## Research Article

# Forced Oscillations of Half-Linear Elliptic Equations via Picone-Type Inequality 

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Picone-type inequality is established for a class of half-linear elliptic equations with forcing term, and oscillation results are derived on the basis of the Picone-type inequality. Our approach is to reduce the multi-dimensional oscillation problems to one-dimensional oscillation problems for ordinary half-linear differential equations.

## 1. Introduction

The $p$-Laplacian $\Delta_{p} v=\nabla \cdot\left(|\nabla v|^{p-2} \nabla v\right)$ arises from a variety of physical phenomena such as non-Newtonian fluids, reaction-diffusion problems, flow through porous media, nonlinear elasticity, glaciology, and petroleum extraction (cf. Díaz [1]). It is important to study the qualitative behavior (e.g., oscillatory behavior) of solutions of $p$-Laplace equations with superlinear terms and forcing terms.

Forced oscillations of superlinear elliptic equations of the form

$$
\begin{equation*}
\nabla \cdot\left(A(x)|\nabla v|^{\alpha-1} \nabla v\right)+C(x)|v|^{\beta-1} v=f(x) \quad(\beta>\alpha>0) \tag{1.1}
\end{equation*}
$$

were studied by Jaroš et al. [2], and the more general quasilinear elliptic equation with firstorder term

$$
\begin{equation*}
\nabla \cdot\left(A(x)|\nabla v|^{\alpha-1} \nabla v\right)+(\alpha+1) B(x) \cdot\left(|\nabla v|^{\alpha-1} \nabla v\right)+C(x)|v|^{\beta-1} v=f(x) \tag{1.2}
\end{equation*}
$$

was investigated by Yoshida [3], where the $\operatorname{dot}(\cdot)$ denotes the scalar product. There appears to be no known oscillation results for the case where $\alpha=\beta$. The techniques used in $[2,3]$ are not applicable to the case where $\alpha=\beta$.

The purpose of this paper is to establish a Picone-type inequality for the half-linear elliptic equation with the forcing term:

$$
\begin{equation*}
P[v]:=\nabla \cdot\left(A(x)|\nabla v|^{\alpha-1} \nabla v\right)+(\alpha+1) B(x) \cdot\left(|\nabla v|^{\alpha-1} \nabla v\right)+C(x)|v|^{\alpha-1} v=f(x) \tag{1.3}
\end{equation*}
$$

and to derive oscillation results on the basis of the Picone-type inequality. The approach used here is motivated by the paper [4] in which oscillation criteria for second-order nonlinear ordinary differential equations are studied. Our method is an adaptation of that used in [5]. Since the proofs of Theorems 2.2-3.3 are quite similar to those of [5, Theorems 1-4], we will omit them.

## 2. Picone-Type Inequality

Let $G$ be a bounded domain in $\mathbb{R}^{n}$ with piecewise smooth boundary $\partial G$. It is assumed that $\alpha>0$ is a constant, $A(x) \in C(\bar{G} ;(0, \infty)), B(x) \in C\left(\bar{G} ; \mathbb{R}^{n}\right), C(x) \in C(\bar{G} ; \mathbb{R})$, and $f(x) \in$ $C(\bar{G} ; \mathbb{R})$.

The domain $\Phi_{P}(G)$ of $P$ is defined to be the set of all functions $v \in C^{1}(\bar{G} ; \mathbb{R})$ with the property that $A(x)|\nabla v|^{\alpha-1} \nabla v \in C^{1}\left(G ; \mathbb{R}^{n}\right) \cap C\left(\bar{G} ; \mathbb{R}^{n}\right)$.

