

## Research Article

# An Extension of Generalized ( $\psi, \varphi$ )-Weak Contractions

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We prove a fixed-point theorem for a class of maps that satisfy generalized ( $\psi, \varphi$ )-weak contractions depending on a given function. An example is given to illustrate our extensions.

## 1. Introduction

Because fixed-point theory has a wide array of applications in many areas such as economics, computer science, and engineering, it plays evidently a crucial role in nonlinear analysis. One of the cornerstones of this theory is the Banach fixed-point theorem, also known as the Banach contraction mapping theorem [1], which can be stated as follows.

Let  $T : X \rightarrow X$  be a contraction on a complete metric space  $(X; d)$ ; that is, there is a nonnegative real number  $k < 1$  such that  $d(T(x), T(y)) \leq kd(x, y)$  for all  $x, y \in X$ . Then the map  $T$  admits one and only one point  $x^* \in X$  such that  $Tx^* = x^*$ . Moreover, this fixed point is the limit of the iterative sequence  $x_{n+1} = T(x_n)$  for  $n = 0, 1, 2, \dots$ , where  $x_0$  is an arbitrary starting point in  $X$ . This theorem attracted a lot of attention because of its importance in the field. Many authors have started studying on fixed-point theory to explore some new contraction mappings to generalize the Banach contraction mapping theorem. In particular, Boyd and Wong [2] introduced the notion of  $\Phi$ -contractions. In 1997 Alber and Guerre-Delabriere [3] defined the  $\varphi$ -weak contraction which is a generalization of  $\Phi$ -contractions (see also [4–8]).

On the other hand, the notion of  $T$ -contractions introduced and studied by the authors of the interesting papers in [9–11]. Following this trend, we explore in this paper another extension of ( $\psi, \varphi$ )-weak contractions in the context of  $T$ -contractions.

## 2. Preliminaries

Let  $(X, d)$  be a metric space. Boyd and Wong [2] introduced the notion of  $\Phi$ -contraction as follows. A map  $T : X \rightarrow X$  is called a  $\Phi$ -contraction if there exists an upper semicontinuous function  $\Phi : [0, +\infty) \rightarrow [0, +\infty)$  such that

$$d(Tx, Ty) \leq \Phi(d(x, y)) \quad (2.1)$$

for all  $x, y \in X$ . The concept of the  $\varphi$ -weak contraction was defined by Alber and Guerre-Delabriere [3] as a generalization of  $\Phi$ -contraction under the setting of Hilbert spaces and obtained fixed-point results. A map  $T : X \rightarrow X$  is a  $\varphi$ -weak contraction, if there exists a function  $\varphi : [0, +\infty) \rightarrow [0, +\infty)$  such that

$$d(Tx, Ty) \leq d(x, y) - \varphi(d(x, y)) \quad (2.2)$$

for all  $x, y \in X$  provided that the function  $\varphi$  satisfies the following condition:

$$\varphi(t) = 0 \quad \text{iff } t = 0. \quad (2.3)$$

Later Rhoades [7] proved analogs of the result in [3] in the context of metric spaces.

**Theorem 2.1.** *Let  $(X, d)$  be a complete metric space. Let  $\varphi : [0, +\infty) \rightarrow [0, +\infty)$  be a continuous and nondecreasing function such that  $\varphi(t) = 0$  if and only if  $t = 0$ . If  $T : X \rightarrow X$  is a  $\varphi$  weak contraction, then  $T$  has a unique fixed point.*

In [12], Dutta and Choudhury proved an extension of Rhoades.

**Theorem 2.2.** *Let  $(X, d)$  be a complete metric space, and let  $T : X \rightarrow X$  be a self-mapping satisfying*

$$\varphi(d(Tx, Ty)) \leq \varphi(d(x, y)) - \varphi(d(x, y)), \quad \forall x, y \in X, \quad (2.4)$$

where  $\varphi, \psi : [0, +\infty) \rightarrow [0, +\infty)$  are continuous and nondecreasing functions with  $\varphi(t) = \psi(t) = 0$  if and only if  $t = 0$ . Then  $T$  has a unique fixed point.

