

## EXISTENCE OF PERIODIC SOLUTIONS FOR SUB-LINEAR FIRST-ORDER HAMILTONIAN SYSTEMS

MOHSEN TIMOUMI

ABSTRACT. We prove the existence solutions for the sub-linear first-order Hamiltonian system  $J\dot{u}(t) + Au(t) + \nabla H(t, u(t)) = h(t)$  by using the least action principle and a version of the Saddle Point Theorem.

### 1. INTRODUCTION

In this article, we consider the first-order Hamiltonian system

$$J\dot{u}(t) + Au(t) + \nabla H(t, u(t)) = h(t) \quad (1.1)$$

where  $A$  is a  $(2N \times 2N)$  symmetric matrix,  $H \in C^1(\mathbb{R} \times \mathbb{R}^{2N}, \mathbb{R})$  is  $T$ -periodic in the first variable ( $T > 0$ ) and  $h \in C(\mathbb{R}, \mathbb{R}^{2N})$  is  $T$ -periodic.

When  $A = 0$  and  $h = 0$ , it has been proved that system (1.1) has at least one  $T$ -periodic solution by the use of critical point theory and minimax methods [1, 2, 3, 4, 5, 6, 7, 13, 15, 16]. Many solvability conditions are given, such as the convex condition (see [3,5]), the super-quadratic condition (see [1, 4, 6, 7, 9, 12, 13, 16]), the sub-linear condition (see [2, 15]). When  $A$  is not identically null, the existence of periodic solutions for (1.1) has been studied in [7, 14]. In all these last papers, the Hamiltonian is assumed to be super-quadratic. As far as the general case ( $A$  not identically null) is concerned, to our best knowledge, there is no research about the existence of periodic solutions for (1.1) when  $H$  is sub-linear. In [2], the authors considered the special case  $A = 0$  and  $h = 0$  and obtain the existence of subharmonic solutions for (1.1) under the following assumptions:

(A1) There exist constants  $a, b, c > 0$ ,  $\alpha \in [0, 1[$ , functions  $p \in L^{\frac{2}{1-\alpha}}(0, T; \mathbb{R}^+)$ ,  $q \in L^2(0, T; \mathbb{R}^+)$  and a nondecreasing function  $\gamma \in C(\mathbb{R}^+, \mathbb{R}^+)$  with the following properties:

- (i)  $\gamma(s + t) \leq c(\gamma(s) + \gamma(t))$  for all  $s, t \in \mathbb{R}^+$ ,
- (ii)  $\gamma(t) \leq at^\alpha + b$  for all  $t \in \mathbb{R}^+$ ,
- (iii)  $\gamma(t) \rightarrow +\infty$  as  $t \rightarrow +\infty$ , such that

$$|\nabla H(t, x)| \leq p(t)\gamma(|x|) + q(t), \quad \forall x \in \mathbb{R}^{2N}, \text{ a.e. } t \in [0, T];$$

---

2010 *Mathematics Subject Classification.* 34C25.

*Key words and phrases.* Hamiltonian systems; periodic solutions; saddle point theorem; least action principle; sub-linear conditions.

©2015 Texas State University - San Marcos.

Submitted March 13, 2014. Published May 15, 2015.

$$\lim_{|x| \rightarrow \infty} \frac{1}{\gamma^2(|x|)} \int_0^T H(t, x) dt = \pm \infty.$$

Similarly, in [15] the author considered the case  $A = 0$  and  $h = 0$  and obtained the existence of subharmonic solutions for (1.1) under the following assumptions:

(A2) There exist a positive constant  $a$ ,  $g \in L^2(0, T; \mathbb{R})$  and a non-increasing function  $\omega \in C(\mathbb{R}^+, \mathbb{R}^+)$  with the properties:

$$\begin{aligned} \liminf_{s \rightarrow \infty} \frac{\omega(s)}{\omega(\sqrt{s})} &> 0, \\ \omega(s) \rightarrow 0, \quad \omega(s)s \rightarrow \infty &\text{ as } s \rightarrow \infty, \end{aligned}$$

such that

$$\begin{aligned} |\nabla H(t, x)| &\leq a\omega(|x|)|x| + g(t), \quad \forall x \in \mathbb{R}^{2N}, \text{ a.e. } t \in [0, T]; \\ \frac{1}{[\omega(|x|)|x|]^2} \int_0^T H(t, x) dt &\rightarrow +\infty \text{ as } |x| \rightarrow \infty. \end{aligned}$$

In Sections 4,5, we will use the Least Action Principle and a version of the Saddle Point Theorem to study the existence of periodic solutions for (1.1), when  $A$  and  $h$  are not necessary null and  $H$  satisfies some more general variants conditions replacing conditions (A1), (A2).

## 2. PRELIMINARIES

Let  $T > 0$  and  $A$  be a  $(2N \times 2N)$  symmetric matrix. Consider the Hilbert space  $H^{1/2}(S^1, \mathbb{R}^{2N})$  where  $S^1 = \mathbb{R}/(T\mathbb{Z})$  and the continuous quadratic form  $Q$  defined on  $E$  by

$$Q(u) = \frac{1}{2} \int_0^T (J\dot{u}(t) \cdot u(t) + Au(t) \cdot u(t)) dt$$

where  $x \cdot y$  is the inner product of  $x, y \in \mathbb{R}^{2N}$ . Let us denote by  $E^0, E^-, E^+$  respectively the subspaces of  $E$  on which  $Q$  is null, negative definite and positive definite. It is well known that these subspaces are mutually orthogonal in  $L^2(S^1, \mathbb{R}^{2N})$  and in  $E$  with respect to the bilinear form

$$B(u, v) = \frac{1}{2} \int_0^T (J\dot{u}(t) \cdot v(t) + Au(t) \cdot v(t)) dt, \quad u, v \in E$$

associated with  $Q$ . If  $u \in E^+$  and  $v \in E^-$ , then  $B(u, v) = 0$  and  $Q(u + v) = Q(u) + Q(v)$ .

For  $u = u^- + u^0 + u^+ \in E$ , the expression  $\|u\| = [Q(u^+) - Q(u^-) + |u^0|^2]^{1/2}$  is an equivalent norm in  $E$ . It is well known that the space  $E$  is compactly embedded in  $L^s(S^1, \mathbb{R}^{2N})$  for all  $s \in [1, \infty[$ . In particular, for all  $s \in [1, \infty[$ , there exists  $\lambda_s > 0$  such that for all  $u \in E$ ,

$$\|u\|_{L^s} \leq \lambda_s \|u\|. \quad (2.1)$$

Next, we have a version of the Saddle Point Theorem [11].

