

REMARKS ON A FIXED-POINT THEOREM OF GERALD JUNGCK

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ABSTRACT. Jungck [1] obtained a fixed-point theorem for a pair of continuous self-mappings on a complete metric space. Recently, Barada K. Ray [2] extended the theorem of Jungck [1] for three self-mappings on a complete metric space. In the present paper we omit the continuity of the mapping used by Ray [2] and replace his four conditions by a single condition. Our results so obtained generalize and/or unify fixed-point theorems of Jungck [1], Ray [2], Rhoades [3], Ćirić [4], Pal and Maiti [5], and Sharma and Yuel [6].

KEYWORDS AND PHRASES. Fixed Point Theorem, Continuous Self-Mappings, and Complete Metric Space.

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1. INTRODUCTION.

We quote two theorems:

Theorem 1. (Jungck [1]). If S and T are continuous mappings of a complete metric space (X, d) into itself such that

- i) $S(X) \subset T(X)$,
- ii) $ST = TS$, and
- iii) $d(Sx, Sy) < \alpha d(Tx, Ty)$ for every pair of points $x, y \in X$ and for $\alpha \in [0, 1)$, then
 $F_S = F_T = F_{S, T} = \{u\}$ for some u in X ,

where $F_S = \{x \in X: x = Sx\}$, $F_T = \{x \in X: x = Tx\}$

and $F_{S, T} = \{x \in X: x = Sx = Tx\}$.

Theorem 2 (Ray [2]). Let T be a continuous mapping and T_1 and T_2 be any other two mappings of a complete metric space (X, d) into itself such that

- i) $TT_i = T_iT$, $i = 1, 2$,
- ii) $\bigcup_{i=1}^2 T_i(X) \subseteq T(X)$, and
- iii) at least one of the following is satisfied for every pair of points x, y in X :

$$d(T_1x, T_2y) < \frac{\alpha d(Ty, T_2y) d(Tx, T_1x)}{1 + d(Tx, Ty)} + \beta d(Tx, Ty),$$

where $0 < \alpha, \beta, \alpha + \beta < 1$, (1.1)

$$d(T_1x, T_2y) < \lambda \max \{d(Tx, Ty), 1/2[d(Tx, T_1x) + d(Ty, T_2y)], \\ 1/2[d(Tx, T_2y) + d(Ty, T_1x)]\}$$

where $0 < \lambda < 1$, (1.2)

$$d(T_1x, T_2y) < \mu \max \{d(Tx, Ty), d(Tx, T_1y), d(Ty, T_2y), \\ d(Tx, T_2y), d(Ty, T_1x)\}$$

where $0 < \mu < 1/2$, (1.3)

$$d(T_1x, T_2y) < \max \{|K_1 d(Tx, Ty) - K_2 d(Tx, T_1x)|, \\ |K_1 d(Tx, Ty) - K_2 d(Ty, T_2y)|\}$$

where $-1 < K_2 < K_1 < K_2 + 1 < 2, K_1 < 1$. (1.4)

Then F_{T, T_1, T_2} is non-empty, where

$$F_{T, T_1, T_2} = \{x \in X: x = Tx = T_1x = T_2x\}$$

Furthermore, $F_{T_1} = F_{T_2} = F_{T, T_1, T_2} = \{u\}$, for some u in X .

2. MAIN RESULTS.

Now we give our result.

THEOREM 2.1. Let (X, d) be a complete metric space. Let $T, T_1, T_2: X \rightarrow X$ satisfy (i), (ii) of Theorem 2 and (i) let the following conditions hold for every pair of points x, y in X :

$$d(T_1Tx, T_2Ty) < \mu \max \{d(x, T_1Tx), d(y, T_2Ty), d(y, T_1Tx), d(x, T_2Ty), \\ [d(x, T_1Tx) + d(y, T_2Ty)], [\frac{\alpha[1 + d(y, T_2Ty)]d(x, T_1Tx)}{1 + d(x, y)} \\ + \beta[d(x, T_1Tx) + d(y, T_2Ty)] + \nu[d(y, T_1Tx) + d(x, T_2Ty)] \\ + \delta d(x, y)\}, |K_1 d(x, y) - K_2 d(x, T_1Tx)|, \\ |K_1 d(x, y) - K_2 d(y, T_2Ty)|\}$$

where $0 < \mu < 1$, $\alpha, \beta, \nu, \delta > 0$, $\alpha + \beta + \nu + \delta < 1$, $2\nu + \delta < 1$,

$$0 < \frac{\mu(\beta + \nu + \delta)}{1 - \mu(\alpha + \beta + \nu)} < 1, \quad -1 < K_2 < K_1 < 1 + \mu K_2 < 2, \quad K_1 < 1.$$

Then $F_{T, T_1 T_2}$ is non-empty, where

$$F_{T, T_1, T_2} = \{x \in X: x = Tx = T_1 x = T_2 x\}$$

Furthermore, $F_{T_1} = F_{T_2} = F_{T, T_1, T_2} = \{u\}$, for some u in X .

