ON \Theta-C-OPEN SETS

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ABSTRACT. The properties of the collection of complements of Θ -closures of sets in a topological space are investigated in this paper. A strong continuity condition is defined in terms of these sets. Some applications to H-closed spaces and Katetov spaces are given.

KEY WORDS AND PHRASES. θ-C-open, θ-C-continuous, supercontinuous, H-closed space, Katetov space.
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1. PRELIMINARIES.

All spaces are topological spaces with no separation axioms assumed unless explicitly stated. Let A be a subset of a space x. The closure of A and the interior of A are denoted by Cl A and Int A, respectively. The set A is said to be regular open (regular closed) if A = Int Cl A (A = Cl Int A). The θ -closure (S-closure) (Velicko [1]) of A is the set of all x in X such that every closed neighborhood (the interior of every closed neighborhood) of x intersects A nontrivially. The θ -closure and the S-closure of A are denoted by Cl_{Θ} A and Cl_{S} A, respectively. The set A is called θ -closed (δ -closed) if A = Cl_{Θ} A (A = Cl_{Σ} A). A set A is said to be ∂ -open (5-open) if its complement is θ -closed (δ -closed). For a given space X both the collection of all θ -open sets and the collection of all δ -open sets form topologies. The collection of S-open sets is usually referred to as the semi-regular topology.

DEFINITION 1. Arya and Gupta [2]. A function f: $X \rightarrow Y$ is said to be completely continuous if for each open subset V of Y, $f^{-1}(V)$ is regular open in X.

DEFINITION 2. Munshi and Basson [3]. A function f: $X \rightarrow Y$ is said to be super-continuous if for each $x \equiv X$ and each open

neighborhood V of f(x), there exists an open neighborhood U of of x for which $f(Int \ Cl \ U) \subseteq V$.

DEFINITION 3. Long and Herrington [4]. A function f: X \neg Y is said to be strongly \bigcirc -continuous if for each x \Subset X and each open neighborhood V of f(x), there exists an open neighborhood U of x for which f(Cl U) \subsetneq V.

DEFINITION 4. Porter and Tikoo [5]. A space X is said to be H-closed if X is a closed subset in every space containing X as a subspace.

DEFINITION 5. Porter and Tikoo [5]. A space is said to be Katetov if it has a coarser minimal H-closed topology or equivalently a coarser H-closed topology.

2. ∂-C-OPEN SETS

We define a subset U of a space X be θ -C-open provided there exists a subset A of X for which X - U = Cl_{θ} A. We call a set θ -C-closed if its complement is θ -C-open or equivalently if there is a subset A of X such that the set equals Cl_{θ} A.

THEOREM 1. If U is θ -open, then U is θ -C-open.

PROOF. Since U is θ -open, X - U is θ -closed. Hence X - U = $Cl_{\theta}(X - U)$.

THEOREM 2. If U is open, then Int Cl U is θ -C-open.

PROOF. Int Cl U = X - Cl(X - Cl U). Since X - Cl U is open, Cl(X - Cl U) = Cl_{θ}(X - Cl U) (Velicko [1]). Hence X - Int Cl U = Cl_{θ}(X - Cl U).

COROLLARY. If U is regular open, then U is P-C-open.

Since the real numbers with the usual topology contain θ -open sets that are not regular open, it follows that the real numbers contain θ -C-open sets that are not regular open.

THEOREM 3. Regular openness is equivalent to θ -C openness if and only if Cl_{μ} A is regular closed for every set A.

PROOF. Let X be a space. Assume regular openness is equivalent to ∂ -C-openness and let A \subseteq X. Then X - Cl_{∂} A is regular open. Thus X - Cl_{∂} A = Int Cl(X - Cl_{∂} A) = Int(X - Int Cl_{∂} A) = X - Cl Int Cl_{∂} A. Therefore Cl_{∂} A = Cl Int Cl_{∂} A which implies that Cl_{∂} A is regular closed.

Assume $Cl_{\Theta} A$ is regular closed for every set A. Suppose U is Θ -C-open and let $A \in X$ such that $U = X - Cl_{\Theta} A$. Then Int Cl U = Int $Cl(X - Cl_{\Theta} A) = Int(X - Int Cl_{\Theta} A) = X - Cl$ Int $Cl_{\Theta} A =$ = $X - Cl_{\Theta} A = U$. Therefore U is regular open and hence regular openness is equivalent to Θ -C-openness.

