

**THEOREMS ON ASSOCIATION OF VARIABLES IN
 MULTIDIMENSIONAL LAPLACE TRANSFORMS**

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ABSTRACT. The inverse of the multidimensional Laplace transform is often obtained by the method of association of variables. In this paper, some basic theorems are developed for evaluating the associated transform of certain types of transformed functions. Many useful associated pairs can be produced with the aid of these fundamental theorems. Several illustrative examples are included.

KEY WORDS AND PHRASES. Multidimensional Laplace transforms, association of variables, associated pair and associated transform.

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1. INTRODUCTION.

In non-linear systems analysis, multidimensional Laplace transform is applied to solve Volterra model. The special technique often used for the inverse Laplace transform solution is known as the association of variables. Suppose $F(s_1, s_2, \dots, s_n)$ be a Laplace transform. Its n-dimensional inverse is given by the integral

$$\begin{aligned}
 f(t_1, t_2, \dots, t_n) &\equiv L_n^{-1}[F(s_1, s_2, \dots, s_n); t_1, t_2, \dots, t_n] \\
 &= \frac{1}{(2\pi i)^n} \int_{\alpha_1 - i\infty}^{\alpha_1 + i\infty} \dots \int_{\alpha_n - i\infty}^{\alpha_n + i\infty} \exp\left(\sum_{j=1}^n s_j t_j\right) \\
 &\quad \cdot F(s_1, s_2, \dots, s_n) ds_1 ds_2 \dots ds_n
 \end{aligned}
 \tag{1.1}$$

In certain types of systems analysis, particularly in Volterra series applications [1-2] on non-linear systems [3-5], it becomes essential to invert the n-dimensional Laplace transform and specify the inverse image at a single variable, t. We denote this image function of one variable as

$$g(t) = f(t_1, t_2, \dots, t_n) \Big|_{t_1=t_2=\dots=t_n=t}
 \tag{1.2}$$

One approach to obtain the time function, g(t), is to associate with $F(s_1, s_2, \dots, s_n)$ a function G(s) from which an application of the one-dimensional inverse transform

yields $g(t)$. This particular approach is called the Association of Variables. The function $G(s)$ is said to be the associated transform of $F(s_1, s_2, \dots, s_n)$.

Chen and Chiu [6] and Koh [7] have presented several theorems for evaluating $G(s)$ for certain types of $F(s_1, s_2, \dots, s_n)$. In this paper, some additional theorems are developed. Few examples are also included for each theorem. However, once the fundamental theorems are established, it is possible to derive as many associated pairs as one desires, and use them flexibly.

2. THEOREMS ON ASSOCIATION OF VARIABLES

Suppose $G(s)$ be the associated transform of $F(s_1, s_2, \dots, s_n)$ and $G_1(s)$ be that of $F(s_1, s_2, \dots, s_{m-1}, s_{m+1}, \dots, s_n)$, $m \leq n$. Let k be any constant, and we restrict the variables s, s_1, s_2, \dots, s_n to the right half of the complex plane.

Theorem 2.1. If a given function $F(s_1, s_2, \dots, s_n)$ can be written in the form

$$F(s_1, s_2, \dots, s_n) = \frac{k}{s_m(s_m+a)} F_1(s_1, s_2, \dots, s_{m-1}, s_{m+1}, \dots, s_n)$$

and if $F_1(s_1, s_2, \dots, s_{m-1}, s_{m+1}, \dots, s_n) \xrightarrow{A_{n-1}} G_1(s)$. Then the associated transform

$$F(s_1, s_2, \dots, s_n) \xrightarrow{A_n} G(s) = \frac{k}{a} [G_1(s) - G_1(s+a)]$$

where A_n means the association process for finding $G(s)$ from $F(s_1, s_2, \dots, s_n)$. A_{n-1} has the similar meaning.

Proof: By Equations (1.1) and (1.2), we have

$$\begin{aligned} g(t) &= f(t_1, t_2, \dots, t_n) |_{t_1=t_2=\dots=t_n=t} \\ &= L_n^{-1}[F(s_1, s_2, \dots, s_n); t_1, t_2, \dots, t_n] |_{t_1=t_2=\dots=t_n=t} \\ &= \frac{1}{(2\pi i)^n} \int_{\alpha_1-i\infty}^{\alpha_1+i\infty} \int_{\alpha_2-i\infty}^{\alpha_2+i\infty} \dots \int_{\alpha_n-i\infty}^{\alpha_n+i\infty} F(s_1, s_2, \dots, s_n) \\ &\quad \cdot \exp\left(\sum_{j=1}^n s_j t\right) ds_1 ds_2 \dots ds_n \\ &= \frac{1}{(2\pi i)^n} \int_{\alpha_1-i\infty}^{\alpha_1+i\infty} \dots \int_{\alpha_n-i\infty}^{\alpha_n+i\infty} \frac{k}{s_m(s_m+a)} F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n) \\ &\quad \cdot \exp\left(\sum_{j=1}^n s_j t\right) ds_1 ds_2 \dots ds_n \end{aligned}$$

