

NORM ESTIMATES FOR FUNCTIONS OF TWO NON-COMMUTING MATRICES*

MICHAEL GIL'

Abstract. A class of matrix valued analytic functions of two non-commuting matrices is considered. A sharp norm estimate is established. Applications to matrix and differential equations are also discussed.

Key words. Functions of non-commuting matrices, Norm estimate, Matrix equation, Differential equation.

AMS subject classifications. 15A54, 15A45, 15A60

1. Introduction and statement of the main result. In the book [5], I.M. Gel'fand and G.E. Shilov have established an estimate for the norm of a regular matrix-valued function in connection with their investigations of partial differential equations. However, that estimate is not sharp; it is not attained for any matrix. The problem of obtaining a sharp estimate for the norm of a matrix-valued function has been repeatedly discussed in the literature, cf. [2]. In the paper [6] (see also [7]), the author has derived an estimate for regular matrix-valued functions, which is attained in the case of normal matrices. In [8], the results of the paper [6] were generalized to functions of two commuting matrices. In the present paper, we establish a sharp estimate for the norm of a matrix-valued function of two non-commuting matrices.

It should be noted that functions of many operators were investigated by many mathematicians, (cf. [1, 15, 16] and references therein) however the norm estimates were not considered, but as it is well-known, matrix valued functions give us representations of solutions of various differential, difference equations and matrix equations. This fact allows us to investigate stability, well-posedness and perturbations of these equations by norm estimates for matrix valued functions, cf. [2].

Let \mathbb{C}^n be the Euclidean space with scalar product (\cdot,\cdot) , the Euclidean norm $\|\cdot\| = \sqrt{(\cdot,\cdot)}$ and the unit operator I. Unless otherwise stated A, K and \tilde{A} will be $n \times n$ matrices. $\|A\| = \sup_{h \in \mathbb{C}^n} \|Ah\|/\|h\|$ is the spectral (operator) norm of A. By $\sigma(A)$ and $R_z(A) = (A - zI)^{-1}$ $(z \notin \sigma(A))$ we denote the spectrum and resolvent of A, respectively.

^{*}Received by the editors on December 23, 2010. Accepted for publication on May 14, 2011. Handling Editor: Harm Bart.

[†]Department of Mathematics, Ben Gurion University of the Negev, PO Box 653, Beer-Sheva 84105, Israel (gilmi@bezeqint.net).

Functions of Non-Commuting Matrices

Let Ω_A and $\Omega_{\tilde{A}}$ be open simple connected supersets of $\sigma(A)$ and $\sigma(\tilde{A})$, respectively, and f be a scalar function analytic on $\Omega_A \times \Omega_{\tilde{A}}$. We define the matrix valued function

$$F(f, A, K, \tilde{A}) := -\frac{1}{4\pi^2} \int_{C_{\tilde{A}}} \int_{C_A} f(z, w) R_z(A) K R_w(\tilde{A}) dw dz, \tag{1.1}$$

where $C_A \subset \Omega_A, C_{\tilde{A}} \subset \Omega_{\tilde{A}}$ are closed contour surrounding $\sigma(A)$ and $\sigma(\tilde{A})$, respectively. Such functions play an essential role in the theory of matrix equations. More specifically, consider the matrix equation

$$\sum_{j=0}^{m_1} \sum_{k=0}^{m_2} c_{jk} A^j X \tilde{A}^k = K, \tag{1.2}$$

where X should be found and c_{ik} are complex numbers. Put

$$p(z, w) = \sum_{j=0}^{m_1} \sum_{k=0}^{m_2} c_{jk} z^j \tilde{w}^k.$$

Then by Theorem 3.1 from [2, Chapter 1] a unique solution of equation (1.2) is given by the formula

$$X = F\left(\frac{1}{p(z,w)}, A, K, \tilde{A}\right) \tag{1.3}$$

provided $\lambda_k \neq \tilde{\lambda}_j$ (j, k = 1, ..., n). Throughout the rest of this paper λ_k and $\tilde{\lambda}_j$ are the eigenvalues counted with their multiplicities of A and \tilde{A} , respectively. Equations of the type (1.2) naturally arose in various applications, cf. [2, 14, 12]. The Lyapunov equation $A^*X + XA = K$, cf. [2], and the Lyapunov type equation

