THE AUTOMATIC COMPUTATION OF SECOND-ORDER SLOPE TUPLES FOR SOME NONSMOOTH FUNCTIONS*

MARCO SCHNURR[†]

Abstract. In this paper, we show how the automatic computation of second-order slope tuples can be performed. The algorithm allows for nonsmooth functions, such as $\varphi(x) = |u(x)|$ and $\varphi(x) = \max\{u(x), v(x)\}$, to occur in the function expression of the underlying function. Furthermore, we allow the function expression to contain functions given by two or more branches. By using interval arithmetic, second-order slope tuples provide verified enclosures of the range of the underlying function. We give some examples comparing range enclosures given by a second-order slope tuple with enclosures from previous papers.

Key words. slope tuple, interval analysis, automatic slope computation, range enclosure

AMS subject classifications. 65G20, 65G99

1. Introduction. Automatic differentiation [13] is a tool for evaluating functions and derivatives simultaneously without using an explicit formula for the derivative. Combining this technique with interval analysis [1], enclosures of the function range and the derivative range on an interval [x] may be computed simultaneously.

By using an arithmetic analogous to automatic differentiation, the automatic computation of first-order slope tuples is possible. For this purpose, the operations $+, -, \cdot, /$ and the evaluation of elementary functions need to be defined for first-order slope tuples. This approach goes back to Krawczyk and Neumaier [10] and was extended by Rump [16] and Ratz [14]. First-order slope tuples provide enclosures of the function range that may be sharper than enclosures obtained by the well-known mean value form. Moreover, slope tuples can be used in existence tests [4, 5, 11, 17, 19] or for verified global optimization [7, 8, 14, 15, 21].

In this paper, we extend this technique by defining a second-order slope tuple and by describing how the automatic computation of such tuples can be carried out. Shen and Wolfe [24] introduced an arithmetic for the automatic computation of second-order slope enclosures, and Kolev [9] improved this by providing optimal enclosures for convex and concave elementary functions. However, both papers require the underlying function $f:D\subseteq\mathbb{R}\to\mathbb{R}$ to be twice continuously differentiable. In this paper, we present similar results that allow for nonsmooth functions $\varphi:D\subseteq\mathbb{R}\to\mathbb{R}$ occurring in the function expression of f, such as $\varphi(x)=|u(x)|$ and $\varphi(x)=\max\{u(x),v(x)\}$. Furthermore, the function expression of f may contain functions given by two or more branches. Moreover, intermediate results are enclosed by intervals. Hence, these algorithms can be used for verified computations on a floating-point computer.

The paper is organized as follows. Section 2 recalls slope functions and slope enclosures. In Section 3, we define second-order slope tuples for univariate functions and explain how the automatic computation can be performed. In Section 4, we compare range enclosures obtained by second-order slope tuples with range enclosures given by other methods. Section 5 extends the technique from Section 3 to multivariate functions. Furthermore, we explain an alternative approach called componentwise computation of slope tuples and give examples for both methods.

The numerical results were computed using Pascal-XSC programs on a floating-point computer under the operating system Suse Linux 9.3. The source code of the programs

^{*}Received December 12, 2007. Accepted for publication April 21, 2008. Published online on August 4, 2008. Recommended by A. Frommer. This paper contains some results from the author's dissertation [22].

[†]Institute for Applied and Numerical Mathematics, University of Karlsruhe, D-76128 Karlsruhe, Germany (marco.schnurr@math.uni-karlsruhe.de).

is freely available [18]. A current Pascal-XSC compiler is provided by the working group "Scientific Computing / Software Engineering" of the University of Wuppertal [25].

Throughout this paper, we let $[x] = [\underline{x}, \overline{x}] = \{x = (x_i) \in \mathbb{R}^n, \underline{x_i} \leq x_i \leq \overline{x_i}\}$ with $\underline{x}, \overline{x} \in \mathbb{R}^n$ denote an interval vector. The set of all interval vectors $[x] \subset \mathbb{R}^n$ is denoted by $\mathbb{I}\mathbb{R}^n$. For two interval vectors $[x], [y] \in \mathbb{I}\mathbb{R}^n$, the *interval hull* $[x] \cup [y]$ is the smallest interval vector in $\mathbb{I}\mathbb{R}^n$ containing [x] and [y], i.e.

$$\left(\left[x\right]\underline{\cup}\left[y\right]\right)_{i} := \left[\min\left\{\underline{x_{i}}, y_{i}\right\}, \, \max\left\{\overline{x_{i}}, \overline{y_{i}}\right\}\right].$$

Furthermore, by

$$\operatorname{mid}\left[x\right]:=\frac{\overline{x}+\underline{x}}{2}$$

we define the midpoint of [x]. Analogously, $\mathbb{IR}^{n\times n}$ denotes the set of interval matrices $[A] = \left([a]_{ij}\right) = \left\{A \in \mathbb{R}^{n\times n}, \underline{a_{ij}} \leq A_{ij} \leq \overline{a_{ij}}\right\}$. In the following sections, we assume that a function f is given by a function expres-

In the following sections, we assume that a function f is given by a function expression consisting of a finite number of operations $+,-,\cdot,/$, and elementary functions; cf. [1]. Furthermore, we suppose that an interval arithmetic evaluation f([x]) on a given interval [x] exists.

2. Slope Tuples. In this section, we consider functions $f:D\subseteq\mathbb{R}\to\mathbb{R}$

DEFINITION 2.1. (cf. [3]) Let
$$f \in C^n(D)$$
. Furthermore, let $p(x) = \sum_{i=0}^n a_i x^i$ be the

Hermitian interpolation polynomial for f with respect to the nodes $x_0, \ldots, x_n \in D$. Here, exactly k+1 elements of x_0, \ldots, x_n are equal to x_i , if $f(x_i), \ldots, f^{(k)}(x_i)$ are given for some node x_i . The leading coefficient a_n of p is called the slope of n—th order of f with respect to x_0, \ldots, x_n . Notation:

$$\delta_n f(x_0, \dots, x_n) := a_n.$$

In the following theorem, we give some basic properties of slopes. The statements d) and e) in Theorem 2.2 are easy consequences of the Hermite-Genocchi Theorem; see [3].

THEOREM 2.2. Let $f \in C^n(D)$ and let $\delta_n f(x_0, \ldots, x_n)$ be the slope of n-th order of f with respect to x_0, \ldots, x_n . Then, the following statements hold:

- a) $\delta_n f(x_0, \dots, x_n)$ is symmetric with respect to its arguments x_i .
- b) For $x_i \neq x_j$ we have the recursion formula

$$\delta_{n}f\left(x_{0},...,x_{n}\right)=\frac{\delta_{n-1}f\left(x_{0},...,x_{i-1},x_{i+1},...,x_{n}\right)-\delta_{n-1}f\left(x_{0},...,x_{j-1},x_{j+1},...,x_{n}\right)}{x_{j}-x_{i}}.$$

c) Setting
$$\omega_k(x) := \prod_{i=0}^{k-1} (x - x_i)$$
, we have

$$(2.1) f(x) = \sum_{i=0}^{n-1} \delta_i f(x_0, \dots, x_i) \cdot \omega_i(x) + \delta_n f(x_0, \dots, x_{n-1}, x) \cdot \omega_n(x), n \ge 1.$$

d) The function $g:D\subseteq\mathbb{R}^{n+1}\to\mathbb{R}$ defined by

$$g(x_0,\ldots,x_n):=\delta_n f(x_0,\ldots,x_n)$$

205

is continuous.

e) For the nodes $x_0 \le x_1 \le \ldots \le x_n$ there exists a $\xi \in [x_0, x_n]$ such that

$$\delta_n f(x_0,\ldots,x_n) = \frac{f^{(n)}(\xi)}{n!}.$$

DEFINITION 2.3. Let f be continuous and $x_0 \in D$ be fixed. A function $\delta f: D \to \mathbb{R}$ satisfying

$$(2.2) f(x) = f(x_0) + \delta f(x; x_0) \cdot (x - x_0), \quad x \in D,$$

is called a first-order slope function of f with respect to x_0 .

An interval $\delta f([x]; x_0) \in \mathbb{IR}$ that encloses the range of $\delta f(x; x_0)$ on the interval $[x] \subseteq D$, i.e.

$$\delta f([x]; x_0) \supseteq \{\delta f(x; x_0) \mid x \in [x]\},\,$$

is called a (first-order) slope enclosure of f on [x] with respect to x_0 .

In $x = x_0$, (2.2) is fulfilled for an arbitrary $\delta f(x_0; x_0) \in \mathbb{R}$. If f is differentiable at x_0 , then we always set $\delta f(x_0; x_0) := f'(x_0)$. Often, the midpoint mid [x] of the interval [x] is used for x_0 .

REMARK 2.4. a) Let $\delta f([x]; x_0) = \left[\underline{\delta f}, \overline{\delta f}\right]$ be a first-order slope enclosure of f on [x]. Then, by (2.2), we have

$$(2.3) f(x) \in f(x_0) + \delta f([x]; x_0) \cdot ([x] - x_0)$$

for all $x \in [x]$.

b) Let f be differentiable on [x] and $x_0 \in [x]$. Then, we have

$$\left\{\delta f(x;x_{0})\mid x\in\left[x
ight],\,x
eq x_{0}
ight\}\subseteq\left\{f^{'}(x)\mid x\in\left[x
ight]
ight\}.$$

Therefore, (2.3) may provide sharper enclosures of the range of f on [x] than the well-known mean value form.

