

SOME SUBMERSIONS OF CR-HYPERSURFACES OF KAEHLER-EINSTEIN MANIFOLD

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The Riemannian submersions of a CR-hypersurface M of a Kaehler-Einstein manifold \tilde{M} are studied. If M is an extrinsic CR-hypersurface of \tilde{M} , then it is shown that the base space of the submersion is also a Kaehler-Einstein manifold.

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1. Introduction. The study of the Riemannian submersions $\pi : M \rightarrow B$ was initiated by O'Neill [14] and Gray [9]. This theory was very much developed in the last thirty five years. Besse's book [3, Chapter 9] is a reference work. Bejancu introduced a remarkable class of submanifolds of a Kaehler manifold that are known as CR-submanifolds (see [1, 2]). On a CR-submanifold, there are two complementary distributions D and D^\perp , such that D is J -invariant and D^\perp is J -anti-invariant with respect to the complex structure J of the Kaehler manifold. The integrability of the anti-invariant distribution D was proved by Blair and Chen [4].

Recently, Kobayashi [10] considered the similarity between the total space of a Riemannian submersion and a CR-submanifold of a Kaehler manifold in terms of the distribution. He studied the case of a generic CR-submanifolds in a Kaehler manifold and proved that the base space is a Kaehler manifold.

In Section 3, we extend the result of Kobayashi to the general case of a CR-submanifold.

In Section 4, we study a Riemannian submersion from an extrinsic hypersurface M of a Kaehler-Einstein manifold \tilde{M} onto an almost-Hermitian manifold B . In this case, we prove that the basic manifold is a Kaehler-Einstein manifold. If \tilde{M} is C^{n+1} , a standard example is the Hopf fibration $S^{2n+1} \rightarrow CP^n$ equipped with the canonical metrics.

For the basic formulas of Riemannian geometry, we use [11, 12].

2. Preliminaries. Let \tilde{M} be a complex m -dimensional Kaehler manifold with complex structure J and Hermitian metric $\langle \cdot, \cdot \rangle$. Bejancu [2] introduced the concept of a CR-submanifold of \tilde{M} as follows: a real Riemannian manifold M , isometrically immersed in a Kaehler manifold \tilde{M} , is called a CR-submanifold of \tilde{M} if there exists on M a differentiable holomorphic distribution D and its

orthogonal complement D^\perp on M is a totally real distribution, that is, $JD_x^\perp \subseteq T_x^\perp M$, where $T_x^\perp M$ is the normal space to M at $x \in M$ for any $x \in M$. It is easily seen that each real orientable hypersurface of M is a CR-submanifold. The Riemannian metric induced on M will be denoted by the same symbol $\langle \cdot, \cdot \rangle$.

Let $\tilde{\nabla}$ (resp., ∇) be the operator of covariant differentiation with respect to the Levi-Civita connection on \tilde{M} (resp., M). The second-fundamental form B is given by

$$B(E, F) = \tilde{\nabla}_E F - \nabla_E F \tag{2.1}$$

for all $E, F \in \Gamma(TM)$, where $\Gamma(TM)$ is the space of differentiable vector field on M . We denote everywhere by $\Gamma(\tau)$ the space of differentiable sections of a vector bundle τ .

For a normal vector field N , that is, $N \in \Gamma(T^\perp M)$, we write

$$\tilde{\nabla}_E N = -L_N E + \nabla_E^\perp N, \tag{2.2}$$

where $-L_N E$ (resp., $\nabla_E^\perp N$) denotes the tangential (resp., normal) component of $\tilde{\nabla}_E N$.

Let μ be the orthogonal complementary vector bundle of $J(D^\perp)$ in $T^\perp M$, that is, $T^\perp M = J(D^\perp) \oplus \mu$.

It is clear that μ is a holomorphic subbundle of $T^\perp M$, that is, $J\mu = \mu$.

DEFINITION 2.1 (Kobayashi [10]). Let M be a CR-submanifold of a Kaehler manifold \tilde{M} . A submersion from a CR-manifold M onto an almost-Hermitian manifold is a Riemannian submersion $\pi : M \rightarrow M'$ with the following conditions:

- (i) D^\perp is the kernel of π_* ,
- (ii) $\pi_* : D_x \rightarrow T_{\pi(x)} M'$ is a complex isometry for every $x \in M$.

This definition is given by Kobayashi for the case where μ is a null subbundle of $T^\perp M$ (see [10]). If $JD_x^\perp = T_x^\perp M$ for any $x \in M$, we say that M is a *generic CR-submanifold* of \tilde{M} (Yano and Kon [15]). For example, any real orientable hypersurface of \tilde{M} is a generic CR-submanifold of \tilde{M} .

