Research Article

Forced Oscillations of Half-Linear Elliptic Equations via Picone-Type Inequality

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Picone-type inequality is established for a class of half-linear elliptic equations with forcing term, and oscillation results are derived on the basis of the Picone-type inequality. Our approach is to reduce the multi-dimensional oscillation problems to one-dimensional oscillation problems for ordinary half-linear differential equations.

1. Introduction

The *p*-Laplacian $\Delta_p v = \nabla \cdot (|\nabla v|^{p-2} \nabla v)$ arises from a variety of physical phenomena such as non-Newtonian fluids, reaction-diffusion problems, flow through porous media, nonlinear elasticity, glaciology, and petroleum extraction (cf. Díaz [1]). It is important to study the qualitative behavior (e.g., oscillatory behavior) of solutions of *p*-Laplace equations with superlinear terms and forcing terms.

Forced oscillations of superlinear elliptic equations of the form

$$\nabla \cdot \left(A(x) |\nabla v|^{\alpha - 1} \nabla v \right) + C(x) |v|^{\beta - 1} v = f(x) \quad (\beta > \alpha > 0)$$
(1.1)

were studied by Jaroš et al. [2], and the more general quasilinear elliptic equation with firstorder term

$$\nabla \cdot \left(A(x) |\nabla v|^{\alpha - 1} \nabla v \right) + (\alpha + 1) B(x) \cdot \left(|\nabla v|^{\alpha - 1} \nabla v \right) + C(x) |v|^{\beta - 1} v = f(x)$$
(1.2)

was investigated by Yoshida [3], where the dot (·) denotes the scalar product. There appears to be no known oscillation results for the case where $\alpha = \beta$. The techniques used in [2, 3] are not applicable to the case where $\alpha = \beta$.

The purpose of this paper is to establish a Picone-type inequality for the half-linear elliptic equation with the forcing term:

$$P[v] := \nabla \cdot \left(A(x) |\nabla v|^{\alpha - 1} \nabla v \right) + (\alpha + 1) B(x) \cdot \left(|\nabla v|^{\alpha - 1} \nabla v \right) + C(x) |v|^{\alpha - 1} v = f(x),$$
(1.3)

and to derive oscillation results on the basis of the Picone-type inequality. The approach used here is motivated by the paper [4] in which oscillation criteria for second-order nonlinear ordinary differential equations are studied. Our method is an adaptation of that used in [5]. Since the proofs of Theorems 2.2–3.3 are quite similar to those of [5, Theorems 1–4], we will omit them.

2. Picone-Type Inequality

Let *G* be a bounded domain in \mathbb{R}^n with piecewise smooth boundary ∂G . It is assumed that $\alpha > 0$ is a constant, $A(x) \in C(\overline{G}; (0, \infty))$, $B(x) \in C(\overline{G}; \mathbb{R}^n)$, $C(x) \in C(\overline{G}; \mathbb{R})$, and $f(x) \in C(\overline{G}; \mathbb{R})$.

The domain $\mathfrak{D}_P(G)$ of P is defined to be the set of all functions $v \in C^1(\overline{G}; \mathbb{R})$ with the property that $A(x)|\nabla v|^{\alpha-1}\nabla v \in C^1(G; \mathbb{R}^n) \cap C(\overline{G}; \mathbb{R}^n)$.

Lemma 2.1. If $v \in \mathfrak{D}_P(G)$ and $|v| \ge k_0$ for some $k_0 > 0$, then the following Picone-type inequality holds for any $u \in C^1(G; \mathbb{R})$:

$$-\nabla \cdot \left(u\varphi(u) \frac{A(x)|\nabla v|^{\alpha-1} \nabla v}{\varphi(v)} \right)$$

$$\geq -A(x) \left| \nabla u - \frac{u}{A(x)} B(x) \right|^{\alpha+1} + \left(C(x) - k_0^{-\alpha} |f(x)| \right) |u|^{\alpha+1}$$

$$+ A(x) \left[\left| \nabla u - \frac{u}{A(x)} B(x) \right|^{\alpha+1} + \alpha \left| \frac{u}{v} \nabla v \right|^{\alpha+1} - (\alpha+1) \left(\nabla u - \frac{u}{A(x)} B(x) \right) \cdot \Phi \left(\frac{u}{v} \nabla v \right) \right]$$

$$- \frac{u\varphi(u)}{\varphi(v)} (P[v] - f(x)), \qquad (2.1)$$

where $\varphi(s) = |s|^{\alpha-1}s$ $(s \in \mathbb{R})$ and $\Phi(\xi) = |\xi|^{\alpha-1}\xi$ $(\xi \in \mathbb{R}^n)$.