For some continuous functions f and some $x_0 \in [x] \subseteq D$, a slope enclosure $\delta f([x]; x_0) \in \mathbb{IR}$ does not exist, e.g.,

$$f(x) = \begin{cases} \sqrt{x} & \text{for } x \ge 0, \\ 0 & \text{for } x < 0, \end{cases}$$

with $x_0 = 0$, [x] = [-1, 1]. If f is continuous on [x] and differentiable at $x_0 \in [x]$, then a slope enclosure $\delta f([x]; x_0) \in \mathbb{IR}$ exists. For a sufficient, more general existence criterion, we define the *limiting slope interval* [12].

DEFINITION 2.5. Let f be continuous on [x] and $x_0 \in [x]$. Suppose that both

$$\liminf_{x \to x_0} \frac{f(x) - f(x_0)}{x - x_0}$$

and

$$\limsup_{x \to x_0} \frac{f(x) - f(x_0)}{x - x_0}$$

exist. Then, the limiting slope interval $\delta f_{\lim}([x_0]) \in \mathbb{IR}$ is

$$\delta f_{\lim} ([x_0]) := \left[\liminf_{x \to x_0} \frac{f(x) - f(x_0)}{x - x_0}, \lim \sup_{x \to x_0} \frac{f(x) - f(x_0)}{x - x_0} \right].$$

REMARK 2.6. If f is Lipschitz continuous in some neighbourhood of x_0 , then the limiting slope interval $\delta f_{\lim}([x_0])$ exists.

EXAMPLE 2.7. For $f(x) = |x|, x_0 = 0$ we have $\delta f_{\lim}([x_0]) = [-1, 1]$.

LEMMA 2.8. Let f be continuous on [x] and $x_0 \in [x]$. If $\delta f_{\lim}([x_0]) \in \mathbb{IR}$ exists, then

$$\delta f([x]; x_0) = \left[\inf_{\substack{x \in [x] \\ x \neq x_0}} \frac{f(x) - f(x_0)}{x - x_0}, \sup_{\substack{x \in [x] \\ x \neq x_0}} \frac{f(x) - f(x_0)}{x - x_0} \right]$$

is a slope enclosure of f on [x] with respect to x_0 .

Proof.
$$g:[x]\setminus\{x_0\}\to\mathbb{R},\ g(x):=\frac{f(x)-f(x_0)}{x-x_0}$$
, is bounded. \square REMARK 2.9. Let f be Lipschitz continuous in some neighbourhood of x_0 . Then,

Muñoz und Kearfott [12] show the inclusion

$$\delta f_{\lim} ([x_0]) \subseteq \partial f (x_0),$$

where $\partial f(x_0)$ is the generalized gradient (see [2]). Furthermore, they give an example where

$$\delta f_{\lim}([x_0]) \subset \partial f(x_0)$$

holds and also a sufficient condition for equality in (2.4).

DEFINITION 2.10. Let f be continuous, $[x] \subseteq D$ and $x_0 \in [x]$. Assume that $f'(x_0)$ exists. A function $\delta_2 f: D \to \mathbb{R}$ satisfying

$$f(x) = f(x_0) + f'(x_0) \cdot (x - x_0) + \delta_2 f(x; x_0, x_0) \cdot (x - x_0)^2, \ x \in D,$$

is called a second-order slope function of f with respect to x_0 .

An interval $\delta_2 f([x]; x_0, x_0) \in \mathbb{IR}$ with

$$(2.5) f(x) \in f(x_0) + f'(x_0) \cdot (x - x_0) + \delta_2 f([x]; x_0, x_0) \cdot (x - x_0)^2, \quad x \in [x],$$

is called a second-order slope enclosure of f on [x] with respect to x_0 .

As an abbreviation we set

$$\delta_2 f(x; x_0) := \delta_2 f(x; x_0, x_0)$$

and

$$\delta_2 f([x]; x_0) := \delta_2 f([x]; x_0, x_0).$$

Furthermore, if f is twice differentiable at x_0 , then we set $\delta_2 f(x;x_0) := \frac{1}{2} f''(x_0)$. REMARK 2.11. Assume that (2.5) holds. Then, we have the enclosure

$$f(x) \in f(x_0) + f'(x_0) \cdot ([x] - x_0) + \delta_2 f([x]; x_0) \cdot ([x] - x_0)^2$$

for all $x \in [x]$.

3. The automatic computation of second-order slope tuples for univariate functions. In this section, we consider univariate functions $u, v, w, z : D \subseteq \mathbb{R} \to \mathbb{R}$.

First, we recall the definition of a first-order slope tuple [14, 16]. Afterwards, we give a definition of second-order slope tuples that also permits nonsmooth functions.

DEFINITION 3.1. Let u be continuous, $[x] \subseteq D$ and $x_0 \in [x]$. A triple $\mathcal{U} = (U_x, U_{x_0}, \delta U)$ with $U_x, U_{x_0}, \delta U \in \mathbb{IR}$ satisfying

$$\begin{array}{cccc} u\left(x\right) & \in & U_{x}, \\ u\left(x_{0}\right) & \in & U_{x_{0}}, \\ u\left(x\right) - u\left(x_{0}\right) & \in & \delta U \cdot (x - x_{0}), \end{array}$$

for all $x \in [x]$ is called a first-order slope tuple for u on [x] with respect to x_0 .

DEFINITION 3.2. Let u be continuous, $[x] \subseteq D$ and $x_0 \in [x]$. A second-order slope tuple for u on [x] with respect to x_0 is a 5-tuple $\mathcal{U} = (U_x, U_{x_0}, \delta U_{x_0}, \delta U, \delta_2 U)$ with $U_x, U_{x_0}, \delta U_{x_0}, \delta U, \delta_2 U \in \mathbb{IR}$, $U_{x_0} \subseteq U_x$, satisfying

- $(3.1) u(x) \in U_x,$
- $(3.2) u(x_0) \in U_{x_0},$
- $(3.3) \delta u_{\lim} ([x_0]) \subseteq \delta U_{x_0},$
- $(3.4) u(x) u(x_0) \in \delta U \cdot (x x_0),$

$$(3.5) u(x) - u(x_0) \in \delta U_{x_0} \cdot (x - x_0) + \delta_2 U \cdot (x - x_0)^2,$$

for all $x \in [x]$.

REMARK 3.3. Property (3.5) does not imply that $\delta_2 U$ is a second-order slope enclosure in the sense of (2.5) because δU_{x_0} is a superset of $\delta u_{\lim}([x_0])$. However, Remark 3.12 will explain why the term *slope tuple* is justified.

REMARK 3.4. By (3.1)-(3.5) we get the enclosures

$$u(x) \in U_{x_{0}},$$

$$u(x) \in U_{x_{0}} + \delta U \cdot ([x] - x_{0}),$$

$$u(x) \in U_{x_{0}} + \delta U_{x_{0}} \cdot ([x] - x_{0}) + \delta_{2} U \cdot ([x] - x_{0})^{2},$$

for the range of u on [x], where

$$([x] - x_0)^2 = \left[\min_{x \in [x]} (x - x_0)^2, \max_{x \in [x]} (x - x_0)^2\right].$$

REMARK 3.5. If $x = x_0$, then (3.4) and (3.5) are fulfilled for arbitrary δU , δU_{x_0} and $\delta_2 U$. So in checking these relations, we can restrict ourselves to $x \neq x_0$.

LEMMA 3.6. $\mathcal{K} = (k, k, 0, 0, 0)$ is a second-order slope tuple for the constant function $u(x) \equiv k \in \mathbb{R}$ and $\mathcal{X} = ([x], x_0, 1, 1, 0)$ is a second-order slope tuple for the identity function u(x) = x (both on [x] with respect to $x_0 \in [x]$).

DEFINITION 3.7. Let \mathcal{U} and \mathcal{V} be second-order slope tuples for the continuous functions u and v, respectively, on $[x] \subseteq D$ with respect to $x_0 \in [x]$.

a) For the addition or subtraction of \mathcal{U} and \mathcal{V} we define the 5-tuple $\mathcal{W} := \mathcal{U} \pm \mathcal{V}$ by

$$\begin{array}{lll} W_x & := & U_x \pm V_x, \\ W_{x_0} & := & U_{x_0} \pm V_{x_0}, \\ \delta W_{x_0} & := & \delta U_{x_0} \pm \delta V_{x_0}, \\ \delta W & := & \delta U \pm \delta V, \\ \delta_2 W & := & \delta_2 U \pm \delta_2 V. \end{array}$$

b) The multiplication $W := U \cdot V$ is defined by

$$\begin{array}{lll} W_x & := & U_x \cdot V_x, \\ W_{x_0} & := & U_{x_0} \cdot V_{x_0}, \\ \delta W_{x_0} & := & \delta U_{x_0} \cdot V_{x_0} + U_{x_0} \cdot \delta V_{x_0}, \\ \delta W & := & \delta U \cdot V_{x_0} + U_x \cdot \delta V, \\ \delta_2 W & := & \delta_2 U \cdot V_{x_0} + U_x \cdot \delta_2 V + \delta U \cdot \delta V_{x_0}. \end{array}$$

c) If $0 \notin V_x$, then the division $W := \mathcal{U}/\mathcal{V}$ is defined by

$$\begin{array}{lll} W_x & := & U_x/V_x, \\ W_{x_0} & := & U_{x_0}/V_{x_0}, \\ \delta W_{x_0} & := & \left(\delta U_{x_0} - W_{x_0} \cdot \delta V_{x_0}\right)/V_{x_0}, \\ \delta W & := & \left(\delta U - W_{x_0} \cdot \delta V\right)/V_x, \\ \delta_2 W & := & \left(\delta_2 U - W_{x_0} \cdot \delta_2 V - \delta W \cdot \delta V\right)/V_{x_0}. \end{array}$$

d) If φ is twice continuously differentiable, we define $\mathcal{W} := \varphi(\mathcal{U})$ by

$$\begin{array}{lll} W_x & := & \varphi\left(U_x\right), \\ W_{x_0} & := & \varphi\left(U_{x_0}\right), \\ \delta W_{x_0} & := & \delta\varphi\left(U_{x_0}; U_{x_0}\right) \cdot \delta U_{x_0}, \\ \delta W & := & \delta\varphi\left(U_x; U_{x_0}\right) \cdot \delta U, \\ \delta_2 W & := & \delta\varphi\left(U_x; U_{x_0}\right) \cdot \delta_2 U + \delta_2\varphi\left(U_x; U_{x_0}\right) \cdot \delta U_{x_0} \cdot \delta U. \end{array}$$