Concerning the basic notions on the Riemannian submersions, see O'Neill [14] and Gray [9].

The vertical distribution of a Riemannian submersion is an integrable distribution. In our case, the distribution vertical is D^\perp , which is integrable according to a theorem by Blair and Chen [4].

The sections of D^\perp (resp., D) are called the *vertical vector fields* (resp., the *horizontal vector fields*) of the Riemannian submersion $\pi : M \rightarrow M'$. The letters U, V, W , and W' will always denote vertical vector fields, and the letters X, Y, Z , and Z' denote horizontal vector fields. For any $E \in \mathcal{X}(M)$, vE and hE denote the vertical and horizontal components of E , respectively. A horizontal vector field X on M is said to be basic if X is π -related to a vector field X' on M' .

It is easy to see that every vector field X' on M' has a unique horizontal lift X to M , and X is basic.

Conversely, let X be a horizontal vector field and suppose that $\langle X, Y \rangle_x = \langle X, Y \rangle_y$ for all Y basic vector fields on M , for all $x, y \in \pi^{-1}(x')$, and for all $x' \in M'$. Then, the vector field X is basic. We have the following O'Neill's lemma (see [8, 14]).

LEMMA 2.2. *Let X and Y be basic vector fields on M . Then, they are satisfying the following:*

- (i) *the horizontal component $h[X, Y]$ of $[X, Y]$ is a basic vector field and $\pi_* h[X, Y] = [X', Y'] \circ \pi$,*
- (ii) *$h(\nabla_X Y)$ is a basic vector field corresponding to $\nabla'_{X'} Y'$, where ∇' is the Levi-Civita connection on $(M', \langle \cdot, \cdot \rangle')$,*
- (iii) *$[X, U] \in \Gamma(D^\perp)$ for any vertical field $U \in \Gamma(D^\perp)$.*

We recall that a Riemannian submersion $\pi : (M, g) \rightarrow (M', g')$ determines the fundamental tensor field T and A by the formulas

$$\begin{aligned} T_E F &= h \nabla_{v_E} v F + v \nabla_{v_E} h F, \\ A_E F &= v \nabla_{h_E} h F + h \nabla_{h_E} v F, \end{aligned} \tag{2.3}$$

for all $E, F \in \Gamma(TM)$ (cf. O'Neill [14] and Besse [3]).

It is easy to prove that T and A satisfy

$$T_U V = T_v U, \tag{2.4}$$

$$A_X Y = \frac{1}{2} v [X, Y], \tag{2.5}$$

for any $U, V \in \Gamma(D^\perp)$ and $X, Y \in \Gamma(D)$.

Formula (2.4) means that the restriction of T to the integrable distribution D^\perp is the second-fundamental form of the fiber submanifolds in M , and (2.5) measures the integrability of the distribution D .

We have the following properties:

$$\begin{aligned} \nabla_U X &= T_U X + h \nabla_U X, \\ \nabla_X U &= v \nabla_X U + A_X U, \\ \nabla_X Y &= h \nabla_X Y + A_X Y, \end{aligned} \tag{2.6}$$

for any $X, Y \in \Gamma(\mathcal{H})$ and $U \in \Gamma(\mathcal{V})$.

3. Kaehler structure on the basic space M' . From (2.1), we have

$$\tilde{\nabla}_X Y = h \nabla_X Y + v \nabla_X Y + \bar{h} B(X, Y) + \bar{v} B(X, Y) \tag{3.1}$$

for any $X, Y \in \Gamma(D)$.

Here, we denote by h and v (resp., \bar{h} and \bar{v}) the canonical projections on D and D^\perp (resp., μ and JD^\perp). Define a tensor field C on M as the vertical component $v(\nabla_X Y)$ of $\nabla_X Y$ (cf. Kobayashi [10]). The tensor field C is known to be a skew-symmetric tensor field defined by Kobayashi such that

$$C(X, Y) = \frac{1}{2}v[X, Y] \tag{3.2}$$

for all $X, Y \in \Gamma(D)$.

Note that the tensor field C is the restriction of A to $\Gamma(\mathcal{H}) \times \Gamma(\mathcal{H})$.

From Definition 2.1 and Lemma 2.2, we obtain that $Jh\nabla_X Y$ (resp., $h\nabla_X JY$) is a basic vector field and corresponds to $J'\nabla'_{X'} Y'$ (resp., $\nabla'_{X'} J'Y'$) for any basic vector fields X and Y on M .

