

## EXISTENCE OF TWO INFINITE FAMILIES OF SOLUTIONS FOR SINGULAR SUPERLINEAR EQUATIONS ON EXTERIOR DOMAINS

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ABSTRACT. In this article we study radial solutions of  $\Delta u + K(|x|)f(u) = 0$  in the exterior of the ball of radius  $R > 0$  in  $\mathbb{R}^N$  with  $N > 2$  where  $f$  grows superlinearly at infinity and is singular at 0 with  $f(u) \sim \frac{1}{|u|^{q-1}u}$  and  $0 < q < 1$  for small  $u$ . We assume  $K(|x|) \sim |x|^{-\alpha}$  for large  $|x|$  and establish existence of two infinite families of sign-changing solutions when  $N + q(N - 2) < \alpha < 2(N - 1)$ .

### 1. INTRODUCTION

In this article we are interested in radial solutions of

$$\Delta u + K(|x|)f(u) = 0 \quad \text{on } \mathbb{R}^N \setminus B_R, \quad u = 0 \quad \text{on } \partial B_R, \quad u \rightarrow 0 \text{ as } |x| \rightarrow \infty, \quad (1.1)$$

when  $N > 2$  and where  $B_R$  is the ball of radius  $R > 0$  centered at the origin.

Assuming  $u(x) = u(|x|) = u(r)$  the above problem becomes

$$u'' + \frac{N-1}{r}u' + K(r)f(u) = 0 \quad \text{for } R < r < \infty, \quad (1.2)$$

$$u(R) = 0, \quad \lim_{r \rightarrow \infty} u(r) = 0. \quad (1.3)$$

Numerous papers have proved existence of positive solutions of these equations with various nonlinearities  $f(u)$  and for various functions  $K(|x|) \sim |x|^{-\alpha}$  with  $\alpha > 0$ . See for example [1, 4, 5, 7, 11, 12, 13].

Here we prove existence of two infinite families of solutions including sign-changing solutions for this equation. We have also proved the existence of sign-changing solutions in other recent papers [2, 3, 9, 10].

We use the following assumptions:

(H1)  $f : \mathbb{R} \setminus \{0\} \rightarrow \mathbb{R}$  is odd, locally Lipschitz, and

$$f(u) = |u|^{p-1}u + g(u) \text{ with } p > 1$$

for large  $|u|$  and  $\lim_{u \rightarrow \infty} \frac{|g(u)|}{|u|^p} = 0$ .

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(H2) There exists a locally Lipschitz  $g_1 : \mathbb{R} \rightarrow \mathbb{R}$  such that

$$f(u) = \frac{1}{|u|^{q-1}u} + g_1(u) \text{ with } 0 < q < 1 \text{ for small } |u| \text{ and } g_1(0) = 0.$$

(H3)  $f > 0$  on  $(0, \infty)$ .

Let  $F(u) = \int_0^u f(t) dt$ . Since  $f$  is odd then  $F$  is even. Also, since  $0 < q < 1$  (by (H2)) it follows that  $f$  is integrable at 0 and therefore  $F$  is continuous with  $F(0) = 0$ . Also since  $f > 0$  on  $(0, \infty)$  it follows that  $F(u) > 0$  for  $u > 0$ . Since  $F(u)$  is even then  $F(u) > 0$  for  $u \neq 0$ .

We also assume  $K(r) > 0$  and  $K'(r)$  are continuous on  $[R, \infty)$ . In addition, we assume that

(H4) there exist  $\alpha_1, \alpha_2$  and positive  $K_1, K_2, K_3$  such that

$$\frac{K_1}{r^{\alpha_1}} \leq K \leq \frac{K_2}{r^{\alpha_2}} \quad \text{and} \quad \frac{r|K'|}{K} \leq K_3 \quad \text{on } [R, \infty), \quad (1.4)$$

where  $N + q(N - 2) < \alpha_2 \leq \alpha_1 < 2(N - 1)$ .

In this article we prove the following result.

**Theorem 1.1.** *Let  $N > 2$  and assume (H1)–(H4). If  $R > 0$ , then there exist two infinite families  $u_n^\pm$  of solutions to (1.2)–(1.3). If  $R > 0$  is sufficiently large then there are 2 solutions,  $u_n^\pm$ , with  $n$  interior zeros on  $(R, \infty)$  for all positive integers  $n$  and there is 1 positive solution. If  $R > 0$  is sufficiently small then there is an  $n_0 \geq 0$  such that there are 2 solutions with  $n$  zeros on  $(R, \infty)$  for all  $n > n_0$  and there is one solution with  $n_0$  zeros on  $(R, \infty)$ .*

We remark that the solutions of (1.2)–(1.3) have continuous second derivatives except at points where  $u(r_0) = 0$  because  $\lim_{u \rightarrow 0} |f(u)| = \infty$ . Solutions, however, do turn out to be  $C^1[R, \infty)$ . In addition, we will see in Lemma 2.1 that if  $a > 0$  then  $u(r)$  and  $u'(r)$  cannot both be zero at any  $r \in [R, \infty)$ . In particular, if  $u(z) = 0$  then  $u'(z) \neq 0$  and so by (H2) it follows that  $r^{N-1}Kf(u)$  is integrable at  $z$ . Therefore, by a  $C^1[R, \infty)$  solution of (1.2)–(1.3) we mean  $u \in C^1[R, \infty)$  such that  $r^{N-1}u' + \int_R^r t^{N-1}Kf(u) dt = R^{N-1}u'(R)$  for  $r \geq R$ ,  $u(R) = 0$ , and  $\lim_{r \rightarrow \infty} u(r) = 0$ .

## 2. PRELIMINARIES

Let  $R > 0$ . We begin our analysis of (1.2)–(1.3) by first making the change of variables  $u(r) = v(r^{2-N}) = v(t)$  and obtaining

$$v''(t) + h(t)f(v(t)) = 0,$$

where

$$0 < h(t) = \frac{t^{\frac{2(N-1)}{2-N}} K(t^{\frac{1}{2-N}})}{(N-2)^2}.$$

Henceforth we denote  $R_1 = R^{2-N}$ .

We now attempt to solve the initial value problem

$$v_a'' + h(t)f(v_a) = 0 \quad \text{for } 0 < t < R_1, \quad (2.1)$$

$$v_a(0) = 0, \quad v_a'(0) = a > 0 \quad (2.2)$$

and then try to find values of  $a$  so that

$$v_a(R_1) = 0. \quad (2.3)$$

Let

$$\tilde{\alpha}_1 = \frac{2(N-1) - \alpha_1}{N-2}, \quad \tilde{\alpha}_2 = \frac{2(N-1) - \alpha_2}{N-2}.$$

It follows from (H4) and the definition of  $h$  that there exist positive  $h_1, h_2, h_3$  such that

$$0 < h_1 t^{-\tilde{\alpha}_1} \leq h(t) \leq h_2 t^{-\tilde{\alpha}_2} \quad \text{and} \quad \frac{t|h'|}{h} \leq h_3, \quad (2.4)$$

where  $0 < \tilde{\alpha}_1 \leq \tilde{\alpha}_2 < 1 - q$ .