Here, we require $\varphi(U_x) \in \mathbb{IR}$ and $\varphi(U_{x_0}) \in \mathbb{IR}$ to enclose the range of φ on U_x and U_{x_0} , respectively, and $\delta\varphi(U_{x_0}; U_{x_0}) \in \mathbb{IR}$ to enclose

$$(3.6) \qquad \{\delta\varphi\left(\widetilde{u_{x_0}};u_{x_0}\right) \mid \widetilde{u_{x_0}} \in U_{x_0}, u_{x_0} \in U_{x_0}\},\,$$

 $\delta \varphi (U_x; U_{x_0}) \in \mathbb{IR}$ to enclose

$$\{\delta\varphi\left(u_{x};u_{x_{0}}\right)\mid u_{x}\in U_{x},u_{x_{0}}\in U_{x_{0}}\},$$

and $\delta_2 \varphi (U_x; U_{x_0}) \in \mathbb{IR}$ to enclose

$$\{\delta_2 \varphi (u_x; u_{x_0}) \mid u_x \in U_x, u_{x_0} \in U_{x_0} \}.$$

THEOREM 3.8. The 5-tuples $W = (W_x, W_{x_0}, \delta W_{x_0}, \delta W, \delta_2 W)$ in Definition 3.7 are second-order slope tuples for the functions $w = u \circ v, o \in \{+, -, \cdot, /\}$ and $w(x) = \varphi(u(x))$ on [x] with respect to x_0 , i.e. they satisfy (3.1)-(3.5).

Proof. The proof of (3.1), (3.2), and (3.4) for W are analogous to those in [14, 16]. So, we only need to prove (3.3) and (3.5). We will show this for $W := U \cdot V$ and $W := \varphi(U)$. The proofs for addition, subtraction, and division are similar. Details can be found in [22].

For $w(x) = u(x) \cdot v(x)$ and $x \in [x]$ we have

$$w(x) - w(x_0) = u(x) v(x) - u(x) v(x_0) + u(x) v(x_0) - u(x_0) v(x_0)$$
$$= \left(u(x) \cdot \delta v(x; x_0) + \delta u(x; x_0) \cdot v(x_0) \right) \cdot (x - x_0)$$

and thus obtain

$$\delta w_{\lim} ([x_0]) \subseteq u(x_0) \cdot \delta v_{\lim} ([x_0]) + \delta u_{\lim} ([x_0]) \cdot v(x_0)$$

$$\subseteq U_{x_0} \cdot \delta V_{x_0} + \delta U_{x_0} \cdot V_{x_0},$$

which is (3.3) for $W = U \cdot V$.

Furthermore, by using interval analysis and the slope tuple properties of \mathcal{U} and \mathcal{V} we have

$$w(x) - w(x_{0}) = u(x) (v(x) - v(x_{0})) + v(x_{0}) (u(x) - u(x_{0}))$$

$$\in u(x) (\delta V_{x_{0}} \cdot (x - x_{0}) + \delta_{2} V \cdot (x - x_{0})^{2})$$

$$+ v(x_{0}) (\delta U_{x_{0}} \cdot (x - x_{0}) + \delta_{2} U \cdot (x - x_{0})^{2})$$

$$= (u(x) \cdot \delta V_{x_{0}} + v(x_{0}) \cdot \delta U_{x_{0}}) \cdot (x - x_{0})$$

$$+ (u(x) \cdot \delta_{2} V + v(x_{0}) \cdot \delta_{2} U) \cdot (x - x_{0})^{2}$$

$$\subseteq ((u(x_{0}) + \delta U \cdot (x - x_{0})) \cdot \delta V_{x_{0}} + v(x_{0}) \cdot \delta U_{x_{0}}) \cdot (x - x_{0})$$

$$+ (u(x) \cdot \delta_{2} V + v(x_{0}) \cdot \delta_{2} U) \cdot (x - x_{0})^{2}$$

$$\subseteq \delta W_{x_{0}} \cdot (x - x_{0}) + \delta_{2} W \cdot (x - x_{0})^{2},$$

which proves (3.5).

Next, we consider $w(x) = \varphi(u(x))$ and $x \in [x]$. By

$$w(x) - w(x_0) = \delta\varphi(u(x); u(x_0)) \cdot (u(x) - u(x_0))$$

we get

$$\delta w_{\lim}([x_0]) \subseteq \varphi'(u(x_0)) \cdot \delta U_{x_0} \subseteq \delta \varphi(U_{x_0}; U_{x_0}) \cdot \delta U_{x_0},$$

which is (3.3) for $W = \varphi(\mathcal{U})$. Because of

$$\varphi(u(x)) = \varphi(u(x_0)) + \varphi'(u(x_0)) \cdot (u(x) - u(x_0)) + \delta_2 \varphi(u(x); u(x_0)) \cdot (u(x) - u(x_0))^2$$

we obtain

$$\delta\varphi(u(x);u(x_{0})) = \varphi'(u(x_{0})) + \delta_{2}\varphi(u(x);u(x_{0})) \cdot (u(x) - u(x_{0})).$$

Hence, we have

$$\begin{split} w\left(x\right) - w\left(x_{0}\right) &= \delta\varphi\left(u\left(x\right); u\left(x_{0}\right)\right) \cdot \left(u\left(x\right) - u\left(x_{0}\right)\right) \\ &\in \delta\varphi\left(u\left(x\right); u\left(x_{0}\right)\right) \cdot \left(\delta U_{x_{0}} \cdot (x - x_{0}) + \delta_{2}U \cdot (x - x_{0})^{2}\right) \\ &= \varphi^{'}\left(u\left(x_{0}\right)\right) \cdot \delta U_{x_{0}} \cdot (x - x_{0}) \\ &+ \delta_{2}\varphi\left(u\left(x\right); u\left(x_{0}\right)\right) \cdot \delta U_{x_{0}} \cdot \left(u\left(x\right) - u\left(x_{0}\right)\right) \cdot (x - x_{0}) \\ &+ \delta\varphi\left(u\left(x\right); u\left(x_{0}\right)\right) \cdot \delta_{2}U \cdot (x - x_{0})^{2} \\ &\subseteq \delta\varphi\left(U_{x_{0}}; U_{x_{0}}\right) \cdot \delta U_{x_{0}} \cdot (x - x_{0}) \\ &+ \left(\delta_{2}\varphi\left(U_{x}; U_{x_{0}}\right) \cdot \delta U_{x_{0}} \cdot \delta U + \delta\varphi\left(U_{x}; U_{x_{0}}\right) \cdot \delta_{2}U\right) \cdot (x - x_{0})^{2} \\ &\subseteq \delta W_{x_{0}} \cdot (x - x_{0}) + \delta_{2}W \cdot (x - x_{0})^{2}, \end{split}$$

which is (3.5). \square

REMARK 3.9. It is possible to define δW and $\delta_2 W$ differently in Definition 3.7 b)-d), such that they still satisfy (3.1)-(3.5). For example, an alternative definition of δW for the multiplication $\mathcal{W} = \mathcal{U} \cdot \mathcal{V}$ would be $\delta W := \delta U \cdot V_x + U_{x_0} \cdot \delta V$. Furthermore, the intersection of this alternative δW with the δW from Definition 3.7 b) may be used; cf. [16].

Next, we compute enclosures $\delta \varphi (U_{x_0}; U_{x_0})$, $\delta \varphi (U_x; U_{x_0})$, $\delta_2 \varphi (U_x; U_{x_0}) \in \mathbb{IR}$ of (3.6)-(3.8), where φ is twice continuously differentiable. Note that such enclosures exist because the sets (3.6)-(3.8) are bounded as a consequence of the assumptions on φ and \mathcal{U} .

By the Mean Value Theorem and Taylor's Theorem we have the enclosures

$$\delta\varphi\left(U_{x_0};U_{x_0}\right) = \varphi'(U_{x_0}),$$

$$\delta\varphi\left(U_{x};U_{x_{0}}\right)=\varphi'\left(U_{x}\right),$$

and

(3.11)
$$\delta_2 \varphi (U_x; U_{x_0}) = \frac{1}{2} \varphi''(U_x)$$

of (3.6)-(3.8). However, for some functions, such as $\varphi(x) = x^2$ and $\varphi(x) = \sqrt{x}$, sharper enclosures for (3.7) and (3.8) can be found. By explicit computation of $\delta\varphi(u_x;u_{x_0})$ and $\delta_2\varphi(u_x;u_{x_0})$ we get the following two lemmas.

LEMMA 3.10. Let \mathcal{U} be a second-order slope tuple for u on [x] with respect to $x_0 \in [x]$, and let $\varphi : \mathbb{R} \to \mathbb{R}$, $\varphi(x) = x^2$. Then, we have the enclosures

$$\delta\varphi\left(u_{x};u_{x_{0}}\right)\in U_{x}+U_{x_{0}},$$

$$\delta_2 \varphi \left(u_x; u_{x_0} \right) \in [1, 1]$$

for all $u_x \in U_x$ and all $u_{x_0} \in U_{x_0}$.