Zhang and Song [8] improved Theorem 2.1 and gave the following result which states the existence of common fixed points of certain maps in metric spaces.

**Theorem 2.3.** *Let  $(X, d)$  be a complete metric space, and let  $f, g : X \rightarrow X$  be self-mappings satisfying*

$$d(fx, gy) \leq M(x, y) - \varphi(M(x, y)), \quad \forall x, y \in X, \quad (2.5)$$

where

$$M(x, y) = \max \left\{ d(x, y), d(x, fx), d(y, gy), \frac{d(x, fy) + d(y, gx)}{2} \right\} \quad (2.6)$$

and  $\varphi : [0, +\infty) \rightarrow [0, +\infty)$  are lower semicontinuous functions with  $\varphi(t) = 0$  if and only if  $t = 0$ . Then  $f, g$  have a unique common fixed point.

Combining the theorems above with the results of Dutta and Choudhury [12], Ćororić [13] obtained the following theorem.

**Theorem 2.4.** Let  $(X, d)$  be a complete metric space, and let  $T, S : X \rightarrow X$  be self-mappings satisfying

$$\varphi(d(fx, gy)) \leq \varphi(M(x, y)) - \varphi(M(x, y)), \quad \forall x, y \in X, \quad (2.7)$$

where

$$M(x, y) = \max \left\{ d(x, y), d(x, fx), d(y, gy), \frac{d(x, gy) + d(y, fx)}{2} \right\}, \quad (2.8)$$

$\varphi : [0, +\infty) \rightarrow [0, +\infty)$  is a continuous and nondecreasing function with  $\varphi(t) = 0$  if and only if  $t = 0$ , and  $\varphi : [0, +\infty) \rightarrow [0, +\infty)$  is a lower semicontinuous function with  $\varphi(t) = 0$  if and only if  $t = 0$ . Then  $f, g$  have a unique common fixed point.

The notion of the  $T$ -contraction is defined in ([10, 11]) as follows.

*Definition 2.5.* Let  $T$  and  $S$  be two self-mappings on a metric space  $(X, d)$ . The mapping  $S$  is said to be a  $T$ -contraction if there exists  $k \in (0, 1)$  such that

$$d(TSx, TSy) \leq kd(Tx, Ty), \quad \forall x, y \in X. \quad (2.9)$$

It can be easily seen that if  $T$  is the identity map, then the  $T$ -contraction coincides with the usual contraction.

*Example 2.6.* Let  $X = (0, \infty)$  with the usual metric  $d(x, y) = |x - y|$  induced by  $(\mathbb{R}, d)$ . Consider the following self-mappings  $T(x) = 1/x$  and  $Sx = 3x$  on  $X$ . It is clear that  $S$  is not a contraction. On the contrary,

$$d(TSx, TSy) = \left| \frac{1}{3x} - \frac{1}{3y} \right| = \frac{1}{3} \left| \frac{1}{y} - \frac{1}{x} \right| \leq \frac{1}{3} d(Tx, Ty), \quad \forall x, y \in X. \quad (2.10)$$

*Definition 2.7* (see, e.g., [9, 11]). Let  $(X, d)$  be a metric space. If  $\{y_n\}$  is a convergent sequence whenever  $\{Ty_n\}$  is convergent, then  $T : X \rightarrow X$  is called *sequentially convergent*.

The aim of this work is to give a proper extension of Āoricorić's result of using the concept of  $T$ -contraction, that is, the contraction depending on a given function. We will show the existence of a common fixed point for a class of certain maps.

### 3. Main Results

We start this section by recalling the following two classes of functions.

Let  $\Psi$  denote the set of all functions  $\varphi : [0, \infty) \rightarrow [0, \infty)$  which satisfy

- (i)  $\varphi$  is continuous and nondecreasing,
- (ii)  $\varphi(t) = 0$  if and only if  $t = 0$ .

Similarly  $\Phi$  denotes the set of all functions  $\varphi : [0, \infty) \rightarrow [0, \infty)$  which satisfy

- (i)  $\varphi$  is lower semi continuous,
- (ii)  $\varphi(t) = 0$  if and only if  $t = 0$ .

