

EXISTENCE AND GLOBAL STABILITY OF PERIODIC SOLUTION FOR DELAYED DISCRETE HIGH-ORDER HOPFIELD-TYPE NEURAL NETWORKS

HONG XIANG, KE-MING YAN, AND BAI-YAN WANG

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By using coincidence degree theory as well as a priori estimates and Lyapunov functional, we study the existence and global stability of periodic solution for discrete delayed high-order Hopfield-type neural networks. We obtain some easily verifiable sufficient conditions to ensure that there exists a unique periodic solution, and all their solutions converge to such a periodic solution.

1. Introduction

It is well known that studies on neural dynamical systems not only involve discussion of stability property, but also involve other dynamics behaviors such as periodic oscillatory, bifurcation and chaos. In many applications, the property of periodic oscillatory solutions are of great interest. For example, the human brain has been in periodic oscillatory or chaos state, hence it is of prime importance to study periodic oscillatory and chaos phenomenon of neural networks. Recently, Liu and Liao [8], Zhou and Liu [15] consider the existence and global exponential stability of periodic solutions of delayed Hopfield neural networks and delayed cellular neural networks. Liu et al. [7] address the existence and global exponential stability of periodic solutions of delayed BAM neural networks. Since high-order neural networks have stronger approximation property, faster convergence rate, greater storage capacity, and higher fault tolerance than lower-order neural networks, they have attracted considerable attention (see, e.g., [1, 2, 4, 5, 10, 11, 13, 14]). In our previous paper [12], we study the global exponential stability and existence of periodic solutions of the following high-order Hopfield-type neural networks

$$\begin{aligned} \frac{dx_i(t)}{dt} = & -a_i(t)x_i(t) + \sum_{j=1}^m b_{ij}(t)f_j(x_j(t)) \\ & + \sum_{j=1}^m \tilde{b}_{ij}(t)f_j(x_j(t - \tau_{ij}(t))) + \sum_{j=1}^m \sum_{l=1}^m e_{ijl}(t)f_j(x_j(t))f_l(x_l(t)) \\ & + \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}(t)f_j(x_j(t - \sigma_{ijl}(t)))f_l(x_l(t - \sigma_{ijl}(t))) + I_i(t), \end{aligned} \quad (1.1)$$

where $i = 1, 2, \dots, m$, $t > 0$, $x_i(t)$ denotes the potential (or voltage) of the cell i at time t . $a_i(t)$ are positive ω -periodic functions, they denote the rate with which the cell i reset their potential to the resting state when isolated from the other cells and inputs. $b_{ij}(t)$, $e_{ijl}(t)$ are the first-and second-order connection weights of the neural network, respectively; $I_i(t)$ denote the i th component of an external input source introduced from outside the network to the cell i .

In [6], Li investigates global stability and existence of periodic solutions of discrete delayed cellular neural networks. However, few authors have studies the dynamical behaviors of the discrete-time analogues of delayed high-order Hopfield-type neural networks with variable coefficient. In this paper, we are concerned with the following discrete analogue of (1.1) of the form

$$\begin{aligned}
 x_i(n+1) = & e^{-a_i(n)h}x_i(n) + \theta_i(h) \sum_{j=1}^n b_{ij}(n)f_j(x_j(n)) \\
 & + \theta_i(h) \sum_{j=1}^n \tilde{b}_{ij}(n)f_j(x_j(n - \tau_{ij}(n))) + \theta_i(h) \sum_{j=1}^n \sum_{l=1}^n e_{ijl}(n)f_j(x_j(n))f_l(x_l(n)) \\
 & + \theta_i(h) \sum_{j=1}^n \sum_{l=1}^n \tilde{e}_{ijl}(n)f_j(x_j(n - \sigma_{ijl}(n)))f_l(x_l(n - \sigma_{ijl}(n))) \\
 & + \theta_i(h)I_i(n), \quad i = 1, 2, \dots, m,
 \end{aligned}
 \tag{1.2}$$

in which $\theta_i, a_i, b_{ij}, e_{ijl}, i, j, l = 1, 2, \dots, m$, will be specified in the next section.

With the help of Mawhin’s continuation theorem of coincidence degree theory and constructing Lyapunov functional, we obtain some sufficient conditions ensure that for the discrete networks (1.2) there exists a unique periodic solution, and all theirs solutions converge to such a periodic solution. To the best of our knowledge, this is the first time to study the existence and global attractivity of the periodic solution for the discrete-time analogues of delayed high-order Hopfield-type neural networks with variable coefficient.

The tree of this paper is as follows. In Section 2, following the semi-discretization technique [6, 9], we obtain a discrete-time analogue of (1.1). In Section 3, with the help of Mawhin’s continuation theorem of coincidence degree theory, we study the existence of the periodic solution of (1.2). In Section 4, by constructing Lyapunov functional, we derive sufficient conditions to ensure that the periodic solution of (1.2) is globally asymptotically stable.

2. Discrete-time analogues

There is no unique way of deriving discrete time version of dynamical equations corresponding to continuous time formulation. First, following [6, 9], we reformulate system (1.1) by an approximation of the form

$$\begin{aligned}
 \frac{dx_i(t)}{dt} = & -a_i\left(\left[\frac{t}{h}\right]h\right)x_i(t) + \sum_{j=1}^m b_{ij}\left(\left[\frac{t}{h}\right]h\right)f_j\left(x_j\left(\left[\frac{t}{h}\right]h\right)\right) \\
 & + \sum_{j=1}^m \tilde{b}_{ij}\left(\left[\frac{t}{h}\right]h\right)f_j\left(x_j\left(\left(\left[\frac{t}{h}\right]h\right) - \tau_{ij}\left(\left[\frac{t}{h}\right]h\right)\right)\right)
 \end{aligned}$$