LEMMA 3.11. Let U be a second-order slope tuple for u on [x] with respect to $x_0 \in [x]$ such that $\inf (U_x) \ge 0$ and $\inf (U_{x_0}) > 0$. Furthermore, let $\varphi : \mathbb{R}_{\ge 0} \to \mathbb{R}$, $\varphi(x) = \sqrt{x}$. Then, for all $u_x \in U_x$ and all $u_{x_0} \in U_{x_0}$ we have

$$\delta\varphi\left(u_{x};u_{x_{0}}\right) \in \frac{1}{\sqrt{U_{x}} + \sqrt{U_{x_{0}}}},$$

$$\delta_2 \varphi \left(u_x; u_{x_0} \right) \in -\frac{1}{2\sqrt{U_{x_0}} \left(\sqrt{U_x} + \sqrt{U_{x_0}} \right)^2}.$$

Furthermore, by exploiting convexity or concavity of φ and φ' we can get sharper enclosures for (3.7) and (3.8) than by (3.10) and (3.11). The formulas and the proofs can be found in [9] and [16]. Moreover, exploiting a unique point of inflection of φ or φ' may also give sharper enclosures for (3.7) or (3.8) than (3.10) or (3.11). This applies to functions such as $\varphi(x) = \sinh x$, $\varphi(x) = \cosh x$, etc. We omit the details of these formulas and refer to [20]. REMARK 3.12. Let f be twice continuously differentiable and

$$\mathcal{F} = (F_x, F_{x_0}, \delta F_{x_0}, \delta F, \delta_2 F)$$

be a second-order slope tuple for f on [x] obtained by using Lemma 3.6 and Definition 3.7. Then, we get

$$f(x) - f(x_0) \in f'(x_0) \cdot (x - x_0) + \delta_2 F \cdot (x - x_0)^2, \quad x \in [x],$$

analogously to the proof of Theorem 3.8. This is stronger than (3.5). Hence, by (2.5), $\delta_2 F$ is a second-order slope enclosure of f on [x] with respect to x_0 . This justifies the term second-order slope tuple in Definition 3.2.

3.1. Nonsmooth elementary functions. Let \mathcal{U} and \mathcal{V} be second-order slope tuples for u and v on $[x] \subseteq D$ with respect to $x_0 \in [x]$. We compute a second-order slope tuple \mathcal{W} for $w(x) = |u(x)|, w(x) = \max\{u(x), v(x)\}$ and $w(x) = \min\{u(x), v(x)\}$, so that the automatic computation of second-order slope tuples can be extended to some nonsmooth functions.

1.
$$w(x) = \varphi(u(x)) = |u(x)|$$
:

We define the evaluation of $\varphi(x) = |x|$ on an interval $[x] \in \mathbb{IR}$ by

$$|[x]| = \mathrm{abs}\left([x]\right) := \left\{|x| \mid x \in [x]\right\} = \left[\min_{x \in [x]} |x|, \max_{x \in [x]} |x|\right].$$

Furthermore, we compute $W = \varphi(\mathcal{U}) = abs(\mathcal{U})$ by

$$\begin{array}{rcl} W_x & = & \mathrm{abs} \left(U_x \right), \\ W_{x_0} & = & \mathrm{abs} \left(U_{x_0} \right), \\ \delta W_{x_0} & = & \delta \varphi \left(U_{x_0} ; U_{x_0} \right) \cdot \delta U_{x_0}, \\ \delta W & = & \delta \varphi \left(U_x ; U_{x_0} \right) \cdot \delta U, \\ \delta_2 W & = & [r], \end{array}$$

where

$$\delta\varphi\left(U_{x_0};U_{x_0}\right) = \begin{cases} [-1,-1] & \text{if } \overline{u_x} \leq 0 \\ [1,1] & \text{if } \underline{u_x} \geq 0 \\ [-1,-1] & \text{if } 0 \in U_x \, \wedge \, \overline{u_{x_0}} < 0 \\ [1,1] & \text{if } 0 \in U_x \, \wedge \, \underline{u_{x_0}} > 0 \\ [-1,1] & \text{otherwise,} \end{cases}$$

$$\delta\varphi\left(U_{x};U_{x_{0}}\right) = \begin{cases} \begin{bmatrix} -1,-1 \end{bmatrix} & \text{if } \overline{u_{x}} \leq 0 \\ \begin{bmatrix} 1,1 \end{bmatrix} & \text{if } \underline{u_{x}} \geq 0 \\ \begin{bmatrix} \frac{|u_{x}|-|u_{x_{0}}|}{u_{x}-u_{x_{0}}}, & \frac{|\overline{u_{x}}|-|\overline{u_{x_{0}}}|}{\overline{u_{x}}-\overline{u_{x_{0}}}} \end{bmatrix} & \text{if } 0 \in U_{x} \land \underline{u_{x}} \neq \underline{u_{x_{0}}} \land \overline{u_{x}} \neq \overline{u_{x_{0}}} \\ \begin{bmatrix} -1, & \frac{|\overline{u_{x}}|-|\overline{u_{x_{0}}}|}{\overline{u_{x}}-\overline{u_{x_{0}}}} \end{bmatrix} & \text{if } 0 \in U_{x} \land \underline{u_{x}} = \underline{u_{x_{0}}} \land \overline{u_{x}} \neq \overline{u_{x_{0}}} \\ \begin{bmatrix} \frac{|u_{x}|-|u_{x_{0}}|}{u_{x}}, & 1 \end{bmatrix} & \text{if } 0 \in U_{x} \land \underline{u_{x}} \neq \underline{u_{x_{0}}} \land \overline{u_{x}} = \overline{u_{x_{0}}} \\ \end{bmatrix} \\ \begin{bmatrix} -1, 1 \end{bmatrix} & \text{otherwise,} \end{cases}$$

and

$$[r] = \begin{cases} -1 \cdot \delta_2 U & \text{if } \overline{u_x} \leq 0 \\ \delta_2 U & \text{if } \underline{u_x} \geq 0 \\ \delta \varphi \left(U_x; U_{x_0} \right) \cdot \delta_2 U + \left[0, -\frac{1}{2 \cdot \overline{u_{x_0}}} \right] \cdot \delta U_{x_0} \cdot \delta U & \text{if } 0 \in U_x \wedge \overline{u_{x_0}} < 0 \wedge -\overline{u_{x_0}} \in U_x \\ \delta \varphi \left(U_x; U_{x_0} \right) \cdot \delta_2 U + \left[0, \frac{2 \cdot \overline{u_x}}{\left(\overline{u_x} - \overline{u_{x_0}} \right)^2} \right] \cdot \delta U_{x_0} \cdot \delta U & \text{if } 0 \in U_x \wedge \overline{u_{x_0}} < 0 \wedge -\overline{u_{x_0}} \notin U_x \\ \delta \varphi \left(U_x; U_{x_0} \right) \cdot \delta_2 U + \left[0, \frac{1}{2 \cdot \underline{u_{x_0}}} \right] \cdot \delta U_{x_0} \cdot \delta U & \text{if } 0 \in U_x \wedge \underline{u_{x_0}} > 0 \wedge -\underline{u_{x_0}} \in U_x \\ \delta \varphi \left(U_x; U_{x_0} \right) \cdot \delta_2 U + \left[0, -\frac{2 \cdot u_x}{\left(\underline{u_x} - \underline{u_{x_0}} \right)^2} \right] \cdot \delta U_{x_0} \cdot \delta U & \text{if } 0 \in U_x \wedge \underline{u_{x_0}} > 0 \wedge -\underline{u_{x_0}} \notin U_x \\ \left[-1, 1 \right] \cdot \delta_2 U & \text{otherwise.} \end{cases}$$

2. $w(x) = \max\{u(x), v(x)\}$:

We define the evaluation of the max-function for two intervals [a] and [b] by

$$\max \{ [a], [b] \} := \left[\max \{ \underline{a}, \underline{b} \}, \max \{ \overline{a}, \overline{b} \} \right].$$

Furthermore, we compute $W = \max \{U, V\}$ by

$$\begin{split} W_x &= \max \left\{ U_x, V_x \right\}, \\ W_{x_0} &= \max \left\{ U_{x_0}, V_{x_0} \right\}, \\ \delta W_{x_0} &= \left\{ \begin{array}{ll} \delta U_{x_0} & \text{if } \underline{u_x} \geq \overline{v_x} \\ \delta V_{x_0} & \text{if } \underline{v_x} \geq \overline{u_x} \\ \delta U_{x_0} \sqcup \delta V_{x_0} & \text{otherwise,} \end{array} \right. \\ \delta W &= \left\{ \begin{array}{ll} \delta U & \text{if } \underline{u_x} \geq \overline{v_x} \\ \delta V & \text{if } \underline{v_x} \geq \overline{u_x} \\ \delta U \sqcup \delta V & \text{otherwise,} \end{array} \right. \\ \delta_2 W &= \left\{ \begin{array}{ll} \delta_2 U & \text{if } \underline{u_x} \geq \overline{v_x} \\ \delta_2 V & \text{if } \underline{v_x} \geq \overline{u_x} \\ \delta_2 U \sqcup \delta_2 V & \text{otherwise.} \end{array} \right. \end{split}$$

We compute \mathcal{W} for $w\left(x\right)=\min\left\{ u\left(x\right),v\left(x\right)\right\}$ analogously to \mathcal{W} for

$$w(x) = \max \{u(x), v(x)\}.$$

THEOREM 3.13. Let \mathcal{U} and \mathcal{V} be second-order slope tuples for u and v, respectively, on $[x] \subseteq D$ with respect to $x_0 \in [x]$. Then, the tuples $\mathcal{W} = \varphi(\mathcal{U}) = abs(\mathcal{U})$ and $\mathcal{W} = \max\{\mathcal{U}, \mathcal{V}\}$ defined above are second-order slope tuples for the functions $w(x) = \varphi(u(x)) = |u(x)|$ and $w(x) = \max\{u(x), v(x)\}$, respectively.

