

## ON MINIMAX THEORY IN TWO HILBERT SPACES

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**ABSTRACT.** In this paper, we investigated the minimax of the bifunction

$$J: H^1(\Omega) \times V_2 \rightarrow \mathbb{R}^m \times \mathbb{R}^n,$$

such that

$$J(v_1, v_2) = ((\frac{1}{2} a(v_1, v_1) - L(v_1)), v_2)$$

where

$a(\cdot, \cdot)$  is a finite symmetric bilinear bicontinuous, coercive form on  $H^1(\Omega)$  and  $L$  belongs to the dual of  $H^1(\Omega)$ .

In order to obtain the minimax point we use lagrangian functional.

**KEY WORDS AND PHRASES.** Hilbert spaces, dual spaces, minimization of functionals, minimax point, saddle point, concave functions, convex function, bicontinuous form, coercive form.

### 1. INTRODUCTION.

The minimization of functionals defined only on one Hilbert space has been studied by Jean Cea[1], and the saddle functions has been introduced and investigated by Rockafellar [2]. Our aim, is to generalize the above work in order to obtain a general minimax of functionals defined on two Hilbert spaces. We consider the Sobolev space  $H^1(\Omega)$  with inner-product,

$$((u, v)) = \int_{\Omega} \{uv + \sum_{j=1}^n (D_j u)(D_j v)\} dx,$$

as a Hilbert space.

The Green's formula will be used to obtain a minimal solution in this work.

### 2. PRIMILARIES

Let  $\Omega$  be a bounded open subset in  $\mathbb{R}^n$  and  $\Gamma$  denote its boundary. The Sobolev space  $H^1(\Omega)$  can be defined as follows, [1]:

$$H^1(\Omega) = \{v: v \in L^2(\Omega), \partial v / \partial x_j \in L^2(\Omega), j = 1, 2, \dots, n\}$$

where  $D_j v = \partial v / \partial x_j$  are taken in the sense of distributions i.e.

$$\langle D_j v, \varphi \rangle = - \langle v, D_j \varphi \rangle \quad \text{for all } \varphi \in \mathcal{D}(\Omega)$$

are  $\mathcal{D}(\Omega)$  denotes the space of all  $C^\infty$ -functions with compact support in  $\Omega$ , Also  $\langle, \rangle$  denotes the duality between  $\mathcal{D}(\Omega)$  and the space of distribution  $\mathcal{D}'(\Omega)$  on  $\Omega$ . The space  $H^1(\Omega)$  is provided with the inner-product.

$$\begin{aligned} ((u, v)) &= (u, v)_{L^2(\Omega)} + \sum_{j=1}^n (D_j u, D_j v)_{L^2(\Omega)} \\ &= \int_{\Omega} \{uv + \sum_{j=1}^n (D_j u)(D_j v)\} dx. \end{aligned}$$

The vector  $\varphi \in V$ ,  $\varphi \neq 0$  is called a direction in  $V$ .

If  $\Gamma$  is "regular" (for instance,  $\Gamma$  is a  $C^1$  (or  $C^\infty$ )-manifold of dimension  $n-1$ ) then the linear mapping  $v \rightarrow \gamma v$  of  $C^1(\bar{\Omega}) \rightarrow C^1(\Gamma)$  (resp. of  $C^\infty(\bar{\Omega}) \rightarrow C^\infty(\Gamma)$ ) extends to a continuous linear map of  $H^1(\Omega)$  into  $L^2(\Gamma)$  denoted by  $\gamma$  and for  $v \in H^1(\Omega)$ ,  $\gamma(v)$  is called the trace of  $v$  on  $\Gamma$ .

A linear transformation  $L: v \rightarrow L(v)$  is continuous if there exists a constant  $N$  such that

$$L(v) \leq N \|v\|_V \quad \text{for } v \in V.$$

A bilinear function  $a(u, v): V \times V \rightarrow \mathbb{R}^m$ , is bicontinuous if there exists a constant  $M > 0$  such that

$$a(u, v) \leq M \|u\|_V \|v\|_V \quad \text{for all } u, v \in V.$$

A bilinear function  $a(u, v)$  is  $V$ -coercive if there exists a constant  $\alpha > 0$  such that

$$a(u, v) \geq \alpha \|v\|_V^2 \quad \text{for all } v \in V.$$

Let  $E$  be a vector space, a cone with vertex at  $o$  in  $E$  is a subset  $\Lambda$  of  $E$  such that, if  $\lambda$  belongs to  $\Lambda$  and if  $\alpha$  belongs to  $\mathbb{R}$  with  $\alpha \geq 0$  then  $\alpha\lambda$  also belongs to  $\Lambda$ .

