



## Solutions to an anisotropic system via sub-supersolution method and Mountain Pass Theorem

Giovany Figueiredo<sup>1</sup> and Julio R. S. Silva <sup>1, 2</sup>

<sup>1</sup>Departamento de Matemática, Universidade de Brasília – UNB, CEP: 70910-900, Brasília-DF, Brazil

<sup>2</sup>Universidade Federal do Pará – Campus Universitário de Cametá,  
CEP: 68.400-000, Cametá-PA, Brazil

Received 21 September 2018, appeared 28 June 2019

Communicated by Dimitri Mugnai

**Abstract.** We use the sub-supersolution method and the Mountain Pass Theorem in order to show existence and multiplicity of solutions for the quasilinear system given by

$$\begin{cases} - \left[ \sum_{i=1}^N \frac{\partial}{\partial x_i} \left| \frac{\partial u}{\partial x_i} \right|^{p_i-2} \frac{\partial u}{\partial x_i} \right] = a_1(x)u + F_u(x, u, v) & \text{in } \Omega, \\ - \left[ \sum_{i=1}^N \frac{\partial}{\partial x_i} \left| \frac{\partial v}{\partial x_i} \right|^{p_i-2} \frac{\partial v}{\partial x_i} \right] = a_2(x)v + F_v(x, u, v) & \text{in } \Omega, \\ u, v > 0 & \text{in } \Omega, \\ u = v = 0 & \text{on } \partial\Omega, \end{cases}$$

where  $a_j, j = 1, 2$  are functions in  $L^\infty(\Omega)$  and  $F_u$  and  $F_v$  are continuous functions on  $\Omega \times \mathbb{R}^2$ .


**Keywords:** anisotropic operator, sub-supersolution method, Mountain Pass Theorem.

**2010 Mathematics Subject Classification:** 35J65, 35B45.

### 1 Introduction

In this paper we are concerned with existence and multiplicity of positive solutions for the following class of system nonlinear boundary value anisotropic problems given by

$$\begin{cases} - \left[ \sum_{i=1}^N \frac{\partial}{\partial x_i} \left( \left| \frac{\partial u}{\partial x_i} \right|^{p_i-2} \frac{\partial u}{\partial x_i} \right) \right] = a_1(x)u + F_u(x, u, v) & \text{in } \Omega, \\ - \left[ \sum_{i=1}^N \frac{\partial}{\partial x_i} \left( \left| \frac{\partial v}{\partial x_i} \right|^{p_i-2} \frac{\partial v}{\partial x_i} \right) \right] = a_2(x)v + F_v(x, u, v) & \text{in } \Omega, \\ u, v > 0 & \text{in } \Omega, \\ u, v \in W_0^{1, \vec{p}}(\Omega), \end{cases} \quad (1.1)$$

 Corresponding author. Email: [giovany@unb.br](mailto:giovany@unb.br)

where  $\Omega \subset \mathbb{R}^N$  is a bounded smooth domain with smooth boundary,  $N \geq 3$ ,  $\vec{p} = (p_1, \dots, p_N)$ ,  $p_i > 1$ ,  $\sum_{i=1}^N \frac{1}{p_i} > 1$ ,  $p_1 < p_2 < \dots < p_N < p^* := \frac{N\bar{p}}{N-\bar{p}}$ . In this paper  $\bar{p}$  denotes the harmonic mean

$$\bar{p} = \frac{N}{\sum_{i=1}^N \frac{1}{p_i}}.$$

For  $j = 1, 2$ ,  $a_j \geq 0$  is a nontrivial measurable function. More precisely, we will suppose that the function  $a_j$  satisfy the following assumption:

(H) The function  $a_j \in L^\infty(\Omega)$  with  $a_j(x) > 0$ .

In this paper  $F$  is a function on  $\Omega \times \mathbb{R}^2$  of class  $C^1$  satisfying

(H<sub>1</sub>) There is  $\delta > 0$  such that

$$F_s(x, s, t) \geq (1-s)a_1(x), \quad \text{for every } 0 \leq s \leq \delta, \text{ a.e. in } \Omega,$$

and

$$F_t(x, s, t) \geq (1-t)a_2(x), \quad \text{for every } 0 \leq t \leq \delta, \text{ a.e. in } \Omega.$$

(H<sub>2</sub>) There is  $1 < r < p^*$  such that

$$F_s(x, s, t) \leq a_1(x)(s^{r-1} + t^{r-1} + 1), \quad \text{for every } 0 \leq s,$$

and

$$F_t(x, s, t) \leq a_2(x)(s^{r-1} + t^{r-1} + 1), \quad \text{for every } 0 \leq t.$$

Thus, in order to show existence and multiplicity of solutions to problem (1.1), we define the Sobolev space  $E = W_0^{1, \vec{p}}(\Omega) \times W_0^{1, \vec{p}}(\Omega)$  endowed with the norm

$$\|(u, v)\| = \|u\|_{1, \vec{p}} + \|v\|_{1, \vec{p}},$$

where

$$\|u\|_{1, \vec{p}} = \sum_{i=1}^N \left\| \frac{\partial u}{\partial x_i} \right\|_{p_i}.$$

We say that  $u, v \in E$  is a positive weak solution of (1.1) if  $u, v > 0$  in  $\Omega$  and it verifies

$$\sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u}{\partial x_i} \right|^{p_i-2} \frac{\partial u}{\partial x_i} \frac{\partial \varphi}{\partial x_i} dx = \int_{\Omega} a_1(x) u \varphi dx + \int_{\Omega} F_u(x, u, v) \varphi dx,$$

and

$$\sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u}{\partial x_i} \right|^{p_i-2} \frac{\partial u}{\partial x_i} \frac{\partial \psi}{\partial x_i} dx = \int_{\Omega} a_2(x) v \psi dx + \int_{\Omega} F_v(x, u, v) \psi dx,$$

for all  $\varphi, \psi \in W_0^{1, \vec{p}}(\Omega)$ .

In our first theorem we apply the sub-supersolution method to establish the existence of a weak solution for (1.1).

**Theorem 1.1.** *Assume that conditions (H), (H<sub>1</sub>) and (H<sub>2</sub>) hold. If  $\|a_j\|_\infty$  is small, for  $j = 1, 2$ , then system (1.1) has a positive weak solution.*

In order to establish the existence of two solutions for problem (1.1), we also assume

(H<sub>3</sub>) There are  $s_0, t_0 > 0$  such that

$$0 < F(x, s, t) \leq \theta_s s F_s(x, s, t) + \theta_t t F_t(x, s, t), \text{ a.e in } \Omega, \text{ for all } t \geq t_0 \text{ and } s \geq s_0 \text{ in } \Omega,$$

$$\text{where } \frac{1}{p^*} < \theta_s, \theta_t < \frac{1}{p_N}.$$

**Theorem 1.2.** *Assume that conditions (H), (H<sub>1</sub>)–(H<sub>3</sub>) hold. Then, problem (1.1) has two positive weak solutions if  $\|a_j\|_\infty$  is small, for  $j = 1, 2$ .*

A considerable effort has been devoted during the last years to the study anisotropic problems. With no hope to be thorough, let us mention, for example [1, 2, 4–7, 9–14, 16, 20–22] and references therein.