Proof. The proof of (3.1), (3.2), and (3.4) for \mathcal{W} can be found in [14]. Therefore, we only need to check (3.3) and (3.5).

ETNA Kent State University

1.
$$w(x) = \varphi(u(x)) = |u(x)|$$
:

We prove (3.3). For each $x \in [x]$ with $u(x) = u(x_0)$ we have

$$w(x) - w(x_0) = [a] \cdot (u(x) - u(x_0))$$

with an arbitrary $[a] \in \mathbb{IR}$. If $u(x) \neq u(x_0)$, then

$$\frac{w(x) - w(x_0)}{x - x_0} = \frac{|u(x)| - |u(x_0)|}{u(x) - u(x_0)} \cdot \frac{u(x) - u(x_0)}{x - x_0}$$

holds. By considering the various cases in the definition of δW_{x_0} we obtain

$$\delta w_{\lim}([x_0]) \subseteq \delta W_{x_0}.$$

Next, we prove (3.5).

Case 1: $\overline{u_x} \leq 0$.

We have

$$w(x) - w(x_0) = -1 \cdot (u(x) - u(x_0))$$

$$\in -1 \cdot \delta U_{x_0} \cdot (x - x_0) - 1 \cdot \delta_2 U \cdot (x - x_0)^2.$$

Case 2: $u_x \ge 0$. This case is analogous to the previous case.

Case 3: $\overline{0} \in U_x \land \overline{u_{x_0}} < 0 \land -\overline{u_{x_0}} \in U_x$. For all $x \in [x]$ with $u(x) \ge 0$ we get

$$w(x) - w(x_{0}) \in \frac{|u(x)| - |u(x_{0})|}{u(x) - u(x_{0})} \cdot \left(\delta U_{x_{0}} \cdot (x - x_{0}) + \delta_{2} U \cdot (x - x_{0})^{2}\right)$$

$$= \left(-1 + \frac{2u(x)}{u(x) - u(x_{0})}\right) \cdot \delta U_{x_{0}} \cdot (x - x_{0})$$

$$+ \frac{|u(x)| - |u(x_{0})|}{u(x) - u(x_{0})} \cdot \delta_{2} U \cdot (x - x_{0})^{2}$$

$$= -\delta U_{x_{0}} \cdot (x - x_{0}) + \left(\frac{|u(x)| - |u(x_{0})|}{u(x) - u(x_{0})} \cdot \delta_{2} U\right)$$

$$+ \frac{2u(x)}{(u(x) - u(x_{0}))^{2}} \cdot \frac{u(x) - u(x_{0})}{x - x_{0}} \cdot \delta U_{x_{0}} \cdot \delta U_{x_{0}}\right) \cdot (x - x_{0})^{2}.$$

Because of $u(x) \ge 0$ we have

(3.12)
$$0 \leq \frac{2 u(x)}{(u(x) - u(x_0))^2} \leq \frac{2 u(x)}{(u(x) - \overline{u_{x_0}})^2}.$$

By computing the maximum of the right expression in (3.12) and by using $u(x) \ge 0$ and $-\overline{u_{x_0}} \in U_x$, we obtain

$$\frac{2 u \left(x\right)}{\left(u \left(x\right) - \overline{u_{x_0}}\right)^2} \leq \frac{2 \left(-\overline{u_{x_0}}\right)}{\left(-\overline{u_{x_0}} - \overline{u_{x_0}}\right)^2}.$$

Thus, we have

$$\frac{2 u(x)}{\left(u(x) - u(x_0)\right)^2} \in \left[0, -\frac{1}{2 \overline{u_{x_0}}}\right].$$

Therefore, for all $x \in [x]$ with $u(x) \ge 0$ we have shown that

$$(3.14) w(x) - w(x_0) \in -\delta U_{x_0} \cdot (x - x_0) + \left(\delta \varphi(U_x; U_{x_0}) \cdot \delta_2 U_{x_0} + \left[0, -\frac{1}{2\overline{u_{x_0}}}\right] \cdot \delta U_{x_0} \cdot \delta U\right) \cdot (x - x_0)^2$$

holds. For all $x \in [x]$ with u(x) < 0 we get

$$w(x) - w(x_0) = (u(x) - u(x_0))$$

 $\in -\delta U_{x_0} \cdot (x - x_0) - \delta_2 U \cdot (x - x_0)^2$.

Because of $-1 \in \delta \varphi (U_x; U_{x_0})$ and $0 \in \left[0, -\frac{1}{2u_{x_0}}\right]$ we have

$$-1 \cdot \delta_2 U \cdot (x - x_0)^2$$

$$\subseteq \left(\delta \varphi \left(U_x; U_{x_0}\right) \cdot \delta_2 U + \left[0, -\frac{1}{2 \overline{u_{x_0}}}\right] \cdot \delta U_{x_0} \cdot \delta U\right) \cdot (x - x_0)^2.$$

Hence, (3.14) also holds for all $x \in [x]$ with u(x) < 0. Thus, we have

$$w(x) - w(x_0) \subseteq \delta W_{x_0} \cdot (x - x_0) + \delta_2 W \cdot (x - x_0)^2$$

for all $x \in [x]$.

Case 4: $0 \in U_x \land \overline{u_{x_0}} < 0 \land -\overline{u_{x_0}} \notin U_x$.

The proof is analogous to case 3. Instead of (3.13), we get

$$\frac{2 \cdot u\left(x\right)}{\left(u\left(x\right) - u\left(x_0\right)\right)^2} \in \left[0, \frac{2 \cdot \overline{u_x}}{\left(\overline{u_x} - \overline{u_{x_0}}\right)^2}\right].$$

Case 5: $0 \in U_x \land \underline{u_{x_0}} > 0 \land -\underline{u_{x_0}} \in U_x$. This case is analogous to case 3. Case 6: $0 \in U_x \land \underline{u_{x_0}} > 0 \land -\underline{u_{x_0}} \notin U_x$. This case is analogous to case 4.

Case 7: We have

$$|u(x)| - |u(x_0)| \in [-1, 1] \cdot \left(u(x) - u(x_0) \right)$$

$$\subseteq [-1, 1] \cdot \delta U_{x_0} \cdot (x - x_0) + [-1, 1] \cdot \delta_2 U \cdot (x - x_0)^2,$$

which completes the proof.

2. $w(x) = \max \{u(x), v(x)\}$:

Case 1: $u_x \geq \overline{v_x}$.

We have $\max \{u(x), v(x)\} = u(x)$ and $\max \{u(x_0), v(x_0)\} = u(x_0)$. Therefore, the proof of (3.3) and (3.5) is obvious.

Case 2: $v_x \ge \overline{u_x}$. This case can be proven analogously to case 1.

Case 3: In the remaining case we have

$$\delta w_{\lim}([x_0]) \subseteq \delta U_{x_0} \cup \delta V_{x_0}.$$

Therefore, we get (3.3). Next, we prove (3.5).

If $\max \{u(x), v(x)\} = u(x)$ and $\max \{u(x_0), v(x_0)\} = v(x_0)$, then we have

$$v(x) - v(x_0) < u(x) - v(x_0) < u(x) - u(x_0)$$

http://etna.math.kent.edu

ETNA Kent State University

and therefore,

$$(3.15) w(x) - w(x_0) \in (\delta U_{x_0} \cup \delta V_{x_0}) \cdot (x - x_0) + (\delta_2 U \cup \delta_2 V) \cdot (x - x_0)^2$$

holds. Clearly, (3.15) also holds, if

$$\max \{u(x), v(x)\} = u(x)$$
 and $\max \{u(x_0), v(x_0)\} = u(x_0)$.

Analogously, (3.15) is fulfilled, if u and v are interchanged. Therefore, we get (3.5). \square

3.2. Continuous functions given by two or more branches. In order to automatically compute second-order slope tuples for continuous functions given by two or more branches, we first define the function ite: $\mathbb{R}^3 \longrightarrow \mathbb{R}$ ("if-then-else").

DEFINITION 3.14. *ite* : $\mathbb{R}^3 \longrightarrow \mathbb{R}$ *is the function*

(3.16)
$$ite(z,u,v) := \begin{cases} u & if \ z < 0 \\ v & otherwise. \end{cases}$$

Let $u, v, z : D \subseteq \mathbb{R} \longrightarrow \mathbb{R}$ be continuous, $[x] \subseteq D$ and define $w : D \subseteq \mathbb{R} \longrightarrow \mathbb{R}$ by

(3.17)
$$w(x) = ite(z(x), u(x), v(x)).$$

w is now a function given by two branches u and v, with the function z determining which branch is chosen. For details see [23].