$$X + A^*XA = K (1.4)$$

which play an important role in the theory of difference equations, cf. [9] are the examples of equation (1.2). These equations recently attracted the attention of many mathematicians. Mainly, numerical methods for the solutions of matrix equations were developed, cf. [11, 13, 17]. In the paper [3], reflexive and anti-reflexive solutions of a linear matrix equation were explored. No estimates were established for solutions of these equations. Furthermore, suppose that

$$T(t) := -\frac{1}{4\pi^2} \int_{C_{\tilde{A}}} \int_{C_A} e^{t(z+w)} R_z(A) K R_w(\tilde{A}) dw \ dz. \tag{1.5}$$

Take into account that $zR_z(A) = AR_z(A) - I$. Then simple calculations show that

$$T'(t) = -\frac{1}{4\pi^2} \int_{C_{\tilde{A}}} \int_{C_A} (z+w)e^{t(z+w)} R_z(A) K R_w(\tilde{A}) dw \ dz =$$

505



506 M.I. Gil'

$$-\frac{1}{4\pi^2}\int_{C_{\tilde{A}}}\int_{C_A}e^{t(z+w)}[AR_z(A)KR_w(\tilde{A})+R_z(A)KR_w(\tilde{A})\tilde{A}]dw\ dz.$$

So

$$T'(t) = AT(t) + T(t)\tilde{A}. \tag{1.6}$$

Such equations arise in numerous applications, in particular in the theory of vector differential equations, cf. [10, p. 509], [2, Section VI.4, equation (4.15) and Section VI.2], [4, Section XV.10]. Additional examples are given in Section 3.

The following quantity plays a key role in this article:

$$g(A) = \left[N_2^2(A) - \sum_{k=1}^n |\lambda_k|^2 \right]^{1/2},$$

where $N_2(A) = (Trace \ AA^*)^{1/2}$ is the Frobenius (Hilbert-Schmidt norm) of A. Here, A^* is adjoint to A. The following relations are checked in [7, Section 2.1]:

$$g^{2}(A) \le N_{2}^{2}(A) - |Trace A^{2}| \text{ and } g^{2}(A) \le \frac{N_{2}^{2}(A - A^{*})}{2} = 2N_{2}^{2}(A_{I}),$$
 (1.7)

where $A_I = (A - A^*)/2i$. If A is a normal matrix: $AA^* = A^*A$, then g(A) = 0.

By co(A) we denote the closed convex hull of $\sigma(A)$. Let f(z, w) be regular on a neighborhood of $co(A) \times co(\tilde{A})$. Put

$$f^{(j,k)}(z,w) = \frac{\partial^{j+k} f(z,w)}{\partial z^j \partial w^k},$$

and let the numbers $\eta_{jk} = \eta_{jk}(f, A, \tilde{A})$ be given by

$$\eta_{00} = \sup_{z \in \sigma(A), w \in \sigma(\tilde{A})} |f(z, w)|; \eta_{jk} = \frac{1}{(j!k!)^{3/2}} \sup_{z \in co(A), w \in co(\tilde{A})} |f^{(j,k)}(z, w)|;$$

$$\eta_{0j} := \frac{1}{(j!)^{3/2}} \sup_{z \in \sigma(A), w \in co(\tilde{A})} \left| \frac{\partial^j f(z, w)}{\partial w^j} \right|,$$

and

$$\eta_{j0} := \frac{1}{(j!)^{3/2}} \sup_{z \in co(A), w \in \sigma(\tilde{A})} \left| \frac{\partial^j f(z, w)}{\partial z^j} \right| \quad (j, k \ge 1).$$

Now we are in a position to formulate the main result of the paper.