It is easy to see that  $\varphi_1(t) = t$ ,  $\varphi_2(t) = t/(t + 1)$ ,  $\varphi_3(t) = t^2$  belong to  $\Psi$  and  $\varphi_1(t) = \min\{t, 1\}$ ,  $\varphi_2(t) = \ln(1 + t)$  belong to  $\Phi$ .

We are ready to state our main theorem that is a proper extension of Theorem 2.4.

**Theorem 3.1.** *Let  $(X, d)$  be a complete metric space and  $T : X \rightarrow X$  an injective, continuous, and sequentially convergent mapping. Let  $f, g : X \rightarrow X$  be self-mappings. If there exist  $\varphi \in \Psi$  and  $\varphi \in \Phi$  such that*

$$\varphi(d(Tfx, Tgy)) \leq \varphi(M(Tx, Ty)) - \varphi(M(Tx, Ty)), \quad (3.1)$$

for all  $x, y \in X$ , where

$$M(Tx, Ty) = \max \left\{ d(Tx, Ty), d(Tx, Tfx), d(Ty, Tgy), \frac{d(Tx, Tgy) + d(Ty, Tfx)}{2} \right\}, \quad (3.2)$$

then  $f, g$  have a unique common fixed point.

*Proof.* We will follow the lines in the proof of the main result in [13]. By injection of  $T$ , we easily check that  $M(Tx, Ty) = 0$  if and only if  $x = y$  is a common fixed point of  $f$  and  $g$ . Let  $x_0 \in X$ . We define two iterative sequences  $\{x_n\}$  and  $\{y_n\}$  in the following way:

$$x_{2n+2} = fx_{2n+1}, \quad x_{2n+1} = gx_{2n}, \quad y_n = Tx_n, \quad \forall n = 0, 1, 2, \dots \quad (3.3)$$

We prove  $\{y_n\}$  is a Cauchy sequence. For this purpose, we first claim that  $\lim_{n \rightarrow \infty} d(y_{n+1}, y_n) = 0$ . It follows from property of  $\varphi$  that if  $n$  is odd

$$\begin{aligned} \varphi(d(y_{n+1}, y_n)) &= \varphi(d(Tx_{n+1}, Tx_n)) = \varphi(d(Tfx_n, Tgx_{n-1})) \\ &\leq \varphi(M(Tx_n, Tx_{n-1})) - \varphi(M(Tx_n, Tx_{n-1})) \\ &\leq \varphi(M(Tx_n, Tx_{n-1})), \end{aligned} \quad (3.4)$$

where

$$\begin{aligned}
 M(Tx_n, Tx_{n-1}) &= \max \left\{ d(Tx_n, Tx_{n-1}), d(Tfx_n, Tx_n), d(Tgx_{n-1}, Tx_{n-1}), \right. \\
 &\quad \left. \frac{d(Tgx_{n-1}, Tx_n) + d(Tfx_n, Tx_{n-1})}{2} \right\} \\
 &= \max \left\{ d(y_n, y_{n-1}), d(y_{n+1}, y_n), d(y_n, y_{n-1}), \frac{d(y_{n-1}, y_{n+1})}{2} \right\} \\
 &\leq \max \left\{ d(y_n, y_{n-1}), d(y_{n+1}, y_n), \frac{d(y_{n-1}, y_n) + d(y_n, y_{n+1})}{2} \right\}.
 \end{aligned} \tag{3.5}$$

Hence, we have

$$\psi(d(y_{n+1}, y_n)) \leq \psi \left( \max \left\{ d(y_n, y_{n-1}), d(y_{n+1}, y_n), \frac{d(y_{n-1}, y_n) + d(y_n, y_{n+1})}{2} \right\} \right). \tag{3.6}$$