DEFINITION 3.15. We define the evaluation of the ite-function for intervals $[z] = [\underline{z}, \overline{z}]$, $[u] = [\underline{u}, \overline{u}]$ and $[v] = [\underline{v}, \overline{v}]$ by

$$(3.18) \qquad ite([z],[u],[v]) := \begin{cases} [u] & \text{if } \overline{z} < 0 \\ [v] & \text{if } \underline{z} \ge 0 \\ [u] \ \underline{\cup} \ [v] & \text{otherwise.} \end{cases}$$

Theorem 3.16. Let \mathcal{U} , \mathcal{V} and \mathcal{Z} be second-order slope tuples for the continuous functions u, v and z on some interval $[x] \subseteq D$ with respect to $x_0 \in [x]$. Furthermore, let w(x) = ite(z(x), u(x), v(x)) be continuous on [x]. We define the 5-tuple $\mathcal{W} = ite(\mathcal{Z}, \mathcal{U}, \mathcal{V})$

$$W_x = ite(Z_x, U_x, V_x),$$

 $W_{x_0} = ite(Z_{x_0}, U_{x_0}, V_{x_0})$

$$\delta W = \begin{cases} \delta U & \text{if } \overline{z_x} < 0 \\ \delta V & \text{if } \underline{z_x} \ge 0 \\ \delta U \ \, \underline{\cup} \left(\delta V + (\delta U - \delta V) \cdot [0, 1] \right) & \text{if } 0 \in Z_x \land \overline{z_{x_0}} < 0 \\ \delta V \ \, \underline{\cup} \left(\delta U + (\delta V - \delta U) \cdot [0, 1] \right) & \text{if } 0 \in Z_x \land \underline{z_{x_0}} \ge 0 \\ \left(\delta U \ \, \underline{\cup} \left(\delta V + (\delta U - \delta V) \cdot [0, 1] \right) \right) & \text{otherwise,} \end{cases}$$

Then, $W = ite(\mathcal{Z}, \mathcal{U}, \mathcal{V})$ is a second-order slope tuple for w on [x] with respect to x_0 . Proof. See [22] and [23]. \square

REMARK 3.17. In some papers, the formula

$$\delta W = \begin{cases} \delta U & \text{if } \overline{z} < 0\\ \delta V & \text{if } \underline{z} \ge 0\\ \delta U \cup \delta V & \text{otherwise} \end{cases}$$

is used for computation of a first-order slope tuple for w(x) = ite(z(x), u(x), v(x)) on [x]. However, this formula is not correct because it does not provide a slope enclosure of w on [x] for all possible choices of z, u, v. For details see [22] and [23].

4. Numerical results. We use the technique from the previous section to automatically compute a second-order slope tuple

$$\mathcal{F} = (F_x, F_{x_0}, \delta F_{x_0}, \delta F, \delta_2 F)$$

for f on [x] with respect to $x_0 \in [x]$. In this way, we obtain the range enclosures

$$(4.1) S_1 := F_{x_0} + \delta F \cdot ([x] - x_0)$$

and

$$(4.2) S_2 := F_{x_0} + \delta F_{x_0} \cdot ([x] - x_0) + \delta_2 F \cdot ([x] - x_0)^2$$

of f on [x]; see Remark 3.4. S_1 was already considered in [14]. If f is twice continuously differentiable, we can also compare these results with the centered forms

$$(4.3) D_1 := f(x_0) + f'([x]) \cdot ([x] - x_0)$$

and

$$(4.4) D_2 := f(x_0) + f'(x_0) \cdot ([x] - x_0) + \frac{1}{2} f''([x]) \cdot ([x] - x_0)^2.$$

Here, $f^{'}([x])$ and $f^{''}([x])$ are enclosures of the range of $f^{'}$ and $f^{''}$ on [x]. They are computed via automatic differentiation.

REMARK 4.1. By using machine interval arithmetic on a floating-point computer for the operations from Section 3, the slope tuple properties (3.1)-(3.5) are preserved. Hence, by applying machine interval arithmetic, we obtain verified range enclosures.

We consider the following examples:

1.
$$f(x) = (x + \sin x) \cdot \exp(-x^2)$$

2. $f(x) = x^4 - 10x^3 + 35x^2 - 50x + 24$
3. $f(x) = (\ln(x + 1.25) - 0.84x)^2$
4. $f(x) = \frac{2}{100}x^2 - \frac{3}{100}\exp(-(20(x - 0.875))^2)$
5. $f(x) = \exp(x^2)$
6. $f(x) = x^4 - 12x^3 + 47x^2 - 60x - 20\exp(-x)$
7. $f(x) = x^6 - 15x^4 + 27x^2 + 250$
8. $f(x) = (\arctan(|x - 1|))^2/(x^6 - 2x^4 + 20)$
9. $f(x) = \max\{\exp(-x), \sin(|x - 1|)\}$
10. $f(x) = \text{ite}(x - 1, x^4 - 1 + \sin(x - 1), |x^2 - \frac{5}{2}x + \frac{3}{2}|)$
11. $f(x) = |(x - 1)(x^2 + x + 5)| \cdot \exp((x - 2)^2)$
12. $f(x) = \max\{x^5 - x^2 + x, \exp(x) \cdot (x - 1) + 1\}$
13. $f(x) = \text{ite}(x - 1, (x - 1) \cdot \arctan x \cdot \exp(x + \sin x), |(x^2 - \frac{5}{2}x + \frac{3}{2}) \cdot \sin x|)$

In each case, we consider [x] = [0.75, 1.75] and set $x_0 := mid[x]$. Examples 1-7 have also been considered in [14].

We obtained the results in Table 4.1. For the examples 1-7, S_1 and S_2 provide sharper enclosures than D_1 and D_2 , respectively. Furthermore, S_2 is a subset of S_1 for the examples 1-7 except for example 4. For nonsmooth functions φ , it is possible that a very large interval $\delta_2 W$ is computed for $\mathcal{W} = \varphi(\mathcal{U})$. Hence, S_2 is not always contained in S_1 in our examples. However, except for example 9, one or both bounds of S_2 provide sharper bounds for the range of f than S_1 .

TABLE 4.1

Range enclosure for examples 1-13

No.	D_1	D_2	S_1	S_2
1	[-2.262, 3.184]	[-0.910, 2.889]	[-0.939, 1.861]	[-0.247, 1.476]
2	[-44.75, 42.95]	[-5.215, 7.598]	[-22.84, 21.04]	[-1.778, 3.536]
3	[-0.376, 0.412]	[-0.042, 0.190]	[-0.199, 0.235]	[-0.041, 0.151]
4	[-10.51, 10.57]	[-1835, 3.062]	[-0.133, 0.195]	[-0.345, 0.115]
5	[-32.65, 42.19]	[-1.193, 48.82]	[-11.84, 21.39]	[-1.193, 21.39]
6	[-85.86, 29.28]	[-40.03, -11.73]	[-61.07, 4.492]	[-35.76, -16.47]
7	[119.5, 399.3]	[182.7, 304.4]	[185.9, 332.9]	[210.4, 275.1]
8	-	=	[-0.333, 0.339]	[-0.386, 0.233]
9	-	-	[-0.214, 0.787]	[-0.284, 1.271]
10	-	=	[-7.375, 7.500]	[-5.945, 7.516]
11	-	=	[-19.85, 26.70]	[-8.953, 34.22]
12	-	-	[-10.13, 15.61]	[-2.615, 15.11]
13	-	-	[-15.00, 15.12]	[-12.64, 13.27]

5. The automatic computation of second-order slope tuples for multivariate functions. In this section, let $f:D\subseteq\mathbb{R}^n\to\mathbb{R}$. We define slope enclosures and the limiting slope interval analogously to Section 2.

DEFINITION 5.1. Let f be continuous and $x_0 \in D$ be fixed. A function $\delta f: D \to \mathbb{R}^{1 \times n}$ satisfying

$$f(x) = f(x_0) + \delta f(x; x_0) \cdot (x - x_0), \quad x \in D,$$

is called a first-order slope function of f with respect to x_0 .

An interval matrix $\delta f([x]; x_0) \in \mathbb{IR}^{1 \times n}$ with

$$\delta f([x]; x_0) \supseteq \{\delta f(x; x_0) \mid x \in [x]\}$$

is called a (first-order) slope enclosure of f on [x] with respect to x_0 .

A slope function of $f: \mathbb{R}^n \to \mathbb{R}$ is not unique, and there are various ways for computing one; see, for example, [6, 7].

DEFINITION 5.2. Let f be continuous on $[x] \in \mathbb{IR}^n$, $[x] \subseteq D$. Furthermore, let $x_0 \in [x]$ and $f_i(t) := f((x_0)_1, \ldots, (x_0)_{i-1}, t, (x_0)_{i+1}, \ldots, (x_0)_n)$. If

$$\liminf_{t \to (x_0)_i} \frac{f_i(t) - f_i((x_0)_i)}{t - (x_0)_i}$$

and

$$\limsup_{t \to (x_0)_i} \frac{f_i(t) - f_i((x_0)_i)}{t - (x_0)_i}$$

exist for all $i \in \{1, ..., n\}$, then we define the limiting slope interval $\delta f_{\lim}([x_0]) \in \mathbb{IR}^n$ by

$$\left(\delta f_{\lim}\left(\left[x_{0}\right]\right)\right)_{i} := \left[\liminf_{t \to \left(x_{0}\right)_{i}} \frac{f_{i}\left(t\right) - f_{i}\left(\left(x_{0}\right)_{i}\right)}{t - \left(x_{0}\right)_{i}}, \lim_{t \to \left(x_{0}\right)_{i}} \frac{f_{i}\left(t\right) - f_{i}\left(\left(x_{0}\right)_{i}\right)}{t - \left(x_{0}\right)_{i}}\right].$$

DEFINITION 5.3. Let f be continuous, $[x] \subseteq D$, $x_0 \in [x]$, and assume that $f'(x_0)$ exists. A function $\delta_2 f: D \to \mathbb{R}^{n \times n}$ satisfying

$$f(x) = f(x_0) + f'(x_0) \cdot (x - x_0) + (x - x_0)^T \cdot \delta_2 f(x; x_0, x_0) \cdot (x - x_0), \ x \in D,$$

is called a second-order slope function of f with respect to x_0 .