First we prove existence of a solution to (2.1)-(2.2) on  $[0, \epsilon_0]$  for some  $\epsilon_0 > 0$ . To do this we reformulate (2.1)-(2.2) as an appropriate integral equation. Let us suppose first that  $v_a$  is a solution (2.1)-(2.2). Integrating on  $(0, t)$  gives:

$$v'_a + \int_0^t h(x) f(v_a(x)) dx = a \quad \text{for } a > 0. \quad (2.5)$$

Integrating on  $(0, t)$  gives

$$v_a + \int_0^t \int_0^s h(x) f(v_a(x)) dx ds = at \quad \text{for } a > 0. \quad (2.6)$$

A bit of care needs to be taken here because we first need to know that the integral in (2.5) is defined. To see this notice that if  $v_a$  is a solution of (2.1)-(2.2) then for sufficiently small  $t > 0$  we have  $\frac{a}{2}t \leq v_a \leq at$ . In addition, it follows from (H1) and (H2) that there is a constant  $f_1 > 0$  such that  $f(v_a) \leq f_1(v_a^{-q} + v_a^p)$  and therefore by (2.4) we have

$$\begin{aligned} 0 < h(t)f(v_a) &\leq f_1 h_2 \left( \frac{t^{-\tilde{\alpha}_2}}{v_a^q} + t^{-\tilde{\alpha}_2} v_a^p \right) \\ &\leq f_1 h_2 \left( \frac{t^{-\tilde{\alpha}_2}}{\left(\frac{a}{2}\right)^q t^q} + t^{-\tilde{\alpha}_2 + p} a^p \right) \\ &= f_1 h_2 \left( \frac{2^q}{a^q} t^{-\tilde{\alpha}_2 - q} + t^{-\tilde{\alpha}_2 + p} a^p \right). \end{aligned} \quad (2.7)$$

From (2.4) we have  $1 - \tilde{\alpha}_2 - q > 0$  and  $1 - \tilde{\alpha}_2 + p > 0$  so it follows from (2.7) that  $h(t)f(v_a)$  is integrable near  $t = 0$ . Thus the integral in (2.5) is defined and is a continuous function. It then follows that (2.6) is also defined.

Now using (H2) we see that (2.6) is equivalent to

$$v_a + \int_0^t \int_0^s h(x) \left( \frac{1}{v_a^q(x)} + g_1(v_a) \right) dx ds = at. \quad (2.8)$$

Next let  $v_a = tw$  in (2.8) which gives

$$w = a - \frac{1}{t} \int_0^t \int_0^s h(x) \left( \frac{1}{x^q w^q(x)} + g_1(xw) \right) dx ds. \quad (2.9)$$

We now define

$$S_\epsilon = \{w \in C[0, \epsilon] : w(0) = a > 0, \text{ and } |w - a| \leq \frac{a}{2} \text{ for all } t \in [0, \epsilon]\}.$$

Here  $C[0, \epsilon]$  is the set of real-valued continuous functions on  $[0, \epsilon]$  with the supremum norm  $\|\cdot\|$ . We define  $T : S_\epsilon \rightarrow C[0, \epsilon]$  by  $Tw(0) = a$  and

$$Tw = a - \frac{1}{t} \int_0^t \int_0^s h(x) \left( \frac{1}{x^q w^q(x)} + g_1(xw) \right) dx ds \quad \text{for } t > 0.$$

As mentioned in (2.4) and (2.7) it follows that  $0 < \frac{h(x)}{x^q} \leq h_2 x^{-\tilde{\alpha}_2 - q}$  and  $\tilde{\alpha}_2 + q < 1$ . Hence  $x^{-\tilde{\alpha}_2 - q}$  is integrable on  $(0, \epsilon)$ . Then it is straightforward to show  $T$  maps  $S_\epsilon$  into  $S_\epsilon$  if  $\epsilon > 0$  is sufficiently small. Next let  $L$  be the Lipschitz constant for the function  $g_1$  defined in (H2) and suppose  $w_1, w_2 \in S$ . Using the mean value theorem and the fact that  $\frac{a}{2} \leq w_i \leq a$  for  $i = 1, 2$  on  $[0, \epsilon]$  we see that

$$\begin{aligned} |Tw_1 - Tw_2| &\leq \frac{1}{t} \int_0^t \int_0^s \left( qh_2 \left(\frac{2}{a}\right)^{q+1} x^{-\tilde{\alpha}_2 - q} + Lx^{1-\tilde{\alpha}_2} \right) |w_1 - w_2| dx ds \\ &\leq \|w_1 - w_2\| \left( \frac{qh_2}{(1 - \tilde{\alpha}_2 - q)(2 - \tilde{\alpha}_2 - q)} \left(\frac{2}{a}\right)^{q+1} t^{1-\tilde{\alpha}_2 - q} \right. \\ &\quad \left. + \frac{L}{(2 - \tilde{\alpha}_2)(3 - \tilde{\alpha}_2)} t^{2-\tilde{\alpha}_2} \right). \end{aligned} \tag{2.10}$$

Since the term in parentheses in (2.10) goes to 0 as  $t \rightarrow 0^+$ , it follows that there exists  $\epsilon_0 > 0$  and a  $c$  with  $0 < c < 1$  so that

$$\|Tw_1 - Tw_2\| \leq c\|w_1 - w_2\| \quad \text{for all } w_i \in S_{\epsilon_0}.$$

Thus  $T$  is a contraction and so by the contraction mapping principle  $T$  has a unique fixed point [8]. Therefore, we obtain a unique solution of (2.6) on  $[0, \epsilon_0]$ . It then follows that the integral term in (2.6) is differentiable which implies that  $v_a$  is differentiable and satisfies (2.5).

Next we let

$$E_a = \frac{v_a'^2}{2h} + F(v_a). \tag{2.11}$$

Recall from the comments after (H3) that  $F(v_a) \geq 0$ . Therefore from (2.1) and (2.4) it follows that

$$|E_a'| = \left| -\frac{h'}{2h^2} v_a'^2 \right| \leq \left| \frac{th'}{h} \right| \frac{v_a'^2}{2th} \leq \frac{h_3 E_a}{t}. \tag{2.12}$$

Thus  $\left(\frac{E_a}{t^{h_3}}\right)' \leq 0$  for  $t > 0$  and therefore integrating on  $(\epsilon_0/2, t)$  (with the  $\epsilon_0$  in the proof of existence) gives

$$\frac{v_a'^2}{2h} + F(v_a) = E_a(t) \leq C_1 t^{h_3} \leq C_1 R_1^{h_3},$$

where  $C_1 = E_a(\epsilon_0/2) \cdot (\epsilon_0/2)^{h_3}$ .

Thus  $v_a$  and  $v_a'$  are uniformly bounded on a largest interval of the form  $[\epsilon_0/2, T] \subset [\epsilon_0/2, R_1]$ . It then follows from this that  $v_a$  and  $v_a'$  are defined and continuous on all of  $[0, R_1]$ . In addition, it also follows from this that the  $v_a$  vary continuously with respect to  $a$ .