If  $d(y_n, y_{n+1}) > d(y_{n-1}, y_n) \geq 0$  then  $M(Tx_n, Tx_{n-1}) = d(y_n, y_{n+1})$ , hence

$$\psi(d(y_n, y_{n+1})) \leq \psi(d(y_n, y_{n+1})) - \varphi(d(y_n, y_{n+1})) \tag{3.7}$$

and which contradicts with  $d(y_n, y_{n+1}) > 0$  and the property of  $\varphi$ . Thus, it follows from (3.5) that

$$d(y_{n+1}, y_n) \leq M(Tx_n, Tx_{n-1}) = d(y_n, y_{n-1}). \tag{3.8}$$

If  $n$  is even then by the same argument above, we obtain

$$d(y_{n+1}, y_n) \leq M(Tx_{n-1}, Tx_n) = d(y_n, y_{n-1}). \tag{3.9}$$

Therefore,

$$d(y_{n+1}, y_n) \leq M(Tx_n, Tx_{n-1}) = d(y_n, y_{n-1}) \tag{3.10}$$

for all  $n$  and  $\{d(y_n, y_{n+1})\}$  is a nonincreasing sequence of nonnegative real numbers. Hence, there exists  $r \geq 0$  such that

$$\lim_{n \rightarrow \infty} d(y_n, y_{n+1}) = \lim_{n \rightarrow \infty} M(Tx_n, Tx_{n-1}) = r. \tag{3.11}$$

By the lower semicontinuity of  $\varphi$ , we have

$$\varphi(r) \leq \liminf_{n \rightarrow \infty} \varphi(M(Tx_n, Tx_{n-1})). \tag{3.12}$$

Taking the upper limits as  $n \rightarrow \infty$  on either side of

$$\varphi(d(y_n, y_{n+1})) \leq \varphi(M(Tx_n, Tx_{n-1})) - \varphi(M(Tx_n, Tx_{n-1})), \quad (3.13)$$

we get

$$\varphi(r) \leq \varphi(r) - \liminf_{n \rightarrow \infty} \varphi(M(Tx_n, Tx_{n-1})) \leq \varphi(r) - \varphi(r), \quad (3.14)$$

that is,  $\varphi(r) \leq 0$ . By the property of  $\varphi$ , this implies that  $\varphi(r) = 0$ . It follows that  $r = 0$  and

$$\lim_{n \rightarrow \infty} d(y_n, y_{n+1}) = 0. \quad (3.15)$$

It is implied from (3.10) that

$$\lim_{n \rightarrow \infty} M(Tx_n, Tx_{n-1}) = 0. \quad (3.16)$$

Now, we claim that  $\{y_n\}$  is a Cauchy sequence. Since  $\lim_{n \rightarrow \infty} d(y_n, y_{n+1}) = 0$ , it is sufficient to prove that  $\{y_{2n}\}$  is a Cauchy sequence. Suppose on the contrary that  $\{y_{2n}\}$  is not a Cauchy sequence. Then, there exist  $\varepsilon > 0$  and subsequences  $\{y_{2n(k)}\}$  and  $\{y_{2m(k)}\}$  of  $\{y_{2n}\}$  such that  $n(k)$  is the smallest index for which

$$n(k) > m(k) > k, \quad d(y_{2m(k)}, y_{2n(k)}) > \varepsilon. \quad (3.17)$$

This means that

$$d(y_{2m(k)}, y_{2n(k)-2}) < \varepsilon. \quad (3.18)$$

From (3.18) and the triangle inequality, we get

$$\begin{aligned} \varepsilon &\leq d(y_{2m(k)}, y_{2n(k)}) \\ &\leq d(y_{2m(k)}, y_{2n(k)-2}) + d(y_{2n(k)-2}, y_{2n(k)-1}) + d(y_{2n(k)-1}, y_{2n(k)}) \\ &< \varepsilon + d(y_{2n(k)-2}, y_{2n(k)-1}) + d(y_{2n(k)-1}, y_{2n(k)}). \end{aligned} \quad (3.19)$$

Letting  $k \rightarrow \infty$  and using (3.15), we get

$$\lim_{k \rightarrow \infty} d(y_{2m(k)}, y_{2n(k)}) = \varepsilon. \quad (3.20)$$

By the fact

$$\begin{aligned} |d(y_{2m(k)}, y_{2n(k)+1}) - d(y_{2m(k)}, y_{2n(k)})| &\leq d(y_{2n(k)}, y_{2n(k)+1}) \\ |d(y_{2m(k)-1}, y_{2n(k)}) - d(y_{2m(k)}, y_{2n(k)})| &\leq d(y_{2m(k)-1}, y_{2m(k)}) \end{aligned} \quad (3.21)$$

and using (3.15) and (3.20), we obtain

$$\lim_{k \rightarrow \infty} d(y_{2m(k)-1}, y_{2n(k)}) = \lim_{k \rightarrow \infty} d(y_{2m(k)}, y_{2n(k)+1}) = \varepsilon. \quad (3.22)$$