**Lemma 2.1.** *Let  $E = E^1 \oplus E^2$  be a real Hilbert space with  $E^2 = (E^1)^\perp$ . Suppose that  $f \in C^1(E, \mathbb{R})$  satisfies*

- $f(u) = \frac{1}{2} \langle Lu, u \rangle + g(u)$  and  $Lu = L_1 P_1 u + L_2 P_2 u$  with  $L_i : E^i \rightarrow E^i$  bounded and self-adjoint,  $i = 1, 2$ ;
- $g'$  is compact;
- There exists  $\beta \in \mathbb{R}$  such that  $f(u) \leq \beta$  for all  $u \in E^1$ ;

(d) *There exists  $\gamma \in \mathbb{R}$  such that  $f(u) \geq \gamma$  for all  $u \in E^2$ .*

*Furthermore, if  $f$  satisfies the Palais-Smale condition  $(PS)_c$  for all  $c \geq \gamma$ , then  $f$  possesses a critical value  $c \in [\gamma, \beta]$ .*

### 3. LINEAR HAMILTONIAN SYSTEMS

Let  $A$  be a  $(2N \times 2N)$  symmetric matrix, we consider the linear Hamiltonian system

$$\dot{x} = JAx. \tag{3.1}$$

Let  $\lambda_1, \dots, \lambda_s$  be all the distinct eigenvalues of  $B = JA$  and  $F_1, \dots, F_s$  be the corresponding root subspaces. The dimension of the root subspace  $F_\sigma$  is equal to the multiplicity  $m_\sigma$  of the corresponding root  $\lambda_\sigma$  of the characteristic equation  $\det(B - \lambda I_{2N}) = 0$  ( $m_1 + \dots + m_s = 2N$ ). The space  $\mathbb{R}^{2N}$  splits into a direct sum of the  $B$ -invariant subspaces  $F_\sigma$ :

$$\mathbb{R}^{2N} = F_1 \oplus \dots \oplus F_s. \tag{3.2}$$

Each subspace  $F_\sigma$  possesses a basis  $(a_1^\sigma, \dots, a_{m_\sigma}^\sigma)$  satisfying

$$Ba_1^\sigma = \lambda_\sigma a_1^\sigma, Ba_2^\sigma = \lambda_\sigma a_2^\sigma + a_1^\sigma, \dots, Ba_{m_\sigma}^\sigma = \lambda_\sigma a_{m_\sigma}^\sigma + a_{m_\sigma-1}^\sigma.$$

The  $(m_\sigma \times m_\sigma)$  matrix

$$Q_\sigma(\lambda_\sigma) = \begin{pmatrix} \lambda_\sigma & 1 & 0 & 0 & \dots & 0 \\ 0 & \lambda_\sigma & 1 & 0 & \dots & 0 \\ \cdot & \cdot & \cdot & \cdot & \dots & \cdot \\ 0 & 0 & 0 & \dots & \lambda_\sigma & 1 \\ 0 & 0 & 0 & \dots & 0 & \lambda_\sigma \end{pmatrix}$$

is called an elementary Jordan matrix. We have  $B = SQS^{-1}$  where  $Q$  is a direct sum of elementary Jordan matrices

$$Q = \begin{pmatrix} Q_1(\lambda_1) & 0 & 0 & \dots & 0 \\ 0 & Q_2(\lambda_2) & 0 & \dots & 0 \\ \cdot & \cdot & \cdot & \dots & \cdot \\ \cdot & 0 & 0 & \dots & Q_s(\lambda_s) \end{pmatrix} = Q_1(\lambda_1) \oplus \dots \oplus Q_s(\lambda_s)$$

the columns of the matrix  $S$ ,

$$a_1^1, \dots, a_{m_1}^1; a_1^2, \dots, a_{m_2}^2; \dots; a_1^s, \dots, a_{m_s}^s$$

form a basis for  $\mathbb{R}^{2N}$  and so  $\det(S) \neq 0$ .

The matrizant of equation (3.1) is given by

$$R(t) = e^{tB} = S[\exp(tQ_1(\lambda_1)) \oplus \dots \oplus \exp(tQ_s(\lambda_s))]S^{-1} = Se^{tQ}S^{-1}.$$

then the solution of equation (3.1) with initial condition  $x(0)$  is

$$x(t) = e^{tB}x(0).$$

Therefore to each eigenvalue  $\lambda_\sigma$  corresponds a group of  $m_\sigma$ -linearly independent solutions:

$$\begin{aligned} x_1^\sigma(t) &= e^{\lambda_\sigma t} a_1^\sigma \\ x_2^\sigma(t) &= e^{\lambda_\sigma t} (ta_1^\sigma + a_2^\sigma) \\ &\dots \\ x_{m_\sigma}^\sigma(t) &= e^{\lambda_\sigma t} \left( \frac{1}{(m_\sigma - 1)!} t^{m_\sigma - 1} a_1^\sigma + \dots + a_{m_\sigma}^\sigma \right). \end{aligned} \tag{3.3}$$

Moreover, combining the solutions of all the groups (3.3) (there are obviously  $2N$  in all, since  $m_1 + \dots + m_s = 2N$ ), we obtain a complete system of linearly independent solutions of (3.1). Now, assume that  $\lambda_1 = 0$  is an eigenvalue of  $B = JA$  and let  $1 \leq m \leq m_1$  be the dimension of the corresponding eigenspace  $E_1$ . We can replace the basis  $(a_1^1, \dots, a_{m_1}^1)$  of the root subspace  $F_1$  by the basis  $(b_1^1, \dots, b_{m_1}^1)$  where  $(b_1^1, \dots, b_m^1)$  is a basis of  $E_1$ ,  $b_j^1 = a_j^1$  for  $m+1 \leq j \leq m_1$  and such that  $b_{m+1}^1 = Bb_m^1$ . To this basis corresponds the group of  $2N$  linearly independent solutions:

$$\begin{aligned} u_1^1(t) &= b_1^1 \\ &\dots \\ u_m^1(t) &= b_m^1 \\ u_{m+1}^1(t) &= b_m^1 t + b_{m+1}^1 \\ &\dots \\ u_{m_1}^1(t) &= \frac{1}{(m_1 - m)!} b_m^1 t^{m_1 - m} + \dots + b_{m_1}^1 \\ u_k^\sigma(t) &= x_k^\sigma(t), \quad 2 \leq \sigma \leq s, \quad 1 \leq k \leq m_\sigma. \end{aligned} \tag{3.4}$$

A solution  $u$  of (3.1) may be written in the form

$$u(t) = \sum_{\sigma=1}^s \sum_{j=1}^{m_\sigma} \alpha_j^\sigma u_j^\sigma(t).$$

Let  $T > 0$  be such that  $\lambda_\sigma T \notin 2i\pi\mathbb{Z}$  for all  $1 \leq \sigma \leq s$ . If  $u$  is  $T$ -periodic, then for any  $1 \leq \sigma \leq s$ , we have

$$\sum_{j=1}^{m_\sigma} \alpha_j^\sigma u_j^\sigma(kT) = \sum_{j=1}^{m_\sigma} \alpha_j^\sigma u_j^\sigma(0), \quad \forall k \in \mathbb{Z}.$$

It is easy to see that  $\alpha_j^1 = 0$  for  $m+1 \leq j \leq m_1$  and  $\alpha_j^\sigma = 0$  for  $2 \leq \sigma \leq s$  and  $1 \leq j \leq m_{m_\sigma}$ . Therefore,  $u(t) = \sum_{j=1}^m \alpha_j^1 b_j^1$ . Hence the set of  $T$ -periodic solutions of (3.1) is equal to  $N(A)$ .

**Example 3.1.** Let

$$A = \begin{pmatrix} -12 & 6 & 5 & 1 \\ -2 & 1 & 0 & 1 \\ 2 & -1 & 0 & -1 \\ 2 & -1 & 0 & -1 \end{pmatrix}$$

The characteristic equation corresponding to  $B = JA$  is  $\det(JA - XI_4) = X^3(X - 5) = 0$ . To the eigenvalue  $\lambda_1 = 0$  corresponds the eigenspace

$$E_1 = \text{span}\{e_1, e_2\}$$

and the root subspace

$$F_1 = \text{span}\{e_1, e_2, e_3\}$$

where  $e_1 = (1, 2, 0, 0)$ ,  $e_2 = (1, 1, 1, 1)$ ,  $e_3 = (0, 0, 0, 1)$  with  $Be_3 = e_2$ . To the eigenvalue  $\lambda_2 = 5$  corresponds the root subspace

$$E_2 = F_2 = \text{span}\{e_4\},$$

where  $e_4 = (0, 0, 1, 0)$ . Then we have  $JA = SQS^{-1}$  with

$$S = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 2 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{pmatrix}, \quad Q = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 5 \end{pmatrix}$$

The matrizant of the corresponding equation (3.1) is then

$$R(t) = SQS^{-1} = S \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & t & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & e^{5t} \end{pmatrix} S^{-1}.$$

To the basis  $(e_1, e_2, e_3, e_4)$  corresponds the group of 4-linearly independent solutions

$$\begin{aligned} u_1(t) &= e_1 \\ u_2(t) &= e_2 \\ u_3(t) &= te_2 + e_3 \\ u_4(t) &= e^{5t}e_4. \end{aligned} \tag{3.5}$$

A solution of equation (3.1) takes the form

$$u(t) = \alpha_1 u_1(t) + \alpha_2 u_2(t) + \alpha_3 u_3(t) + \alpha_4 u_4(t)$$

and it is easy to verify that  $u$  is  $T$ -periodic for  $T > 0$  if and only if  $\alpha_3 = \alpha_4 = 0$ , i.e.  $u \in N(A)$ .