In some sense our paper is a natural continuation of the studies initiated in [2] and it completes the results obtained there, because we study the existence and multiplicity of solutions for a system involving an anisotropic operator using subsolution & supersolution method. This paper seems to be the first to show results on an elliptic system involving an anisotropic operator.

When  $p_i = 2$  we have  $[\sum_{i=1}^N \frac{\partial}{\partial x_i} (|\frac{\partial u}{\partial x_i}|^{p_i-2} \frac{\partial u}{\partial x_i})] = \Delta u$  and when  $p_i = p$  we have  $[\sum_{i=1}^N \frac{\partial}{\partial x_i} (|\frac{\partial u}{\partial x_i}|^{p-2} \frac{\partial u}{\partial x_i})] = \Delta_p u$ . Both cases are called isotropic cases or non-anisotropic cases and this kind of problem has been studied by many authors.

This paper is organized as follows. In the Section 2 we prove the unicity of solutions for the Linear anisotropic problem, a Comparison Principle and a regularity result for solutions to this class of problems. In the Section 3 we prove Theorem 1.1. Theorem 1.2 is proved in Section 4.

## 2 Technical results

We start proving a result of unicity of solution to the linear problem and a Comparison Principle of the anisotropic operator.

**Lemma 2.1.** *There is  $u \in W_0^{1, \vec{p}}(\Omega)$  the unique solution of problem*

$$\begin{cases} -[\sum_{i=1}^N \frac{\partial}{\partial x_i} (|\frac{\partial w}{\partial x_i}|^{p_i-2} \frac{\partial w}{\partial x_i})] = a(x) \text{ in } \Omega, \\ w = 0 \text{ on } \partial\Omega. \end{cases} \quad (2.1)$$

*Proof.* Consider the operator  $T : W_0^{1, \vec{p}}(\Omega) \rightarrow (W_0^{1, \vec{p}}(\Omega))'$  such that  $\langle Tu, \phi \rangle$  is given by

$$\langle Tu, \phi \rangle = \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u}{\partial x_i} \right|^{p_i-2} \frac{\partial u}{\partial x_i} \frac{\partial \phi}{\partial x_i} dx.$$

Since the inequality

$$C_i \left| \frac{\partial u}{\partial x_i} - \frac{\partial v}{\partial x_i} \right|^{p_i} \leq \left\langle \left| \frac{\partial u}{\partial x_i} \right|^{p_i-2} \frac{\partial u}{\partial x_i} - \left| \frac{\partial v}{\partial x_i} \right|^{p_i-2} \frac{\partial v}{\partial x_i}, \frac{\partial u}{\partial x_i} - \frac{\partial v}{\partial x_i} \right\rangle \quad (2.2)$$

is true for some  $C_i > 0$  and for all  $i = 1, \dots, N$ , we have that

$$\langle Tu - Tv, u - v \rangle > 0 \quad \text{for all } u, v \in W_0^{1, \vec{p}}(\Omega) \text{ with } u \neq v.$$

Moreover, if  $\|u\| \rightarrow +\infty$ , then, without loss of generality, we can assume that

$$\int_{\Omega} \left| \frac{\partial u}{\partial x_i} \right|^{p_i} dx \geq 1, \quad \text{for all } i = 1, 2, \dots, N.$$

Hence, since  $1 < p_1 \leq p_i$ , for all  $i = 1, 2, \dots, N$ , we have

$$\sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u}{\partial x_i} \right|^{p_i} dx \geq \sum_{i=1}^N \left( \int_{\Omega} \left| \frac{\partial u}{\partial x_i} \right|^{p_i} dx \right)^{\frac{p_1}{p_i}} \geq \frac{1}{N^{p_1-1}} \left( \sum_{i=1}^N \left| \frac{\partial u}{\partial x_i} \right|_{L^{p_i}} \right)^{p_1},$$

which implies

$$\lim_{\|u\| \rightarrow \infty} \frac{\langle Tu, u \rangle}{\|u\|} = +\infty.$$

Thus, by Minty-Browder's Theorem [8, Théorème 5.16], there exists a unique  $u \in W_0^{1, \vec{p}}(\Omega)$  that satisfies  $Tu = a(x)$ .  $\square$

**Lemma 2.2.** *If  $\Omega$  is a bounded domain and if  $u, v \in W_0^{1, \vec{p}}(\Omega)$  satisfy*

$$\begin{cases} - \left[ \sum_{i=1}^N \frac{\partial}{\partial x_i} \left( \left| \frac{\partial u}{\partial x_i} \right|^{p_i-2} \frac{\partial u}{\partial x_i} \right) \right] \leq - \left[ \sum_{i=1}^N \frac{\partial}{\partial x_i} \left( \left| \frac{\partial v}{\partial x_i} \right|^{p_i-2} \frac{\partial v}{\partial x_i} \right) \right] & \text{in } \Omega, \\ u \leq v & \text{on } \partial\Omega, \end{cases}$$

then  $u \leq v$  a.e. in  $\Omega$ .

*Proof.* Taking  $0 \leq \phi = \max\{u - v, 0\} \in W_0^{1, \vec{p}}(\Omega)$  as a test function, we obtain

$$\int_{\Omega \cap \{u > v\}} \sum_{i=1}^N \left\langle \left| \frac{\partial u}{\partial x_i} \right|^{p_i-2} \frac{\partial u}{\partial x_i} - \left| \frac{\partial v}{\partial x_i} \right|^{p_i-2} \frac{\partial v}{\partial x_i}, \frac{\partial u}{\partial x_i} - \frac{\partial v}{\partial x_i} \right\rangle dx \leq 0.$$

From inequality (2.2), we conclude that  $\|(u - v)^+\| \leq 0$ , this implies  $u \leq v$  a.e. in  $\Omega$ .  $\square$

Before proving the  $L^\infty$ -regularity we enunciate an iteration lemma by Stampacchia that we will use.

**Lemma 2.3** (See [18]). *Assume that  $\phi : [0, \infty) \rightarrow [0, \infty)$  is a nonincreasing function such that if  $h > k > k_0$ , for some  $\alpha > 0, \beta > 1$ ,  $\phi(h) \leq C(\phi(k))^\beta / (h - k)^\alpha$ . Then  $\phi(k_0 + d) = 0$ , where  $d^\alpha = c 2^{\frac{\alpha\beta}{\beta-1}} \phi(k_0)^{\beta-1}$ .*

**Lemma 2.4.** *Let  $v \in W_0^{1, \vec{p}}(\Omega)$  be a solution to problem*

$$\begin{cases} - \left[ \sum_{i=1}^N \frac{\partial}{\partial x_i} \left( \left| \frac{\partial v}{\partial x_i} \right|^{p_i-2} \frac{\partial v}{\partial x_i} \right) \right] = f & \text{in } \Omega, \\ v = 0 & \text{on } \partial\Omega. \end{cases}$$

such that  $f \in L^r(\Omega)$  with  $r > p^* / (p^* - p_1)$ . Then  $v \in L^\infty(\Omega)$ . In particular, if  $\|f\|_r$  is small, then also  $\|v\|_\infty$  is small.