$$\begin{aligned}
 &= \frac{1}{2\pi i} \int_{\alpha_m - i\infty}^{\alpha_m + i\infty} \frac{k}{s_m(s_m+a)} \exp(s_m t) ds_m . \\
 &\frac{1}{(2\pi i)^{n-1}} \int_{\alpha_1 - i\infty}^{\alpha_1 + i\infty} \dots \int_{\alpha_{m-1} - i\infty}^{\alpha_{m-1} + i\infty} \int_{\alpha_{m+1} - i\infty}^{\alpha_{m+1} + i\infty} \dots \int_{\alpha_n - i\infty}^{\alpha_n + i\infty} \\
 &F(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n) \exp\left(\sum_{\substack{j=1 \\ j \neq m}}^n s_j t\right) ds_1 \dots ds_{m-1} ds_{m+1} \dots ds_n \\
 &= k L_1^{-1}\left[\frac{1}{s_m(s_m+a)}; t\right] L_{n-1}^{-1}[F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n); t, t, \dots, t]
 \end{aligned}$$

Using the table of inverse Laplace transform given in [8], we get

$$\begin{aligned}
 g(t) &= k \frac{1 - \exp(-at)}{a} g_1(t) \\
 &= \frac{k}{a} [g_1(t) - \exp(-at)g_1(t)]
 \end{aligned} \tag{2.1}$$

Taking Laplace transform of both sides of the Equation (2.1) yields

$$G(s) = \frac{k}{a} [G_1(s) - G_1(s+a)] .$$

Hence the theorem is proved.

Example 2.1

Consider

$$F(s_1, s_2, s_3) = \frac{k}{s_3(s_1+a)(s_2+b)(s_3+c)}$$

and let

$$F_1(s_1, s_2) = \frac{1}{(s_1+a)(s_2+b)}$$

Using the table given in [6]

$$F_1(s_1, s_2) \xrightarrow{A_2} G_1(s) = \frac{1}{s+a+b}$$

By Theorem 2.1,

$$\begin{aligned}
 F(s_1, s_2, s_3) &\xrightarrow{A_3} G(s) = \frac{k}{c} \left[\frac{1}{s+a+b} - \frac{1}{s+a+b+c} \right] \\
 &= \frac{k}{(s+a+b)(s+a+b+c)}
 \end{aligned}$$

Example 2.2

Let

$$F(s_1, s_2, s_3) = \frac{k}{[a(s_1+s_2)^2 + b(s_1+s_2) + c]s_3(s_3+d)}$$

and

$$F_1(s_1, s_2) = \frac{1}{a(s_1+s_2)^2 + b(s_1+s_2) + c}$$

Use of the table given in [6] gives

$$F_1(s_1, s_2) \xrightarrow{A_2} G_1(s) = \frac{1}{as^2 + bs + c}$$

Theorem 2.1 yields

$$\begin{aligned} F(s_1, s_2, s_3) \xrightarrow{A_3} G(s) &= \frac{k}{d} \left[\frac{1}{as^2 + bs + c} - \frac{1}{a(s+d)^2 + b(s+d) + c} \right] \\ &= \frac{k(2as + ad + b)}{(as^2 + bs + c)\{a(s+d)^2 + b(s+d) + c\}} \end{aligned}$$

Theorem 2.2. If a given function $F(s_1, s_2, \dots, s_n)$ can be factored in the form

$$F(s_1, s_2, \dots, s_n) = \frac{k(s_m + a)}{(s_m + \alpha)(s_m + \beta)} F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n)$$

and if $F_1(s_1, s_2, \dots, s_{m-1}, s_{m+1}, \dots, s_n) \xrightarrow{A_{n-1}} G_1(s)$. Then the associated transform

$$F(s_1, s_2, \dots, s_n) \xrightarrow{A_n} G(s) = \frac{\alpha - a}{\alpha - \beta} G_1(s + \alpha) + \frac{\beta - a}{\beta - \alpha} G_1(s + \beta)$$

