

## THE $Q$ -PROPERTY OF A MULTIPLICATIVE TRANSFORMATION IN SEMIDEFINITE LINEAR COMPLEMENTARITY PROBLEMS\*

R. BALAJI<sup>†</sup> AND T. PARTHASARATHY<sup>‡</sup>

**Abstract.** The  $Q$ -property of a multiplicative transformation  $AXA^T$  in semidefinite linear complementarity problems is characterized when  $A$  is normal.

**Key words.** Multiplicative transformations,  $Q$ -property, Complementarity.

**AMS subject classifications.** 90C33, 17C55.

**1. Introduction.** Let  $S^n$  be the space of all real symmetric matrices of order  $n$ . Suppose that  $L : S^n \rightarrow S^n$  is a linear transformation and  $Q \in S^n$ . We write  $X \succeq 0$ , if  $X$  is symmetric and positive semidefinite. The semidefinite linear complementarity problem,  $\text{SDLCP}(L, Q)$  is to find a matrix  $X$  such that

$$X \succeq 0, \quad Y := L(X) + Q \succeq 0, \quad \text{and} \quad XY = 0.$$

$\text{SDLCP}$  has various applications in control theory, semidefinite programming and other optimization related problems. We refer to [2] for details.  $\text{SDLCP}$  can be considered as a generalization of the standard linear complementarity problem [1]. However many results in the linear complementarity problem cannot be generalized to  $\text{SDLCP}$ , as the semidefinite cone is nonpolyhedral and the matrix multiplication is noncommutative.

We say that a linear transformation  $L$  defined on  $S^n$  has the  $Q$ -property if  $\text{SDLCP}(L, Q)$  has a solution for all  $Q \in S^n$ . Let  $A \in R^{n \times n}$ . Then the double sided multiplicative linear transformation  $M_A : S^n \rightarrow S^n$  is defined by  $M_A(X) := AXA^T$ . One of the problems in  $\text{SDLCP}$  is to characterize the  $Q$ -property of a multiplicative linear transformation. When  $A$  is a symmetric matrix, Sampangi Raman [6] proved that  $M_A$  has the  $Q$ -property if and only if  $A$  is either positive definite or negative definite and conjectured that the result holds when  $A$  is normal. In this paper, we prove this conjecture.

The transformation  $M_A$  has the following property:  $X \succeq 0 \Rightarrow M_A(X) \succeq 0$ . In other words, the multiplicative transformation leaves the positive semidefinite cone invariant. Using this interesting property, Gowda et al. [3] derived some specialized results for the multiplicative transformation. However, the problem of characterizing the  $Q$ -property of  $M_A$  remains open.

We recall a theorem due to Karamardian [5].

**THEOREM 1.1.** *Let  $L$  be a linear transformation on  $S^n$ . If  $\text{SDLCP}(L, 0)$  and  $\text{SDLCP}(L, I)$  have unique solutions then  $L$  has the  $Q$ -property.*

\*Received by the editors 6 September 2007. Accepted for publication 26 November 2007. Handling Editor: Michael J. Tsatsomeros.

<sup>†</sup>Department of Mathematics and Statistics, University of Hyderabad, Hyderabad 46, India (balaji149@gmail.com). Supported by a generous grant from NBHM.

<sup>‡</sup>Indian Statistical Institute, Chennai (pacha14@yahoo.com). Supported by INSA.

The following theorem is well known, see for example [3].

**THEOREM 1.2.** *Let  $A$  be a  $n \times n$  matrix. Then the following are equivalent:*

1.  $A$  is positive definite or negative definite.
2.  $\text{SDLCP}(M_A, Q)$  has a unique solution for all  $Q \in S^n$ .

We mention a few notations. If  $k$  is a positive integer, let  $I_k$  be the  $k \times k$  identity matrix. Let  $\text{SOL}(M_A, Q)$  be the set of all solutions to  $\text{SDLCP}(M_A, Q)$ . Suppose that  $F$  is a  $n \times n$  matrix. Then  $f_{ij}$  will denote the  $(i, j)$ -entry of  $F$ . Given a vector  $x \in R^n$ , we let  $\text{diag}(x)$  to denote the diagonal matrix with the vector  $x$  along its diagonal.