THEOREM 4. If U is $\Theta\text{-}C\text{-}open,$ then U is a union of regular open sets (that is $\epsilon\text{-}open$).

PROOF. Let U be θ -C-open. Let $x \in U$. Since U is θ -C-open, there exists a set A \subseteq X such that U = X - Cl_{θ} A. Because $x \notin$ Cl_{θ} A, there exists an open set W for which $x \in W$ and (Cl W) \cap A = ϑ . Hence $x \in$ Int Cl W \subseteq X - Cl_{θ} A = U. Thus U is a union of regular open sets.

It follows from Theorem 4 and the corollary to Theorem 2 that the θ -C-open sets form a basis for the semi-regular topology.

THEOREM 5. The intersection of two P-C-open sets is P-C-open.

PROOF. Let U and V be θ -C-open sets. There exist sets A and B such that U = X - Cl_{θ} A and V = X - Cl_{θ} B. Then U \cap V = (X - Cl_{θ} A) \cap (X - Cl_{θ} B) = X - (Cl_{θ}(A) \cup Cl_{θ}(B)) = X - Cl_{θ}(A \cup B).

The following example shows that the union of two θ -C-open sets need not be θ -C-open. It follows that the θ -C-open sets do not form a topology and hence θ -C-openness is not equivalent to either S-openness or θ -openness.

EXAMPLE 1. Let X = {a, b, c} and \Im = {X, ø, {a}, {c}, {a, c}}. The Θ -C-open sets of X are X, ø, {a}, and {c}.

3. θ -C-CONTINUITY.

We define a function f: X - Y to be θ -C-continuous if for each open subset V of Y, f⁻¹(V) is θ -C-open in X. Since θ -C-open sets are open, obviously θ -C-continuity implies continuity. Since by Theorem 2 regular openness implies θ -C-openness, complete continuity implies θ -C-continuity. The identity mapping on the real numbers with the usual topology is θ -Ccontinuous but not completely continuous.

THEOREM 6. (Munshi and Basson [3]) A function f: $X \rightarrow Y$ is super-continuous if and only if the inverse image of each open set in Y is S-open in X.

By Theorem 4 every θ -C-open set is 5-open. Hence θ -Ccontinuity implies super-continuity. The identity mapping on the space in Example 1 is super-continuous but not θ -C-continuous.

It also follows from Theorem 4 that the corresponding "local" or "pointwise" version of θ -C-continuity is equivalent to supercontinuity.

THEOREM 7. A function f: $X \Rightarrow Y$ is super-continuous if and only if for each $x \in X$ and each open neighborhood V of f(x), there exists a Θ -C-open set U $\subseteq X$ for which $x \in U$ and $f(U) \subseteq V$.

THEOREM 8. (Long and Herrington [4]). A function f: X - Y is strongly θ -continuous if and only if the inverse image of each open set in Y is θ -open in X.

From Theorem 1 θ -openness implies θ -C-openness. Hence strong θ -continuity implies θ -C-continuity.

EXAMPLE 2. Let X = {a. b, c}, \mathfrak{I}_1 = {X, \mathfrak{S} , {a}, {c}, {a, c}} and \mathfrak{I}_2 = {X, \mathfrak{S} , {a}}. The identity mapping (X, \mathfrak{I}_1) \rightarrow (X, \mathfrak{I}_2) is θ -C-continuous but not strongly θ -continuous.

Based upon the above theorems and remarks, we have the following implications, none of which are reversible.

complete continuity $\} \Rightarrow \theta$ -C-continuity \Rightarrow super-continuity

THEOREM 9. If f: X \rightarrow Y is θ -C-continuous and Cl_{θ} A is regular closed for every subset A of X, then f is completely continuous.