Moreover, from

$$|d(y_{2m(k)-1}, y_{2n(k)+1}) - d(y_{2m(k)-1}, y_{2n(k)})| \leq d(y_{2n(k)}, y_{2n(k)+1}) \quad (3.23)$$

and combining with (3.15) and (3.22), we conclude that

$$\lim_{k \rightarrow \infty} d(y_{2m(k)-1}, y_{2n(k)+1}) = \varepsilon. \quad (3.24)$$

Now, by the definition of  $M(Tx, Ty)$  and from (3.10), (3.15), and (3.20)–(3.24), we can deduce that

$$\lim_{k \rightarrow \infty} M(Tx_{2m(k)-1}, Tx_{2n(k)}) = \varepsilon. \quad (3.25)$$

Due to (3.1), we have

$$\begin{aligned} \psi(d(y_{2m(k)}, y_{2n(k)+1})) &= \psi(d(Tx_{2m(k)}, Tx_{2n(k)+1})) = \psi(d(Tfx_{2m(k)-1}, Tgx_{2n(k)})) \\ &\leq \psi(M(Tx_{2m(k)-1}, Tx_{2n(k)})) - \varphi(M(Tx_{2m(k)-1}, Tx_{2n(k)})). \end{aligned} \quad (3.26)$$

Letting  $k \rightarrow \infty$  and using (3.22) and (3.25), we have

$$\psi(\varepsilon) \leq \psi(\varepsilon) - \varphi(\varepsilon). \quad (3.27)$$

It is a contradiction to  $\varphi(t) > 0$  for every  $t > 0$ . This proves that  $\{y_n\}$  is a Cauchy sequence.

Since  $X$  is a complete metric space, there exists  $u \in X$  such that  $\lim_{n \rightarrow \infty} y_n = u$ . Since  $T$  is sequentially convergent, we can deduce that  $\{x_n\}$  converges to  $v \in X$ . By the continuity of  $T$ , we infer that

$$u = \lim_{n \rightarrow \infty} y_n = \lim_{n \rightarrow \infty} Tx_n = Tv. \quad (3.28)$$

We will show that  $v = fv = gv$ . Indeed, suppose that  $v \neq fv$ , since  $T$  is injective, we have  $u = Tv \neq Tfv$ . Hence,  $d(Tv, Tfv) > 0$ . Since

$$\begin{aligned} \lim_{n \rightarrow \infty} y_{2n+1} &= \lim_{n \rightarrow \infty} y_{2n} = u, \\ \lim_{n \rightarrow \infty} d(y_{2n}, y_{2n+1}) &= 0, \end{aligned} \quad (3.29)$$

we can seek  $N_0 \in \mathbb{N}$  such that for any  $n \geq N_0$

$$d(y_{2n+1}, u) < \frac{d(Tv, Tfv)}{4}, \quad d(y_{2n}, u) < \frac{d(Tv, Tfv)}{4}, \quad d(y_{2n}, y_{2n+1}) < \frac{d(Tv, Tfv)}{4}. \quad (3.30)$$

Then, we have

$$\begin{aligned} d(Tv, Tfv) &\leq M(Tv, Tx_{2n}) = \max \left\{ d(Tv, Tx_{2n}), d(Tv, Tfv), d(Tx_{2n}, Tgx_{2n}), \right. \\ &\quad \left. \frac{d(Tv, Tgx_{2n}) + d(Tx_{2n}, Tfv)}{2} \right\} \\ &= \max \left\{ d(u, y_{2n}), d(Tv, Tfv), d(y_{2n}, y_{2n+1}), \right. \\ &\quad \left. \frac{d(u, y_{2n+1}) + d(y_{2n}, Tfv)}{2} \right\} \\ &\leq \max \left\{ d(u, y_{2n}), d(Tv, Tfv), d(y_{2n}, y_{2n+1}), \right. \\ &\quad \left. \frac{d(u, y_{2n+1}) + d(y_{2n}, Tv) + d(Tv, Tfv)}{2} \right\} \\ &\leq \max \left\{ \frac{d(Tv, Tfv)}{4}, d(Tv, Tfv), \frac{d(Tv, Tfv)}{4}, \right. \\ &\quad \left. \frac{d(Tv, Tfv)/4 + d(Tv, Tfv)/4 + d(Tv, Tfv)}{2} \right\} \\ &\leq \max \left\{ d(Tv, Tfv), \frac{3}{4} d(Tv, Tfv) \right\} = d(Tv, Tfv). \end{aligned} \quad (3.31)$$