In the following we have collected the Lemmas and Theorems we needed to obtain our main results. It should be noted that these are based on [1] except corollary (4) on [2].

1. LEMMA. The following equality

$$\sum_{j=1}^n (D_j u, D_j v)_{L^2(\Omega)} = - \int_{\Omega} (\Delta u) v dx + \int_{\Gamma} \frac{\partial u}{\partial \underline{n}} v d\sigma \quad (1)$$

where

$$(D_j u, D_j v)_{L^2(\Omega)} \text{ is the inner product defined in } L^2(\Omega) \text{ is true.}$$

PROOF. If  $u, v \in C^1(\Omega)$ , and by using Green's formula [3], we get

$$\int_{\Omega} (D_j u) v dx = - \int_{\Omega} u (D_j v) dx + \int_{\Gamma} u v n_j d\sigma \quad (2)$$

where  $d\sigma$  is the area element on  $\Gamma$ .

We define the operator of exterior normal derivation formally as

$$\frac{\partial}{\partial \underline{n}} = \sum_{j=1}^n n_j(x) D_j,$$

such that  $\underline{n}(x)$  is the unique outer normal vector at each point  $x$  on  $\Gamma$ , and  $(n_1(x), \dots, n_n(x))$  are the direction cosines of  $\underline{n}(x)$ .

Next, if  $u, v \in C^2(\bar{\Omega})$ , then applying the above formula to  $D_j u, D_j v$  becomes

$$\int_{\Omega} (D_j^2 u) v dx = - \int_{\Omega} (D_j u) (D_j v) dx + \int_{\Gamma} (D_j u) v n_j d\sigma$$

and

$$\sum_{j=1}^n \int_{\Omega} (D_j u) (D_j v) dx = - \sum_{j=1}^n \int_{\Omega} (D_j^2 u) v dx + \sum_{j=1}^n \int_{\Gamma} (D_j u) v n_j d\sigma.$$

Then

$$\sum_{j=1}^n (D_j u, D_j v)_{L^2(\Omega)} = - \sum_{j=1}^n \int_{\Omega} (D_j^2 u) v dx + \int_{\Gamma} \frac{\partial u}{\partial \underline{n}} v d\sigma$$

$$\sum_{j=1}^n (D_j u, D_j v)_{L^2(\Omega)} = - \int_{\Omega} (\Delta u) v dx + \int_{\Gamma} \frac{\partial u}{\partial n} v ds.$$

2. LEMMA. Let  $V$  be a Hilbert space,  $V'$  be its strong dual, and  $J: V \rightarrow \mathbb{R}$  be a functional such that

$$J(v) = \frac{1}{2} a(v, v) - L(v)$$

where  $a(\cdot, \cdot)$  is a symmetric bilinear, bicontinuous, coercive form on  $V$  and  $L \in V'$ . Further, let  $K$  be a closed convex subset of  $V$  then for all  $v \in K$  there exist  $u \in K$  such that

$$J(u) \leq J(v)$$

3. THEOREM. There exists a unique solution  $u \in K$  which minimizes  $J$  on  $K$ , and this problem is equivalent to the following variational problem: Find  $u \in K$  such that  $a(u, v - u) \geq L(v - u)$

4. COROLLARY. Let  $C$  and  $D$  be non-empty closed convex sets in  $\mathbb{R}^m$  and  $\mathbb{R}^n$ , respectively, and let  $K$  be any finite continuous concave-convex function on  $C \times D$ .

Let  $\underline{K}$  and  $\overline{K}$  be the lower and upper simple extensions of  $K$  to  $\mathbb{R}^m \times \mathbb{R}^n$ , respectively. Then  $\underline{K}$  is lower closed,  $\overline{K}$  is upper closed, and there exists a unique closed convex bifunction from  $\mathbb{R}^m$  to  $\mathbb{R}^n$  such that

$$\underline{K}(u, \dot{x}) = \langle Fu, \dot{x} \rangle, \quad \overline{K}(u, \dot{x}) = \langle u, F^* \dot{x} \rangle.$$

The bifunctions  $F$  and  $F^*$  are expressed in terms of  $K$  by

$$(Fu)(x) = \begin{cases} \sup \{ \langle x, \dot{x} \rangle - K(u, \dot{x}); \dot{x} \in D \} & \text{if } u \in C, \\ +\infty & \text{if } u \notin C, \end{cases}$$

$$(F^* \dot{x})(u) = \begin{cases} \inf \{ \langle u, \dot{x} \rangle - K(u, \dot{x}); u \in C \} & \text{if } \dot{x} \in D, \\ -\infty & \text{if } \dot{x} \notin D. \end{cases}$$

In particular,  $\text{dom } F = C$  and  $\text{dom } F^* = D$ .