Functions of Non-Commuting Matrices

THEOREM 1.1. Let both A and \tilde{A} be non-normal matrices and f(z, w) be regular on a neighborhood of $co(A) \times co(\tilde{A})$. Then

$$||F(f, A, K, \tilde{A})|| \le N_2(K) \sum_{j,k=0}^{n-1} \eta_{jk} g^j(A) g^k(\tilde{A}).$$

If A is normal, \tilde{A} is non-normal and f(z, w) is regular on a neighborhood of $\sigma(A) \times co(\tilde{A})$, then

$$||F(f, A, K, \tilde{A})|| \le N_2(K) \sum_{i=0}^{n-1} \eta_{0j} g^j(\tilde{A}).$$

If \tilde{A} is normal, A is non-normal and f(z,w) is regular on a neighborhood of $\sigma(\tilde{A}) \times co(A)$, then

$$||F(f, A, K, \tilde{A})|| \le N_2(K) \sum_{j=0}^{n-1} \eta_{j0} g^j(A).$$

If both A and \tilde{A} are normal and f(z, w) is regular on a neighborhood of $\sigma(A) \times \sigma(\tilde{A})$, then

$$||F(f, A, K, \tilde{A})|| \le N_2(K) \max_{j,k} |f(\lambda_j, \tilde{\lambda}_k)|.$$

2. Proof of Theorem 1.1. We need the following result proved in [8].

LEMMA 2.1. Let Ω and $\tilde{\Omega}$ be the closed convex hulls of the complex points x_0, x_1, \ldots, x_n and y_0, y_1, \ldots, y_m , respectively, and let a scalar-valued function f(z, w) be regular on a neighborhood of $\Omega \times \tilde{\Omega}$. Additionally, let L and \tilde{L} be the boundaries of Ω and $\tilde{\Omega}$, respectively. Then with the notation

$$Y(x_0, \dots, x_n; y_0, \dots, y_m) = -\frac{1}{4\pi^2} \int_L \int_{\tilde{L}} \frac{f(z, w) dz dw}{(z - x_0) \cdots (z - x_n)(w - y_0) \cdots (w - y_m)},$$

we have

$$|Y(x_0,\ldots,x_n; y_0,\ldots,y_m)| \le \frac{1}{n!m!} \sup_{z \in \Omega, w \in \tilde{\Omega}} |f^{(n,m)}(z,w)|.$$

Let $\{e_k\}$ and $\{\tilde{e}_k\}$ be the orthogonal normal bases of the triangular representation (Schur's bases) to A and \tilde{A} , respectively. So,

$$Ae_k = \sum_{j=1}^k a_{jk} e_j.$$

507



508 M.I. Gil

We can write

$$A = D_A + V_A, \quad \tilde{A} = D_{\tilde{A}} + V_{\tilde{A}}, \tag{2.1}$$

where $D_A, D_{\tilde{A}}$ are the diagonal parts, V_A and $V_{\tilde{A}}$ are the nilpotent parts of A and \tilde{A} , respectively. Namely,

$$D_A e_k = \lambda_k e_k; \ V_A e_k = \sum_{j=1}^{k-1} a_{jk} e_j.$$

Similarly, $D_{\tilde{A}}$ and $V_{\tilde{A}}$ are defined. Furthermore, let $|V_A|$ be the operator whose entries in $\{e_k\}$ are the absolute values of the entries of a matrix V_A . That is, $(|V_A|e_j,e_k) = |(V_Ae_j,e_k)|$ and

$$|V_A| = \sum_{k=1}^n \sum_{j=1}^{k-1} |a_{jk}| (\cdot, e_k) e_j.$$

Similarly, $|V_{\tilde{A}}|$ is defined with respect to $\{\tilde{e}_k\}$. In addition, |K| is defined by

$$|K|\tilde{e}_j = \sum_{k=1}^n |(K\tilde{e}_j, e_k)| e_k.$$

LEMMA 2.2. Under the hypothesis of Theorem 1.1, the inequality

$$||F(f, A, K, \tilde{A})|| \le |||K||| \sum_{j,k=1}^{n-1} \sqrt{k!j!} \eta_{jk} |||V_{\tilde{A}}|^{j} ||| ||V_{\tilde{A}}|^{k} ||$$

is true, where V_A and $V_{\tilde{A}}$ are the nilpotent parts of A and \tilde{A} , respectively.