$$\begin{aligned}
 &+ \sum_{j=1}^m \sum_{l=1}^m e_{ijl} \left(\left[\frac{t}{h} \right] h \right) f_j \left(x_j \left(\left[\frac{t}{h} \right] h \right) \right) f_l \left(x_l \left(\left[\frac{t}{h} \right] h \right) \right) \\
 &+ \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl} \left(\left[\frac{t}{h} \right] h \right) f_j \left(x_j \left(\left(\left[\frac{t}{h} \right] h \right) - \sigma_{ijl} \left(\left[\frac{t}{h} \right] h \right) \right) \right) \\
 &\times f_l \left(x_l \left(\left(\left[\frac{t}{h} \right] h \right) - \sigma_{ijl} \left(\left[\frac{t}{h} \right] h \right) \right) \right) + I_i \left(\left[\frac{t}{h} \right] h \right),
 \end{aligned} \tag{2.1}$$

where h is a positive number denoting a uniform discretization step size and $[t/h]$ denotes the greatest integer in t/h . For convenience, we denote $[t/h] = n$, $n \in Z_0^+$, and $a_i(nh) = a_i(n)$, $b_{ij}(nh) = b_{ij}(n)$, $\tilde{b}_{ij}(nh) = \tilde{b}_{ij}(n)$, $e_{ijl}(nh) = e_{ijl}(n)$, $\tilde{e}_{ijl}(nh) = \tilde{e}_{ijl}(n)$, $\tau_{ij}(nh) = \tau_{ij}$, $\sigma_{ijl}(nh) = \sigma_{ijl}$, $x_i(nh) = x_i(n)$, $I_i(nh) = I_i$. Thus (2.1) takes on the form

$$\begin{aligned}
 \frac{dx_i(t)}{dt} &= -a_i(n)x_i(t) + \sum_{j=1}^m b_{ij}(n)f_j(x_j(n)) \\
 &+ \sum_{j=1}^m \tilde{b}_{ij}(n)f_j(x_j(n - \tau_{ij}(n))) \\
 &+ \sum_{j=1}^m \sum_{l=1}^m e_{ijl}(n)f_j(x_j(n))f_l(x_l(n)) \\
 &+ \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}(n)f_j(x_j(n - \sigma_{ijl}(n))) \\
 &\times f_l(x_l(n - \sigma_{ijl}(n))) + I_i(n), \quad n \in Z_0^+.
 \end{aligned} \tag{2.2}$$

Integrate it over the interval $[nh, t]$ for $t < (n + 1)h$ to obtain

$$\begin{aligned}
 &x_i(t)e^{a_i(n)t} - x_i(n)e^{a_i(n)nh} \\
 &= \frac{e^{a_i(n)t} - e^{a_i(n)nh}}{a_i(n)} \left\{ \sum_{j=1}^m b_{ij}(n)f_j(x_j(n)) + \sum_{j=1}^m \tilde{b}_{ij}(n)f_j(x_j(n - \tau_{ij}(n))) \right. \\
 &\quad + \sum_{j=1}^m \sum_{l=1}^m e_{ijl}(n)f_j(x_j(n))f_l(x_l(n)) \\
 &\quad + \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}(n)f_j(x_j(n))f_l(x_l(n))f_l(x_l(n - \sigma_{ijl}(n))) \\
 &\quad \left. + I_i(n) \right\}, \quad i = 1, 2, \dots, m.
 \end{aligned} \tag{2.3}$$

We let $t \rightarrow (n + 1)h$ and obtain

$$\begin{aligned}
 x_i(n + 1) &= x_i(n)e^{-a_i(n)h} + \theta_i(h) \sum_{j=1}^m b_{ij}(n)f_j(x_j(n)) \\
 &\quad + \theta_i(h) \sum_{j=1}^m \tilde{b}_{ij}(n)f_j(x_j(n - \tau_{ij}(n))) \\
 &\quad + \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m e_{ijl}(n)f_j(x_j(n))f_l(x_l(n)) \\
 &\quad + \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}(n)f_j(x_j(n - \sigma_{ijl}(n)))f_l(x_l(n - \sigma_{ijl}(n))) \\
 &\quad + \theta_i(h)I_i(n), \quad i = 1, 2, \dots, m, \quad n \in Z_0^+,
 \end{aligned} \tag{2.4}$$

where

$$\theta_i(h) = \frac{1 - e^{-a_i(n)h}}{a_i(n)}, \quad i = 1, 2, \dots, m, \quad n \in Z_0^+. \tag{2.5}$$

It is not difficult to verify that $\theta_i(h) > 0$ if $a_i, h > 0$ and $\theta_i(h) \approx h + o(h^2)$ for small $h > 0$. Also, one can see that (1.2) converges towards (1.1) when $h \rightarrow 0^+$. The system (1.2) is supplemented with initial values given by

$$x_i(s) = \varphi_i(s), \quad s \in (-\tau^*, 0)_Z, \quad \tau^* = \max_{1 \leq i, j, l \leq m} \left(\max_{n \in Z} (\tau_{ij}(n), \sigma_{ijl}(n)) \right). \tag{2.6}$$

In this paper, we assume that

(H1) $a_i : Z \rightarrow (0, \infty)$, $b_{ij}, \tilde{b}_{ij}, e_{ijl}, \tilde{e}_{ijl}, I_i \in Z \rightarrow R$, $\tau_{ij}, \sigma_{ijl} : Z \rightarrow Z_0^+$, $i, j, l = 1, 2, \dots, m$, $h \in (0, \infty)$.

(H2) f_j are Lipschitzian with Lipschitz constants $L_j > 0$,

$$|f_j(x) - f_j(y)| \leq L_j|x - y| \tag{2.7}$$

for any $x, y \in R$, ($j \in \{1, \dots, m\}$).