5. THEOREM. (Ky Fan and Sion)

Let  $V$  and  $E$  be two Hausdorff topological vector spaces,  $U$  be a convex compact subset of  $V$  and  $\Lambda$  be a convex compact subset of  $E$ . Suppose

$$\mathcal{L}: U \times \Lambda \rightarrow \mathbb{R}$$

be a functional such that

i) for every  $v \in U$  the functional

$$\mathcal{L}(v, \cdot): \mu \rightarrow \mathcal{L}(v, \mu)$$

is upper-semi-continuous and concave,

ii) for every  $\mu \in \Lambda$  the functional

$$\mathcal{L}(\cdot, \mu): v \rightarrow \mathcal{L}(v, \mu)$$

is lower-semi-continuous and convex. Then there exists a saddle point  $(u, \lambda) \in U \times \Lambda$  for  $\mathcal{L}$

3. MAIN RESULTS.

6. THEOREM. Let  $\Omega$  be a bounded open set in  $\mathbb{R}^n$  with smooth boundary  $\Gamma$ . Let  $V_1$  and  $V_2$  be two Hilbert spaces,  $V_1 = H^1(\Omega)$ , and  $V_1', V_2'$  be two (strongly) duals. If the bifunction

$$J: V_1 \times V_2 \rightarrow \mathbb{R}^m \times \mathbb{R}^n$$

is defined by

$$J(v_1, v_2) = ((\frac{1}{2} a(v_1, v_1) - L(v_1)), v_2)$$

where  $a(\cdot, \cdot)$  is a finite symmetric bilinear, bicontinuous, coercive form on  $V_1, L \in V_1'$ , and  $K_1$  is the following subset:

$$K_1 = \{v_1; v_1 \in H^1(\Omega), \|\gamma v_1\|_{L^2(\Gamma)} \leq 1; \gamma(v_1) \text{ is a trace}\}.$$

Then there exist a minimax of  $J$ .

PROOF. We first prove that  $K_1$  is a closed convex set. To show that it is closed, we suppose

$(v_1^n) \in K_1$  is a sequence such that  $(v_1^n) \rightarrow v_1$  in  $V_1$ , and since

$$\gamma: H^1(\Omega) \rightarrow L^2(\Gamma)$$

is a continuous linear map. Then

$$\gamma(v_1^n) \rightarrow \gamma(v_1) \text{ in } L^2(\Gamma).$$

If  $\varphi \in L^2(\Gamma)$  is such that  $\varphi > 0$  on  $\Gamma$ , then

$$\begin{aligned} \int_{\Gamma} |\gamma(v_1) \varphi| d\sigma &= \lim_{n \rightarrow \infty} \int_{\Gamma} |\gamma(v_1^n) \varphi| d\sigma \\ &\leq \lim_{n \rightarrow \infty} \left( \int_{\Gamma} |\gamma(v_1^n)|^2 d\sigma \right)^{1/2} \left( \int_{\Gamma} |\varphi|^2 d\sigma \right)^{1/2}, \end{aligned}$$

we choose  $\|\varphi\|_{L^2(\Gamma)} = 1$  such that

$$\lim_{n \rightarrow \infty} \|\gamma(v_1^n)\|_{L^2(\Gamma)} \leq 1 \quad \text{for } (v_1^n) \in K_1.$$

From which we deduce that  $\|\gamma(v_1)\|_{L^2(\Gamma)} \leq 1$ .

