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# Multidimensional fractional advection-dispersion equations and related stochastic processes 

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#### Abstract

In this paper we study multidimensional fractional advection-dispersion equations involving fractional directional derivatives both from a deterministic and a stochastic point of view. For such equations we show the connection with a class of multidimensional Lévy processes. We introduce a novel Lévy-Khinchine formula involving fractional gradients and study the corresponding infinitesimal generator of multidimensional random processes. We also consider more general fractional transport equations involving Frobenius-Perron operators and their stochastic solutions. Finally, some results about fractional power of second order directional derivatives and their applications are also provided.


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## 1 Introduction

Fractional calculus is a developing field of the applied mathematics regarding integrodifferential equations involving fractional integrals and derivatives. The increasing interest in fractional calculus has been motivated by many applications of fractional equations in different fields of research (see for example [6, 16, 17, 22]). However, most of the papers in this field are focused on the analysis of fractional equations and processes in one dimension, there are few works regarding fractional vector calculus and its applications in theory of electromagnetic fields, fluidodynamics and multidimensional processes. A first attempt to give a formulation of fractional vector calculus is due to Ben Adda [3]. Recently a different approach in the framework of multidimensional fractional advection-dispersion equation has been developed by Meerschaert et al. $[18,19,20]$. They present a general definition of gradient, divergence and curl, in relation to fractional directional derivatives. In their view, the fractional gradient is a weighted sum of fractional directional derivatives in each direction. We notice that

[^0]this general approach to fractional gradient, depending on the choice of the mixing measure, includes also the definition of fractional gradient given by Tarasov in [29, 30] (see also the recent book [28]) as a natural extension of the ordinary case. Starting from these works, many authors have been interested in understanding the applications of this fractional vector calculus in the theory of electromagnetic fields in fractal media (see for example [2] and [23]) and in the analysis of multidimensional advectiondispersion equation ([5, 20]). Moreover, in [11], the authors study the application of fractional vector calculus to the multidimensional Bloch-Torrey equation.

In this paper we study multidimensional fractional advection and dispersion equations involving fractional directional derivatives, both from the deterministic and stochastic point of view. We show some consequences of our approach, to treat multidimensional fractional differential equations. From a physical point of view, we present a formulation of the fractional advection equation based on the fractional conservation of mass, introduced in [32]. In this framework we also find the stochastic solution for the multidimensional fractional advection equation with random initial data.

Furthermore, the properties of a class of multidimensional Lévy processes related to fractional gradients are investigated. Some results about a new Lévy-Khinchine formula (and the corresponding generators) are presented. It is well known that long jump random walks lead to limit processes governed by the fractional Laplacian. We establish some connections between compound Poisson processes with given jumps and the corresponding limit processes which are driven by our Lévy-Khinchine formula involving fractional gradient.

A general translation semigroup and the related Frobenius-Perron operator are also introduced and the associated advection equations are investigated. As in the previous cases, we find relation with compound Poisson processes.

We finally study the fractional power of the second order directional derivative $(\boldsymbol{\theta} \cdot \nabla)^{2}$ and the heat-type equation involving this operator.

## 2 Fractional gradient operators and fractional directional derivatives

In the general approach developed by Meerschaert et al. [20] in the framework of the multidimensional fractional advection-dispersion equation, given a scalar function $f(\mathbf{x})$, the fractional gradient can be defined as

$$
\begin{equation*}
\nabla_{M}^{\beta} f(\mathbf{x})=\int_{\|\boldsymbol{\theta}\|=1} \boldsymbol{\theta} D_{\boldsymbol{\theta}}^{\beta} f(\mathbf{x}) M(d \boldsymbol{\theta}), \mathbf{x} \in \mathbb{R}^{d}, \beta \in(0,1) \tag{2.1}
\end{equation*}
$$

where $\boldsymbol{\theta}=\left(\theta_{1}, \ldots, \theta_{d}\right)$ is a unit column vector; $M(d \boldsymbol{\theta})$ is a positive finite measure, called mixing measure;

$$
\begin{equation*}
D_{\boldsymbol{\theta}}^{\beta} f(\mathbf{x})=(\boldsymbol{\theta} \cdot \nabla)^{\beta} f(\mathbf{x}) \tag{2.2}
\end{equation*}
$$

is the fractional directional derivative of order $\beta$ (see for example [8]).
The Fourier transform of fractional directional derivatives (2.2) (in our notation) is given by

$$
\widehat{D_{\boldsymbol{\theta}}^{\beta}} f(\mathbf{k})=\widehat{(\boldsymbol{\theta} \cdot \nabla)^{\beta}} f(\mathbf{k})=(-i \boldsymbol{\theta} \cdot \mathbf{k})^{\beta} \widehat{f}(\mathbf{k})
$$

where

$$
\widehat{f}(\mathbf{k})=\int_{\mathbb{R}^{d}} e^{i \mathbf{k} \cdot \mathbf{x}} f(\mathbf{x}) d \mathbf{x}
$$

Hence the Fourier transform of (2.1) is written as

$$
\begin{equation*}
\widehat{\nabla_{M}^{\beta} f}(\mathbf{k})=\int_{\|\boldsymbol{\theta}\|=1} \boldsymbol{\theta}(-i \mathbf{k} \cdot \boldsymbol{\theta})^{\beta} \widehat{f}(\mathbf{k}) M(d \boldsymbol{\theta}) \tag{2.3}
\end{equation*}
$$

This is a general definition of fractional gradient, depending on the choice of the mixing measure $M(d \boldsymbol{\theta})$. We can infer the physical and geometrical meaning of this definition: it is a weighted sum of the fractional directional derivatives in each direction on a unitary sphere. The definition (2.1) is really general and directly related to multidimensional stable distributions. The divergence of (2.1) is given by

$$
\begin{equation*}
\mathbb{D}_{M}^{\alpha} f(\mathbf{x}):=\nabla \cdot \nabla_{M}^{\alpha-1} f(\mathbf{x})=\int_{\|\boldsymbol{\theta}\|=1} D_{\boldsymbol{\theta}}^{\alpha} f(\mathbf{x}) M(d \boldsymbol{\theta}), \mathbf{x} \in \mathbb{R}^{d}, \alpha \in(1,2] \tag{2.4}
\end{equation*}
$$

whose Fourier transform, from (2.3), is written as

$$
\widehat{\mathbb{D}_{M}^{\alpha} f}(\mathbf{k})=\int_{\|\boldsymbol{\theta}\|=1}(-i \mathbf{k} \cdot \boldsymbol{\theta})^{\alpha} \widehat{f}(\mathbf{k}) M(d \boldsymbol{\theta})
$$

The scalar operator $\mathbb{D}_{M}^{\alpha}$ plays the role of fractional Laplacian in the fractional diffusion equation, introducing a more general class of processes depending on the choice of the measure $M$. For the sake of clarity we refer to Meerschaert et al. [18] about multidimensional fractional diffusion-type equations involving this kind of operators.

Let us consider the multidimensional fractional diffusion-type equation involving $\mathrm{D}_{M}^{\alpha}$, given by

$$
\begin{equation*}
\frac{\partial u}{\partial t}(\mathbf{x}, t)=\mathbb{D}_{M}^{\alpha} u(\mathbf{x}, t) \tag{2.5}
\end{equation*}
$$

with initial condition

$$
u(\mathbf{x}, 0)=\delta(\mathbf{x})
$$

We obtain by Fourier transform

$$
\frac{\partial \hat{u}}{\partial t}(\mathbf{k}, t)=\int_{\|\boldsymbol{\theta}\|=1}(-i \mathbf{k} \cdot \boldsymbol{\theta})^{\alpha} M(d \boldsymbol{\theta}) \hat{u}(\mathbf{k}, t)
$$

Then, the solution of (2.5) in the Fourier space is given by

$$
\hat{u}(\mathbf{k}, t)=\exp \left(t \int_{\|\boldsymbol{\theta}\|=1}(-i \mathbf{k} \cdot \boldsymbol{\theta})^{\alpha} M(d \boldsymbol{\theta})\right)
$$

which is strictly related with multivariate stable distributions, as the following well known result entails

Theorem 2.1 ([26], pag. 65). Let $\alpha \in(0,2)$, then $\boldsymbol{\theta}=\left(\theta_{1}, \ldots, \theta_{d}\right)$ is an $\alpha$-stable random vector in $\mathbb{R}^{d}$ if and only if there exists a finite measure $\Gamma$ on the unitary sphere and a vector $\boldsymbol{\mu}^{0}=\left(\mu_{1}^{0}, \ldots . \mu_{d}^{0}\right)$ such that its characteristic function is given by

$$
\mathbb{E} \exp \{i(\mathbf{k} \cdot \boldsymbol{\theta})\}=e^{-\sigma \psi(\mathbf{k})}
$$

where $\sigma=\cos \left(\frac{\pi \alpha}{2}\right)$, and

$$
\psi(\mathbf{k})= \begin{cases}\int_{\|\boldsymbol{\theta}\|=1}|\boldsymbol{\theta} \cdot \mathbf{k}|^{\alpha}\left(1-i \operatorname{sign}(\boldsymbol{\theta} \cdot \mathbf{k}) \tan \frac{\pi \alpha}{2}\right) \Gamma(d \boldsymbol{\theta})+i\left(\mathbf{k} \cdot \boldsymbol{\mu}^{0}\right), & \text { if } \alpha \neq 1 \\ \int_{\|\boldsymbol{\theta}\|=1}|\boldsymbol{\theta} \cdot \mathbf{k}|\left(1+i \frac{2}{\pi} \operatorname{sign}(\boldsymbol{\theta} \cdot \mathbf{k}) \ln |(\boldsymbol{\theta} \cdot \mathbf{k})|\right) \Gamma(d \boldsymbol{\theta})+i\left(\mathbf{k} \cdot \boldsymbol{\mu}^{0}\right), & \text { if } \alpha=1\end{cases}
$$

The pair $\left(\Gamma, \mu^{0}\right)$ is unique.
In light of Theorem 2.1 and the fact that

$$
(-i \zeta)^{\alpha}=|\zeta|^{\alpha} e^{-i \frac{\pi}{2} \alpha \frac{\zeta}{|\zeta|}}=|\zeta|^{\alpha} e^{-i \frac{\pi}{2} \alpha \operatorname{sign}(\zeta)}
$$

the solution of (2.5) can be interpreted as the law of a $d$-dimensional $\alpha$-stable vector, whose characteristic function is given, for $\alpha \neq 1$, by the pair ( $M, \boldsymbol{0}$ ), i.e. the vector $\boldsymbol{\mu}^{0}$
is null and the measure $M$ is the spectral measure of the random vector $\theta$. This is a general approach to multidimensional fractional differential equations, suggesting the geometrical and probabilistic meaning of (2.5). On the other hand it includes a wide class of processes, depending on the spectral measure $M$. As a first notable example, being $M(d \boldsymbol{\theta})=m(\boldsymbol{\theta}) d \boldsymbol{\theta}$, if we take $m(\boldsymbol{\theta})=$ const. in (2.4), then we obtain the well known Riesz derivative (see e.g. [25], pag. 500 formula (25.62)). In the framework of fractional vector calculus we obtain a geometric interpretation of the fractional Laplacian which is strictly related to uniform isotropic measure.

We also notice that the definition of fractional gradient given by Tarasov [29] is a special case of (2.1), corresponding to the case in which the mixing measure is a point mass at each coordinate vector $\mathbf{e}_{i}$, for $i=1, \ldots, d$. In this case the fractional gradient seems to be a formal extension of the ordinary to the fractional case, i.e.

$$
\begin{equation*}
\nabla^{\beta} f(\mathbf{x})=\sum_{i=1}^{d} \frac{\partial^{\beta} f(\mathbf{x})}{\partial x_{i}^{\beta}} \mathbf{e}_{i} \tag{2.6}
\end{equation*}
$$

where $\frac{\partial^{\beta} f}{\partial x_{i}^{\beta}}$ is the Weyl partial fractional derivative of order $\beta \in(0,1)$, defined as ([25], pag. 95)

$$
\frac{d^{\beta} f}{d x^{\beta}}=\frac{1}{\Gamma(1-\beta)} \frac{d}{d x} \int_{-\infty}^{x}(x-y)^{-\beta} f(y) d y, \quad x \in \mathbb{R}
$$

Formula (2.6) seems to be a natural way to generalize the definition of gradient of fractional order. Indeed, for $\beta=1$ we recover the ordinary gradient. From a geometrical point of view this is an integration centered on preferred directions given by the Cartesian set of axes. From a probabilistic point of view this is the unique case in which an $\alpha$-stable random vector has independent components as shown by Samorodnitsky and Taqqu ([26], Example 2.3.5, pag. 68). It corresponds to a choice of the spectral measure $\Gamma$ discrete and concentrated on the intersection of the axes with the unitary sphere.

In this paper we adopt an intermediate approach between the special case treated by Tarasov in [28] and the most general one treated by Meerschaert et al. in [20]. Indeed, we consider the following subcase of the general definition (2.1)

Definition 2.2. For $\beta \in(0,1)$ and a "good" scalar function $f(\mathbf{x}), \mathbf{x} \in \mathbb{R}^{d}$, being $\left(\boldsymbol{\theta}_{1}, \ldots \ldots, \boldsymbol{\theta}_{d}\right)$, with $\boldsymbol{\theta}_{j} \in \mathbb{R}^{d}$, for $j=1,2, . ., d$, an orthonormal basis, the fractional gradient is written as

$$
\begin{equation*}
\nabla_{\theta}^{\beta} f(\mathbf{x})=\sum_{l=1}^{d} \boldsymbol{\theta}_{l}\left(\boldsymbol{\theta}_{l} \cdot \nabla\right)^{\beta} f(\mathbf{x}), \quad f \in L^{1}\left(\mathbb{R}^{d}\right) \tag{2.7}
\end{equation*}
$$

where we use the subscript $\theta$ to underline the connection with the mixing measure $M$ which is a point mass measure at each coordinate vectors $\boldsymbol{\theta}_{l}, l=1, \cdots, d$.