(H3) There exist positive constants $N_j > 0$, $j \in \{1, \dots, m\}$ such that

$$|f_j(x)| \leq N_j, \quad j \in \{1, \dots, m\}. \tag{2.8}$$

For convenience, we will introduce the notation:

$$I_\omega = \{0, 1, \dots, \omega - 1\}, \quad \bar{u} = \frac{1}{\omega} \sum_{k=0}^{\omega-1} u(k), \tag{2.9}$$

where $u(k)$ an ω -periodic sequence of real numbers defined for $k \in Z$ and notations:

$$\begin{aligned}
 a_i &= \min_{n \in I_\omega} (a_i(n)), \quad i = 1, 2, \dots, m, \\
 I^M &= \max_{n \in I_\omega} \{ |I_i(n)|, i = 1, 2, \dots, m \}, \quad M = \sup_{u \in R} \{ |f_j(u)|, j = 1, 2, \dots, m \}, \\
 b_{ij}^M &= \max_{n \in I_\omega} \{ |b_{ij}(n)| \}, \quad \tilde{b}_{ij}^M = \max_{n \in I_\omega} \{ |\tilde{b}_{ij}(n)| \} \\
 e_{ijl}^M &= \max_{n \in I_\omega} \{ |e_{ijl}(n)| \}, \quad \tilde{e}_{ijl}^M = \max_{n \in I_\omega} \{ |\tilde{e}_{ijl}(n)| \}.
 \end{aligned}
 \tag{2.10}$$

3. Existence of periodic solution

In this section, based on the Mawhin’s continuation theorem and Lyapunov functional, we will study the existence of periodic solutions of discrete-time high-order Hopfield-type neural networks (1.2).

First, we will make some preparations.

Let X and Z be two Banach spaces. Consider an operator equation

$$Lx = \lambda Nx, \quad \lambda \in (0, 1), \tag{3.1}$$

where $L : \text{Dom}L \cap X \rightarrow Z$ is a linear operator and λ is a parameter. Let P and Q denote two projectors such that

$$P : X \cap \text{Dom}L \rightarrow \text{Ker}L, \quad Q : Z \rightarrow \frac{Z}{\text{Im}L}. \tag{3.2}$$

Denote by $H : \text{Im}Q \rightarrow \text{Ker}L$ is an isomorphism of $\text{Im}Q$ onto $\text{Ker}L$. In the sequel, we will use the following result of Mawhin [3, page 40].

LEMMA 3.1. *Let X and Z be two Banach spaces and L a Fredholm mapping of index zero. Assume that $N : \overline{\Omega} \rightarrow Z$ is L -compact on $\overline{\Omega}$ with Ω open bounded in X . Furthermore assume:*

(a) for each $\lambda \in (0, 1), y \in \partial\Omega \cap \text{Dom}L$,

$$Lx \neq \lambda Nx; \tag{3.3}$$

(b) for each $x \in \partial\Omega \cap \text{Ker}L$,

$$QNx \neq 0, \quad \text{deg}\{HQNx, \Omega \cap \text{Ker}L, 0\} \neq 0. \tag{3.4}$$

Then the equation $Lx = Nx$ has at least one solution in $\text{dom}L \cap \overline{\Omega}$.

Recall that a linear mapping $L : \text{Dom}L \cap x \rightarrow Z$ with $\text{Ker}L = L^{-1}(0)$ and $\text{Im}L = L(\text{Dom}L)$, will be called a Fredholm mapping if the following two conditions hold:

- (i) $\text{Ker}L$ has a finite dimension;
- (ii) $\text{Im}L$ is closed and has a finite codimension.

Recall also that the codimension of $\text{Im}L$ is the dimension of $Z/\text{Im}L$, that is, the dimension of the cokernel $\text{coker} L$ of L .

When L is a Fredholm mapping, its index is the integer $\text{Ind}L = \dim \ker L - \text{codim} \text{Im}L$.

We will say that a mapping N is L -compact on Ω if the mapping $QN : \bar{\Omega} \rightarrow Z$ is continuous, $QN(\bar{\Omega})$ is bounded, and $K_p(I - Q)N : \bar{\Omega} \rightarrow Y$ is compact, that is, it is continuous and $K_p(I - Q)N(\bar{\Omega})$ is relatively compact, where $K_p : \text{Im}L \rightarrow \text{Dom}L \cap \text{Ker}P$ is a inverse of the restriction L_p of L to $\text{Dom}L \cap \text{Ker}P$, so that $LK_p = I$ and $K_pL = I - P$.

Next, we will state and prove the existence of periodic solutions of system (1.2).

THEOREM 3.2. *Assume that the condition (H1), (H2), and (H3) are satisfied. Furthermore, assume that*

(H4) $a_i, b_{ij}, \tilde{b}_{ij}, e_{ij}, \tilde{e}_{ij}, I_i, i, j, l = 1, 2, \dots, m$, are all ω -periodic functions.

Then system (1.2) has at least one ω -periodic solution.

Proof. Similar to that of [6], we define

$$l_m = \{x = \{x(k)\} : x(k) \in R^m, k \in Z\}. \tag{3.5}$$

Let $l^\omega \subset l_m$ denote the subspace of all ω periodic sequences equipped with the usual supremum norm $\|\cdot\|$, that is,

$$\begin{aligned} \|x\| &= \left\| (x_1(k), \dots, x_m(k))^T \right\| \\ &= \sum_{i=1}^m \max_{k \in I_\omega} |x_i(k)|, \quad \text{for any } x = \{(x_1(k), \dots, x_m(k)) : k \in Z\} \in l^\omega. \end{aligned} \tag{3.6}$$

It is not difficult to show that l^ω is a finite-dimensional Banach space.

Let

$$\begin{aligned} l_0^\omega &= \left\{ x = \{x(k)\} \in l^\omega : \sum_{k=0}^{\omega-1} x(k) = 0 \right\}, \\ l_c^\omega &= \{x = \{x(k)\} \in l^\omega : x(k) = h \in R^m, k \in Z\}, \end{aligned} \tag{3.7}$$

then it follows that l_0^ω and l_c^ω are both closed linear subspaces of l^ω and

$$l^\omega = l_0^\omega \oplus l_c^\omega, \quad \dim l_c^\omega = m. \tag{3.8}$$