Proof. By Equations (1.1) and (1.2), we get

$$\begin{aligned} g(t) &= f(t_1, t_2, \dots, t_n) \Big|_{t_1=t_2=\dots=t_n=t} \\ &= L_n^{-1} [F(s_1, s_2, \dots, s_n); t_1, t_2, \dots, t_n] \Big|_{t_1=t_2=\dots=t_n=t} \\ &= \frac{1}{(2\pi i)^n} \int_{\alpha_1 - i\infty}^{\alpha_1 + i\infty} \dots \int_{\alpha_n - i\infty}^{\alpha_n + i\infty} F(s_1, s_2, \dots, s_n) \\ &\quad \cdot \exp\left(\sum_{j=1}^n s_j t\right) ds_1 \dots ds_n \\ &= \frac{1}{(2\pi i)^n} \int_{\alpha_1 - i\infty}^{\alpha_1 + i\infty} \dots \int_{\alpha_n - i\infty}^{\alpha_n + i\infty} \frac{k(s_m + a)}{(s_m + \alpha)(s_m + \beta)} F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n) \\ &\quad \cdot \exp\left(\sum_{j=1}^n s_j t\right) ds_1 ds_2 \dots ds_n \end{aligned}$$

$$\begin{aligned}
 &= \frac{1}{2\pi i} \int_{\alpha_m - i\infty}^{\alpha_m + i\infty} \frac{k(s_m + a)}{(s_m + \alpha)(s_m + \beta)} \exp(s_m t) ds_m \\
 &\cdot \frac{1}{(2\pi i)^{n-1}} \int_{\alpha_1 - i\infty}^{\alpha_1 + i\infty} \dots \int_{\alpha_{m-1} - i\infty}^{\alpha_{m-1} + i\infty} \int_{\alpha_{m+1} - i\infty}^{\alpha_{m+1} + i\infty} \dots \int_{\alpha_n - i\infty}^{\alpha_n + i\infty} \\
 &F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n) \exp\left(\sum_{\substack{j=1 \\ j \neq m}}^n s_j t\right) ds_1 \dots ds_{m-1} ds_{m+1} \dots ds_n \\
 &= k L_1^{-1}\left[\frac{(s_m + a)}{(s_m + \alpha)(s_m + \beta)}; t\right] L_{n-1}^{-1}[F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n); t, t, \dots, t]
 \end{aligned}$$

Referring to the table of inverse Laplace transform [8],

$$\begin{aligned}
 g(t) &= k\left[\frac{\alpha - a}{\alpha - \beta} \exp(-\alpha t) + \frac{\beta - a}{\beta - \alpha} \exp(-\beta t)\right] g_1(t) \\
 &= \frac{k(\alpha - a)}{\alpha - \beta} \exp(-\alpha t) g_1(t) + \frac{k(\beta - a)}{\beta - \alpha} \exp(-\beta t) g_1(t) \tag{2.2}
 \end{aligned}$$

On taking Laplace transform of both sides of Equation (2.2), we obtain

$$G(s) = \frac{k(\alpha - a)}{\alpha - \beta} G_1(s + \alpha) + \frac{k(\beta - a)}{\beta - \alpha} G_1(s + \beta)$$

This establishes the theorem.

Example 2.3

Suppose

$$F(s_1, s_2, s_3) = \frac{k(s_3 + c)}{(s_1 + a)(s_2 + b)(s_3 + \alpha)(s_3 + \beta)}$$

and let

$$F_1(s_1, s_2) = \frac{1}{(s_1 + a)(s_2 + b)} \cdot$$

From the table shown in [6],

$$F_1(s_1, s_2) \xrightarrow{A_2} G_1(s) = \frac{1}{(s + a + b)}$$

Then by using Theorem 2.2, we get

$$\begin{aligned}
 F(s_1, s_2, s_3) \xrightarrow{A_3} G(s) &= \left(\frac{\alpha - c}{\alpha - \beta}\right) \left(\frac{k}{s + \alpha + a + b}\right) + \left(\frac{\beta - c}{\beta - \alpha}\right) \left(\frac{k}{s + \beta + a + b}\right) \\
 &= \frac{k}{\alpha - \beta} \left[\frac{\alpha - c}{s + \alpha + a + b} - \frac{\beta - c}{s + \beta + a + b}\right] \\
 &= \frac{k(s + a + b + c)}{(s + \alpha + a + b)(s + \beta + a + b)}
 \end{aligned}$$