**2. Main Result.** We introduce the following definitions.

**DEFINITION 2.1.** Let  $A$  be a  $k \times k$  matrix. We say that  $A$  is of *type*( $*$ ), if  $A = I + B$  where  $B$  is a  $k \times k$  skew-symmetric matrix.

**EXAMPLE 2.2.** Let  $A := \begin{pmatrix} 1 & -5 \\ 5 & 1 \end{pmatrix}$ . Then  $A$  is a *type*( $*$ ) matrix.

**DEFINITION 2.3.** Let  $A \in R^{n \times n}$ . We say that  $A$  is of *form*( $n_1, n_2$ ), if there exist *type*( $*$ ) matrices  $S$  and  $T$  of order  $n_1$  and  $n_2$  respectively such that  $n_1 + n_2 = n$  and

$$A = \begin{pmatrix} S & 0 \\ 0 & -T \end{pmatrix}.$$

**DEFINITION 2.4.** Let  $m > 2$  and  $A \in R^{m \times m}$ . We say that  $A$  is of *form*( $*$ ), if there exists a skew-symmetric matrix  $W$  of order  $k \geq 2$  such that

$$A = \begin{pmatrix} W & 0 \\ 0 & \hat{A} \end{pmatrix},$$

where  $\hat{A} \in R^{(m-k) \times (m-k)}$ .

**DEFINITION 2.5.** We say that an  $n \times n$  symmetric matrix  $D = (d_{ij})$  is a *corner* matrix if its rank is one,  $d_{11}, d_{1n}, d_{n1}$  and  $d_{nn}$  are nonzero real numbers and all the remaining entries are zeros.

**DEFINITION 2.6.** We say that an  $n \times n$  symmetric matrix  $Q$  is of *type*( $n_1, n_2$ ), if  $Q$  is not positive semidefinite and there exist integers  $n_1$  and  $n_2$  and a rank one matrix  $Q_1 \in R^{n_1 \times n_2}$  such that  $n_1 + n_2 = n$  and  $Q = \begin{pmatrix} I_{n_1} & Q_1 \\ Q_1^T & I_{n_2} \end{pmatrix}$ .

Define

$$\tilde{Q} := \begin{pmatrix} I_{n-1} & q \\ q^T & 1 \end{pmatrix},$$

where  $q := (2, 0, \dots, 0)^T$ .

By the well-known formula of Schur,  $\det \tilde{Q} = -3$ . Therefore  $\tilde{Q}$  is not positive semidefinite. It is clear that if  $n_1$  and  $n_2$  are any two positive integers such that  $n_1 + n_2 = n$ , then  $\tilde{Q}$  can be written as a *type*( $n_1, n_2$ ) matrix. Throughout the paper, we use  $\tilde{Q}$  to denote this matrix.

We will make use of the following proposition. The proof is a direct verification.

**PROPOSITION 2.7.** *Let  $A \in R^{n \times n}$ . Then the following statements are true.*

1. If  $0 \in \text{SOL}(M_A, Q)$ , then  $Q \succeq 0$ .
2. Suppose that  $P$  is a nonsingular matrix. Then

$$X \in \text{SOL}(M_A, Q) \Leftrightarrow P^{-1}XP^{-T} \in \text{SOL}(M_{P^TAP}, P^TQP).$$

Thus  $M_A$  has the  $Q$ -property iff  $M_{PAP^T}$  has the  $Q$ -property.

3. If  $M_A$  has the  $Q$ -property, then  $A$  must be nonsingular.

We will use the following property of positive semidefinite matrices.

**THEOREM 2.8.** Suppose that  $X := \begin{pmatrix} X_1 & Y_1 \\ Y_1^T & Z_1 \end{pmatrix} \succeq 0$ . If  $X_1 = 0$  or  $Z_1 = 0$ , then  $Y_1 = 0$ .

We begin with the following lemma.