Also, to show that  $K_1$  is convex, let  $v_1$  and  $v_2$  be two elements in  $K_1$ , i.e.

$$\|\gamma(v_1)\|_{L^2(\Gamma)} \leq 1 \quad \text{and} \quad \|\gamma(v_2)\|_{L^2(\Gamma)} \leq 1.$$

Let  $\lambda$  be a number such that  $0 \leq \lambda \leq 1$ . Now  $\lambda v_1 + (1 - \lambda)v_2 \in K_1$ ;  $\gamma$  is a continuous linear map, therefore

$$\begin{aligned} \|\gamma(\lambda v_1 + (1 - \lambda)v_2)\|_{L^2(\Gamma)} &\leq \|\lambda \gamma(v_1) + (1 - \lambda)\gamma(v_2)\|_{L^2(\Gamma)} \leq \|\lambda \gamma(v_1)\|_{L^2(\Gamma)} + \|(1 - \lambda)\gamma(v_2)\|_{L^2(\Gamma)} \\ &\leq \lambda \|\gamma(v_1)\|_{L^2(\Gamma)} + (1 - \lambda)\|\gamma(v_2)\|_{L^2(\Gamma)} \leq \lambda + (1 - \lambda) = 1. \end{aligned}$$

Now consider  $f \in L^2(\Gamma)$ , then the problem of minimizing  $J$  where

$$J(v_1, v_2) = ((\frac{1}{2} a(v_1, v_1)_{v_1} - (f, v_1)_{v_1}), v_2)$$

on the closed convex set  $K_1$  is equivalent to finding  $u \in K_1$  satisfying the inequality

$$\begin{aligned} (a(u, v_1 - u), v_2) &= ((u, v_1 - u)_{v_1}, v_2) \\ &\geq \left( (f, v_1 - u)_{L^2(\Gamma)}, v_2 \right) \quad \forall v_1 \in K_1 \end{aligned}$$

where  $(f, v_1 - u)_{L^2(\Gamma)} = L(v_1 - u)$ .

Therefore, assuming the solution  $u$  (which exists and unique by Theorem 3) is sufficiently regular, we can interpret  $u$  as follows:

By Green's formula (1), we have

$$\int_{\Omega} (-\Delta u + u - f)(v_1 - u) dx + \int_{\Gamma} \frac{\partial u}{\partial \underline{n}} (v_1 - u) d\sigma \geq 0, \quad \forall v_1 \in K_1.$$

$\Omega, \Gamma$  are subsets of  $\mathbb{R}^m$ .

If  $\varphi \in \mathcal{D}(\Omega)$  then the boundary integral vanishes for  $v_1 = u \pm \varphi$  which belongs to  $K_1$  and

$$\int_{\Omega} (-\Delta u + u - f)\varphi dx \geq 0$$

which implies that  $-\Delta u + u - f \geq 0$  in  $\Omega$ .

Next since  $v_1 = 2u$  and  $v_1 = \frac{1}{2}u$  are both belong to  $K_1$ , we have

$$\int_{\Gamma} \frac{\partial u}{\partial \underline{n}} u d\sigma = 0$$

which implies that  $\frac{\partial u}{\partial \underline{n}} u = 0$  on  $\Gamma$ .

Thus the minimal of  $J$  is equivalent to the solution of the following problem

$$\begin{cases} -\Delta u + u - f \geq 0 & \text{in } \Omega, \\ \frac{\partial u}{\partial \underline{n}} u = 0 & \text{on } \Gamma, \\ \frac{\partial u}{\partial \underline{n}} u \geq 0 & \text{on } \Gamma, \\ u \geq 0 & \text{on } \Gamma, \end{cases} \tag{I}$$

One can also deduce from (I) that on the subset of  $\Gamma$  where  $u > 0$ ,  $u$  satisfies the homogeneous Neumann condition  $\frac{\partial u}{\partial \underline{n}} = 0$ .

From the Corollary 4, and since  $K_2$  is a nonempty closed convex set in  $V_2$ , we then have

$$J(v_1, u_2) = \begin{cases} \max_{v_2} \{J(v_1, v_2); v_2 \in K_2\} & \text{if } v_1 \in K_1, \\ +\infty & \text{if } v_1 \notin K_1 \end{cases}$$

i.e.,

$$J(v_1, u_2) = \begin{cases} \max_{v_2} \{((\frac{1}{2}a(v_1, v_1) - L(v_1)), v_2); v_2 \in K_2\} & \text{if } v_1 \in K_1, \\ +\infty & \text{if } v_1 \notin K_1 \end{cases}$$