**Lemma 2.1.** *Assume (H1)–(H4) and let  $v_a$  solve (2.1)-(2.2) with  $a > 0$ . Then  $|v_a| + |v_a'| > 0$  on  $[0, R_1]$ .*

*Proof.* First since  $v_a(0) = 0$  and  $v_a'(0) = a > 0$  it follows that  $v_a$  and  $v_a'$  cannot both be zero at any  $t \in [0, \epsilon]$  for some  $\epsilon > 0$ . Suppose now that there is a  $t_0 \in (0, R_1]$  such that  $v_a(t_0) = v_a'(t_0) = 0$ . Thus  $E_a(t_0) = 0$  and then from (2.12) it follows that  $(E_a t^{h_3})' \geq 0$  on  $(t, t_0)$ . Integrating this on  $(t, t_0)$  yields  $E_a \leq 0$  on  $(t, t_0)$ . Since  $E_a \geq 0$  it follows then that  $E_a \equiv 0$  on  $[0, t_0]$  and thus  $v_a = v_a' = 0$  on  $[0, t_0]$ . This however contradicts that  $v_a'(0) = a > 0$ . Thus the lemma follows.  $\square$

**Lemma 2.2.** *Assume (H1)–(H4) and let  $v_a$  solve (2.1)-(2.2) with  $a > 0$ . Then  $v_a$  only has a finite number of zeros on  $[0, R_1]$ .*

*Proof.* First since  $v_a(0) = 0$  and  $v'_a(0) = a > 0$  it follows that  $v_a > 0$  on  $(0, \epsilon)$  for some  $\epsilon > 0$ . Now suppose  $v_a(z_k) = 0$  for  $z_k \in [\epsilon/2, R_1]$  with  $z_1 < z_2 < \dots \leq R_1$ . Then there exists  $z^*$  with  $\epsilon/2 < z^* \leq R_1$  such that  $z_k \rightarrow z^* \in [\epsilon/2, R_1]$  and  $v_a(z^*) = 0$ . In addition, it follows from Lemma 2.1 that  $v'_a(z_k) \neq 0$  and thus there exist local extrema,  $M_k$ , with  $z_k < M_k < z_{k+1}$  and  $v'_a(M_k) = 0$ . Thus we see  $M_k \rightarrow z^*$  and  $v'_a(z^*) = 0$ . But this along with  $v_a(z^*) = 0$  contradicts Lemma 2.1. Thus  $v_a$  has only a finite number of zeros on  $[0, R_1]$ .  $\square$

**Lemma 2.3.** *Assume (H1)–(H4) and let  $v_a$  solve (2.1)–(2.2). Suppose  $a > 0$  is sufficiently small. Then  $v_a$  has a local maximum,  $M_{1,a}$ , and a zero,  $z_{1,a}$ , on  $(0, R_1)$ . In addition,  $z_{1,a} \rightarrow 0$ ,  $v'_a(z_{1,a}) \rightarrow 0$ , and  $v_a(M_{1,a}) \rightarrow 0$  as  $a \rightarrow 0^+$ . More generally, if  $a > 0$  is sufficiently small and  $k \geq 1$  then  $v_a$  has  $k$  zeros,  $z_{i,a}$ , and  $k$  local extrema,  $M_{i,a}$ , with  $0 < M_{1,a} < z_{1,a} < M_{2,a} < z_{2,a} < \dots < M_{k,a} < z_{k,a}$  on  $(0, R_1)$ . In addition,  $\lim_{a \rightarrow 0^+} z_{i,a} = 0$ ,  $\lim_{a \rightarrow 0^+} v'_a(z_{i,a}) = 0$ , and  $\lim_{a \rightarrow 0^+} |v_a(M_{i,a})| = 0$  for  $1 \leq i \leq k$ .*

*Proof.* From (2.6) we have

$$v_a + \int_0^t \int_0^s h(x)f(v_a(x)) \, dx \, ds = at. \tag{2.13}$$

Suppose now that  $v_a > 0$  on  $(0, R_1)$ . Then from (H2) and (H3) there is a constant  $f_2 > 0$  such that  $f(v_a) \geq f_2 v_a^{-q}$ . In addition, from (2.4) we see that  $h(t) \geq h_1 t^{-\tilde{\alpha}_1}$  and  $1 - \tilde{\alpha}_1 - q > 0$ . Substituting into (2.13) gives

$$\int_0^t \int_0^s h(x)f(v_a(x)) \, dx \, ds \geq f_2 h_1 \int_0^t \int_0^s x^{-\tilde{\alpha}_1} v_a^{-q}(x) \, dx \, ds. \tag{2.14}$$

Also, it follows from (2.1) and (H3) that when  $v_a > 0$  we have  $v''_a < 0$  and so integrating this inequality twice on  $(0, t)$  gives

$$0 < v_a < at. \tag{2.15}$$

Substituting this into (2.14) gives

$$\begin{aligned} f_2 h_1 \int_0^t \int_0^s x^{-\tilde{\alpha}_1} v_a^{-q} \, dx \, ds &\geq \frac{f_2 h_1}{a^q} \int_0^t \int_0^s x^{-\tilde{\alpha}_1 - q} \, dx \, ds \\ &= \frac{f_2 h_1 t^{2 - \tilde{\alpha}_1 - q}}{a^q (1 - \tilde{\alpha}_1 - q)(2 - \tilde{\alpha}_1 - q)}. \end{aligned} \tag{2.16}$$

Substituting this expression into (2.13)–(2.14) gives

$$0 < v_a \leq at - \frac{f_2 h_1 t^{2 - \tilde{\alpha}_1 - q}}{a^q (1 - \tilde{\alpha}_1 - q)(2 - \tilde{\alpha}_1 - q)}. \tag{2.17}$$

However, the right-hand side of (2.17) is zero when

$$t = \left( \frac{a^{q+1} (1 - \tilde{\alpha}_1 - q)(2 - \tilde{\alpha}_1 - q)}{f_2 h_1} \right)^{\frac{1}{2 - \tilde{\alpha}_1 - q}}$$

and notice that this value of  $t$  is less than or equal to  $R_1$  if  $a > 0$  is sufficiently small. Thus (2.17) yields a contradiction and therefore  $v_a$  has a first zero,  $z_{1,a}$ , and  $0 < z_{1,a} < R_1$  if  $a > 0$  is sufficiently small. In addition, the above argument shows that

$$0 < z_{1,a} \leq \left( \frac{a^{q+1} (1 - \tilde{\alpha}_1 - q)(2 - \tilde{\alpha}_1 - q)}{f_2 h_1} \right)^{\frac{1}{2 - \tilde{\alpha}_1 - q}} \rightarrow 0 \quad \text{as } a \rightarrow 0^+. \tag{2.18}$$

Thus

$$\lim_{a \rightarrow 0^+} z_{1,a} = 0. \quad (2.19)$$

Next we examine the following identity which is straightforward to establish by differentiation and (2.1),

$$\frac{1}{2}v_a'^2 + h(t)F(v_a) + \int_0^t (-h'(s))F(v_a) ds = \frac{1}{2}a^2. \quad (2.20)$$

