# EXISTENCE OF SOLUTIONS FOR IMPLICIT OBSTACLE PROBLEMS INVOLVING NONHOMOGENEOUS PARTIAL DIFFERENTIAL OPERATORS AND MULTIVALUED TERMS 

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#### Abstract

In this article, we study an implicit obstacle problem with a nonlinear nonhomogeneous partial differential operator and a multivalued operator which is described by a generalized gradient. Under quite general assumptions on the data, and employing Kluge's fixed point principle for multivalued operators, Minty technique and a surjectivity theorem, we prove that the set of weak solutions to the problem is nonempty, bounded and weakly closed.


## 1. Introduction

Let $\Omega \subseteq \mathbb{R}^{N}$ be a bounded domain with a $C^{1, \alpha}$-boundary $\partial \Omega$ for some $0<\alpha<1$. In this paper, we study the following implicit obstacle problem with a nonlinear nonhomogeneous partial differential operator and a multivalued operator which is described by a generalized gradient, namely

$$
\begin{gather*}
-\operatorname{div} a(x, \nabla u(x))+\partial j(x, u(x)) \ni f(x) \text { in } \Omega, \\
u=0 \quad \text { on } \partial \Omega  \tag{1.1}\\
T(u) \leq U(u) .
\end{gather*}
$$

In the above $f: \Omega \rightarrow \mathbb{R}$ and $j: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ are given two functions, such that $f \in L^{p^{\prime}}(\Omega)$ (where $1<p<\infty$ and $\frac{1}{p}+\frac{1}{p^{\prime}}=1$ ) and $j$ is locally Lipschitz with respect to the second variable. By $\partial j(x, u(x))$ we denote the Clarke's generalized gradient of $j$ with respect to the last variable. Finally $T, U: W_{0}^{1, p}(\Omega) \rightarrow \mathbb{R}$ are two given functions, which satisfy appropriate assumptions listed in Section 3 .

In this article we prove that the set of weak solutions to the problem is nonempty, bounded and weakly closed. In particular we obtain the existence of at least one weak solution to problem (1.1). The main tools used in the proof are the surjectivity theorem for multivalued mappings due to Le [33], Kluge's fixed point principle as well as some techniques of nonsmooth analysis. Problem 1.1) combines several interesting phenomena like a nonhomogeneous operator of $p$-Laplacian type, a multivalued mapping provided by the Clarke generalized subdifferential and an implicit obstacle inequality. The latter means that any solution $u \in W_{0}^{1, p}(\Omega)$ of (1.1) has to

[^0]belong to $K(u)$, which is the image of the multivalued map $K: W_{0}^{1, p}(\Omega) \rightarrow 2^{W_{0}^{1, p}(\Omega)}$ defined by
$$
K(u):=\left\{v \in W_{0}^{1, p}(\Omega): T(v)-U(u) \leq 0\right\}
$$
for some obstacles given by the functions $T: W_{0}^{1, p}(\Omega) \rightarrow \mathbb{R}$ and $U: W_{0}^{1, p}(\Omega) \rightarrow$ $(0,+\infty)$.

For the problems with a nonhomogeneous operator of $p$-Laplacian type we refer to Bai-Gasińnski-Papageorgiou [2], Candito-Gasiński-Livrea [6], Gasiński-O'ReganPapageorgiou [20, 21, Gasiński-Papageorgiou [27, 28, Marino-Winkert [35, 36, Papageorgiou-Winkert [39, Papageorgiou-Rǎdulescu [40], Papageorgiou-RǎdulescuRepovš [41, 42. In all the aforementioned papers, we find different types of nonhomogeneous operators and boundary value conditions, but we do not have multivalued terms as well as they do not deal with obstacle problems. For the problems dealing with multivalued terms modeled by Clarke's subdifferential we refer to the papers of Averna-Marano-Motreanu 1], Denkowski-Gasiński-Papageorgiou 10, 11, 12, 13, Filippakis-Gasiński-Papageorgiou 15, 16, Gasiński [17, 18, Gasiński-Motreanu-Papageorgiou [19], Gasiński-Papageorgiou [23, 24, Kalita-Kowalski 30], Papageorgiou-Vetro-Vetro [43, 44, Zeng-Liu-Migórski 45. None of them deals with nonhomogeneous operators and obstacle problems. Finally, for the problems dealing with obstacle problems we refer to the papers of Caffarelli-Salsa-Silvestre 4, Caffarelli-Ros-Oton-Serra [5], Choe [8], Choe-Lewis [9, Feehan-Pop [14], Oberman 38. As for the paper combining both nonhomogeneous operator and multivalued term provided by a subdifferential we refer to the paper of GasińskiPapageorgiou [25, although their approach is different from ours and is based on the nonsmooth critical point theory.

This article is organized as follows. In Section 2 we recall some definitions of function spaces needed in the sequel as well as the formulations of the main tools needed for our proofs, in particular the surjectivity results of Le 33 and Kluge's fixed point theorem. In Section 3 we provide the list of assumptions on the data of problem (1.1) and give the definition of the weak solution. In Section 4 we consider an auxiliary problem (see (4.2) and indicate some properties of its solution set. Finally, in Section 5 , we state and prove the main result of the paper (Theorem 5.1), which says that the solution set of (1.1) is a nonempty, bounded and weakly closed subset of $W_{0}^{1, p}(\Omega)$.

## 2. Preliminaries

For a bounded domain $\Omega \subseteq \mathbb{R}$ and $1 \leq r \leq \infty$, in what follows, by $L^{r}(\Omega)$ and $L^{r}\left(\Omega ; \mathbb{R}^{N}\right)$ we denote the usual Lebesgue spaces endowed with the norms denoted by $\|\cdot\|_{r}$. Moreover, $W_{0}^{1, r}(\Omega)$ stands for the Sobolev space endowed with the norm

$$
\|u\|=\|\nabla u\|_{r} \quad \text { for all } u \in W_{0}^{1, r}(\Omega)
$$

Let us now consider the eigenvalue problem for the $r$-Laplacian with homogeneous Dirichlet boundary condition and $1<r<\infty$ which is defined by

$$
\begin{gather*}
-\Delta_{r} u=\lambda|u|^{r-2} u \quad \text { in } \Omega  \tag{2.1}\\
u=0 \quad \text { on } \partial \Omega
\end{gather*}
$$

A number $\lambda \in \mathbb{R}$ is an eigenvalue of $\left(-\Delta_{r}, W_{0}^{1, r}(\Omega)\right)$ if problem 2.1 has a nontrivial solution $u \in W_{0}^{1, r}(\Omega)$ which is called an eigenfunction corresponding to the eigenvalue $\lambda$. We denote by $\sigma_{r}$ the set of eigenvalues of $\left(-\Delta_{r}, W_{0}^{1, r}(\Omega)\right)$. From Lê
[34] we know that the set $\sigma_{r}$ has a smallest element $\lambda_{1, r}$ which is positive, isolated, simple and it can be variationally characterized through

$$
\begin{equation*}
\lambda_{1, r}=\inf \left\{\frac{\|\nabla u\|_{r}^{r}}{\|u\|_{r}^{r}}: u \in W_{0}^{1, r}(\Omega), u \neq 0\right\} \tag{2.2}
\end{equation*}
$$

For $s>1$, we denote by $s^{\prime}=\frac{s}{s-1}$ its conjugate, the inner product in $\mathbb{R}^{N}$ is denoted by $\cdot$ and the norm of $\mathbb{R}^{N}$ is given by $|\cdot|$. Moreover, $\mathbb{R}_{+}=[0,+\infty)$ and the Lebesgue measure in $\mathbb{R}^{N}$ is denoted by $|\cdot|_{N}$.

Let $E$ be a Banach space with its topological dual $E^{*}$. A function $J: E \rightarrow \mathbb{R}$ is said to be locally Lipschitz at $u \in E$ if there exist a neighborhood $N(u)$ of $u$ and a constant $L_{u}>0$ such that

$$
|J(w)-J(v)| \leq L_{u}\|w-v\|_{E} \quad \text { for all } w, v \in N(u)
$$

Definition 2.1. Let $J: E \rightarrow \mathbb{R}$ be a locally Lipschitz function and let $u, v \in E$. The generalized directional derivative $J^{0}(u ; v)$ of $J$ at the point $u$ in the direction $v$ is defined by

$$
J^{0}(u ; v):=\limsup _{w \rightarrow u, t \downarrow 0} \frac{J(w+t v)-J(w)}{t}
$$

The generalized gradient $\partial J: E \rightarrow 2^{E^{*}}$ of $J: E \rightarrow \mathbb{R}$ is defined by

$$
\partial J(u):=\left\{\xi \in E^{*} \mid J^{0}(u ; v) \geq\langle\xi, v\rangle_{E^{*} \times E} \quad \text { for all } v \in E\right\} \quad \text { for all } u \in E .
$$

The next proposition collects some basic results (see Migórski-Ochal-Sofonea 37, Proposition 3.23]).