PROOF. Let $x_0 \in X$, define

$$x_{2n+1} = T_1 x_{2n}, \quad n = 0, 1, 2, \dots$$

$$x_{2n} = T_2 x_{2n-1}, \quad n = 1, 2, 3, \dots$$

Then, using Theorem 2.1, (i), we have

$$d(x_{2n+1}, x_{2n}) < K d(x_{2n}, x_{2n-1})$$

where $K = \max \left\{ \mu, \frac{\mu}{1-\mu}, \frac{\mu(\beta + \nu + \delta)}{1-\mu(\alpha + \beta + \nu)}, r \right\}$

$$\text{where } r = \begin{cases} \mu \max \left\{ K_1 - K_2, \frac{K_1}{1 + \mu K_2} \right\}, & K_1 > 0, \\ \mu \max \left\{ K_1 - K_2, \frac{-K_1}{1 - \mu K_2} \right\}, & K_1 < 0. \end{cases}$$

$\{x_n\}$ is a Cauchy sequence. Since X is complete there exists $u \in X$ such that $x_n \rightarrow u$ as $n \rightarrow \infty$.

Now,

$$d(T_1 Tu, x_{2n}) = d(T_1 Tu, T_2 T x_{2n-1}).$$

Then using Theorem 2.1 (i) and allowing $n \rightarrow \infty$ such that $x_{2n} \rightarrow u$, $x_{2n-1} \rightarrow u$ etc, we have $u = T_1 Tu$. Hence $u = T_1 Tu = TT_1 u$ using Theorem 2 (i). Further,

$d(x_{2n+1}, T_2 Tu) = d(T_1 T x_{2n}, T_2 Tu)$. Again using Theorem 2 (i) and allowing $n \rightarrow \infty$ such that $x_{2n} \rightarrow u$, $x_{2n+1} \rightarrow u$ etc, we have $u = T_2 Tu$. Hence $u = T_2 Tu = TT_2 u$.

Now, let v denote any common fixed point of $T_1 T$ and $T_2 T$. From Theorem 2.1 (i), it is easy to see that $u = v$ since $2\nu + \delta < 1$. For proving $u = Tu$ we have

$$d(Tu, u) = d(TT_1 Tu, T_2 Tu) = d(T_1 TTu, T_2 Tu)$$

which yields $Tu = u$ using Theorem 2.1 (i). Hence $u = T_1 Tu = T_1 u$. Similarly, $u = T_2 Tu = T_2 u$. Hence, $u = Tu = T_1 u = T_2 u$ which shows that F_T, F_{T_1}, F_{T_2} are non-empty. Then we

can see that $F_{T_1} = F_{T_2} = F_{T_1 T_2} = \{u\}$ for some u in X . This completes the proof.

EXAMPLE. Let $X = [0, 1]$ with Euclidean metric d . Let $Tx = x$, $0 < x < 1$, $Tx = 1/2$, $x = 1$, $T_1x = \frac{x}{4}$, $0 < x < 1$, $T_1x = \frac{1}{8}$, $x = 1$, $T_2x = \frac{x}{8}$, $0 < x < 1$, $T_2x = \frac{1}{16}$, $x = 1$. Here T, T_1, T_2 , are all discontinuous at $x = 1$ and have a unique common fixed point $x = 0$. Take $x = \frac{1}{2}$, $y = \frac{1}{4}$. Obviously all the conditions (i), (ii) of Theorem 2 and (i) of Theorem 2.1 hold true. Hence the result.

REMARKS. (1) Contractive Definition 20 of Rhoades [3] is a special case of condition (i) of Theorem 2.1. (2) Theorem 1 of Ćirić [4], Theorem 1 of Pal and Maiti [5], and Theorem 4 of Sharma and Yuel [6] are special cases of Theorem 2.1.

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