*Proof.* Consider  $v_k = \text{sign}(u)(|u| - k)^+$ , then  $v_k \in W_0^{1, \vec{p}}(\Omega)$  and  $\frac{\partial v}{\partial x_i} = \frac{\partial v_k}{\partial x_i}$  in  $A(k) = \{x \in \Omega : |u(x)| > k\}$ . Let  $|A(k)|$  be the Lebesgue measure of  $A(k)$ . Using  $v_k$  as test function and the Hölder inequality, we have

$$\sum_{i=1}^N \int_{A(k)} \left| \frac{\partial v_k}{\partial x_i} \right|^{p_i} dx = \int_{\Omega} f v_k dx \leq \left( \int_{\Omega} |v_k|^{p^*} dx \right)^{\frac{1}{p^*}} \left( \int_{\Omega} |f|^r dx \right)^{\frac{1}{r}} |A(k)|^{1 - \left(\frac{1}{p^*} + \frac{1}{r}\right)}.$$

Let

$$0 < S = \inf_{u \in D^{1, \vec{p}}(\mathbb{R}^N), \|u\|_{p^*} = 1} \left\{ \sum_{i=1}^N \frac{1}{p_i} \left\| \frac{\partial u}{\partial x_i} \right\|_{p_i}^{p_i} \right\}, \quad \text{see [12].}$$

Once that  $p_i \geq p_1 > 1$ , we have

$$S \left( \int_{\Omega} |u|^{p^*} dx \right)^{\frac{p_1}{p^*}} \leq \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u}{\partial x_i} \right|^{p_i} dx, \quad \text{for all } u \in W_0^{1, \vec{p}}(\Omega).$$

This implies

$$S \left( \int_{A(k)} |v_k|^{p^*} dx \right)^{\frac{p_1-1}{p^*}} \leq \left( \int_{\Omega} |f|^r dx \right)^{\frac{1}{r}} |A(k)|^{1 - \left(\frac{1}{p^*} + \frac{1}{r}\right)}.$$

Note that if  $0 < k < h$ ,  $A(h) \subset A(k)$  and

$$|A(h)|^{\frac{1}{p^*}} (h - k) = \left( \int_{A(h)} (h - k)^{p^*} dx \right)^{\frac{1}{p^*}} \leq \left( \int_{A(k)} |v_k|^{p^*} dx \right)^{\frac{1}{p^*}},$$

then

$$|A(h)| \leq \frac{1}{(h - k)^{p^*}} \frac{1}{S^{\frac{p^*}{p_1-1}}} \|f\|_r^{\frac{p^*}{p_1-1}} |A(k)|^{\frac{p^*}{p_1-1}} \left[ 1 - \left(\frac{1}{p^*} + \frac{1}{r}\right) \right].$$

Since  $r > \frac{p^*}{p^* - p_1}$ , we have  $\beta := \frac{p^*}{p_1-1} \left[ 1 - \left(\frac{1}{p^*} + \frac{1}{r}\right) \right] > 1$ . Therefore, if we define

$$\phi(h) = |A(h)|, \quad \alpha = p^*, \quad \beta = \frac{p^*}{p_1-1} \left[ 1 - \left(\frac{1}{p^*} + \frac{1}{r}\right) \right], \quad k_0 = 0,$$

we have that  $\phi$  is a nonincreasing function and

$$\phi(h) \leq \frac{C}{(h - k)^\alpha} \phi(k)^\beta, \quad \text{for all } h > k > 0.$$

By Lemma 2.3, we have  $\phi(d) = 0$  for  $d = c \|f\|_r^{\frac{1}{p_1-1}} |\Omega|^{\frac{\beta-1}{\alpha}} / S^{\frac{1}{p_1-1}}$ , then

$$\|u\|_\infty \leq \frac{c \|f\|_r^{\frac{1}{p_1-1}} |\Omega|^{\frac{\beta-1}{\alpha}}}{S^{\frac{1}{p_1-1}}}. \quad \square$$

### 3 Proof of Theorem 1.1

We say that  $[(\underline{u}, \underline{v}), (\bar{u}, \bar{v})]$  is a pair of sub and supersolution for the problem (1.1), respectively, if  $\underline{u}, \underline{v} \in E \cap L^\infty(\Omega)$ ,  $\bar{u}, \bar{v} \in E \cap L^\infty(\Omega)$

- a)  $\underline{u} \leq \bar{u}, \underline{v} \leq \bar{v}$  in  $\Omega$  and  $\underline{u} = 0 \leq \bar{u}, \underline{v} = 0 \leq \bar{v}$  on  $\partial\Omega$ ,
- b) Given  $\varphi, \psi$ , with  $\varphi, \psi \geq 0$ , we have

$$\begin{cases} \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial \underline{u}}{\partial x_i} \right|^{p_i-2} \frac{\partial \underline{u}}{\partial x_i} \frac{\partial \varphi}{\partial x_i} \leq \int_{\Omega} a_1(x) \underline{u} \varphi + \int_{\Omega} F_u(x, \underline{u}, w) \varphi \, dx \text{ for all } w \in [\underline{v}, \bar{v}] \\ \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial \underline{v}}{\partial x_i} \right|^{p_i-2} \frac{\partial \underline{v}}{\partial x_i} \frac{\partial \psi}{\partial x_i} \leq \int_{\Omega} a_2(x) \underline{v} \psi + \int_{\Omega} F_v(x, w, \underline{v}) \psi \, dx \text{ for all } w \in [\underline{u}, \bar{u}] \end{cases} \quad (3.1)$$

$$\begin{cases} \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial \bar{u}}{\partial x_i} \right|^{p_i-2} \frac{\partial \bar{u}}{\partial x_i} \frac{\partial \varphi}{\partial x_i} \geq \int_{\Omega} a_1(x) \bar{u} \varphi + \int_{\Omega} F_u(x, \bar{u}, w) \varphi \, dx \text{ for all } w \in [\underline{v}, \bar{v}] \\ \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial \bar{v}}{\partial x_i} \right|^{p_i-2} \frac{\partial \bar{v}}{\partial x_i} \frac{\partial \psi}{\partial x_i} \geq \int_{\Omega} a_2(x) \bar{v} \psi + \int_{\Omega} F_v(x, w, \bar{v}) \psi \, dx \text{ for all } w \in [\underline{u}, \bar{u}] \end{cases} \quad (3.2)$$

**Lemma 3.1.** *Assume that (H), (H<sub>1</sub>) and (H<sub>2</sub>) hold. If  $\|a_j\|_{\infty}$  is small, for  $j = 1, 2$ , then there exist  $\underline{u}, \underline{v}, \bar{u}, \bar{v} \in E \cap L^{\infty}(\Omega)$  such that*

- i)  $\|(\underline{u}, \underline{v})\|_{\infty} \leq \delta$ , where  $\delta$  is the constant that appeared in the hypothesis (H<sub>1</sub>).
- ii)  $0 < \underline{u}(x) \leq u(x)$  a.e in  $\Omega$  and  $0 < \underline{v}(x) \leq \bar{v}(x)$  a.e in  $\Omega$ .
- iii)  $(\underline{u}, \underline{v})$  is a subsolution and  $(\bar{u}, \bar{v})$  is a supersolution of (1.1).