Proposition 2.2. Let $J: E \rightarrow \mathbb{R}$ be locally Lipschitz of rank $L_{u}>0$ at $u \in E$. Then we have
(a) the function $v \mapsto J^{0}(u ; v)$ is positively homogeneous, subadditive, and satisfies

$$
\left|J^{0}(u ; v)\right| \leq L_{u}\|v\|_{E} \text { for all } v \in E .
$$

(b) $(u, v) \mapsto J^{0}(u ; v)$ is upper semicontinuous.
(c) for each $u \in E, \partial J(u)$ is a nonempty, convex, and weak* compact subset of $E^{*}$ with $\|\xi\|_{E^{*}} \leq L_{u}$ for all $\xi \in \partial J(u)$.
(d) $J^{0}(u ; v)=\max \left\{\langle\xi, v\rangle_{E^{*} \times E} \mid \xi \in \partial J(u)\right\}$ for all $v \in E$.
(e) the multivalued function $E \ni u \mapsto \partial J(u) \subset E^{*}$ is upper semicontinuous from $E$ into $w^{*}-E^{*}$.

Next, let $\vartheta \in C^{1}(0, \infty)$ be any function satisfying

$$
\begin{equation*}
0<a_{1} \leq \frac{t \vartheta^{\prime}(t)}{\vartheta(t)} \leq a_{2} \quad \text { and } \quad a_{3} t^{p-1} \leq \vartheta(t) \leq a_{4}\left(t^{q-1}+t^{p-1}\right) \tag{2.3}
\end{equation*}
$$

for all $t>0$, with some constants $a_{i}>0, i \in\{1,2,3,4\}$ and for $1<q<p<\infty$. The hypotheses on $a: \bar{\Omega} \times \mathbb{R}^{N} \rightarrow \mathbb{R}^{N}$ are listed below.
(H1) $a(x, \xi)=a_{0}(x,|\xi|) \xi$ with $a_{0} \in C\left(\bar{\Omega} \times \mathbb{R}_{+}\right)$for all $\xi \in \mathbb{R}^{N}$ and with $a_{0}(x, t)>$ 0 for all $x \in \bar{\Omega}$, for all $t>0$ and
(i) $a_{0} \in C^{1}(\bar{\Omega} \times(0, \infty)), t \mapsto t a_{0}(x, t)$ is strictly increasing in $(0, \infty)$, $\lim _{t \rightarrow 0^{+}} t a_{0}(x, t)=0$ for all $x \in \bar{\Omega}$ and

$$
\lim _{t \rightarrow 0^{+}} \frac{t a_{0}^{\prime}(x, t)}{a_{0}(x, t)}=c>-1 \quad \text { for all } x \in \bar{\Omega}
$$

(ii) $\left|\nabla_{\xi} a(x, \xi)\right| \leq a_{5} \vartheta(|\xi|) /|\xi|$ for all $x \in \bar{\Omega}$, for all $\xi \in \mathbb{R}^{N} \backslash\{0\}$ and some $a_{5}>0$;
(iii) $\nabla_{\xi} a(x, \xi) y \cdot y \geq \vartheta(|\xi|)|y|^{2} /|\xi|$ for all $x \in \bar{\Omega}$, for all $\xi \in \mathbb{R}^{N} \backslash\{0\}$ and all $y \in \mathbb{R}^{N}$.
The following lemma summarizes some properties of the function $a: \bar{\Omega} \times \mathbb{R}^{N} \rightarrow \mathbb{R}^{N}$.
Lemma 2.3. If hypotheses (H1) hold, then:
(i) $a \in C\left(\bar{\Omega} \times \mathbb{R}^{N} ; \mathbb{R}^{N}\right) \cap C^{1}\left(\bar{\Omega} \times\left(\mathbb{R}^{N} \backslash\{0\}\right) ; \mathbb{R}^{N}\right)$ and for all $x \in \bar{\Omega}$ the map $\xi \mapsto a(x, \xi)$ is continuous, strictly monotone and so maximal monotone as well;
(ii) there exists $a_{6}>0$, such that $|a(x, \xi)| \leq a_{6}\left(1+|\xi|^{p-1}\right)$ for all $x \in \bar{\Omega}$ and $\xi \in \mathbb{R}^{N}$;
(iii) $a(x, \xi) \cdot \xi \geq \frac{a_{3}}{p-1}|\xi|^{p}$ for all $x \in \bar{\Omega}$ and for all $\xi \in \mathbb{R}^{N}$.

Lemma 2.4. Let $p \geq 2$. If the following condition holds,
(H2) $t \mapsto a_{0}(t) t-c_{a} t^{p-1}$ is increasing on $[0, \infty)$ with some $c_{a}>0$, then there exists a constant $m_{a}>0$ such that

$$
\left(a\left(x, \xi_{1}\right)-a\left(x, \xi_{2}\right), \xi_{1}-\xi_{2}\right)_{\mathbb{R}^{N}} \geq m_{a}\left|\xi_{1}-\xi_{2}\right|^{p}
$$

for all $\xi_{1}, \xi_{2} \in \mathbb{R}^{N}$ and a.e. $x \in \Omega$.
Proof. Since $p \geq 2$, it follows from Glowinski-Marroco [29, Lemma 5.1], that there exists a constant $m(p)>0$, which depends on $p$ only, such that

$$
\left(\left|\xi_{1}\right|^{p-2} \xi_{1}-\left|\xi_{2}\right|^{p-2} \xi_{2}\right) \cdot\left(\xi_{1}-\xi_{2}\right) \geq m(p)\left|\xi_{1}-\xi_{2}\right|^{p}
$$

for all $\xi_{1}, \xi_{2} \in \mathbb{R}^{N}$.
The monotonicity of $t \mapsto a_{0}(t) t-c_{a} t^{p-1}$ ensures that

$$
a_{0}(t) t-a_{0}(s) s \geq c_{a}\left(t^{p-1}-s^{p-1}\right)
$$

for all $t, s \in[0,+\infty)$ with $t \geq s$. This inequality leads to

$$
\begin{aligned}
& \left(a\left(\xi_{1}\right)-a\left(\xi_{2}\right), \xi_{1}-\xi_{2}\right)_{\mathbb{R}^{N}} \\
& =\left(a_{0}\left(\left|\xi_{1}\right|\right) \xi_{1}-a_{0}\left(\left|\xi_{2}\right|\right) \xi_{2}, \xi_{1}-\xi_{2}\right) \\
& =\left[a_{0}\left(\left|\xi_{1}\right|\right)\left|\xi_{1}\right|-a_{0}\left(\left|\xi_{2}\right|\right)\left|\xi_{2}\right|\right]\left[\left|\xi_{1}\right|-\left|\xi_{2}\right|\right]+\left[a_{0}\left(\left|\xi_{1}\right|\right)+a_{0}\left(\left|\xi_{2}\right|\right)\right]\left[\left|\xi_{1}\right|\left|\xi_{2}\right|-\xi_{1} \cdot \xi_{2}\right] \\
& \geq c_{a}\left[\left|\xi_{1}\right|^{p-1}-\left|\xi_{2}\right|^{p-1}\right]\left[\left|\xi_{1}\right|-\left|\xi_{2}\right|\right]+c_{a}\left[\left|\xi_{1}\right|^{p-2}+\left|\xi_{2}\right|^{p-2}\right]\left[\left|\xi_{1}\right|\left|\xi_{2}\right|-\xi_{1} \cdot \xi_{2}\right] \\
& =c_{a}\left(\left|\xi_{1}\right|^{p-2} \xi_{1}-\left|\xi_{2}\right|^{p-2} \xi_{2}\right) \cdot\left(\xi_{1}-\xi_{2}\right) \\
& \geq c_{a} m(p)\left|\xi_{1}-\xi_{2}\right|^{p}
\end{aligned}
$$

for all $\xi_{1}, \xi_{2} \in \mathbb{R}^{N}$. This means that the desired inequality is satisfied with $m_{a}=$ $c_{a} m(p)$.