Example 2.4

Consider

$$F(s_1, s_2, s_3) = \frac{k(s_3+d)}{[a(s_1+s_2)^2+b(s_1+s_2)+c](s_3+\alpha)(s_3+\beta)}$$

and suppose

$$F_1(s_1, s_2) = \frac{1}{a(s_1+s_2)^2+b(s_1+s_2)+c}$$

Using the table shown in [6], we obtain

$$F_1(s_1, s_2) \xrightarrow{A_2} G_1(s) = \frac{1}{as^2+bs+c}$$

Then Theorem 2.2 gives the associated transform

$$\begin{aligned} F(s_1, s_2, s_3) &\xrightarrow{A_3} G(s) = k \left(\frac{\alpha-d}{\alpha-\beta}\right) \left(\frac{1}{a(s+\alpha)^2+b(s+\alpha)+c}\right) + k \left(\frac{\beta-d}{\beta-\alpha}\right) D \left(\frac{1}{a(s+\beta)^2+b(s+\beta)+c}\right) \\ &= \frac{k}{\alpha-\beta} \left[\frac{(\alpha-d)}{a(s+\alpha)^2+b(s+\alpha)+c} + \frac{(d-\beta)}{a(s+\beta)^2+b(s+\beta)+c} \right] \\ &= \frac{k d [2as+a(a+\beta)+b]+as^2+bs-a\alpha\beta}{\{a(s+\alpha)^2+b(s+\alpha)+c\}\{a(s+\beta)^2+b(s+\beta)+c\}} \end{aligned}$$

Theorem 2.3. If a function $F(s_1, s_2, \dots, s_n)$ is of the form

$$F(s_1, s_2, \dots, s_n) = \frac{k}{s_m(s_m+\alpha)^2} F_1(s_1, s_2, \dots, s_{m-1}, s_{m+1}, \dots, s_n)$$

with

$$F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n) \xrightarrow{A_{n-1}} G_1(s)$$

Then

$$F(s_1, s_2, \dots, s_n) \xrightarrow{A_n} G(s) = \frac{k}{\alpha^2} G_1(s) - \frac{k}{\alpha} \left[\frac{1}{\alpha} G_1(s+\alpha) + (-1) \frac{d}{ds} G_1(s+\alpha)\right]$$

Proof: By definitions (1.1) and (1.2)

$$\begin{aligned} g(t) &= f(t_1, t_2, \dots, t_n) |_{t_1=t_2=\dots=t_n=t} \\ &= L_n^{-1}[F(s_1, s_2, \dots, s_n); t, t, \dots, t] \end{aligned}$$

$$\begin{aligned}
 &= \frac{1}{2\pi i} \int_{\alpha_m - i\infty}^{\alpha_m + i\infty} \frac{k}{s_m (s_m + \alpha)^2} \exp(s_m t) ds_m \\
 &\cdot \frac{1}{(2\pi i)^{n-1}} \int_{\alpha_1 - i\infty}^{\alpha_1 + i\infty} \dots \int_{\alpha_{m-1} - i\infty}^{\alpha_{m-1} + i\infty} \int_{\alpha_{m+1} - i\infty}^{\alpha_{m+1} + i\infty} \dots \int_{\alpha_n - i\infty}^{\alpha_n + i\infty} \\
 &F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n) \exp\left(\sum_{\substack{j=1 \\ j \neq m}}^n s_j t\right) ds_1 \dots ds_{m-1} ds_{m+1} \dots ds_n
 \end{aligned}$$

Using the results of inverse Laplace transform from [8], we get

$$\begin{aligned}
 g(t) &= k \left[\frac{1}{\alpha^2} - \frac{1}{\alpha} \left(\frac{1}{\alpha} + t \right) \exp(-\alpha t) \right] g_1(t) \\
 &= \frac{k}{\alpha^2} g_1(t) - \frac{k}{\alpha^2} \exp(-\alpha t) g_1(t) - \frac{k}{\alpha} t \exp(-\alpha t) g_1(t) \tag{2.3}
 \end{aligned}$$

Taking Laplace transform on both sides of (2.3),

$$G(s) = \frac{k}{\alpha^2} G_1(s) - \frac{k}{\alpha} \left[\frac{1}{\alpha} G_1(s+\alpha) + (-1) \frac{d}{ds} G_1(s+\alpha) \right].$$

Example 2.5

Consider

$$F(s_1, s_2, s_3) = \frac{k}{(s_1 + a)(s_2 + b)s_3(s_3 + \alpha)^2}$$

Direct use of the table given in [6], we find

$$F_1(s_1, s_2) = \frac{1}{(s_1 + a)(s_2 + b)} \xrightarrow{A_2} G_1(s) = \frac{1}{s + a + b}$$