#### 4. FIRST CLASS OF SUB-LINEAR HAMILTONIAN SYSTEMS

Consider the first-order Hamiltonian system

$$J\dot{u}(t) + Au(t) + \nabla H(t, u(t)) = h(t) \tag{4.1}$$

where  $A$  is a  $(2N \times 2N)$  symmetric matrix,  $H : \mathbb{R} \times \mathbb{R}^{2N} \rightarrow \mathbb{R}$  is a continuous function,  $T$ -periodic in the first variable ( $T > 0$ ) and differentiable with respect to the second variable with continuous derivative  $\nabla H(t, x) = \frac{\partial H}{\partial x}(t, x)$ ,  $h \in C(\mathbb{R}, \mathbb{R}^{2N})$  is  $T$ -periodic and  $J$  is the standard symplectic matrix  $J = \begin{pmatrix} 0 & -I \\ I & 0 \end{pmatrix}$ . Let  $\gamma : \mathbb{R}^+ \rightarrow \mathbb{R}^+$  be a nondecreasing continuous function satisfying the properties:

- (i)  $\gamma(s+t) \leq c(\gamma(s) + \gamma(t))$  for all  $s, t \in \mathbb{R}^+$ ,
- (ii)  $\gamma(t) \leq at^\alpha + b$  for all  $t \in \mathbb{R}^+$ ,
- (iii)  $\gamma(t) \rightarrow +\infty$  as  $t \rightarrow +\infty$ ,

where  $a, b, c$  are positive constants and  $\alpha \in [0, 1[$ . Consider the following assumptions

- (C1)  $\dim(N(A)) = m \geq 1$  and  $A$  has no eigenvalue of the form  $ki\frac{2\pi}{T}$  ( $k \in \mathbb{N}^*$ );
- (H1) There exist two functions  $p \in L^{\frac{2}{1-\alpha}}(0, T; \mathbb{R}^+)$  and  $q \in L^2(0, T; \mathbb{R}^+)$  such that

$$|\nabla H(t, x)| \leq p(t)\gamma(|x|) + q(t), \quad \forall x \in \mathbb{R}^{2N}, \text{ a.e. } t \in [0, T].$$

Our main results in this section are the following theorems.

**Theorem 4.1.** *Assume (C1) and (H1) hold and*

(H2)  $H$  satisfies

$$\limsup_{|x| \rightarrow \infty, x \in N(A)} \frac{|x|}{\gamma^2(|x|)} < +\infty, \quad \lim_{|x| \rightarrow \infty, x \in N(A)} \frac{1}{\gamma^2(|x|)} \int_0^T H(t, x) dt = +\infty.$$

Then (4.1) possesses at least one  $T$ -periodic solution.

**Example 4.2.** Let  $A$  be the matrix defined in Example 3.1 and let

$$H(t, x) = \left(\frac{3}{4}T - t\right)|x|^{8/5}, \quad \forall x \in \mathbb{R}^{2N}, \forall t \in [0, T].$$

Then

$$|\nabla H(t, x)| = \frac{8}{5} \left|\frac{3}{4}T - t\right| |x|^{3/5}.$$

Let  $\gamma(t) = t^{3/5}$ ,  $t \geq 0$ . It is clear that properties (i), (ii), (iii) are satisfied. Moreover, we have

$$\begin{aligned} \limsup_{|x| \rightarrow \infty, x \in N(A)} \frac{|x|}{\gamma^2(|x|)} &= \limsup_{|x| \rightarrow \infty, x \in N(A)} \frac{|x|}{|x|^{6/5}} = 0 < +\infty, \\ \lim_{|x| \rightarrow \infty, x \in N(A)} \frac{1}{\gamma^2(|x|)} \int_0^T H(t, x) dt &= \lim_{|x| \rightarrow \infty, x \in N(A)} \frac{\frac{1}{4}T^2|x|^{8/5}}{|x|^{6/5}} = +\infty \end{aligned}$$

Hence, by Theorem 4.1, the corresponding system (4.1) possesses at least one  $T$ -periodic solution.

**Theorem 4.3.** Assume (C1) and (H1) hold and

(H3)  $H$  satisfies

$$\limsup_{|x| \rightarrow \infty, x \in N(A)} \frac{\gamma^2(|x|)}{|x|} < \infty, \quad \lim_{|x| \rightarrow \infty} \frac{1}{|x|} \int_0^T H(t, x) dt = +\infty.$$

Then (4.1) possesses at least one  $T$ -periodic solution.

**Theorem 4.4.** Assume (C1) and (H1) hold and

(H4)  $H$  satisfies

$$\limsup_{|x| \rightarrow \infty, x \in N(A)} \frac{\gamma^2(|x|)}{|x|} = 0, \quad \lim_{|x| \rightarrow \infty} \frac{1}{|x|} \int_0^T H(t, x) dt > \int_0^T |h(t)| dt.$$

Then (4.1) possesses at least one  $T$ -periodic solution.

**Example 4.5.** Let  $A$  be the matrix defined in Example 3.1 and let

$$H(t, x) = \left(\frac{1}{2}T - t\right) \ln^{\frac{3}{2}}(1 + |x|^2) + \frac{l(t)|x|^3}{1 + |x|^2}, \quad \forall x \in \mathbb{R}^{2N}, \forall t \in [0, T],$$

where  $l \in C([0, T], \mathbb{R}^+)$  with  $\int_0^T l(t) dt > \int_0^T |h(t)| dt$ . Then

$$\begin{aligned} |\nabla H(t, x)| &\leq \frac{3}{2} \left|\frac{1}{2}T - t\right| (\ln(1 + |x|^2))^{1/2} \frac{|x|}{1 + |x|^2} + \frac{l(t)(5|x|^4) + 3|x|^2}{1 + 2|x|^2 + |x|^4} \\ &\leq \frac{3}{2} \left|\frac{1}{2}T - t\right| (\ln(1 + |x|^2))^{1/2} \frac{|x|}{1 + |x|^2} + c_1 \end{aligned}$$

where  $c_1$  is a positive constant. Let  $\gamma(t) = (\ln(1 + |t|^2))^{1/2}$ ,  $t \geq 0$ . It is clear that conditions (i), (ii), (iii) are satisfied. Moreover,

$$\limsup_{|x| \rightarrow \infty, x \in N(A)} \frac{\gamma^2(|x|)}{|x|} = \limsup_{|x| \rightarrow \infty, x \in N(A)} \frac{\ln(1 + |x|^2)}{|x|} = 0 < +\infty,$$

$$\lim_{|x| \rightarrow \infty, x \in N(A)} \frac{1}{|x|} \int_0^T H(t, x) dt = \int_0^T l(t) dt > \int_0^T |h(t)| dt.$$

Hence, by Theorem 4.4, the corresponding system (4.1) possesses at least one  $T$ -periodic solution.