Let us introduce the nonlinear operator $A: W_{0}^{1, p}(\Omega) \rightarrow W_{0}^{1, p}(\Omega)^{*}$ as follows

$$
\begin{equation*}
\langle A(u), \phi\rangle=\int_{\Omega}(a(x, \nabla u(x)), \nabla \phi(x))_{\mathbb{R}^{N}} d x \quad \text { for all } u, \phi \in W_{0}^{1, p}(\Omega) \tag{2.4}
\end{equation*}
$$

which possesses the following useful properties (see Gasiński-Papageorgiou [26]).
Proposition 2.5. If (H1) hold and the operator $A: W_{0}^{1, p}(\Omega) \rightarrow W_{0}^{1, p}(\Omega)^{*}$ is defined by (2.4), then $A$ is bounded, monotone, continuous, hence maximal monotone and of type $\left(S_{+}\right)$. Moreover, if the function $t \mapsto a_{0}(t) t-c_{a} t^{p-1}$ is increasing on $[0, \infty)$
with some $c_{a}>0$, then $A$ is strongly monotone with constant $m_{a}>0$, where $m_{a}$ is given in Lemma 2.4.

The following examples present some operators fitting in our setting.
Example 2.6. In the definitions of the operators $a$, we drop the dependence on $x$ just for simplicity. All the following maps satisfy (H1):
(i) If $a(\xi)=|\xi|^{p-2} \xi$ with $1<p<\infty$, then the corresponding operator is the classical $p$-Laplacian

$$
\Delta_{p} u=\operatorname{div}\left(|\nabla u|^{p-2} \nabla u\right) \quad \text { for all } u \in W^{1, p}(\Omega)
$$

(ii) If $a(\xi)=|\xi|^{p-2} \xi+\mu|\xi|^{q-2} \xi$ with $1<q<p<\infty$ and $\mu>0$, then the corresponding operator is the so called weighted $(p, q)$-Laplacian defined by $\Delta_{p} u+\mu \Delta_{q} u$ for all $u \in W^{1, p}(\Omega)$.
(iii) If $a(\xi)=\left(1+|\xi|^{2}\right)^{\frac{p-2}{2}} \xi$ with $1<p<\infty$, then this map represents the generalized $p$-mean curvature differential operator defined by

$$
\operatorname{div}\left[\left(1+|\nabla u|^{2}\right)^{\frac{p-2}{2}} \nabla u\right] \quad \text { for all } u \in W^{1, p}(\Omega)
$$

Besides, we recall the notion of pseudomonotonicity for multivalued operators (see e.g., Gasiński-Papageorgiou [22, Definition 1.4.8]).

Definition 2.7. Let $X$ be a real reflexive Banach space. The operator $A: X \rightarrow 2^{X^{*}}$ is called pseudomonotone if the following conditions hold:
(i) the set $A(u)$ is nonempty, bounded, closed and convex for all $u \in X$.
(ii) $A$ is upper semicontinuous from each finite-dimensional subspace of $X$ to the weak topology on $X^{*}$.
(iii) if $\left\{u_{n}\right\} \subset X$ with $u_{n} \rightharpoonup u$ in $X$ and if $u_{n}^{*} \in A\left(u_{n}\right)$ is such that

$$
\limsup _{n \rightarrow \infty}\left\langle u_{n}^{*}, u_{n}-u\right\rangle_{X^{*} \times X} \leq 0
$$

then to each element $v \in X$, exists $u^{*}(v) \in A(u)$ with

$$
\left\langle u^{*}(v), u-v\right\rangle_{X^{*} \times X} \leq \liminf _{n \rightarrow \infty}\left\langle u_{n}^{*}, u_{n}-v\right\rangle_{X^{*} \times X} .
$$

Furthermore, we will state the surjectivity theorem for multivalued mappings which are defined as the sum of a maximal monotone multivalued operator and a bounded multivalued pseudomonotone mapping. This theorem was proved in Le [33, Theorem 2.2]. We use the notation $B_{R}(0)=\left\{u \in X:\|u\|_{X}<R\right\}$.

Theorem 2.8. Let $X$ be a real reflexive Banach space, let $F: D(F) \subset X \rightarrow 2^{X^{*}}$ be a maximal monotone operator, let $G: D(G)=X \rightarrow 2^{X^{*}}$ be a bounded multivalued pseudomonotone operator and let $L \in X^{*}$. Assume that there exist $u_{0} \in X$ and $R \geq\left\|u_{0}\right\|_{X}$ such that $D(F) \cap B_{R}(0) \neq \emptyset$ and

$$
\left\langle\xi+\eta-L, u-u_{0}\right\rangle_{X^{*} \times X}>0
$$

for all $u \in D(F)$ with $\|u\|_{X}=R$, all $\xi \in F(u)$ and all $\eta \in G(u)$. Then there exists $u \in D(F) \cap D(G)$ such that

$$
F(u)+G(u) \ni L .
$$

Finally, we recall the fixed point theorem of Kluge [32] which will be used in the proof of our main existence result.

Theorem 2.9. Let $Z$ be a reflexive Banach space and let $C \subset Z$ be a nonempty, closed and convex set. Assume that $\Psi: C \rightarrow 2^{C}$ is a multivalued mapping such that for every $u \in C$, the set $\Psi(u)$ is nonempty, closed, and convex, and $\operatorname{Gr} \Psi$ (the graph of $\Psi)$ is sequentially weakly closed. If either $C$ is bounded or $\Psi(C)$ is bounded, then the map $\Psi$ has at least one fixed point in $C$.

## 3. Assumptions and Data Properties

To obtain the existence of solutions for problem 1.1), we need the following assumptions for the data of problem (1.1).
(H3) $f \in L^{p^{\prime}}(\Omega)$,
(H4) $j: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ is a function such that
(i) $x \mapsto j(x, r)$ is measurable on $\Omega$ for all $r \in \mathbb{R}$ and there exists a function $l \in L^{q_{1}}(\Omega)$ with $q_{1} \in\left(1, p^{*}\right)$ such that the function $x \mapsto j(x, l(x))$ belongs to $L^{1}(\Omega)$.
(ii) $r \mapsto j(x, r)$ is locally Lipschitz continuous for a.e. $x \in \Omega$.
(iii) there exist $\theta \geq 1$ with $\theta \leq \min \left\{q_{1}, p\right\}$, $\alpha_{j} \geq 0$ with $\alpha_{j} \lambda_{1, p}<\frac{a_{3}}{p-1} \delta_{\theta}$, and $\beta_{j} \in L_{+}^{1}(\Omega)$ such that for all $r \in \mathbb{R}$ and a.e. $x \in \Omega$ it holds

$$
j^{0}(x, r ;-r) \leq \alpha_{j}|r|^{\theta}+\beta_{j}(x)
$$

where

$$
\delta_{\theta}= \begin{cases}1 & \text { if } \theta=p \\ +\infty & \text { otherwise }\end{cases}
$$

(iv) there exist $c_{j} \geq 0$ and $\gamma_{j} \in L_{+}^{\frac{q_{1}}{q_{1}-1}}(\Omega)$ such that
$|\xi| \leq c_{j}|r|^{q_{1}-1}+\gamma_{j}(x)$ for all $\xi \in \partial j(x, r)$, all $r \in \mathbb{R}$ and a.e. $x \in \Omega$,
where $\partial j(x, r)$ stands for the generalized gradient of $j$ with respect to the variable $r$.
(v) there exists a constant $m_{j} \geq 0$ such that for all $r_{1}, r_{2} \in \mathbb{R}$ and a.e. $x \in \Omega$ the inequality is satisfied

$$
\left(\xi_{1}-\xi_{2}\right)\left(r_{1}-r_{2}\right) \geq-m_{j}\left|r_{1}-r_{2}\right|^{p}
$$

whenever $\xi_{1} \in \partial j\left(x, r_{1}\right)$ and $\xi_{2} \in \partial j\left(x, r_{2}\right)$.
(H5) $T: W_{0}^{1, p}(\Omega) \rightarrow \mathbb{R}$ is a positively homogeneous (i.e., $T(t u)=t T(u)$ for all $t>0$ and $\left.u \in W_{0}^{1, p}(\Omega)\right)$ and subadditive function such that

$$
\begin{equation*}
T(u) \leq \limsup _{n \rightarrow \infty} T\left(u_{n}\right) \tag{3.1}
\end{equation*}
$$

whenever $\left\{u_{n}\right\} \subset W_{0}^{1, p}(\Omega)$ is a sequence such that $u_{n} \rightharpoonup u$ in $W_{0}^{1, p}(\Omega)$, as $n \rightarrow \infty$, for some $u \in W_{0}^{1, p}(\Omega)$.
(H6) $U: W_{0}^{1, p}(\Omega) \rightarrow(0,+\infty)$ is weakly continuous, i.e., for any sequence $\left\{u_{n}\right\} \subset$ $W_{0}^{1, p}(\Omega)$ such that $u_{n} \rightharpoonup u$, as $n \rightarrow \infty$, for some $u \in W_{0}^{1, p}(\Omega)$, we have

$$
\begin{equation*}
U\left(u_{n}\right) \rightarrow U(u), \quad \text { as } n \rightarrow \infty \tag{3.2}
\end{equation*}
$$

Remark 3.1. Assumption (H4)(v) is usually called relaxed monotonicity condition (see e.g. Migórski-Ochal-Sofonea [37]) for the locally Lipschitz function $r \mapsto j(x, r)$. It is equivalent to the inequality

$$
j^{0}\left(x, s_{1} ; s_{2}-s_{1}\right)+j^{0}\left(x, s_{2} ; s_{1}-s_{2}\right) \leq m_{j}\left|s_{1}-s_{2}\right|^{p}
$$

for all $s_{1}, s_{2} \in \mathbb{R}$ and for a.e. $x \in \Omega$.
Indeed, positive homogeneity and subadditivity of $T$ confirm that $T$ is also a convex function. On the other hand, it is not difficult to see that if $T: W_{0}^{1, p}(\Omega) \rightarrow \mathbb{R}$ is lower semicontinuous, then inequality (3.1) holds automatically.