*Proof.* By Lemma 2.1, there is a unique positive solution  $\underline{u} \in W_0^{1, \vec{p}}(\Omega)$  satisfying the problem below

$$\begin{cases} - \left[ \sum_{i=1}^N \frac{\partial}{\partial x_i} \left( \left| \frac{\partial \underline{u}}{\partial x_i} \right|^{p_i-2} \frac{\partial \underline{u}}{\partial x_i} \right) \right] = a_1(x) & \text{in } \Omega, \\ \underline{u} = 0 & \text{on } \partial\Omega. \end{cases}$$

Similarly, there exists a unique positive solution  $\underline{v} \in W_0^{1, \vec{p}}(\Omega)$  satisfying

$$\begin{cases} - \left[ \sum_{i=1}^N \frac{\partial}{\partial x_i} \left( \left| \frac{\partial \underline{v}}{\partial x_i} \right|^{p_i-2} \frac{\partial \underline{v}}{\partial x_i} \right) \right] = a_2(x) & \text{in } \Omega, \\ \underline{v} = 0 & \text{on } \partial\Omega. \end{cases}$$

By Lemma 2.4,  $\underline{u}, \underline{v} \in L^{\infty}(\Omega)$  and there exist  $C_1, C_2 > 0$  such that  $\|\underline{u}\|_{\infty} \leq C_1 \|a\|_{\infty}$  and  $\|\underline{v}\|_{\infty} \leq C_2 \|a\|_{\infty}$ . Now we fix  $\|a_j\|_{\infty}$ , with  $j = 1, 2$  so that

$$\|\underline{u}\|_{\infty} \leq \frac{\delta}{2} \quad \text{and} \quad \|\underline{v}\|_{\infty} \leq \frac{\delta}{2},$$

which ends the proof of the condition (i).

In order to prove ii), we invoke Lemma 2.1 one more time to show that there exists a unique positive solution  $\bar{u} \in W_0^{1, \vec{p}}(\Omega) \cap L^{\infty}(\Omega)$

$$\begin{cases} - \left[ \sum_{i=1}^N \frac{\partial}{\partial x_i} \left( \left| \frac{\partial \bar{u}}{\partial x_i} \right|^{p_i-2} \frac{\partial \bar{u}}{\partial x_i} \right) \right] = 1 + a_1(x) & \text{in } \Omega, \\ \bar{u} = 0 & \text{on } \partial\Omega \end{cases} \quad (3.3)$$

and there exists a unique positive solution  $\bar{v} \in W_0^{1, \vec{p}}(\Omega)$

$$\begin{cases} - \left[ \sum_{i=1}^N \frac{\partial}{\partial x_i} \left( \left| \frac{\partial \bar{v}}{\partial x_i} \right|^{p_i-2} \frac{\partial \bar{v}}{\partial x_i} \right) \right] = 1 + a_2(x) & \text{in } \Omega, \\ \bar{v} = 0 & \text{on } \partial\Omega. \end{cases} \quad (3.4)$$

Note that, for all  $0 \leq \varphi, \psi \in W_0^{1, \vec{p}}(\Omega)$ , we have

$$\sum_{i=1}^N \int_{\Omega} \left| \frac{\partial \bar{u}}{\partial x_i} \right|^{p_i-2} \frac{\partial \bar{u}}{\partial x_i} \frac{\partial \varphi}{\partial x_i} dx = \int_{\Omega} [a_1(x) + 1] \varphi dx \geq \int_{\Omega} a_1(x) \varphi dx = \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial \underline{u}}{\partial x_i} \right|^{p_i-2} \frac{\partial \underline{u}}{\partial x_i} \frac{\partial \varphi}{\partial x_i} dx$$

and

$$\sum_{i=1}^N \int_{\Omega} \left| \frac{\partial \bar{v}}{\partial x_i} \right|^{p_i-2} \frac{\partial \bar{v}}{\partial x_i} \frac{\partial \psi}{\partial x_i} dx = \int_{\Omega} [a_2(x) + 1] \psi dx \geq \int_{\Omega} a_2(x) \psi dx = \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial \underline{v}}{\partial x_i} \right|^{p_i-2} \frac{\partial \underline{v}}{\partial x_i} \frac{\partial \psi}{\partial x_i} dx.$$

Then, from Lemma 2.2 we conclude that  $\underline{u}(x) \leq \bar{u}(x)$  a.e. in  $\Omega$  and  $\underline{v}(x) \leq \bar{v}(x)$  a.e. in  $\Omega$ , which proves the condition *ii*).

Our final task is to check that the condition *iii*) holds. First, we use the maximum principle in [9, Corollary 4.4] and conclude that  $\underline{u}, \underline{v} > 0$ . Now using the definition of  $\underline{u}, \underline{v}$  and  $(H_1)$ , we obtain, for each  $\varphi, \psi \geq 0$ ,

$$\begin{aligned} & \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial \underline{u}}{\partial x_i} \right|^{p_i-2} \frac{\partial \underline{u}}{\partial x_i} \frac{\partial \varphi}{\partial x_i} - \int_{\Omega} a_1(x) \underline{u} \varphi dx - \int_{\Omega} F_u(x, \underline{u}, \underline{v}) \varphi dx \\ & \leq \int_{\Omega} a_1(x) \varphi dx - \int_{\Omega} a_1(x) \underline{u} \varphi dx - \int_{\Omega} (1 - \underline{u}) a_1(x) \varphi dx \\ & = 0 \end{aligned}$$

and

$$\begin{aligned} & \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial \underline{v}}{\partial x_i} \right|^{p_i-2} \frac{\partial \underline{v}}{\partial x_i} \frac{\partial \psi}{\partial x_i} - \int_{\Omega} a_2(x) \underline{v} \psi dx - \int_{\Omega} F_v(x, \underline{u}, \underline{v}) \psi dx \\ & \leq \int_{\Omega} a_2(x) \psi dx - \int_{\Omega} a_2(x) \underline{v} \psi dx - \int_{\Omega} (1 - \underline{v}) a_2(x) \psi dx \\ & = 0 \end{aligned}$$

Then,  $(\underline{u}, \underline{v})$  is a subsolution for problem (1.1).