Therefore,  $M(Tv, Tx_{2n}) = d(Tv, Tfv)$  for every  $n \geq N_0$ . Since

$$\begin{aligned} \varphi(d(Tfv, y_{2n+1})) &= \varphi(d(Tfv, Tx_{2n+1})) = \varphi(d(Tfv, Tgx_{2n})) \\ &\leq \varphi(M(Tv, Tx_{2n})) - \varphi(M(Tv, Tx_{2n})) \\ &= \varphi(d(Tv, Tfv)) - \varphi(d(Tv, Tfv)) \end{aligned} \quad (3.32)$$

and letting  $n \rightarrow \infty$ , we arrive at

$$\varphi(d(Tfv, Tv)) \leq \varphi(d(Tv, Tfv)) - \varphi(d(Tv, Tfv)). \quad (3.33)$$

We get a contradiction. Hence,  $v = fv$ . By the same argument, we get  $v = gv$ .

Let  $w \in X$  such that  $w = fw = gw$ . Then, we have

$$\begin{aligned} M(Tv, Tw) &= \max \left\{ d(Tv, Tw), d(Tv, Tfv), d(Tw, Tgw), \frac{d(Tv, Tgw) + d(Tfv, Tw)}{2} \right\} \\ &= \max \left\{ d(Tv, Tw), \frac{d(Tv, Tw) + d(Tv, Tw)}{2} \right\} = d(Tw, Tv). \end{aligned} \quad (3.34)$$

Thus

$$\begin{aligned} \varphi(d(Tv, Tw)) &= \varphi(d(Tfv, Tgw)) \leq \varphi(M(Tv, Tw)) - \varphi(M(Tv, Tw)) \\ &= \varphi(d(Tv, Tw)) - \varphi(d(Tv, Tw)). \end{aligned} \quad (3.35)$$

This implies that  $d(Tv, Tw) = 0$ , or  $Tv = Tw$ . Since  $T$  is injective, we have  $w = v$ . The theorem is proved.  $\square$

*Remark 3.2.* (1) In Theorem 3.1, if we choose  $Tx = x$  for all  $x \in X$ , then we get Theorem 2.4.

(2) In Theorem 3.1, if we fix  $\varphi(t) = t$  for all  $t$ , then we obtain another extension of Theorem 2.3.

(3) In Theorem 3.1, if we choose  $f = g$ , then we get the uniqueness and existence of fixed point of generalized  $\varphi$ -weak  $T$ -contractions.

The following example shows that Theorem 3.1 is a proper extension of Theorem 2.4.

*Example 3.3.* Let  $X = [1, +\infty)$  and  $d$  be the usual metric in  $X$ . Consider the maps  $f(x) = g(x) = 4\sqrt{x}$ . It is easy to see that 16 is the unique fixed point of  $f$  and  $g$ . We claim that  $f$  and  $g$  are not generalized  $\varphi$ -weak contraction. Indeed, if there exist lower semicontinuous functions  $\varphi, \varphi : [0, \infty) \rightarrow [0, \infty)$  with  $\varphi(t) > 0$ ,  $\varphi(t) > 0$  for  $t \in (0, \infty)$  and  $\varphi(0) = \varphi(0) = 0$ , such that

$$\varphi(d(fx, gy)) \leq \varphi(M(x, y)) - \varphi(M(x, y)), \quad \forall x, y \in X, \quad (3.36)$$

then

$$\varphi(4|\sqrt{x} - \sqrt{y}|) \leq \varphi(M(x, y)) - \varphi(M(x, y)), \quad \forall x, y \in X, \quad (3.37)$$