Let us introduce a multivalued map $K: W_{0}^{1, p}(\Omega) \rightarrow 2^{W_{0}^{1, p}(\Omega)}$ defined by

$$
\begin{equation*}
K(u)=\left\{v \in W_{0}^{1, p}(\Omega): T(v)-U(u) \leq 0\right\} \tag{3.3}
\end{equation*}
$$

for all $u \in W_{0}^{1, p}(\Omega)$.
Lemma 3.2. Assume that $T: W_{0}^{1, p}(\Omega) \rightarrow \mathbb{R}$ satisfies $H(T)$ and let $U: W_{0}^{1, p}(\Omega) \rightarrow$ $(0,+\infty)$ be any map. Then the map $K$ defined by (3.3) has nonempty, closed and convex values.

Proof. Let $u \in W_{0}^{1, p}(\Omega)$ be fixed. It follows from the positive homogeneity of $T$ and $U(u)>0$, that $T(0)=0<U(u)$, namely, $0 \in K(u) \neq \emptyset$ for each $u \in W_{0}^{1, p}(\Omega)$.

Let $\left\{v_{n}\right\} \subset K(u)$ be a sequence such that $v_{n} \rightarrow v$ in $W_{0}^{1, p}(\Omega)$ as $n \rightarrow \infty$ for some $v \in W_{0}^{1, p}(\Omega)$. Then, for each $n \in \mathbb{N}$, we have

$$
T\left(v_{n}\right) \leq U(u)
$$

Passing to the upper limit as $n \rightarrow \infty$ in the above inequality and using (3.1) we deduce that

$$
T(v) \leq \limsup _{n \rightarrow \infty} T\left(v_{n}\right) \leq U(u)
$$

This means that $v \in K(u)$, i.e., the set $K(u)$ is closed.
For any $v_{1}, v_{2} \in K(u)$ and $t \in(0,1)$ fixed, let us set $v_{t}=t v_{1}+(1-t) v_{2}$. Therefore, $T\left(v_{i}\right) \leq U(u)$ for $i=1,2$. However, the convexity of $T$ (see Remark 3.1) guarantees

$$
T\left(v_{t}\right) \leq t T\left(v_{1}\right)+(1-t) T\left(v_{2}\right) \leq t U(u)+(1-t) U(u)=U(u)
$$

which gives that $v_{t} \in K(u)$. Therefore, we conclude that the set $K(u)$ is convex in $W_{0}^{1, p}(\Omega)$.

The weak solutions for problem (1.1) are understood in the following sense.
Definition 3.3. We say that $u \in W_{0}^{1, p}(\Omega)$ is a weak solution of problem 1.1) if $u \in K(u)$ and

$$
\begin{aligned}
& \int_{\Omega}(a(x, \nabla u(x)), \nabla v(x)-\nabla u(x))_{\mathbb{R}^{N}} d x+\int_{\Omega} j^{0}(x, u(x) ; v(x)-u(x)) d x \\
& \geq \int_{\Omega} f(x)[v(x)-u(x)] d x
\end{aligned}
$$

for all $v \in K(u)$, where the multivalued function $K$ is given by (3.3).
Consider the function $J: L^{q_{1}}(\Omega) \rightarrow \mathbb{R}$ defined by

$$
\begin{equation*}
J(u)=\int_{\Omega} j(x, u(x)) d x \quad \text { for all } u \in L^{q_{1}}(\Omega) \tag{3.4}
\end{equation*}
$$

On account of hypotheses (H4) and the definition of $J$ (see (3.4), the next lemma is a direct consequence of Migórski-Ochal-Sofonea [37, Theorem 3.47].

Lemma 3.4. Under assumptions (H4)(i)-(iv), we have
(i) $J: L^{q_{1}}(\Omega) \rightarrow \mathbb{R}$ is locally Lipschitz continuous;
(ii) we have

$$
\begin{gathered}
J^{0}(u ; v) \leq \int_{\Omega} j^{0}(x, u(x) ; v(x)) d x \\
J^{0}(u ;-u) \leq \alpha_{j}\|u\|_{\theta}^{\theta}+\left\|\beta_{j}\right\|_{1}
\end{gathered}
$$

for all $u, v \in L^{q_{1}}(\Omega)$;
(iii) for each $u \in L^{q_{1}}(\Omega)$, we have

$$
\begin{gathered}
\partial J(u) \subset \int_{\Omega} \partial j(x, u(x)) d x \\
\|\xi\|_{q_{1}^{\prime}} \leq c_{J}\left(1+\|u\|_{q_{1}}^{q_{1}-1}\right) \quad \text { for all } \xi \in \partial J(u)
\end{gathered}
$$

with some $c_{J}>0$.
Moreover, if condition $(\mathrm{H} 4)(\mathrm{v})$ holds, then

$$
\begin{equation*}
J^{0}(u ; v-u)+J^{0}(v ; u-v) \leq m_{j}\|u-v\|_{p}^{p} \tag{3.5}
\end{equation*}
$$

for all $u, v \in W_{0}^{1, p}(\Omega)$.

## 4. Auxiliary problems

Employing Lemma 3.4 (ii) we know that if $u \in W_{0}^{1, p}(\Omega)$ solves the following problem: Find $u \in W_{0}^{1, p}(\Omega)$ such that $u \in K(u)$ and

$$
\begin{align*}
& \int_{\Omega}(a(x, \nabla u(x)), \nabla v(x)-\nabla u(x))_{\mathbb{R}^{N}} d x+J^{0}(u ; v-u) \\
& \geq \int_{\Omega} f(x)[v(x)-u(x)] d x \tag{4.1}
\end{align*}
$$

for all $v \in K(u)$, then $u$ is a weak solution to problem (1.1) as well. Using this fact, we will prove that problem 4.1) is solvable. To this end, first we investigate the following inequality problem:

Given $w \in W_{0}^{1, p}(\Omega)$, find $u \in K(w)$ such that

$$
\begin{align*}
& \int_{\Omega}(a(x, \nabla u(x)), \nabla v(x)-\nabla u(x))_{\mathbb{R}^{N}} d x+J^{0}(u ; v-u)  \tag{4.2}\\
& \geq \int_{\Omega} f(x)[v(x)-u(x)] d x
\end{align*}
$$

for all $v \in K(w)$. Additionally, consider the multivalued map $\Gamma: W_{0}^{1, p}(\Omega) \rightarrow$ $2^{W_{0}^{1, p}(\Omega)}$ given by

$$
\begin{equation*}
\Gamma(w)=\left\{u \in W_{0}^{1, p}(\Omega): u \text { solves problem } 4.2 \text { associated with } w\right\} \tag{4.3}
\end{equation*}
$$

for all $w \in W_{0}^{1, p}(\Omega)$. Indeed, it is not difficult to verify that $u \in W_{0}^{1, p}(\Omega)$ is a fixed point of $\Gamma$, if and only if $u$ solves problem 4.1). Motivated by this fact, we shall employ Kluge's fixed point theorem (see Theorem 2.9), to show that the fixed point set of $\Gamma$ is nonempty.
Theorem 4.1. Let $U: W_{0}^{1, p}(\Omega) \rightarrow(0,+\infty)$. Under the assumptions (H1), (H3), (H4)(i)-(iv) and (H5), we have
(i) for each $w \in W_{0}^{1, p}(\Omega)$, the set of solutions to problem 4.2 is nonempty, bounded, and closed in $W_{0}^{1, p}(\Omega)$, i.e., $\Gamma$ has nonempty, bounded, and closed values.
(ii) if $p \geq 2$, hypotheses $(\mathrm{H} 4)(\mathrm{v}), \mathrm{H}(0)$, and the smallness condition

$$
\begin{equation*}
m_{j} \lambda_{1, p}^{-1} \leq m_{a} \tag{4.4}
\end{equation*}
$$

are fulfilled, then for each $w \in W_{0}^{1, p}(\Omega)$, the set of solutions to problem (4.2) is convex, namely, $\Gamma(w)$ is convex.