Now, we use  $(H_2)$ , (3.3) and (3.4) we have for  $\|a_j\|_{\infty}$  sufficiently small such that

$$\begin{aligned} & \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial \bar{u}}{\partial x_i} \right|^{p_i-2} \frac{\partial \bar{u}}{\partial x_i} \frac{\partial \varphi}{\partial x_i} - \int_{\Omega} a_1(x) \bar{u} \varphi - \int_{\Omega} F_u(x, \bar{u}, \bar{v}) \varphi dx \\ & \geq \left( 1 - \|a_1\|_{\infty} \|\bar{u}\|_{\infty} - \|a_1\|_{\infty} - \|a_1\|_{\infty} \|\bar{u}\|_{\infty}^{r-1} - \|a_1\|_{\infty} \|\bar{v}\|_{\infty}^{r-1} \right) \int_{\Omega} \varphi dx > 0 \end{aligned}$$

and

$$\begin{aligned} & \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial \bar{v}}{\partial x_i} \right|^{p_i-2} \frac{\partial \bar{v}}{\partial x_i} \frac{\partial \psi}{\partial x_i} - \int_{\Omega} a_2(x) \bar{v} \psi - \int_{\Omega} F_v(x, \bar{u}, \bar{v}) \psi dx \\ & \geq \left( 1 - \|a_2\|_{\infty} \|\bar{v}\|_{\infty} - \|a_2\|_{\infty} - \|a_2\|_{\infty} \|\bar{u}\|_{\infty}^{r-1} - \|a_2\|_{\infty} \|\bar{v}\|_{\infty}^{r-1} \right) \int_{\Omega} \psi dx > 0 \end{aligned}$$

Then  $\bar{u}, \bar{v}$  is a supersolution of (1.1).  $\square$

Consider the functions

$$G_s(x, s, t) = \begin{cases} a_1(x)\bar{u}(x) + F_s(x, \bar{u}(x), t), & s > \bar{u}(x) \\ a_1(x)s + F_s(x, s, t), & \underline{u}(x) \leq s \leq \bar{u}(x) \\ a_1(x)\underline{u}(x) + F_s(x, \underline{u}(x), t), & s < \underline{u}(x), \end{cases} \quad (3.5)$$

and

$$G_t(x, s, t) = \begin{cases} a_2(x)\bar{v}(x) + F_t(x, s, \bar{v}(x)), & t > \bar{v}(x) \\ a_2(x)t + F_t(x, s, t), & \underline{v}(x) \leq t \leq \bar{v}(x) \\ a_2(x)\underline{v}(x) + F_t(x, s, \underline{v}(x)), & t < \underline{v}(x), \end{cases} \quad (3.6)$$

and the auxiliary problem

$$\begin{cases} - \left[ \sum_{i=1}^N \frac{\partial}{\partial x_i} \left( \left| \frac{\partial u}{\partial x_i} \right|^{p_i-2} \frac{\partial u}{\partial x_i} \right) \right] = G_u(x, u, v) \text{ in } \Omega, \\ u > 0 \text{ in } \Omega, \\ - \left[ \sum_{i=1}^N \frac{\partial}{\partial x_i} \left( \left| \frac{\partial v}{\partial x_i} \right|^{p_i-2} \frac{\partial v}{\partial x_i} \right) \right] = G_v(x, u, v) \text{ in } \Omega, \\ u, v > 0 \text{ in } \Omega, \\ u, v \in W_0^{1, \vec{p}}(\Omega). \end{cases} \quad (3.7)$$

We define the functional  $\Phi : E \rightarrow \mathbb{R}$  by

$$\Phi(u, v) = \sum_{i=1}^N \int_{\Omega} \frac{1}{p_i} \left| \frac{\partial u}{\partial x_i} \right|^{p_i} dx + \sum_{i=1}^N \int_{\Omega} \frac{1}{p_i} \left| \frac{\partial v}{\partial x_i} \right|^{p_i} dx - \int_{\Omega} G(x, u, v) dx. \quad (3.8)$$

We have  $\Phi \in C^1(E, \mathbb{R})$  with

$$\begin{aligned} \Phi'(u, v)(\varphi, \psi) &= \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u}{\partial x_i} \right|^{p_i-2} \frac{\partial u}{\partial x_i} \frac{\partial \varphi}{\partial x_i} dx + \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial v}{\partial x_i} \right|^{p_i-2} \frac{\partial v}{\partial x_i} \frac{\partial \psi}{\partial x_i} dx \\ &\quad - \int_{\Omega} G_u(x, u, v) \varphi dx - \int_{\Omega} G_v(x, u, v) \psi dx, \end{aligned}$$

for all  $u, v, \varphi, \psi \in E$ .

From  $(H_2)$  and definition of  $G_s$  and  $G_t$ , we have that

$$|G_s(x, s, t)| \leq K_1, \text{ for some } K_1 > 0, \text{ a.e. in } \Omega \quad (3.9)$$

and

$$|G_t(x, s, t)| \leq K_2, \text{ for some } K_2 > 0, \text{ a.e. in } \Omega. \quad (3.10)$$

From (3.9) and (3.10), we have that  $\Phi$  is coercive. Then, we can obtain that  $(u_n, v_n)$  is a bounded sequence in  $E$  such that

$$\Phi(u_n, v_n) \rightarrow c = \inf_{\mathcal{M}} \Phi,$$

where

$$\mathcal{M} = \{(u, v) \in E : \underline{u} \leq u \leq \bar{u} \text{ a.e. in } \Omega \text{ and } \underline{v} \leq v \leq \bar{v} \text{ a.e. in } \Omega\}.$$



Hence, up to subsequence, we have

$$\begin{cases} (u_n, v_n) \rightharpoonup (u, v) \text{ in } E, \\ (u_n, v_n) \rightarrow v \text{ in } L^s(\Omega) \times L^s(\Omega), 1 \leq s < p^*, \\ (u_n(x), v_n(x)) \rightarrow (u(x), v(x)) \text{ a.e in } \Omega. \end{cases} \quad (3.11)$$

Now, note that  $\mathcal{M}$  is closed and convex in  $E$ . By [19, Thorem 1.2], the restriction  $\Phi|_{\mathcal{M}}$  attains its infimum at a point  $(u, v)$  in  $\mathcal{M}$ . Using the same argument as in the proof of [19, Thorem 2.4], we see that  $(u, v)$  weakly solves (3.7). Since  $G_s(x, s, t) = a_1(x)s + F_s(x, s, t)$  for  $s \in [\underline{u}, \bar{u}]$  and  $G_t(x, s, t) = a_2(x)t + F_t(x, s, t)$  for  $t \in [\underline{v}, \bar{v}]$  then  $(u, v)$  is a positive weak solution of (1.1).

## 4 Proof of Theorem 1.2

Let  $(\underline{u}, \underline{v}) \in E \cap L^\infty(\Omega)$  the subsolution of Problema (1.1). In our next result we prove that the functional  $\Phi$  satisfies the geometric hypotheses of the Mountain Pass Theorem (to see [3]).