Lemma 2.1. If $v \in \Phi_{P}(G)$ and $|v| \geq k_{0}$ for some $k_{0}>0$, then the following Picone-type inequality holds for any $u \in C^{1}(G ; \mathbb{R})$ :

$$
\begin{align*}
-\nabla \cdot & \left(u \varphi(u) \frac{A(x)|\nabla v|^{\alpha-1} \nabla v}{\varphi(v)}\right) \\
\geq & -A(x)\left|\nabla u-\frac{u}{A(x)} B(x)\right|^{\alpha+1}+\left(C(x)-k_{0}^{-\alpha}|f(x)|\right)|u|^{\alpha+1} \\
& +A(x)\left[\left|\nabla u-\frac{u}{A(x)} B(x)\right|^{\alpha+1}+\alpha\left|\frac{u}{v} \nabla v\right|^{\alpha+1}-(\alpha+1)\left(\nabla u-\frac{u}{A(x)} B(x)\right) \cdot \Phi\left(\frac{u}{v} \nabla v\right)\right] \\
& -\frac{u \varphi(u)}{\varphi(v)}(P[v]-f(x)), \tag{2.1}
\end{align*}
$$

where $\varphi(s)=|s|^{\alpha-1} s(s \in \mathbb{R})$ and $\Phi(\xi)=|\xi|^{\alpha-1} \xi\left(\xi \in \mathbb{R}^{n}\right)$.

Proof. The following Picone identity holds for any $u \in C^{1}(G ; \mathbb{R})$ :

$$
\begin{align*}
-\nabla \cdot & \left(u \varphi(u) \frac{A(x)|\nabla v|^{\alpha-1} \nabla v}{\varphi(v)}\right) \\
= & -A(x)\left|\nabla u-\frac{u}{A(x)} B(x)\right|^{\alpha+1}+C(x)|u|^{\alpha+1} \\
& +A(x)\left[\left|\nabla u-\frac{u}{A(x)} B(x)\right|^{\alpha+1}+\alpha\left|\frac{u}{v} \nabla v\right|^{\alpha+1}-(\alpha+1)\left(\nabla u-\frac{u}{A(x)} B(x)\right) \cdot \Phi\left(\frac{u}{v} \nabla v\right)\right] \\
& -\frac{u \varphi(u)}{\varphi(v)}(P[v]-f(x))-\frac{u \varphi(u)}{\varphi(v)} f(x) \tag{2.2}
\end{align*}
$$

(see, e.g., Yoshida [6, Theorem 1.1]). Since $|v| \geq k_{0}$, we obtain

$$
\begin{equation*}
|\varphi(v)|=|v|^{\alpha} \geq k_{0}^{\alpha}, \tag{2.3}
\end{equation*}
$$

and therefore

$$
\begin{equation*}
\left|\frac{u \varphi(u)}{\varphi(v)} f(x)\right| \leq|u|^{\alpha+1} k_{0}^{-\alpha}|f(x)| \tag{2.4}
\end{equation*}
$$

Combining (2.2) with (2.4) yields the desired inequality (2.1).
Theorem 2.2. Let $k_{0}>0$ be a constant. Assume that there exists a nontrivial function $u \in C^{1}(\bar{G} ; \mathbb{R})$ such that $u=0$ on $\partial G$ and

$$
\begin{equation*}
M_{G}[u]:=\int_{G}\left[A(x)\left|\nabla u-\frac{u}{A(x)} B(x)\right|^{\alpha+1}-\left(C(x)-k_{0}^{-\alpha}|f(x)|\right)|u|^{\alpha+1}\right] d x \leq 0 \tag{2.5}
\end{equation*}
$$

Then for every solution $v \in \Phi_{P}(G)$ of (1.3), either $v$ has a zero on $\bar{G}$ or

$$
\begin{equation*}
\left|v\left(x_{0}\right)\right|<k_{0} \quad \text { for some } x_{0} \in G . \tag{2.6}
\end{equation*}
$$

## 3. Oscillation Results

In this section we investigate forced oscillations of (1.3) in an exterior domain $\Omega$ in $\mathbb{R}^{n}$, that is, $\Omega \supset E_{r_{0}}$ for some $r_{0}>0$, where

$$
\begin{equation*}
E_{r}=\left\{x \in \mathbb{R}^{n} ;|x| \geq r\right\} \quad(r>0) \tag{3.1}
\end{equation*}
$$

It is assumed that $\alpha>0$ is a constant, $A(x) \in C(\Omega ;(0, \infty)), B(x) \in C\left(\Omega ; \mathbb{R}^{n}\right), C(x) \in C(\Omega ; \mathbb{R})$, and $f(x) \in C(\Omega ; \mathbb{R})$.