Evaluating at  $z_{1,a}$  gives

$$\frac{1}{2}v_a'^2(z_{1,a}) = \frac{1}{2}a^2 + \int_0^{z_{1,a}} h'(s)F(v_a) ds. \quad (2.21)$$

Since  $F(t) = \int_0^t f(s) ds$  it follows from (H1) and (H2) that there is a constant  $f_3 > 0$  such that

$$F(v_a) \leq f_3(v_a^{1-q} + v_a^{p+1}) \quad \text{when } v_a > 0. \quad (2.22)$$

Also from (2.4) we have

$$\frac{t|h'|}{h} \leq h_3 \quad \text{and so} \quad |h'| \leq h_2 h_3 t^{-1-\tilde{\alpha}_2}. \quad (2.23)$$

Substituting this into the right-hand side of (2.21) and using (2.15), (2.22) gives

$$\begin{aligned} \int_0^{z_{1,a}} h'(s)F(v_a) ds &\leq \int_0^{z_{1,a}} f_3 h_2 h_3 t^{-1-\tilde{\alpha}_2} (a^{1-q} t^{1-q} + a^{p+1} t^{p+1}) dt \\ &= f_3 h_2 h_3 \left( \frac{a^{1-q} z_{1,a}^{1-\tilde{\alpha}_2-q}}{1-\tilde{\alpha}_2-q} + \frac{a^{p+1} z_{1,a}^{1-\tilde{\alpha}_2+p}}{1-\tilde{\alpha}_2+p} \right) \\ &\leq f_3 h_2 h_3 a^{1-q} R_1^{1-\tilde{\alpha}_2-q} \left( \frac{1}{1-\tilde{\alpha}_2-q} + \frac{a^{p+q} R_1^{p+q}}{1-\tilde{\alpha}_2+p} \right). \end{aligned} \quad (2.24)$$

Thus substituting (2.22) and (2.24) into (2.21) gives

$$\frac{1}{2}v_a'^2(z_{1,a}) \leq \frac{1}{2}a^2 + f_3 h_2 h_3 a^{1-q} R_1^{1-\tilde{\alpha}_2-q} \left( \frac{1}{1-\tilde{\alpha}_2-q} + \frac{a^{p+q} R_1^{p+q}}{1-\tilde{\alpha}_2+p} \right) \rightarrow 0 \quad (2.25)$$

as  $a \rightarrow 0^+$ . Therefore,

$$\lim_{a \rightarrow 0^+} v_a'(z_{1,a}) = 0. \quad (2.26)$$

Next since  $v_a(0) = v_a(z_{1,a}) = 0$  and  $v_a'(0) = a > 0$  it follows that there is a local maximum,  $M_{1,a}$ , with  $0 < M_{1,a} < z_{1,a}$ . Evaluating (2.20) at  $M_{1,a}$  gives

$$h(M_{1,a})F(v_a(M_{1,a})) = \frac{1}{2}a^2 + \int_0^{M_{1,a}} h'(t)F(v_a) dt. \quad (2.27)$$

Estimating as in (2.24)-(2.24) but now on  $[0, M_{1,a}]$  (instead of  $[0, z_{1,a}]$ ) we again obtain

$$\int_0^{M_{1,a}} h'(t)F(v_a) dt \leq f_3 h_2 h_3 a^{1-q} R_1^{1-\tilde{\alpha}_2-q} \left( \frac{1}{1-\tilde{\alpha}_2-q} + \frac{a^{p+q} R_1^{p+q}}{1-\tilde{\alpha}_2+p} \right). \quad (2.28)$$

Then from (2.27)-(2.28) and (2.4) we obtain

$$F(v_a(M_{1,a})) \leq \frac{f_3 h_2 h_3 a^{1-q} R_1^{1-\tilde{\alpha}_2+\tilde{\alpha}_1-q}}{h_1} \left( \frac{1}{1-\tilde{\alpha}_2-q} + \frac{a^{p+q} R_1^{p+q}}{1-\tilde{\alpha}_2+p} \right) \rightarrow 0 \quad (2.29)$$

as  $a \rightarrow 0^+$ . Therefore,

$$\lim_{a \rightarrow 0^+} v_a(M_{1,a}) = 0. \quad (2.30)$$

In a similar way we can show  $v_a$  has as many zeros as desired by choosing  $a > 0$  sufficiently small and we can also similarly establish the analogs of (2.19), (2.26), and (2.30). This completes the proof of the lemma.  $\square$

**Lemma 2.4.** *Assume (H1)–(H4) and let  $v_a$  solve (2.1)–(2.2). If  $a > 0$  is sufficiently large then  $v_a$  has a local maximum,  $M_{1,a}$ , on  $(0, R_1)$ .*

*Proof.* Suppose not and so suppose  $v_a$  is increasing on  $(0, R_1)$  for all sufficiently large  $a > 0$ . Then  $v_a > 0$  on  $(0, R_1)$  and so it follows from (2.1) that  $v_a'' < 0$  on  $(0, R_1)$ .

We now claim that  $v_a(t_0) \rightarrow \infty$  as  $a \rightarrow \infty$  for any fixed  $t_0$  with  $0 < t_0 \leq R_1$ . So suppose not. Thus suppose  $0 < v_a \leq C_2$  on  $(0, t_0]$  where  $C_2$  is independent of  $a$ . Using (2.15) and (2.22) we see that

$$\begin{aligned} F(v_a) &\leq f_3(v_a^{1-q} + v_a^{p+1}) = f_3v_a^{1-q}(1 + v_a^{p+q}) \\ &\leq f_3v_a^{1-q}(1 + C_2^{p+q}) = f_3C_3v_a^{1-q} \end{aligned} \tag{2.31}$$

where  $C_3 = 1 + C_2^{p+q}$ .

Then using (2.15) in (2.31) we obtain

$$F(v_a) \leq f_3C_3v_a^{1-q} \leq f_3C_3a^{1-q}t^{1-q}. \tag{2.32}$$

Substituting this into (2.20) and using (2.4) we then have  $h(t) \leq h_2t^{-\tilde{\alpha}_2}$  and  $|h'| \leq h_2h_3t^{-\tilde{\alpha}_2-1}$ . This gives

$$\begin{aligned} h(t)F(v_a) + \int_0^t (-h'(s))F(v_a) ds &\leq f_3h_2C_3 \left(1 + \frac{h_3}{1 - \tilde{\alpha}_2 - q}\right) a^{1-q}t^{1-\tilde{\alpha}_2-q} \\ &= C_4a^{1-q}t^{1-\tilde{\alpha}_2-q} \\ &\leq C_4a^{1-q}t_0^{1-\tilde{\alpha}_2-q} \end{aligned} \tag{2.33}$$

where  $C_4 = f_3h_2C_3 \left(1 + \frac{h_3}{1 - \tilde{\alpha}_2 - q}\right)$ . Therefore from (2.20) and (2.33) we see that

$$\frac{1}{2}v_a'^2 \geq \frac{1}{2}a^2 - C_4t_0^{1-\tilde{\alpha}_2-q}a^{1-q} \geq \frac{1}{2}a^2 - C_4R_1^{1-\tilde{\alpha}_2-q}a^{1-q} \geq \frac{1}{8}a^2$$

for  $a$  sufficiently large. Thus  $v_a' \geq a/2$  for  $a$  sufficiently large, and integrating this on  $(0, t_0)$  gives

$$C_2 \geq v_a(t_0) \geq \frac{a}{2}t_0 \rightarrow \infty \quad \text{as } a \rightarrow \infty.$$

Hence we obtain a contradiction. Thus it follows that if  $v_a$  is increasing on  $[0, R_1]$  then  $v_a(t_0) \rightarrow \infty$  as  $a \rightarrow \infty$  for every  $t_0$  with  $0 < t_0 \leq R_1$ .