This is a superposition of fractional directional derivatives, taking into account all the directions $\boldsymbol{\theta}_{i}$, it is a more general approach than that adopted by Tarasov. However, also in this case, for $\beta=1$ we recover the definition of the ordinary gradient. An explicit representation of the fractional gradient (2.7) is given by means of operational methods. Indeed, in [8], it was shown that the fractional power of the directional derivative is given by

$$
(\boldsymbol{\theta} \cdot \nabla)^{\beta} f(\mathbf{x})=\frac{\beta}{\Gamma(1-\beta)} \int_{0}^{\infty}(f(\mathbf{x})-f(\mathbf{x}-s \boldsymbol{\theta})) s^{-\beta-1} d s, \quad \beta \in(0,1)
$$

so that (2.7) has the following representation

$$
\nabla_{\theta}^{\beta} f(\mathbf{x})=\sum_{l=1}^{d} \frac{\beta \boldsymbol{\theta}_{l}}{\Gamma(1-\beta)} \int_{0}^{\infty}\left(f(\mathbf{x})-f\left(\mathbf{x}-s \boldsymbol{\theta}_{l}\right)\right) s^{-\beta-1} d s
$$

Our specialization of (2.1) provides useful and manageable tools to treat fractional equations in multidimensional spaces in order to find explicit solutions. We notice that each vector in the orthonormal basis $\left(\boldsymbol{\theta}_{1}, \ldots \ldots ., \boldsymbol{\theta}_{d}\right)$ can be expressed in terms of the canonical basis $\mathbf{e}_{i}$ by applying a rotation matrix, such that

$$
\boldsymbol{\theta}_{i}=\sum_{k=1}^{d} \theta_{i k} \mathbf{e}_{k}
$$

The Fourier transform of (2.7) is given by

$$
\begin{equation*}
\widehat{\nabla_{\theta}^{\beta}} f(\mathbf{k})=\sum_{l=1}^{d} \boldsymbol{\theta}_{l}\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\beta} \widehat{f}(\mathbf{k}) \tag{2.8}
\end{equation*}
$$

A relevant point to understand the consequence of this definition in the framework of fractional vector calculus is given by the definition of fractional Laplacian. For $\beta \in$ $(1,2]$, given a scalar function $f(\mathbf{x})$, with $\mathbf{x} \in \mathbb{R}^{d}$, the fractional directional operator corresponding to the definition (2.7) is given by

$$
\mathbb{D}_{\theta}^{\beta} f(\mathbf{x})=\nabla_{\theta} \cdot \nabla_{\theta}^{\beta-1} f(\mathbf{x})
$$

that is the inverse Fourier transform of

$$
\begin{equation*}
\widehat{\mathrm{D}_{\theta}^{\beta} f}(\mathbf{k})=\sum_{l=1}^{d}\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\beta} \widehat{f}(\mathbf{k}) . \tag{2.9}
\end{equation*}
$$

We remark that the fractional operator (2.9) is given by the sum of fractional directional derivatives of order $\beta \in(1,2]$. Indeed, by inverting (2.9), we get

$$
\mathbb{D}_{\theta}^{\beta} f(\mathbf{x})=\sum_{l=1}^{d}\left(\boldsymbol{\theta}_{l} \cdot \nabla\right)^{\beta} f(\mathbf{x})
$$

In the same way we can give a definition of fractional divergence of a vector field as follows

$$
\operatorname{div}^{\beta} \mathbf{u}(\mathbf{x}, t)=\nabla_{\theta}^{\beta} \cdot \mathbf{u}=\sum_{l=1}^{d}\left(\boldsymbol{\theta}_{l} \cdot \nabla\right)^{\beta} \boldsymbol{\theta}_{l} \cdot \mathbf{u}(\mathbf{x}, t)
$$

with $\beta \in(0,1)$.
Example 2.3. Let us consider the case $\mathbf{x} \in \mathbb{R}^{2}$. In this case we denote $\boldsymbol{\theta}_{1} \equiv\left(\cos \theta_{1}, \sin \theta_{1}\right)$ and $\boldsymbol{\theta}_{2} \equiv\left(\cos \theta_{2}, \sin \theta_{2}\right)$. By definition, these two vectors must be orthonormal, hence $\theta_{2}=\theta_{1}+\frac{\pi}{2}$. These two fixed directions are given by a rotation of the cartesian axes. In this case the fractional gradient is given by

$$
\nabla_{\theta}^{\beta} f(\mathbf{x}) \equiv\left[\left(\cos \theta_{1}, \sin \theta_{1}\right)\left(\cos \theta_{1} \partial_{x}+\sin \theta_{1} \partial_{y}\right)^{\beta}+\left(\cos \theta_{2}, \sin \theta_{2}\right)\left(\cos \theta_{2} \partial_{x}+\sin \theta_{2} \partial_{y}\right)^{\beta}\right] f(\mathbf{x})
$$

An interesting discussion about this two-dimensional case can be found in [10].

Remark 2.4. We observe that in the case $\boldsymbol{\theta}_{i} \equiv \mathbf{e}_{i}$, we have the definition of fractional gradient given by Tarasov. The divergence of this operator brings to the analog of the fractional Laplacian, given by

$$
\begin{equation*}
\nabla_{\theta} \cdot \nabla_{\theta}^{\beta} f(\mathbf{x})=\sum_{k=1}^{d} \frac{\partial}{\partial x_{k}} \frac{\partial^{\beta}}{\partial x_{k}^{\beta}} f(\mathbf{x}) \tag{2.10}
\end{equation*}
$$

which means that, for $\beta=1$, we recover the classical definition of Laplacian. We remark that the operator (2.10) strongly differs from the fractional Laplacian. From an analytical point of view, the sum of fractional derivatives clearly differs from the fractional power of the sum of second order ordinary derivatives. From a probabilistic point of view, the operator appearing in (2.10) is the governing operator of a random vector with independent components, while the fractional Laplacian is the generator of a random vector with dependent components.
Moreover, we observe that in some cases the Riemann-Liouville derivative does not satisfy the law of exponent,

$$
\frac{\partial}{\partial x} \frac{\partial^{\beta}}{\partial x^{\beta}} f(\mathbf{x}) \neq \frac{\partial^{1+\beta}}{\partial x^{1+\beta}} f(\mathbf{x})
$$

Hence, in this case the fractional heat equation, for $d=2$, has the following form

$$
\frac{\partial}{\partial t} f(x, y, t)=\left(\frac{\partial}{\partial x} \frac{\partial^{\beta}}{\partial x^{\beta}}+\frac{\partial}{\partial y} \frac{\partial^{\beta}}{\partial y^{\beta}}\right) f(x, y, t)
$$

i.e. a multidimensional heat equation with fractional sequential derivatives. We observe that (2.10) leads to the Riemann-Liouville fractional analog of the Laplace operator recently studied by Dalla Riva and Yakubovich in [7]. The physical and probabilistic meaning of this formulation will be discussed below in relation to the general formulation concerning Definition 2.2.

Remark 2.5. An interesting generalization of the fractional gradient defined in (2.1) can be given in the case where the fractional order depends by the direction. In this case we have the following definition

$$
\begin{equation*}
\nabla_{M}^{\beta(\boldsymbol{\theta})} f(\mathbf{x})=\int_{\|\boldsymbol{\theta}\|=1} \boldsymbol{\theta} D_{\boldsymbol{\theta}}^{\beta(\boldsymbol{\theta})} f(\mathbf{x}) M(d \boldsymbol{\theta}), \quad \mathbf{x} \in \mathbb{R}^{d}, \beta(\cdot) \in(0,1) \tag{2.11}
\end{equation*}
$$

As a special case of this definition, that can be more simple and suitable for the applications, one can consider the following operator

$$
\begin{equation*}
\nabla_{\theta}^{\beta(\boldsymbol{\theta})} f(\mathbf{x})=\sum_{l=1}^{d} \boldsymbol{\theta}_{l}\left(\boldsymbol{\theta}_{l} \cdot \nabla\right)^{\beta_{l}} f(\mathbf{x}), \quad f \in L^{1}\left(\mathbb{R}^{d}\right) \tag{2.12}
\end{equation*}
$$

This directional-dependent fractional operator should be object of further investigations.

## 3 Multidimensional fractional directional advection equation

We study the $d$-dimensional fractional advection equation by following the approach to fractional vector calculus suggested in the previous section. From a physical point of view we get inspiration from [20], where the fractional vector calculus has been applied in order to study the flow of contaminants in an heterogeneous porous medium. First of all we derive the fractional multidimensional advection equation, starting from the continuity equation, that is

$$
\begin{equation*}
\frac{\partial \rho_{\alpha}}{\partial t}=-\operatorname{div}^{\alpha} \mathbf{V}, \alpha \in(0,1) \tag{3.1}
\end{equation*}
$$

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where $\rho_{\alpha}(\mathbf{x}, t)$ is the density of contaminant particles and $\mathbf{V}(\mathbf{x}, t)$ is the flux, that is the vector rate at which mass is transported through a unit surface. The physical meaning of this fractional conservation of mass can be directly related to the recent paper by Wheatcraft and Meerschaert [32]. The relation between flux and density of contaminants is given by the classical Fick's law, its form in absence of dispersion is simply

$$
\mathbf{V}(\mathbf{x}, t)=\mathbf{u} \rho_{\alpha}(\mathbf{x}, t)
$$

where $\mathbf{u}$ is the velocity field of contaminant particles; for simplicity in the following discussion we take this velocity field constant in all directions. By substitution we find the $n$-dimensional fractional advection equation in the following form

$$
\frac{\partial \rho_{\alpha}}{\partial t}=-\operatorname{div}^{\alpha}\left(\mathbf{u} \rho_{\alpha}\right)=-\nabla_{\theta}^{\alpha} \cdot\left(\mathbf{u} \rho_{\alpha}\right)
$$

We observe that, even if we roughly consider a constant velocity field $\mathbf{u}$, this apparently unrealistic assumption, is considered and discussed also in the literature about the applications of fractional advection-dispersion in geophysics (see for example [27] and references therein).

Hereafter we denote by $\chi_{D}$ the characteristic function of the set $D$. We are now ready to state the following
Theorem 3.1. Let us consider the d-dimensional fractional advection equation

$$
\begin{equation*}
\frac{\partial}{\partial t} \rho_{\alpha}+\nabla_{\theta}^{\alpha} \cdot\left(\mathbf{u} \rho_{\alpha}\right)=0, \quad \mathbf{x} \in \mathbb{R}^{d}, t>0 \tag{3.2}
\end{equation*}
$$

where $\alpha \in(0,1)$, and $\mathbf{u} \equiv\left(u_{1}, \ldots ., u_{d}\right)$ is the velocity field, with $u_{i}, i=1, \ldots, d$, constants. The solution to (3.2), subject to the initial condition

$$
\rho_{\alpha}(\mathbf{x}, 0)=f(\mathbf{x}) \in L^{1}\left(\mathbb{R}^{d}\right)
$$

is written as

$$
\begin{equation*}
\rho_{\alpha}(\mathbf{x}, t)=\int_{\mathbb{R}^{d}} f(\mathbf{y}) \prod_{l=1}^{d} \mathcal{U}_{\alpha}\left(\boldsymbol{\theta}_{l} \cdot(\mathbf{x}-\mathbf{y}),\left(\mathbf{u} \cdot \boldsymbol{\theta}_{l}\right) t\right) \chi_{\left\{\boldsymbol{\theta}_{l} \cdot(\mathbf{x}-\mathbf{y}) \geq 0\right\}}(\mathbf{y}) d \mathbf{y} \tag{3.3}
\end{equation*}
$$

where $\mathcal{U}_{\alpha}$ is the solution to

$$
\begin{equation*}
\left(\frac{\partial}{\partial t}+\lambda \frac{\partial^{\alpha}}{\partial x^{\alpha}}\right) \mathcal{U}_{\alpha}(x, t)=0, \quad x \in \mathbb{R}_{+}, t>0, \lambda \in \mathbb{R}_{+} \tag{3.4}
\end{equation*}
$$

with initial condition $\mathcal{U}_{\alpha}(x, 0)=\delta(x)$.
Proof. We start by taking the Fourier transform of equation (3.2), given by

$$
\frac{\partial}{\partial t} \widehat{\rho_{\alpha}}(\mathbf{k}, t)+\mathbf{u} \cdot \widehat{\nabla_{\theta}^{\alpha} \rho_{\alpha}}(\mathbf{k}, t)=0
$$

From (2.8), we obtain that

$$
\left(\frac{\partial}{\partial t}+\left(\sum_{l=1}^{d}\left(\mathbf{u} \cdot \boldsymbol{\theta}_{l}\right)\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\right)\right) \widehat{\rho_{\alpha}}(\mathbf{k}, t)=0
$$

and by integration we find

$$
\begin{align*}
\widehat{\rho_{\alpha}}(\mathbf{k}, t) & =\widehat{f}(\mathbf{k}) \exp \left(-t \sum_{l=1}^{d}\left(\mathbf{u} \cdot \boldsymbol{\theta}_{l}\right)\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\right)  \tag{3.5}\\
& =\widehat{f}(\mathbf{k}) \prod_{l=1}^{d} \exp \left(-t\left(\mathbf{u} \cdot \boldsymbol{\theta}_{l}\right)\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\right)
\end{align*}
$$

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If we take the Fourier transform of equation (3.4), then we obtain

$$
\begin{equation*}
\left(\frac{\partial}{\partial t}+\lambda(-i \gamma)^{\alpha}\right) \widehat{\mathcal{U}_{\alpha}}(\gamma, t)=0 \tag{3.6}
\end{equation*}
$$

where we used the fact that

By integrating (3.6), and by taking into account the initial condition, we obtain

$$
\widehat{\mathcal{U}_{\alpha}}(\gamma, t)=\exp \left(-\lambda t(-i \gamma)^{\alpha}\right) .
$$

Thus, we can rearrange (3.5) as follows

$$
\begin{aligned}
\widehat{\rho}_{\alpha}(\mathbf{k}, t) & =\widehat{f}(\mathbf{k}) \prod_{l=1}^{d} \exp \left(-t\left(\mathbf{u} \cdot \boldsymbol{\theta}_{l}\right)\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\right) \\
& =\left.\widehat{f}(\mathbf{k}) \prod_{l=1}^{d} \widehat{\mathcal{U}_{\alpha}}\left(\gamma_{l}, \lambda_{l} t\right)\right|_{\gamma_{l}=\mathbf{k} \cdot \boldsymbol{\theta}_{l}, \lambda_{l}=\mathbf{u} \cdot \boldsymbol{\theta}_{l}} .
\end{aligned}
$$

Finally, we observe that the inverse Fourier transform of any

$$
\widehat{\mathcal{U}_{\alpha}}\left(\mathbf{k} \cdot \boldsymbol{\theta}_{l}, \lambda_{l} t\right), \quad l=1,2, \cdots, d
$$

is given by

$$
\mathcal{U}_{\alpha}\left(\mathbf{x} \cdot \boldsymbol{\theta}_{l}, \lambda_{l} t\right) \chi_{\left\{\left(\mathbf{x} \cdot \boldsymbol{\theta}_{l}\right) \geq 0\right\}} \quad l=1,2, \cdots, d,
$$

and therefore, we get that

$$
\begin{equation*}
\rho_{\alpha}(\mathbf{x}, t)=(f * G)(\mathbf{x}, t), \tag{3.7}
\end{equation*}
$$

where the symbol $*$ stands for Fourier convolution, and

$$
G(\mathbf{x}, t)=\prod_{l=1}^{d} \mathcal{U}_{\alpha}\left(\mathbf{x} \cdot \boldsymbol{\theta}_{l},\left(\mathbf{u} \cdot \boldsymbol{\theta}_{l}\right) t\right) \chi_{\left\{\left(\mathbf{x} \cdot \boldsymbol{\theta}_{l}\right) \geq 0\right\}}
$$

Formula (3.7) can be explicitly written as

$$
\begin{equation*}
\rho_{\alpha}(\mathbf{x}, t)=\int_{\mathbb{R}^{d}} f(\mathbf{y}) G(\mathbf{x}-\mathbf{y}, t) d \mathbf{y} \tag{3.8}
\end{equation*}
$$

therefore (3.8) coincides with (3.3) and the proof is completed.