Proof. The following Picone identity holds for any $u \in C^1(G; \mathbb{R})$:

$$-\nabla \cdot \left(u\varphi(u) \frac{A(x)|\nabla v|^{\alpha-1} \nabla v}{\varphi(v)} \right)$$

= $-A(x) \left| \nabla u - \frac{u}{A(x)} B(x) \right|^{\alpha+1} + C(x)|u|^{\alpha+1}$
+ $A(x) \left[\left| \nabla u - \frac{u}{A(x)} B(x) \right|^{\alpha+1} + \alpha \left| \frac{u}{v} \nabla v \right|^{\alpha+1} - (\alpha+1) \left(\nabla u - \frac{u}{A(x)} B(x) \right) \cdot \Phi\left(\frac{u}{v} \nabla v \right) \right]$
 $- \frac{u\varphi(u)}{\varphi(v)} (P[v] - f(x)) - \frac{u\varphi(u)}{\varphi(v)} f(x)$
(2.2)

(see, e.g., Yoshida [6, Theorem 1.1]). Since $|v| \ge k_0$, we obtain

$$\left|\varphi(\upsilon)\right| = \left|\upsilon\right|^{\alpha} \ge k_{0}^{\alpha},\tag{2.3}$$

and therefore

$$\left|\frac{u\varphi(u)}{\varphi(v)}f(x)\right| \le |u|^{\alpha+1}k_0^{-\alpha}|f(x)|.$$
(2.4)

Combining (2.2) with (2.4) yields the desired inequality (2.1).

Theorem 2.2. Let $k_0 > 0$ be a constant. Assume that there exists a nontrivial function $u \in C^1(\overline{G}; \mathbb{R})$ such that u = 0 on ∂G and

$$M_{G}[u] := \int_{G} \left[A(x) \left| \nabla u - \frac{u}{A(x)} B(x) \right|^{\alpha+1} - \left(C(x) - k_{0}^{-\alpha} \left| f(x) \right| \right) |u|^{\alpha+1} \right] dx \le 0.$$
(2.5)

Then for every solution $v \in \mathfrak{D}_P(G)$ of (1.3), either v has a zero on \overline{G} or

$$|v(x_0)| < k_0 \quad \text{for some } x_0 \in G. \tag{2.6}$$

3. Oscillation Results

In this section we investigate forced oscillations of (1.3) in an exterior domain Ω in \mathbb{R}^n , that is, $\Omega \supset E_{r_0}$ for some $r_0 > 0$, where

$$E_r = \{ x \in \mathbb{R}^n; |x| \ge r \} \quad (r > 0).$$
(3.1)

It is assumed that $\alpha > 0$ is a constant, $A(x) \in C(\Omega; (0, \infty))$, $B(x) \in C(\Omega; \mathbb{R}^n)$, $C(x) \in C(\Omega; \mathbb{R})$, and $f(x) \in C(\Omega; \mathbb{R})$.

The domain $\mathfrak{D}_P(\Omega)$ of *P* is defined to be the set of all functions $v \in C^1(\Omega; \mathbb{R})$ with the property that $A(x)|\nabla v|^{\alpha-1}\nabla v \in C^1(\Omega; \mathbb{R}^n)$.

A solution $v \in \mathfrak{D}_P(\Omega)$ of (1.3) is said to be *oscillatory* in Ω if it has a zero in Ω_r for any r > 0, where

$$\Omega_r = \Omega \cap E_r. \tag{3.2}$$

Theorem 3.1. Assume that for any $k_0 > 0$ and any $r > r_0$ there exists a bounded domain $G \subset E_r$ such that (2.5) holds for some nontrivial $u \in C^1(\overline{G}; \mathbb{R})$ satisfying u = 0 on ∂G . Then for every solution $v \in \mathfrak{D}_P(\Omega)$ of (1.3), either v is oscillatory in Ω or

$$\liminf_{|x| \to \infty} |v(x)| = 0. \tag{3.3}$$

Theorem 3.2. Assume that for any $k_0 > 0$ and any $r > r_0$ there exists a bounded domain $G \subset E_r$ such that