Proof. It is not hard to see that the representation (2.1) implies the equality

$$(A - I\lambda)^{-1} = (D_A + V_A - \lambda I)^{-1} = (I + R_\lambda (D_A)V_A)^{-1}R_\lambda (D_A)$$

for all regular λ . According to Lemma 1.7.1 from [7] $R_{\lambda}(D_A)V_A$ is a nilpotent operator, because V_A and $R_{\lambda}(D_A)$ the same invariant subspaces. Hence, $(R_{\lambda}(D_A)V_A)^n = 0$. Therefore, from (1.1) it follows

$$F(f, A, K, \tilde{A}) = \sum_{j,k=0}^{n-1} M_{jk}, \tag{2.2}$$

 $_{
m where}$

$$M_{jk} = \frac{(-1)^{k+j}}{4\pi^2} \int_{C_{\tilde{A}}} \int_{C_A} f(z, w) (R_z(D_A) V_A)^j R_z(D_A) K(R_w(D_{\tilde{A}}) V_{\tilde{A}})^k R_w(D_{\tilde{A}}) dz \ dw.$$

509

Since D_A is a diagonal matrix with respect to the Schur basis $\{e_k\}$ and its diagonal entries are the eigenvalues of A, we obtain

$$R_z(D_A) = \sum_{j=1}^n \frac{Q_j}{\lambda_j(A) - z},$$

where $Q_k = (\cdot, e_k)e_k$. Similarly,

$$R_z(D_{\tilde{A}}) = \sum_{j=1}^n \frac{\tilde{Q}_j}{\lambda_j(\tilde{A}) - z},$$

where $\tilde{Q}_k = (\cdot, \tilde{e}_k)\tilde{e}_k$. Taking into account that $Q_sV_AQ_m = 0$, $\tilde{Q}_sV_{\tilde{A}}\tilde{Q}_m = 0$ $(s \ge m)$, we get

$$M_{jk} = \sum_{1 \le s_1 < s_2 < \dots < s_{j+1} \le n} Q_{s_1} V_A Q_{s_2} V_A \cdots V_A Q_{s_{j+1}} K \times Q_{s_{j+1}} V_A Q_{s_2} V_A \cdots V_A Q_{s_{j+1}} V_A$$

$$\times \sum_{1 \le m_1 < m_2 < \dots < m_{k+1} \le n} \tilde{Q}_{m_1} V_{\tilde{A}} \tilde{Q}_{m_2} V_{\tilde{A}} \cdots V_{\tilde{A}} \tilde{Q}_{m_{k+1}} \hat{I}(s_1, \dots, s_{j+1}, m_1, \dots, m_{k+1}),$$

where $0 \le j, k \le n-1$ and

$$\hat{I}(s_1,\ldots,s_{j+1},m_1,\ldots m_{k+1}) =$$

$$\frac{(-1)^{k+j}}{4\pi^2} \int_{C_A} \int_{C_{\tilde{A}}} \frac{f(z,w)dz \, dw}{(\lambda_{s_1}(A) - z) \cdots (\lambda_{s_{k+1}}(A) - z)(\lambda_{m_1}(\tilde{A}) - w) \cdots (\lambda_{m_{k+1}}(\tilde{A}) - w)}.$$

Hence, with $M_{jk} = M$, we have

$$|(M\tilde{e}_m, e_s)| = |\sum_{s < s_2 < \dots < s_{j+1} \le n} \sum_{1 \le m_1 < m_2 < \dots < m} \hat{I}(s, \dots, s_{j+1}, m_1, \dots, m) \times |$$

$$\times (Q_s V_A Q_{s_2} V_A \cdots V_A Q_{s_{j+1}} K \tilde{Q}_{m_1} V_{\tilde{A}} \tilde{Q}_{m_2} V_{\tilde{A}} \cdots V_{\tilde{A}} \tilde{Q}_m \tilde{e}_m, e_s)| \leq J_{jk} \sum_{s < s_2 < \cdots < s_{j+1} < n} V_{\tilde{A}} \tilde{Q}_m \tilde{e}_m, e_s = 0$$

$$\times \sum_{1 < m_1 < m_2 < \dots < m} (Q_s | V_A | Q_{s_2} | V_A | \dots Q_{s_{j+1}} | K | \tilde{Q}_{m_1} | V_{\tilde{A}} | \tilde{Q}_{m_2} | V_{\tilde{A}} | \dots \tilde{Q}_m \tilde{e}_m, e_s),$$

where

$$J_{jk} := \max_{1 \le s_1 < \dots < s_{j+1} \le n; 1 \le m_1 < \dots < m_{k+1} \le n} |\hat{I}(s_1, \dots, s_{j+1}, m_1, \dots m_{k+1})|.$$