Let us consider the Lévy process $\left(\boldsymbol{X}_{t}\right)_{t \geq 0}$, with infinitesimal generator $\mathcal{A}$ and transition semigroup $P_{t}=e^{t \mathcal{A}}$. The transition law of $\left(\boldsymbol{X}_{t}\right)_{t \geq 0}$ is written as

$$
P_{t} u_{0}(\mathbf{x})=\mathbb{E} u_{0}\left(\mathbf{X}_{t}+\mathbf{x}\right),
$$

and solves the Cauchy problem

$$
\left\{\begin{array}{l}
\frac{\partial}{\partial t} u(\mathbf{x}, t)=(\mathcal{A} u)(\mathbf{x}, t)  \tag{3.9}\\
u(\mathbf{x}, 0)=u_{0}(\mathbf{x})
\end{array}\right.
$$

We say that the process $\left(\boldsymbol{X}_{t}\right)_{t \geq 0}$ is the stochastic solution of (3.9). We also consider the integral representation of $\mathcal{A}$, given by

$$
\begin{equation*}
(\mathcal{A} f)(\mathbf{x})=\frac{1}{(2 \pi)^{d}} \int_{\mathbb{R}^{d}} e^{-i \mathbf{k} \cdot \mathbf{x}} \Phi(\mathbf{k}) \widehat{f}(\mathbf{k}) d \mathbf{k} \tag{3.10}
\end{equation*}
$$

for all functions $f$ in the domain

$$
D(\mathcal{A})=\left\{f(\mathbf{x}) \in L_{l o c}^{1}\left(\mathbb{R}^{d}, d \mathbf{x}\right): \int_{\mathbb{R}^{d}} \Phi(\mathbf{k})|\widehat{f}(\mathbf{k})|^{2} d \mathbf{k}<\infty\right\}
$$

Then, we say that $P_{t}$, with symbol $\widehat{P}_{t}=\exp (t \Phi)$, is the semigroup associated with the pseudo-differential operator $\mathcal{A}$ and $\Phi$ is the Fourier multiplier of $\mathcal{A}$. Furthermore from the characteristic function of the process $\left(\boldsymbol{X}_{t}\right)_{t \geq 0}$, we obtain that

$$
\left[\frac{\partial}{\partial t} \mathbb{E} e^{i \mathbf{k} \cdot \boldsymbol{X}_{t}}\right]_{t=0}=\Phi(\mathbf{k})
$$

We also recall that a stable subordinator $\left(\mathfrak{H}_{t}^{\alpha}\right)_{t>0}, \alpha \in(0,1)$, is a Lévy process with nonnegative, independent and stationary increments, whose law, say $h_{\alpha}(x, t), x \geq 0, t \geq 0$, has the Laplace transform

$$
\begin{equation*}
\tilde{h}_{\alpha}(s, t)=\int_{0}^{+\infty} e^{-s x} h_{\alpha}(x, t) d x=e^{-t s^{\alpha}}, \quad s \geq 0 \tag{3.11}
\end{equation*}
$$

For more details on this topic we refer to [4].
Let $P_{t}$ be the semigroup associated with (3.2), then, for all $t>0$

$$
\begin{equation*}
\left\|P_{t} f\right\|_{\infty} \leq d\|f\|_{L^{1}} \tag{3.12}
\end{equation*}
$$

Indeed, from the fact that

$$
\left\|\mathcal{U}_{\alpha}(\cdot, t)\right\|_{\infty} \leq 1, \quad \text { uniformly }
$$

and, from (3.7),

$$
\|G(\cdot, t)\|_{\infty} \leq d\left\|\mathcal{U}_{\alpha}(\cdot, t)\right\|_{\infty}
$$

we have that

$$
\left\|P_{t} f\right\|_{\infty} \leq d\left\|\mathcal{U}_{\alpha}(\cdot, t)\right\|_{\infty}\|f\|_{L^{1}} \leq d\|f\|_{L^{1}}
$$

We present the following result concerning the equation (3.2).
Theorem 3.2. The stochastic solution to the d-dimensional fractional advection equation (3.2), subject to the initial condition $\rho_{\alpha}(\mathbf{x}, 0)=\delta(\mathbf{x})$, is given by the process

$$
\boldsymbol{Z}_{t}=\sum_{l=1}^{d} \boldsymbol{\theta}_{l} \mathfrak{H}_{l}^{\alpha}\left(\lambda_{l} t\right), \quad t \geq 0
$$

which is a random vector in $\mathbb{R}^{d}$, where for $l=1, \ldots, d, \lambda_{l}=\mathbf{u} \cdot \boldsymbol{\theta}_{l}$ and $\mathfrak{H}_{l}^{\alpha}(t), t>0$, are independent $\alpha$-stable subordinators.

Proof. We recall that

$$
\begin{equation*}
\widehat{\rho_{\alpha}}(\mathbf{k}, t)=\prod_{l=1}^{d} \exp \left(-t\left(\mathbf{u} \cdot \boldsymbol{\theta}_{l}\right)\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\right) \tag{3.13}
\end{equation*}
$$

is the Fourier transform of the solution to (3.2), with initial condition $\rho_{0}(\mathbf{x})=\delta(\mathbf{x})$. By using (3.11), formula (3.13) can be written as

$$
\begin{align*}
\widehat{\rho_{\alpha}}(\mathbf{k}, t) & =\prod_{l=1}^{d} \mathbb{E} \exp \left(\left(i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right) \mathfrak{H}_{l}^{\alpha}\left(\lambda_{l} t\right)\right)  \tag{3.14}\\
& =\mathbb{E} \exp \left(i \sum_{l=1}^{d}\left(\mathbf{k} \cdot \boldsymbol{\theta}_{l}\right) \mathfrak{H}_{l}^{\alpha}\left(\lambda_{l} t\right)\right) \\
& =\mathbb{E} \exp \left(i \mathbf{k} \cdot \sum_{l=1}^{d} \boldsymbol{\theta}_{l} \mathfrak{H}_{l}^{\alpha}\left(\lambda_{l} t\right)\right)=\mathbb{E} e^{i \mathbf{k} \cdot \boldsymbol{Z}_{t}} .
\end{align*}
$$

Hence $\rho_{\alpha}$ is the law of the process $\boldsymbol{Z}_{t}=\sum_{l=1}^{d} \boldsymbol{\theta}_{l} \mathfrak{H}_{l}^{\alpha}\left(\lambda_{l} t\right)$, that is a random vector whose components are given by different linear combination of $d$ independent $\alpha$-stable subordinators.

We observe that these processes can be studied in the general framework of Lévy additive processes.

We now study the Cauchy problem for the multidimensional fractional advection equation with random initial data. The theory of random solutions of partial differential equations has a long history, starting from the pioneeristic works of Kampé de Fériet [14].

Theorem 3.3. Let us consider the Cauchy problem

$$
\left\{\begin{array}{l}
\frac{\partial}{\partial t} \rho_{\alpha}+\nabla_{\theta}^{\alpha} \cdot\left(\mathbf{u} \rho_{\alpha}\right)=0, \quad \mathbf{x} \in \mathbb{R}^{d}, t>0, \alpha \in(0,1)  \tag{3.15}\\
\rho_{\alpha}(\mathbf{x}, 0)=X(\mathbf{x}) \in L^{2}(\mathbb{R})
\end{array}\right.
$$

where the random field $X(\mathrm{x}), \mathrm{x} \in \mathbb{R}_{+}^{d}$, is a random initial condition $X:(\Omega, \mathcal{A}, P) \rightarrow$ $\left(\mathbb{R}, \mathcal{B}(\mathbb{R}), e^{-x^{2} / 2} / \sqrt{2 \pi}\right)$, such that

$$
\begin{equation*}
X(\mathbf{x})=\sum_{j \in \mathbb{N}} c_{j} \varphi_{j}(\mathbf{x}), \quad c_{j}=\int_{\mathbb{R}^{d}} X(\mathbf{x}) \varphi_{j}(\mathbf{x}) d \mathbf{x} \tag{3.16}
\end{equation*}
$$

where $\left\{\varphi_{j}\right\}$ is dense in $L^{2}(\mathbb{R})$. Then, the stochastic solution of (3.15) is given by

$$
\rho_{\alpha}(\mathbf{x}, t)=\sum_{j \in \mathbb{N}} c_{j} P_{t} \varphi_{j}(\mathbf{x})
$$

where $P_{t}$ is the transition semigroup associated with (3.2).
Proof. Since $X \in L^{2}$, then there exists an orthonormal system $\left\{\varphi_{j}: j \in \mathbb{N}\right\}$ such that (3.16) holds true in $L^{2}$. Indeed the first identity in (3.16) must be understood in $L^{2}(d P \times$ $d \mathbf{x}$ ) sense as follows

$$
\lim _{L \rightarrow \infty} \mathbb{E}\left[\int_{\mathbb{R}^{d}}\left(X(\mathbf{x})-\sum_{j=0}^{L} c_{j} \varphi_{j}(\mathbf{x})\right)^{2} d \mathbf{x}\right]=0
$$

From Theorem 3.2, we know that $\mathbf{Z}_{t}$ is the stochastic solution to the $d$-dimensional fractional advection equation (3.2). In view of these facts we write the solution of (3.15) as follows

$$
\begin{align*}
\rho_{\alpha}(\mathbf{x}, t) & =\mathbb{E}\left[X\left(\mathbf{x}+\mathbf{Z}_{t}\right) \mid \mathcal{F}_{X}\right]  \tag{3.17}\\
& =\mathbb{E}\left[\sum_{j \in \mathbb{N}} c_{j} \varphi_{j}\left(\mathbf{x}+\mathbf{Z}_{t}\right) \mid \mathcal{F}_{X}\right] \\
& =\sum_{j \in \mathbb{N}} c_{j} \mathbb{E} \varphi_{j}\left(\mathbf{x}+\mathbf{Z}_{t}\right),
\end{align*}
$$

where $\mathcal{F}_{X}$ is the $\sigma$-algebra generated by $X$ and we recall that

$$
c_{j}=\int_{\mathbb{R}^{d}} X(\mathbf{x}) \varphi_{j}(\mathbf{x}) d \mathbf{x}
$$

We observe that

$$
\mathbb{E} \varphi_{j}\left(\mathbf{x}+\mathbf{Z}_{t}\right)=P_{t} \varphi_{j}(\mathbf{x})
$$

is the solution to the Cauchy problem

$$
\left\{\begin{array}{l}
\frac{\partial}{\partial t} \rho_{\alpha}+\nabla_{\theta}^{\alpha} \cdot\left(\mathbf{u} \rho_{\alpha}\right)=0, \quad \mathbf{x} \in \mathbb{R}_{+}^{d}, t>0  \tag{3.18}\\
\rho_{\alpha}(\mathbf{x}, 0)=\varphi_{j}(\mathbf{x})
\end{array}\right.
$$

Therefore, (3.17) becomes

$$
\rho_{\alpha}(\mathbf{x}, t)=\sum_{j \in \mathbb{N}} c_{j} P_{t} \varphi_{j}(\mathbf{x})
$$

and solves (3.15) as claimed, being (3.18) satisfied term by term. Also, from the fact that $P_{0}=I d$, we get that

$$
\rho_{\alpha}(\mathbf{x}, 0)=\sum_{j \in \mathbb{N}} c_{j} P_{0} \varphi_{j}(\mathbf{x})=\sum_{j \in \mathbb{N}} c_{j} \varphi_{j}(\mathbf{x})=X(\mathbf{x})
$$

If $X$ is represented as (3.16), then $X$ is square-summable, that is

$$
\int_{\mathbb{R}^{d}} X^{2}(\mathbf{x}) d \mathbf{x}=\sum_{j \in \mathbb{N}} c_{j}^{2}<\infty
$$

Thus, from (3.12), we have that

$$
\left\|\rho_{\alpha}(\cdot, t)\right\|_{\infty} \leq \sum_{j \in \mathbb{N}}\left|c_{j}\right|\left\|\varphi_{j}\right\|_{\infty}<\infty
$$

### 3.1 Multidimensional fractional advection-dispersion equation

We follow our approach to study a general fractional advection-dispersion equation (FADE). We provide a multidimensional nonlocal formulation of the Fick's law, written as follows

$$
\begin{equation*}
\mathbf{V}(\mathbf{x}, t)=-\nu \nabla_{\theta}^{\beta-1} \rho_{\beta}(\mathbf{x}, t), \quad \beta \in(1,2), \nu \in \mathbb{R}_{+} \tag{3.19}
\end{equation*}
$$

such that

$$
\nabla \cdot \mathbf{V}(\mathbf{x}, t)=-\nu \mathbb{D}_{\theta}^{\beta} \rho_{\beta}(\mathbf{x}, t)
$$

The one-dimensional fractional Fick's law has been at the core of many recent papers (see for example [24] and the references therein). The total flux in the conservation of mass (3.1) is given by the sum of the advective flux and the dispersive flux. Hence we obtain the formulation of the FADE investigated in the next theorem.
Theorem 3.4. Let us consider the d-dimensional fractional advection-dispersion equation

$$
\begin{equation*}
\frac{\partial}{\partial t} \rho_{\alpha, \beta}+\nabla_{\theta}^{\alpha} \cdot\left(\mathbf{u} \rho_{\alpha, \beta}\right)=\mathbb{D}_{\theta}^{\beta} \rho_{\alpha, \beta}, \quad \mathbf{x} \in \mathbb{R}^{d}, t>0 \tag{3.20}
\end{equation*}
$$

where $\alpha \in(0,1), \beta \in(1,2)$ and $\mathbf{u} \equiv\left(u_{1}, \ldots ., u_{d}\right)$ is the velocity field, with $u_{i}, i=1, \ldots, d$, are constants. The solution to (3.20), subject to the initial condition

$$
\rho_{\alpha, \beta}(\mathbf{x}, 0)=\delta(\mathbf{x})
$$

is written as

$$
\rho_{\alpha, \beta}(\mathbf{x}, t)=\prod_{l=1}^{d} \mathcal{U}_{\alpha}\left(\boldsymbol{\theta}_{l} \cdot \mathbf{x},\left(\mathbf{u} \cdot \boldsymbol{\theta}_{l}\right) t\right) * \mathcal{U}_{\beta}\left(\boldsymbol{\theta}_{l} \cdot \mathbf{x}, t\right) \chi_{\left\{\left(\mathbf{x} \cdot \boldsymbol{\theta}_{l}\right) \geq 0\right\}},
$$

where $*$ stands for convolution with respect to $\mathrm{x}, \mathcal{U}_{\alpha}$ is the solution to the one-dimensional fractional advection equation

$$
\left(\frac{\partial}{\partial t}+\lambda \frac{\partial^{\alpha}}{\partial x^{\alpha}}\right) \mathcal{U}_{\alpha}(x, t)=0, \quad x \in \mathbb{R}_{+}, t>0, \lambda \in \mathbb{R}_{+}
$$

with initial condition $\mathcal{U}_{\alpha}(x, 0)=\delta(x)$ and $\mathcal{U}_{\beta}$ is the solution of the space-fractional diffusion equation

$$
\begin{equation*}
\left(\frac{\partial}{\partial t}-\frac{\partial^{\beta}}{\partial x^{\beta}}\right) \mathcal{U}_{\beta}(x, t)=0, \quad x \in \mathbb{R}_{+}, t>0, \beta \in(1,2) \tag{3.21}
\end{equation*}
$$

Proof. The proof follows the same arguments of Theorem 3.1. To begin with, we take the Fourier transform of equation (3.20): by using (2.8), we obtain

$$
\left(\frac{\partial}{\partial t}+\left(\sum_{l=1}^{d}\left(\mathbf{u} \cdot \boldsymbol{\theta}_{l}\right)\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\right)\right) \widehat{\rho_{\alpha, \beta}}(\mathbf{k}, t)=\left(\sum_{l=1}^{d}\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\beta}\right) \widehat{\rho_{\alpha, \beta}}(\mathbf{k}, t)
$$

and by integration we find

$$
\begin{align*}
\widehat{\rho_{\alpha, \beta}}(\mathbf{k}, t) & =\exp \left(-t \sum_{l=1}^{d}\left(\mathbf{u} \cdot \boldsymbol{\theta}_{l}\right)\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\right) \exp \left(t \sum_{l=1}^{d}\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\beta}\right)  \tag{3.22}\\
& =\prod_{l=1}^{d} \exp \left(-t\left(\mathbf{u} \cdot \boldsymbol{\theta}_{l}\right)\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\right) \exp \left(t\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\beta}\right)
\end{align*}
$$

On the other hand, if we take the Fourier transform of equation (3.21), we obtain

$$
\left(\frac{\partial}{\partial t}-(-i \gamma)^{\beta}\right) \widehat{\mathcal{U}_{\beta}}(\gamma, t)=0, \quad \beta \in(1,2)
$$

then, integrating, we obtain

$$
\widehat{\mathcal{U}_{\beta}}(\gamma, t)=\exp \left(t(-i \gamma)^{\beta}\right)
$$

Thus, we can rearrange (3.20) in the following way

$$
\begin{aligned}
\widehat{\rho}_{\alpha, \beta}(\mathbf{k}, t) & =\prod_{l=1}^{d}\left(\left.\widehat{\mathcal{U}_{\alpha}}\left(\gamma_{l}, \lambda_{l} t\right)\right|_{\gamma_{l}=\mathbf{k} \cdot \boldsymbol{\theta}_{l}, \lambda_{l}=\mathbf{u} \cdot \boldsymbol{\theta}_{l}}\right)\left(\left.\widehat{\mathcal{U}_{\beta}}\left(\gamma_{l}, t\right)\right|_{\gamma_{l}=\mathbf{k} \cdot \boldsymbol{\theta}_{l}}\right) \\
& =\prod_{l=1}^{d} \exp \left(-t\left(\mathbf{u} \cdot \boldsymbol{\theta}_{l}\right)\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\right) \exp \left(t\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\beta}\right)
\end{aligned}
$$

Finally, from the convolution theorem, we conclude the proof.
For the reader's convenience, we recall that the explicit form of the fundamental solution of the Riemann-Liouville space-fractional equation (3.21) can be found for example in [16]. It is also possible to give an explicit form to the solution of (3.20) in terms of one-sided stable probability density function.