**LEMMA 2.9.** Suppose that  $U_1$  and  $U_2$  are orthogonal matrices of order  $n_1$  and  $n_2$  respectively where  $n_1 + n_2 = n$ . Let  $U = \begin{pmatrix} U_1 & 0 \\ 0 & U_2 \end{pmatrix}$ . If  $A \in R^{n \times n}$  is of form  $(n_1, n_2)$ , then  $UAU^T$  is of form  $(n_1, n_2)$ .

*Proof.* Let  $B := UAU^T$ . Then there exist *type*(\*) matrices  $S$  and  $T$  of order  $n_1$  and  $n_2$  respectively such that

$$A = \begin{pmatrix} S & 0 \\ 0 & -T \end{pmatrix}.$$

It is easy to see that

$$B = \begin{pmatrix} S_1 & 0 \\ 0 & -T_1 \end{pmatrix}$$

where  $S_1 = U_1SU_1^T$  and  $T_1 = U_2TU_2^T$ .

Let  $S = I_{n_1} + W$ , where  $W$  is a skew-symmetric matrix. Then  $W_1 := U_1WU_1^T$  will be skew-symmetric. Therefore  $S_1 = I_{n_1} + W_1$ . So  $S_1$  is of *type*(\*). Similarly,  $T_1$  is of *type*(\*). Thus  $B$  is of form  $(n_1, n_2)$ .  $\square$

**LEMMA 2.10.** Let  $A \in R^{n \times n}$ . Suppose  $X$  is a solution to  $\text{SDLCP}(M_A, P\tilde{Q}P^T)$ , where  $P$  is a permutation matrix. Then rank of  $X$  must be one.

*Proof.* Let  $\hat{Q} := P\tilde{Q}P^T$  and  $Y := AXA^T + \hat{Q}$ . Let  $K$  be the leading principal  $(n-1) \times (n-1)$  submatrix of  $Y$ . Then it can be easily verified that  $K$  is positive definite. Therefore the rank of  $Y$  must be at least  $n-1$ .

Since  $X \in \text{SOL}(M_A, \hat{Q})$ ,  $XY = 0$ . Suppose that  $U$  is a orthogonal matrix which diagonalize  $X$  and  $Y$  simultaneously. Let  $D = U XU^T$  and  $E = U Y U^T$ , where  $D$  and  $E$  are diagonal. Then  $DE = 0$ . The rank of  $E$  is at least  $n-1$ . Therefore the rank of  $D$  can be at most one. If  $D = 0$ , then  $X = 0$ . This implies that  $\hat{Q} \succeq 0$  (Proposition 2.7) which is a contradiction. This means that the rank of  $X$  is exactly one.  $\square$

**LEMMA 2.11.** Let  $A \in R^{n \times n}$ . Suppose that  $A$  is of form  $(n_1, n_2)$ . If  $X \in \text{SOL}(M_A, \tilde{Q})$  then there exists a form  $(n_1, n_2)$  matrix  $B$  and a *type*( $n_1, n_2$ ) matrix  $\hat{Q}$  such that  $\text{SDLCP}(M_B, \hat{Q})$  has a corner solution.

*Proof.* Write

$$X = \begin{pmatrix} X_1 & Y_1 \\ Y_1^T & Z_1 \end{pmatrix},$$

where  $X_1 \in S^{n_1 \times n_1}$  and  $Z_1 \in S^{n_2 \times n_2}$ . The above lemma implies that rank of  $X$  is one. Therefore rank of  $X_1$  can be at most one. We now claim that rank of  $X_1$  is exactly one. Let  $Y := AXA^T + \tilde{Q}$ .