PROOF. By Theorem 3 θ -C-openness is equivalent to regular openness. **THEOREM 10.** If f: X \rightarrow Y is θ -C-continuous and for every subset A of X, Cl_{θ} A is θ -closed, then f is strongly θ -continuous. PROOF. Follows from Theorem 8. The following theorems and examples illustrate some of the basic properties of θ -C-continuous functions. THEOREM 11. If f: $X \rightarrow Y$ is θ -C-continuous and g: $Y \rightarrow Z$ is continuous, then gof: $X \rightarrow Z$ is θ -C-continuous. The proof is routine. COROLLARY. The composition of two e-C-continuous functions is θ -C-continuous. THEOREM 12. Let f_{∞} : X \Rightarrow Y_{∞} be a function for each α in A and let f: X \Rightarrow T Y_w be given by f(x) = (f_w(x)). If f is θ -C-continuous, then \mathbf{f}_{∞} is $\theta\text{-}C\text{-}\mathrm{continuous}$ for each \propto in A. **PROOF.** For each $\alpha \in A$ denote the projection onto Y_{α} by p_{α} . Then $f_{\infty} = p_{\infty} \circ f$ is θ -C-continuous by Theorem 11. The proof of the next theorem follows from Theorem 12. **THEOREM 13.** Let f: X \rightarrow Y be a function and let g: X \rightarrow X \times Y given by g(x) = (x, f(x)) be its graph function. If g is θ -C-continuous, then f is θ -C-continuous. The following example shows that the converse of Theorem 13 does not hold. EXAMPLE 3. Let $X = \{a, b, c\}$ and $\mathcal{T} =$ $\{X, \emptyset, \{a\}, \{c\}, \{a, c\}\}$. Define f: X \rightarrow X by f(a) = f(b) = f(c) = a. Then f is θ -C-continuous, but its graph function is not θ -C-continuous since $g^{-1}(\{(a, a), (c, a)\}) = \{a, c\}$ which is not θ -C-open. The proof of the following theorem is straightforward and is omitted. THEOREM 14. A function f: $X \rightarrow Y$ is θ -C-continuous if and only if for each closed subset F of Y, there exists a subset A of X for which $f^{-1}(F) = Cl_{\theta} A$. THEOREM 15. If the functions f, g: $X \rightarrow Y$ are θ -C-continuous and Y is Hausdorff, then the set $A = \{x : f(x) \neq g(x)\}$ is a union of θ -C-open sets. **PROOF.** Let $x \in A$. Since $f(x) \neq g(x)$ and Y is Hausdorff, there exist disjoint open sets V and W containing f(x) and g(x), respectively. Then $f^{-1}(V)$ and $g^{-1}(W)$ are θ -C-open. By Theorem 5 $f^{-1}(V) \cap g^{-1}(W)$ is θ -C-open. Obviously $x \in f^{-1}(V) \cap g^{-1}(W) \subseteq A$. COROLLARY. If the functions f, g: $X \rightarrow Y$ are θ -C-continuous, then the set $B = \{x : f(x) = g(x)\}$ is \mathcal{S} -closed. PROOF. By Theorem 15 X - B is a union of θ -C-open sets and by Theorem 4 each θ -C-open set is a union of regular open sets. For a function f: $X \rightarrow Y$ the graph of f, denoted by G(f), is the subset $\{(x, f(x)) : x \in X\}$ of the product space $X \times Y$. THEOREM 16. If f: $X \rightarrow Y$ is θ -C-continuous and Y is Hausdorff, then $X \times Y - G(f)$ is a union of sets of the form $A \times B$ where A is ϑ -C-open and B is open.

PROOF. Let $(x, y) \in X \cdot Y - G(f)$. There exist disjoint open sets V and W for which $f(x) \in V$ and $y \in W$. Then $f^{-1}(V)$ is ∂ -Copen and $(x, y) \in f^{-1}(V) \setminus W \subseteq X \cdot Y - G(f)$.

The following theorem is easily proved.

THEOREM 17. If f: X - Y is a Θ -C-continuous injection and Y is Hausdorff, then points in X can be separated by Θ -C-open sets. 4. APPLICATIONS TO H-CLOSED SPACES AND KATETOV SPACES

In this section all spaces are assumed to be Hausdorff.

Since H-closed spaces and Katetov spaces are related to the θ -closures of sets, there are natural relationships between these spaces and θ -C-copen sets and θ -C-continuity. The following results are required.

THEOREM 18. (Porter and Tikoo [5]). If X is an H-closed space and A \subseteq X, then Cl_{i2} A is Katetov.

THEOREM 19. (Porter and Tikoo [5]). An H-closed space in which every closed set is the θ -closure of some set is compact.

The next result follows immediately from Theorems 14 and 18. Theorem 20. If X is H-closed and f: X - Y is e-C-continuous, then for each closed subset F of Y, $f^{-1}(F)$ is a Katetov subspace of X.

As a consequence of Theorem 19 we have the following result. Theorem 21. If X is H-closed and every open set is θ -Copen, then X is compact.

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