In order to use Lemma 3.1 to system (1.2), we take $X = Y = l^\omega$, $(Lx)(k) = x(k + 1) - x(k)$, and let

$$\begin{aligned}
 Nx(n) = & \left[\begin{array}{l}
 x_1(n)(e^{-a_1(n)h} - 1) + \theta_1(h) \sum_{j=1}^m b_{1j}(n) f_j(x_j(n)) + \\
 \vdots \\
 x_m(n)(e^{-a_m(n)h} - 1) + \theta_m(h) \sum_{j=1}^m b_{mj}(n) f_j(x_j(n)) + \\
 \theta_1(h) \sum_{j=1}^m \tilde{b}_{1j}(n) f_j(x_j(n - \tau_{1j}(n))) + \theta_1(h) I_1(n) \\
 \vdots \\
 \theta_m(h) \sum_{j=1}^m \tilde{b}_{mj}(n) f_j(x_j(n - \tau_{mj}(n))) + \theta_m(h) I_m(n) \\
 + \theta_1(h) \sum_{j=1}^m \sum_{l=1}^m e_{1jl}(n) f_j(x_j(n)) f_l(x_l(n)) + \\
 \vdots \\
 + \theta_m(h) \sum_{j=1}^m \sum_{l=1}^m e_{mjl}(n) f_j(x_j(n)) f_l(x_l(n)) + \\
 \theta_1(h) \sum_{j=1}^n \sum_{l=1}^n \tilde{e}_{1jl}(n) f_j(x_j(n - \sigma_{1jl}(n))) f_l(x_l(n - \sigma_{1jl}(n))) \\
 \vdots \\
 \theta_m(h) \sum_{j=1}^n \sum_{l=1}^n \tilde{e}_{mjl}(n) f_j(x_j(n - \sigma_{mjl}(n))) f_l(x_l(n - \sigma_{mjl}(n)))
 \end{array} \right].
 \end{aligned} \tag{3.9}$$

It is trivial to see that L is a bounded linear operator and

$$\text{Ker } L = l_c^\omega, \quad \text{Im } L = l_0^\omega, \tag{3.10}$$

as well as

$$\dim \text{Ker } L = m = \text{codim Im } L; \tag{3.11}$$

then it follows that L is a Fredholm mapping of index zero.

Define

$$Px = \frac{1}{\omega} \sum_{s=0}^{\omega-1} x(s), \quad x \in X, \quad Qz = \frac{1}{\omega} \sum_{s=0}^{\omega-1} z(s), \quad z \in Y. \tag{3.12}$$

It is not difficult to show that P and Q are continuous projectors such that

$$\text{Im } P = \text{Ker } L, \quad \text{Im } L = \text{Ker } Q = \text{Im}(I - Q). \tag{3.13}$$

Furthermore, the generalized inverse (to L) $K_p : \text{Im}L \rightarrow \text{Ker}P \cap \text{dom}L$ has the form

$$K_p(z) = \sum_{s=0}^{k-1} z(s) - \frac{1}{\omega} \sum_{s=0}^{\omega-1} (\omega - s)z(s). \tag{3.14}$$

Clearly, QN and $K_p(I - Q)N$ are continuous. Since X is a finite-dimensional Banach space, using the Arzela-Ascoli theorem, it is not difficult to show that $QN(\overline{\Omega})$, $K_p(I - Q)N(\overline{\Omega})$ are relatively compact for any open bounded set $\Omega \subset X$. Hence, N is L -compact on $\overline{\Omega}$, here Ω is any open bounded set in X .

Now we reach the position to search for an appropriate open, bounded subset Ω for the application of the Lemma 3.1. Corresponding to the operator equation $Lx = \lambda Nx$, $\lambda \in (0, 1)$, we have

$$\begin{aligned} x_i(n+1) - x_i(n) = & \lambda \left(x_i(n)(e^{-a_i(n)h} - 1) + \theta_i(h) \sum_{j=1}^m b_{ij}(n) f_j(x_j(n)) \right. \\ & + \theta_i(h) \sum_{j=1}^m \tilde{b}_{ij}(n) f_j(x_j(n - \tau_{ij}(n))) \\ & + \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m e_{ijl}(n) f_j(x_j(n)) f_l(x_l(n)) \\ & + \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}(n) f_j(x_j(n - \sigma_{ijl}(n))) f_l(x_l(n - \sigma_{ijl}(n))) \\ & \left. + \theta_i(h) I_i(n) \right), \quad i = 1, 2, \dots, m. \end{aligned} \tag{3.15}$$

Assume that $x(n) = (x_1(n), \dots, x_m(n)) \in X$ is a solution of system (3.15) for some $\lambda \in (0, 1)$, from (3.15), we obtain

$$\begin{aligned} \max_{n \in I_\omega} |x_i(n)| = & \max_{n \in I_\omega} |x_i(n+1)| \\ \leq & \left(1 + \lambda(e^{-a_i(n)h} - 1) |x_i(n)| + \lambda \theta_i(h) \sum_{j=1}^m |b_{ij}(n)| |f_j(x_j(n))| \right. \\ & + \lambda \theta_i(h) \sum_{j=1}^m \tilde{b}_{ij}(n) f_j(x_j(n - \tau_{ij}(n))) \\ & + \lambda \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m e_{ijl}(n) f_j(x_j(n)) f_l(x_l(n)) \\ & \left. + \lambda \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}(n) f_j(x_j(n - \sigma_{ijl}(n))) f_l(x_l(n - \sigma_{ijl}(n))) + \lambda \theta_i(h) I_i(n) \right) \end{aligned}$$

$$\begin{aligned} &\leq (1 + \lambda(e^{-a_i(n)h} - 1)) \max_{n \in I_\omega} |x_i(n)| + \lambda\theta_i(h)mbM + \lambda\theta_i(h)m\tilde{b}M \\ &\quad + \lambda\theta_i(h)m^2eM^2 + \lambda\theta_i(h)m^2\tilde{e}M^2 + \lambda\theta_i(h)I^M, \quad i = 1, 2, \dots, m. \end{aligned} \tag{3.16}$$

Hence,

$$\begin{aligned} &(1 - e^{-a_i(n)h}) \max_{n \in I_\omega} |x_i(n)| \\ &\leq \theta_i(h)(mbM + m\tilde{b}M + m^2eM^2 + m^2\tilde{e}M^2 + I^M), \quad i = 1, 2, \dots, m. \end{aligned} \tag{3.17}$$

That is

$$\max_{n \in I_\omega} |x_i(n)| \leq \frac{\theta_i(h)(mbM + m\tilde{b}M + m^2eM^2 + m^2\tilde{e}M^2 + I^M)}{1 - e^{-a_i(n)h}} := A_i. \tag{3.18}$$

Denote $A = \sum_{i=1}^m A_i + E$, where E is taken sufficiently large such that $\|x\| < A$, clearly, A is independent of λ . Now, we take $\Omega = \{u \in X : \|x\| < A\}$. It is clear that Ω satisfies the requirement (a) in Lemma 3.1.