$$\widetilde{M}_{G}[u] := \int_{G} \left[2^{\alpha} A(x) |\nabla u|^{\alpha+1} - \left(C(x) - 2^{\alpha} A(x)^{-\alpha} |B(x)|^{\alpha+1} - k_{0}^{-\alpha} |f(x)| \right) |u|^{\alpha+1} \right] dx \le 0$$
(3.4)

holds for some nontrivial $u \in C^1(\overline{G}; \mathbb{R})$ satisfying u = 0 on ∂G . Then for every solution $v \in \mathfrak{D}_P(\Omega)$ of (1.3), either v is oscillatory in Ω or satisfies (3.3).

Let $\overline{\{Q(x)\}}(r)$ denote the spherical mean of Q(x) over the sphere $S_r = \{x \in \mathbb{R}^n; |x| = r\}$. We define p(r) and $q_{k_0}(r)$ by

$$p(r) = \overline{\{2^{\alpha}A(x)\}}(r),$$

$$q_{k_0}(r) = \overline{\left\{C(x) - 2^{\alpha}A(x)^{-\alpha}|B(x)|^{\alpha+1} - k_0^{-\alpha}|f(x)|\right\}}(r).$$
(3.5)

Theorem 3.3. If the half-linear ordinary differential equation

$$\left(r^{n-1}p(r)|y'|^{\alpha-1}y'\right)' + r^{n-1}q_{k_0}(r)|y|^{\alpha-1}y = 0$$
(3.6)

is oscillatory at $r = \infty$ for any $k_0 > 0$, then for every solution $v \in \mathfrak{D}_P(\Omega)$ of (1.3), either v is oscillatory in Ω or satisfies (3.3).

Oscillation criteria for the half-linear differential equation (3.6) were obtained by numerous authors (see, e.g., Došlý and Řehák [7], Kusano and Naito [8], and Kusanoet al. [9]). International Journal of Differential Equations

Now we derive the following Leighton-Wintner-type oscillation result.

Corollary 3.4. If

$$\int_{r_0}^{\infty} \left(\frac{1}{r^{n-1}p(r)}\right)^{1/\alpha} dr = \infty, \qquad \int_{r_0}^{\infty} r^{n-1}q_{k_0}(r) dr = \infty$$
(3.7)

for any $k_0 > 0$, then for every solution $v \in \mathfrak{D}_P(\Omega)$ of (1.3), either v is oscillatory in Ω or satisfies (3.3).

Proof. The conclusion follows from the Leighton-Wintner oscillation criterion (see Došlý and Řehák [7, Theorem 1.2.9]).

By combining Theorem 3.3 with the results of [8, 9], we obtain Hille-Nehari-type criteria for (1.3) (cf. Došlý and Řehák [7, Section 3.1], Kusano et al. [10], and Yoshida [11, Section 8.1]).

Corollary 3.5. Assume that $q_{k_0}(r) \ge 0$ eventually and suppose that p(r) satisfies

$$\int_{r_0}^{\infty} \left(\frac{1}{r^{n-1}p(r)}\right)^{1/\alpha} dr = \infty,$$
(3.8)

and $q_{k_0}(r)$ satisfies

$$\liminf_{r \to \infty} (P(r))^{\alpha} \int_{r}^{\infty} s^{n-1} q_{k_0}(s) ds > \frac{\alpha^{\alpha}}{(\alpha+1)^{\alpha+1}},$$
(3.9)

for any $k_0 > 0$, where

$$P(r) = \int_{r_0}^r \left(\frac{1}{s^{n-1}p(s)}\right)^{1/\alpha} ds.$$
 (3.10)

Then for every solution $v \in \mathfrak{D}_{\mathbb{P}}(\Omega)$ of (1.3), either v is oscillatory in Ω or satisfies (3.3).