**Theorem 4.6.** *Assume (C1) and (H1) hold and*

(H5)  *$H$  satisfies*

$$\int_0^T h(t) dt \perp N(A), \quad \lim_{|x| \rightarrow \infty, x \in N(A)} \frac{1}{\gamma^2(|x|)} \int_0^T H(t, x) dt = +\infty.$$

*Then (4.1) possesses at least one  $T$ -periodic solution.*

Theorem 4.6 generalizes the result concerning the existence of periodic solutions for (4.1) in [2, Theorem 3.1].

**Example 4.7.** Let  $A$  be the matrix defined in Example 3.1 and let

$$H(t, x) = \left(\frac{3}{4}T - t\right) \ln^{\frac{3}{2}}(1 + |x|^2) + l(t) (\ln(1 + |x|^2))^{1/2}, \quad x \in \mathbb{R}^{2N}, \quad t \in [0, T],$$

where  $l \in C([0, T], \mathbb{R}^+)$  and  $h(t) = c(t)v_1 + d(t)v_2$ , with  $v_1 = (2, -1, 0, -1)$ ,  $v_2 = (0, 0, 1, -1) \in (N(A))^\perp$ ,  $c, d \in C(\mathbb{R}, \mathbb{R})$ . Then  $\int_0^T h(t) dt \perp N(A)$  and

$$|\nabla H(t, x)| \leq \frac{3}{2} \left| \frac{3}{4}T - t \right| (\ln(1 + |x|^2))^{1/2} + l(t).$$

Let  $\gamma(t) = (\ln(1 + |x|^2))^{1/2}$ ,  $t \geq 0$ . It is easy to verify that  $\gamma$  satisfies conditions (i), (ii), (iii). Moreover,

$$\lim_{|x| \rightarrow \infty, x \in N(A)} \frac{1}{\gamma^2(|x|)} \int_0^T H(t, x) dt = \lim_{|x| \rightarrow \infty, x \in N(A)} \frac{T^2}{4} (\ln(1 + |x|^2))^{1/2} = +\infty$$

Hence, by Theorem 4.6, the corresponding system (4.1) possesses at least one  $T$ -periodic solution.

**Remark 4.8.** Let  $u(t)$  be a periodic solution of (4.1), then by replacing  $t$  by  $-t$  in (4.1), we obtain

$$\dot{u}(-t) = JH'(-t, u(-t)).$$

So it is clear that the function  $v(t) = u(-t)$  is a periodic solution of the system

$$\dot{v}(t) = -JH'(-t, v(t)).$$

Moreover,  $-H(-t, x)$  satisfies (H2)–(H5) whenever  $H(t, x)$  satisfies the following assumptions

(H2')

$$\limsup_{|x| \rightarrow \infty, x \in N(A)} \frac{|x|}{\gamma^2(|x|)} < +\infty, \quad \lim_{|x| \rightarrow \infty, x \in N(A)} \frac{1}{\gamma^2(|x|)} \int_0^T H(t, x) dt = -\infty;$$

(H3')

$$\limsup_{|x| \rightarrow \infty, x \in N(A)} \frac{\gamma^2(|x|)}{|x|} < \infty, \quad \lim_{|x| \rightarrow \infty} \frac{1}{|x|} \int_0^T H(t, x) dt = -\infty;$$

(H4')

$$\limsup_{|x| \rightarrow \infty, x \in N(A)} \frac{\gamma^2(|x|)}{|x|} = 0, \quad \lim_{|x| \rightarrow \infty} \frac{1}{|x|} \int_0^T H(t, x) dt < - \int_0^T |h(t)| dt;$$

(H5')

$$\int_0^T h(t) dt \perp N(A), \quad \lim_{|x| \rightarrow \infty, x \in N(A)} \frac{1}{\gamma^2(|x|)} \int_0^T H(t, x) dt = -\infty.$$

Consequently, the previous Theorems remains true if we replace (H2)–(H5) by (H2')–(H5').

**Proofs of Theorems.** Consider the functional

$$\varphi(u) = \frac{1}{2} \int_0^T (J\dot{u}(t) \cdot u(t) + Au(t) \cdot u(t)) dt + \int_0^T H(t, u(t)) dt - \int_0^T h(t) \cdot u(t) dt$$

Let  $E$  be the space introduced in Section 2. By assumption (H1) and the property (ii) of  $\gamma$ , [11, Proposition B37] implies that  $\varphi \in C^1(E, \mathbb{R})$  and the critical points of  $\varphi$  on  $E$  correspond to the  $T$ -periodic solutions of (4.1), moreover

$$\varphi'(u)v = \int_0^T [J\dot{u}(t) + Au(t) + \nabla H(t, u(t))] \cdot v(t) dt - \int_0^T h(t) \cdot v(t) dt.$$

**Lemma 4.9.** *Assume (H1) holds. Then for any (PS) sequence  $(u_n) \subset E$  of the functional  $\varphi$ , there exists a constant  $c_0 > 0$  such that*

$$\|\tilde{u}_n\| \leq c_0(\gamma(\|u_n^0\|) + 1), \quad \forall n \in \mathbb{N} \quad (4.2)$$

where  $\tilde{u}_n = u_n^+ + u_n^- = u_n - u_n^0$ , with  $u_n^0 \in E^0$ ,  $u_n^- \in E^-$ ,  $u_n^+ \in E^+$ .

*Proof.* Let  $(u_n)_{n \in \mathbb{N}}$  be a (PS) sequence, i.e.  $\varphi(u_n)$  is bounded and  $\varphi'(u_n) \rightarrow 0$  as  $n \rightarrow \infty$ . We have

$$\varphi'(u_n)(u_n^+ - u_n^-) = 2\|\tilde{u}_n\|^2 + \int_0^T \nabla H(t, u_n) \cdot (u_n^+ - u_n^-) dt - \int_0^T h(t) \cdot (u_n^+ - u_n^-) dt.$$

Since  $\varphi'(u_n) \rightarrow 0$  as  $n \rightarrow \infty$ , there exists a constant  $c_2 > 0$  such that

$$|\varphi'(u_n)(u_n^+ - u_n^-)| \leq c_2 \|\tilde{u}_n\|, \quad \forall n \in \mathbb{N}.$$

By Hölder's inequality and (H1), we have

$$\begin{aligned} \left| \int_0^T \nabla H(t, u_n) \cdot (u_n^+ - u_n^-) dt \right| &\leq \|\tilde{u}_n\|_{L^2} \left( \int_0^T |\nabla H(t, u_n)|^2 dt \right)^{1/2} \\ &\leq \|\tilde{u}_n\|_{L^2} \left( \int_0^T [p(t)\gamma(|u_n|) + q(t)] dt \right)^{1/2} \\ &\leq \|\tilde{u}_n\|_{L^2} \left[ \left( \int_0^T p^2(t)\gamma^2(|u_n|) dt \right)^{1/2} + \|q\|_{L^2} \right]. \end{aligned} \quad (4.3)$$