Consider the functions

$$\widehat{G}_s(x, s, t) = \begin{cases} a_1(x)s + F_s(x, s, t), & s > \underline{u}(x) \\ a_1(x)\underline{u}(x) + F_s(x, \underline{u}(x), t), & s \leq \underline{u}(x), \end{cases} \quad (4.1)$$

$$\widehat{G}_t(x, s, t) = \begin{cases} a_2(x)t + F_t(x, s, t), & t > \underline{v}(x) \\ a_2(x)\underline{v}(x) + F_t(x, \underline{v}(x), t), & t \leq \underline{v}(x) \end{cases} \quad (4.2)$$

and define the functional  $\widehat{\Phi} : W_0^{1, \vec{p}}(\Omega) \rightarrow \mathbb{R}$  by

$$\widehat{\Phi}(u, v) = \sum_{i=1}^N \int_{\Omega} \frac{1}{p_i} \left| \frac{\partial u}{\partial x_i} \right|^{p_i} dx + \sum_{i=1}^N \int_{\Omega} \frac{1}{p_i} \left| \frac{\partial v}{\partial x_i} \right|^{p_i} dx - \int_{\Omega} \widehat{G}(x, u, v) dx. \quad (4.3)$$

Note that by  $(H_2)$ , (4.1) and (4.2), we have

$$\widehat{G}_s(x, s, t) \leq \widetilde{C}_1 |t| + a_1(x) |s|^r + a_1(x) s |t|^r, \quad \text{for all } s \geq 0, \quad (4.4)$$

and

$$\widehat{G}_t(x, s, t) \leq \widetilde{C}_2 |t| + a_2(x) |t|^r + a_1(x) t |s|^r, \quad \text{for all } t \geq 0, \quad (4.5)$$

for some constants  $\widetilde{C}_1, \widetilde{C}_2 > 0$ .

**Lemma 4.1.** *The functional  $\widehat{\Phi}$  satisfies the (PS)-condition for every  $c \in \mathbb{R}$ .*

*Proof.* Let  $(u_n, v_n) \subset E$  be a sequence such that

$$\widehat{\Phi}(u_n, v_n) \rightarrow c \quad \text{and} \quad \widehat{\Phi}'(u_n, v_n) \rightarrow 0. \quad (4.6)$$

Using  $(H_3)$  and Sobolev's embedding, there are  $C_1, C_2 > 0$  such that

$$\begin{aligned} C_1 + \|(u_n, v_n)\| &\geq \widehat{\Phi}(u_n, v_n) - \left[ \theta_{u_n} \widehat{\Phi}'(u_n, v_n)(u_n, 0) + \theta_{v_n} \widehat{\Phi}'(u_n, v_n)(0, v_n) \right] \\ &\geq C_2 \|(u_n, v_n)\|^{p_1}, \end{aligned} \quad (4.7)$$

where get that  $(u_n, v_n)$  is a bounded sequence in  $E$  and hence, up to subsequence, we have

$$\begin{cases} (u_n, v_n) \rightharpoonup (u, v) & \text{in } E, \\ (u_n, v_n) \rightarrow (u, v) & \text{in } L^s(\Omega) \times L^s(\Omega), \quad 1 \leq s < p^*, \\ (u_n(x), v_n(x)) \rightarrow (u(x), v(x)) & \text{a.e. in } \Omega. \end{cases} \quad (4.8)$$

Using (4.6), (4.8), (2.2), the Lebesgue dominated convergence theorem and standard arguments, up to subsequence, we obtain

$$\sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u_n}{\partial x_i} - \frac{\partial u}{\partial x_i} \right|^{p_i} \leq o_n(1),$$

and

$$\sum_{i=1}^N \int_{\Omega} \left| \frac{\partial v_n}{\partial x_i} - \frac{\partial v}{\partial x_i} \right|^{p_i} \leq o_n(1),$$

which implies  $(u_n, v_n) \rightarrow (u, v)$  in  $E$ . □

**Lemma 4.2.** *Assume that (H), (H<sub>1</sub>)–(H<sub>3</sub>) hold. Then for  $\|a_j\|_{L^\infty}$  small, for  $j = 1, 2$ ,  $\widehat{\Phi}$  satisfies:*

i) *There are  $R > \|(\underline{u}, \underline{v})\|$  and  $\beta > 0$ , such that*

$$\widehat{\Phi}(\underline{u}, \underline{v}) < 0 < \beta \leq \inf_{(u,v) \in \partial B_R(0)} \widehat{\Phi}(u, v).$$

ii) *There are  $e \in W_0^{1, \vec{p}}(\Omega) \setminus B_{2R}(0)$  such that  $\widehat{\Phi}(e) < \beta$ .*

*Proof.* Since  $(\underline{u}, \underline{v})$  is a subsolution of (1.1),  $\widehat{G}_s(x, \underline{u}, t) = (a_1(x)\underline{u} + F_s(x, \underline{u}, t))\underline{u}$  and  $\widehat{G}_t(x, s, \underline{v}) = (a_2(x)\underline{v} + F_t(x, s, \underline{v}))\underline{v}$ , with  $p_i > 1$ , for  $i = 1, 2, \dots, N$ , we have

$$\begin{aligned} \widehat{\Phi}(\underline{u}, \underline{v}) &= \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial \underline{u}}{\partial x_i} \right|^{p_i} dx + \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial \underline{v}}{\partial x_i} \right|^{p_i} dx \\ &\quad - \int_{\Omega} (a_1(x)\underline{u} + F_s(x, \underline{u}, t))\underline{u} dx - \int_{\Omega} (a_2(x)\underline{v} + F_s(x, s, \underline{v}))\underline{v} dx. \end{aligned} \quad (4.9)$$

Now, let  $\|(u, v)\| = R > 1$ , without loss of generality, we can assume that

$$\int_{\Omega} \left| \frac{\partial u}{\partial x_i} \right|^{p_i} dx \geq 1, \quad \text{for all } i = 1, 2, \dots, N,$$

and

$$\int_{\Omega} \left| \frac{\partial v}{\partial x_i} \right|^{p_i} dx \geq 1, \quad \text{for all } i = 1, 2, \dots, N.$$

Hence, using this inequality, (4.4) and (4.5) with the Sobolev Embedding Theorem, we find positive constants, such that

$$\begin{aligned} \widehat{\Phi}(u, v) &\geq K\|(u, v)\| - c_3\|a_1\|_{L^\infty(\Omega)}\|\underline{u}\|_{L^\infty(\Omega)}\|(u, v)\| - c_4\|a_1\|_{L^\infty(\Omega)}\|(u, v)\| \\ &\quad - c_5\|a_1\|_{L^\infty(\Omega)}\|(u, v)\|^r - c_6\|a_2\|_{L^\infty(\Omega)}\|\underline{v}\|_{L^\infty(\Omega)}\|(u, v)\| \\ &\quad - c_7\|a_2\|_{L^\infty(\Omega)}\|(u, v)\| - c_8\|a_2\|_{L^\infty(\Omega)}\|(u, v)\|^r - c_9\|a_1\|_{L^\infty(\Omega)}\|(u, v)\|^r \\ &\quad - c_{10}\|a_1\|_{L^\infty(\Omega)}\|(u, v)\|^r - c_{11}\|a_2\|_{L^\infty(\Omega)}\|(u, v)\|^r \\ &\quad - c_{12}\|a_2\|_{L^\infty(\Omega)}\|(u, v)\|^r, \quad \text{for all } \|(u, v)\| = R, \end{aligned} \quad (4.10)$$

where  $K = \min \left\{ \frac{k_1}{p_N}, \frac{k_2}{p_N} \right\}$ . Note that, if  $(u, v) \in \partial B_R(0)$  with  $R > 1$  and for  $\|a_j\|_{L^\infty(\Omega)}$  sufficiently small, with  $j = 1, 2$ , there exists  $\beta \in \mathbb{R}$  such that  $\widehat{\Phi}(u, v) \geq \beta$ , for all  $(u, v) \in \partial B_R(0)$ . Hence, the choices of  $\beta$ ,  $R$  and  $\|a_j\|_{L^\infty(\Omega)}$  combined with inequalities (4.9) and (4.10) result in

$$\widehat{\Phi}(\underline{u}, \underline{v}) < 0 < \beta \leq \inf_{(u,v) \in \partial B_R(0)} \widehat{\Phi}(u, v),$$

which shows the condition *i*).