Proof. (i) Let $w \in W_{0}^{1, p}(\Omega)$ be fixed and $I_{K(w)}: W_{0}^{1, p}(\Omega) \rightarrow \overline{\mathbb{R}}=\mathbb{R} \cup\{+\infty\}$ be the indicator function of $K(w)$, i.e.,

$$
I_{K(w)}(u)= \begin{cases}0 & \text { if } u \in K(w) \\ +\infty & \text { otherwise }\end{cases}
$$

Keeping in mind that $f \in L^{p^{\prime}}(\Omega) \subset W_{0}^{1, p}(\Omega)^{*}$, problem 4.2) can be rewritten equivalently to the following variational-hemivariational inequality: Find $u \in W_{0}^{1, p}(\Omega)$ such that

$$
\begin{equation*}
\langle A u, v-u\rangle+J^{0}(u ; v-u)+I_{K(w)}(v)-I_{K(w)}(u) \geq\langle f, v-u\rangle \tag{4.5}
\end{equation*}
$$

for all $v \in W_{0}^{1, p}(\Omega)$, where $A: W_{0}^{1, p}(\Omega) \rightarrow W_{0}^{1, p}(\Omega)^{*}$ is given by 2.4). However, by the Hahn-Banach Theorem, see e.g. Brezis [3, Theorem 1.6 (the first geometric form)], it is not difficult to prove that problem (4.5) is equivalent to the following inclusion problem: Find $u \in W_{0}^{1, p}(\Omega)$ such that

$$
\begin{equation*}
A u+\partial J(u)+\partial_{C} I_{K(w)}(u) \ni f, \tag{4.6}
\end{equation*}
$$

where the notation $\partial_{C} I_{K(w)}$ stands for the subdifferential of $I_{K(w)}$ in the sense of convex analysis.

We shall use the surjectivity result (see Theorem 2.8), to show that problem (4.6) is solvable in $W_{0}^{1, p}(\Omega)$. For this reason, we start with the following claim.

Claim 1. $A+\partial J: W_{0}^{1, p}(\Omega) \rightarrow 2^{W_{0}^{1, p}(\Omega)^{*}}$ is a bounded pseudomonotone multivalued operator such that for each $u \in W_{0}^{1, p}(\Omega)$, the set $A(u)+\partial J(u)$ is closed and convex in $W_{0}^{1, p}(\Omega)^{*}$.

Directly from Proposition 2.2 and Lemma 3.4 we see the set $A(u)+\partial J(u)$ is closed and convex in $W_{0}^{1, p}(\Omega)^{*}$ for each $u \in W_{0}^{1, p}(\Omega)$. Moreover, Proposition 2.5 Lemma 3.4 (iii) and the fact $q_{1}<p^{*}$ indicate that $W_{0}^{1, p}(\Omega) \ni u \mapsto A(u)+\partial J(u) \subset$ $W_{0}^{1, p}(\Omega)^{*}$ is a bounded map.

Next, we assert that $W_{0}^{1, p}(\Omega) \ni u \mapsto A(u)+\partial J(u) \subset W_{0}^{1, p}(\Omega)^{*}$ is upper semicontinuous from $W_{0}^{1, p}(\Omega)$ to $W_{0}^{1, p}(\Omega)^{*}$ with weak topology. By f Migórski-Ochal-Sofonea [37, Proposition 3.8], it is sufficient to show that for any weakly closed subset $D$ in $W_{0}^{1, p}(\Omega)^{*}$, the set $(A+\partial J)^{-}(D)$ is closed in $W_{0}^{1, p}(\Omega)$. Let $\left\{u_{n}\right\} \subset(A+\partial J)^{-}(D)$ be a sequence such that

$$
\begin{equation*}
u_{n} \rightarrow u \quad \text { in } W_{0}^{1, p}(\Omega) \text { as } n \rightarrow \infty, \text { for some } u \in W_{0}^{1, p}(\Omega) \tag{4.7}
\end{equation*}
$$

So, for each $n \in \mathbb{N}$, we are able to find $\xi_{n} \in \partial J\left(u_{n}\right)$ such that

$$
u_{n}^{*}=A u_{n}+\xi_{n} \in\left(A\left(u_{n}\right)+\partial J\left(u_{n}\right)\right) \cap D .
$$

But, the continuity of $A$ (see Proposition 2.5) ensures that $A\left(u_{n}\right) \rightarrow A(u)$ in $W_{0}^{1, p}(\Omega)^{*}$, as $n \rightarrow \infty$. Taking into account Lemma 3.4 (iii) and convergence (4.7), we conclude that the sequence $\left\{\xi_{n}\right\}$ is bounded in $W_{0}^{1, p}(\Omega)^{*}$, so, without any loss of generality, we may assume that $\xi_{n} \rightharpoonup \xi$ in $W_{0}^{1, p}(\Omega)^{*}$, as $n \rightarrow \infty$, with
some $\xi \in W_{0}^{1, p}(\Omega)^{*}$. Notice that $\partial J$ is upper semicontinuous from $W_{0}^{1, p}(\Omega)$ to w$W_{0}^{1, p}(\Omega)^{*}$ and has bounded, convex, closed values (see Proposition 2.2 (d)), so, it has a closed graph in $W_{0}^{1, p}(\Omega) \times \mathrm{w}-W_{0}^{1, p}(\Omega)^{*}$ (see Kamenskii-Obukhovskii-Zecca [31, Theorem 1.1.4]). But, thanks to the weak closedness of $D$, we derive that $A(u)+\xi \in D$ and $\xi \in \partial J(u)$, which provides that $u \in(A+\partial J)^{-}(D)$. Consequently, $A+\partial J$ is upper semicontinuous from $W_{0}^{1, p}(\Omega)$ to $W_{0}^{1, p}(\Omega)^{*}$ with weak topology.

Next, we show that $A+\partial J$ is pseudomonotone. Let $\left\{u_{n}\right\}$ and $\left\{u_{n}^{*}\right\}$ be sequences such that

$$
\begin{gather*}
u_{n} \rightharpoonup u \quad \text { in } W_{0}^{1, p}(\Omega)  \tag{4.8}\\
u_{n}^{*} \in A\left(u_{n}\right)+\partial J\left(u_{n}\right) \quad \text { with } \underset{n \rightarrow \infty}{\limsup }\left\langle u_{n}^{*}, u_{n}-u\right\rangle \leq 0 \tag{4.9}
\end{gather*}
$$

Our goal is to show that for each $v \in W_{0}^{1, p}(\Omega)$ there exists an element $u^{*}(v) \in$ $A(u)+\partial J(u)$ such that

$$
\begin{equation*}
\liminf _{n \rightarrow \infty}\left\langle u_{n}^{*}, u_{n}-v\right\rangle \geq\left\langle u^{*}(v), u-v\right\rangle \tag{4.10}
\end{equation*}
$$

From 4.9), we are able to find a sequence $\left\{\xi_{n}\right\} \subset W_{0}^{1, p}(\Omega)^{*}$ such that for each $n \in \mathbb{N}, \xi_{n} \in \partial J\left(u_{n}\right)$ and

$$
u_{n}^{*}=A\left(u_{n}\right)+\xi_{n} .
$$

The latter combined with the inequality in 4.9 implies

$$
\begin{equation*}
\limsup _{n \rightarrow \infty}\left\langle A u_{n}, u_{n}-u\right\rangle+\liminf _{n \rightarrow \infty}\left\langle\xi_{n}, u_{n}-u\right\rangle \leq 0 \tag{4.11}
\end{equation*}
$$

Applying (4.8) and the compactness of the embedding of $W_{0}^{1, p}(\Omega)$ into $L^{q_{1}}(\Omega)$, gives

$$
u_{n} \rightarrow u \quad \text { in } L^{q_{1}}(\Omega), \quad \text { as } n \rightarrow \infty
$$

On the other hand, employing Chang [7. Theorem 2.2], we have

$$
\partial\left(\left.J\right|_{W_{0}^{1, p}(\Omega)}\right)(u) \subset \partial\left(\left.J\right|_{L^{q_{1}}(\Omega)}\right)(u) \quad \text { for all } u \in W_{0}^{1, p}(\Omega)
$$

which implies that

$$
\begin{equation*}
\left\langle\xi_{n}, u_{n}-u\right\rangle=\left\langle\xi_{n}, u_{n}-u\right\rangle_{L^{q_{1}}(\Omega)} . \tag{4.12}
\end{equation*}
$$