Corollary 3.6. Assume that $q_{k_0}(r) \ge 0$ eventually and suppose that p(r) satisfies

$$\int_{r_0}^{\infty} \left(\frac{1}{r^{n-1}p(r)}\right)^{1/\alpha} dr < \infty, \tag{3.11}$$

and $q_{k_0}(r)$ satisfies either

$$\int^{\infty} (\pi(r))^{\alpha+1} r^{n-1} q_{k_0}(r) dr = \infty$$
(3.12)

or

$$\liminf_{r \to \infty} \frac{1}{\pi(r)} \int_{r}^{\infty} (\pi(s))^{\alpha+1} s^{n-1} q_{k_0}(s) ds > \left(\frac{\alpha}{\alpha+1}\right)^{\alpha+1}$$
(3.13)

for any $k_0 > 0$ *, where*

$$\pi(r) = \int_{r}^{\infty} \left(\frac{1}{s^{n-1}p(s)}\right)^{1/\alpha} ds.$$
 (3.14)

Then for every solution $v \in \mathfrak{D}_P(\Omega)$ of (1.3), either v is oscillatory in Ω or satisfies (3.3).

Remark 3.7. If the following hypotheses are satisfied:

$$C(x) - 2^{\alpha} A(x)^{-\alpha} |B(x)|^{\alpha+1} > 0 \text{ (eventually)},$$

$$\lim_{|x| \to \infty} \frac{|f(x)|}{C(x) - 2^{\alpha} A(x)^{-\alpha} |B(x)|^{\alpha+1}} = 0,$$
(3.15)

then we observe that $q_{k_0}(r) > 0$ eventually.

Example 3.8. We consider the half-linear elliptic equation

$$\nabla \cdot \left(A(x) |\nabla v|^{\alpha - 1} \nabla v \right) + (\alpha + 1) B(x) \cdot \left(|\nabla v|^{\alpha - 1} \nabla v \right) + C(x) |v|^{\alpha - 1} v = f(x), \quad x \in \Omega,$$
(3.16)

where n = 2, $\Omega = E_1$, $A(x) = 2|x|^{-1}$, $B(x) = 2|x|^{-1-\alpha/(\alpha+1)}(\cos |x|, \sin |x|)$, $C(x) = |x|^{-1}(5/2 + \sin |x|)$, and $f(x) = |x|^{-1}e^{-|x|}$. It is easy to verify that

$$\int_{1}^{\infty} \left(\frac{1}{rp(r)}\right)^{1/\alpha} dr = \infty,$$

$$q_{k_0}(r) = \frac{1}{r} \left(\frac{1}{2} + \sin r - k_0^{-\alpha} e^{-r}\right),$$
(3.17)

and therefore

$$\int^{\infty} rq_{k_0}(r)dr = \int^{\infty} \left(\frac{1}{2} + \sin r - k_0^{-\alpha} e^{-r}\right)dr = \infty$$
(3.18)

for any $k_0 > 0$. Hence, from Corollary 3.4, we see that for every solution v of (3.16), either v is oscillatory in Ω or satisfies (3.3).

Example 3.9. We consider the half-linear elliptic equation

$$\nabla \cdot \left(A(x) |\nabla v|^{\alpha - 1} \nabla v \right) + (\alpha + 1) B(x) \cdot \left(|\nabla v|^{\alpha - 1} \nabla v \right) + C(x) |v|^{\alpha - 1} v = f(x), \quad x \in \Omega,$$
(3.19)

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where n = 2, $\Omega = E_1$, $A(x) = 2|x|^{-1}$, $B(x) = |x|^{-\alpha/(\alpha+1)}(\sin |x|, \cos |x|)$, $C(x) = 3 + \cos |x|$, and $f(x) = e^{-|x|} \sin |x|$. It is easily checked that

$$\lim_{|x| \to \infty} \frac{|f(x)|}{C(x) - 2^{\alpha} A(x)^{-\alpha} |B(x)|^{\alpha+1}} = \lim_{|x| \to \infty} \frac{e^{-|x|} |\sin|x||}{2 + \cos|x|} = 0,$$
(3.20)

and therefore $q_{k_0}(r) > 0$ eventually by Remark 3.7 . Furthermore, we observe that

$$\int_{1}^{\infty} \left(\frac{1}{rp(r)}\right)^{1/\alpha} dr = \infty,$$

$$q_{k_0}(r) = 2 + \cos r - k_0^{-\alpha} e^{-r} |\sin r|,$$

$$(P(r))^{\alpha} = 2^{-(\alpha+1)} (r-1)^{\alpha},$$

$$\int_{r}^{\infty} sq_{k_0}(s) ds = \int_{r}^{\infty} s(2 + \cos s - k_0^{-\alpha} e^{-s} |\sin s|) ds$$

$$\geq \int_{r}^{\infty} s(1 - k_0^{-\alpha} e^{-s}) ds = \infty$$
(3.21)

for any $k_0 > 0$. Hence we obtain

$$\liminf_{r \to \infty} (P(r))^{\alpha} \int_{r}^{\infty} s^{n-1} q_{k_0}(s) ds = \infty.$$
(3.22)

It follows from Corollary 3.5 that for every solution v of (3.19), either v is oscillatory in Ω or satisfies (3.3).