Now, by definition of  $\widehat{G}_s$  we have

$$\widehat{G}_{s\underline{u}}(x, s\underline{u}, 0) \geq F(x, s\underline{u}, 0) \quad \text{for all } s \geq 1, \text{ a.e. in } \Omega.$$

We invoke  $(H_1)$  and (4.3) to obtain

$$\widehat{\Phi}(s\underline{u}, 0) \leq \sum_{i=1}^N \frac{s^{p_N}}{p_1} \int_{\Omega} \left| \frac{\partial \underline{u}}{\partial x_i} \right|^{p_N} - \int_{\Omega} F(x, s\underline{u}, 0) dx.$$

Using  $(H_3)$ , there exists  $\widetilde{K}_1 > 0$  such that

$$F(x, s, 0) \geq \widetilde{K}_1 s^{\frac{1}{\theta_s}}, \quad \text{for all } s \geq \max\{1, s_0\},$$

where  $s_0$  are the constants that appear in  $(H_3)$ . Then,

$$\widehat{\Phi}(s\underline{u}, 0) \leq s^{p_N} \sum_{i=1}^N \int_{\Omega} \frac{1}{p_1} \left| \frac{\partial \underline{u}}{\partial x_i} \right|^{p_i} - \widetilde{K}_1 s^{\frac{1}{\theta_s}} \int_{\Omega} |\underline{u}|^{\frac{1}{\theta_s}} dx.$$

Since  $\frac{1}{p^*} < \theta_s < \frac{1}{p_N}$ , we conclude that  $\widehat{\Phi}(s\underline{u}, 0) \rightarrow -\infty$  as  $s \rightarrow +\infty$ . So, we may find  $e = s_0(\underline{u}, 0) \in E$  such that  $\|e\| > R$  and  $\widehat{\Phi}(e) < \beta$ , which satisfies the condition *ii*).  $\square$

*Proof of Theorem 1.2.* Let  $(\underline{u}, \underline{v}), (\bar{u}, \bar{v})$  be the subsolution and the supersolution of (1.1) given in Lemma (3.1) and  $(u_1, v_1)$  the solution of (1.1) obtained in Theorem 1.1.

Using the Lemma 4.2, we conclude, with the Mountain Pass Theorem (see [3]), that

$$\widehat{c} = \inf_{\gamma \in \Gamma} \max_{t \in [0,1]} \widehat{\Phi}(\gamma(t)), \quad \text{where } \Gamma = \{\gamma \in C([0,1], W_0^{1,\vec{p}}(\Omega)) : \gamma(0) = (\underline{u}, \underline{v}), \gamma(1) = e\},$$

is critical value of  $\widehat{\Phi}$ .

By (3.5),(3.6),(4.1) and (4.2),  $G_s(x, s, t) = \widehat{G}_s(x, s, t)$  for  $s \in [0, \bar{u}]$  and  $G_t(x, s, t) = \widehat{G}_t(x, s, t)$  for  $t \in [0, \bar{v}]$ , thus  $\Phi(u, v) = \widehat{\Phi}(u, v)$  with  $u \in [0, \bar{u}]$  and  $v \in [0, \bar{v}]$ , where  $\Phi$  and  $\widehat{\Phi}$  are given in (3.8) and (4.3), respectively. Then,

$$\widehat{\Phi}(u_1, v_1) = \inf_{\mathcal{M}} \Phi(u, v),$$

where

$$\mathcal{M} = \{(u, v) \in E : \underline{u} \leq u \leq \bar{u} \text{ a.e. in } \Omega \text{ and } \underline{v} \leq v \leq \bar{v} \text{ a.e. in } \Omega\}.$$

was given in the proof of in Theorem 1.1.

Therefore, the problem (1.1) has two weak solutions  $v_1, v_2 \in W_0^{1,\vec{p}}(\Omega)$ , such that

$$\widehat{\Phi}(u_1, v_1) \leq \widehat{\Phi}(\underline{v}) < 0 < \beta \leq \widehat{c} = \widehat{\Phi}(u_2, v_2).$$

Recall that  $\underline{u} \leq u_1 \leq \bar{u}$  a.e. in  $\Omega$  and  $\underline{v} \leq v_1 \leq \bar{v}$  a.e. in  $\Omega$ , thus  $(u_1, v_1) > 0$ . Now, we will show that  $(u_2, v_2) > 0$ .

Taking  $((\underline{u}, \underline{v}) - (u_2, v_2))^+$ , as test function and defining  $\{(u_2, v_2) < (\underline{u}, \underline{v})\} := \{x \in \Omega : u_2(x) < \underline{u}(x) \text{ and } v_2(x) < \underline{v}(x)\}$ , we have

$$\begin{aligned} & \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u_2}{\partial x_i} \right|^{p_i-2} \frac{\partial u_2}{\partial x_i} \frac{\partial (\underline{u} - u_2)^+}{\partial x_i} dx + \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial v_2}{\partial x_i} \right|^{p_i-2} \frac{\partial v_2}{\partial x_i} \frac{\partial (\underline{v} - v_2)^+}{\partial x_i} dx \\ &= \int_{\{u_2 < \underline{u}\}} (a_1 \underline{u} + F_s(x, \underline{u}, t)) (\underline{u} - u_2)^+ dx + \int_{\{v_2 < \underline{v}\}} (a_2 \underline{v} + F_t(x, s, \underline{v})) (\underline{v} - v_2)^+ dx. \end{aligned} \quad (4.11)$$

Since  $(\underline{u}, \underline{v})$  is a subsolution of (1.1), using (4.11) we obtain

$$\sum_{i=1}^N \int_{\Omega} \left| \frac{\partial \underline{u}}{\partial x_i} \right|^{p_i-2} \frac{\partial \underline{u}}{\partial x_i} \frac{\partial (\underline{u} - u_2)^+}{\partial x_i} dx - \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u_2}{\partial x_i} \right|^{p_i-2} \frac{\partial u_2}{\partial x_i} \frac{\partial (\underline{u} - u_2)^+}{\partial x_i} dx \leq 0$$

and

$$\sum_{i=1}^N \int_{\Omega} \left| \frac{\partial \underline{v}}{\partial x_i} \right|^{p_i-2} \frac{\partial \underline{v}}{\partial x_i} \frac{\partial (\underline{v} - v_2)^+}{\partial x_i} dx - \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial v_2}{\partial x_i} \right|^{p_i-2} \frac{\partial v_2}{\partial x_i} \frac{\partial (\underline{v} - v_2)^+}{\partial x_i} dx \leq 0.$$