Next it follows that if  $v_a$  is increasing on  $[0, R_1]$  then since  $f$  is superlinear (by (H1)) then

$$\frac{h(t)f(v_a)}{v_a} \rightarrow \infty$$

uniformly on  $[t_0, R_1]$  for any  $t_0 > 0$  as  $a \rightarrow \infty$ . Therefore assuming  $v_a$  is increasing on  $[0, R_1]$  we see that

$$I_a = \inf_{[t_0, R_1]} \frac{h(t)f(v_a)}{v_a} \rightarrow \infty \quad \text{as } a \rightarrow \infty. \tag{2.34}$$

Next we rewrite (2.1) as

$$v_a'' + \left(\frac{h(t)f(v_a)}{v_a}\right)v_a = 0. \tag{2.35}$$

Assuming  $v_a$  is increasing on  $[0, R_1]$ , we let  $y$  solve

$$y'' + I_a y = 0 \quad (2.36)$$

with  $y(t_0) = v_a(t_0)$  and  $y'(t_0) = v'_a(t_0)$ . Thus

$$y = v_a(t_0) \cos(\sqrt{I_a}(t - t_0)) + \frac{v'_a(t_0)}{\sqrt{I_a}} \sin(\sqrt{I_a}(t - t_0))$$

and so it follows that  $y$  is  $2\pi/\sqrt{I_a}$ -periodic. Thus  $y$  must have a local maximum on  $[t_0, t_0 + \frac{2\pi}{\sqrt{I_a}}]$ . In addition, it follows from (2.34) that  $[t_0, t_0 + \frac{2\pi}{\sqrt{I_a}}] \subset [t_0, R_1]$  if  $a$  is sufficiently large. We will now show that  $v_a$  must have a local maximum on  $[t_0, t_0 + \frac{2\pi}{\sqrt{I_a}}] \subset [t_0, R_1]$  if  $a$  is sufficiently large. This is essentially the Sturm Comparison Theorem [6] but we write out the details because they are brief.

Let  $a > 0$  be sufficiently large so that  $y$  has a local maximum  $M < R_1$  and that  $y' > 0$  on  $[t_0, M]$ . Multiplying (2.35) by  $y$ , (2.36) by  $v_a$ , and subtracting gives

$$(yv'_a - y'v_a)' + \left( \frac{h(t)f(v_a)}{v_a} - I_a \right) yv_a = 0. \quad (2.37)$$

Integrating this on  $[t_0, M]$  and using  $y'(M) = 0$ ,  $y(t_0) = v_a(t_0)$ , and  $y'(t_0) = v'_a(t_0)$  gives

$$y(M)v'_a(M) + \int_{t_0}^M \left( \frac{h(t)f(v_a)}{v_a} - I_a \right) yv_a dt = 0. \quad (2.38)$$

On  $[t_0, M]$  we have  $y > 0$ ,  $v_a > 0$ . In addition, the term in parentheses in (2.38) is nonnegative. Thus we see  $y(M)v'_a(M) \leq 0$  and therefore  $v'_a(M) \leq 0$  since  $y(M) > 0$ . Now if  $v'_a(M) < 0$  then since  $v'_a(t_0) > 0$  it follows that  $v_a$  has a local maximum,  $M_{1,a}$ , with  $t_0 < M_{1,a} < M$ . On the other hand, if  $v'_a(M) = 0$  then from (2.1) it follows that  $v''_a(M) < 0$  and therefore  $M$  is a local maximum for  $v_a$  and we set  $M_{1,a} = M$ . Therefore in both cases we see that  $v_a$  has a local maximum,  $M_{1,a}$ , with  $0 < M_{1,a} < R_1$  and  $v'_a > 0$  on  $[0, M_{1,a})$  if  $a > 0$  is sufficiently large.  $\square$

**Lemma 2.5.** *Assume (H1)–(H4) and let  $v_a$  solve (2.1)–(2.2). Suppose  $a > 0$  is sufficiently large so that  $v_a$  has a smallest local maximum  $M_{1,a}$  with  $v'_a > 0$  on  $[0, M_{1,a})$  and  $M_{1,a} < R_1$ . Then  $\lim_{a \rightarrow \infty} v_a(M_{1,a}) = \infty$  and  $\lim_{a \rightarrow \infty} M_{1,a} = 0$ .*

*Proof.* We first show that  $v_a(M_{1,a}) \rightarrow \infty$  as  $a \rightarrow \infty$ . So suppose not. Mimicking the proof of Lemma 2.4, suppose there is a  $C_5 > 0$  such that  $v_a(M_{1,a}) \leq C_5$ . Then using (2.31)–(2.32) and evaluating (2.20) and (2.33) at  $t = M_{1,a}$  gives

$$\begin{aligned} \frac{1}{2}a^2 &= h(M_{1,a})F(v_a(M_{1,a})) + \int_0^{M_{1,a}} (-h'(s))F(v_a) ds \\ &\leq f_3 h_2 C_5 \left( 1 + \frac{h_3}{1 - \tilde{\alpha}_2 - q} \right) a^{1-q} t^{1-\tilde{\alpha}_2-q} \\ &= C_6 a^{1-q} M_{1,a}^{1-\tilde{\alpha}_2-q} \\ &\leq C_6 a^{1-q} R_1^{1-\tilde{\alpha}_2-q} \end{aligned} \quad (2.39)$$

where  $C_6 = f_3 h_2 C_5 \left( 1 + \frac{h_3}{1 - \tilde{\alpha}_2 - q} \right)$ . Thus

$$\frac{1}{2}a^{1+q} \leq C_6 R_1^{1-\tilde{\alpha}_2-q}. \quad (2.40)$$

However, the left-hand side of (2.40) goes to infinity as  $a \rightarrow \infty$  but the right-hand side stays finite. Hence we obtain a contradiction and therefore we must have

$$\lim_{a \rightarrow \infty} v_a(M_{1,a}) = \infty. \tag{2.41}$$

Next we show  $M_{1,a} \rightarrow 0$  as  $a \rightarrow \infty$ . By (H1) it follows that

$$f(v_a) \geq f_4 v_a^p \text{ when } v_a > 0 \text{ for some constant } f_4 > 0. \tag{2.42}$$

We integrate (2.1) on  $(t, M_{1,a})$  and estimate using the fact that  $v_a$  is increasing on  $(t, M_{1,a})$  to obtain:

$$v'_a = \int_t^{M_{1,a}} h(s) f(v_a) ds \geq f_4 v_a^p \int_t^{M_{1,a}} h(s) ds. \tag{2.43}$$