Now, by nondecreasing condition and the properties (i) and (ii) of  $\gamma$ , we have

$$\left( \int_0^T p^2(t)\gamma^2(|u_n|) dt \right)^{1/2} \leq \left( \int_0^T p^2(t)\gamma^2(|\tilde{u}_n| + |u_n^0|) dt \right)^{1/2}$$



$$\begin{aligned}
&\leq c \left( \int_0^T [p^2(t)[\gamma(|\tilde{u}_n|) + \gamma(|u_n^0|)]^2 dt \right)^{1/2} \\
&\leq c \left[ \left( \int_0^T p^2(t)\gamma^2(|\tilde{u}_n|) dt \right)^{1/2} + \|p\|_{L^2} \gamma(|u_n^0|) \right] \\
&\leq c \left[ \left( \int_0^T p^2(t)(a|\tilde{u}_n|^\alpha + b)^2 dt \right)^{1/2} + \|p\|_{L^2} \gamma(|u_n^0|) \right] \\
&\leq c \left[ a \left( \int_0^T p^2(t)|\tilde{u}_n|^{2\alpha} dt \right)^{1/2} + b\|p\|_{L^2} + \|p\|_{L^2} \gamma(|u_n^0|) \right] \\
&\leq c \left[ a\|p\|_{L^{\frac{2}{1-\alpha}}} \|\tilde{u}_n\|_{L^2}^\alpha + b\|p\|_{L^2} + \|p\|_{L^2} \gamma(|u_n^0|) \right].
\end{aligned}$$

On the other hand, by (2.1) we have

$$\begin{aligned}
2\|\tilde{u}_n\|^2 &\leq |\varphi'(u_n)(u_n^+ - u_n^-)| + \left| \int_0^T \nabla H(t, u_n) \cdot (u_n^+ - u_n^-) dt \right| \\
&\quad + \left| \int_0^T h(t) \cdot (u_n^+ - u_n^-) \right| \leq c_2 \|\tilde{u}_n\| + \|\tilde{u}_n\|_{L^2} c \left[ a\|p\|_{L^{\frac{2}{1-\alpha}}} \|\tilde{u}_n\|_{L^2}^\alpha \right. \\
&\quad \left. + b\|p\|_{L^2} + \|q\|_{L^2} + \|p\|_{L^2} \gamma(|u_n^0|) \right] + \|h\|_{L^2} \|\tilde{u}_n\|_{L^2} \\
&\leq ac\|p\|_{L^{\frac{2}{1-\alpha}}} \lambda_2^{\alpha+1} \|\tilde{u}_n\|^{\alpha+1} + [c_1 + cb\|p\|_{L^2} \\
&\quad + \|q\|_{L^2} + \|h\|_{L^2}] \lambda_2 \|\tilde{u}_n\| + c\lambda_2 \|p\|_{L^2} \gamma(|u_n^0|) \|\tilde{u}_n\|.
\end{aligned}$$

Since  $0 \leq \alpha < 1$ , we deduce that there exists a constant  $c_0 > 0$  satisfying (4.2).  $\square$

We will apply Lemma 2.1 to the functional  $\varphi$  to obtain critical points.

**Lemma 4.10.** *If (H1) holds and  $H$  satisfies one of the assumptions (H2)–(H5), then  $\varphi$  satisfies the  $(PS)_c$  condition for all  $c \in \mathbb{R}$ .*

*Proof.* Let  $(u_n)_{n \in \mathbb{N}}$  be a  $(PS)_c$  sequence, that is  $\varphi(u_n) \rightarrow c$  and  $\varphi'(u_n) \rightarrow 0$  as  $n \rightarrow \infty$ . Then there exists a positive constant  $c_3$  such that

$$|\varphi(u_n)| \leq c_3, \quad \|\varphi'(u_n)\| \leq c_3, \quad \forall n \in \mathbb{N}.$$

By the Mean Value Theorem and Hölder's inequality, we have

$$\begin{aligned}
&\left| \int_0^T (H(t, u_n) - H(t, u_n^0)) dt \right| \\
&= \left| \int_0^T \int_0^1 \nabla H(t, u_n^0 + s\tilde{u}_n) \cdot \tilde{u}_n ds dt \right| \tag{4.4} \\
&\leq \|\tilde{u}_n\|_{L^2} \int_0^1 \left( \int_0^T |\nabla H(t, u_n^0 + s\tilde{u}_n)|^2 dt \right)^{1/2} ds.
\end{aligned}$$

As in the proof of Lemma 4.9, we have

$$\begin{aligned}
&\left( \int_0^T |\nabla H(t, u_n^0 + s\tilde{u}_n)|^2 dt \right)^{1/2} \\
&\leq ac\|p\|_{L^{\frac{2}{1-\alpha}}} \|\tilde{u}_n\|_{L^2}^\alpha + cb\|p\|_{L^2} + \|q\|_{L^2} + c\|p\|_{L^2} \gamma(|u_n^0|) \|q\|_{L^2}. \tag{4.5}
\end{aligned}$$

Therefore, by properties (2.1), (4.2), (4.4), (4.5) and since  $0 \leq \alpha < 1$ , there exists a positive constant  $c_4$  such that

$$\begin{aligned} \left| \int_0^T (H(t, u_n) - H(t, u_n^0)) dt \right| &\leq c_0(\gamma(|u_n^0|) + 1) [ac \|p\|_{L^{\frac{2}{1-\alpha}}} c_0^\alpha (\gamma(|u_n^0|) + 1)^\alpha \\ &\quad + c \|p\|_{L^2} \gamma(|u_n^0|) + cb \|p\|_{L^2} + \|q\|_{L^2}] \\ &\leq c_4(\gamma^2(|u_n^0|) + 1). \end{aligned} \quad (4.6)$$

Combining (2.1), (4.2), (4.3) and (4.6) yields

$$\begin{aligned} c_3 &\geq \varphi(u_n) \\ &\geq -\|\tilde{u}_n\|^2 + \int_0^T (H(t, u_n) - H(t, u_n^0)) dt + \int_0^T H(t, u_n^0) dt \\ &\quad - \int_0^T h(t)(\tilde{u}_n + u_n^0) dt \\ &\geq -c_0^2(\gamma(|u_n^0|) + 1)^2 - c_4(\gamma^2(|u_n^0|) + 1) - c_0 \|h\|_{L^2} (\gamma(|u_n^0|) + 1) \\ &\quad - \|h\|_{L^1} |u_n^0| + \int_0^T H(t, u_n^0) dt \\ &\geq -c_5(\gamma^2(|u_n^0|) + 1) - \|h\|_{L^1} |u_n^0| + \int_0^T H(t, u_n^0) dt, \end{aligned} \quad (4.7)$$

where  $c_5$  is a positive constant.

**Case 1:**  $H$  satisfies (H2). By (4.7), we have

$$c_3 \geq \gamma^2(|u_n^0|) [-c_5 - \|h\|_{L^1} \frac{|u_n^0|}{\gamma^2(|u_n^0|)} + \frac{1}{\gamma^2(|u_n^0|)} \int_0^T H(t, u_n^0) dt] - c_5.$$

It follows from (H2) that  $(u_n^0)$  is bounded.

**Case 2:**  $H$  satisfies (H3) or (H4). Note that by (4.7)

$$c_3 \geq |u_n^0| [-c_5 \frac{\gamma^2(|u_n^0|)}{|u_n^0|} - \|h\|_{L^1} + \frac{1}{|u_n^0|} \int_0^T H(t, u_n^0) dt] - c_5.$$

Hence (H3) or (H4) implies that  $(u_n^0)$  is bounded.

**Case 2:**  $H$  satisfies (H5). Since  $\int_0^T h(t) dt \perp N(A)$ , we get as in (4.7)

$$\begin{aligned} c_3 &\geq \varphi(u_n) \\ &\geq -\|\tilde{u}_n\|^2 + \int_0^T (H(t, u_n) - H(t, u_n^0)) dt + \int_0^T H(t, u_n^0) dt \\ &\quad - \int_0^T h(t) \cdot \tilde{u}_n dt \\ &\geq -c_5(\gamma^2(|u_n^0|) + 1) + \int_0^T H(t, u_n^0) dt, \\ &\geq \gamma^2(|u_n^0|) [-c_5 + \frac{1}{\gamma^2(|u_n^0|)} \int_0^T H(t, u_n^0) dt] - c_5. \end{aligned} \quad (4.8)$$

Hence (H5) implies that  $(u_n^0)$  is bounded.

