ON A CLASS OF THIRD ORDER NEUTRAL DELAY DIFFERENTIAL EQUATIONS WITH PIECEWISE CONSTANT ARGUMENT

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ABSTRACT. In this paper we study existence, uniqueness and asymptotic stability of the solutions of a class of third order neutral delay differential equations with piecewise constant argument.

KEY WORDS AND PHRASES. Neutral delay differential equations with piecewise constant argument, difference equation, existence and uniqueness of solutions, asymptotic stability.

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1. INTRODUCTION

Recently there has been an increase in interest in the study of differential equations with piecewise constant argument. See Aftabizadeh, Wiener and Xu [1], Cooke and Wiener [2], [3], Huang [4], Ladas, Partheniadis and Schinas [5], Partheniadis [6].

In this paper we study the third order neutral delay differential equations with piecewise constant argument of the form

$$\frac{d^{3}}{dt^{3}} (y(t) + py(t - 1)) = -qy([t - 1])$$
(1)

where $t \in [0, \infty)$, p,q are real constants and $[\cdot]$ denotes the greatest-integer function. It is worthwile to study equations of the form (1) because they include both constant and piecewise constant delays.

A function y: $[-1,\infty) \rightarrow \mathbb{R}$ is a solution of (1) if the following conditions are satisfied:

- (i) y is continuous on the set $[-1,\infty)$,
- (ii) $\frac{d^2}{dt^2}(y(t) + py(t 1)) = g(t)$ exists on $[0,\infty)$ and g is continuous on $[0,\infty)$,
- (iii) $\frac{d^3}{dt^3}(y(t) + py(t 1))$ exists on $[0,\infty)$ except possibly at the points t=n,

n 6 {0,1,...} where one-sided third derivatives exist,

(iv) y satisfies (1) on each interval [n,n+1), $ne\{0,1,\ldots\}$.

In Proposition 1 of this paper we prove that for every initial function $y_0: [-1,0] \rightarrow \mathbb{R}$ continuous on [-1,0] and for every $a_1, a_2 \in \mathbb{R}$ there exists a unique solu-

tion y(t) of (1) such that y(t) = $y_0(t)$, te[-1,0], y(1) = a_1 and y(2) = a_2 . We prove also that equation (1) is not asymptotically stable (see Proposition 2 below).

We note that similar results for the first and the second order differential equations of the form (1) are included in $\lfloor 6 \rfloor$.

2. MAIN RESULTS.

We prove now our main results.

PROPOSITION 1. Equation (1) has a unique solution y(t) such that

$$y(t) = \begin{cases} y_{0}(t) & t \in [-1,0] & \text{for } p \neq 0 \\ a_{-1} & t = -1 & \text{for } p = 0 \\ a_{0} & t = 0 & \text{for } p = 0 \\ a_{1} & t = 1 \\ a_{2} & t = 2 \end{cases}$$
(2)

where $y_0: [-1,0] \rightarrow R$ is a continuous function on [-1,0], a_{-1}, a_0, a_1, a_2 are real constants and $a_0 = y_0(0)$, $a_{-1} = y_0(-1)$ if $p \neq 0$.

The solution y(t) is defined by

$$y(t) = (-p)^{n+1} y_{0}(\theta - 1) + \sum_{k=0}^{n} (-p)^{n-k} \left(\frac{(\theta^{2} - \theta)}{2} a_{k+2} + \left(\frac{\theta^{2}(p-2)}{2} + \frac{\theta(4-p)}{2} \right) a_{k+1} + \left(\frac{\theta^{2}}{2} (\frac{q}{6} - 2p + 1) + \theta(2p - \frac{q}{12} - \frac{3}{2}) + 1 \right) a_{k} + \left(-\frac{q}{6} \theta^{3} + \frac{\theta^{2}}{2} (p + \frac{5q}{6}) - \frac{\theta}{2} (3p + \frac{q}{2}) + p \right) a_{k-1} \right)$$
(3)

where a satisfies the difference equation

$$a_{n+4} + (p-3)a_{n+3} + (\frac{q}{6} - 3p + 3)a_{n+2} + (\frac{2q}{3} + 3p - 1)a_{n+1} + (\frac{q}{6} - p)a_n = 0.$$
 (4)

PROOF. Consider a solution y(t) of (1) which satisfies (2). For each $te[-1,\infty)$ there exists a $ne\{-1,0,\ldots\}$ such that $n \leq t < n+1$. We set

$$y(n) = a_n, n\in\{-1,0,\ldots\}.$$
 (5)

Then from (1) for $t \ge 0$, $t \in [n, n+1)$, $n \in \{0, 1, ...\}$ it holds

$$\frac{d^3}{dt^3} (y(t) + py(t - 1)) = -qa_{n-1}.$$
 (6)