510 M.I. Gil'

Thus $|(M\tilde{e}_m, e_s)| \leq (T\tilde{e}_m, e_s)$, where

$$T = J_{jk} \sum_{s_1 < s_2 < \dots < s_{j+1} \le n} \sum_{1 \le m_1 < m_2 < \dots < m_{k+1} \le n} Q_{s_1} |V_A| Q_{s_2} |V_A| \cdots |V_A| Q_{s_{j+1}} |K| \times C_{s_{j+1}} |V_A| Q_{s_{j+1}} |V_A| Q_{$$

$$\times \tilde{Q}_{m_1} |V_{\tilde{A}}| \tilde{Q}_{m_2} |V_{\tilde{A}}| \cdots |V_{\tilde{A}}| \tilde{Q}_{m_{k+1}}. \tag{2.3}$$

Take into account that

$$Mx = \sum_{k=1}^{n} (x, \tilde{e}_k) M \tilde{e}_k = \sum_{j=1}^{n} \sum_{k=1}^{n} (x, \tilde{e}_k) (M \tilde{e}_k, e_j) e_j \quad (x \in \mathbb{C}^n).$$

So

$$||Mx||^2 = \sum_{j=1}^n \left| \sum_{k=1}^n (x, \tilde{e}_k) (M\tilde{e}_k, e_j) \right|^2 \le$$

$$\sum_{j=1}^{n} \left(\sum_{k=1}^{n} (x, \tilde{e}_k) (T\tilde{e}_k, e_j) \right)^2.$$

Since ||x|| = ||y|| for

$$y = \sum_{k=1}^{n} |(x, \tilde{e}_k)| \tilde{e}_k,$$

we obtain $||M|| \leq ||T||$. But

$$\sum_{1 \le s_1 < s_2 < \dots < s_{j+1} \le n} Q_{s_1} |V_A| Q_{s_2} |V_A| \cdots |V_A| Q_{s_{j+1}} = |V_A|^j$$

and

$$\sum_{1 < m_1 < m_2 < \dots < m_{k+1} < n} \tilde{Q}_{m_1} |V_{\tilde{A}}| \tilde{Q}_{m_2} |V_{\tilde{A}}| \cdots |V_{\tilde{A}}| Q_{m_{k+1}} = |V_{\tilde{A}}|^k.$$

So by (2.3)

$$||M_{ik}|| \le ||T|| \le J_{ik}|| |V_A|^j |K| |V_{\tilde{A}}|^k || (j, k \ge 0).$$
(2.4)

Due to Lemma 2.1

$$J_{jk} \le \sup_{z \in co(A), w \in co(\tilde{A})} \frac{|f^{(j,k)}(z,w)|}{j!k!} = \sqrt{j!k!}\eta_{jk} \ (j,k \ge 1).$$



$$||M_{jk}|| \le \sqrt{j!k!}\eta_{jk}|| |V_A|^j |K||V_{\tilde{A}}|^k || (j,k \ge 0).$$
 (2.5)

This inequality and (2.2) imply the required result. \square

Proof of Theorem 1.1. Theorem 2.5.1 from [7] implies

$$||W^k|| \le \frac{1}{\sqrt{k!}} N_2^k(W)$$
 (2.6)

for any $n \times n$ nilpotent matrix W. Take into account that $N_2(|V_A|) = N_2(V_A)$. Moreover, by Lemma 2.3.2 from [7], $N_2(V_A) = g(A)$. Thus,

$$||V_A|^k|| \le \frac{1}{\sqrt{k!}} g^k(A) \quad (k = 1, \dots, n-1).$$

The similar inequality holds for $V_{\tilde{A}}.$ In addition,

$$N_2^2(|K|) = \sum_{j=1}^n ||K|\tilde{e}_j||^2 = \sum_{j=1}^n \sum_{k=1}^n |(K\tilde{e}_j, e_k)|^2 = \sum_{j=1}^n \sum_{k=1}^n ||K\tilde{e}_j||^2 = N_2^2(K).$$

Now the previous lemma yields the required result. \Box

3. Examples. Consider the equation

$$AX - X\tilde{A} = K \tag{3.1}$$

assuming that

Thus,

$$\delta := dist (co(A), co(\tilde{A})) > 0.$$

Take $f(z, w) = \frac{1}{z-w}$. Then

$$\eta_{jk} \le \frac{(k+j)!}{\delta^{j+k+1} (k!j!)^{3/2}} \quad (j,k=0,1,\ldots,n-1).$$