We also notice that in (3.19) we have considered two different order $\alpha \neq \beta$, respectively for the advection and dispersion term. Indeed, from a physical point of view the two orders $\alpha$ and $\beta$ can be different, although they are certainly related. The parameter $\alpha$ was introduced from the fractional conservation of mass, hence it depends by the geometry of the porous medium. The parameter $\beta$ takes into account nonlocal effects in the Fick's law. Both of them are physically related to the heterogeneity of the porous medium; an explicit relation between them must be object of further investigations.

Remark 3.5. The stochastic solution to (3.20) is given by the sum of a random vector whose components are given by different linear combination of $d$ independent $\alpha$-stable subordinators ( $Z_{t}$ in Theorem 3.2) and a multivariable $\alpha$-stable random vector with discrete spectral measure. This second term corresponds to the unique case in which an $\alpha$-stable random vector has independent components (see [26]). The proof is a direct consequence of theorems 2.1 and 3.2.

## 4 Fractional power of operators and fractional shift operator

In order to highlight the applications of the fractional gradient, we recall some general results about fractional power of operators. The final aim is to find an operational rule for a shift operator involving fractional gradients, in analogy with the exponential shift operator. A power $\alpha$ of a closed linear operator $\mathcal{A}$ can be represented by means of the Dunford integral [15]

$$
\begin{equation*}
\mathcal{A}^{\alpha}=\frac{1}{2 \pi i} \int_{\Gamma} d \lambda \lambda^{\alpha}(\lambda-\mathcal{A})^{-1}, \quad \Re\{\alpha\}>0 \tag{4.1}
\end{equation*}
$$

under the conditions

> (i) $\lambda \in \rho(\mathcal{A})$ (the resolvent set of $\mathcal{A})$ for all $\lambda>0$
> (ii) $\left\|\lambda(\lambda I+\mathcal{A})^{-1}\right\|<M<\infty$ for all $\lambda>0$
where $\Gamma$ encircles the spectrum $\sigma(\mathcal{A})$ counterclockwise avoiding the negative real axis and $\lambda^{\alpha}$ takes the principal branch. For $\Re\{\alpha\} \in(0,1)$, the integral (4.1) can be rewritten in the Bochner sense as follows

$$
\begin{equation*}
\mathcal{A}^{\alpha}=\frac{\sin \pi \alpha}{\pi} \int_{0}^{\infty} d \lambda \lambda^{\alpha-1}(\lambda+\mathcal{A})^{-1} \mathcal{A} \tag{4.2}
\end{equation*}
$$

By inserting (Hille-Yosida theorem)

$$
(\lambda+\mathcal{A})^{-1}=\int_{0}^{\infty} d t e^{-\lambda t} e^{-t \mathcal{A}}
$$

into (4.2) we get that

$$
\int_{0}^{\infty} d \lambda \lambda^{\alpha-1}(\lambda+\mathcal{A})^{-1}=\left(\int_{0}^{\infty} s^{-\alpha} e^{-s} d s\right)\left(\int_{0}^{\infty} d s s^{\alpha-1} e^{-s \mathcal{A}}\right)
$$

where

$$
\int_{0}^{\infty} s^{-\alpha} e^{-s} d s=\Gamma(1-\alpha), \quad \alpha \in(0,1)
$$

and

$$
\frac{1}{\Gamma(\alpha)} \int_{0}^{\infty} d s s^{\alpha-1} e^{-s \mathcal{A}}=\mathcal{A}^{\alpha-1}
$$

which holds only if $0<\alpha<1$. The representation (4.2) can be therefore rewritten as

$$
\mathcal{A}^{\alpha}=\mathcal{A}^{\alpha-1} \mathcal{A}, \quad \alpha \in(0,1) .
$$

and, for $\alpha \in(0,1)$, we get that

$$
\mathcal{A}^{\alpha}=\mathcal{A} \mathcal{A}^{\alpha-1}=\mathcal{A}\left[\frac{1}{\Gamma(1-\alpha)} \int_{0}^{\infty} d s s^{-\alpha} e^{-s \mathcal{A}}\right] .
$$

On the other hand we can write the fractional power of the operator $\mathcal{A}$ as follows

$$
\mathcal{A}^{\alpha}=\mathcal{A}^{n} \mathcal{A}^{\alpha-n}, \quad n-1<\alpha<n, n \in \mathbb{N}
$$

and therefore, we can immediately recover the Riemann-Liouville fractional derivative of order $\alpha \in(0,1)$ as a fractional power of the ordinary first derivative $\mathcal{A}=\partial_{x}$ (see for example [25]). We also remark that, given the operator $\mathcal{A}$ as before, the strong solution to the space fractional equation

$$
\left(\frac{\partial}{\partial t}+\mathcal{A}^{\alpha}\right) u(x, t)=0
$$

subject to a good initial condition $u(x, 0)=u_{0}(x)$, can be represented as the convolution

$$
\begin{equation*}
u(x, t)=e^{-t \mathcal{A}^{\alpha}} u_{0}(x)=\mathbb{E} e^{-\mathfrak{H}_{t}^{\alpha} \mathcal{A}} u_{0}(x) \tag{4.3}
\end{equation*}
$$

in the sense that

$$
\lim _{t \rightarrow 0}\left\|\frac{e^{-t \mathcal{A}^{\alpha}} u-u}{t}-\mathcal{A}^{\alpha} u\right\|_{L^{p}(\mu)}=0
$$

for some $p \geq 1$, with a Radon measure $\mu$. In (4.3), we recall that $\mathfrak{H}_{t}^{\alpha}$, with $t>0$, is the $\alpha$-stable subordinator and

$$
\begin{equation*}
\mathrm{E} e^{-\mathfrak{H}_{t}^{\alpha} \mathcal{A}}=\int_{0}^{\infty} d s h_{\alpha}(s, t) e^{-s \mathcal{A}} \tag{4.4}
\end{equation*}
$$

where $h_{\alpha}$ is the density law of the stable subordinator. For $\alpha=1$, we obtain the solution

$$
u(x, t)=e^{-t \mathcal{A}} u_{0}(x)
$$

from the fact that, we formally have that

$$
\lim _{\alpha \rightarrow 1} h_{\alpha}(x, s)=\delta(x-s)
$$

Indeed, for $\alpha \rightarrow 1$, we get that $\mathfrak{H}_{t}^{\alpha} \xrightarrow{\text { a.s. }} t$ which is the elementary subordinator ([4]). Equation (4.3) appears of interest in relation to operatorial methods in quantum mechanics and, generally to solve differential equations. Actually, we recall the notion of exponential shift operator. It is well known that

$$
e^{\theta \partial_{x}} f(x)=f(x+\theta), \theta \in \mathbb{R}
$$

for $f(x) \in C_{b}(0,+\infty)$, that is the space of continuous bounded functions (see [12]). This operational rule comes directly from the Taylor expansion of the analytic function $f(x)$ near $x$. It provides a clear physical meaning to this operator as a generator of translations in quantum mechanics.

In a recent paper, Miskinis [21] discusses the properties of the generalized onedimensional quantum operator of the momentum in the framework of the fractional quantum mechanics. This is a relevant topic because of the role of the momentum operator as a generator of translation. In its analysis he suggested the following definition of the generealized momentum

$$
\begin{equation*}
\hat{p}=C \frac{\partial^{\alpha}}{\partial x^{\alpha}}, \alpha \in(0,1) \tag{4.5}
\end{equation*}
$$

with $C$ a complex coefficient, such that, if $\alpha=1$ then we have the classical quantum operator $\hat{p}=-i \hbar \partial_{x}$. In the same way, under the previous analysis we can introduce a fractional shift operator as

$$
\begin{equation*}
e^{-\theta \partial_{x}^{\alpha}} f(x)=\int_{0}^{\infty} d s h_{\alpha}(s, \theta) e^{-s \partial_{x}} f(x)=\int_{0}^{\infty} d s h_{\alpha}(s, \theta) f(x-s), \quad \theta>0 \tag{4.6}
\end{equation*}
$$

This fractional operator does not give a pure translation, it is a convolution of the initial condition with the density law of the stable subordinator, stressing again the possible role of this stochastic analysis in the framework of the fractional quantum mechanics. However, in the special case $\alpha=1$, it gives again the classical shift operator. This operational rule has a direct interpretation in relation to the definition of a generalized quantum operator, similar to that of (4.5). This stochastic view of the generator of translations can be, in our view, a good starting point for further investigations. Moreover, we can generalize these considerations to multidimensional fractional operators and give the operational solution of a general class of fractional equations as follows
Proposition 4.1. Consider the multidimensional fractional advection equation

$$
\left(\frac{\partial}{\partial t}+\sum_{i=1}^{d} \frac{\partial^{\alpha}}{\partial x_{i}^{\alpha}}\right) \rho_{\alpha}(\mathbf{x}, t)=0, \alpha \in(0,1), \mathbf{x} \in \mathbb{R}_{+}^{d}, t>0
$$

subject to the initial and boundary conditions

$$
\rho_{\alpha}(\mathbf{x}, 0)=\prod_{i=1}^{d} \rho_{0}\left(x_{i}\right), \quad \rho_{\alpha}(\mathbf{0}, t)=0
$$

Then, its analytic solution is given by

$$
\rho_{\alpha}(\mathbf{x}, t)=e^{-t \sum_{i=1}^{d} \partial_{x_{i}}^{\alpha}} \rho_{\alpha}(\mathbf{x}, 0)
$$

Proof. We can write

$$
\begin{aligned}
\rho_{\alpha}(\mathbf{x}, t) & =e^{-t \sum_{i=1}^{d} \partial_{x}^{\alpha}} \rho_{0}(\mathbf{x}, 0) \\
& =\prod_{i=1}^{d} e^{-t \partial_{x_{i}}^{\alpha}} \rho_{0}\left(x_{i}, 0\right)
\end{aligned}
$$

Hence, by direct application of (4.6) we have

$$
\begin{aligned}
\rho_{\alpha}(\mathbf{x}, t) & =\prod_{i=1}^{d} \int_{0}^{\infty} d s h_{\alpha}(s, t) \rho_{0}\left(x_{i}-s\right) \\
& =\int_{0}^{\infty} d s h_{\alpha}(s, t) \rho_{0}(\mathbf{x}-s)
\end{aligned}
$$

Thus, we conclude that

$$
\rho_{\alpha}(\mathbf{x}, t)=\int_{0}^{\infty} d s h_{\alpha}(s, t) \rho_{0}(\mathbf{x}-s)=e^{-t \sum_{i=1}^{d} \partial_{x_{i}}^{\alpha}} \rho_{\alpha}(\mathbf{x}, 0)
$$

as claimed.
Let us recall definition and main properties of the compound Poisson process. Consider a sequence of independent $\mathbb{R}^{n}$-valued random variables $Y_{i}, i \in \mathbb{N}$, with identical law $\nu(\cdot)$. Let $\left(N_{t}\right)_{t \geq 0}$ be a Poisson process with intensity $\lambda>0$. The compound Poisson process is the Lévy process

$$
X_{t}=\sum_{i=1}^{N(t)} \tau\left(Y_{i}\right)
$$

with infinitesimal generator (see for example [13], pag.131)

$$
(\mathcal{A} f)(x)=\int_{\mathbb{R}^{n}}(f(x+\tau(y))-f(x)) \nu(d y)
$$

We state the following result about the stochastic processes driven by equations involving the fractional gradient (2.7).

## Multidimensional fractional advection-dispersion equations

Theorem 4.2. Let us consider the random vector $\left(\boldsymbol{Z}_{t}\right)_{t \geq 0}$ in $\mathbb{R}^{d}$, given by

$$
\begin{equation*}
\boldsymbol{Z}_{t}=\sum_{j=1}^{d} \boldsymbol{\theta}_{j} \mathfrak{H}_{j}^{\alpha}\left(X_{t}\right) \tag{4.7}
\end{equation*}
$$

where $\mathfrak{H}_{j}^{\alpha}$ are independent $\alpha$-stable subordinators, with $\alpha \in(0,1)$ and $\left(X_{t}\right)_{t \geq 0}$ is an independent compound Poisson process

$$
X_{t}=\sum_{i=1}^{N(t)} \tau\left(Y_{i}\right)
$$

with $\tau: \mathbb{R}^{d} \mapsto \mathbb{R}_{+}$. The infinitesimal generator of the process (4.7) is given by

$$
(\mathcal{A} f)(\mathbf{x})=\sum_{j=1}^{d} \int_{\mathbb{R}^{d}}\left[\left(e^{-\tau(\mathbf{y})\left(\boldsymbol{\theta}_{j} \cdot \nabla\right)^{\alpha}}-1\right) f(\mathbf{x})\right] \nu(d \mathbf{y}) .
$$

Moreover assuming that $\boldsymbol{\theta}_{j} \equiv \mathbf{e}_{j}, \forall j \in \mathbb{N}$ and

$$
f(\mathbf{x})=\prod_{i=0}^{d} g_{i}\left(x_{i}\right)
$$

where $g_{i}\left(x_{i}\right)$ are analytic functions, we find

$$
\begin{equation*}
(\mathcal{A} f)(\mathbf{x})=\sum_{j=1}^{d} \int_{\mathbb{R}^{d}}\left\{\left[\int_{0}^{+\infty} d s h_{\alpha}(s, \tau(\mathbf{y})) g_{j}\left(x_{j}-s\right)\right]-g_{j}\left(x_{j}\right)\right\} \nu(d \mathbf{y}) \tag{4.8}
\end{equation*}
$$

where $h_{\alpha}$ is the density law of a stable subordinator.
Proof. The characteristic function of the random vector (4.7) is

$$
\begin{aligned}
\mathbb{E} e^{i \mathbf{k} \cdot \boldsymbol{Z}_{t}} & =\mathbb{E} \exp \left(i \sum_{j=1}^{d} \mathbf{k} \cdot \boldsymbol{\theta}_{j} \mathfrak{H}_{j}^{\alpha}\left(X_{t}\right)\right) \\
& =\prod_{j=1}^{d} \mathbb{E} \exp \left(i \mathbf{k} \cdot \boldsymbol{\theta}_{j} \mathfrak{H}_{j}^{\alpha}\left(X_{t}\right)\right) \\
& =\prod_{j=1}^{d} \mathbb{E} \exp \left(-X_{t}\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{j}\right)^{\alpha}\right) \\
& =\prod_{j=1}^{d} \exp \left(-\lambda t\left(1-\mathbb{E} e^{-\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{j}\right)^{\alpha} \tau(Y)}\right)\right) .
\end{aligned}
$$