where  $M(x, y) = \max\{d(x, y), d(fx, x), d(gy, y), (1/2)[d(gx, y) + d(fy, x)]\}$ . For  $x = 4$  and  $y = 1$ , we obtain

$$M(x, y) = \max \left\{ 3, 4, 3, \frac{7}{2} \right\} = 4. \quad (3.38)$$

It follows from (3.37) that

$$\varphi(4) \leq \varphi(4) - \varphi(4). \quad (3.39)$$

Hence,  $\varphi(4) \leq 0$ . We arrive at a contradiction with  $\varphi(t) > 0$  for  $t \in (0, \infty)$ .

Consider the map  $Tx = \ln x + 1$ , for all  $x \in X$ . It is easy to see that  $T$  is injective, continuous, and sequentially convergent. Let  $\psi(t) = t$  and  $\varphi(t) = t/3$ , for all  $t \in [0, +\infty)$ . Now, we show that  $f$  and  $g$  are generalized  $\varphi$ -weak  $T$ -contractions. It reduces to check the following inequality:

$$|\ln 4\sqrt{x} - \ln 4\sqrt{y}| \leq \frac{2}{3}M(Tx, Ty), \quad \forall x, y \in [1, +\infty). \quad (3.40)$$

We have

$$|\ln 4\sqrt{x} - \ln 4\sqrt{y}| = \frac{1}{2} \left| \ln \frac{x}{y} \right| \quad (3.41)$$

$$\begin{aligned} M(Tx, Ty) &= \max \left\{ |\ln x - \ln y|, |\ln 4\sqrt{x} - \ln x|, |\ln 4\sqrt{y} - \ln y| \right. \\ &\quad \left. \frac{|\ln 4\sqrt{y} - \ln x| + |\ln 4\sqrt{x} - \ln y|}{2} \right\} \\ &\geq |\ln x - \ln y| = \left| \ln \frac{x}{y} \right|. \end{aligned} \quad (3.42)$$

It follows from (3.41) and (3.42) that

$$|\ln 4\sqrt{x} - \ln 4\sqrt{y}| \leq \frac{1}{2}M(Tx, Ty) \quad (3.43)$$

for every  $x, y \in X$ . This proves that (3.40) is true.

By the same method used in the proof of Theorem 3.1, we get the following theorem.

**Theorem 3.4.** *Let  $(X, d)$  be a complete metric space and  $T : X \rightarrow X$  an injective, continuous, and sequentially convergent mapping. Let  $f, g : X \rightarrow X$  be self-mappings. If there exist  $\psi \in \Psi$  and  $\varphi \in \Phi$  such that*

$$\psi(d(fTx, gTy)) \leq \psi(d(Tx, Ty)) - \varphi(d(Tx, Ty)) \quad (3.44)$$

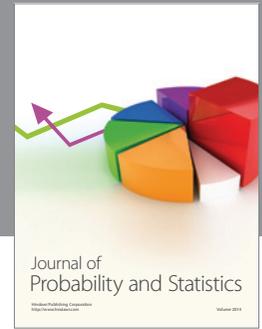
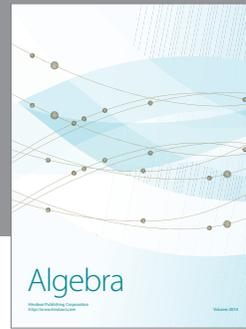
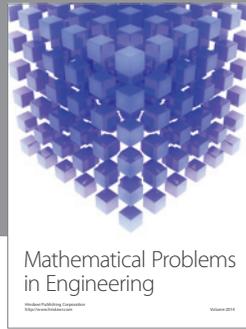
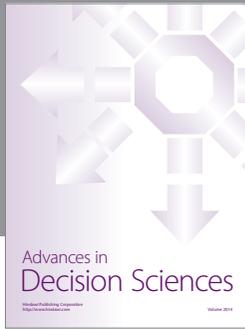
for all  $x, y \in X$ , then  $f, g$  have a unique common fixed point.

*Proof.* It follows from the proof of Theorem 3.1 with necessary modifications.  $\square$

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