Dividing by  $v_a^p$ , recalling  $p > 1$ , and integrating on  $(\frac{M_{1,a}}{2}, M_{1,a})$  gives

$$\frac{v_a^{1-p}(\frac{M_{1,a}}{2})}{p-1} \geq \frac{v_a^{1-p}(\frac{M_{1,a}}{2}) - v_a^{1-p}(M_{1,a})}{p-1} \geq f_3 \int_{\frac{M_{1,a}}{2}}^{M_{1,a}} \int_s^{M_{1,a}} h(s) ds. \tag{2.44}$$

Since  $v''_a < 0$  it follows that  $v_a$  is concave and thus  $v_a(\lambda x + (1-\lambda)y) \geq \lambda v_a(x) + (1-\lambda)v_a(y)$  for  $0 \leq \lambda \leq 1$ . In particular, for  $x = v_a(M_{1,a})$ ,  $y = 0$ , and  $\lambda = \frac{1}{2}$  we obtain  $v_a(\frac{M_{1,a}}{2}) \geq \frac{v_a(M_{1,a})}{2}$ . Then it follows from this and (2.41) that  $v_a(\frac{M_{1,a}}{2}) \rightarrow \infty$  as  $a \rightarrow \infty$ . Since  $p > 1$  it follows then that the left-hand side of (2.44) goes to 0 as  $a \rightarrow \infty$  and thus we must have

$$\lim_{a \rightarrow \infty} M_{1,a} = 0. \tag{2.45}$$

This completes the proof. □

**Lemma 2.6.** *Assume (H1)–(H4) and let  $v_a$  solve (2.1)–(2.2). Suppose  $a > 0$  is sufficiently large. Then  $v_a$  has a zero,  $z_{1,a}$ , with  $M_{1,a} < z_{1,a} < R_1$ . In addition,  $v_a > 0$  and  $v'_a < 0$  on  $(M_{1,a}, z_{1,a})$ . Further  $\lim_{a \rightarrow \infty} z_{1,a} = 0$ ,  $\lim_{a \rightarrow \infty} v_a(M_{1,a}) = \infty$ , and  $\lim_{a \rightarrow \infty} v'_a(z_{1,a}) = -\infty$ . More generally, if  $a$  is sufficiently large and  $k \geq 1$  then  $v_a$  has  $k$  zeros,  $z_{i,a}$ , and  $k$  local extrema,  $M_{i,a}$ , with  $0 < M_{1,a} < z_{1,a} < M_{2,a} < z_{2,a} < \dots < M_{k,a} < z_{k,a}$  on  $(0, R_1)$ . In addition,  $\lim_{a \rightarrow \infty} z_{i,a} = 0$ ,  $\lim_{a \rightarrow \infty} |v'_a(z_{i,a})| = \infty$ , and  $\lim_{a \rightarrow \infty} |v_a(M_{i,a})| = \infty$  for  $1 \leq i \leq k$ .*

*Proof.* It follows from Lemma 2.5 that

$$\lim_{a \rightarrow \infty} v_a(M_{1,a}) = \infty. \tag{2.46}$$

Assume now that  $v_a > 0$  on  $(M_{1,a}, R_1)$ . Then using (2.42) and integrating on  $(M_{1,a}, t)$  we obtain

$$-v'_a \geq f_4 v_a^p \int_{M_{1,a}}^t h(s) ds.$$

Dividing by  $v_a^p$ , integrating on  $(M_{1,a}, t)$ , and using (2.4) gives

$$\begin{aligned} v_a^{1-p} &\geq v_a^{1-p} - v_a^{1-p}(M_{1,a}) \\ &\geq (p-1) f_4 \int_{M_{1,a}}^t \int_{M_{1,a}}^s h(x) dx ds \\ &= \frac{(p-1) f_4 R_1^{-\alpha_1}}{2} (t - M_{1,a})^2. \end{aligned} \tag{2.47}$$

Evaluating (2.47) at  $t = \frac{R_1 + M_{1,a}}{2}$  we see

$$v_a^{1-p} \left( \frac{R_1 + M_{1,a}}{2} \right) \geq \frac{(p-1)f_4 R_1^{-\tilde{\alpha}_1}}{2} \left( \frac{R_1 - M_{1,a}}{2} \right)^2$$

and therefore

$$v_a^{p-1} \left( \frac{R_1 + M_{1,a}}{2} \right) \leq \frac{8R_1^{\tilde{\alpha}_1}}{(p-1)f_4(R_1 - M_{1,a})^2}. \quad (2.48)$$

By (2.45) we see then for large  $a$  that

$$v_a \left( \frac{R_1 + M_{1,a}}{2} \right) \leq \left( \frac{32R_1^{\tilde{\alpha}_1 - 2}}{(p-1)f_4} \right)^{\frac{1}{p-1}}. \quad (2.49)$$

Using that  $v_a'' < 0$  when  $v_a > 0$  and the mean value theorem we see there is a  $c_a$  with  $M_{1,a} < c_a < \frac{R_1 + M_{1,a}}{2}$  such that

$$\begin{aligned} v_a(M_{1,a}) - v_a \left( \frac{R_1 + M_{1,a}}{2} \right) &= -v_a'(c_a) \left( \frac{R_1 - M_{1,a}}{2} \right) \\ &\leq -v_a' \left( \frac{R_1 + M_{1,a}}{2} \right) \left( \frac{R_1}{2} \right). \end{aligned} \quad (2.50)$$

Since  $v_a' > 0$  on  $(0, M_{1,a})$  it follows from (2.41) and (2.49) that the left-hand side of (2.50) goes to infinity as  $a \rightarrow \infty$ . And then from (2.45) and (2.50) it follows that

$$v_a' \left( \frac{R_1 + M_{1,a}}{2} \right) \rightarrow -\infty \quad \text{as } a \rightarrow \infty. \quad (2.51)$$

Since  $v_a'' < 0$  when  $v_a > 0$  it follows that  $v_a'$  is decreasing when  $v_a > 0$  so:

$$v_a' < v_a' \left( \frac{R_1 + M_{1,a}}{2} \right) \text{ for } t > \frac{R_1 + M_{1,a}}{2}.$$

Integrating this on  $(\frac{R_1 + M_{1,a}}{2}, R_1)$  gives

$$v_a(R_1) < v_a \left( \frac{R_1 + M_{1,a}}{2} \right) + v_a' \left( \frac{R_1 + M_{1,a}}{2} \right) \left( \frac{R_1 - M_{1,a}}{2} \right). \quad (2.52)$$

It follows from (2.49) that the first term on the right-hand side (2.52) is bounded. Then from (2.45) we have  $M_{1,a} \rightarrow 0$  as  $a \rightarrow \infty$  and this along with (2.51) implies that the right-hand side of (2.52) becomes negative while the left-hand side stays positive. Thus we obtain a contradiction and therefore there exists  $z_{1,a}$  with  $M_{1,a} < z_{1,a} < R_1$  such that  $v_a(z_{1,a}) = 0$  and  $v_a > 0$  on  $(M_{1,a}, z_{1,a})$ .