Then, by differentiation, we can find the Fourier multiplier

$$
\begin{aligned}
\Phi(\mathbf{k}) & =\left[\partial_{t} \mathbb{E} e^{i \mathbf{k} \cdot \boldsymbol{Z}_{t}}\right]_{t=0} \\
& =\lambda \sum_{j=1}^{d} \int_{\mathbb{R}^{d}}\left(e^{-\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{j}\right)^{\alpha} \tau(\mathbf{y})}-1\right) \nu(d \mathbf{y}),
\end{aligned}
$$

of the generator $\mathcal{A}$, where $\nu(\cdot)$ is the law of the jumps of the compound Poisson process. Finally, by inverse Fourier transform we have

$$
(\mathcal{A} f)(\mathbf{x})=\sum_{j=1}^{d} \int_{\mathbb{R}^{d}}\left[\left(e^{-\tau(\mathbf{y})\left(\boldsymbol{\theta}_{j} \cdot \nabla\right)^{\alpha}}-1\right) f(\mathbf{x})\right] \nu(d \mathbf{y}) .
$$

In order to prove (4.8), we notice that

$$
e^{-t \partial_{x}^{\alpha}} f(x)=\mathbb{E} e^{-\mathfrak{H}_{t}^{\alpha} \partial_{x}} f(x)
$$

where

$$
\mathbb{E} e^{-\mathfrak{H}_{t}^{\alpha} \partial_{x}}=\int_{0}^{+\infty} d s h_{\alpha}(s, t) e^{-s \partial_{x}}
$$

and $h_{\alpha}$ is the density law of the stable subordinator. Recalling that, given an analytic function, the exponential operator acts as a shift operator, i.e.

$$
e^{-t \partial_{x}} f(x)=f(x-t)
$$

we find that

$$
e^{-\tau(\mathbf{y}) \partial_{x_{i}}^{\alpha}} f\left(x_{i}\right)=\int_{0}^{+\infty} d s h_{\alpha}(s, \tau(\mathbf{y})) f\left(x_{i}-s\right) d s
$$

Hence, assuming that

$$
f(\mathbf{x})=\prod_{k=1}^{d} g_{i}\left(x_{i}\right)
$$

in the case $\boldsymbol{\theta}_{j} \equiv \mathbf{e}_{j}, \forall j \in \mathbb{N}$, we conclude that

$$
(\mathcal{A} f)(\mathbf{x})=\sum_{j=1}^{d} \int_{\mathbb{R}^{d}}\left\{\left[\int_{0}^{+\infty} d s h_{\alpha}(s, \tau(\mathbf{y})) g_{j}\left(x_{j}-s\right)\right]-g_{j}\left(x_{j}\right)\right\} \nu(d \mathbf{y})
$$

## 5 Lévy-Khinchine formula with fractional gradient

In this section we discuss some results about Markov processes related to the above definition of fractional gradient. We present a new version of the Lévy-Khinchine formula involving fractional operators and we discuss some possible applications. It is well known that the Lévy-Khinchine formula provides a representation of characteristic functions of infinitely divisible distributions. Let us recall that, given a one-dimensional Lévy process $\left(X_{t}\right)_{t \geq 0}$, we have

$$
\mathbb{E} e^{i k X_{t}}=e^{\Phi(k) t}
$$

with characteristic exponent given by

$$
\Phi(k)=i k b-\frac{k^{2} c}{2}+\int_{\mathbb{R}}\left(e^{i k x}-1-(i k x) \chi_{\{|x|<1\}}\right) \nu(d x)
$$

where $b \in \mathbb{R}$ is the drift term, $c \in \mathbb{R}$ is the diffusion term and $\nu(\cdot)$ is a Lévy measure.
In the following we will consider the case $b=c=0$. In this case the infinitesimal generator of $\left(X_{t}\right)_{t \geq 0}$, is given by

$$
\begin{equation*}
(\mathcal{A} f)(x)=\frac{1}{(2 \pi)} \int_{\mathbb{R}} e^{-i k x} \Phi(k) \widehat{f}(k) d k=\int_{\mathbb{R}}\left(f(x+y)-f(x)-y \partial_{x} f(x) \chi_{\{|y|<1\}}\right) \nu(d y) \tag{5.1}
\end{equation*}
$$

Hereafter the symbols "~" or " ${ }^{d}$ " stand for equality in law or equality in distribution.
Let us consider the random vector $\left(\boldsymbol{Z}_{t}\right)_{t \geq 0}$ in $\mathbb{R}^{d}$, given by

$$
\begin{equation*}
\boldsymbol{Z}_{t}=\sum_{j=1}^{N(t)} \mathbf{Y}_{j}-\sum_{l=1}^{d} \boldsymbol{\theta}_{l}\left(\boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{Y}\right)^{1 / \alpha} \mathfrak{H}_{l}^{\alpha}(\lambda t) \chi_{\mathcal{D}}(\mathbf{Y}) \tag{5.2}
\end{equation*}
$$

where

$$
\mathcal{D}=\left\{\mathbf{Y} \in \mathbb{R}^{d}: \mathbb{E}\left(\boldsymbol{\theta}_{l} \cdot \mathbf{Y}\right)>0, l=1, \cdots, d\right\}
$$

$\mathfrak{H}_{l}^{\alpha}$ are i.i.d $\alpha$-stable subordinators, with $\alpha \in(0,1)$, and $\mathbf{Y}_{j}$ are $d$-dimensional i.i.d. random vectors such that $\mathbf{Y}_{j} \sim \mathbf{Y}$, for all $j \in \mathbb{N}$ and $P(\mathbf{Y} \in A)=\int_{A} \nu(d \mathbf{y})$, as before. We recall that $\left(N_{t}\right)_{t \geq 0}$ in (5.2) is a Poisson process with intensity $\lambda>0$. We also observe that the following equality in distribution holds

$$
\boldsymbol{Z}_{t} \stackrel{d}{=} \sum_{j=1}^{N(t)} \mathbf{Y}_{j}-\sum_{l=1}^{d} \boldsymbol{\theta}_{l}\left(\boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{Y}_{j}\right)^{1 / \alpha} \mathfrak{H}_{l}^{\alpha}(\lambda t) \chi_{\mathcal{D}}\left(\mathbf{Y}_{j}\right)
$$

We are now ready to state the following
Theorem 5.1. The infinitesimal generator of the process (5.2) is given by

$$
\begin{equation*}
\left(\mathcal{L}^{\theta} f\right)(\mathbf{x})=\int_{\mathbb{R}^{d}}\left[\left(f(\mathbf{x}+\mathbf{y})-f(\mathbf{x})-\mathbf{y} \cdot \nabla_{\theta}^{\alpha} f(\mathbf{x}) \chi_{D(\boldsymbol{\theta})}(\mathbf{y})\right] \nu(d \mathbf{y})\right. \tag{5.3}
\end{equation*}
$$

where $\nabla_{\theta}^{\alpha}$ is the fractional gradient in the sense of equation (2.7), and

$$
D(\boldsymbol{\theta})=\bigcap_{l=1}^{d}\left\{\mathbf{y} \in \mathbb{R}^{d}: \boldsymbol{\theta}_{l} \cdot \mathbf{y} \geq 0\right\}
$$

Proof. We consider the characteristic function of the random vector (5.2)

$$
\begin{equation*}
\mathbb{E} e^{i \mathbf{k} \cdot \boldsymbol{Z}_{t}}=\mathbb{E} \exp \left(i \sum_{j=1}^{N(t)} \mathbf{Y}_{j} \cdot \mathbf{k}\right) \mathbb{E} \exp \left(i \sum_{l=1}^{d}\left(\boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{Y}\right)^{1 / \alpha} \mathfrak{H}_{l}^{\alpha}(\lambda t)\left(\mathbf{k} \cdot \boldsymbol{\theta}_{l}\right) \chi_{\mathcal{D}}(\mathbf{Y})\right) \tag{5.4}
\end{equation*}
$$

The first term can be written as follows

$$
\mathbb{E} \exp \left(i \sum_{j=1}^{N(t)} \mathbf{Y}_{j} \cdot \mathbf{k}\right)=\mathbb{E}\left(\mathbb{E} e^{i \sum_{j=1}^{N(t)} \mathbf{Y}_{j} \cdot \mathbf{k}}\right)
$$

and, from the fact that $\mathbf{Y}_{\mathbf{j}} \sim \mathbf{Y}$, we have

$$
\begin{align*}
\mathbb{E}\left(\mathbb{E} e^{i \sum_{j=1}^{n} \mathbf{Y}_{j} \cdot \mathbf{k}} \mid N(t)=n\right) & =\mathbb{E}\left(\left(\mathbb{E} e^{i \mathbf{Y} \cdot \mathbf{k}}\right)^{n} \mid N(t)=n\right)  \tag{5.5}\\
& =\sum_{n=0}^{\infty}\left[\mathbb{E} e^{i \mathbf{Y} \cdot \mathbf{k}}\right]^{n} \operatorname{Pr}\{N(t)=n\} \\
& =\sum_{n=0}^{\infty}\left[\mathbb{E} e^{i \mathbf{Y} \cdot \mathbf{k}}\right]^{n} \frac{(\lambda t)^{n}}{n!} e^{-\lambda t} \\
& =e^{-\lambda t\left(1-\mathbb{E} e^{i \mathbf{Y} \cdot \mathbf{k}}\right)}
\end{align*}
$$

Regarding the second term in (5.4), we notice that

$$
\left(\boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{Y}\right)^{1 / \alpha} \mathfrak{H}_{l}^{\alpha}(\lambda t) \chi_{\mathcal{D}}(\mathbf{Y}) \stackrel{d}{=} \mathfrak{H}_{l}^{\alpha}\left(\left(\boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{Y}\right) \lambda t\right) \chi_{\mathcal{D}}(\mathbf{Y})
$$

From the fact that $\mathfrak{H}_{l}^{\alpha}$ are i.i.d $\alpha$-stable subordinators, we obtain

$$
\begin{aligned}
\mathbb{E} \exp \left(i \sum_{l=1}^{d}\left(\boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{Y}\right)^{1 / \alpha} \mathfrak{H}_{l}^{\alpha}(\lambda t) \mathbf{k} \cdot \boldsymbol{\theta}_{l} \chi_{\mathcal{D}}(\mathbf{Y})\right) & =\prod_{l=1}^{d} \mathbb{E} \exp \left(i\left(\boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{Y}\right)^{1 / \alpha} \mathfrak{H}_{l}^{\alpha}(\lambda t)\left(\mathbf{k} \cdot \boldsymbol{\theta}_{l}\right) \chi_{\mathcal{D}}(\mathbf{Y})\right) \\
& =\prod_{l=1}^{d} \exp \left(-\lambda t\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\left(\boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{Y}\right) \chi_{\mathcal{D}}(\mathbf{Y})\right)
\end{aligned}
$$

## Multidimensional fractional advection-dispersion equations

Finally, we get

$$
\mathbb{E} e^{i \mathbf{k} \cdot \boldsymbol{Z}_{t}}=\exp \left(\lambda t\left(\mathbb{E} e^{i \mathbf{k} \cdot \mathbf{Y}}-1-\sum_{l=1}^{d}\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\left(\boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{Y}\right) \chi_{\mathcal{D}}(\mathbf{Y})\right)\right)
$$

where the Fourier multiplier $-\Phi(\mathbf{k})$, of $\mathcal{L}^{\theta}$, is given by

$$
\begin{aligned}
\Phi(\mathbf{k}) & =\left[\partial_{t} \mathbb{E} e^{i \mathbf{k} \cdot \boldsymbol{Z}_{t}}\right]_{t=0} \\
& =\lambda\left(\mathbb{E} e^{i \mathbf{k} \cdot \mathbf{Y}}-1-\sum_{l=1}^{d}\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\left(\boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{Y}\right) \chi_{\mathcal{D}}(\mathbf{Y})\right) \\
& =\lambda \int_{\mathbb{R}^{d}}\left[e^{i \mathbf{k} \cdot \mathbf{y}}-1-\left(\sum_{l=1}^{d}\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\left(\boldsymbol{\theta}_{l} \cdot \mathbf{y}\right)\right) \chi_{D(\theta)}(\mathbf{y})\right] \nu(d \mathbf{y}) .
\end{aligned}
$$

We recall that $\nu(\cdot)$ is the law of $\mathbf{Y}$. Then, we can use equation (3.10) and, by inverse Fourier transform, we get

$$
\left(\mathcal{L}^{\theta} f\right)(\mathbf{x})=\int_{\mathbb{R}^{d}}\left[(f(\mathbf{x}+\mathbf{y})-f(\mathbf{x}))-\mathbf{y} \cdot \nabla_{\theta}^{\alpha} f(\mathbf{x}) \chi_{D(\theta)}(\mathbf{y})\right] \nu(d \mathbf{y}),
$$

which is the claim.
Remark 5.2. In the case $\boldsymbol{\theta}_{l} \equiv \mathbf{e}_{l}$, for all $l$,

$$
D(\boldsymbol{\theta})=\bigcap_{l=1}^{d}\left\{\mathbf{y} \in \mathbb{R}^{d}: \boldsymbol{e}_{l} \cdot \mathbf{y} \geq 0\right\} \equiv \mathbb{R}_{+}^{d}
$$

and (5.3) becomes

$$
\left(\mathcal{L}^{\theta} f\right)(\mathbf{x})=\int_{\mathbb{R}^{d}}\left[(f(\mathbf{x}+\mathbf{y})-f(\mathbf{x}))-\sum_{j=1}^{d} y_{j} \partial_{x_{j}}^{\alpha} f(\mathbf{x}) \chi_{\mathbb{R}^{+}}(\mathbf{y})\right] \nu(d \mathbf{y})
$$

Remark 5.3. We observe that in the special case $d=1, \alpha=1$, the process (5.2) becomes the compensated Poisson process

$$
Z_{t}=\sum_{j=1}^{N(t)} Y_{j}-\lambda t \mathbb{E} Y, \quad t>0
$$

In this case, the law of $\left(Z_{t}\right)_{t \geq 0}$ is given by

$$
P\left(Z_{t} \in d y\right) / d y=\sum_{n=0}^{\infty} f_{Y}^{* n}(y+\lambda t \mathbb{E} Y) e^{-\lambda t} \frac{(\lambda t)^{n}}{n!}
$$

where $f_{Y}$ is the law of the jumps $Y_{j} \sim Y$ and $f^{* n}$ is the $n$-convolution of $f_{Y}$. Straightforward calculations lead to the explicit representation of the law for $\alpha \neq 1$. Indeed, for $\alpha \in(0,1)$, we have that

$$
P\left(Z_{t} \in d y\right) / d y=\sum_{n=0}^{\infty} \mathbb{E} f_{Y}^{* n}\left(y+(\lambda \mathbb{E} Y)^{1 / \alpha} \mathfrak{H}_{t}^{\alpha}\right)
$$

Let us consider the random vector $\mathbf{W}$, whose components are independent folded Gaussian random variables with variance $r E_{\beta}$, where $r E_{\beta}$ is the inverse Gamma distribution, with probability density function given by

$$
P\left\{r E_{\beta} \in d s\right\} / d s=\frac{1}{\Gamma(\beta)}\left(\frac{s}{r}\right)^{-\beta-1} e^{-\frac{r}{s}}, \quad s \geq 0
$$