If

$$\beta_n = \frac{d^2}{dt^2} (y(t) + py(t - 1)) \text{ at } t = n, \quad ne\{0, 1, ...\}$$
(7)

then by integrating (6) from n to te[n, n+1), $ne\{0, 1, ...\}$ we take

$$\frac{d^2}{dt^2} (y(t) + py(t - 1)) = \beta_n - q(t - n)a_{n-1}.$$
 (8)

Moreover if

$$c_n = \frac{d}{dt} (y(t) + py(t - 1)) \text{ at } t = n, ne\{0, 1, ...\}$$
 (9)

by integrating (8) from n to t, te[n,n+1), $ne\{0,1,\ldots\}$ we have

$$\frac{d}{dt}(y(t) + py(t - 1)) = c_n + (t - n)\beta_n - \frac{q}{2}(t - n)^2 a_{n-1}.$$
(10)

Finally by integrating (10) from n to t, t6[n,n+1), n6{0,1,...} and using (5) we obtain

$$y(t) + py(t-1) = a_n + pa_{n-1} + (t-n)c_n + \frac{(t-n)^2}{2} \beta_n - \frac{q}{6} (t-n)^3 a_{n-1}.$$
 (11)

Applying now Lemma 3 [6,p.96] to (11) we get

$$y(t) = (-p)^{n+1} y_0(\theta - 1) + \sum_{k=0}^{n} (-p)^{n-k} (a_k^+ p a_{k-1}^+ \theta c_k^+ \frac{\theta^2}{2} \beta_k^- \frac{q}{6} \theta^3 a_{k-1}^-)$$
(12)

where $t = n + \theta$, $0 \leq \theta \leq 1$, $n \in \{0, 1, ...\}$.

Since y(t) is continuous in $[-1,\infty)$ by taking the limit as t + n+1 in (11) and using (5) we get for $n \in \{0,1,\ldots\}$

$$a_{n+1} + pa_n = a_n + (p - \frac{q}{6}) a_{n-1} + c_n + \frac{1}{2} \beta_n.$$
 (13)

If we take the limit as $t \rightarrow n+1$ in (8) and since the function $g(t) = \frac{d^2}{dt^2} (y(t) + py(t-1))$ is continuous, using (7) we have for $n \in \{0, 1, ...\}$

$$\beta_{n+1} = \beta_n - qa_{n-1}.$$
 (14)

Obviously the function $h(t) = \frac{d}{dt} (y(t) + py(t - 1))$ is continuous on $[0,\infty)$. Then if we take the limit as $t \rightarrow n+1$ in (10) and using (9) we obtain for $n\in\{0,1,\ldots\}$

$$c_n = c_{n+1} - \beta_n + \frac{q}{2} a_{n-1}.$$
 (15)

By eliminating b_n , c_n from (13), (14), (15) we can easily get

$$-\frac{\beta_{n+1}}{2} + c_{n+1} = a_{n+1} + (p-1)a_n + (\frac{q}{6} - p)a_{n-1}.$$
 (16)

If we eliminate b_{n+1} , c_{n+1} from (14), (16) and the relation which is derived from (13) by setting n+1 instead of n, then it holds

$$\beta_n = a_{n+2} + (p-2) a_{n+1} + (\frac{q}{6} - 2p + 1) a_n + (p + \frac{5q}{6}) a_{n-1}.$$
 (17)

Using (13) and (17) for $n\in\{0,1,\ldots\}$ we can easily take

$$c_n = -\frac{1}{2}a_{n+2} + (2 - \frac{p}{2})a_{n+1} + (2p - \frac{q}{12} - \frac{3}{2})a_n - (\frac{3p}{2} + \frac{q}{4})a_{n-1}.$$
 (18)

Therefore from (12), (17) and (18) we can easily show that y(t) satisfies (3).

Now from relations (14) and (17) it is easy to prove that a satisfies the difference equation (4).

Obviously if $p \neq \frac{q}{6}$ there exists a unique solution a_n of (4) with initial values a_{-1} , a_0 , a_1 , a_2 and if $p = \frac{q}{6}$, $p \neq \frac{1}{7}$, $q \neq \frac{6}{7}$ (resp. $p = \frac{1}{7}$, $q = \frac{6}{7}$) there exists a unique solution of (4) with initial values a_0 , a_1 , a_2 (resp. a_1 , a_2). Therefore we proved that if y(t) is a solution of (1) which satisfies (2) then is defined by (3) and (4) and is uniquely determined by y_0 , a_1 , a_2 if $p \neq 0$

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and a_{-1}^{a} , a_{0}^{a} , a_{1}^{a} , a_{2}^{a} if p = 0.

Conversely we can easily show that the function y(t) defined by (3) and (4) is a solution of (1) which satisfies (2). Thus the proof of the proposition is completed.