From the mean value theorem and that  $v_a'' < 0$  when  $v_a > 0$  it follows that there is a  $d_a$  such that  $M_{1,a} < d_a < z_{1,a}$  and

$$v_a(M_{1,a}) = |v_a(z_{1,a}) - v_a(M_{1,a})| = |v_a'(d_a)| |z_{1,a} - M_{1,a}| \leq |v_a'(d_a)| R_1 \leq |v_a'(z_{1,a})| R_1$$

and since the left-hand side goes to infinity by (2.46) it then follows from the above inequality that

$$\lim_{a \rightarrow \infty} v_a'(z_{1,a}) = -\infty. \quad (2.53)$$

Next it follows from evaluating (2.47) at  $\frac{M_{1,a} + z_{1,a}}{2}$  that we obtain

$$v_a^{1-p} \left( \frac{M_{1,a} + z_{1,a}}{2} \right) \geq \frac{(p-1)f_4 R_1^{-\tilde{\alpha}_1}}{2} \left( \frac{M_{1,a} - z_{1,a}}{2} \right)^2. \quad (2.54)$$

Since  $v_a'' < 0$  when  $v_a > 0$  it follows that  $v_a$  is concave. Then it follows from this and (2.46) that  $v_a \left( \frac{M_{1,a} + z_{1,a}}{2} \right) \geq \frac{v_a(M_{1,a})}{2} + \frac{v_a(z_{1,a})}{2} = \frac{v_a(M_{1,a})}{2} \rightarrow \infty$ . Thus we see

the left-hand side of (2.54) goes to 0 as  $a \rightarrow \infty$  and therefore  $z_{1,a} - M_{1,a} \rightarrow 0$ . Since  $M_{1,a} \rightarrow 0$  by Lemma 2.5 we see then that

$$\lim_{a \rightarrow \infty} z_{1,a} = 0. \tag{2.55}$$

In a similar way we can show that  $v_a$  has as many zeros as desired on  $(0, R_1)$  by choosing  $a > 0$  sufficiently large, and we can obtain the analogs of (2.46), (2.53), and (2.55). This completes the proof.  $\square$

**Lemma 2.7.** *Assume (H1)–(H4) and let  $v_a$  solve (2.1)–(2.2) with  $a > 0$ . If  $R_1$  is sufficiently small then there are values of  $a > 0$  such that  $v_a > 0$  on  $(0, R_1)$ . Also, if  $R_1$  is sufficiently large then  $v_a$  has at least one zero on  $(0, R_1)$  for all  $a > 0$ . Similarly, if  $R_1 > 0$  is sufficiently large then  $v_a$  has at least  $k$  zeros on  $(0, R_1)$  for all  $a > 0$ .*

*Proof.* We prove the second part first. It follows from (H1)–(H3) that there is a constant  $f_5 > 0$  such that  $\frac{f(v)}{v} \geq f_5$  for all  $v \neq 0$ . In addition, we know from (2.4) that  $h(t) \geq h_1 t^{-\tilde{\alpha}_1} \geq h_1 R_1^{-\tilde{\alpha}_1}$ . Thus  $\frac{h(t)f(v_a)}{v_a} \geq \frac{f_5}{R_1^{\tilde{\alpha}_1}}$ .

Next we consider

$$\begin{aligned} w'' + \left(\frac{f_5 h_1}{R_1^{\tilde{\alpha}_1}}\right)w &= 0, \\ w(0) = 0, w'(0) &= a. \end{aligned}$$

Thus:

$$w = c \sin\left(\sqrt{\frac{f_5 h_1}{R_1^{\tilde{\alpha}_1}}} x\right)$$

for some  $c > 0$ , and so  $w$  has a zero on  $[0, \sqrt{\frac{R_1^{\tilde{\alpha}_1}}{f_5 h_1}} \pi]$ . It follows then from the Sturm

Comparison Theorem [6] that  $v_a$  has at least one zero on  $[0, R_1]$  if  $\sqrt{\frac{R_1^{\tilde{\alpha}_1}}{f_5 h_1}} \pi < R_1$ . That is, if

$$R_1 > \left(\frac{\pi^2}{f_5 h_1}\right)^{\frac{1}{2-\tilde{\alpha}_1}} = \left(\frac{\pi^2}{f_5 h_1}\right)^{\frac{N-2}{\tilde{\alpha}_1-2}}.$$

Similarly,  $v_a$  has at least  $k$  zeros on  $[0, R_1]$  if

$$R_1 > \left(\frac{k^2 \pi^2}{f_5 h_1}\right)^{\frac{1}{2-\tilde{\alpha}_1}} = \left(\frac{k^2 \pi^2}{f_5 h_1}\right)^{\frac{N-2}{\tilde{\alpha}_1-2}}.$$

Next we show that if  $R_1$  is sufficiently small then there is a value of  $a > 0$  such that  $v_a > 0$  on  $(0, R_1)$ . First since  $f(v_a) > 0$  for  $v_a > 0$  by (H3) there is a constant  $f_6 > 0$  such that  $f(v_a) \geq f_6 > 0$  for  $v_a > 0$ . Thus it follows from this and (2.4) that  $h(t)f(v_a) \geq f_6 h_1 t^{-\tilde{\alpha}_1}$ . Suppose now that  $v_a$  has a zero,  $z_a$ , on  $(0, R_1)$ . Then there is an  $M_a$  with  $0 < M_a < z_a$  such that  $v_a$  has a local maximum at  $M_a$ . Substituting  $t = M_a$  into (2.5) then gives

$$\frac{f_6 h_1 M_a^{1-\tilde{\alpha}_1}}{1-\tilde{\alpha}_1} \leq \int_0^{M_a} f_6 h_1 t^{-\tilde{\alpha}_1} dt \leq \int_0^{M_a} h(t)f(v_a) dt = a.$$

It follows from this that

$$\lim_{a \rightarrow 0^+} M_a = 0. \tag{2.56}$$

Returning to (2.20) and evaluating at  $M_a$  we see that

$$\frac{1}{2}a^2 = h(M_a)F(v_a(M_a)) + \int_0^{M_a} (-h'(t))F(v_a) dt. \tag{2.57}$$

Then using (2.15), (2.22), and (2.4) we see that

$$\begin{aligned} \int_0^{M_a} (-h'(t))F(v_a) dt &\leq f_3h_2h_3 \int_0^{M_a} t^{-\tilde{\alpha}_2-1}(a^{1-q}t^{1-q} + a^{p+1}t^{p+1}) dt \\ &= f_3h_2h_3a^{1-q} \left( \frac{R_1^{1-\tilde{\alpha}_2-q}}{1-\tilde{\alpha}_2-q} + \frac{a^{p+q}R_1^{1-\tilde{\alpha}_2+p}}{1-\tilde{\alpha}_2+p} \right). \end{aligned} \tag{2.58}$$

Similarly,

$$h(M_a)F(v_a(M_a)) \leq f_3h_2a^{1-q}(R_1^{1-\tilde{\alpha}_2-q} + a^{p+q}R_1^{1-\tilde{\alpha}_2+p}). \tag{2.59}$$