Hence, by Theorem 1.1 and (1.3) a solution of (3.1) satisfies the inequality

$$||X|| \le N_2(K) \sum_{j,k=0}^{n-1} \frac{(k+j)!}{\delta^{j+k+1} (k!j!)^{3/2}} g^j(A) g^k(\tilde{A}).$$

Finally, consider the function

$$S(x) := -\frac{1}{4\pi^2} \int_{C_z} \int_{C_A} \sin \left(x(z+w) \right) R_z(A) K R_w(\tilde{A}) dw \ dz \ (x \in \mathbb{R}).$$

511



512 M.I. Gil'

We have

$$S''(x) = \frac{1}{4\pi^2} \int_{C_{\tilde{A}}} \int_{C_A} (z+w)^2 \sin(x(z+w)) R_z(A) K R_w(\tilde{A}) dw dz.$$

But $zR_z(A) = AR_z(A) - I$ and therefore,

$$z^{2}R_{z}(A) = zAR_{z}(A) - zI = A(AR_{z}(A) - I) - zI = A^{2}R_{z}(A) - I - zI.$$

So, S(x) is a solution of the equation

$$S'' = A^2S + AS\tilde{A} + S\tilde{A}^2.$$

REFERENCES

- R. Arens and A.P. Calderon. Analytic functions of several Banach algebra elements. Ann. Math., 62:204–216, 1955.
- [2] Yu.L. Daleckii and M.G. Krein. Stability of Solutions of Differential Equations in Banach Space. Translations of Mathematical Monographs, Vol. 43, Amer. Math. Soc., Providence, R.I., 1974.
- [3] M. Dehghan and M. Hajarian. The reflexive and anti-reflexive solutions of a linear matrix equation and systems of matrix equations. Rocky Mountain J. Math., 40(3):825–848, 2010.
- [4] F.R. Gantmacher. The Matrix Theory (in Russian). Nauka, Moscow, 1967.
- [5] I.M. Gel'fand and G.E. Shilov. Some Questions of Theory of Differential Equations (in Russian). Nauka, Moscow, 1958.
- [6] M.I. Gil'. Estimates for norm of matrix-valued functions. Linear Multilinear Algebra, 35:65-73, 1993.
- [7] M.I. Gil'. Operator Functions and Localization of Spectra. Lecture Notes in Mathematics, Vol. 1830, Springer-Verlag, Berlin, 2003.
- [8] M.I. Gil'. Norms of functions of commuting matrices. Electron. J. Linear Algebra, 13:122-130, 2005.
- [9] M.I. Gil'. Difference Equations in Normed Spaces. Stability and Oscillations, North-Holland Mathematics Studies, Vol. 206, Elsevier, Amsterdam, 2007.
- [10] R.A. Horn and C.R. Johnson. Topics in Matrix Analysis. Cambridge University Press, Cambridge, 1991.
- [11] K. Jbilou. ADI preconditioned Krylov methods for large Lyapunov matrix equations. *Linear Algebra Appl.*, 432(10):2473–2485, 2010.
- [12] M. Konstantinov, D.-W. Gu, V. Mehrmann, and P. Petkov. Perturbation Theory for Matrix Equations. Studies in Computational Mathematics, Vol. 9, North-Holland Publishing Co., Amsterdam, 2003.
- [13] Y. Liu and Y. Tian. How to use RSVD to solve the matrix equation A = BXC'A = BXC. Linear Multilinear Algebra, 58:537–543, 2010.
- [14] A.G. Mazko. Matrix Equations, Spectral Problems and Stability of Dynamic Systems. Stability, Oscillations and Optimization of Systems, Scientific Publishers, Cambridge, 2008.
- [15] V. Müller. Spectral Theory of Linear Operators. Birkhäusr Verlag, Basel, 2003.
- [16] J.L. Taylor. Analytic functional calculus for several commuting operators. Acta Math., 125:1–38, 1970.
- [17] B. Zhou, J. Lam, and G.-R. Duan. On Smith-type iterative algorithms for the Stein matrix equation. Appl. Math. Lett., 22(7):1038–1044, 2009.