When $x \in \partial\Omega \cap \text{Ker } L$, x is a constant vector in R^m with $\|x\| = A$. Furthermore, take $H : \text{Im } Q \rightarrow \text{Ker } L, r \rightarrow r$. we can let A be greater such that

$$\begin{aligned} &(x_1, \dots, x_m)HQN \begin{pmatrix} x_1 \\ \vdots \\ x_m \end{pmatrix} \\ &= \sum_{i=1}^n \left(-x_i^2 \sum_{s=0}^{\omega-1} \left(\frac{e^{-a_i(s)h} - 1}{\omega} \right) + \theta_i(h)x_i \sum_{j=1}^m \bar{b}_{ij}f_j(x_j)x_i \right. \\ &\quad + \theta_i(h)x_i \sum_{j=1}^m \tilde{b}_{ij}f_j(x_j)x_i + \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m \bar{e}_{ijl}f_j(x_j)f_l(x_l)x_i \\ &\quad \left. + \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}f_j(x_j)f_l(x_l)x_i + \theta_i(h)\bar{I}_i x_i \right) < 0. \end{aligned} \tag{3.19}$$

So for any $x \in \partial\Omega \cap \text{Ker } L, QNx \neq 0$. Furthermore, let $\Psi(r; u) = -rx + (1 - r)JQNx$, then for any $x \in \partial\Omega \cap \text{Ker } L, x^T\Psi(r; x) < 0$, we get

$$\text{deg}\{HQNx, \Omega \cap \text{Ker } L, 0\} = \text{deg}\{-x, \Omega \cap \text{Ker } L, 0\} \neq 0. \tag{3.20}$$

Condition (b) of Lemma 3.1 is also satisfied. By now we have prove that Ω satisfies all the requirements in Lemma 3.1. Hence, system (1.2) has at least one ω -periodic solution. The proof is complete. □

4. Global stability of the periodic solution

In this section, we will obtain sufficient conditions for the global asymptotic stability and global exponential stability of the periodic solution of discrete high-order Hopfield-type networks (1.2).

THEOREM 4.1. Assume that condition (H1), (H2), (H3), and (H4) are satisfied. Furthermore, assume that $\tau_{ij}(n) = \tau_{ij} \in Z^+$, $\sigma_{ijl}(n) = \sigma_{ijl} \in Z^+$, and

(H5) There exists a positive real number sequence α_i such that

$$\begin{aligned} \lambda_i &= \alpha_i(1 - e^{a_i}) - L_i \sum_{j=1}^m \alpha_j \theta_j(h) b_{ji}^M - L_i \sum_{j=1}^m \alpha_j \theta_j(h) \tilde{b}_{ji}^M - L_i \sum_{j=1}^m \sum_{l=1}^m \alpha_j \theta_j(h) e_{jil}^M M \\ &\quad - L_i \sum_{j=1}^m \sum_{l=1}^m \alpha_j \theta_j(h) \tilde{e}_{jil}^M M - L_i \sum_{j=1}^m \sum_{l=1}^m \alpha_j \theta_j(h) e_{jli}^M M \\ &\quad - L_i \sum_{j=1}^m \sum_{l=1}^m \alpha_j \theta_j(h) \tilde{e}_{jli}^M M > 0, \quad i = 1, 2, \dots, m. \end{aligned} \tag{4.1}$$

Then the ω -periodic solution of (1.2) is unique and all other solutions of (1.2) converges to its unique ω -periodic solutions.

Proof. According to Theorem 3.2, we know that (1.2) has a ω -periodic solution $x^*(n) = (x_1^*(n), x_2^*(n), \dots, x_m^*(n))^T$. Obviously, if this periodic solution is globally attractivity, then it is unique. Let $x(n) = (x_1(n), x_2(n), \dots, x_m(n))^T$ is an arbitrary solution of (1.2) and let

$$\begin{aligned} x_i(n+1) - x_i^*(n+1) &= -e^{a_i(n)h} (x_i(n) - x_i^*(n)) \\ &\quad + \theta_i(h) \sum_{j=1}^m b_{ij}(n) (f_j(x_j(n)) - f_j(x_j^*(n))) \\ &\quad + \theta_i(h) \sum_{j=1}^m \tilde{b}_{ij}(n) (f_j(x_j(n - \tau_{ij})) - f_j(x_j^*(n - \tau_{ij}))) \\ &\quad + \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m e_{ijl}(n) (f_j(x_j(n)) f_l(x_l(n)) - f_j(x_j^*(n)) f_l(x_l^*(n))) \\ &\quad + \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}(n) (f_j(x_j(n - \sigma_{ijl})) f_l(x_l(n - \sigma_{ijl}))) \\ &\quad + f_j(x_j^*(n - \sigma_{ijl})) f_l(x_l^*(n - \sigma_{ijl})), \quad i = 1, 2, \dots, m. \end{aligned} \tag{4.2}$$

Hence,

$$\begin{aligned} &|x_i(n+1) - x_i^*(n+1)| \\ &\leq -e^{a_i} |x_i(n) - x_i^*(n)| \\ &\quad + \theta_i(h) \sum_{j=1}^m b_{ij}^M L_j |x_j(n) - x_j^*(n)| \\ &\quad + \theta_i(h) \sum_{j=1}^m \tilde{b}_{ij}^M L_j |x_j(n - \tau_{ij}) - x_j^*(n - \tau_{ij})| \end{aligned}$$

$$\begin{aligned}
 & + \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m e_{ijl}^M M(L_j |x_j(n) - x_j^*(n)| + L_l |x_l(n) - x_l^*(n)|) \\
 & + \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}^M M(L_j |x_j(n - \sigma_{ijl}) - x_j^*(n - \sigma_{ijl})| \\
 & \qquad \qquad \qquad + L_l |x_l(n - \sigma_{ijl}) - x_l^*(n - \sigma_{ijl})|), \quad i=1,2,\dots,m.
 \end{aligned} \tag{4.3}$$