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where $r \geq 0$ is a scale parameter and $\beta>0$ a shape parameter. We observe that

$$
\begin{align*}
P\{\mathbf{W} \in d \mathbf{y}\} / d \mathbf{y} & =2^{d} \int_{0}^{\infty} \frac{e^{-\frac{|\mathbf{y}|^{2}}{4 s}}}{\sqrt{(4 \pi s)^{d}}} P\left\{r E_{\beta} \in d s\right\}  \tag{5.6}\\
& =\frac{2^{d} r^{\beta}}{\sqrt{(4 \pi)^{d}} \Gamma(\beta)} \int_{0}^{\infty} s^{-\beta-1-\frac{d}{2}} e^{-s^{-1}\left(\frac{|\mathbf{y}|^{2}}{4}+r\right)} d s \\
& =\frac{\Gamma\left(\beta+\frac{d}{2}\right)}{\Gamma(\beta)} \frac{2^{2(\beta+d)}}{\sqrt{(4 \pi)^{d}}} \frac{r^{\beta}}{\left(|\mathbf{y}|^{2}+4 r\right)^{\beta+\frac{d}{2}}}=m_{r}\left(|\mathbf{y}|^{2}\right)
\end{align*}
$$

Then we have that

$$
\begin{aligned}
\mathbb{E} W_{j} & =\frac{1}{\Gamma(\beta)} \frac{2 r^{\beta+1}}{\sqrt{4 \pi}} \int_{0}^{\infty} \int_{0}^{\infty} y s^{-\beta-\frac{3}{2}} e^{-s^{-1}\left(\frac{y^{2}}{4}+r\right)} d s d y \\
& =\frac{\Gamma\left(\beta-\frac{1}{2}\right)}{\Gamma(\beta)} \frac{2 r^{\frac{3}{2}}}{\sqrt{\pi}} .
\end{aligned}
$$

We assume that the random vectors $\mathbf{Y}_{j}$ appearing in (5.2) are taken such that

$$
\begin{equation*}
\mathbf{Y}_{j} \sim \epsilon_{j} \mathbf{W}_{j}, \quad j \in \mathbb{N} \tag{5.7}
\end{equation*}
$$

where $\epsilon_{j}$ is the Rademacher random variable, i.e. $P\left(\epsilon_{j}=+1\right)=p$ and $P\left(\epsilon_{j}=-1\right)=q$ and $\mathbf{W}_{j}$ are the i.i.d random vectors distributed like $\mathbf{W}$. It is worth to notice that, in this case, the set $\mathcal{D}$ is given by

$$
\mathcal{D}=\left\{(p-q)\left(\boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{W}\right)>0, l=1, \ldots, d\right\}
$$

where $\mathbb{E} \mathbf{W}$ is positive.
We are now able to state the following theorem.
Theorem 5.4. Let us consider the process (5.2) with jumps (5.7). For $p \neq q$ and $\beta \in(0,1 / 2)$, we have that

$$
\boldsymbol{Z}\left(t / r^{\beta}\right) \underset{r \rightarrow 0}{d} \boldsymbol{Q}(t)
$$

where $\boldsymbol{Q}(t), t \geq 0$, has generator

$$
\begin{align*}
\left(\mathcal{L}_{p, q}^{\theta} f\right)(\mathbf{x}) & =C_{d}(\beta) \int_{\mathbb{R}^{d}}\left[\left(p f(\mathbf{x}+\mathbf{y})+q f(\mathbf{x}-\mathbf{y})-f(\mathbf{x})-(p-q) \mathbf{y} \cdot \nabla_{\theta}^{\alpha} f(\mathbf{x}) \chi_{D(\boldsymbol{\theta})}(\mathbf{y})\right] \frac{d \mathbf{y}}{|\mathbf{y}|^{2 \beta+d}}\right.  \tag{5.8}\\
& =C_{d}(\beta) p \int_{\mathbb{R}^{d}}\left[\left(f(\mathbf{x}+\mathbf{y})-f(\mathbf{x})-\mathbf{y} \cdot \nabla_{\theta}^{\alpha} f(\mathbf{x}) \chi_{D(\boldsymbol{\theta})}(\mathbf{y})\right] \frac{d \mathbf{y}}{|\mathbf{y}|^{2 \beta+d}}\right.  \tag{5.9}\\
& +C_{d}(\beta) q \int_{\mathbb{R}^{d}}\left[\left(f(\mathbf{x}-\mathbf{y})-f(\mathbf{x})+\mathbf{y} \cdot \nabla_{\theta}^{\alpha} f(\mathbf{x}) \chi_{D(\boldsymbol{\theta})}(\mathbf{y})\right] \frac{d \mathbf{y}}{|\mathbf{y}|^{2 \beta+d}}\right. \tag{5.10}
\end{align*}
$$

with $p, q \geq 0$ such that $p+q=1$.
Proof. Under the assumption that $\mathbf{Y}_{j} \sim \epsilon_{j} \mathbf{W}_{j}$ in (5.2) we have that

$$
\mathbb{E} \mathbf{Y}=p \mathbb{E} \mathbf{W}-q \mathbb{E} \mathbf{W}=(p-q) \mathbb{E} \mathbf{W}
$$

Hence, we have

$$
\mathbf{Z}_{t}=\sum_{j=1}^{N(t)} \epsilon_{j} \mathbf{W}_{j}-\sum_{l=1}^{d} \boldsymbol{\theta}_{l}\left((p-q) \boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{W}\right)^{1 / \alpha} \mathfrak{H}_{l}^{\alpha}(\lambda t) \chi_{\mathcal{D}}(\epsilon \mathbf{W})
$$

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Its characteristic function is given by
$\mathbb{E} e^{i \mathbf{k} \cdot \boldsymbol{Z}_{t}}=\mathbb{E} \exp \left(i \sum_{j=1}^{N(t)} \epsilon_{j} \mathbf{W}_{j} \cdot \mathbf{k}\right) \mathbb{E} \exp \left(i \sum_{l=1}^{d}\left((p-q) \boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{W}\right)^{1 / \alpha} \mathfrak{H}_{l}^{\alpha}(\lambda t) \mathbf{k} \cdot \boldsymbol{\theta}_{l} \chi_{\mathcal{D}}(\epsilon \mathbf{W})\right)$.
The first operand in (5.11) can be written as follows

$$
\begin{aligned}
\mathbb{E} \exp \left(i \sum_{j=1}^{N(t)} \epsilon_{j} \mathbf{W}_{j} \cdot \mathbf{k}\right) & =\mathbb{E}\left(\mathbb{E} e^{i \sum_{j=1}^{n} \epsilon_{j} \mathbf{Y}_{j} \cdot \mathbf{k}} \mid N(t)=n\right)=e^{-\lambda t\left(1-\mathbb{E} e^{i \epsilon \boldsymbol{Y} \cdot \mathbf{k}}\right)} \\
& =e^{-\lambda t\left((p+q)-p \mathbb{E} e^{i \boldsymbol{Y} \cdot \mathbf{k}}-q \mathbb{E} e^{-i \boldsymbol{Y} \cdot \mathbf{k}}\right)}
\end{aligned}
$$

The second term in (5.11), being $\mathfrak{H}_{l}^{\alpha}$ i.i.d $\alpha$-stable subordinators, is given by

$$
\begin{aligned}
& \mathbb{E} \exp \left(i \sum_{l=1}^{d}\left((p-q) \boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{W}\right)^{1 / \alpha} \mathfrak{H}_{l}^{\alpha}(\lambda t)\left(\mathbf{k} \cdot \boldsymbol{\theta}_{l}\right) \chi_{\mathcal{D}}(\epsilon \mathbf{W})\right) \\
& =\prod_{l=1}^{d} \mathbb{E} \exp \left(i\left((p-q) \boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{W}\right)^{1 / \alpha} \mathfrak{H}_{l}^{\alpha}(\lambda t) \mathbf{k} \cdot \boldsymbol{\theta}_{l} \chi_{\mathcal{D}}(\epsilon \mathbf{W})\right) \\
& =\prod_{l=1}^{d} \exp \left(-\lambda t\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\left((p-q) \boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{W}\right) \chi_{\mathcal{D}}(\epsilon \mathbf{W})\right) .
\end{aligned}
$$

Finally, we have that

$$
\begin{aligned}
\mathbb{E} e^{i \mathbf{k} \cdot \boldsymbol{Z}_{t}} & =\exp \left(\lambda t\left(p \mathbb{E} e^{i \mathbf{k} \cdot \mathbf{Y}}+q \mathbb{E} e^{-i \mathbf{k} \cdot \mathbf{Y}}-1\right)-\sum_{l=1}^{d}\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\left((p-q) \boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{W}\right) \chi_{\mathcal{D}}(\epsilon \mathbf{W})\right) \\
& =e^{t \Phi_{r}(\mathbf{k})}
\end{aligned}
$$

where

$$
\Phi_{r}(\mathbf{k})=\lambda \int_{\mathbb{R}^{d}}\left[p e^{i \mathbf{k} \cdot \mathbf{y}}+q e^{-i \mathbf{k} \cdot \mathbf{y}}-1-(p-q) \sum_{l=1}^{d}\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\left(\boldsymbol{\theta}_{l} \cdot \mathbf{y}\right) \chi_{D(\theta)}(\mathbf{y})\right] m_{r}\left(|\mathbf{y}|^{2}\right) d \mathbf{y}
$$

with $m_{r}(\cdot)$ given by equation (5.6).
We now consider the process $\boldsymbol{Z}\left(t / r^{\beta}\right)$, whose characteristic function is given by

$$
\mathbb{E} e^{i \mathbf{k} \cdot \boldsymbol{Z}\left(t / r^{\beta}\right)}=\exp \left(\frac{t}{r^{\beta}} \Phi_{r}(\mathbf{k})\right) .
$$

Then, we get the Fourier symbol

$$
\begin{aligned}
& {\left[\partial_{t} \mathbb{E} e^{i \mathbf{k} \cdot \boldsymbol{Z}\left(t / r^{\beta}\right)}\right]_{t=0}=\frac{1}{r^{\beta}} \Phi_{r}(\mathbf{k})} \\
& =\frac{\lambda}{r^{\beta}}\left(p \mathbb{E} e^{i \mathbf{k} \cdot \mathbf{Y}}+q \mathbb{E} e^{-i \mathbf{k} \cdot \mathbf{Y}}-1-\sum_{l=1}^{d}\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\left((p-q) \boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{Y} \chi_{\mathcal{D}}(\epsilon \mathbf{W})\right)\right. \\
& =C_{d}(\beta) \lambda \int_{\mathbb{R}^{d}}\left[p e^{i \mathbf{k} \cdot \mathbf{y}}+q e^{-i \mathbf{k} \cdot \mathbf{y}}-1-(p-q) \sum_{l=1}^{d}\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\left(\boldsymbol{\theta}_{l} \cdot \mathbf{y}\right) \chi_{D(\theta)}(\mathbf{y})\right] \frac{d \mathbf{y}}{\left(|\mathbf{y}|^{2}+4 r\right)^{\beta+\frac{d}{2}}},
\end{aligned}
$$

where

$$
C_{d}(\beta)=\frac{\Gamma\left(\beta+\frac{d}{2}\right)}{\Gamma(\beta)} \frac{2^{2(\beta+d)}}{\sqrt{(4 \pi)^{d}}} .
$$

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This implies that the process $\boldsymbol{Q}(t)$, obtained from

$$
\boldsymbol{Z}\left(t / r^{\beta}\right) \underset{r \rightarrow 0}{d} \boldsymbol{Q}(t),
$$

has a generator with Fourier multiplier

$$
\begin{equation*}
\frac{1}{r^{\beta}} \Phi_{r}(\mathbf{k}) \xrightarrow{r \rightarrow 0} \Phi(\mathbf{k}) \tag{5.12}
\end{equation*}
$$

where

$$
\Phi(\mathbf{k})=C_{d}(\beta) \lambda \int_{\mathbb{R}^{d}}\left[p e^{i \mathbf{k} \cdot \mathbf{y}}+q e^{-i \mathbf{k} \cdot \mathbf{y}}-1-(p-q) \sum_{l=1}^{d}\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{l}\right)^{\alpha}\left(\boldsymbol{\theta}_{l} \cdot \mathbf{y}\right) \chi_{D(\theta)}(\mathbf{y})\right] \frac{d \mathbf{y}}{|\mathbf{y}|^{2 \beta+d}}
$$

We conclude that the generator of the process $\boldsymbol{Q}(t)$ is given by the inverse Fourier transform of $\Phi$ in (5.12), i.e.
$\left(\mathcal{L}_{p, q}^{\theta} f\right)(\mathbf{x})=C_{d}(\beta) \int_{\mathbb{R}^{d}}\left[\left(p f(\mathbf{x}+\mathbf{y})+q f(\mathbf{x}-\mathbf{y})-f(\mathbf{x})-(p-q) \mathbf{y} \cdot \nabla_{\theta}^{\alpha} f(\mathbf{x}) \chi_{D(\boldsymbol{\theta})}(\mathbf{y})\right] \frac{d \mathbf{y}}{|\mathbf{y}|^{2 \beta+d}}\right.$,
as claimed.

We now study the convergence of the integral (5.13). By taking the multidimensional MacLaurin expansion of the integrand up to the second order term, we have

$$
\begin{align*}
& p f(\mathbf{x}+\mathbf{y})+q f(\mathbf{x}-\mathbf{y})-(p+q) f(\mathbf{x})-(p-q) \mathbf{y} \cdot \nabla_{\theta}^{\alpha} f(\mathbf{x}) \chi_{D(\boldsymbol{\theta})}(\mathbf{y})  \tag{5.14}\\
& \approx(p-q)\left[\mathbf{y} \cdot \nabla f(\mathbf{x})-\mathbf{y} \cdot \nabla_{\theta}^{\alpha} f(\mathbf{x}) \chi_{D(\boldsymbol{\theta})}(\mathbf{y})\right]+|\mathbf{y}|^{2} \Delta f(\mathbf{x}),
\end{align*}
$$

hence we obtain

$$
\begin{aligned}
& \frac{\left|p f(\mathbf{x}+\mathbf{y})+q f(\mathbf{x}-\mathbf{y})-(p+q) f(\mathbf{x})-(p-q) \mathbf{y} \cdot \nabla_{\theta}^{\alpha} f(\mathbf{x}) \chi_{D(\boldsymbol{\theta})}(\mathbf{y})\right|}{|\mathbf{y}|^{2 \beta+d}} \\
& \leq \frac{|P(|\mathbf{y}|)|\left\|D_{p, q}^{2, \alpha} f(\mathbf{x})\right\|_{\infty}}{|\mathbf{y}|^{2 \beta+d}},
\end{aligned}
$$

where $P(z)$ is a second order polynomial in the variable $z=|\mathbf{y}|$, arising from the MacLaurin expansion (5.14). We observe that

$$
\left|\nabla_{\theta}^{\beta} f\right| \leq \int_{\mathbb{R}^{d}}\left|\widehat{\nabla_{\theta}^{\beta} f}(\mathbf{x})\right| d \mathbf{x}
$$

and therefore, by definition (see (2.8)),

$$
\left|\nabla_{\theta}^{\beta} f\right|<+\infty
$$

Due to the first order term appearing in $|P(|\mathbf{y}|)|$, we have that

$$
\frac{|P(|\mathbf{y}|)|\left\|D_{p, q}^{2, \alpha} f\right\|_{\infty}}{|\mathbf{y}|^{2 \beta+d}} \leq \frac{\left\|D_{p, q}^{2, \alpha} f\right\|_{\infty}}{|\mathbf{y}|^{2 \beta+d-1}}
$$

which implies that (5.13) converges for $\beta \in(0,1 / 2)$. The same reasoning applies for the convergence of (5.9) and (5.10).