From inequality (2.2), we conclude that  $\|(\underline{u} - u_2)^+\|_{1, \vec{p}} \leq 0$  and  $\|(\underline{v} - v_2)^+\|_{1, \vec{p}} \leq 0$ , this implies  $0 < \underline{u} \leq u_2$  a.e. in  $\Omega$  and  $0 < \underline{v} \leq v_2$  a.e. in  $\Omega$ . We concluded that  $(u_2, v_2) > 0$ .  $\square$

## References

- [1] A. ALBERICO, G. DI BLASIO, F. FEO, A priori estimates for solutions to anisotropic elliptic problems via symmetrization, *Math. Nachr.* **290**(2017), No. 7, 986–1003. <https://doi.org/10.1002/mana.201500282>.
- [2] C. O. ALVES, A. EL HAMIDI, Existence of solution for a anisotropic equation with critical exponent, *Differential Integral Equations* **21**(2008), No. 1–2, 25–40. [MR2479660](https://doi.org/10.1080/10236190802479660).
- [3] A. AMBROSETTI, P. H. RABINOWITZ, Dual variational methods in critical point theory and applications, *J. Funct. Anal.* **14**(1973), 349–381. [https://doi.org/10.1016/0022-1236\(73\)90051-7](https://doi.org/10.1016/0022-1236(73)90051-7).
- [4] H. AYADI, F. MOKHTARI, Nonlinear anisotropic elliptic equations with variable exponents and degenerate coercivity, *Electron. J. Differential Equations* **2018**, No. 45, 1–23. [MR3781160](https://doi.org/10.1515/ejde-2018-0160).
- [5] P. BARONI, A. DI CASTRO, G. PALATUCCI, Intrinsic geometry and De Giorgi classes for certain anisotropic problems, *Discrete Contin. Dyn. Syst. Ser. S* **10**(2017), No. 4, 647–659. <https://doi.org/10.3934/dcdss.2017032>,
- [6] M. BENDAHMANE, K. H. KARLSEN, Renormalized solutions of an anisotropic reaction-diffusion-advection system with  $L^1$  data, *Commun. Pure Appl. Anal.* **5**(2006), No. 4, 733–762. <https://doi.org/10.3934/cpaa.2006.5.733>.
- [7] M. BENDAHMANE, M. LANGLAIS, M. SAAD, On some anisotropic reaction-diffusion systems with  $L^1$ -data modeling the propagation of an epidemic disease, *Nonlinear Anal.* **54**(2003), No. 4, 617–636. [https://doi.org/10.1016/S0362-546X\(03\)00090-7](https://doi.org/10.1016/S0362-546X(03)00090-7).
- [8] H. BREZIS, *Analyse fonctionnelle*, Masson, Paris, 1983. [MR697382](https://doi.org/10.1016/0003-6818(83)90000-0).

- [9] A. DI CASTRO, E. MONTEFUSCO, Nonlinear eigenvalues for anisotropic quasilinear degenerate elliptic equations, *Nonlinear Anal.* **70**(2009), 4093–4105. <https://doi.org/10.1016/j.na.2008.06.001>.
- [10] A. DI CASTRO, Existence and regularity results for anisotropic elliptic problems, *Adv. Nonlinear Stud.* **9**(2009), 367–393. <https://doi.org/10.1515/ans-2009-0207>.
- [11] A. DI CASTRO, Anisotropic elliptic problems with natural growth terms, *Manuscripta Math.* **135**(2011), 521–543. <https://doi.org/10.1007/s00229-011-0431-3>.
- [12] A. EL HAMIDI, J. M. RAKOTOSON, Extremal functions for the anisotropic Sobolev inequalities, *Ann. Inst. H. Poincaré Anal. Non Linéaire* **24**(2007), 741–756. <https://doi.org/10.1016/j.anihpc.2006.06.003>.
- [13] B. ELLAHYANI, A. EL HACHIMI, Existence and multiplicity of solutions for anisotropic elliptic problems with variable exponent and nonlinear Robin boundary conditions, *Electron. J. Differential Equations* **2017**, No. 188, 1–17. [MR3690215](https://doi.org/10.1186/1029-242X-188-1).
- [14] G. M. FIGUEIREDO, J. R. SANTOS JUNIOR, A. SUAREZ, Multiplicity results for an anisotropic equation with subcritical or critical growth, *Adv. Nonlinear Stud.* **15**(2015), No. 2, 377–394. <https://doi.org/10.1515/ans-2015-0206>.
- [15] I. FRAGALA, F. GAZZOLA, B. KAWOHL, Existence and nonexistence results for anisotropic quasilinear elliptic equations, *Ann. Inst. H. Poincaré Anal. Non Linéaire* **21**(2004), 715–734. <https://doi.org/10.1016/j.anihpc.2003.12.001>.
- [16] H. GAO, S. LIANG, Y. CUI, Regularity for anisotropic solutions to some nonlinear elliptic system, *Front. Math. China* **11**(2016), No. 1, 77–87. <https://doi.org/10.1007/s11464-015-0443-5>.
- [17] D. REPOVŠ, Infinitely many symmetric solutions for anisotropic problems driven by nonhomogeneous operators, *Discrete Contin. Dyn. Syst. Ser. S* **12**(2019), No. 2, 401–411. <https://doi.org/10.3934/dcdss.2019026>.
- [18] G. STAMPACCHIA, *Équations elliptiques du second ordre à coefficients discontinus*, Séminaire Jean Leray, No. 3 (1963–1964), pp. 1–77. [http://www.numdam.org/item/SJL\\_1963-1964\\_\\_3\\_1\\_0/](http://www.numdam.org/item/SJL_1963-1964__3_1_0/)
- [19] M. STRUWE, *Variational methods. Applications to nonlinear partial differential equations and Hamiltonian systems*, Springer-Verlag, 1996. <https://doi.org/10.1007/978-3-540-74013-1>.
- [20] J. VÉTOIS, The blow-up of critical anisotropic equations with critical directions, *Nonlinear Differ. Equ. Appl.* **18**(2011), 173–197. <https://doi.org/10.1007/s00030-010-0090-1>.
- [21] J. VÉTOIS, Decay estimates and a vanishing phenomenon for the solutions of critical anisotropic equations, *Adv. Math.* **284**(2015), 122–158. <https://doi.org/10.1016/j.aim.2015.04.029>.
- [22] J. VÉTOIS, Strong maximum principles for anisotropic elliptic and parabolic equations, *Adv. Nonlinear Stud.* **12**(2012), 101–114. <https://doi.org/10.1515/ans-2012-0106>.