Define a Lyapunov functional $V(\cdot)$ by

$$\begin{aligned}
 V(n) = \sum_{i=1}^m & \left(\alpha_i |x_i(n) - x_i^*(n)| \right. \\
 & + \alpha_i \theta_i(h) \sum_{j=1}^m \tilde{b}_{ij}^M L_j \sum_{k=n}^{n+\tau_{ij}-1} |x_j(k - \tau_{ij}) - x_j^*(k - \tau_{ij})| \\
 & + \alpha_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}^M M \left(L_j \sum_{k=n}^{n+\sigma_{ijl}-1} |x_j(k - \tau_{ij}) - x_j^*(k - \tau_{ij})| \right. \\
 & \qquad \qquad \qquad \left. \left. + L_l \sum_{k=n}^{n+\sigma_{ijl}-1} |x_l(k - \tau_{ij}) - x_l^*(k - \tau_{ij})| \right) \right).
 \end{aligned} \tag{4.4}$$

Then

$$\begin{aligned}
 \Delta V(n) \leq & \sum_{i=1}^m \left(\alpha_i (e^{a_i} - 1) |x_i(n) - x_i^*(n)| + \alpha_i \theta_i(h) \sum_{j=1}^m b_{ij}^M L_j |x_j(n) - x_j^*(n)| \right. \\
 & + \alpha_i \theta_i(h) \sum_{j=1}^m \tilde{b}_{ij}^M L_j |x_j(n) - x_j^*(n)| \\
 & + \alpha_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m e_{ijl}^M M(L_j |x_j(n) - x_j^*(n)| + L_l |x_l(n) - x_l^*(n)|) \\
 & \left. + \alpha_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}^M M(L_j |x_j(n) - x_j^*(n)| + L_l |x_l(n) - x_l^*(n)|) \right) \\
 \leq & \sum_{i=1}^m \left(\alpha_i (e^{a_i} - 1) + L_i \sum_{j=1}^m \alpha_j \theta_j(h) b_{ji}^M + L_i \sum_{j=1}^m \alpha_j \theta_j(h) \tilde{b}_{ji}^M \right. \\
 & + L_i \sum_{j=1}^m \sum_{l=1}^m \alpha_j \theta_j(h) e_{jil}^M M + L_i \sum_{j=1}^m \sum_{l=1}^m \alpha_j \theta_j(h) \tilde{e}_{jil}^M M \\
 & \left. + L_i \sum_{j=1}^m \sum_{l=1}^m \alpha_j \theta_j(h) e_{jil}^M M + L_i \sum_{j=1}^m \sum_{l=1}^m \alpha_j \theta_j(h) \tilde{e}_{jil}^M M \right) |x_i(n) - x_i^*(n)| \\
 \leq & - \sum_{i=1}^m \lambda_i |x_i(n) - x_i^*(n)| \leq 0.
 \end{aligned} \tag{4.5}$$

Summing both sides of (4.5) from 0 to $n - 1$, we get

$$V(n) + \sum_{k=0}^{n-1} \left(\sum_{i=1}^m \lambda_i |x_i(k) - x_i^*(k)| \right) \leq V(0), \tag{4.6}$$

which yields

$$\sum_{k=0}^{\infty} \sum_{i=1}^m \lambda_i |x_i(k) - x_i^*(k)| \leq V(0) < \infty. \tag{4.7}$$

Therefore, we have

$$\lim_{n \rightarrow \infty} (x_i(n) - x_i^*(n)) = 0 \tag{4.8}$$

and we can conclude that the ω -periodic solution of (1.2) is globally attractivity and this completes the proof of the theorem. \square

Next, we will study global exponential stability of the periodic solution of discrete high-order Hopfield-type networks (1.2).

THEOREM 4.2. *Assume that condition (H1), (H2), (H3), and (H4) are satisfied. Furthermore, assume that $\tau_{ij}(n) = \tau_{ij} \in Z^+$, $\sigma_{ijl}(n) = \sigma_{ijl} \in Z^+$, and (H5)*

$$\begin{aligned} \underline{a}_i &> L_i \sum_{j=1}^m b_{ji}^M + L_i \sum_{j=1}^m \tilde{b}_{ji}^M + L_i \sum_{j=1}^m \sum_{l=1}^m e_{jil}^M M L_i + L_i \sum_{j=1}^m \sum_{l=1}^m e_{lji}^M M \\ &+ L_i \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{jil}^M M + L_i \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{lji}^M M, \quad i = 1, 2, \dots, m. \end{aligned} \tag{4.9}$$

Then the ω -periodic solution of (1.2) is unique and is globally exponentially stable.

Proof. According to Theorem 3.2, we know that (1.2) has a ω -periodic solution $x^*(n) = (x_1^*(n), x_2^*(n), \dots, x_m^*(n))^T$. Let $x(n) = (x_1(n), x_2(n), \dots, x_m(n))^T$ is an arbitrary solution of (1.2), then

$$\begin{aligned} &|x_i(n+1) - x_i^*(n+1)| \\ &\leq -e^{a_i} |x_i(n) - x_i^*(n)| + \theta_i(h) \sum_{j=1}^m b_{ij}^M L_j |x_j(n) - x_j^*(n)| \\ &\quad + \theta_i(h) \sum_{j=1}^m \tilde{b}_{ij}^M L_j |x_j(n - \tau_{ij}) - x_j^*(n - \tau_{ij})| \end{aligned}$$

$$\begin{aligned}
 &+ \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m e_{ijl}^M M \left(L_j |x_j(n) - x_j^*(n)| + L_l |x_l(n) - x_l^*(n)| \right) \\
 &+ \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}^M M \left(L_j |x_j(n - \sigma_{ijl}) - x_j^*(n - \sigma_{ijl})| \right. \\
 &\quad \left. + L_l |x_l(n - \sigma_{ijl}) - x_l^*(n - \sigma_{ijl})| \right), \quad i = 1, 2, \dots, m.
 \end{aligned}
 \tag{4.10}$$