Thus, by Theorem 2.3,

$$F(s_1, s_2, s_3) \xrightarrow{A_3} G(s) = \frac{k}{\alpha^2 (s + a + b)} - \frac{k}{\alpha} \left[\frac{1}{\alpha (s + a + b)} + \frac{1}{(s + a + b)^2} \right]$$

or

$$G(s) = \frac{k}{\alpha} \left[\frac{1}{\alpha (s + a + b)} - \frac{s + 2\alpha + a + b}{\alpha (s + a + b)^2} \right]$$

Example 2.6

Suppose

$$F(s_1, s_2, s_3) = \frac{k}{[s_3(s_3 + \alpha)]^2 [a(s_1 + s_2)^2 + b(s_1 + s_2) + c]}$$

Use of the results of [6],

$$F_1(s_1, s_2) = \frac{1}{a(s_1+s_2)^2+b(s_1+s_2)+c} \xrightarrow{A_2} G_1(s) = \frac{1}{as^2+bs+c}$$

Then Theorem 2.3 yields

$$F(s_1, s_2, s_3) \xrightarrow{A_3} G(s) = \frac{k}{\alpha^2} \left(\frac{1}{as^2+bs+c} \right) - \frac{k}{\alpha} \left[\frac{1}{\alpha\{a(s+\alpha)^2+b(s+\alpha)+c\}} + \frac{2a(s+\alpha)+b}{\{a(s+\alpha)^2+b(s+\alpha)+c\}^2} \right]$$

Theorem 2.4. If $F(s_1, s_2, \dots, s_n)$ can be expressed in the following form

$$F(s_1, s_2, \dots, s_n) = \frac{k(s_m+a)}{s_m(s_m^2-\alpha^2)} F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n)$$

where

$$F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n) \xrightarrow{A_{n-1}} G_1(s)$$

Then the associated transform

$$G(s) = \frac{k(a+\alpha)}{2\alpha^2} G_1(s-\alpha) + \frac{k(a-\alpha)}{2\alpha^2} G_1(s+\alpha) - \frac{ka}{\alpha^2} G_1(s)$$

Proof: By definitions (1.1) and (1.2),

$$\begin{aligned} g(t) &= L_n^{-1}[F(s_1, s_2, \dots, s_n); t_1, t_2, \dots, t_n] |_{t_1=t_2=\dots=t_n=t} \\ &= \frac{1}{2\pi i} \int_{\alpha_m-i\infty}^{\alpha_m+i\infty} \frac{(s_m+a)k}{s_m(s_m^2-\alpha^2)} \exp(s_m t) ds_m \\ &\cdot \frac{1}{(2\pi i)^{n-1}} \int_{\alpha_1-i\infty}^{\alpha_1+i\infty} \dots \int_{\alpha_{m-1}-i\infty}^{\alpha_{m-1}+i\infty} \dots \int_{\alpha_{m+1}-i\infty}^{\alpha_{m+1}+i\infty} \dots \int_{\alpha_n-i\infty}^{\alpha_n+i\infty} F(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n) \\ &\cdot \exp\left(\sum_{\substack{j=1 \\ j \neq m}}^n s_j t\right) ds_1 \dots ds_{m-1} ds_{m+1} \dots ds_n \end{aligned}$$

By the results of inverse Laplace transform shown in [8], we obtain

$$g(t) = \left[\frac{k}{\alpha} \sinh(\alpha t) + \frac{ka}{\alpha^2} \cosh(\alpha t) - \frac{ka}{\alpha^2} \right] g_1(t) \tag{2.4}$$

On taking Laplace transform of both sides of (2.4),

$$L[g(t); s] = L\left[\frac{k}{\alpha} \sinh(\alpha t) g_1(t) + \frac{ka}{\alpha^2} \cosh(\alpha t) g_1(t) - \frac{ka}{\alpha^2} g_1(t); s\right]$$

we establish the theorem. That is

$$G(s) = \frac{k}{2\alpha} [G_1(s-\alpha) - G_1(s+\alpha)] + \frac{ka}{2\alpha^2} [G_1(s-\alpha) + G_1(s+\alpha)] - \frac{ka}{\alpha^2} G_1(s)$$

or

$$G(s) = \frac{k(a+\alpha)}{2\alpha^2} G_1(s-\alpha) + \frac{k(a-\alpha)}{2\alpha^2} G_1(s+\alpha) - \frac{ka}{\alpha^2} G_1(s) .$$