7. THEOREM. Suppose the functional

$$J: H^1(\Omega) \rightarrow \mathbb{R}$$

is given by

$$J(v) = \frac{1}{2} a(v, v) - L(v)$$

and the closed convex set  $K$  of  $V = H^1(\Omega)$  is given by

$$K = \{v; v \in H^1(\Omega), 1 - \text{grad}^2 v(x) \geq 0 \text{ a. e. in } \Omega\}$$

where

$$1 - \text{grad}^2 u(x) \in L^1(\Omega) \quad \text{and} \quad (L^1(\Omega))' = L^\infty(\Omega).$$

Then the lagrangian

$$\mathcal{L}(v, \mu) = J(v) + \langle \mu, v \rangle_{L^\infty(\Omega) \times L^1(\Omega)}$$

associated to the primal problem ( finding  $u \in K$  such that  $J(u) \leq J(v), \forall v \in K$ ), has a minimax point ( saddle point).

PROOF. Let  $\ell > 0$  be any real number. We consider the subsets  $K_\ell$  and  $\Lambda_\ell$  of  $H^1(\Omega)$  and  $\Lambda$  respectively are defined by

$$K_\ell = \{v; v \in H^1(\Omega), 0 \leq 1 - \text{grad}^2 v(x) \leq \ell \text{ a.e. in } \Omega\}$$

$$\Lambda_\ell = \{\mu; \mu \in L^\infty(\Omega), 0 \leq \mu \leq \ell \text{ in } \Omega\}$$

such that  $\Lambda_\ell$  being the cone in infinite dimensional Banach space.

Frist, we show that  $K_\ell$  and  $\Lambda_\ell$  are convex sets in  $\Omega$ .

Let  $v_1, v_2 \in K_\ell$  i.e.,

$$\int_\Omega |1 - \text{grad}^2 v_1(x)| dx \leq \ell^{1/2} \text{ a.e. in } \Omega,$$

and

$$\int_\Omega |1 - \text{grad}^2 v_2(x)| dx \leq \ell^{1/2} \text{ a.e. in } \Omega.$$

Let  $0 \leq \lambda \leq 1$  we have

$$\begin{aligned} \int_\Omega |1 - \text{grad}^2(\lambda v_1(x) + (1-\lambda)v_2(x))| dx &= \int_\Omega |1 - \lambda \text{grad}^2 v_1(x) - (1-\lambda)\text{grad}^2 v_2(x)| dx \\ &= \int_\Omega |\lambda(1 - \text{grad}^2 v_1(x)) + (1-\lambda)(1 - \text{grad}^2 v_2(x))| dx \\ &\leq \int_\Omega |\lambda(1 - \text{grad}^2 v_1(x))| dx + \int_\Omega |(1-\lambda)(1 - \text{grad}^2 v_2(x))| dx \\ &\leq \lambda \sqrt{\ell} + (1-\lambda)\sqrt{\ell} = \sqrt{\ell} \text{ a.e. in } \Omega. \end{aligned}$$

and hence is a convex set.

Now let  $\mu_1, \mu_2 \in \Lambda_\ell$  i.e.,  $\text{Sup}|\mu_1| \leq \ell$  in  $\Omega$  and  $\text{Sup}|\mu_2| \leq \ell$  in  $\Omega$ , for  $0 \leq \lambda \leq 1$  we get

$$\begin{aligned} \text{Sup}|\lambda\mu_1 + (1-\lambda)\mu_2| &\leq \text{Sup}(|\lambda\mu_1| + |(1-\lambda)\mu_2|) \text{ in } \Omega \\ &\leq \text{Sup}|\lambda\mu_1| + \text{Sup}|(1-\lambda)\mu_2| \leq \lambda \ell + (1-\lambda)\ell = \ell \text{ in } \Omega \end{aligned}$$

Thus  $\Lambda_\ell$  is a convex set in  $\Omega$ . And  $\Lambda_\ell$  is compact in the dual weak topology of  $L^\infty(\Omega)$ .

Since  $K_\ell$  is a closed bounded set in the Hilbert space  $H^1(\Omega)$ ,  $K_\ell$  is weakly compact. We consider  $H^1(\Omega)$  with its weak topology.

Now  $H^1(\Omega) = V$  with the weak topology is a Hausdorff topological vector space.