We notice that, considering jumps (5.7), the second term in (5.2) reduces to a sum of orthonormal vectors, whose components are given by independent stable subordinators, that is

$$
\sum_{l=1}^{d} \boldsymbol{\theta}_{l}\left((p-q) \boldsymbol{\theta}_{l} \cdot \mathbb{E} \mathbf{W}\right)^{1 / \alpha} \mathfrak{H}_{l}^{\alpha}(\lambda t) \chi_{\mathcal{D}}(\epsilon \mathbf{W})=r^{\frac{3}{2 \alpha}} \sum_{l=1}^{d} \boldsymbol{\theta}_{l} C_{l} \mathfrak{H}_{l}^{\alpha}(\lambda t) \chi_{\mathcal{D}}(\epsilon \mathbf{W})
$$

where

$$
C_{l}=\left((p-q) \frac{2 \Gamma\left(\beta-\frac{1}{2}\right)}{\sqrt{\pi} \Gamma(\beta)} \sum_{i=1}^{d} \theta_{l i}\right)^{1 / \alpha}
$$

Moreover, we observe that, by considering zero-mean jumps in (5.2), we obtain that (see for example [9])

$$
\boldsymbol{Z}_{t / r^{\beta}}=\sum_{j=1}^{N\left(t / r^{\beta}\right)} \mathbf{Y}_{j} \xrightarrow{d} \mathbf{S}_{t}^{2 \beta}, \quad \text { as } r \rightarrow 0,
$$

where $\left(\mathbf{S}_{t}\right)_{t \geq 0}$ is an isotropic vector of stable processes.
Remark 5.5. We recall that the fractional Laplacian is defined as follows

$$
\begin{aligned}
(-\Delta)^{\alpha} f(\mathbf{x}) & =C_{d}(\alpha) \text { p.v. } \int_{\mathbb{R}^{d}} \frac{f(\mathbf{x})-f(\mathbf{y})}{|\mathbf{x}-\mathbf{y}|^{2 \alpha+d}} d \mathbf{y} \\
& =\frac{C_{d}(\alpha)}{2} \int_{\mathbb{R}^{d}} \frac{f(\mathbf{x}+\mathbf{y})+f(\mathbf{x}-\mathbf{y})-2 f(\mathbf{x})}{|\mathbf{y}|^{2 \alpha+d}} d \mathbf{y}
\end{aligned}
$$

where $\alpha \in(0,1)$ and "p.v." stands for "principle value". Also, the fractional Laplacian is commonly defined in terms of its Fourier transform, i.e.

$$
\begin{equation*}
(-\Delta)^{\alpha} f(\mathbf{x})=\frac{1}{(2 \pi)^{d}} \int_{\mathbb{R}^{d}} e^{-i \mathbf{k} \cdot \mathbf{x}}|\mathbf{k}|^{2 \alpha} \widehat{f}(\mathbf{k}) d \mathbf{k} \tag{5.15}
\end{equation*}
$$

with domain given by the Sobolev space of $L^{2}$ functions for which (5.15) converges.
Formula (5.8), for $p=q=1 / 2$, takes the form

$$
\begin{equation*}
\left(\mathcal{L}_{1 / 2,1 / 2}^{\theta} f\right)(\mathbf{x})=\frac{C_{d}(\beta)}{2} \int_{\mathbb{R}^{d}}\left[(f(\mathbf{x}+\mathbf{y})+f(\mathbf{x}-\mathbf{y})-2 f(\mathbf{x})] \frac{d \mathbf{y}}{|\mathbf{y}|^{2 \beta+d}}=-(-\Delta)^{\beta} f(\mathbf{x})\right. \tag{5.16}
\end{equation*}
$$

which is independent from the direction $\boldsymbol{\theta}$. We observe that (5.16) converges for $\beta \in(0,1)$. This comes from the fact that the first order term in $P(|\mathbf{y}|)$ disappears and therefore

$$
\frac{|P(|\mathbf{y}|)|\left\|D_{p, q}^{2, \alpha} f\right\|_{\infty}}{|\mathbf{y}|^{2 \beta+d}} \leq \frac{\left\|D_{p, q}^{2, \alpha} f\right\|_{\infty}}{|\mathbf{y}|^{2 \beta+d-2}}
$$

Remark 5.6. We notice that formula (5.8) includes as special cases, completely positively or negatively skewed operators. Indeed, we have the specular cases

$$
\left\{\begin{array}{l}
\left(\mathcal{L}_{1,0}^{\theta} f\right)(\mathbf{x})=C_{d}(\beta) \int_{\mathbb{R}^{d}}\left[\left(f(\mathbf{x}+\mathbf{y})-f(\mathbf{x})-\mathbf{y} \cdot \nabla_{\theta}^{\alpha} f(\mathbf{x}) \chi_{D(\boldsymbol{\theta})}(\mathbf{y})\right] \frac{d \mathbf{y}}{|\mathbf{y}|^{2 \beta+d}},\right. \\
\left(\mathcal{L}_{0,1}^{\theta} f\right)(\mathbf{x})=C_{d}(\beta) \int_{\mathbb{R}^{d}}\left[\left(f(\mathbf{x}-\mathbf{y})-f(\mathbf{x})+\mathbf{y} \cdot \nabla_{\theta}^{\alpha} f(\mathbf{x}) \chi_{D(\boldsymbol{\theta})}(\mathbf{y})\right] \frac{d \mathbf{y}}{|\mathbf{y}|^{2 \beta+d}} .\right.
\end{array}\right.
$$

The first operator is the infinitesimal generator governing processes with only positive jumps, the second one with purely negative jumps.
Remark 5.7. It is well known that the generator of the subordinate process $\left(\mathbf{X}_{\mathfrak{H}_{t}^{\alpha}}\right)_{t>0}$ is given by

$$
-(-\mathcal{L})^{\alpha} f(\mathbf{x})=\frac{\alpha}{\Gamma(1-\alpha)} \int_{0}^{\infty}\left(P_{s} f(\mathbf{x})-f(\mathbf{x})\right) \frac{d s}{s^{\alpha+1}}
$$

where $P_{s}=e^{s \mathcal{L}}$ is the Feller semigroup of the Lévy process $\left(\mathbf{X}_{s}\right)_{s>0}$ (see for example [1]).

## 6 Frobenius-Perron operator and fractional equations

In this section we recall some results about transport equations involving FrobeniusPerron operator. Then we show some applications of this approach in the framework of differential equations involving fractional operators.

Given the measure space $(X, \mathcal{B}(X), \mu)$, the Frobenius-Perron operator $K: L^{1}(X) \rightarrow$ $L^{1}(X)$ corresponds to the non singular transformation $T: X \mapsto X$, satisfying the condition

$$
\int_{E} K f(x) d x=\int_{T^{-1}(E)} f(x) d x
$$

for every measurable set $E$ and $f \in L^{1}(X, \mathcal{B}(X), \mu)$.

Let us consider the transport equation

$$
\begin{equation*}
\frac{\partial u}{\partial t}=A u-\lambda(I-K) u \tag{6.1}
\end{equation*}
$$

where

$$
A u=-\sum_{k=1}^{n} \frac{\partial}{\partial x_{k}}(a(\mathbf{x}) u),
$$

and $K$ is the Frobenius-Perron operator associated with the map $T: x \mapsto x-\tau(x)$ (see for example [31]). This means that the term $\lambda(I-K) u$ appearing in (6.1) describes the jumps of the new process obtained by the process driven by $A$. Then, the stochastic solution, say $\left(\mathbf{X}_{t}\right)_{t \geq 0}$, to (6.1) is the solution to the stochastic differential equation

$$
d \mathbf{X}_{t}=a\left(\mathbf{X}_{t}\right) d t+\tau\left(\mathbf{X}_{t}\right) d \mathbf{N}_{t},
$$

where $\left(\mathbf{N}_{t}\right)_{t \geq 0}$ is the Poisson process such that

$$
d \mathbf{N}_{t}= \begin{cases}1, & \text { Poisson arrival at time } t \\ 0, & \text { otherwise }\end{cases}
$$

We notice that, if $a(\mathbf{x})=0$, then $K$ is the backward operator $B$ and $u(k, t)=p_{k}(t)$, $k \in \mathbb{N}, t>0$, becomes the law of the homogeneous Poisson process. Indeed, formula (6.1) takes the form

$$
\begin{aligned}
\frac{\partial p_{k}}{\partial t}(t) & =-\lambda(I-B) p_{k}(t) \\
& =-\lambda\left(p_{k}(t)-p_{k-1}(t)\right)
\end{aligned}
$$

On the other hand, as already pointed out before, the compound Poisson process

$$
Z_{t}=\sum_{j=1}^{N(t)} Y_{j}
$$

has a generator written as

$$
(\mathcal{A} f)(x)=\int_{\mathbb{R}}(f(x-y)-f(x)) P(Y \in d y)
$$

where the jump $\tau$ equals $Y$ with law $P(Y \in d y) / d y$.
We can now state the following

## Multidimensional fractional advection-dispersion equations

Theorem 6.1. Let us consider the process

$$
\begin{equation*}
Z_{t}=\sum_{j=1}^{N(t)} Y_{j} \tag{6.2}
\end{equation*}
$$

with

$$
Y_{j} \stackrel{d}{=} Y(1), \quad \forall j \in \mathbb{N},
$$

where $\left(Y_{t}\right)_{t \geq 0}$ is the stochastic process driven by

$$
\frac{\partial f}{\partial t}=\mathcal{G} f
$$

Then (6.2) is the stochastic solution to the equation

$$
\begin{equation*}
\frac{\partial u}{\partial t}=-\lambda\left(I-e^{\mathcal{G}}\right) u, \quad x \in \mathbb{R}, t>0 . \tag{6.3}
\end{equation*}
$$

This means that the law of the jumps in the compound Poisson process is fixed by the operator $\mathcal{G}$.

Proof. The process $\left(Y_{t}\right)_{t \geq 0}$ has infinitesimal generator $\mathcal{G}$ and transition semigroup $P_{t}=$ $e^{t \mathcal{G}}$ with symbol $\widehat{P}_{t}=e^{t \Phi}$. The transition law is written as

$$
P_{t} f_{0}(x)=\mathbb{E} f_{0}\left(Y_{t}+x\right),
$$

and solves the Cauchy problem

$$
\left\{\begin{array}{l}
\frac{\partial f}{\partial t}=\mathcal{G} f \\
f(x, 0)=f_{0}(x)
\end{array}\right.
$$

Then, we have that $P_{1}=e^{\mathcal{G}}$. Let us consider the Fourier transform of (6.3),

$$
\frac{\partial \widehat{u}}{\partial t}=-\lambda\left(1-e^{\Phi(k)}\right) \widehat{u},
$$

where $\Phi$ is the Fourier multiplier of the operator $\mathcal{G}$. By integrating with respect to time, we obtain

$$
\begin{equation*}
\widehat{u}(k, t)=\exp \left(-\lambda t\left(1-e^{\Phi(k)}\right)\right) . \tag{6.4}
\end{equation*}
$$

The characteristic function of the process $\left(Z_{t}\right)_{t \geq 0}$ is given by (see formula (5.5) above)

$$
\begin{equation*}
\mathbb{E} e^{i k Z_{t}}=\exp \left[-\lambda t\left(1-\mathbb{E} e^{i Y(1) k}\right)\right] . \tag{6.5}
\end{equation*}
$$

Since

$$
\mathbb{E} e^{i Y(1) k}=e^{\Phi(k)},
$$

we have that (6.5) coincides with (6.4), as claimed.
Remark 6.2. We specialize formula (6.3) in order to obtain some connections with (6.2). In the case $\mathcal{G}=-\partial_{x}$, the Perron-Frobenius operator $K$ is associated to the map $T: x \mapsto x-1$. Then we have that (6.3) becomes

$$
\begin{equation*}
\frac{\partial u}{\partial t}=-\lambda\left(I-e^{-\partial_{x}}\right) u=\lambda(u(x-1, t)-u(x, t)), \tag{6.6}
\end{equation*}
$$

and $e^{\mathcal{G}}=B$, is the backward operator. The stochastic solution to (6.6) is therefore

$$
Z_{t}=N(t),
$$

that is the homogenous Poisson process.
If $\mathcal{G}=-\partial_{x}^{\alpha}$, that is the Riemann-Liouville derivative of order $\alpha \in(0,1)$ then, by using (4.6) we have that

$$
e^{\mathcal{G}} f(x)=e^{-\partial_{x}^{\alpha}} f(x)=\int_{0}^{\infty} d s h_{\alpha}(s, 1) f(x-s)
$$

Hence, we have that

$$
Y_{j} \stackrel{d}{=} \mathfrak{H}^{\alpha}(1), \quad \forall j,
$$

so that

$$
Z_{t} \stackrel{d}{=} \sum_{j=1}^{N(t)} \mathfrak{H}_{j}^{\alpha}(1)
$$

Moreover, by using the fact that (see (4.4) above)

$$
e^{-t \partial_{x}^{\alpha}} f(x)=\mathbb{E} e^{-\mathfrak{H}_{t}^{\alpha} \partial_{x}} f(x),
$$

we have that

$$
\begin{aligned}
-\lambda\left(I-e^{-\partial_{x}^{\alpha}}\right) f(x) & =\lambda \mathbb{E}\left(e^{-\mathfrak{H}_{t}^{\alpha} \partial_{x}}-1\right) f(x) \\
& =\lambda \int_{0}^{+\infty}\left(e^{-y \partial_{x}} f(x)-f(x)\right) h_{\alpha}(d y, 1) \\
& =\lambda \int_{0}^{+\infty}(f(x-y)-f(x)) h_{\alpha}(d y, 1) .
\end{aligned}
$$

Theorem 6.3. Let us consider the equation

$$
\begin{equation*}
\frac{\partial v}{\partial t}+\nabla_{\theta}^{\alpha}(\mathbf{u} v)=-\lambda(I-K) v, \quad \mathbf{x} \in \mathbb{R}^{d}, t>0 \tag{6.7}
\end{equation*}
$$

subject to the initial condition $v(\mathbf{x}, 0)=\delta(\mathbf{x})$, where $\alpha \in(0,1)$, $\mathbf{u}$ is a vector with constant coefficients and $K=e^{-1 \cdot \nabla}$. The stochastic solution to (6.7) is given by

$$
\begin{equation*}
\mathbf{Y}_{t}=\mathbf{N}_{t}+\sum_{j=1}^{d} \boldsymbol{\theta}_{j} \mathfrak{H}^{\alpha}\left(\left(\boldsymbol{\theta}_{j} \cdot \mathbf{u}\right) t\right) \tag{6.8}
\end{equation*}
$$

where $\mathbf{N}_{t}=\mathbf{1} N_{t}$ and $\mathbf{1}=(1,1, \ldots, 1)$. Furthermore,

$$
\begin{equation*}
v(\mathbf{x}, t)=\sum_{m=0}^{\infty} \rho_{\alpha}(\mathbf{x}-m \mathbf{1}, t) e^{-\lambda t} \frac{(\lambda t)^{m}}{m!} \tag{6.9}
\end{equation*}
$$

where $\rho_{\alpha}(\mathrm{x}, t)$ is the fundamental solution of (3.2).
Proof. The characteristic function of (6.8), is given by

$$
\begin{align*}
\mathbb{E} e^{i \mathbf{k} \cdot \mathbf{Y}} & =\mathbb{E} \exp \left(i \mathbf{k} \cdot \mathbf{1} N_{t}+\sum_{j=1}^{d} i \mathbf{k} \cdot \boldsymbol{\theta}_{j} \mathfrak{H}^{\alpha}\left(\left(\boldsymbol{\theta}_{j} \cdot \mathbf{u}\right) t\right)\right)  \tag{6.10}\\
& =\exp \left(-\lambda t\left(1-e^{i \mathbf{k} \cdot \mathbf{1}}\right)-\sum_{j=1}^{d}\left(\boldsymbol{\theta}_{j} \cdot \mathbf{u}\right)\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{j}\right)^{\alpha} t\right)
\end{align*}
$$

From (6.7), by taking the Fourier transform we obtain

$$
\frac{\partial \widehat{v}}{\partial t}+\sum_{j=1}^{d}\left(\boldsymbol{\theta}_{j} \cdot \mathbf{u}\right)\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{j}\right)^{\alpha} \widehat{v}=-\lambda\left(1-e^{i \mathbf{k} \cdot \mathbf{1}}\right) \widehat{v}
$$

which leads to

$$
\begin{equation*}
\widehat{v}(\mathbf{k}, t)=\exp \left(-\lambda t\left(1-e^{i \mathbf{k} \cdot \mathbf{1}}\right)-\sum_{j=1}^{d}\left(\boldsymbol{\theta}_{j} \cdot \mathbf{u}\right)\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{j}\right)^{\alpha} t\right) . \tag{6.11}
\end{equation*}
$$

Formula (6.11) coincides with (6.10), as claimed.