On the Kaehler manifold \tilde{M} , we have

$$\tilde{\nabla}_E JF = J\tilde{\nabla}_E F. \tag{3.3}$$

From (3.1) and (3.3), we obtain the following proposition.

PROPOSITION 3.1. For any basic vector fields X and Y on M ,

$$Jh\nabla_X Y = h\nabla_X JY, \tag{3.4}$$

$$JC(X, Y) = \bar{v}B(X, JY), \tag{3.5}$$

$$C(X, JY) = J\bar{v}B(X, Y), \tag{3.6}$$

$$J\bar{h}B(X, Y) = \bar{h}B(X, JY). \tag{3.7}$$

THEOREM 3.2. Let M be a CR-submanifold of a Kaehler manifold \tilde{M} and $\pi : M \rightarrow M'$ be a CR-submersion of M on an almost-Hermitian manifold M' . Then, M' is a Kaehler manifold.

PROOF. From Lemma 2.2 and (3.4), we obtain that $\nabla'_{X'} J'Y' = J'\nabla'_{X'} Y'$, so that M' is a Kaehler manifold. □

REMARK 3.3. Proposition 3.1 is proved for generic CR-submanifolds of \tilde{M} (i.e., $\mu = 0$) in [10].

4. Riemannian submersions from extrinsic hyperspheres of Einstein-Kaehler manifolds. We recall that a totally umbilical submanifold M of a Riemannian manifold \tilde{M} is a submanifold whose first-fundamental form and second-fundamental form are proportional.

The extrinsic hyperspheres are defined to be totally umbilical hypersurfaces, having nonzero parallel mean-curvature vector field (cf. Nomizu and Yano [13]). Many of the basic results concerning extrinsic spheres in Riemannian and Kaehlerian geometry were obtained by Chen [5, 6, 7].

Let M be an orientable hypersurface in a Kaehler manifold \tilde{M} . Then, M is an extrinsic hypersphere of \tilde{M} if it satisfies

$$B(E, F) = \langle E, F \rangle H \tag{4.1}$$

for any vector fields E and F on M . Here, H denote the mean-curvature vector field of M . If we put $k = \|H\|$ (where the norm $\|\cdot\|$ is, with respect to a scalar product, induced on every tangent space to M), then k is a nonzero constant function on the extrinsic hypersphere M .

We denote by N the global unit normal vector field to M . Then, $\xi = -JN$ is a global unit vector on M such that $N = J\xi$. Let D be the maximal J -invariant subspace (with respect to J) of the tangent space T_pM for every $p \in M$. We see that M is a CR-hypersurface of \tilde{M} such that $TM = D \oplus D^\perp$, where D^\perp is the one-dimensional anti-invariant distribution generated by the vector field ξ on M .

The anti-invariant distribution D^\perp is integrable, and its leaves are totally geodesic in M (but not in \tilde{M}).

This is an easy consequence from Gauss and Weingarten's formulas of the leaves of D^\perp in M . This means that O'Neill's tensor T vanishes on the fibres of the Riemannian submersion $\pi : M \rightarrow B$.

The main result of this section is the following theorem.

THEOREM 4.1. *Let M be an orientable extrinsic hypersphere of an Kaehler-Einstein manifold \tilde{M} . If $\pi : M \rightarrow B$ is a CR-submersion of M on an almost-Hermitian manifold B , then B is an Kaehler-Einstein manifold.*

To prove [Theorem 4.1](#), we need several lemmas.

LEMMA 4.2. *Following the assumptions of [Theorem 4.1](#), then*

$$\langle A_x \xi, A_y \xi \rangle = k^2 \langle X, Y \rangle \tag{4.2}$$

for any horizontal vector X on M .

PROOF. From Gauss's formula [\(2.1\)](#) and the umbilicity of M , we get $\tilde{\nabla}_X \xi = \nabla_X \xi$ for any vector field X on M . Then, we have

$$\langle \tilde{\nabla}_X JN, Y \rangle = \langle \nabla_X \xi, Y \rangle = \langle h \nabla_X \xi, Y \rangle = \langle A_X \xi, Y \rangle. \tag{4.3}$$

On the other hand, \tilde{M} is a Kaehler manifold, so that ∇ commute with J :

$$\begin{aligned} \langle \tilde{\nabla}_X JN, Y \rangle &= \langle J \tilde{\nabla}_X N, Y \rangle = -\langle \tilde{\nabla}_X N, JY \rangle = \langle B(X, JY), N \rangle \\ &= \langle G(X, JY)H, N \rangle = k \langle X, JY \rangle. \end{aligned} \tag{4.4}$$

Consequently,

$$\langle A_X \xi, A_Y \xi \rangle = k \langle X, J A_Y \xi \rangle = -k \langle J X, A_Y \xi \rangle = k^2 \langle X, Y \rangle. \quad (4.5)$$

□

LEMMA 4.3. *Following the assumptions of [Theorem 4.1](#), then*

$$\langle A_X Y, A_Z W \rangle = k^2 \langle X, J Y \rangle \langle Z, J W \rangle \quad (4.6)$$

for any horizontal vector fields on M .