All the hypothesis of the theorem of Ky Fan and Sion are satisfied by  $K_\ell, \Lambda_\ell$  and  $\mathcal{L}$  in view of (i) and (ii). Hence

$$\mathcal{L}: K_\ell \times \Lambda_\ell \rightarrow \mathbb{R}$$

has a saddle point  $(u_\ell, \lambda_\ell)$ , i.e., there exist  $(u_\ell, \lambda_\ell) \in K_\ell \times \Lambda_\ell$  such that

$$(II) \begin{cases} J(u_\ell) + \langle \mu, u_\ell \rangle_{L^\infty(\Omega) \times L^1(\Omega)} \leq J(u_\ell) + \langle \lambda_\ell, u_\ell \rangle_{L^\infty(\Omega) \times L^1(\Omega)} \\ \leq J(v) + \langle \lambda_\ell, v \rangle_{L^\infty(\Omega) \times L^1(\Omega)}, \quad \forall (v, \mu) \in K_\ell \times \Lambda_\ell. \end{cases}$$

We shall show that if we choose  $\ell > 0$  sufficiently large then such a saddle point can be obtained independent of  $\ell$ .

For this we shall first prove  $\|u_\ell\|_{H^1(\Omega)}$  and  $\lambda_\ell$  are bounded by constants independent of  $\ell$ .

If we take  $\mu = 0 \in \Lambda_\ell$  in (II) we get

$$J(u_\ell) \leq J(v) + \langle \lambda_\ell, v \rangle_{L^\infty(\Omega); L^1(\Omega)}, \quad \forall v \in K_\ell \tag{3}$$

taking  $v = 0 \in K_\ell \cap K$  such that

$$1 - \text{grad}^2 v(x) \geq 0 \quad \text{a.e. in } \Omega$$

we get

$$J(u_\ell) \leq J(0) \quad \text{for } 1 - \text{grad}^2 v(x) \geq 0 \quad \text{a.e. in } \Omega.$$

On the other hand, since  $a(u_\ell, u_\ell) \geq 0$  and since  $u_\ell \in K_\ell$

$$L(u_\ell) \leq \|L\|_v \cdot \left\| 1 - \text{grad}^2 v(x) \right\|_{L^1(\Omega)} \leq \ell \|L\|_v \quad \text{a.e. in } \Omega$$

and hence

$$J(u_\ell) = \frac{1}{2} a(u_\ell, u_\ell) - L(u_\ell) \geq -\ell \|L\|_v \quad \text{a.e. in } \Omega$$

Thus we have

$$-\ell \|L\|_v \leq J(u_\ell) \leq J(0) \quad \text{a.e. in } \Omega \tag{4}$$

Now by coercivity of  $a(\cdot, \cdot)$  and (4) we find

$$\alpha \| \| u_\ell \| \|^2 \leq a(u_\ell, u_\ell) = 2(J(u_\ell) + L(u_\ell)) \leq 2(J(0) + \|L\|_v \cdot \| \| u_\ell \| \|) \quad \text{a.e. in } \Omega$$

with a constant  $\alpha > 0$  ( independent of  $\ell$  ) and  $\| \| \cdot \| \|$  defined the norm  $\| \cdot \|_{H^1(\Omega)}$ .

By using the inequality

$$\|L\|_v \cdot \| \| u_\ell \| \| \leq \varepsilon \| \| u_\ell \| \|^2 + \frac{1}{\varepsilon} \|L\|_v^2 \quad \text{for any } \varepsilon > 0$$

with  $\varepsilon = \alpha / 4 > 0$ , we obtain

$$\alpha \| \| u_\ell \| \| \leq 2J(0) + \frac{\alpha}{2} \| \| u_\ell \| \|^2 + \frac{8}{\alpha} \|L\|_v^2.$$

Therefore,

$$\| \| u_\ell \| \|^2 \leq \frac{4}{\alpha} (J(0) + \|L\|_v^2).$$

This proves that there exists a constant  $C_1 > 0$  such that

$$\| \| u_\ell \| \|^2 \leq C_1 \quad \forall \ell, \quad \text{a.e. in } \Omega. \tag{5}$$