Since  $A$  is of *form* $(n_1, n_2)$ , there exist *type* $(*)$  matrices  $S_1$  and  $S_2$  of order  $n_1$  and  $n_2$  respectively such that

$$A = \begin{pmatrix} S_1 & 0 \\ 0 & -S_2 \end{pmatrix}.$$

Now

$$\tilde{Q} = \begin{pmatrix} I_{n_1} & Q_1 \\ Q_1^T & I_{n_2} \end{pmatrix},$$

where  $Q_1$  is of rank one. Suppose  $X_1 = 0$ . Then Theorem 2.8 implies that  $Y_1 = 0$ . Thus,

$$AXA^T = \begin{pmatrix} 0 & 0 \\ 0 & S_2 Z_1 S_2^T \end{pmatrix}$$

and hence

$$Y = \begin{pmatrix} I_{n_1} & Q_1 \\ Q_1^T & S_2 Z_1 S_2^T + I_{n_2} \end{pmatrix}.$$

From the condition  $XY = 0$ , we see that

$$Z_1(S_2 Z_1 S_2^T + I_{n_2}) = 0.$$

This implies that  $Z_1 = 0$ ; so  $X = 0$ . Therefore  $\tilde{Q} \succeq 0$  (Proposition 2.7) which is a contradiction. Thus,  $X_1$  is of rank one. Similarly we can prove that  $Z_1$  and  $Y_1$  are of rank one.

Since  $X_1$  is a rank one matrix, we can find an orthogonal matrix  $U_1$  such that

$$D := U_1 X_1 U_1^T = \begin{pmatrix} d & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \cdots & \cdots & 0 \end{pmatrix},$$

where  $d > 0$ .

Let  $U_2$  be an orthogonal matrix such that

$$R := U_2 Z_1 U_2^T = \begin{pmatrix} 0 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \cdots & \cdots & r \end{pmatrix},$$

where  $r > 0$ . Let  $G = U_1 Y_1 U_2^T$ . Then rank of  $G$  must be one as rank of  $Y_1$  is one. Define

$$U := \begin{pmatrix} U_1 & 0 \\ 0 & U_2 \end{pmatrix}.$$

Then  $U$  is orthogonal. Let  $Z := UXU^T$ . Now

$$Z = \begin{pmatrix} D & G \\ G^T & R \end{pmatrix}.$$

Since  $Z \succeq 0$ , by Theorem 2.8,

$$Z = \begin{pmatrix} d & 0 & \dots & 0 & e \\ 0 & 0 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ e & 0 & \dots & 0 & r \end{pmatrix}.$$

As  $G$  is of rank one,  $e$  is nonzero. Thus  $Z$  is a *corner* matrix.

Let  $B := UAU^T$ . Then by Proposition 2.7,  $Z$  is a solution to  $\text{SDLCP}(M_B, \widehat{Q})$ , where  $\widehat{Q} := U\widetilde{Q}U^T$ . By Lemma 2.9,  $B$  must be of *form* $(n_1, n_2)$ . It is direct to verify that  $\widehat{Q}$  is of *type* $(n_1, n_2)$ . This completes the proof.  $\square$

LEMMA 2.12. *Let  $Q$  be a  $m \times n$  matrix defined as follows:*

$$Q = \begin{pmatrix} 0 & 0 & \dots & 0 & \pm 1 \\ q_{21} & q_{22} & \dots & q_{2n-1} & 0 \\ \dots & \dots & \dots & \dots & \dots \\ q_{m1} & q_{m2} & \dots & q_{mn-1} & 0 \end{pmatrix}.$$

*Suppose the rank of  $Q$  is one. Then the submatrix of  $Q$  obtained by deleting the first row and the last column is a zero matrix.*

*Proof.* We claim that  $q_{21} = 0$ . Consider the  $2 \times 2$  submatrix

$$\begin{pmatrix} 0 & \pm 1 \\ q_{21} & 0 \end{pmatrix}.$$

Since  $Q$  is of rank one,  $q_{21} = 0$ . By repeating a similar argument for the remaining entries we get the result.  $\square$

LEMMA 2.13. *Suppose that  $\widehat{B}$  is of *form* $(n_1, n_2)$ . Let  $\widehat{Q}$  be a *type* $(n_1, n_2)$  matrix. Then a corner matrix cannot be a solution to  $\text{SDLCP}(M_{\widehat{B}}, \widehat{Q})$ .*

*Proof.* Since  $\widehat{B}$  is of *form* $(n_1, n_2)$ , there exist *type* $(*)$  matrices  $B$  and  $C$  of order  $n_1$  and  $n_2$  respectively such that

$$\widehat{B} = \begin{pmatrix} B & 0 \\ 0 & -C \end{pmatrix}.$$

Let  $B = (b_{ij})$  and  $C = (c_{ij})$ . Then  $b_{ii} = c_{ii} = 1$ . Every off-diagonal entry of  $B$  and  $C$  will now satisfy  $b_{ij} + b_{ji} = 0$  and  $c_{ij} + c_{ji} = 0$ .