Now substituting (2.58)-(2.59) into (2.57) gives

$$\frac{1}{2}a^2 \leq f_3h_2a^{1-q}(C_7R_1^{1-\tilde{\alpha}_2-q} + a^{p+q}C_8R_1^{1-\tilde{\alpha}_2+p}), \tag{2.60}$$

where  $C_7 = (1 + \frac{h_3}{1-\tilde{\alpha}_2-q})$  and  $C_8 = (1 + \frac{h_3}{1-\tilde{\alpha}_2+p})$ . Select  $a = 1$  and we see (2.60) becomes

$$1 \leq 2f_3h_2 \left( C_7R_1^{1-\tilde{\alpha}_2-q} + C_8R_1^{1-\tilde{\alpha}_2+p} \right) \tag{2.61}$$

Now if  $R_1$  is sufficiently small we see that this violates (2.61). Thus if  $R_1$  is sufficiently small and if  $a = 1$  then  $v_a > 0$  on  $(0, R_1)$ . This completes the proof.  $\square$

### 3. PROOF OF THEOREM 1.1

We saw from Lemma 2.2 that  $v_a$  has a finite number of zeros on  $(0, R_1)$  for  $a > 0$ . Thus there exists an  $a > 0$  such that  $v_a$  has the *least* number of zeros on  $(0, R_1)$  among all  $a > 0$ . We denote the number of zeros of this particular  $v_a$  as  $n_0 \geq 0$ . (There may be more than one choice of  $a$  such that  $v_a$  has  $n_0$  zeros on  $(0, R_1)$  but choose one such  $a$ ). Now let

$$S_{n_0} = \{a > 0 : v_a \text{ solves (2.1)-(2.2) and has exactly } n_0 \text{ zeros on } (0, R_1)\}.$$

From the above comments it follows that  $S_{n_0}$  is nonempty and from Lemma 2.6 it follows that  $S_{n_0}$  is bounded above.

Next let  $a_{n_0} = \sup S_{n_0}$ . We now prove that  $v_{a_{n_0}}$  has exactly  $n_0$  zeros on  $(0, R_1)$  and  $v_{a_{n_0}}(R_1) = 0$ . From the definition of  $n_0$  it follows that  $v_{a_{n_0}}$  has at least  $n_0$  zeros on  $(0, R_1)$ . Now if  $v_{a_{n_0}}$  has an  $(n_0 + 1)$ st zero on  $(0, R_1)$  then by continuity with respect to initial conditions then so does  $v_a$  for  $a$  close to  $a_{n_0}$  and  $a < a_{n_0}$  but if  $a < a_{n_0}$  then  $v_a$  has only  $n_0$  zeros. Thus  $v_{a_{n_0}}$  has exactly  $n_0$  zeros on  $(0, R_1)$ . Now suppose  $v_{a_{n_0}}(R_1) \neq 0$ . Without loss of generality suppose that  $v_{a_{n_0}}(R_1) > 0$ . Now if  $a$  is close to  $a_{n_0}$  and  $a > a_{n_0}$  then by continuity with respect to initial conditions and the fact that if  $v_a(z) = 0$  then  $v'_a(z) \neq 0$  it follows that  $v_a(R_1) > 0$  and also  $v_a$  has  $n_0$  zeros on  $(0, R_1)$ . But since  $a > a_{n_0}$  then  $v_a$  has at least  $n_0 + 1$  zeros on  $(0, R_1)$  and so we obtain a contradiction. Thus it must be the case that  $v_{a_{n_0}}(R_1) = 0$  and thus we obtain a solution of (2.1)-(2.2). Then by Lemma 2.1 it follows that  $v'_{a_{n_0}}(R_1) \neq 0$  so let us assume without loss of generality that  $v'_{a_{n_0}}(R_1) < 0$ .

In a similar way we now define

$$S_{n_0+1} = \{a > 0 : v_a \text{ solves (2.1)-(2.2) and has exactly } n_0 + 1 \text{ zeros on } (0, R_1)\}.$$

It follows from Lemma 2.6 that  $S_{n_0+1}$  is bounded from above. For  $a > a_{n_0}$  and  $a$  sufficiently close to  $a_{n_0}$  it follows again by continuity with respect to initial conditions that  $v_a$  has an  $(n_0 + 1)$ st zero  $z_{n_0+1} < R_1$  and  $z_{n_0+1}$  is close to  $R_1$ . In addition, since  $v'_{a_{n_0}}(R_1) < 0$  it follows that  $v'_a(z_{n_0+1}) < 0$ . Thus  $v_a$  has exactly  $n_0 + 1$  zeros on  $(0, R_1)$  for  $a > a_{n_0}$  and  $a$  sufficiently close to  $a_{n_0}$ . Therefore  $S_{n_0+1}$  is nonempty.

Similarly we define  $a_{n_0+1} = \sup S_{n_0+1}$  and we can similarly show that  $v_{a_{n_0+1}}$  has exactly  $n_0 + 1$  zeros on  $(0, R_1)$  and  $v_{a_{n_0+1}}(R_1) = 0$ .

Continuing in this way we see that we can find an infinite number of solutions,  $v_{a_n}$ , where  $v_{a_n}$  has exactly  $n$  zeros on  $(0, R_1)$  and  $v_{a_n}(R_1) = 0$  for each  $n \geq n_0$ . Thus we have found one infinite family of solutions of (2.1)-(2.2).

Next we let

$$b_{n_0} = \inf S_{n_0}.$$

By the above comments  $S_{n_0}$  is nonempty and by definition  $S_{n_0}$  is bounded below. Then  $b_{n_0} \leq a_{n_0}$  and by a similar argument we can show that  $v_{b_{n_0}}$  has exactly  $n_0$  zeros on  $(0, R_1)$  and  $v_{a_{n_0}}(R_1) = 0$ . Now it may be the case that  $a_{n_0} = b_{n_0}$  so there may be only one solution with  $n_0$  zeros. Next we let

$$b_{n_0+1} = \inf S_{n_0+1}.$$

Then we have  $b_{n_0+1} < b_{n_0} \leq a_{n_0} < a_{n_0+1}$  and we can show  $v_{b_{n_0+1}}$  has exactly  $n_0 + 1$  zeros on  $(0, R_1)$  and  $v_{b_{n_0+1}}(R_1) = 0$ . Since  $b_{n_0+1} < a_{n_0+1}$  it follows that we have two solutions,  $v_{a_{n_0}}$  and  $v_{b_{n_0}}$ , with  $n_0 + 1$  zeros on  $(0, R_1)$ . Continuing in this way we see that if  $n > n_0$  we can find a second infinite family of solutions of (2.1)-(2.2),  $v_{b_n}$ , where  $v_{b_n}$  has exactly  $n$  zeros on  $(0, R_1)$  and  $v_{b_n}(R_1) = 0$ .

Finally, we let  $u_n^+(t) = v_{a_n}(t^{\frac{1}{2-N}})$  and  $u_n^-(t) = v_{b_n}(t^{\frac{1}{2-N}})$  for all  $n \geq n_0$ . This completes the proof of Theorem 1.1.  $\square$

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