An interval matrix $\delta_2 f([x]; x_0, x_0) \in \mathbb{IR}^{n \times n}$ with

$$f(x) \in f(x_0) + f'(x_0) \cdot (x - x_0) + (x - x_0)^T \cdot \delta_2 f([x]; x_0, x_0) \cdot (x - x_0), \ x \in [x],$$

is called a second-order slope enclosure of f on [x] with respect to x_0 .

DEFINITION 5.4. Let $u: D \subseteq \mathbb{R}^n \to \mathbb{R}$ be continuous, $[x] \in \mathbb{IR}^n$ with $[x] \subseteq D$, and $x_0 \in [x]$. A second-order slope tuple for u on [x] with respect to x_0 is a 5-tuple $\mathcal{U} = (U_x, U_{x_0}, \delta U_{x_0}, \delta U, \delta_2 U)$ with $U_x, U_{x_0} \in \mathbb{IR}$, $\delta U_{x_0}, \delta U \in \mathbb{IR}^n$, $\delta_2 U \in \mathbb{IR}^{n \times n}$, $U_{x_0} \subseteq U_x$, satisfying

- $(5.1) u(x) \in U_x,$
- $(5.2) u(x_0) \in U_{x_0},$
- $\delta u_{\lim} ([x_0]) \subseteq \delta U_{x_0},$
- $(5.4) u(x) u(x_0) \in \delta U^T \cdot (x x_0),$

(5.5)
$$u(x) - u(x_0) \in \delta U_{x_0}^T \cdot (x - x_0) + (x - x_0)^T \cdot \delta_2 U \cdot (x - x_0)$$

for all $x \in [x]$.

LEMMA 5.5. Let $[x] \in \mathbb{IR}^n$, $x_0 \in [x]$, $i \in \{1, ..., n\}$, and let $e^i \in \mathbb{R}^n$ be the i-th unit vector.

a) K = (k, k, 0, 0, 0) is a second-order slope tuple for the constant function $u : \mathbb{R}^n \to \mathbb{R}$, $u(x) \equiv k \in \mathbb{R}$, on [x] with respect to x_0 . Here, the first and the second 0 symbolize the zero vector, and the last 0 stands for the zero matrix.

b) $\mathcal{X} = ([x]_i, (x_0)_i, e^i, e^i, 0)$ is a second-order slope tuple for $u : \mathbb{R}^n \to \mathbb{R}$, $u(x) = x_i$, on [x] with respect to x_0 . Here, 0 stands for the zero matrix.

REMARK 5.6. For the automatic computation of second-order slope tuples, the definitions and theorems are completely analogous to Section 3. We only have to take into account that δU_{x_0} , δU , δV_{x_0} , $\delta V \in \mathbb{IR}^n$ and $\delta_2 U$, $\delta_2 V \in \mathbb{IR}^{n \times n}$. Therefore, we get $\delta U_{x_0} \cdot \delta U^T$ instead of $\delta U_{x_0} \cdot \delta U$ and $(x-x_0)^T \cdot \delta_2 U \cdot (x-x_0)$ instead of $\delta_2 U \cdot (x-x_0)^2$. For details, see [22].

5.1. The componentwise computation of second-order slope tuples. The automatic computation of slope tuples for multivariate functions can be reduced to the one-dimensional case by the *componentwise computation of slope tuples*. For first-order slope tuples, Ratz [14] uses this technique for verified global optimization. Hence, we also consider the componentwise computation of second-order slope tuples in this paper.

DEFINITION 5.7. Let $u : \mathbb{R}^n \to \mathbb{R}$ be continuous on [x] and let $i \in \{1, ..., n\}$ be fixed. We define the family of functions

$$(5.6) \quad \mathcal{G}_{i} := \left\{ \begin{array}{l} g: [x]_{i} \subseteq \mathbb{R} \to \mathbb{R}, \quad g(t) := u\left(x_{1}, \ldots, x_{i-1}, t, x_{i+1}, \ldots, x_{n}\right) \\ \text{with } x_{j} \in [x]_{j} \text{ fixed for } j \in \left\{1, \ldots, n\right\}, \ j \neq i. \end{array} \right\}$$

Each $g \in \mathcal{G}_i$ is a continuous function of one variable t. Hence, for each $g \in \mathcal{G}_i$ the automatic computation of a second-order slope tuple on $[x]_i$ with respect to a fixed $(x_0)_i \in [x]_i$, $(x_0)_i \in \mathbb{R}$, is defined as in Section 3.

For the componentwise computation we have to modify the definition of a second-order slope tuple as follows:

DEFINITION 5.8. Let $u:D\subseteq\mathbb{R}^n\to\mathbb{R}$ be continuous and $[x]\in\mathbb{IR}^n$, $[x]\subseteq D$. Furthermore, let $i\in\{1,\ldots,n\}$ and $(x_0)_i\in[x]_i\subseteq\mathbb{R}$ be fixed. A second-order slope tuple

for u on [x] with respect to the i-th component is a 5-tuple $\mathcal{U}=(U_x,U_{x_0},\delta U_{x_0},\delta U,\delta_2 U)$ with $U_x,U_{x_0},\delta U_{x_0},\delta U,\delta_2 U\in \mathbb{IR},\ U_{x_0}\subseteq U_x$, satisfying

$$\begin{array}{rcl} g\left(x_{i}\right) & \in & U_{x}, \\ g\left(\left(x_{0}\right)_{i}\right) & \in & U_{x_{0}}, \\ \delta g_{\lim}\left(\left[x_{0}\right]_{i}\right) & \subseteq & \delta U_{x_{0}}, \\ g\left(x_{i}\right) - g\left(\left(x_{0}\right)_{i}\right) & \in & \delta U \cdot \left(x_{i} - \left(x_{0}\right)_{i}\right), \\ g\left(x_{i}\right) - g\left(\left(x_{0}\right)_{i}\right) & \in & \delta U_{x_{0}} \cdot \left(x_{i} - \left(x_{0}\right)_{i}\right) + \delta_{2} U \cdot \left(x_{i} - \left(x_{0}\right)_{i}\right)^{2} \end{array}$$

for all $x_i \in [x]_i$ and all $g \in \mathcal{G}_i$, where \mathcal{G}_i is defined by (5.6).

REMARK 5.9. Let \mathcal{U} be a second-order slope tuple for u on [x] with respect to the i-th component. Then, for all $x \in [x]$ we have

$$(5.7) u(x) \in U_{x_0} + \delta U \cdot \left(\left[x \right]_i - \left(x_0 \right)_i \right)$$

and

(5.8)
$$u(x) \in U_{x_0} + \delta U_{x_0} \cdot \left([x]_i - (x_0)_i \right) + \delta_2 U \cdot \left([x]_i - (x_0)_i \right)^2.$$

Hence, we have reduced the automatic computation of second-order slope tuples to the one-dimensional case from Section 3. Therefore, the same formulas can be used except for Lemma 3.6. We need to modify Lemma 3.6 as follows:

LEMMA 5.10. Let $[x] \in \mathbb{IR}^n$, $x_0 \in [x]$, and $i \in \{1, ..., n\}$.

a) For each $i \in \{1, ..., n\}$, the tuple $\mathcal{K} = (k, k, 0, 0, 0)$ is a second-order slope tuple for the constant function $u : \mathbb{R}^n \to \mathbb{R}$, $u(x) \equiv k \in \mathbb{R}$, on [x] with respect to the i-th component.

b) For $u: \mathbb{R}^n \to \mathbb{R}$, $u(x) = x_k$, a second-order slope tuple on [x] with respect to the i-th component is given by

$$\mathcal{X} = \left\{ \begin{array}{ll} \left(\left[x \right]_{k}, \left[x \right]_{k}, 0, 0, 0 \right), & \text{if } k \neq i, \\ \left[x \right]_{i}, \left(x_{0} \right)_{i}, 1, 1, 0 \right), & \text{if } k = i. \end{array} \right.$$

REMARK 5.11. Using a technique similar to [6, 7], we obtain range enclosures that are sharper than (5.7) and (5.8). For a fixed $x_0 \in [x] \subseteq D$ we have

$$(5.9) \quad f(x_{1},...,x_{n}) - f((x_{0})_{1},...,(x_{0})_{n})$$

$$= f(x_{1},...,x_{n}) - f((x_{0})_{1},x_{2},...,x_{n})$$

$$+ f((x_{0})_{1},x_{2},...,x_{n}) - f((x_{0})_{1},(x_{0})_{2},x_{3},...,x_{n})$$

$$+ f((x_{0})_{1},(x_{0})_{2},x_{3},...,x_{n}) - + \cdots$$

$$+ f((x_{0})_{1},...,(x_{0})_{n-1},x_{n}) - f((x_{0})_{1},...,(x_{0})_{n}).$$

for all $x \in [x]$. For each $i \in \{1, ..., n\}$, we now compute a second-order slope tuple

$$\mathcal{F}_i := (F_{x:i}, F_{x_0:i}, \delta F_{x_0:i}, \delta F_i, \delta_2 F_i)$$

for the function

$$f_i: ((x_0)_1, \dots, (x_0)_{i-1}, [x]_i, [x]_{i+1}, \dots, [x]_n) \to \mathbb{R},$$

221

AUTOMATIC COMPUTATION OF SECOND-ORDER SLOPE TUPLES

$$f_{i}(x) := u((x_{0})_{1}, \dots, (x_{0})_{i-1}, x_{i}, x_{i+1}, \dots, x_{n})$$

for $x \in ((x_{0})_{1}, \dots, (x_{0})_{i-1}, [x]_{i}, [x]_{i+1}, \dots, [x]_{n}),$

on $((x_0)_1,\ldots,(x_0)_{i-1},[x]_i,[x]_{i+1},\ldots,[x]_n)$ with respect to the i-th component. Then, by (5.9) we have

$$\begin{array}{lcl} f\left(x\right) & \in & F_{x;1}, \\ f\left(x\right) & \in & F_{x_{0};n} + \sum_{j=1}^{n} \, \delta F_{j} \cdot \left(\left[x\right]_{j} - \left(x_{0}\right)_{j} \right) =: \, S_{c;1}, \\ f\left(x\right) & \in & F_{x_{0};n} + \sum_{j=1}^{n} \, \delta F_{x_{0};j} \cdot \left(\left[x\right]_{j} - \left(x_{0}\right)_{j} \right) + \sum_{j=1}^{n} \, \delta_{2} F_{j} \cdot \left(\left[x\right]_{j} - \left(x_{0}\right)_{j} \right)^{2} \\ & =: \, S_{c;2} \end{array}$$

for all $x \in [x]$.