PROOF. We say that $A_X Y$ is a vertical vector field, hence

$$A_X Y = \langle A_X Y, \xi \rangle \xi. \quad (4.7)$$

Then,

$$\langle A_X Y, A_Z W \rangle = \langle A_X Y, \xi \rangle \langle A_Z W, \xi \rangle = k^2 \langle X, J Y \rangle \langle Z, J W \rangle. \quad (4.8)$$

□

LEMMA 4.4. *Following the assumptions of [Theorem 4.1](#), then*

$$\tilde{R}(X, Y, Z, W) = R(X, Y, Z, W) + k^2 \{ \langle X, Z \rangle \langle Y, W \rangle - \langle X, W \rangle \langle Y, Z \rangle \}, \quad (4.9)$$

where \tilde{R} and R are the curvature tensor on \tilde{M} and M , respectively.

PROOF. We have the Gauss equation

$$\begin{aligned} \tilde{R}(X, Y, Z, W) &= R(X, Y, Z, W) + \langle B(X, Z), B(Y, W) \rangle \\ &\quad - \langle B(Y, Z), B(X, W) \rangle. \end{aligned} \quad (4.10)$$

Using the umbilicity condition, we get [\(4.9\)](#). □

LEMMA 4.5. *For any horizontal vector fields X and Y on M ,*

$$\tilde{R}(\xi, X, Y, \xi) = 0, \quad \tilde{R}(\xi, J X, J Y, \xi) = 0. \quad (4.11)$$

PROOF. For a Riemannian submersion with totally geodesic fibres, the following formula is known:

$$\tilde{R}(X, V, Y, U) = \langle (\nabla_V A)(X, Y), U \rangle + \langle A_X V, A_Y U \rangle. \quad (4.12)$$

On the other hand, the first term on the right part is skew-symmetric with respect to the vertical vector fields V and U . From [\(4.12\)](#) and [\(4.9\)](#), we obtain [\(4.11\)](#). □

PROOF OF THEOREM 4.1. For the horizontal vector fields $X, Y, Z,$ and W on $M,$ we have the following equation of O'Neill:

$$R(X, Y, Z, W) = R'(X', Y' \cdot Z', W') - 2\langle A_X Y, A_Z W \rangle + \langle A_Y Z, A_X W \rangle - \langle A_X Z, A_Y W \rangle \tag{4.13}$$

(see [3, 14]).

By (4.9) and (4.11), we get the following formula that connects the curvature of M' to the curvature of the Kaehler manifold \tilde{M} :

$$\begin{aligned} \tilde{R}(X, Y, Z, W) &= R'(X', Y', Z', W') \\ &\quad - k^2 \{ \langle X, JZ \rangle \langle Y, JW \rangle - \langle X, JW \rangle \langle Y, JZ \rangle \\ &\quad \quad + 2 \langle X, JY \rangle \langle Z, JW \rangle \} \\ &\quad - k^2 \{ \langle X, Z \rangle \langle Y, W \rangle - \langle X, W \rangle \langle Y, Z \rangle \}. \end{aligned} \tag{4.14}$$

Let $(e_1, \dots, e_p; J e_1, \dots, J e_p)$ be a local J -frame of basic vector fields for the horizontal distribution $D.$ Then, $(e_1, \dots, e'_p; J' e_1, \dots, J' e_p)$ is a local J' -frame if $\pi_{\text{star}} e_i = e'_i$ on the Kaehler manifold $B.$

Using the above lemmas, from (4.14) by a straightforward calculation, we conclude that B is a Kaehler-Einstein manifold if \tilde{M} is a Kaehler-Einstein manifold.

□

COROLLARY 4.6. Let \tilde{M} be a complex-form space and M an orientable CR-hypersurface of $\tilde{M}.$ Then, the base space of submersion $\pi : M \rightarrow B$ is also a complex-form space.

PROOF. The corollary follows by straightforward calculation making use of (4.14). □

EXAMPLE 4.7. Let S^{2n+1} be the standard hypersphere in $C^{n+1}.$ Then, S^{2n+1} is an extrinsic hypersphere in $C^{n+1},$ and we have the Hopf fibration $\pi : S^{2n+1} \rightarrow CP^n$ equipped with the canonical metrics.

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