Example 2.7

Let

$$F(s_1, s_2, s_3) = \frac{k(s_3+c)}{s_3(s_3^2-\alpha^2)(s_1+a)(s_2+b)}$$

Then

$$F_1(s_1, s_2) = \frac{1}{(s_1+a)(s_2+b)} \xrightarrow{A_2} G_1(s) = \frac{1}{s+a+b}$$

and by applying Theorem 2.4,

$$\begin{aligned} F(s_1, s_2, s_3) \xrightarrow{A_3} G(s) &= \frac{k}{2\alpha} \left[\frac{1}{s-\alpha+a+b} - \frac{1}{s+\alpha+a+b} \right] + \frac{ck}{2\alpha^2} \left[\frac{1}{s-\alpha+a+b} + \frac{1}{s+\alpha+a+b} \right] - \frac{ck}{\alpha^2} \frac{1}{s+a+b} \\ &= \frac{k(c+\alpha)}{2\alpha^2(s-\alpha+a+b)} + \frac{k(c-\alpha)}{2\alpha^2(s+\alpha+a+b)} - \frac{ck}{\alpha^2(s+a+b)} . \end{aligned}$$

Example 2.8

Considering

$$F(s_1, s_2, s_3) = \frac{(s_3+d)k}{s_3(s_3^2-\alpha^2)[a(s_1+s_2)^2+b(s_1+s_2)+c]}$$

we find

$$F_1(s_1, s_2) = \frac{1}{a(s_1+s_2)^2+b(s_1+s_2)+c} \xrightarrow{A_2} G_1(s) = \frac{1}{as^2+bs+c}$$

and Theorem 2.4 shows that

$$\begin{aligned} F(s_1, s_2, s_3) \xrightarrow{A_3} G(s) &= \frac{k(d+\alpha)}{2\alpha^2\{a(s-\alpha)^2+b(s-\alpha)+c\}} \\ &+ \frac{k(d-\alpha)}{2\alpha^2\{a(s+\alpha)^2+b(s+\alpha)+c\}} \\ &+ \frac{kd}{\alpha^2(as^2+bs+c)} . \end{aligned}$$

Theorem 2.5. If a function $F(s_1, s_2, \dots, s_n)$ can be factored in the form

$$F(s_1, s_2, \dots, s_n) = \frac{k}{s_m(s_m^3 + \alpha^3)} F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n)$$

Then

$$F(s_1, s_2, \dots, s_n) \xrightarrow{A_n} G(s) = \frac{k}{3\alpha^3} [3G_1(s) - G_1(s + \alpha) - G_1(s - \frac{\alpha}{2} - \frac{\sqrt{3}}{2} i\alpha) - G_1(s - \frac{\alpha}{2} + \frac{\sqrt{3}}{2} i\alpha)]$$

where $F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n) \xrightarrow{A_{n-1}} G_1(s)$.

Proof: By definitions (1.1) and (1.2)

$$\begin{aligned} g(t) &= L_n^{-1}[F(s_1, s_2, \dots, s_n); t, t, \dots, t] \\ &= k \cdot L_1^{-1}\left[\frac{1}{s_m(s_m^3 + \alpha^3)}; t\right] \cdot L_{n-1}^{-1}[F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n); t, t, \dots, t] \end{aligned}$$

Referring to the results given in [8],

$$g(t) = k \cdot \frac{1}{\alpha^3} \left[1 - \frac{1}{3} \exp(-\alpha t) - \frac{2}{3} \exp\left(\frac{\alpha t}{2}\right) \cos\left(\frac{\sqrt{3}}{2} \alpha t\right) \right] g_1(t) \tag{2.5}$$

Taking Laplace transform on both sides,

$$L[g(t); s] = \frac{k}{\alpha^3} L\left[g_1(t) - \frac{1}{3} \exp(-\alpha t) g_1(t) - \frac{2}{3} \exp\left(\frac{\alpha t}{2}\right) \cos\left(\frac{\sqrt{3}}{2} \alpha t\right) g_1(t); s\right],$$

we obtain

$$G(s) = \frac{k}{3\alpha^3} [3G_1(s) - G_1(s + \alpha) - G_1(s - \frac{\alpha}{2} - \frac{\sqrt{3}}{2} i\alpha) - G_1(s - \frac{\alpha}{2} + \frac{\sqrt{3}}{2} i\alpha)].$$