The domain $\Phi_{P}(\Omega)$ of $P$ is defined to be the set of all functions $v \in C^{1}(\Omega ; \mathbb{R})$ with the property that $A(x)|\nabla v|^{\alpha-1} \nabla v \in C^{1}\left(\Omega ; \mathbb{R}^{n}\right)$.

A solution $v \in \Phi_{P}(\Omega)$ of (1.3) is said to be oscillatory in $\Omega$ if it has a zero in $\Omega_{r}$ for any $r>0$, where

$$
\begin{equation*}
\Omega_{r}=\Omega \cap E_{r} . \tag{3.2}
\end{equation*}
$$

Theorem 3.1. Assume that for any $k_{0}>0$ and any $r>r_{0}$ there exists a bounded domain $G \subset E_{r}$ such that (2.5) holds for some nontrivial $u \in C^{1}(\bar{G} ; \mathbb{R})$ satisfying $u=0$ on $\partial G$. Then for every solution $v \in \boldsymbol{\Phi}_{P}(\Omega)$ of (1.3), either $v$ is oscillatory in $\Omega$ or

$$
\begin{equation*}
\liminf _{|x| \rightarrow \infty}|v(x)|=0 \tag{3.3}
\end{equation*}
$$

Theorem 3.2. Assume that for any $k_{0}>0$ and any $r>r_{0}$ there exists a bounded domain $G \subset E_{r}$ such that

$$
\begin{equation*}
\widetilde{M}_{G}[u]:=\int_{G}\left[2^{\alpha} A(x)|\nabla u|^{\alpha+1}-\left(C(x)-2^{\alpha} A(x)^{-\alpha}|B(x)|^{\alpha+1}-k_{0}^{-\alpha}|f(x)|\right)|u|^{\alpha+1}\right] d x \leq 0 \tag{3.4}
\end{equation*}
$$

holds for some nontrivial $u \in C^{1}(\bar{G} ; \mathbb{R})$ satisfying $u=0$ on $\partial G$. Then for every solution $v \in \mathbb{D}_{P}(\Omega)$ of (1.3), either $v$ is oscillatory in $\Omega$ or satisfies (3.3).

Let $\overline{\{Q(x)\}}(r)$ denote the spherical mean of $Q(x)$ over the sphere $S_{r}=\left\{x \in \mathbb{R}^{n} ;|x|=\right.$ $r\}$. We define $p(r)$ and $q_{k_{0}}(r)$ by

$$
\begin{align*}
p(r) & =\overline{\left\{2^{\alpha} A(x)\right\}}(r), \\
q_{k_{0}}(r) & =\overline{\left\{C(x)-2^{\alpha} A(x)^{-\alpha}|B(x)|^{\alpha+1}-k_{0}^{-\alpha}|f(x)|\right\}}(r) . \tag{3.5}
\end{align*}
$$

Theorem 3.3. If the half-linear ordinary differential equation

$$
\begin{equation*}
\left(r^{n-1} p(r)\left|y^{\prime}\right|^{\alpha-1} y^{\prime}\right)^{\prime}+r^{n-1} q_{k_{0}}(r)|y|^{\alpha-1} y=0 \tag{3.6}
\end{equation*}
$$

is oscillatory at $r=\infty$ for any $k_{0}>0$, then for every solution $v \in \Phi_{P}(\Omega)$ of (1.3), either $v$ is oscillatory in $\Omega$ or satisfies (3.3).

Oscillation criteria for the half-linear differential equation (3.6) were obtained by numerous authors (see, e.g., Došlý and Řehák [7], Kusano and Naito [8], and Kusanoet al. [9]).