Suppose that  $X$  is a *corner* matrix and solves  $\text{SDLCP}(M_{\widehat{B}}, \widehat{Q})$ . Let

$$X = \begin{pmatrix} d & 0 & \dots & 0 & e \\ 0 & 0 & \dots & 0 & 0 \\ \dots & \dots & \dots & \dots & \dots \\ e & 0 & \dots & 0 & r \end{pmatrix}.$$

Let  $\widehat{Q} = \begin{pmatrix} I_{n_1} & Q_1 \\ Q_1^T & I_{n_2} \end{pmatrix}$  where

$$Q_1 = \begin{pmatrix} q_{11} & q_{12} & \dots & q_{1n_2} \\ q_{21} & q_{22} & \dots & q_{2n_2} \\ \dots & \dots & \dots & \dots \\ q_{n_11} & q_{n_12} & \dots & q_{n_1n_2} \end{pmatrix}.$$

Suppose that  $Y := \widehat{B}X\widehat{B}^T + \widehat{Q}$ . Then

$$Y = \begin{pmatrix} d+1 & * & \dots & * & q_{1n_2} - e \\ -b_{12}d & * & \dots & * & b_{12}e + q_{2n_2} \\ \dots & \dots & \dots & * & \dots \\ -b_{1n_1}d & * & \dots & * & b_{1n_1}e + q_{n_1n_2} \\ c_{1n_2}e + q_{11} & * & \dots & * & -c_{1n_2}r \\ c_{2n_2}e + q_{12} & * & \dots & * & -c_{2n_2}r \\ \dots & \dots & \dots & * & \dots \\ -e + q_{1n_2} & * & \dots & * & r+1 \end{pmatrix}.$$

Suppose that  $y_1, y_2, \dots, y_n$  are the columns of  $Y$  and  $x_1, x_2, \dots, x_n$  are the columns of  $X$ . Since  $X$  is a solution to  $\text{SDLCP}(M_{\widehat{B}}, \widehat{Q})$ ,  $XY = 0$ . Therefore for all  $i \in \{1, \dots, n\}$  and  $j \in \{1, \dots, n\}$ , we must have  $y_i^T x_j = 0$ .

From the equations  $y_1^T x_1 = 0$  and  $y_n^T x_n = 0$ , we have

$$(2.1) \quad d(d+1) + e(q_{1n_2} - e) = 0,$$

$$(2.2) \quad r(r+1) + e(q_{1n_2} - e) = 0.$$

Equations (2.1) and (2.2) imply that

$$d(d+1) = r(r+1).$$

As  $d$  and  $r$  are positive,  $d = r$ . Since  $X$  is a *corner* matrix, rank of  $X$  must be one and hence

$$d = r = \pm e.$$

Now  $d^2 = e^2$ , and therefore from (2.1) we have

$$q_{1n_2} = \pm 1.$$

Let  $i \in \{2, \dots, n_1\}$ . Then  $y_i^T x_1 = 0$  gives

$$-b_{1i}d^2 + b_{1i}e^2 + q_{in_2}e = 0.$$

As  $d^2 = e^2$  and  $e$  is nonzero,

$$q_{in_2} = 0.$$

Thus the last column of  $Q_1$  is  $(\pm 1, 0, \dots, 0)^T$ .

Let  $i \in \{1, \dots, n_2 - 1\}$ . Then

$$c_{in_2}ed + q_{1i}d - c_{in_2}re = 0.$$

Using  $r = d$ , we have

$$q_{1i} = 0.$$

Thus the first row of  $Q_1$  is  $(0, \dots, 0, \pm 1)$ .