Additionally, Lemma 3.4 (iii) and the boundedness of the sequence $\left\{u_{n}\right\}$ in $W_{0}^{1, p}(\Omega)$ implies that the sequence $\left\{\xi_{n}\right\}$ is contained in $L^{q_{1}}(\Omega)$. Then, passing to the limit in 4.12) as $n \rightarrow \infty$ to obtain

$$
\lim _{n \rightarrow \infty}\left\langle\xi_{n}, u_{n}-u\right\rangle=\lim _{n \rightarrow \infty}\left\langle\xi_{n}, u_{n}-u\right\rangle_{L^{q_{1}}(\Omega)}=0
$$

Inserting the above equality into 4.11 yields

$$
\limsup _{n \rightarrow \infty}\left\langle A u_{n}, u_{n}-u\right\rangle=\limsup _{n \rightarrow \infty}\left\langle A u_{n}, u_{n}-u\right\rangle+\liminf _{n \rightarrow \infty}\left\langle\xi_{n}, u_{n}-u\right\rangle \leq 0
$$

The latter combined with Proposition 2.5 (i.e., the fact that $A$ is type of $\left(S_{+}\right)$) and (4.8) finds that $u_{n} \rightarrow u$ in $W_{0}^{1, p}(\Omega)$, as $n \rightarrow \infty$. Moreover, the reflexivity of $W_{0}^{1, p}(\Omega)^{*}$ and boundedness of $\left\{\xi_{n}\right\} \subset W_{0}^{1, p}(\Omega)^{*}$ permit us to conclude that

$$
\xi_{n} \rightharpoonup \xi \text { in } W_{0}^{1, p}(\Omega)^{*} \quad \text { for some } \xi \in W_{0}^{1, p}(\Omega)^{*}
$$

Now we can assert that $\xi \in \partial J(u)$ (see, e.g., Kamenskii-Obukhovskii-Zecca 31, Theorem 1.1.4]). Now, because

$$
\liminf _{n \rightarrow \infty}\left\langle u_{n}^{*}, u_{n}-v\right\rangle=\liminf _{n \rightarrow \infty}\left\langle A\left(u_{n}\right)+\xi_{n}, u_{n}-v\right\rangle=\langle A(u)+\xi, u-v\rangle,
$$

it is clear that 4.10 holds with $u^{*}=A(u)+\xi \in A(u)+\partial J(u)$. Therefore, $A+\partial J$ is pseudomonotone. This proves Claim 1.

Next, we prove that there exists $R>0$ such that

$$
\begin{equation*}
\langle A u+\xi+\eta-f, u\rangle>0 \tag{4.13}
\end{equation*}
$$

for all $u \in K(w)$ with $\|u\|=R$, all $\xi \in \partial J(u)$ and all $\eta \in \partial_{C}\left(I_{K(w)}\right)(u)$.
For this purpose, let $u \in W_{0}^{1, p}(\Omega)$ be fixed. For any $\xi \in \partial J(u)$ and $\eta \in$ $\partial_{C}\left(I_{K(w)}\right)(u)$, since $0 \in K(w)$ and $f \in L^{p^{\prime}}(\Omega) \subset W_{0}^{1, p}(\Omega)^{*}$, we have

$$
\begin{align*}
& \langle A u+\xi+\eta-f, u\rangle \\
& \geq \int_{\Omega}(a(x, \nabla u(x)), \nabla u(x))_{\mathbb{R}^{N}} d x+\int_{\Omega} \xi(x) u(x) d x+I_{K(w)}(u)-I_{K(w)}(0) \\
& \quad-\|f\|_{W_{0}^{1, p}(\Omega)^{*}}\|u\|  \tag{4.14}\\
& \geq \frac{a_{3}}{p-1}\|\nabla u\|_{p}^{p}-\int_{\Omega} \xi(x)[-u(x)] d x+I_{K(w)}(u)-\|f\|_{W_{0}^{1, p}(\Omega)^{*}}\|u\| \\
& \geq \frac{a_{3}}{p-1}\|\nabla u\|_{p}^{p}-J^{0}(u ;-u)+I_{K(w)}(u)-\|f\|_{W_{0}^{1, p}(\Omega)^{*}}\|u\|,
\end{align*}
$$

where we have used Lemma 2.3 (iii). Notice that $I_{K(w)}: W_{0}^{1, p}(\Omega) \rightarrow \overline{\mathbb{R}}$ is a proper, convex and lower semicontinuous function, so we now apply Gasiński-Papageorgiou [22, Proposition 1.3.1], for finding $a_{K(w)}, b_{K(w)} \geq 0$ such that

$$
\begin{equation*}
I_{K(w)}(v) \geq-a_{K(w)}\|v\|-b_{K(w)} \quad \text { for all } v \in W_{0}^{1, p}(\Omega) \tag{4.15}
\end{equation*}
$$

Additionally, Lemma 3.4(ii) implies that

$$
\begin{equation*}
J^{0}(u ;-u) \leq \alpha_{j}\|u\|_{\theta}^{\theta}+\left\|\beta_{j}\right\|_{1} \tag{4.16}
\end{equation*}
$$

We now distinguish two cases: $\theta<p$ and $\theta=p$. When $\theta<p$, let $c(\theta)>0$ be such that

$$
\begin{equation*}
\|u\|_{\theta} \leq c(\theta)\|u\| \quad \text { for all } u \in W_{0}^{1, p}(\Omega) \tag{4.17}
\end{equation*}
$$

(its existence is follows from the continuity of the embedding from $W_{0}^{1, p}(\Omega)$ to $L^{r}(\Omega)$ for any $\left.r \in\left(1, p^{*}\right)\right)$. Inserting 4.15 and 4.16) into 4.14 and using 4.17), we have

$$
\begin{align*}
\langle A u+\xi+\eta-f, u\rangle \geq & \frac{a_{3}}{p-1}\|\nabla u\|_{p}^{p}-\alpha_{j}\|u\|_{\theta}^{\theta}-\left\|\beta_{j}\right\|_{1}-a_{K(w)}\|u\| \\
& -b_{K(w)}-\|f\|_{W_{0}^{1, p}(\Omega)^{*}}\|u\| \\
\geq & \frac{a_{3}}{p-1}\|u\|^{p}-\alpha_{j} c(\theta)^{\theta}\|u\|^{\theta}-\left\|\beta_{j}\right\|_{1}-a_{K(w)}\|u\|  \tag{4.18}\\
& -b_{K(w)}-\|f\|_{W_{0}^{1, p}(\Omega)^{*}}\|u\| .
\end{align*}
$$

Since $\theta<p$, we can find a constant $R_{0}>0$ large enough such that

$$
\frac{a_{3}}{p-1} R_{0}^{p}-\alpha_{j} c(\theta)^{\theta} R_{0}^{\theta}-\left\|\beta_{j}\right\|_{1}-a_{K(w)} R_{0}-b_{K(w)}-\|f\|_{W_{0}^{1, p}(\Omega)^{*}} R_{0}>0
$$

Therefore, for each $R \geq R_{0}$ fixed, the desired inequality 4.13 holds.

Next, if $\theta=p$, using variational characterization of $\lambda_{1, p}$ (see 2.2), we deduce that

$$
\begin{align*}
& \langle A u+\xi+\eta-f, u\rangle \\
& \geq \frac{a_{3}}{p-1}\|\nabla u\|_{p}^{p}-\alpha_{j}\|u\|_{p}^{p}-\left\|\beta_{j}\right\|_{1}-a_{K(w)}\|u\|-b_{K(w)}-\|f\|_{W_{0}^{1, p}(\Omega)^{*}}\|u\|  \tag{4.19}\\
& \geq\left(\frac{a_{3}}{p-1}-\alpha_{j} \lambda_{1, p}^{-1}\right)\|\nabla u\|_{p}^{p}-\left\|\beta_{j}\right\|_{1}-a_{K(w)}\|u\|-b_{K(w)}-\|f\|_{W_{0}^{1, p}(\Omega)^{*}}\|u\|
\end{align*}
$$

As $1<p$ and $\alpha_{j} \lambda_{1, p}^{-1}<\frac{a_{3}}{p-1}$, we can take $R_{0}>0$ large enough such that for all $R \geq R_{0}$ it holds

$$
\left(\frac{a_{3}}{p-1}-\alpha_{j} \lambda_{1, p}^{-1}\right) R^{p}-\left\|\beta_{j}\right\|_{1}-a_{K(w)} R-b_{K(w)}-\|f\|_{W_{0}^{1, P}(\Omega)^{*}} R>0
$$

Therefore, the inequality (4.13) holds.
Recall that $I_{K(w)}: W_{0}^{1, p}(\Omega) \rightarrow \overline{\mathbb{R}}$ is a proper, convex and lower semicontinuous function, so, $\partial_{C} I_{K(w)}: W_{0}^{1, p}(\Omega) \rightarrow 2^{W_{0}^{1, p}(\Omega)^{*}}$ is maximal monotone. The latter together with Theorem 2.8 implies that there exists $u_{w} \in W_{0}^{1, p}(\Omega)$ resolving inclusion 4.6. Thus, $\Gamma(w) \neq \emptyset$ for each $w \in W_{0}^{1, p}(\Omega)$.