Now we derive the following Leighton-Wintner-type oscillation result.
Corollary 3.4. If

$$
\begin{equation*}
\int_{r_{0}}^{\infty}\left(\frac{1}{r^{n-1} p(r)}\right)^{1 / \alpha} d r=\infty, \quad \int^{\infty} r^{n-1} q_{k_{0}}(r) d r=\infty \tag{3.7}
\end{equation*}
$$

for any $k_{0}>0$, then for every solution $v \in \Phi_{P}(\Omega)$ of (1.3), either $v$ is oscillatory in $\Omega$ or satisfies (3.3).

Proof. The conclusion follows from the Leighton-Wintner oscillation criterion (see Došly and Ǩehák [7, Theorem 1.2.9]).

By combining Theorem 3.3 with the results of [8, 9], we obtain Hille-Nehari-type criteria for (1.3) (cf. Došlý and Řehák [7, Section 3.1], Kusano et al. [10], and Yoshida [11, Section 8.1]).

Corollary 3.5. Assume that $q_{k_{0}}(r) \geq 0$ eventually and suppose that $p(r)$ satisfies

$$
\begin{equation*}
\int_{r_{0}}^{\infty}\left(\frac{1}{r^{n-1} p(r)}\right)^{1 / \alpha} d r=\infty, \tag{3.8}
\end{equation*}
$$

and $q_{k_{0}}(r)$ satisfies

$$
\begin{equation*}
\liminf _{r \rightarrow \infty}(P(r))^{\alpha} \int_{r}^{\infty} s^{n-1} q_{k_{0}}(s) d s>\frac{\alpha^{\alpha}}{(\alpha+1)^{\alpha+1}}, \tag{3.9}
\end{equation*}
$$

for any $k_{0}>0$, where

$$
\begin{equation*}
P(r)=\int_{r_{0}}^{r}\left(\frac{1}{s^{n-1} p(s)}\right)^{1 / \alpha} d s . \tag{3.10}
\end{equation*}
$$

Then for every solution $v \in \Phi_{P}(\Omega)$ of (1.3), either $v$ is oscillatory in $\Omega$ or satisfies (3.3).
Corollary 3.6. Assume that $q_{k_{0}}(r) \geq 0$ eventually and suppose that $p(r)$ satisfies

$$
\begin{equation*}
\int_{r_{0}}^{\infty}\left(\frac{1}{r^{n-1} p(r)}\right)^{1 / \alpha} d r<\infty, \tag{3.11}
\end{equation*}
$$

and $q_{k_{0}}(r)$ satisfies either

$$
\begin{equation*}
\int^{\infty}(\pi(r))^{\alpha+1} r^{n-1} q_{k_{0}}(r) d r=\infty \tag{3.12}
\end{equation*}
$$

or

$$
\begin{equation*}
\liminf _{r \rightarrow \infty} \frac{1}{\pi(r)} \int_{r}^{\infty}(\pi(s))^{\alpha+1} s^{n-1} q_{k_{0}}(s) d s>\left(\frac{\alpha}{\alpha+1}\right)^{\alpha+1} \tag{3.13}
\end{equation*}
$$

for any $k_{0}>0$, where

$$
\begin{equation*}
\pi(r)=\int_{r}^{\infty}\left(\frac{1}{s^{n-1} p(s)}\right)^{1 / \alpha} d s \tag{3.14}
\end{equation*}
$$

Then for every solution $v \in \Phi_{P}(\Omega)$ of (1.3), either $v$ is oscillatory in $\Omega$ or satisfies (3.3).
Remark 3.7. If the following hypotheses are satisfied:

$$
\begin{gather*}
C(x)-2^{\alpha} A(x)^{-\alpha}|B(x)|^{\alpha+1}>0 \text { (eventually) } \\
\lim _{|x| \rightarrow \infty} \frac{|f(x)|}{C(x)-2^{\alpha} A(x)^{-\alpha}|B(x)|^{\alpha+1}}=0 \tag{3.15}
\end{gather*}
$$

then we observe that $q_{k_{0}}(r)>0$ eventually.
Example 3.8. We consider the half-linear elliptic equation

$$
\begin{equation*}
\nabla \cdot\left(A(x)|\nabla v|^{\alpha-1} \nabla v\right)+(\alpha+1) B(x) \cdot\left(|\nabla v|^{\alpha-1} \nabla v\right)+C(x)|v|^{\alpha-1} v=f(x), \quad x \in \Omega \tag{3.16}
\end{equation*}
$$