Now  $\widehat{Q}$  is a  $type(n_1, n_2)$  matrix and hence  $Q_1$  is of rank one. Thus  $Q_1$  satisfies the conditions of Lemma 2.12 and therefore the submatrix obtained by deleting the first row and last column of  $Q_1$  is a zero matrix. Thus

$$\widehat{Q} = \begin{pmatrix} I_{n-1} & e \\ e^T & 1 \end{pmatrix},$$

where  $e$  is the  $n - 1$  vector  $(\pm 1, 0, \dots, 0)^T$ .

If  $x \in R^n$ , then

$$x^T \widehat{Q} x = (x_1 \pm x_n)^2 + \sum_{i=2}^{n-1} x_i^2 \geq 0.$$

Hence  $\widehat{Q} \succeq 0$ . This contradicts that  $\widehat{Q}$  is a  $type(n_1, n_2)$  matrix. This completes the proof.  $\square$

Lemmas 2.11 and 2.13 now implies the following result.

LEMMA 2.14. *Let  $A$  be a  $form(n_1, n_2)$  matrix. Then  $M_A$  cannot have the  $Q$ -property.*

We now claim that a skew-symmetric matrix cannot have  $Q$ -property.

LEMMA 2.15. *If  $A$  is a  $n \times n$  skew-symmetric matrix, then  $SDLCP(M_A, \widetilde{Q})$  has no solution.*

*Proof.* Suppose that  $X$  is a solution. Then the rank of  $X$  must be one. Therefore  $X = xx^T$  for some vector  $x \in R^n$ . By the skew-symmetry of  $A$ ,  $x^T Ax = 0$ ; hence  $XAX = 0$ . Now  $X(AXA^T + \widetilde{Q}) = 0$ . So  $X\widetilde{Q} = 0$ . Since  $\widetilde{Q}$  is nonsingular,  $X = 0$ . This implies that  $\widetilde{Q} \succeq 0$  (Proposition 2.7) which is a contradiction.  $\square$

LEMMA 2.16. *Let  $A \in R^{n \times n}$ . If  $A$  is a  $form(*)$  matrix, then  $M_A$  cannot have the  $Q$ -property.*

*Proof.* Suppose that  $M_A$  has the  $Q$ -property. Since  $A$  is of  $form(*)$ ,

$$A = \begin{pmatrix} W & 0 \\ 0 & B \end{pmatrix},$$

where  $W$  is skew-symmetric of order  $k \geq 2$  and  $B$  is of order  $l$ .

Define a  $k \times k$  matrix by

$$Q_{11} = \begin{pmatrix} I_{k-1} & p \\ p^T & 1 \end{pmatrix},$$

where  $p := (2, 0, \dots, 0)^T$ .

Now define

$$Q' = \begin{pmatrix} Q_{11} & 0 \\ 0 & I_l \end{pmatrix}.$$

Note that there exists a permutation matrix  $P$  such that  $P\tilde{Q}P^T = Q'$ . Suppose that  $X$  is a solution to  $\text{SDLCP}(M_A, Q')$ . Write

$$X = \begin{pmatrix} X_1 & X_2 \\ X_2^T & X_3 \end{pmatrix},$$

where  $X_1$  is of order  $k$ .

Suppose that  $X_3 = 0$ . Then, as  $X \succeq 0$ ,  $X_2 = 0$ .

Now

$$AXA^T + Q' = \begin{pmatrix} WX_1W^T + Q_{11} & 0 \\ 0 & I_l \end{pmatrix}.$$

It is now easy to verify that  $X_1$  is a solution to  $\text{SDLCP}(M_W, Q_{11})$ . However by applying the previous lemma, we see that  $\text{SDLCP}(M_W, Q_{11})$  has no solution. Thus, we have a contradiction. Therefore  $X_3$  cannot be zero.

In view of Lemma 2.10, rank of  $X$  must be one. Hence the rank of  $X_1$  can be at most one and the rank of  $X_3$  is exactly one.