Next, we demonstrate that $\Gamma(w)$ is closed in $W_{0}^{1, p}(\Omega)$. Let $\left\{u_{n}\right\} \subset \Gamma(w)$ be such that

$$
u_{n} \rightarrow u \text { in } W_{0}^{1, p}(\Omega) \text { as } n \rightarrow \infty
$$

for some $u \in W_{0}^{1, p}(\Omega)$. So, for each $n \in \mathbb{N}$, we have

$$
\left\langle A u_{n}, v-u_{n}\right\rangle+J^{0}\left(u_{n} ; v-u_{n}\right)+I_{K(w)}(v)-I_{K(w)}\left(u_{n}\right) \geq\left\langle f, v-u_{n}\right\rangle
$$

for all $v \in W_{0}^{1, p}(\Omega)$. Passing to the upper limit as $n \rightarrow \infty$ in the above inequality, we obtain

$$
\begin{aligned}
& \langle A u, v-u\rangle+J^{0}(u ; v-u)+I_{K(w)}(v)-I_{K(w)}(u) \\
& \geq \limsup _{n \rightarrow \infty}\left[\left\langle A u_{n}, v-u_{n}\right\rangle+J^{0}\left(u_{n} ; v-u_{n}\right)+I_{K(w)}(v)-I_{K(w)}\left(u_{n}\right)\right] \\
& \geq \limsup _{n \rightarrow \infty}\left\langle f, v-u_{n}\right\rangle \\
& =\langle f, v-u\rangle
\end{aligned}
$$

for all $v \in W_{0}^{1, p}(\Omega)$, where we have used the continuity of $A$ (see Proposition 2.5), upper semicontinuity of $(u, v) \mapsto J^{0}(u ; v)$ (see Proposition $2.2(\mathrm{~d})$ ) and lower semicontinuity of $I_{K(w)}$. This indicates that $u \in \Gamma(w)$, hence $\Gamma(w)$ is closed.

Finally, we prove that $\Gamma(w)$ is bounded. Arguing by contradiction, we suppose that $\Gamma(w)$ is unbounded. Then there exists a sequence $\left\{u_{n}\right\}$ in $\Gamma(w)$ such that

$$
\begin{equation*}
\left\|u_{n}\right\| \rightarrow+\infty \quad \text { as } n \rightarrow \infty \tag{4.20}
\end{equation*}
$$

By a simple computation (see (4.18) and (4.19), we are able to find $N_{0} \in \mathbb{N}$ such the for all $n \geq N_{0}$, it holds

$$
0 \geq\left\langle A u_{n}, u_{n}\right\rangle-J^{0}\left(u_{n} ;-u_{n}\right)+I_{K(w)}\left(u_{n}\right)>0
$$

where we have used the fact $0 \in K(w)$ and 4.20 . This leads to a contradiction. Therefore, $\Gamma(w)$ is bounded.
(ii) Assume that hypothesis (H3)(v) holds. Let $u_{1}, u_{2} \in W_{0}^{1, p}(\Omega)$ be two solutions to problem 4.2. Hence

$$
\left\langle A u_{i}, v-u_{i}\right\rangle+J^{0}\left(u_{i} ; v-u_{i}\right)+I_{K(w)}(v)-I_{K(w)}\left(u_{i}\right) \geq\left\langle f, v-u_{i}\right\rangle
$$

for all $v \in W_{0}^{1, p}(\Omega)$ and for $i=1,2$. But, Proposition 2.5 and Lemma 3.4 give

$$
\begin{aligned}
0 & \geq\left\langle A v_{1}-A v_{2}, v_{1}-v_{2}\right\rangle-\left(J^{0}\left(v_{1} ; v_{2}-v_{1}\right)+J^{0}\left(v_{2} ; v_{1}-v_{2}\right)\right) \\
& \geq m_{a}\left\|\nabla v_{1}-\nabla v_{2}\right\|_{p}^{p}-m_{j}\left\|v_{1}-v_{2}\right\|_{p}^{p} \\
& \geq\left(m_{a}-m_{j} \lambda_{1, p}^{-1}\right)\left\|v_{1}-v_{2}\right\|_{p}^{p} \geq 0
\end{aligned}
$$

for all $v_{1}, v_{2} \in W_{0}^{1, p}(\Omega)$. Hence, for $i=1,2$, we have

$$
\left\langle A v, v-u_{i}\right\rangle+J^{0}\left(v ; v-u_{i}\right)+I_{K(w)}(v)-I_{K(w)}\left(u_{i}\right) \geq\left\langle f, v-u_{i}\right\rangle
$$

for all $v \in W_{0}^{1, p}(\Omega)$. Let $t \in(0,1)$ be arbitrary and let us put $u_{t}=t u_{1}+(1-t) u_{2}$. Therefore, we have

$$
\begin{aligned}
& \left\langle A v, v-u_{t}\right\rangle+J^{0}\left(v ; v-u_{t}\right)+I_{K(w)}(v)-I_{K(w)}\left(u_{t}\right) \\
& \geq t\left[\left\langle A v, v-u_{1}\right\rangle+J^{0}\left(v ; v-u_{1}\right)+I_{K(w)}(v)-I_{K(w)}\left(u_{1}\right)\right] \\
& \quad+(1-t)\left[\left\langle A v, v-u_{2}\right\rangle+J^{0}\left(v ; v-u_{2}\right)+I_{K(w)}(v)-I_{K(w)}\left(u_{2}\right)\right] \\
& \geq\left\langle f, v-u_{t}\right\rangle
\end{aligned}
$$

for all $v \in W_{0}^{1, p}(\Omega)$.
Now, employing the Minty approach we obtain that $u_{t} \in \Gamma(w)$. Consequently, the set $\Gamma(w)$ is convex in $W_{0}^{1, p}(\Omega)$.

## 5. Main Result

Now we can state the main result of the paper. Its proof is based on Theorem4.1 and Kluge's fixed point theorem (see Theorem 2.9.
Theorem 5.1. Assume that (H1), (H3)-(H5), (H6) hold and $p \geq 2$. If, in addition, (H2)) and the smallness condition (4.4) are satisfied, then the set of solutions of problem 1.1), denoted by $\mathcal{S}$, is nonempty, bounded and weakly closed.

Proof. As we have already mentioned, the fixed point set of $\Gamma$ (see (4.3p) is the corresponding set of solutions to problem 4.1). Besides, Lemma 3.2 points out that the set of solutions for problem 4.1) is a subset of the set of solutions for problem 1.1. Consequently, it suffices to prove that the fixed point set of $\Gamma$ is nonempty.

First we show that

$$
\begin{equation*}
\mathrm{Gr} \Gamma \text { is sequentially weakly closed. } \tag{5.1}
\end{equation*}
$$

For this purpose, let $\left\{w_{n}\right\},\left\{u_{n}\right\} \subset W_{0}^{1, p}(\Omega)$ be two sequences such that $w_{n} \rightharpoonup w$ in $W_{0}^{1, p}(\Omega)$ and $u_{n} \in \Gamma\left(w_{n}\right)$ with $u_{n} \rightharpoonup u$ in $W_{0}^{1, p}(\Omega)$, as $n \rightarrow \infty$, for some $w, u \in$ $W_{0}^{1, p}(\Omega)$. Then, for each $n \in \mathbb{N}$, we have $u_{n} \in K\left(w_{n}\right)$ (namely, $T\left(u_{n}\right) \leq U\left(u_{n}\right)$ ) and

$$
\begin{equation*}
\left\langle A u_{n}, v-u_{n}\right\rangle+J^{0}\left(u_{n} ; v-u_{n}\right) \geq\left\langle f, v-u_{n}\right\rangle \tag{5.2}
\end{equation*}
$$

for all $v \in K\left(w_{n}\right)$.
However, hypotheses (H5) and (H6) imply that

$$
T(u) \leq \limsup _{n \rightarrow \infty} T\left(u_{n}\right) \leq \limsup _{n \rightarrow \infty} U\left(w_{n}\right) \leq U(w)
$$

This means $u \in K(w)$.