We observe that since  $J$  satisfies all assumptions of Theorem (3), there will exist a unique global minimum in  $V = H^1(\Omega)$  i.e., there exists a unique  $\tilde{u} \in H^1(\Omega)$  such that

$$J(\tilde{u}) \leq J(v), \quad \forall v \in V \tag{6}$$

But, if we take  $v = 1 \in K_\ell$  in the inequality (3) we get

$$J(u_\ell) + \sup \lambda_\ell \leq J(1).$$

The last two inequalities imply that

$$C_2 = -J(\tilde{u}) + J(1) \geq \sup \lambda_\ell \geq 0 \tag{7}$$

which proves that  $\lambda_\ell$  is also bounded,  $\ell$  may be taken as follows

$$\ell > \max(C_1, 2C_2) > 0 \tag{8}$$

Next we show that (II) holds for any  $\mu \in \Lambda$ . For this we write the first inequality of (II) in the form

$$\langle \mu, u_\ell \rangle_{L^\infty(\Omega) \times L^1(\Omega)} \leq \langle \lambda_\ell, u_\ell \rangle_{L^\infty(\Omega) \times L^1(\Omega)},$$

which implies that

i) taking  $\mu = 0$  we have  $\langle \lambda_\ell, u_\ell \rangle_{L^\infty(\Omega) \times L^1(\Omega)} \geq 0$ , and

ii) taking  $\mu = 2\lambda_\ell \leq 2C_2 < \ell$  we have  $\langle \lambda_\ell, u_\ell \rangle_{L^\infty(\Omega) \times L^1(\Omega)} \leq 0$ .

Thus

$$\langle \lambda_\ell, u_\ell \rangle_{L^\infty(\Omega) \times L^1(\Omega)} = 0 \quad \text{and} \quad \langle \mu, u_\ell \rangle_{L^\infty(\Omega) \times L^1(\Omega)} \leq 0, \quad \forall \mu \in \Lambda_\ell$$

In particular,  $\mu = \ell \in \Lambda_\ell$  and so  $\langle \ell, u_\ell \rangle_{L^\infty(\Omega) \times L^1(\Omega)} \leq 0$  which means that

$$\langle \mu, u_\ell \rangle_{L^\infty(\Omega) \times L^1(\Omega)} \leq 0 \quad \text{for any } \mu \geq 0,$$

and therefore

$$\mathcal{L}(u_\ell, \mu) \leq \mathcal{L}(u_\ell, \lambda_\ell) \leq \mathcal{L}(v, \lambda_\ell) \quad \forall \mu \geq 0 \quad \text{and } v \in K_\ell \tag{9}$$

where  $\ell > \max(C_1, 2C_2)$ .

We have now only to show that the inequality (9) holds for any  $v \in H^1(\Omega) = V$ .

For this, we note that  $\| \| u_\ell \| \|^2 \leq C_1 < \ell$  a.e. in  $\Omega$ , and hence we can find an  $r > 0$  such that the ball

$$B(u_\ell, r) = \{v; v \in H^1(\Omega): 1 - \text{grad}^2(v(x) - u_\ell(x)) < r \text{ a.e. in } \Omega\}$$

is contained in the ball

$$B(u_\ell, r) = \{v; v \in H^1(\Omega): 1 - \text{grad}^2 v(x) < \ell \text{ a.e. in } \Omega\}$$

In fact, it is enough to take  $0 < r < (\ell - C_1)/2$ . Now the functional

$$\begin{aligned} \mathcal{L}(\cdot, \lambda_\ell): v &\rightarrow \mathcal{L}(v, \lambda_\ell) \\ \mathcal{L}(v, \lambda_\ell) &= J(v) + \langle \lambda_\ell, v \rangle_{L^\infty(\Omega) \times L^1(\Omega)} \end{aligned}$$

has a local minimum in  $B(u_\ell, r)$ . But since this functional is convex such a minimum is also a global minimum. This means that

$$\inf_{v \in B(u_\ell, r)} \mathcal{L}(v, \lambda_\ell) = \inf_{v \in V} \mathcal{L}(v, \lambda_\ell).$$

On the other hand, since  $B(u_\ell, r) \subset K_\ell$ , we see from (9) that

$$\mathcal{L}(u_\ell, \mu) \leq \mathcal{L}(u_\ell, \lambda_\ell) \leq \inf_{v \in K_\ell} \mathcal{L}(v, \lambda_\ell) \leq \inf_{v \in B(u_\ell, r)} \mathcal{L}(v, \lambda_\ell) = \inf_{v \in V} \mathcal{L}(v, \lambda_\ell).$$

In other words, we have

$$\mathcal{L}(u_\ell, \mu) \leq \mathcal{L}(u_\ell, \lambda_\ell) \leq \mathcal{L}(v, \lambda_\ell), \quad \forall v \in V, \quad \text{and } \forall \mu \geq 0,$$

which means that  $\mathcal{L}$  has a saddle point.

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