Let $F_i(\cdot, \cdot)$, $i \in \{1, \dots, m\}$ be defined by

$$\begin{aligned}
 F_i(v_i, n) &= 1 - v_i e^{-a_i h} - L_i \theta_i(h) v_i \sum_{j=1}^m b_{ji}^M - L_i \theta_i(h) \sum_{j=1}^m \tilde{b}_{ji}^M v_i^{\tau_{ij}+1} \\
 &\quad - v_i L_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m e_{jil}^M - v_i L_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m e_{lji}^M M \\
 &\quad - L_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{jil}^M M v_i^{\sigma_{ji}+1} - L_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{lji}^M v_i^{\sigma_{ij}+1} M,
 \end{aligned}
 \tag{4.11}$$

where $v_i \in [1, \infty)$, $n \in I_\omega$, $i \in \{1, \dots, m\}$. Since

$$\begin{aligned}
 F_i(1, n) &= 1 - e^{-a_i h} - L_i \theta_i(h) \sum_{j=1}^m b_{ji}^M - L_i \theta_i(h) \sum_{j=1}^m \tilde{b}_{ji}^M \\
 &\quad - L_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m e_{jil}^M M - L_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m e_{lji}^M M \\
 &\quad - L_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{jil}^M M - L_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{lji}^M M \\
 &= \theta_i(h) \left(a_i - L_i \sum_{j=1}^m b_{ji}^M - L_i \sum_{j=1}^m \tilde{b}_{ji}^M - L_i \sum_{j=1}^m \sum_{l=1}^m e_{jil}^M M L_i \right. \\
 &\quad \left. - L_i \sum_{j=1}^m \sum_{l=1}^m e_{lji}^M M - L_i \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{jil}^M M - L_i \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{lji}^M M \right) \\
 &\geq \min_{1 \leq i \leq m} (\theta_i(h)) \gamma > 0, \quad i = 1, 2, \dots, m,
 \end{aligned}
 \tag{4.12}$$

where

$$\begin{aligned}
 \gamma &= a_i - L_i \sum_{j=1}^m b_{ji}^M - L_i \sum_{j=1}^m \tilde{b}_{ji}^M - L_i \sum_{j=1}^m \sum_{l=1}^m e_{jil}^M M L_i \\
 &\quad - L_i \sum_{j=1}^m \sum_{l=1}^m e_{lji}^M M - L_i \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{jil}^M M - L_i \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{lji}^M M,
 \end{aligned}
 \tag{4.13}$$

using the continuity of $F_i(v_i, n)$ on $[1, \infty)$ with respect to v_i and the fact that $F_i(v_i, n) \rightarrow -\infty$ as $v_i \rightarrow \infty$ uniformly in $n \in I_\omega$, $i = 1, 2, \dots, m$, we see that there exist $v_i^*(n) \in (1, \infty)$ such that $F_i(v_i^*(n), n) = 0$ for $n \in I_\omega$, $i = 1, 2, \dots, m$. By choosing $\lambda = \min\{v_1^*, v_2^*, \dots, v_m^*\}$, where $\lambda > 1$, we obtain $F_i(\lambda, n) \geq 0$ for $n \in I_\omega$, $i = 1, 2, \dots, m$, then

$$\begin{aligned} & \lambda e^{-a_i(n)h} + \theta_i(h)L_i\lambda \sum_{j=1}^m b_{ji}^M + \theta_i(h)L_i \sum_{j=1}^m \tilde{b}_{ji}^M \lambda^{\tau_{ji}+1} \\ & + \theta_i(h)L_i \sum_{j=1}^m \sum_{l=1}^m e_{jil}^M M L_i + \theta_i(h)L_i \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{jil}^M M \lambda^{\sigma_{ijl}+1} \leq 1. \end{aligned} \quad (4.14)$$

Now let us consider

$$u_i(n) = \lambda^n \frac{|x_i(n) - x_i^*(n)|}{\theta_i(h)}, \quad n \in (-\tau, \infty)_{\mathbb{Z}}, \quad i = 1, 2, \dots, m, \quad (4.15)$$

where $\lambda > 1$. Then it follows from (1.2) and (4.15) that

$$\begin{aligned} u_i(n+1) & \leq \lambda e^{-a_i h} u_i(n) + \lambda \sum_{j=1}^m b_{ij}^M L_j \theta_j(h) u_j(n) \\ & + \sum_{j=1}^m \tilde{b}_{ij}^M L_j \theta_j(h) \lambda^{\tau_{ij}+1} u_j(n - \tau_{ij}) \\ & + \lambda \sum_{j=1}^m \sum_{l=1}^m e_{ijl}^M M (L_j \theta_j(h) u_j(n) + L_l \theta_l(h) u_l(n)) \\ & + \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}^M M (L_j \theta_j(h) \lambda^{\sigma_{ijl}+1} u_j(n - \sigma_{ijl}) + L_l \theta_l(h) \lambda^{\sigma_{ijl}+1} u_l(n - \sigma_{ijl})). \end{aligned} \quad (4.16)$$

Define a Lyapunov functional $V(\cdot)$ by

$$\begin{aligned} V(n) & = \sum_{i=1}^m \left(u_i(n) + \sum_{j=1}^m \tilde{b}_{ij}^M L_j \theta_j(h) \lambda^{\tau_{ij}+1} \sum_{s=n-\tau_{ij}}^{n-1} u_j(s) \right. \\ & \left. + \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}^M \theta_j(h) \lambda^{\sigma_{ijl}+1} M \left(L_j \sum_{s=n-\sigma_{ijl}}^{n-1} u_j(s) + L_l \sum_{s=n-\sigma_{ijl}}^{n-1} u_l(s) ds \right) \right) \end{aligned} \quad (4.17)$$