In order to prove (6.9), we observe that (6.11) can be written as follows

$$
\begin{align*}
\widehat{v}(\mathbf{k}, t) & =\exp \left(-\lambda t\left(1-e^{i \mathbf{k} \cdot \mathbf{1}}\right)\right) \exp \left(-\sum_{j=1}^{d}\left(\boldsymbol{\theta}_{j} \cdot \mathbf{u}\right)\left(-i \mathbf{k} \cdot \boldsymbol{\theta}_{j}\right)^{\alpha} t\right)  \tag{6.12}\\
& =\exp \left(-\lambda t\left(1-e^{i \mathbf{k} \cdot \mathbf{1}}\right)\right) \widehat{\rho}_{\alpha}(\mathbf{k}, t)
\end{align*}
$$

where $\widehat{\rho}_{\alpha}(\mathbf{k}, t)$ is the Fourier transform of the fundamental solution of (3.2). We now consider the Fourier transform of (6.9). Recalling the operational rule

$$
\rho_{\alpha}(\mathbf{x}-m \mathbf{1}, t)=e^{-m(\mathbf{1} \cdot \nabla)} \rho_{\alpha}(\mathbf{x}, t),
$$

we have

$$
\widehat{\rho}_{\alpha}(\mathbf{k}, t) e^{-\lambda t} \sum_{m=0}^{\infty} e^{i(\mathbf{1} \cdot \mathbf{k}) m} \frac{(\lambda t)^{m}}{m!}=\widehat{\rho}_{\alpha}(\mathbf{k}, t) e^{-\lambda t\left(1-e^{i \mathbf{k} \cdot \mathbf{1}}\right)}
$$

which coincides with (6.12).
Remark 6.4. We observe that for $\lambda=0$, we have that

$$
v(\mathbf{x}, t)=\rho_{\alpha}(\mathbf{x}, t)
$$

is the fundamental solution of (3.2).

## 7 Second order directional derivatives and their fractional power

We start to deepen the meaning of second order directional derivative $(\boldsymbol{\theta} \cdot \nabla)^{2}$. We notice that

$$
\begin{align*}
(\boldsymbol{\theta} \cdot \nabla)^{2} & =\sum_{i, j} \theta_{i} \theta_{j} \partial_{x_{i}} \partial_{x_{j}}  \tag{7.1}\\
& =\sum_{i, j} a_{i j} \partial_{x_{i}} \partial_{x_{j}},
\end{align*}
$$

where the associated matrix $\left\{a_{i j}\right\}$ is symmetric and singular. Also we assume that $\|\boldsymbol{\theta}\|=1$.

The solution to the equation

$$
\begin{equation*}
\frac{\partial}{\partial t} u(\mathbf{x}, t)=(\boldsymbol{\theta} \cdot \nabla)^{2} u(\mathbf{x}, t), \quad \mathbf{x} \in \mathbb{R}^{d}, t \geq 0 \tag{7.2}
\end{equation*}
$$

subject to the initial condition $u(\mathbf{x}, 0)=\delta(\boldsymbol{\theta} \cdot \mathbf{x})$, is given by (see for example [8])

$$
\begin{equation*}
u(\mathbf{x}, t)=g((\boldsymbol{\theta} \cdot \mathbf{x}), t) \tag{7.3}
\end{equation*}
$$

where

$$
g(x, t)=\frac{e^{-\frac{x^{2}}{4 t}}}{\sqrt{4 \pi t}}
$$

is the law of the one-dimensional Brownian motion $\left(B_{t}\right)_{t>0}$. We will write $\left(\mathbf{B}_{t}\right)_{t>0}$ for the $d$-dimensional vector, whose elements are completely correlated one dimensional Brownian motions. We say that

$$
\mathcal{I}_{t}=\boldsymbol{\theta} \cdot \mathbf{B}_{t}, \quad t \geq 0
$$

is the stochastic solution to (7.2). Notice that $\mathcal{I}_{t}$ is a Gaussian process with singular covariance matrix and degenerate multivariate normal distribution.

Therefore, we can write the solution to (7.2), subject to an initial condition $u(\mathrm{x}, 0)=$ $u_{0}(\mathbf{x})$, as

$$
\begin{equation*}
P_{t} u_{0}(\mathbf{x})=\int_{\mathbb{R}^{d}} u_{0}(\mathbf{y}) \frac{e^{-\frac{|\boldsymbol{\theta} \cdot(\mathbf{y}-\mathbf{x})|^{2}}{4 t}}}{\sqrt{4 \pi t}} d \mathbf{y} \tag{7.4}
\end{equation*}
$$

where $P_{t}=e^{t(\boldsymbol{\theta} \cdot \nabla)^{2}}$ is the associated semigroup. We note that: $P_{0}=I d ; P_{t} 1=1$ and $P_{t} P_{s} f=P_{t+s} f$.

We are now ready to present an integral representation of the power $\alpha \in(0,1)$ of the operator $(\theta \cdot \nabla)^{2}$ and a stochastic representation of the related solutions.

Theorem 7.1. The stochastic solution of the fractional differential equation

$$
\begin{equation*}
\left(\frac{\partial}{\partial t}+\left(-(\boldsymbol{\theta} \cdot \nabla)^{2}\right)^{\alpha}\right) u(\mathbf{x}, t)=0, \quad \mathbf{x} \in \mathbb{R}^{d}, t>0, \alpha \in(0,1) \tag{7.5}
\end{equation*}
$$

subject to the initial condition $u(\mathbf{x}, 0)=f(\mathbf{x}) \in L^{1}\left(\mathbb{R}^{d}\right)$, is given by

$$
\begin{equation*}
\mathcal{I}_{t}^{\alpha}=\boldsymbol{\theta} \cdot \mathbf{B}_{\mathfrak{H}_{t}^{\alpha}} \tag{7.6}
\end{equation*}
$$

In equation (7.5), the power $\alpha \in(0,1)$ of the operator $(\boldsymbol{\theta} \cdot \nabla)^{2}$, is given by

$$
\begin{equation*}
-\left(-(\boldsymbol{\theta} \cdot \nabla)^{2}\right)^{\alpha} f(\mathbf{x})=\frac{C(\alpha)}{2} \int_{\mathbb{R}^{d}} \frac{(f(\mathbf{y}+\mathbf{x})+f(\mathbf{x}-\mathbf{y})-2 f(\mathbf{x}))}{|\boldsymbol{\theta} \cdot \mathbf{y}|^{2 \alpha+1}} d \mathbf{y} \tag{7.7}
\end{equation*}
$$

with

$$
C(\alpha)=\frac{1}{\pi} \Gamma(2 \alpha+1) \sin (\pi \alpha)
$$

Proof. Let us prove (7.7). The general expression for the power $\alpha$ of the operator $\mathcal{A}$ is given by (see for example [1, 13])

$$
\begin{equation*}
-(-\mathcal{A})^{\alpha} f(\mathbf{x})=\frac{\alpha}{\Gamma(1-\alpha)} \int_{0}^{\infty} \frac{\left(P_{s} f(\mathbf{x})-f(\mathbf{x})\right)}{s^{\alpha+1}} d s \tag{7.8}
\end{equation*}
$$

where $P_{s}=e^{s \mathcal{A}}$, is the transition semigroup related to equation (3.9) with representation (3.10) for $\mathcal{A}$.

By using equation (7.8) and (7.4), we have that

$$
\begin{aligned}
-\left(-(\boldsymbol{\theta} \cdot \nabla)^{2}\right)^{\alpha} f(\mathbf{x}) & =\frac{\alpha}{\Gamma(1-\alpha)} \int_{0}^{\infty}\left(P_{s} f(\mathbf{x})-f(\mathbf{x})\right) \frac{d s}{s^{\alpha+1}} \\
& =\frac{\alpha}{\Gamma(1-\alpha)} \int_{\mathbb{R}^{d}}(f(\mathbf{y})-f(\mathbf{x}))\left[\int_{0}^{\infty} \frac{e^{-\frac{|\boldsymbol{\theta} \cdot(\mathbf{y}-\mathbf{x})|^{2}}{4 s}}}{\sqrt{4 \pi s}} \frac{d s}{s^{\alpha+1}}\right] d \mathbf{y} \\
& =\frac{4^{\alpha} \alpha}{\Gamma(1-\alpha)} \frac{\Gamma\left(\alpha+\frac{1}{2}\right)}{\sqrt{\pi}} \int_{\mathbb{R}^{d}} \frac{f(\mathbf{y})-f(\mathbf{x})}{|\boldsymbol{\theta} \cdot(\mathbf{y}-\mathbf{x})|^{2 \alpha+1}} d \mathbf{y}
\end{aligned}
$$

and therefore, we arrive at the following representation

$$
\begin{equation*}
-\left(-(\boldsymbol{\theta} \cdot \nabla)^{2}\right)^{\alpha} f(\mathbf{x})=C(\alpha) \int_{\mathbb{R}^{d}} \frac{f(\mathbf{y})-f(\mathbf{x})}{|\boldsymbol{\theta} \cdot(\mathbf{y}-\mathbf{x})|^{2 \alpha+1}} d \mathbf{y} \tag{7.9}
\end{equation*}
$$

where, in view of the duplication formula

$$
\Gamma(2 \alpha)=\frac{4^{\alpha-1}}{\sqrt{\pi}} \Gamma(\alpha) \Gamma\left(\alpha+\frac{1}{2}\right)
$$

we get that

$$
C(\alpha)=\frac{4^{\alpha} \alpha}{\Gamma(1-\alpha)} \frac{\Gamma\left(\alpha+\frac{1}{2}\right)}{\sqrt{\pi}}=\frac{1}{\pi} \Gamma(2 \alpha+1) \sin (\pi \alpha) .
$$

We notice that (7.9), must be considered in principal value, due to the singular kernel. However, we have that

$$
\begin{align*}
& C(\alpha) \text { p.v. } \int_{\mathbb{R}^{d}} \frac{f(\mathbf{y}+\mathbf{x})-f(\mathbf{x})}{|\boldsymbol{\theta} \cdot \mathbf{y}|^{2 \alpha+1}} d \mathbf{y}  \tag{7.10}\\
& =\frac{C(\alpha)}{2} \int_{\mathbb{R}^{d}} \frac{(f(\mathbf{y}+\mathbf{x})+f(\mathbf{x}-\mathbf{y})-2 f(\mathbf{x}))}{|\boldsymbol{\theta} \cdot \mathbf{y}|^{2 \alpha+1}} d \mathbf{y}
\end{align*}
$$

Indeed, taking the Fourier transform of the last term, we obtain

$$
\begin{aligned}
& \frac{C(\alpha)}{2} \int_{\mathbb{R}^{d}} \frac{\left(e^{i \mathbf{k} \cdot \mathbf{y}}+e^{-i \mathbf{k} \cdot \mathbf{y}}-2\right)}{|\boldsymbol{\theta} \cdot \mathbf{y}|^{2 \alpha+1}} \widehat{f}(\mathbf{k}) d \mathbf{y} \\
& =\frac{C(\alpha)}{2} \int_{\mathbb{R}^{d}} \frac{\left(e^{i \mathbf{k} \cdot \mathbf{y}}-1\right)+\left(e^{-i \mathbf{k} \cdot \mathbf{y}}-1\right)}{|\boldsymbol{\theta} \cdot \mathbf{y}|^{2 \alpha+1}} \widehat{f}(\mathbf{k}) d \mathbf{y} \\
& =C(\alpha) \int_{\mathbb{R}^{d}} \frac{\left(e^{i \mathbf{k} \cdot \mathbf{y}}-1\right)}{|\boldsymbol{\theta} \cdot \mathbf{y}|^{2 \alpha+1}} \widehat{f}(\mathbf{k}) d \mathbf{y}
\end{aligned}
$$

which coincides with the Fourier transform of the first term in (7.10).
In order to prove that (7.6) is the stochastic solution of (7.5), let us consider

$$
\begin{align*}
u(\mathbf{x}, t) & =\int_{0}^{\infty} d s h_{\alpha}(s, t) P_{s} f(\mathbf{x})  \tag{7.11}\\
& =\int_{0}^{\infty} d s h_{\alpha}(s, t) e^{s(\boldsymbol{\theta} \cdot \nabla)^{2}} f(\mathbf{x}) \\
& =\int_{0}^{\infty} d s h_{\alpha}(s, t) e^{-s\left(-(\boldsymbol{\theta} \cdot \nabla)^{2}\right)} f(\mathbf{x}) \\
& =e^{-t\left(-(\boldsymbol{\theta} \cdot \nabla)^{2}\right)^{\alpha}} f(\mathbf{x})
\end{align*}
$$

Then, (7.11) is the solution to (7.5), as claimed.
Remark 7.2. We notice that for $d=1$ and $\alpha \in(0,1)$, the equation (7.7) becomes

$$
-\left(-\left(\frac{\partial}{\partial x}\right)^{2}\right)^{\alpha} f(x)=C(\alpha) \int_{\mathbb{R}} \frac{f(y)-f(x)}{|y-x|^{2 \alpha+1}} d y=\frac{\partial^{2 \alpha} f(x)}{\partial|x|^{2 \alpha}}
$$

that is the Riesz fractional derivative as expected. Also, from equation (7.7), we find that

$$
\begin{equation*}
\sum_{l=1}^{d}-\left(-\left(\boldsymbol{\theta}_{l} \cdot \nabla\right)^{2}\right)^{\alpha} f(\mathbf{x})=\sum_{l=1}^{d} \int_{\mathbb{R}^{d}}(f(\mathbf{y})-f(\mathbf{x})) J\left(\boldsymbol{\theta}_{l} \cdot(\mathbf{x}-\mathbf{y})\right) d \mathbf{y} \tag{7.12}
\end{equation*}
$$

where

$$
J\left(\boldsymbol{\theta}_{l} \cdot(\mathbf{x}-\mathbf{y})\right)=\frac{C(\alpha)}{\left|\boldsymbol{\theta}_{l} \cdot(\mathbf{x}-\mathbf{y})\right|^{2 \alpha+1}}
$$

If $\boldsymbol{\theta}_{i} \equiv \mathbf{e}_{i}, i=1, \cdots, d$ and $\alpha \in(0,1)$, then we have that

$$
\sum_{l=1}^{d}-\left(-\left(\mathbf{e}_{l} \cdot \nabla\right)^{2}\right)^{\alpha} f(\mathbf{x})=\sum_{l=1}^{d} \frac{\partial^{2 \alpha}}{\partial\left|x_{l}\right|^{2 \alpha}} f(\mathbf{x})
$$

## Multidimensional fractional advection-dispersion equations

Remark 7.3. Special care must be given to the case $\alpha=\frac{1}{2}$ in $d=1$. In this case equation (7.12) becomes a Cauchy integral

$$
-\left(-\left(\frac{\partial}{\partial x}\right)^{2}\right)^{1 / 2} f(x)=\frac{p . v .}{\pi} \int_{\mathbb{R}} \frac{f(y)-f(x)}{|y-x|^{2}} d y
$$

where, as usual, "p.v." stands for "principal value".

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