In all the above cases,  $(u_n^0)$  is bounded. We deduce from Lemma 4.9 that  $(u_n)$  is also bounded in  $E$ . By a standard argument, we conclude that  $(u_n)$  possesses a convergent subsequence. The proof of Lemma 4.10 is complete.  $\square$

Now, decompose  $E = E^- \oplus (E^0 \oplus E^+)$  and let  $E^1 = E^-$  and  $E^2 = E^0 \oplus E^+$ . Remark that by Section 3, we have  $E^0 = N(A)$ . We will verify that  $\varphi$  satisfies condition c) of Lemma 2.1. For  $u \in E^1$ , we have

$$\varphi(u) = -\|u\|^2 + \int_0^T (H(t, u) - H(t, 0))dt + \int_0^T H(t, 0)dt - \int_0^T h(t) \cdot u dt.$$

As in the proof of Lemma 4.10,

$$\left| \int_0^T (H(t, u) - H(t, 0))dt \right| \leq [ac\|p\|_{L^{\frac{2}{1-\alpha}}} \|u\|_{L^2}^\alpha + cb\|p\|_{L^2} + \|q\|_{L^2}] \|u\|_{L^2}.$$

Hence by (2.1), we deduce

$$\begin{aligned} \varphi(u) &\leq -\|u\|^2 + ac\|p\|_{L^{\frac{2}{1-\alpha}}} \lambda_2^{\alpha+1} \|u\|^{\alpha+1} + (cb\|p\|_{L^2} \\ &\quad + \|q\|_{L^2} + \|h\|_{L^2})\lambda_2 \|u\| + \int_0^T H(t, 0)dt. \end{aligned} \tag{4.9}$$

Since  $0 \leq \alpha < 1$ , (4.9) implies that  $\varphi(u) \rightarrow -\infty$  as  $\|u\| \rightarrow \infty$ . Hence there exists  $\beta \in \mathbb{R}$  such that  $f(u) \leq \beta$  for all  $u \in E^1$ . Condition (c) of Lemma 2.1 is then proved.

Let us verify that  $\varphi$  satisfies condition (d) of Lemma 2.1. In fact, for  $u \in E^2 = E^0 \oplus E^+$ , as in the proof of Lemma 4.10, we have

$$\begin{aligned} &\left| \int_0^T (H(t, u) - H(t, u^0))dt \right| \\ &\leq [ac\|p\|_{L^{\frac{2}{1-\alpha}}} \|u^+\|_{L^2}^\alpha + cb\|p\|_{L^2} + c\|p\|_{L^2} \gamma(|u^0|) + \|q\|_{L^2}] \|u^+\|_{L^2}^\alpha. \end{aligned} \tag{4.10}$$

From (2.1) and (4.10), we deduce that

$$\begin{aligned} \varphi(u) &\geq \|u^+\|^2 - ac\|p\|_{L^{\frac{2}{1-\alpha}}} \lambda_2^{\alpha+1} \|u^+\|^{\alpha+1} - c\|p\|_{L^2} \lambda_2 \|u^+\| \gamma(|u^0|) \\ &\quad - (cb\|p\|_{L^2} + \|q\|_{L^2} + \|h\|_{L^2})\lambda_2 \|u^+\| - \int_0^T |h|dt |u^0| + \int_0^T H(t, u^0)dt. \end{aligned} \tag{4.11}$$

For  $\epsilon > 0$ , there exists a constant  $C(\epsilon)$  such that

$$c\|p\|_{L^2} \lambda_2 \|u^+\| \gamma(|u^0|) \leq \epsilon \|u^+\|^2 + C(\epsilon) \gamma^2(|u^0|).$$

Taking  $\epsilon = 1/2$ , it follows from (4.11) that

$$\begin{aligned} \varphi(u) &\geq \frac{1}{2} \|u^+\|^2 - ac\|p\|_{L^{\frac{2}{1-\alpha}}} \lambda_2^{\alpha+1} \|u^+\|^{\alpha+1} - \lambda_2 (cb\|p\|_{L^2} + \|q\|_{L^2} \\ &\quad + \|h\|_{L^2}) \|u^+\| - C\left(\frac{1}{2}\right) \gamma^2(|u^0|) - \int_0^T |h|dt |u^0| + \int_0^T H(t, u^0)dt. \end{aligned} \tag{4.12}$$

Since  $0 \leq \alpha < 1$ , the term

$$\frac{1}{2} \|u^+\|^2 - ac\|p\|_{L^{\frac{2}{1-\alpha}}} \lambda_2^{\alpha+1} \|u^+\|^{\alpha+1} - \lambda_2 (cb\|p\|_{L^2} + \|q\|_{L^2} + \|h\|_{L^2}) \|u^+\|$$

approaches  $+\infty$  as  $\|u^+\| \rightarrow \infty$ . It remains to study the following member of (4.12)

$$\psi(u^0) = -C\left(\frac{1}{2}\right) \gamma^2(|u^0|) - \int_0^T |h|dt |u^0| + \int_0^T H(t, u^0)dt.$$

**Case 1:** (H2) holds. We have

$$\psi(u^0) \geq \gamma^2(|u^0|) \left( -C\left(\frac{1}{2}\right) - \int_0^T |h| dt \frac{|u^0|}{\gamma^2(|u^0|)} + \frac{1}{\gamma^2(|u^0|)} \int_0^T H(t, u^0) dt \right).$$

It follows from (H2) that  $\psi(u^0) \rightarrow +\infty$  as  $|u^0| \rightarrow \infty$ .

**Case 2:** (H3) or (H4) holds. We have

$$\psi(u^0) \geq |u^0| \left( -C\left(\frac{1}{2}\right) \frac{\gamma^2(|u^0|)}{|u^0|} - \int_0^T |h| dt + \frac{1}{|u^0|} \int_0^T H(t, u^0) dt \right).$$

It follows from (H3) or (H4) that  $\psi(u^0) \rightarrow +\infty$  as  $|u^0| \rightarrow \infty$ .

**Case 3:** (H5) holds. Since  $\int_0^T h(t) dt \perp N(A)$ , we have

$$\psi(u^0) \geq \gamma^2(|u^0|) \left( -C\left(\frac{1}{2}\right) + \frac{1}{\gamma^2(|u^0|)} \int_0^T H(t, u^0) dt \right).$$

It follows from (H5) that  $\psi(u^0) \rightarrow +\infty$  as  $|u^0| \rightarrow \infty$ .

Therefore, if one of assumptions (H2)–(H5) is satisfied, then  $\varphi(u) \rightarrow +\infty$  as  $\|u\| \rightarrow \infty$ . So there exists a constant  $\rho$  such that  $\varphi(u) \geq \rho$  for all  $u \in E^2$ . Condition d) of Lemma 2.1 is satisfied. Moreover, it is well known that the derivative of the functional  $d(u) = \int_0^T H(t, u) dt - \int_0^T h u dt$  is compact. All the conditions of Lemma 2.1 are satisfied, so  $\varphi$  possesses a critical point  $u$  which is a  $T$ -periodic solution of system (4.1)

## 5. SECOND CLASS OF HAMILTONIAN SYSTEMS

For  $A, H$  and  $h$  be defined as in Section 4, we have the following result.