Example 2.9

Suppose

$$F(s_1, s_2, s_3) = \frac{k}{(s_1 + a)(s_2 + b)s_3(s_3^3 + \alpha^3)}$$

Then

$$F_1(s_1, s_2) = \frac{1}{(s_1 + a)(s_2 + b)} \xrightarrow{A_2} G_1(s) = \frac{1}{s + a + b}$$

So, by Theorem 2.5,

$$F(s_1, s_2, s_3) \xrightarrow{A_3} G(s) = \frac{k}{3\alpha^3} \left[\frac{3}{s + a + b} - \frac{1}{s + \alpha + a + b} - \frac{1}{s - \frac{\alpha}{2}(1 + \sqrt{3}i) + a + b} - \frac{1}{s - \frac{\alpha}{2}(1 - \sqrt{3}i) + a + b} \right]$$

Example 2.10

Consider

$$F(s_1, s_2, s_3) = \frac{k}{s_3(s_3 + \alpha^3)\{a(s_1 + s_2)^2 + b(s_1 + s_2) + c\}}$$

Then

$$F_1(s_1, s_2) = \frac{1}{a(s_1 + s_2)^2 + b(s_1 + s_2) + c} \xrightarrow{A_2} G_1(s) = \frac{1}{as^2 + bs + c}$$

By applying Theorem 2.5, we find

$$\begin{aligned} F(s_1, s_2, s_3) \xrightarrow{A_3} G(s) &= \frac{k}{3\alpha^3} \left[\frac{3}{as^2 + bs + c} - \frac{1}{a(s + \alpha)^2 + b(s + \alpha) + c} \right. \\ &\quad - \frac{1}{a\left(s - \frac{\alpha}{2}(1 + \sqrt{3}i)\right)^2 + b\left(s - \frac{\alpha}{2}(1 + \sqrt{3}i)\right) + c} \\ &\quad \left. - \frac{1}{a\left(s - \frac{\alpha}{2}(1 - \sqrt{3}i)\right)^2 + b\left(s - \frac{\alpha}{2}(1 - \sqrt{3}i)\right) + c} \right] \end{aligned}$$

Theorem 2.6.

If a function

$$F(s_1, s_2, \dots, s_n) = \frac{k}{s_m^2(s_m + \alpha)} F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n)$$

then its associated transform

$$G(s) = \frac{k}{\alpha^2} \left[G_1(s + \alpha) - \alpha \frac{d}{ds} G_1(s) - G_1(s) \right]$$

Proof. By definitions

$$\begin{aligned} g(t) &= L_n^{-1}[F(s_1, s_2, \dots, s_n); t, t, \dots, t] \\ &= k L_1^{-1}\left[\frac{1}{s_m^2(s_m + \alpha)}; t\right] \cdot L_{n-1}^{-1}[F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n); t, t, \dots, t] \\ &= \frac{k}{\alpha^2} [\exp(-\alpha t) + \alpha t - 1] g_1(t) \end{aligned} \tag{2.6}$$

On taking Laplace transform on both sides, one obtains

$$\begin{aligned} G(s) &= \frac{k}{\alpha^2} L[\exp(-\alpha t)g_1(t) + \alpha t g_1(t) - g_1(t); s] \\ &= \frac{k}{\alpha^2} [G_1(s + \alpha) - \alpha \frac{d}{ds} G_1(s) - G_1(s)] \end{aligned}$$

Example 2.11

Take

$$F(s_1, s_2, s_3) = \frac{k}{(s_1+a)(s_2+b)s_3^2(s_3+\alpha)}$$

Thus as before

$$F_1(s_1, s_2) \xrightarrow{A_2} G_1(s) = \frac{1}{s+a+b}$$

and by Theorem 2.6

$$F(s_1, s_2, s_3) \xrightarrow{A_3} G(s) = \frac{k}{\alpha^2} \left[\frac{(s+a+b)^2 + \alpha - s(a+b+c)}{(s+\alpha+a+b)(s+a+b)^2} \right]$$

Example 2.12

Let

$$F(s_1, s_2, s_3) = \frac{k}{\{a(s_1+s_2)^2 + b(s_1+s_2) + c\}s_3^2(s_3+\alpha)}$$

Thus as before

$$F_1(s_1, s_2) \xrightarrow{A_2} G_1(s) = \frac{1}{as^2+bs+c}$$

and by Theorem 2.6

$$F(s_1, s_2, s_3) \xrightarrow{A_3} G(s) = \frac{k}{\alpha^2} \left[\frac{1}{a(s+\alpha)^2 + b(s+\alpha) + c} + \frac{\alpha(2as+b)}{(as^2+bs+c)^2} - \frac{1}{as^2+bs+c} \right]$$

Following analogous arguments, it is easy to prove the following results.