then calculating the $\Delta V(n) = V(n + 1) - V(n)$ along (4.16), we have

$$\begin{aligned}
 \Delta V(n) &= \sum_{i=1}^m \left(u_i(n+1) - u_i(n) + \sum_{j=1}^m \tilde{b}_{ij}^M L_j \theta_j(h) \lambda^{\tau_{ij}+1} (u_j(n) - u_j(n - \tau_{ij})) \right. \\
 &\quad \left. \times \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}^M \theta_j(h) \lambda^{\sigma_{ijl}+1} M(L_j(u_j(n) - u_j(n - \sigma_{ijl})) + L_l(u_l(n) - u_l(n - \sigma_{ijl}))) \right) \\
 &\leq \sum_{i=1}^m \left((\lambda e^{-a_i h} - 1) u_i(n) + \lambda \sum_{j=1}^m b_{ij}^M L_j \theta_j(h) u_j(n) + \sum_{j=1}^m \tilde{b}_{ij}^M L_j \theta_j(h) \lambda^{\tau_{ij}+1} u_j(n) \right. \\
 &\quad + \lambda \sum_{j=1}^m \sum_{l=1}^m e_{ijl}^M M(L_j \theta_j(h) u_j(n) + L_l \theta_l(h) u_l(n)) \\
 &\quad \left. + \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}^M \lambda^{\sigma_{ijl}+1} M(L_j \theta_j(h) u_j(n) + L_l \theta_l(h) u_l(n)) \right) \\
 &\leq - \sum_{i=1}^m \left(1 - \lambda e^{-a_i h} - L_i \theta_i(h) \lambda \sum_{j=1}^m b_{ji}^M - L_i \theta_i(h) \sum_{j=1}^m \tilde{b}_{ji}^M \lambda^{\tau_{ji}+1} \right. \\
 &\quad - L_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m e_{jil}^M M - L_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m e_{lji}^M M \\
 &\quad \left. - L_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{jil}^M \lambda^{\sigma_{jil}+1} M - L_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{lji}^M \lambda^{\sigma_{lji}+1} M \right) u_i(n) \leq 0, \quad t > 0
 \end{aligned} \tag{4.18}$$

and hence from (4.17) we have

$$\sum_{i=1}^m u_i(n) \leq V(n) \leq V(0), \quad \text{for } n \in Z^+. \tag{4.19}$$

Thus

$$\begin{aligned}
 \sum_{i=1}^m u_i(n) &= \lambda^n \sum_{i=1}^m \frac{|x_i(n) - x_i^*(n)|}{\theta_i(h)} \\
 &\leq \sum_{i=1}^m \left(u_i(0) + \sum_{j=1}^m \tilde{b}_{ij}^M L_j \theta_j(h) \lambda^{\tau_{ij}+1} \sum_{s=-\tau_{ij}}^{-1} u_j(s) \right. \\
 &\quad \left. + \sum_{j=1}^m \sum_{l=1}^m \tilde{e}_{ijl}^M \theta_j(h) \lambda^{\sigma_{ijl}+1} M \left(L_j \sum_{s=-\sigma_{ijl}}^{-1} u_j(s) + L_l \sum_{s=-\sigma_{ijl}}^{-1} u_l(s) ds \right) \right)
 \end{aligned}$$

$$\begin{aligned}
 &\leq \sum_{i=1}^m \left(1 + L_i \theta_i(h) \sum_{j=1}^m b_{ji}^M \lambda^{\tau_{ji}+1} \tau_{ji} + L_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m e_{ijl}^M \lambda^{\sigma_{ijl}+1} M \sigma_{ijl} \right. \\
 &\quad \left. + L_i \theta_i(h) \sum_{j=1}^m \sum_{l=1}^m e_{lji}^M \lambda^{\sigma_{lji}+1} M \sigma_{lji} \right) \sup_{s \in [-\tau^*, 0]} |u_i(s) - u_i^*(s)| \\
 &\leq Y \left(\sum_{i=1}^m \sup_{s \in [-\tau^*, 0]} |u_i(s) - u_i^*(s)| \right),
 \end{aligned} \tag{4.20}$$

where

$$Y = \max_{1 \leq i \leq m} \left(1 + \sum_{j=1}^m b_{ij}^M L_j e^{\epsilon \tau_{ij}} \tau_{ij} + \sum_{j=1}^m \sum_{l=1}^m e_{ijl}^M e^{\epsilon \sigma_{ijl}} M \sigma_{ijl} (L_j + L_l) \right) \geq 1, \tag{4.21}$$

then

$$\begin{aligned}
 \sum_{i=1}^m |x_i(n) - x_i^*(n)| &\leq \frac{\max_{1 \leq i \leq m} (\theta_i(h))}{\min_{1 \leq i \leq m} (\theta_i(h))} Y \left(\frac{1}{\lambda} \right)^n \left(\sum_{i=1}^m \sup_{s \in [-\tau^*, 0]} |x_i(s) - x_i^*(s)| \right) \\
 &\leq \delta \left(\frac{1}{\lambda} \right)^n \left(\sum_{i=1}^m \sup_{s \in [-\tau^*, 0]} |x_i(s) - x_i^*(s)| \right),
 \end{aligned} \tag{4.22}$$

where

$$\delta = \frac{\max_{1 \leq i \leq m} (\theta_i(h))}{\min_{1 \leq i \leq m} (\theta_i(h))} Y \geq 1 \tag{4.23}$$

and we can conclude that the ω -periodic solution of (1.2) is globally exponentially stable and this completes the proof of the theorem. \square

Remark 4.3. If we let $e_{ijl}(t) = \tilde{e}_{ijl}(t) = 0$, then system (1.2) reduces to the discrete cellular neural networks, and our Theorems 3.2, 4.1, and 4.2 are [6, Theorem 3.1, Theorem 4.1, and Theorem 4.2], respectively. So our results generalized the main results of [6].

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Hong Xiang: Institute of Applied Mathematics, Lanzhou University of Technology, Lanzhou, Gansu 730050, China
E-mail address: xiangh1969@sohu.com

Ke-Ming Yan: Institute of Applied Mathematics, Lanzhou University of Technology, Lanzhou, Gansu 730050, China
E-mail address: yankm@lut.cn.

Bai-Yan Wang: Institute of Applied Mathematics, Lanzhou University of Technology, Lanzhou, Gansu 730050, China