Example 3.10. We consider the half-linear elliptic equation

$$\nabla \cdot \left(A(x) |\nabla v|^{\alpha - 1} \nabla v \right) + (\alpha + 1) B(x) \cdot \left(|\nabla v|^{\alpha - 1} \nabla v \right) + C(x) |v|^{\alpha - 1} v = f(x), \quad x \in \Omega,$$
(3.23)

where n = 2, $\Omega = E_1$, $A(x) = |x|^{-1}e^{|x|}$, $B(x) = |x|^{-\alpha/(\alpha+1)}e^{|x|}(\cos |x|, \sin |x|)$, $C(x) = e^{2|x|}$, and f(x) is a bounded function. It is easy to see that

$$C(x) - 2^{\alpha} A(x)^{-\alpha} |B(x)|^{\alpha+1} = e^{2|x|} - 2^{\alpha} e^{|x|},$$

$$\lim_{|x| \to \infty} \frac{|f(x)|}{C(x) - 2^{\alpha} A(x)^{-\alpha} |B(x)|^{\alpha+1}} = \lim_{|x| \to \infty} \frac{|f(x)|}{e^{2|x|} - 2^{\alpha} e^{|x|}} = 0,$$
(3.24)

and hence $q_{k_0}(r) > 0$ eventually by Remark 3.7. Since f(x) is bounded, there exists a constant M > 0 such that $|f(x)| \le M$. Moreover, we see that

$$\int_{1}^{\infty} \left(\frac{1}{rp(r)}\right)^{1/\alpha} dr = \int_{1}^{\infty} \left(\frac{1}{4e^{r}}\right)^{1/2} dr < \infty,$$

$$\pi(r) = \alpha 2^{-2/\alpha} e^{-r/\alpha},$$

$$q_{k_{0}}(r) = e^{2r} - 2^{\alpha} e^{r} - k_{0}^{-\alpha} \overline{\{|f(x)|\}}(r) \ge e^{2r} - 2^{\alpha} e^{r} - k_{0}^{-\alpha} M.$$
(3.25)

If $\alpha > 1$, then

$$\int_{0}^{\infty} (\pi(r))^{\alpha+1} r q_{k_0}(r) dr \ge \frac{\alpha^{\alpha+1}}{2^{2(\alpha+1)/\alpha}} \int_{0}^{\infty} r \Big(e^{((\alpha-1)/\alpha)r} - 2^{\alpha} e^{-r/\alpha} - k_0^{-\alpha} M e^{-((\alpha+1)/\alpha)r} \Big) dr = \infty,$$
(3.26)

and if $0 < \alpha < 1$, then

$$\liminf_{r \to \infty} \frac{1}{\pi(r)} \int_{r}^{\infty} (\pi(s))^{\alpha+1} sq_{k_{0}}(s) ds$$

$$\geq \liminf_{r \to \infty} \frac{\alpha^{\alpha}}{4} e^{r/\alpha} \int_{r}^{\infty} s\left(e^{((\alpha-1)/\alpha)s} - 2^{\alpha} e^{-s/\alpha} - k_{0}^{-\alpha} M e^{-((\alpha+1)/\alpha)s}\right) ds$$

$$\geq \liminf_{r \to \infty} \frac{\alpha^{\alpha}}{4} e^{r/\alpha} \int_{r}^{\infty} \left(e^{((\alpha-1)/\alpha)s} - 2^{\alpha} e^{-s/\alpha} - k_{0}^{-\alpha} M e^{-((\alpha+1)/\alpha)s}\right) ds$$

$$= \liminf_{r \to \infty} \frac{\alpha^{\alpha}}{4} \left(\frac{\alpha}{1-\alpha} e^{r} - 2^{\alpha} \alpha - k_{0}^{-\alpha} M \frac{\alpha}{\alpha+1} e^{-r}\right) = \infty$$
(3.27)

for any $k_0 > 0$. Corollary 3.6 implies that for every solution v of (3.23), either v is oscillatory in Ω or satisfies (3.3).

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