5.2. Examples. We consider the following examples $f: \mathbb{R}^n \to \mathbb{R}$. Most of them have been considered in [14]:

1.
$$f(x) = \left(\left(\frac{5}{\pi} x_4 - \frac{5 \cdot 1}{4\pi^2} x_4^2 + x_2 - 6 \right)^2 + 10 \left(1 - \frac{1}{8\pi} \right) \cos x_4 + 10 \right) \cdot x_3^2 - x_1^5 + x_2 \frac{\sinh(x_5)}{x_6^2 + 1} x_6 - \exp(x_3) \cdot x_5$$

2.
$$f(x) = 4x_1^2 - 2.1x_1^4 + \frac{1}{3}x_1^6 + x_1x_2 - 4x_2^2 + 4x_2^4$$

3.
$$f(x) = 100(x_2 - x_1^2)^2 + (x_1 - 1)^2$$

4.
$$f(x) = 12x_1^2 - 6.3x_1^4 + x_1^6 + 6x_2(x_2 - x_1)$$

5.
$$f(x) = \sin x_1 + \sin(\frac{10}{3}x_1) + \ln x_1 - 0.84x_1 + 1000x_1x_2^2 \exp(-x_3^2)$$

6.
$$f(x) = (x_1 + \sin x_1) \exp(-x_1^2) + \ln(x_3) \frac{x_2^2}{x_1}$$

In each example, we take

$$[x] \ = \ \left(\ [x]_1 \ , \ldots, [x]_n \ \right) \ = \ \left(\ [4,4.25] \ , \ldots, [4,4.25] \ \right)$$

and $x_0 = \min[x]$.

Using the technique from Remark 5.6, we compute a second-order slope tuple

$$\mathcal{F} = (F_x, F_{x_0}, \delta F_{x_0}, \delta F, \delta_2 F)$$

for f on [x], as introduced in Definition 5.4. Then, by (5.1)-(5.5) we have

$$f(x) \in F_{x_0} + \delta F^T \cdot ([x] - x_0) =: S_{m;1}$$

and

$$f(x) \in F_{x_0} + \delta F_{x_0}^T \cdot ([x] - x_0) + ([x] - x_0)^T \cdot \delta_2 F \cdot ([x] - x_0) =: S_{m,2}$$

with $F_{x_0} \in \mathbb{IR}$, δF_{x_0} , $\delta F \in \mathbb{IR}^n$ and $\delta_2 F \in \mathbb{IR}^{n \times n}$.

In Table 5.1, we compare the range enclosures $S_{m;1}$ and $S_{m;2}$ with $S_{c;1}$ and $S_{c;2}$ obtained via Remark 5.11. Except for the first example, we have $S_{c;1} \subseteq S_{m;1}$ and $S_{c;2} \subseteq S_{m;2}$. Furthermore, for each of the examples $S_{c;2} \subseteq S_{c;1}$ holds.

Table 5.1 Comparison of range enclosures $S_{m;1}$ and $S_{m;2}$ with $S_{c;1}$ and $S_{c;2}$.

No.	$S_{m;1}$	$S_{m;2}$	
1	[-1497.1, -973.01]	[-1494.0, -976.12]	
2	[1809.5, 2609.1]	[1816.2, 2602.5]	
3	[13 467, 19 786]	[13 467, 19 786]	
4	[2538.7, 4074.7]	[2558.4, 4055.0]	
5	[-2.1275, -1.7755]	[-2.0521, -1.8508]	
6	[5.1531, 6.5377]	[5.1529, 6.5379]	
	$S_{c;1}$	$S_{c;2}$	
1	$S_{c;1}$ [-1497.9, -972.20]	$\frac{S_{c;2}}{[-1495.2, -986.94]}$	
1 2			
-	[-1497.9, -972.20]	[-1495.2, -986.94]	
2	[-1497.9, -972.20] [1809.5, 2609.1]	[-1495.2, -986.94] [1843.0, 2602.5]	
2 3	[-1497.9, -972.20] [1809.5, 2609.1] [13 467, 19 786]	[-1495.2, -986.94] [1843.0, 2602.5] [13 619, 19 786]	

6. Conclusion. In this paper, we have shown how the automatic computation of second-order slope tuples can be performed. Here, the function expression of the underlying function may contain nonsmooth functions such as $\varphi(x) = |u(x)|$ and $\varphi(x) = \max\{u(x), v(x)\}$. Furthermore, we allow for functions given by two or more branches. Some examples illustrated that second-order slope tuples may provide sharper enclosures of the function range than first-order slope enclosures. Machine interval arithmetic yields verified range enclosures on a floating-point computer. Hence, the automatic computation of second-order slope tuples can also be applied to verified global optimization [21, 22].

REFERENCES

- [1] G. ALEFELD AND J. HERZBERGER, *Introduction to Interval Computations*, Academic Press, New York, 1983.
- [2] F. H. CLARKE, Optimization and Nonsmooth Analysis, John Wiley & Sons, New York, 1983.
- [3] P. DEUFLHARD AND A. HOHMANN, Numerical Analysis, de Gruyter, Berlin, 1995.
- [4] A. FROMMER, B. LANG, AND M. SCHNURR, A comparison of the Moore and Miranda existence tests, Computing, 72 (2004), pp. 349–354.
- [5] A. GOLDSZTEJN, Comparison of the Hansen-Sengupta and the Frommer-Lang-Schnurr existence tests, Computing, 79 (2007), pp. 53–60.
- [6] E. R. HANSEN, Interval forms of Newton's method, Computing, 20 (1978), pp. 153–163.
- [7] E. R. HANSEN AND G. W. WALSTER, Global Optimization Using Interval Analysis, Second Ed., Revised and Expanded, Marcel Dekker, New York, 2004.
- [8] R. B. KEARFOTT, Rigorous Global Search: Continuous Problems, Kluwer Academic Publishers, Dordrecht, 1996.
- [9] L. KOLEV, Use of interval slopes for the irrational part of factorable functions, Reliab. Comput., 3 (1997), pp. 83–93.
- [10] R. KRAWCZYK AND A. NEUMAIER, Interval slopes for rational functions and associated centered forms, SIAM J. Numer. Anal., 22 (1985), pp. 604–616.
- [11] R. E. MOORE, A test for existence of solutions to nonlinear systems, SIAM J. Numer. Anal., 14 (1977), pp. 611–615.
- [12] H. Muñoz and R. B. Kearfott, Slope intervals, generalized gradients, semigradients, slant derivatives, and csets, Reliab. Comput., 10 (2004), pp. 163–193.
- [13] L. B. RALL, Automatic Differentiation: Techniques and Applications, Lecture Notes in Comput. Sci., Vol. 120, Springer, Berlin, 1981.
- [14] D. RATZ, Automatic Slope Computation and its Application in Nonsmooth Global Optimization, Shaker Verlag, Aachen, 1998.

AUTOMATIC COMPUTATION OF SECOND-ORDER SLOPE TUPLES

- -, A nonsmooth global optimization technique using slopes the one-dimensional case, J. Global Optim., 14 (1999), pp. 365-393.
- [16] S. M. RUMP, Expansion and estimation of the range of nonlinear functions, Math. Comp., 65 (1996), pp. 1503-1512.
- [17] U. SCHÄFER AND M. SCHNURR, A comparison of simple tests for accuracy of approximate solutions to nonlinear systems with uncertain data, J. Ind. Manag. Optim., 2 (2006), pp. 425-434.
- [18] M. Schnurr, Webpage for software download.
- $\verb|http://iamlasun8.mathematik.uni-karlsruhe.de/~ae26/software/.$ -, On the proofs of some statements concerning the theorems of Kantorovich, Moore, and Miranda,
- Reliab. Comput., 11 (2005), pp. 77-85.
- [20] -, Computing slope enclosures by exploiting a unique point of inflection, to appear in Appl. Math. Comput.
- [21]
- —, A second-order pruning step for verified global optimization, to appear in J. Global Optim. —, Steigungen höherer Ordnung zur verifizierten globalen Optimierung, PhD thesis, Department of [22] Mathematics, Universität Karlsruhe, 2007. http://digbib.ubka.uni-karlsruhe.de/volltexte/1000007229.
- [23] M. SCHNURR AND D. RATZ, Slope enclosures for functions given by two or more branches, submitted for publication.
- [24] Z. SHEN AND M. A. WOLFE, On interval enclosures using slope arithmetic, Appl. Math. Comput., 39 (1990), pp. 89-105.
- [25] XSC Website on programming languages for scientific computing with validation. http://www.xsc.de[December 2007].