**Theorem 5.1.** *Let  $\omega \in C(\mathbb{R}^+, \mathbb{R}^+)$  be a non-increasing function with the following properties:*

- (a)  $\liminf_{s \rightarrow \infty} \frac{\omega(s)}{\omega(\sqrt{s})} > 0$ ,
- (b)  $\omega(s) \rightarrow 0$  and  $\omega(s)s \rightarrow +\infty$  as  $s \rightarrow \infty$ .

Assume that  $A$  satisfies (C1), and  $H$  satisfies

(H6) *There exist a positive constant  $a$  and a function  $g \in L^2(0, T; \mathbb{R})$  such that*

$$|\nabla H(t, x)| \leq a\omega(|x|) + g(t), \quad \forall x \in \mathbb{R}^{2N}, \text{ a.e. } t \in [0, T];$$

(H7)

$$\lim_{|x| \rightarrow \infty, x \in N(A)} \frac{1}{(\omega(|x|)|x|)^2} \int_0^T H(t, x) dt = +\infty;$$

(H8) *There exists  $f \in L^1(0, T; \mathbb{R})$  such that*

$$H(t, x) \geq f(t), \quad \forall x \in \mathbb{R}^{2N}, \text{ a.e. } t \in [0, T].$$

Then system (4.1) possesses at least one  $T$ -periodic solution.

The above theorem generalizes [15, Theorem 1.1].

**Example 5.2.** Take  $\omega(s) = \frac{1}{\ln(2+s^2)}$ ,  $s \geq 0$ ,

$$H(t, x) = \left( \frac{1}{2} + \cos\left(\frac{2\pi}{T}t\right) \right) \frac{|x|^2}{\ln(2+|x|^2)}, \quad \forall t \in [0, T], \forall x \in \mathbb{R}^{2N}$$

and let  $A$  be the matrix defined in Section 3,  $h \in C([0, T], \mathbb{R})$ . Then  $A, H, h$  satisfy assumptions of Theorem 5.1.

**Proof of Theorem 5.1.** As in Section 4, we will apply Lemma 2.1 to the functional  $\varphi$  defined on the space  $E$  introduced in section 2.

**Lemma 5.3** ([15]). *Assume (H6) and (H7) hold, then there exists a non-increasing function  $\theta \in C(]0, +\infty[, \mathbb{R}^+)$  and a positive constant  $c_0$  such that*

- (i)  $\theta(s) \rightarrow 0$  and  $\theta(s)s \rightarrow \infty$  as  $s \rightarrow \infty$ ,
- (ii)  $\|\nabla H(t, u)\|_{L^2} \leq c_0(\theta(\|u\|)\|u\| + 1)$  for all  $u \in E$
- (iii)

$$\frac{1}{(\theta(\|u^0\|)\|u^0\|)^2} \int_0^T H(t, u^0) dt \rightarrow +\infty \quad \text{as } \|u^0\| \rightarrow \infty.$$

**Lemma 5.4.** *Assume (H6) holds. Then for any (PS) sequence of the functional  $\varphi$ , there exists a constant  $c_1 > 0$  such that*

$$\|\tilde{u}_n\| \leq c_1(\theta(\|u_n^0\|)\|u_n^0\| + 1). \tag{5.1}$$

*Proof.* Let  $(u_n)$  be a Palais-Smale sequence, that is  $(\varphi(u_n))$  is bounded and  $\varphi'(u_n) \rightarrow 0$ , as  $n \rightarrow \infty$ . We have

$$\varphi'(u_n)(u_n^+ - u_n^-) = 2\|\tilde{u}_n\|^2 + \int_0^T \nabla H(t, u_n(t)) \cdot (u_n^+ - u_n^-) dt - \int_0^T h(t) \cdot (u_n^+ - u_n^-) dt.$$

Since  $\theta$  is non-increasing and  $\|u\| \geq \max(\|\tilde{u}\|, \|u^0\|)$ , we have

$$\theta(\|u\|) \leq \min(\theta(\|\tilde{u}\|), \theta(\|u^0\|)). \tag{5.2}$$

By Hölder's inequality, inequalities (2.1), (5.1), (5.2) and Lemma 5.3, we have

$$\begin{aligned} & \left| \int_0^T \nabla H(t, u_n(t)) \cdot (u_n^+ - u_n^-) dt \right| \\ & \leq \|u_n^+ - u_n^-\|_{L^2} \left( \int_0^T |\nabla H(t, u_n)|^2 dt \right)^{1/2} \\ & \leq c_2 \|\tilde{u}_n\| (\theta(\|u_n\|)\|u_n\| + 1) \\ & \leq c_2 \|\tilde{u}_n\| (\theta(\|\tilde{u}_n\|)\|\tilde{u}_n\| + \theta(\|u_n^0\|)\|u_n^0\| + 1). \end{aligned}$$

Thus there exists positive constants  $c_3, c_4$  such that

$$\begin{aligned} c_3 \|\tilde{u}_n\| & \geq \varphi'(u_n)(u_n^+ - u_n^-) \\ & \geq 2\|\tilde{u}_n\|^2 - c_2 \|\tilde{u}_n\| (\theta(\|\tilde{u}_n\|)\|\tilde{u}_n\| + \theta(\|u_n^0\|)\|u_n^0\| + 1) - c_4 \|\tilde{u}_n\|. \end{aligned}$$

Hence

$$c_2 \theta(\|u_n^0\|)\|u_n^0\| \geq \|\tilde{u}_n\| [2 - c_2 \|\tilde{u}_n\|] - c_3 - c_4.$$

Since  $\theta(s) \rightarrow 0$  as  $s \rightarrow \infty$ , this implies the existence of a constant  $c_1$  satisfying (5.1). □

**Lemma 5.5.**  *$\varphi$  satisfies the  $(PS)_c$  condition for all real  $c$ .*

*Proof.* Let  $(u_n)$  be a  $(PS)_c$ -sequence. Assume that  $(u_n^0)$  is unbounded. Going to a subsequence if necessary, we can assume that  $\|u_n^0\| \rightarrow \infty$  as  $n \rightarrow \infty$ . By the

Mean Value Theorem, Hölder's inequality, inequality (2.1) and Lemma 5.3 (ii), there exists a positive constant  $c_5$  such that

$$\begin{aligned} & \left| \int_0^T (H(t, u_n) - H(t, u_n^0)) dt \right| \\ &= \left| \int_0^T \int_0^1 \nabla H(t, u_n^0 + s\tilde{u}_n) \cdot \tilde{u}_n ds dt \right| \\ &\leq \|\tilde{u}_n\|_{L^2} \int_0^1 \left( \int_0^T |\nabla H(t, u_n^0 + s\tilde{u}_n)| dt \right)^{1/2} ds \\ &\leq c_5 \|\tilde{u}_n\| [\theta(\|u_n^0\|)\|u_n^0\| + \theta(\|u_n^0\|)\|\tilde{u}_n\| + 1]. \end{aligned} \quad (5.3)$$

Hence by Lemma 5.4, there exists a positive constant  $c_6$  such that

$$\left| \int_0^T (H(t, u_n) - H(t, u_n^0)) dt \right| \leq c_6 ([\theta(\|u_n^0\|)\|\tilde{u}_n^0\|]^2 + 1). \quad (5.4)$$

Combining (2.1), (5.1) and (5.4) yields

$$\varphi(u_n) \geq -c_7([\theta(\|u_n^0\|)\|\tilde{u}_n^0\|]^2 + 1) - \frac{1}{T} \int_0^T |h(t)| dt \|u_n^0\| + \int_0^T H(t, u_n^0) dt$$

where  $c_7$  is a positive constant.