Let  $U_1$  be an orthogonal matrix such that

$$U_1 X_1 U_1^T = \begin{pmatrix} d & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & 0 \end{pmatrix},$$

and  $U_2$  be an orthogonal matrix such that

$$U_2 X_3 U_2^T = \begin{pmatrix} 0 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & r \end{pmatrix}.$$

Define an orthogonal matrix  $U$  by

$$U := \begin{pmatrix} U_1 & 0 \\ 0 & U_2 \end{pmatrix}.$$



Suppose that  $Z := UXU^T$ . Then by Theorem 2.8

$$Z = \begin{pmatrix} d & 0 & \dots & e \\ 0 & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ e & 0 & \dots & r \end{pmatrix}.$$

Note that  $r > 0$ . Now  $Z$  is a solution to  $\text{SDLCP}(M_{UAU^T}, UQ'U^T)$ . Suppose that  $Y := M_{UAU^T} + UQ'U^T$ .

Now

$$UQ'U^T = \begin{pmatrix} U_1Q_{11}U_1^T & 0 \\ 0 & I_l \end{pmatrix} \quad \text{and} \quad UAU^T = \begin{pmatrix} U_1WU_1^T & 0 \\ 0 & U_2BU_2^T \end{pmatrix}.$$

Let  $\alpha$  be the  $(n, n)$ -entry of  $UBU^T$ . Clearly,  $U_1WU_1^T$  is skew-symmetric. Let the last row of  $Y$  be the vector  $\mathbf{y} := (y_1, \dots, y_n)^T$ . Then by a direct verification,  $y_1 = 0$  and  $y_n = \alpha^2r + 1$ . By the complementarity condition,  $\mathbf{y}$  is orthogonal to  $(e, 0, \dots, 0, r)^T$ . Thus,  $r(\alpha^2r + 1) = 0$ , which is a contradiction. This completes the proof.  $\square$

The next result is apparent from Theorem 2.5.8 in Horn and Johnson [4]; hence we omit the proof.

LEMMA 2.17. *Suppose that  $A \in R^{n \times n}$  is a nonsingular normal matrix. If  $A$  is neither positive definite nor negative definite, then one of the following statements must be true:*

1. *There exists a nonsingular matrix  $Q$  and positive integers  $n_1$  and  $n_2$  such that  $QAQ^T$  is of form  $(n_1, n_2)$ .*
2. *There exists a nonsingular matrix  $Q$  such that  $QAQ^T$  is a form  $(*)$  matrix.*
3.  *$A$  is skew-symmetric.*

Now the following theorem which is our main result follows from item (2) of Proposition 2.7 and the above results.

THEOREM 2.18. *Let  $A \in R^{n \times n}$  be normal. Then the following are equivalent:*

- (i)  *$\pm A$  is positive definite.*
- (ii)  *$\text{SDLCP}(M_A, Q)$  has a unique solution for all  $Q \in S^n$ .*
- (iii)  *$M_A$  has the  $Q$ -property.*

**Acknowledgment.** We wish to thank Professor Seetharama Gowda for his comments and suggestions.

#### REFERENCES

- [1] R. Cottle, J.-S. Pang, and R.E. Stone. *The Linear Complementarity Problem*. Academic Press, Boston, 1992.
- [2] M.S. Gowda and Y. Song. On semidefinite linear complementarity problems. *Mathematical Programming A*, 88:575–587, 2000.
- [3] M.S. Gowda, Y. Song, and G. Ravindran. On some interconnections between strict monotonicity, globally uniquely solvable, and P properties in semidefinite linear complementarity problems. *Linear Algebra and its Applications*, 370:355-368, 2003.
- [4] R.A. Horn and C.R. Johnson. *Matrix Analysis*. Cambridge University press, Cambridge, 1985.

- [5] S. Karamardian. An existence theorem for the complementarity problem. *Journal of Optimization Theory and its Applications*, 19:227–232, 1976.
- [6] D. Sampangi Raman. Some contributions to semidefinite linear complementarity problems. Ph.D. Thesis, Indian Statistical Institute, Kolkata, 2002.