Using (3) and the same argument as in the proof of the Corollary 4 [6,p.110-111] we can easily prove the following corollary.

COROLLARY 1. Let y(t) be the solution of (1) which satisfies (2). Then it holds

$$y(t) = (-p)^{n+1} y_0(\theta - 1) + (-p)^{n+1} \left(-\frac{\theta^2}{2} (1 + \frac{q}{6}) + \frac{\theta}{2} (\frac{q}{6} + 3) - 1 \right) a_{-1} + + (-p)^{n+1} \left(\theta^2 (1 - p) + \theta (p - 2) \right) a_0 + (-p)^{n+1} \frac{(-\theta^2 + \theta)}{2} a_1 + + \left(\frac{\theta^2}{2} (\frac{q}{6} + 1) - \frac{\theta}{2} (\frac{q}{6} + 3) + 1 \right) a_n + (2\theta - \theta^2) a_{n+1} + \frac{(\theta^2 - \theta)}{2} a_{n+2} + + \sum_{k=0}^{n} (-p)^{n-k} \left(-\frac{q}{6} \theta^3 + \frac{\theta^2 q}{12} (5 - p) + \frac{\theta q}{4} (\frac{p}{3} - 1) \right) a_{k-1}$$

where $t = n + \theta$, $0 \le \theta \le 1$, $n \in \{0, 1, \ldots\}$.

In Proposition 2 of this paper we prove that (1) is not asymptotically stable. We need the following lemma.

LEMMA 1. Consider the difference equation

$$a_{n+4} + \mu_1 a_{n+3} + \mu_2 a_{n+2} + \mu_3 a_{n+1} + \mu_4 a_n = 0$$
 (19)

where $n\in\{-1,0,1,\ldots\}$ and μ_i , i = 1,2,3,4 are real constants. Then (19) is asymptotically stable if and only if the following conditions are satisfied:

(i)
$$\lambda_1 \neq 0$$
, (ii) $\frac{\lambda_2}{\lambda_1} > 0$, (iii) $\frac{\lambda_3}{\lambda_1} > 0$, (iv) $\frac{\lambda_5}{\lambda_1} > 0$
(v) $\frac{\lambda_4}{\lambda_1} \left(\frac{\lambda_2 \lambda_3}{\lambda_1^2} - \frac{\lambda_4}{\lambda_1} \right) > \frac{\lambda_2^2 \cdot \lambda_5}{\lambda_1^3}$
(20)

where

$$\lambda_{1} = 1 + \mu_{1} + \mu_{2} + \mu_{3} + \mu_{4}, \qquad \lambda_{2} = 4 + 2\mu_{1} - 2\mu_{3} - 4\mu_{4},$$

$$\lambda_{3} = 6 - 2\mu_{2} + 6\mu_{4}, \quad \lambda_{4} = 4 - 2\mu_{1} + 2\mu_{3} - 4\mu_{4}, \quad \lambda_{5} = 1 - \mu_{1} + \mu_{2} - \mu_{3} + \mu_{4}.$$
(21)

PROOF. It is known that (19) is asymptotically stable if and only if every root v of the characteristic equation

$$v^{4} + \mu_{1}v^{3} + \mu_{2}v^{2} + \mu_{3}v + \mu_{4} = 0$$
 (22)

satisfies $|\mathbf{v}| < 1$. Then it is clear that $\lambda_1 \neq 0$. Therefore using the Mobius transformation

$$\mathbf{v} = \frac{\mathbf{z} + 1}{\mathbf{z} - 1}$$

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to (22) we can take the equation

$$z^{4} + \frac{\lambda_{2}}{\lambda_{1}} z^{3} + \frac{\lambda_{3}}{\lambda_{1}} z^{2} + \frac{\lambda_{4}}{\lambda_{1}} z + \frac{\lambda_{5}}{\lambda_{1}} = 0$$
(23)

where the constants λ_i , i = 1,2,3,4,5 are defined in (21).

It is easy to show that every root v of (22) satisfies |v| < 1 if and only if Rez < 0, where Rez is the real part of z and z is the root of (23). Using Routh-Hurwitz criteria [7,p.158] we have Rez < 0 if and only if all the conditions (20) are satisfied. This completes the proof of the lemma.

PROPOSITION 2. Equation (1) is not asymptotically stable.

PROOF. Suppose that (1) is asymptotically stable. Then the difference equation (4) is also asymptotically stable. We apply Lemma 1 to (4). It is easy to show that

$$\lambda_1 = q$$
 and $\lambda_2 = -2q$.

Then $\frac{\Lambda_2}{\lambda_*} = -2 < 0$ which contradicts the second condition of (20). Therefore (1) is not asymptotically stable.

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