On the other hand, it is easy to see that  $\liminf_{s \rightarrow \infty} \frac{\theta(s)}{\theta(\sqrt{s})} > 0$ . So there exists a positive constant  $c_8$  such that for  $s$  large enough  $\theta(s) \geq c_8\theta(\sqrt{s})$ . Hence for  $n$  large enough

$$\frac{\|u_n^0\|}{[\theta(\|u_n^0\|)\|u_n^0\|]^2} \geq \frac{1}{c_8^2[\theta(\|u_n^0\|^{1/2})\|u_n^0\|^{1/2}]^2} \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

Therefore,

$$\begin{aligned} \varphi(u_n) &\geq [\theta(\|u_n^0\|)\|u_n^0\|]^2 \left[ -c_7 - \frac{1}{T} \int_0^T |h(t)| dt \frac{\|u_n^0\|}{[\theta(\|u_n^0\|)\|u_n^0\|]^2} \right. \\ &\quad \left. + \frac{1}{[\theta(\|u_n^0\|)\|u_n^0\|]^2} \int_0^T H(t, u_n^0) dt \right] - c_7 \rightarrow +\infty \end{aligned}$$

as  $n \rightarrow \infty$ , which contradicts the boundedness of  $(\varphi(u_n))$ . Hence  $(\|u_n^0\|)$  is bounded, and by Lemma 5.4,  $(u_n)$  is also bounded. By a standard argument, we conclude that  $(u_n)$  possesses a convergent subsequence. The proof is complete.  $\square$

Now, for  $u = u^0 + u^+ \in E^2 = E^0 \oplus E^+$ , we have as in (5.3),

$$\left| \int_0^T (H(t, u) - H(t, u^0)) dt \right| \leq c_5 \|u^+\| [\theta(\|u^0\|)\|u^0\| + \theta(\|u^0\|)\|u^+\| + 1].$$

Since  $c_5\theta(\|u^0\|)\|u^0\|\|u^+\| \leq \frac{1}{2}\|u^+\|^2 + 2c_5^2[\theta(\|u^0\|)\|u^0\|]^2$ , we obtain

$$\begin{aligned} \varphi(u) &\geq \left( \frac{1}{2} - c_5\theta(\|u^0\|) \right) \|u^+\|^2 - c_5 \|u^+\| \\ &\quad + [\theta(\|u^0\|)\|u^0\|]^2 \left( -2c_5^2 - \frac{1}{T} \int_0^T |h(t)| dt \frac{\|u^0\|}{[\theta(\|u^0\|)\|u^0\|]^2} \right. \\ &\quad \left. + \frac{1}{[\theta(\|u^0\|)\|u^0\|]^2} \int_0^T H(t, u^0) dt \right). \end{aligned}$$

Since  $\theta(s) \rightarrow 0$  as  $s \rightarrow \infty$ , there exists  $r > 0$  such that  $c_5\theta(s) \leq \frac{1}{4}$  for  $s \geq r$ . Then, if  $\|u^0\| \geq r$ , we have

$$\begin{aligned} \varphi(u) &\geq \frac{1}{4}\|u^+\|^2 - c_5\|u^+\| + [\theta(\|u^0\|)\|u^0\|]^2(-2c_5^2 \\ &\quad - \frac{1}{T} \int_0^T |h(t)|dt \frac{\|u^0\|}{[\theta(\|u^0\|)\|u^0\|]^2} + \frac{1}{[\theta(\|u^0\|)\|u^0\|]^2} \int_0^T H(t, u^0)dt). \end{aligned}$$

then  $\varphi(u) \rightarrow +\infty$  as  $\|u^0 + u^+\| \rightarrow \infty$ ,  $\|u^0\| \geq r$ .

If  $\|u^0\| \leq r$ , we have by (H8) and (2.1)

$$\varphi(u) \geq \|u^+\|^2 + \int_0^T f(t)dt - \frac{r}{T} \int_0^T |h(t)|dt - \lambda_2 \|h\|_{L^2} \|u^+\|$$

then  $\varphi(u) \rightarrow +\infty$  as  $\|u^0 + u^+\| \rightarrow \infty$ ,  $\|u^0\| \leq r$ . Therefore  $\varphi(u) \rightarrow +\infty$  as  $\|u\| \rightarrow \infty$ ,  $u \in E^2$ .

In  $E^1$ , as in [15], we obtain  $\varphi(u) \rightarrow -\infty$  as  $\|u\| \rightarrow \infty$ . Hence, by Lemma 2.1,  $\varphi$  possesses at least a critical point  $u$  which is a  $T$ -periodic solution of (4.1).

#### REFERENCES

- [1] T. An; *Periodic solutions of superlinear autonomous Hamiltonian systems with prescribed period*, J. Math. Anal. Appl. 323 (2006), pp. 854-863.
- [2] A. R. Chouikha, M. Timoumi; *Subharmonic solutions for nonautonomous sublinear first order Hamiltonian systems*, Arxiv, 1302-4309 V1 (math.DS) 18, Feb 2013.
- [3] I. Ekeland; *Periodic solutions of Hamiltonian equations and a theorem of P. Rabinowitz*, J. Diff. Eq. (1979), pp. 523-534.
- [4] P-L. Felmer; *Periodic solutions of superquadratic Hamiltonian systems*, J. Diff. Eq. 102 (1993), pp. 188-307.
- [5] M. Gilardi, M. Matzeu; *Periodic solutions of convex autonomous Hamiltonian systems with a quadratic growth at the origin and superquadratic at infinity*, Annali di Matematica Pura and Applicata-(IV), vol. CXL VII, pp 21-72.
- [6] C. Li, Z-Q. Ou, C-L. Tang; *Periodic and subharmonic solutions for a class of non-autonomous Hamiltonian systems*, Nonlinear Analysis 75 (2012), pp 2262-2272.
- [7] S. Li, A. Szulkin; *Periodic solutions for a class of non-autonomous Hamiltonian systems*, J. Diff. Eq., (1994), pp. 226-238.
- [8] S. Li, M. Willem; *Applications of local linking to critical point theory*, J. Math. Anal. Appl. 189, (1995), pp. 6-32.
- [9] S. Luan, A. Mao; *Periodic solutions for a class of non-autonomous Hamiltonian systems*, Nonlinear Analysis 61, (2005), pp. 1413-1426.
- [10] J. Mawhin, M. Willem; *Critical point theory and Hamiltonian systems*, Applied Mathematical Sciences, 74, Springer, New York, 1989.
- [11] P. H. Rabinowitz; *Minimax methods in critical point theory with applications to differential equations*, CBMS. Reg. Conf. Ser. Math., vol 65, Amer. Math. Soc., Providence, RI (1986).
- [12] P. Rabinowitz; *Periodic solutions of Hamiltonian systems*, Comm. Pure Appl. Math. 31 (1978), pp. 157-184.
- [13] M. Timoumi; *Periodic and subharmonic solutions for a class of non coercive superquadratic Hamiltonian systems*, Nonl. Dyn. and Syst. Theory, 11(3) (2011), pp. 319-336.
- [14] M. Timoumi; *Periodic solutions for non coercive super-quadratic Hamiltonian systems*, Dem. Mathematica, Vol. XI, No 2, (2007), pp. 331-346.
- [15] M. Timoumi; *Subharmonic solutions for first-order Hamiltonian systems*, Elect. J. Diff. Eq., Vol. 2013 (2013), No. 197, pp. 1-14.
- [16] X. Xu; *Periodic solutions for non-autonomous Hamiltonian systems possessing super-quadratic potentials*, Nonlinear Analysis 51, (2002), pp. 941-955.

MOHSEN TIMOUMI

DEPARTMENT OF MATHEMATICS, FACULTY OF SCIENCES, 5000 MONASTIR, TUNISIA

E-mail address: m.timoumi@yahoo.com