where $n=2, \Omega=E_{1}, A(x)=2|x|^{-1}, B(x)=2|x|^{-1-\alpha /(\alpha+1)}(\cos |x|, \sin |x|), C(x)=|x|^{-1}(5 / 2+$ $\sin |x|)$, and $f(x)=|x|^{-1} e^{-|x|}$. It is easy to verify that

$$
\begin{gather*}
\int_{1}^{\infty}\left(\frac{1}{r p(r)}\right)^{1 / \alpha} d r=\infty  \tag{3.17}\\
q_{k_{0}}(r)=\frac{1}{r}\left(\frac{1}{2}+\sin r-k_{0}^{-\alpha} e^{-r}\right),
\end{gather*}
$$

and therefore

$$
\begin{equation*}
\int^{\infty} r q_{k_{0}}(r) d r=\int^{\infty}\left(\frac{1}{2}+\sin r-k_{0}^{-\alpha} e^{-r}\right) d r=\infty \tag{3.18}
\end{equation*}
$$

for any $k_{0}>0$. Hence, from Corollary 3.4, we see that for every solution $v$ of (3.16), either $v$ is oscillatory in $\Omega$ or satisfies (3.3).

Example 3.9. We consider the half-linear elliptic equation

$$
\begin{equation*}
\nabla \cdot\left(A(x)|\nabla v|^{\alpha-1} \nabla v\right)+(\alpha+1) B(x) \cdot\left(|\nabla v|^{\alpha-1} \nabla v\right)+C(x)|v|^{\alpha-1} v=f(x), \quad x \in \Omega \tag{3.19}
\end{equation*}
$$

where $n=2, \Omega=E_{1}, A(x)=2|x|^{-1}, B(x)=|x|^{-\alpha /(\alpha+1)}(\sin |x|, \cos |x|), C(x)=3+\cos |x|$, and $f(x)=e^{-|x|} \sin |x|$. It is easily checked that

$$
\begin{equation*}
\lim _{|x| \rightarrow \infty} \frac{|f(x)|}{C(x)-2^{\alpha} A(x)^{-\alpha}|B(x)|^{\alpha+1}}=\lim _{|x| \rightarrow \infty} \frac{e^{-|x|}|\sin | x| |}{2+\cos |x|}=0 \tag{3.20}
\end{equation*}
$$

and therefore $q_{k_{0}}(r)>0$ eventually by Remark 3.7. Furthermore, we observe that

$$
\begin{align*}
\int_{1}^{\infty}\left(\frac{1}{r p(r)}\right)^{1 / \alpha} d r & =\infty, \\
q_{k_{0}}(r) & =2+\cos r-k_{0}^{-\alpha} e^{-r}|\sin r|, \\
(P(r))^{\alpha} & =2^{-(\alpha+1)}(r-1)^{\alpha},  \tag{3.21}\\
\int_{r}^{\infty} s q_{k_{0}}(s) d s & =\int_{r}^{\infty} s\left(2+\cos s-k_{0}^{-\alpha} e^{-s}|\sin s|\right) d s \\
& \geq \int_{r}^{\infty} s\left(1-k_{0}^{-\alpha} e^{-s}\right) d s=\infty
\end{align*}
$$

for any $k_{0}>0$. Hence we obtain

$$
\begin{equation*}
\liminf _{r \rightarrow \infty}(P(r))^{\alpha} \int_{r}^{\infty} s^{n-1} q_{k_{0}}(s) d s=\infty \tag{3.22}
\end{equation*}
$$

It follows from Corollary 3.5 that for every solution $v$ of (3.19), either $v$ is oscillatory in $\Omega$ or satisfies (3.3).