Theorem 2.7.

If a function

$$F(s_1, s_2, \dots, s_n) = \frac{k(s_m + a)}{s_m^2(s_m + \alpha)} F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n),$$

then its associated transform

$$G(s) = k \left(\frac{1}{\alpha} - \frac{a}{\alpha^2} \right) [G_1(s) - G_1(s+\alpha)] - \frac{ak}{\alpha} \frac{d}{ds} G_1(s)$$

Example 2.13

Consider

$$F_1(s_1, s_2, s_3) = \frac{(s_3+c)k}{(s_1+a)(s_2+b)s_3^2(s_3+\alpha)}$$

and

$$F_1(s_1, s_2) = \frac{1}{(s_1+a)s_2+b}$$

Then using Theorem 2.7, we can get

$$G(s) = \frac{k(s+a+b+c)}{(s+a+b)^2(s+\alpha+a+b)}$$

Example 2.14

Considering

$$F_1(s_1, s_2, s_3) = \frac{(s_3+c)k}{s_3^2(s_3+\alpha)\{a(s_1+s_2)^2+b(s_1+s_2)+c\}}$$

and

$$F_1(s_1, s_2) = \frac{1}{a(s_1+s_2)^2+b(s_1+s_2)+c}$$

we obtain, by Theorem 2.7,

$$G(s) = \frac{k}{\alpha^2} (\alpha-c) \left[\frac{1}{as^2+bs+c} - \frac{1}{a(s+\alpha)^2+b(s+\alpha)+c} \right] + \frac{ck(2as+b)}{\alpha(as^2+bs+c)}.$$

Theorem 2.8.

If a function

$$F(s_1, s_2, \dots, s_n) = \frac{k}{(s_m+\alpha)(s_m+\beta)(s_m+\gamma)} F_1(s_1, \dots, s_{m-1}, s_{m+1}, \dots, s_n),$$

then its associated transform is given by

$$G(s) = k \left[\frac{G_1(s+\alpha)}{(\beta-\alpha)(\gamma-\alpha)} + \frac{G_1(s+\beta)}{(\alpha-\beta)(\gamma-\beta)} + \frac{G_1(s+\gamma)}{(\alpha-\gamma)(\beta-\gamma)} \right]$$

Example 2.15

Let

$$F_1(s_1, s_2, s_3) = \frac{k(s_3+\alpha)^{-1}(s_3+\beta)^{-1}(s_3+\gamma)^{-1}}{(s_1+a)(s_2+b)}$$

and

$$F(s_1, s_2) = \frac{1}{(s_1+a)(s_2+b)}$$

Then the use of Theorem 2.8 yields

$$G(s) = k \left[\frac{(\beta-\alpha)^{-1}(\gamma-\alpha)^{-1}}{s+\alpha+a+b} + \frac{(\alpha-\beta)^{-1}(\gamma-\beta)^{-1}}{s+\beta+a+b} + \frac{(\alpha-\gamma)^{-1}(\beta-\gamma)^{-1}}{s+\gamma+a+b} \right]$$

Example 2.16

Suppose

$$F(s_1, s_2, s_3) = \frac{k(s_3+\alpha)^{-1}(s_3+\beta)^{-1}(s_3+\gamma)^{-1}}{a(s_1+s_2)^2+b(s_1+s_2)+c}$$

and take

$$F_1(s_1, s_2) = \frac{1}{a(s_1+s_2)^2+b(s_1+s_2)+c}$$

Then, direct application of Theorem 2.8 gives,

$$G(s) = k \left[\frac{(\beta-\alpha)^{-1}(\gamma-\alpha)^{-1}}{a(s+\alpha)^2+b(s+\alpha)+c} + \frac{(\alpha-\beta)^{-1}(\gamma-\beta)^{-1}}{a(s+\beta)^2+b(s+\beta)+c} + \frac{(\alpha-\gamma)^{-1}(\beta-\gamma)^{-1}}{a(s+\gamma)^2+b(s+\gamma)+c} \right].$$

3. CONCLUSIONS.

Theorems on associated transform developed in this paper are rigorous and very useful in performing the inverse Laplace transform for certain functions. These theorems can be applied to directly derive many associated pairs, and thus one can easily extend the tables given in [5]-[7] many fold. Moreover, the results of this paper will help develop more basic theorems in this direction, and will appear in subsequent papers.

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