For any $v \in K(w)$ fixed, owing to $U(w)>0$, we now consider the sequence $\left\{v_{n}\right\}$ constructed by

$$
v_{n}=\frac{U\left(w_{n}\right)}{U(w)} v \quad \text { for all } n \in \mathbb{N}
$$

The non-negativity of $U$, positive homogeneity of $T$ and the fact that $v \in K(w)$ (thus is, $T(v) \leq U(w)$ ) give

$$
T\left(v_{n}\right)=T\left(\frac{U\left(w_{n}\right)}{U(w)} v\right)=\frac{U\left(w_{n}\right)}{U(w)} T(v) \leq \frac{U\left(w_{n}\right) U(w)}{U(w)}=U\left(w_{n}\right)
$$

hence $v_{n} \in K\left(w_{n}\right)$. Moreover, a simple calculating gives

$$
\lim _{n \rightarrow \infty}\left\|v_{n}-v\right\|=\lim _{n \rightarrow \infty}\left|U\left(w_{n}\right)-U(w)\right| \frac{\|v\|}{U(w)}=0
$$

Thus, we obtain that $v_{n} \rightarrow v$, as $n \rightarrow \infty$.
Since $u \in K(w)$, we can take the sequence $\left\{\bar{u}_{n}\right\} \subset W_{0}^{1, p}(\Omega)$ such that $\bar{u}_{n}=$ $\frac{U\left(w_{n}\right)}{U(w)} u \in K\left(w_{n}\right)$ for each $n \in \mathbb{N}$ and

$$
\bar{u}_{n} \rightarrow u \quad \text { as } n \rightarrow \infty .
$$

Inserting $v=\bar{u}_{n}$ into 5 gives

$$
\begin{equation*}
\left\langle A u_{n}, u_{n}-\bar{u}_{n}\right\rangle \leq J^{0}\left(u_{n} ; \bar{u}_{n}-u_{n}\right)-\left\langle f, \bar{u}_{n}-u_{n}\right\rangle . \tag{5.3}
\end{equation*}
$$

It follows from Lemma 3.4 and the convergence $u_{n} \rightarrow u$ in $L^{q_{1}}(\Omega)$, as $n \rightarrow \infty$ that

$$
\limsup _{n \rightarrow \infty} J^{0}\left(u_{n} ; \bar{u}_{n}-u_{n}\right) \leq 0
$$

Passing to the upper limit as $n \rightarrow \infty$ into 5.3) and using the above inequality, we have

$$
\begin{aligned}
\limsup _{n \rightarrow \infty}\left\langle A u_{n}, u_{n}-u\right\rangle & \leq \limsup _{n \rightarrow \infty}\left\langle A u_{n}, u_{n}-u\right\rangle+\liminf _{n \rightarrow \infty}\left\langle A u_{n}, u-\bar{u}_{n}\right\rangle \\
& \leq \limsup _{n \rightarrow \infty}\left\langle A u_{n}, u_{n}-\bar{u}_{n}\right\rangle \\
& \leq \limsup _{n \rightarrow \infty} J^{0}\left(u_{n} ; \bar{u}_{n}-u_{n}\right)-\liminf _{n \rightarrow \infty}\left\langle f, \bar{u}_{n}-u_{n}\right\rangle \leq 0
\end{aligned}
$$

The latter combined with Proposition 2.5 ( $A$ is of type $\left(S_{+}\right)$) implies $u_{n} \rightarrow u$ in $W_{0}^{1, p}(\Omega)$, as $n \rightarrow \infty$.

For any $v \in K(w)$ fixed, let $\left\{v_{n}\right\} \subset W_{0}^{1, p}(\Omega)$ be such that $v_{n} \in K\left(w_{n}\right)$ for each $n \in \mathbb{N}$ and $v_{n} \rightarrow v$ in $W_{0}^{1, p}(\Omega)$, as $n \rightarrow \infty$. We put $v=v_{n}$ in 5.2 and then pass to the upper limit as $n \rightarrow \infty$, to obtain

$$
\begin{aligned}
\langle A u, v-u\rangle+J^{0}(u ; v-u) & \geq \limsup _{n \rightarrow \infty}\left\langle A u_{n}, v_{n}-u_{n}\right\rangle+\limsup _{n \rightarrow \infty} J^{0}\left(u_{n} ; v_{n}-u_{n}\right) \\
& \geq \limsup _{n \rightarrow \infty}\left[\left\langle A u_{n}, v_{n}-u_{n}\right\rangle+J^{0}\left(u_{n} ; v_{n}-u_{n}\right)\right] \\
& \geq \limsup _{n \rightarrow \infty}\left\langle f, v_{n}-u_{n}\right\rangle=\langle f, v-u\rangle
\end{aligned}
$$

where we have used the upper semicontinuity of $L^{q_{1}}(\Omega) \times L^{q_{1}}(\Omega) \ni(v, u) \rightarrow$ $J^{0}(u ; v) \in \mathbb{R}$ (see Proposition 2.2). Hence, $u \in \Gamma(w)$. Therefore, we conclude that $\operatorname{Gr} \Gamma$ is sequentially weakly closed. This proves (5.1).

Next we show that

$$
\begin{equation*}
\text { the set } \Gamma\left(W_{0}^{1, p}(\Omega)\right) \text { is bounded in } W_{0}^{1, p}(\Omega) \tag{5.4}
\end{equation*}
$$

If the above were not true, then there would exist a sequence $\left\{w_{n}\right\}$ such that

$$
\begin{equation*}
\left\|u_{n}\right\| \rightarrow \infty \quad \text { as } n \rightarrow \infty \tag{5.5}
\end{equation*}
$$

where $u_{n}=\Gamma\left(w_{n}\right)$. For every $n \in \mathbb{N}$, one has (5.2) for all $v \in K\left(w_{n}\right)$. Keeping in mind that $0 \in K(w)$ for each $w \in W_{0}^{1, p}(\Omega)$, we take $v=0$ as test function in 5.2 obtaining

$$
\left\langle A u_{n}, u_{n}\right\rangle-J^{0}\left(u_{n} ;-u_{n}\right) \leq\|f\|_{W_{0}^{1, p}(\Omega)^{*}}\left\|u_{n}\right\| .
$$

Using the same argument as in the proof of Theorem 4.1 (see 4.18) or 4.19) , we could find $N_{0} \in \mathbb{N}$ large enough such that

$$
0<\left\langle A u_{n}, u_{n}\right\rangle-J^{0}\left(u_{n} ;-u_{n}\right)-\|f\|_{W_{0}^{1, p}(\Omega)^{*}}\left\|u_{n}\right\| \leq 0
$$

for all $n \geq N_{0}$, this gives a contradiction. Therefore, we conclude that the set $\Gamma\left(W_{0}^{1, p}(\Omega)\right)$ is bounded in $W_{0}^{1, p}(\Omega)$. This proves 5.4.

To conclude the proof, we need to verify the conditions of Theorem 2.9 for the mapping $\Gamma$. Then, $\Gamma$ will admit a fixed point in $W_{0}^{1, p}(\Omega)$, which will imply that problem (1.1) has at least one weak solution in $W_{0}^{1, p}(\Omega)$.

Indeed, the boundedness of $\mathcal{S}$ can be obtained directly via using the analogous arguments as in the proof of (5.4).

It remains to illustrate the weak closedness of $\mathcal{S}$. Let $\left\{u_{n}\right\} \subset \mathcal{S}$ be a sequence such that $u_{n} \rightharpoonup u$ in $W_{0}^{1, p}(\Omega)$, as $n \rightarrow \infty$, for some $u \in W_{0}^{1, p}(\Omega)$. Hence, for each $n \in \mathbb{N}$, it is easy to see that $u_{n} \in K\left(u_{n}\right)$ and

$$
\begin{equation*}
\left\langle A v, v-u_{n}\right\rangle+\int_{\Omega} j^{0}\left(v(x) ; v(x)-u_{n}(x)\right) d x \geq\left\langle f, v-u_{n}\right\rangle \tag{5.6}
\end{equation*}
$$

for all $v \in K\left(u_{n}\right)$. Because $\mathrm{Gr} K$ is sequentially weakly closed (see the proof of (5.1)), this implies $u \in K(u)$. For any $v \in K(u)$, set $v_{n}=\frac{U\left(u_{n}\right)}{U(u)} v$. We have $v_{n} \in K\left(u_{n}\right)$ and $v_{n} \rightarrow v$ in $W_{0}^{1, p}(\Omega)$, as $n \rightarrow \infty$. Putting $v=v_{n}$ into (5.6) and passing to the upper limit as $n \rightarrow \infty$, we obtain

$$
\langle A v, v-u\rangle+\int_{\Omega} j^{0}(v(x) ; v(x)-u(x)) d x \geq\langle f, v-u\rangle
$$

for all $v \in K(u)$, where we have applied Fatou's lemma. Invoking Minty approach, we obtain $u \in \mathcal{S}$, therefore, $\mathcal{S}$ is weakly closed in $W_{0}^{1, p}(\Omega)$.

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