Example 3.10. We consider the half-linear elliptic equation

$$
\begin{equation*}
\nabla \cdot\left(A(x)|\nabla v|^{\alpha-1} \nabla v\right)+(\alpha+1) B(x) \cdot\left(|\nabla v|^{\alpha-1} \nabla v\right)+C(x)|v|^{\alpha-1} v=f(x), \quad x \in \Omega \tag{3.23}
\end{equation*}
$$

where $n=2, \Omega=E_{1}, A(x)=|x|^{-1} e^{|x|}, B(x)=|x|^{-\alpha /(\alpha+1)} e^{|x|}(\cos |x|, \sin |x|), C(x)=e^{2|x|}$, and $f(x)$ is a bounded function. It is easy to see that

$$
\begin{gather*}
C(x)-2^{\alpha} A(x)^{-\alpha}|B(x)|^{\alpha+1}=e^{2|x|}-2^{\alpha} e^{|x|}, \\
\lim _{|x| \rightarrow \infty} \frac{|f(x)|}{C(x)-2^{\alpha} A(x)^{-\alpha}|B(x)|^{\alpha+1}}=\lim _{|x| \rightarrow \infty} \frac{|f(x)|}{e^{2|x|}-2^{\alpha} e^{|x|}}=0, \tag{3.24}
\end{gather*}
$$

and hence $q_{k_{0}}(r)>0$ eventually by Remark 3.7. Since $f(x)$ is bounded, there exists a constant $M>0$ such that $|f(x)| \leq M$. Moreover, we see that

$$
\begin{align*}
& \int_{1}^{\infty}\left(\frac{1}{r p(r)}\right)^{1 / \alpha} d r=\int_{1}^{\infty}\left(\frac{1}{4 e^{r}}\right)^{1 / 2} d r<\infty \\
& \pi(r)=\alpha 2^{-2 / \alpha} e^{-r / \alpha}  \tag{3.25}\\
& q_{k_{0}}(r)=e^{2 r}-2^{\alpha} e^{r}-k_{0}^{-\alpha} \overline{\{|f(x)|\}}(r) \geq e^{2 r}-2^{\alpha} e^{r}-k_{0}^{-\alpha} M
\end{align*}
$$

If $\alpha>1$, then

$$
\begin{equation*}
\int^{\infty}(\pi(r))^{\alpha+1} r q_{k_{0}}(r) d r \geq \frac{\alpha^{\alpha+1}}{2^{2(\alpha+1) / \alpha}} \int^{\infty} r\left(e^{((\alpha-1) / \alpha) r}-2^{\alpha} e^{-r / \alpha}-k_{0}^{-\alpha} M e^{-((\alpha+1) / \alpha) r}\right) d r=\infty \tag{3.26}
\end{equation*}
$$

and if $0<\alpha<1$, then

$$
\begin{align*}
& \liminf _{r \rightarrow \infty} \frac{1}{\pi(r)} \int_{r}^{\infty}(\pi(s))^{\alpha+1} s q_{k_{0}}(s) d s \\
& \quad \geq \liminf _{r \rightarrow \infty} \frac{\alpha^{\alpha}}{4} e^{r / \alpha} \int_{r}^{\infty} s\left(e^{((\alpha-1) / \alpha) s}-2^{\alpha} e^{-s / \alpha}-k_{0}^{-\alpha} M e^{-((\alpha+1) / \alpha) s}\right) d s  \tag{3.27}\\
& \quad \geq \liminf _{r \rightarrow \infty} \frac{\alpha^{\alpha}}{4} e^{r / \alpha} \int_{r}^{\infty}\left(e^{((\alpha-1) / \alpha) s}-2^{\alpha} e^{-s / \alpha}-k_{0}^{-\alpha} M e^{-((\alpha+1) / \alpha) s}\right) d s \\
& \quad=\liminf _{r \rightarrow \infty} \frac{\alpha^{\alpha}}{4}\left(\frac{\alpha}{1-\alpha} e^{r}-2^{\alpha} \alpha-k_{0}^{-\alpha} M \frac{\alpha}{\alpha+1} e^{-r}\right)=\infty
\end{align*}
$$

for any $k_{0}>0$. Corollary 3.6 implies that for every solution $v$ of (3.23), either $v$ is oscillatory in $\Omega$ or satisfies (3.3).

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