) \rightarrow +\infty \quad (2.9)$$

as $\|(u_1, u_2)\|_W \rightarrow \infty$ in \widetilde{W} . In fact, by the proof of Theorem 1.1, one has

$$\begin{aligned} \varphi(u_1, u_2) &= \frac{1}{q} \int_0^T |\dot{u}_1(t)|^q dt + \frac{1}{p} \int_0^T |\dot{u}_2(t)|^p dt \\ &\quad + \int_0^T (F(t, u_1(t), u_2(t)) - F(t, \bar{u}_1, \bar{u}_2)) dt + \int_0^T F(t, \bar{u}_1, \bar{u}_2) dt \\ &\geq \frac{1}{2q} \|\dot{u}_1\|_q^q + \frac{1}{4p} \|\dot{u}_2\|_p^p - 2^{q-1} C_1^{\alpha_1+1} \|f_1\|_{L^1} \|\dot{u}_1\|_q^{\alpha_1+1} \\ &\quad - 2^{p-1} C_1^{\alpha_2+1} \|f_2\|_{L^1} \|\dot{u}_2\|_p^{\alpha_2+1} - \frac{4^{p'/p} (2^{\beta_2} \|g_2\|_{L^1} C_1^{\beta_2+1})^{p'}}{p'} \|\dot{u}_1\|_q^{\beta_2 p'} \\ &\quad - C_1 \|h_1\|_{L^1} \|\dot{u}_1\|_q - C_1 \|h_2\|_{L^1} \|\dot{u}_2\|_p + \int_0^T F(t, \bar{u}_1, \bar{u}_2) dt \end{aligned}$$

for all $(u_1, u_2) \in \widetilde{W}$. By Wirtinger's inequality, the norm

$$\| (u_1, u_2) \| = \| (\dot{u}_1, \dot{u}_2) \|_{L^q \times L^p} = \|\dot{u}_1\|_q + \|\dot{u}_2\|_p$$

is an equivalent norm on \widetilde{W} . Hence, (2.9) follows from the above inequality.

On the other hand, one has

$$\varphi(x_1, x_2) \rightarrow -\infty \quad (2.10)$$

as $|(x_1, x_2)| \rightarrow \infty$ in $\mathbb{R}^N \times \mathbb{R}^N$, which follows from (H3). Now, Theorem 1.4 is proved by (2.9), (2.10) and the Saddle Point Theorem (see [11, Theorem 4.6]). \square

Acknowledgements. This research was supported by the National Natural Science Foundation of China (No. 11071198) and the Fundamental Research Funds for the Central Universities (No. XDJK2010C055).

REFERENCES

- [1] M. S. Berger, M. Schechter; *On the solvability of semilinear gradient operator equations*, Adv. Math. 25 (1977), 97-132.
- [2] Y.-M. Long; *Nonlinear oscillations for classical Hamiltonian systems with bi-even sub-quadratic potentials*, Nonlinear Anal. 24 (12) (1995), 1665-1671.
- [3] J. Mawhin; *Semi-coercive monotone variational problems*, Acad. Roy. Belg. Bull. Cl. Sci. 73 (1987), 118-130.
- [4] J. Mawhin, M. Willem; *Critical Point Theory and Hamiltonian Systems*, Springer-Verlag, Berlin/New York, 1989.
- [5] D. Paşa; *Periodic solutions for second order differential inclusions with sublinear nonlinearity*, PanAmer. Math. J. 10(4) (2000), 35-45.
- [6] D. Paşa; *Periodic solutions for nonautonomous second order differential inclusions systems with p -Laplacian*, Commun. Appl. Nonlinear Anal. 16(2) (2009), 13-23.
- [7] D. Paşa; *Periodic solutions of a class of nonautonomous second order differential systems with (q,p) -Laplacian*, Bull. Belg. Math. Soc. Simon Stevin 17 (2010), no. 5, 841-850.
- [8] D. Paşa; *Periodic solutions of second-order differential inclusions systems with (q,p) -Laplacian*, Anal. Appl. (Singap.) 9 (2011), no. 2, 201-223.
- [9] D. Paşa, C.-L. Tang; *Some existence results on periodic solutions of nonautonomous second-order differential systems with (q,p) -Laplacian*, Appl. Math. Lett. 23 (2010), 246-251.

- [10] D. Pașca, C.-L. Tang; *Some existence results on periodic solutions of ordinary (q,p) -Laplacian systems*, J. Appl. Math. Inform. 29 (2011), no. 1-2, 39-48.
- [11] P. H. Rabinowitz; *Minimax methods in critical point theory with applications to differential equations*, CBMS Reg. Conf. Ser. in Math. No. 65, AMS, Providence, RI, 1986.
- [12] C.-L. Tang; *Periodic solutions of nonautonomous second order systems with γ -quasi-subadditive potential*, J. Math. Anal. Appl. 189 (1995), 671-675.
- [13] C.-L. Tang; *Periodic solutions of nonautonomous second order systems*, J. Math. Anal. Appl. 202 (1996), 465-469.
- [14] C.-L. Tang; *Periodic solutions for nonautonomous second order systems with sublinear nonlinearity*, Proc. Amer. Math. Soc. 126(11) (1998), 3263-3270.
- [15] C.-L. Tang, X. P. Wu; *Periodic solutions for second order systems with not uniformly coercive potential*, J. Math. Anal. Appl. 259 (2001), 386-397.
- [16] X. H. Tang, Q. Meng; *Solutions of a second-order Hamiltonian system with periodic boundary conditions*, Nonlinear Anal. 11 (2010) 3722-3733.
- [17] Y. Tian, W. Ge; *Periodic solutions of non-autonomous second-order systems with a p -Laplacian*, Nonlinear Anal. 66 (1) (2007), 192-203.
- [18] M. Willem; *Oscillations forcées de systèmes hamiltoniens*, in: Public. Sémin. Analyse Non Linéaire, Univ. Besançon, 1981.
- [19] X.-P. Wu, C.-L. Tang; *Periodic solutions of a class of nonautonomous second order systems*, J. Math. Anal. Appl. 236 (1999), 227-235.

CHUN LI

SCHOOL OF MATHEMATICS AND STATISTICS, SOUTHWEST UNIVERSITY, CHONGQING 400715, CHINA
E-mail address: Lch1999@swu.edu.cn

ZENG-QI OU

SCHOOL OF MATHEMATICS AND STATISTICS, SOUTHWEST UNIVERSITY, CHONGQING 400715, CHINA
E-mail address: ouzengq707@sina.com

CHUN-LEI TANG (CORRESPONDING AUTHOR)

SCHOOL OF MATHEMATICS AND STATISTICS, SOUTHWEST UNIVERSITY, CHONGQING 400715, CHINA
 TEL +86 23 68253135, FAX +86 23 68253135
E-mail address: tangc1@swu.edu.cn