Internat. J. Math. & Math. Sci. Vol. 4 No. 1 (1981) 137-146

## OSCILLATION IN SECOND ORDER FUNCTIONAL EQUATIONS WITH DEVIATING ARGUMENTS

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(Received October 16, 1979)

ABSTRACT. For the pair of functional equations

(A) (r(t)y'(t))' + p(t)h(h(g(t))) = f(t)

and

(B) (r(t)y'(t))' - p(t)h(y(g(t))) = 0

sufficient conditions have been found to cause all solutions of equation (A) to be oscillatory. These conditions depend upon a positive solution of equation (B). KEY WORDS AND PHRASES: Oscillatory, Nonoscillatory, Sublinear, Superlinear

## 1980 MATHEMATICS SUBJECT CLASSIFICATION CODES:

#### 1. INTRODUCTION.

Our main goal, in this work, is to seek the oscillatory behavior of the equation

$$(r(t)y'(t))' + p(t)h(y(g(t))) = f(t)$$
, (1.1)

via the nonoscillation of the equation

$$(r(t)y'(t))' - p(t)h(y(g(t))) = 0.$$
 (1.2)

Oscillation properties of equation (1.1) were studied by Kartsatos [3] and Kusano and Onose [4] by first "homogenizing" it and then using the techniques known for homogeneous equations. In fact a function  $\lambda(t)$  was sought to satisfy

$$(r(t)(y(t) - \lambda(t))' = f(t).$$
 (1.3)

A similar approach was later used by this author [9] in finding conditions for the oscillation of the equation

$$(r(t)y'(t))^{(n-1)} + (-1)^{n+1}p(t)y(g(t)) = f(t).$$
(1.4)

Recently Rankin [8] presented a new approach to study the oscillatory behavior of the ordinary differential equation

$$y''(t) + p(t)y(t) = f(t),$$
 (1.5)

by using the transformation

$$y(t) = \phi(t)z(t)$$
, (1.6)

where  $\phi(t)$  is a positive solution of the equation

$$y''(t) + p(t)y(t) = 0.$$
 (1.7)

Transformations usually do not carry over to functional equations (1.1) and (1.2). The failure in study of equation (1.1) leads us to this work in which we present a different approach to study the oscillation of equation (1.1) which may be sublinear, superlinear, retarded or advanced.

Since our results do not depend on the integral size of p(t), they are different from those of Kartsatos [3], Kusano and Onose [4] and this author [9]. Our results are also different than those of Rankin [8]. In fact the following example shows that Rankin's results are not true for the pair of retarded equations

$$y''(t) + \frac{3}{16t^{2}(t-\pi)^{3/4}}y(t-\pi) = -100t \sin 10t + 20 \cos 10t + \frac{3}{8}\frac{(t-\pi)^{1/4}}{t^{2}} + \frac{3(t-\pi)^{1/4}}{16t^{2}} \sin 10t, \quad (1.8)$$

and

$$y''(t) + \frac{3}{16t^2(t-\pi)^{3/4}}y(t-\pi) = 0.$$
 (1.9)

Equation (1.9) has the nonoscillatory solution  $\phi(t) = t^{3/4}$  which satisfies the conclusion of Rankin's main theorem ([8, Theorem 2]) namely

$$\liminf_{t \to \infty} \int_{T}^{t} \frac{1}{\phi^{2}(x)} \int_{T}^{x} \phi(s) f(s) ds dx = -\infty, \qquad (1.10)$$

$$\limsup_{t \to \infty} \int_{T}^{t} \frac{1}{\phi^{2}(x)} \int_{T}^{x} \phi(s) f(s) ds dx = \infty, \qquad (1.11)$$

and

$$\int_{T}^{\infty} \frac{1}{\phi^{2}(\mathbf{x})} d\mathbf{x} < \infty,$$

for any large T > 0; where  $f(t) = -100t \sin(10t) + 20\cos(10t) + \frac{3(t-\pi)^{1/4}}{8t^2} + \frac{3(t-\pi)^{1/4}}{16t^2}\sin(10t).$ 

But equation (1.8) has the nonoscillatory solution

y(t) = 2t + t sin(10t).

#### 2. DEFINITIONS AND ASSUMPTIONS

Throughout this study we assume the following:

- (i) g(t), r(t), p(t), h(t) and f(t) are C[R,R] where R denotes the real line;
- (ii) r(t)>0, r'(t)<0 and p(t)>0 for t>t<sub>0</sub>>0 where we shall assume t<sub>0</sub>
  to be fixed arbitrarily. t<sub>0</sub> will be referred to in this study
  without any further mention;

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(iii) g(t) \rightarrow \infty as t \rightarrow \infty;
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(iv) sign h(t) = sign t.

The term "solution" refers to nontrivial continuously extendable solutions of equations under consideration over the interval  $[t_0,\infty)$ . We call a function  $Q(t) \in C [[t_0,\infty), R]$  oscillatory if Q(t) has arbitrarily large zeros on  $[t_0,\infty)$ ; otherwise Q(t) is called nonoscillatory. Equations (1.1) and (1.2) are called sublinear or superlinear

$$0 < \frac{h(t)}{t^{\alpha}} \leq k$$

if  $0 < \alpha \leq 1$  or  $\alpha < 1$  respectively where k is constant and  $\alpha$  is the ratio of odd integers.

### 3. MAIN RESULTS

THEOREM 1: In addition to (i)-(iv) suppose there exists a function  $\phi(t)$ which is continuous for  $t \ge t_0$  and satisfies  $(r(t)\phi'(t))' \ge o$  ( $\ddagger 0$  in any interval),

$$\liminf_{t\to\infty} \int_{-\infty}^{t} \frac{1}{\phi^2(s)} \int_{-\infty}^{s} \phi(x) f(x) dx ds = -\infty, \qquad (3.1)$$

$$\limsup_{t \to \infty} \int^{t} \frac{1}{\phi^{2}(s)} \int^{s} \phi(x) f(x) dx ds = \infty$$
(3.2)

and

$$\int_{0}^{\infty} \frac{1}{\phi^{2}(t)} dt < \infty .$$
(3.3)

Then all solutions of equation (1.1) are oscillatory.

PROOF: Suppose to the contrary that equation (1.1) has a nonoscillatory solution y(t). Without any loss of generality suppose  $T>t_0$  is large enough so that for t>T, y(g(t))>0 and y(t)>0. Rewriting equation (1.1) after multiplication with  $\phi(t)$  we have

$$(r(t)\phi(t)y'(t))' - (r(t)\phi'(t))y'(t) + p(t)\phi(t)h(y(g(t))) = \phi(t)f(t).$$
 (3.4)

140

# Integrating (3.4) for t $\geq$ T we have

$$r(t)\phi(t)y'(t) - r(T)\phi(T)y'(T) - r(t)\phi'(t)y(t) + r(T)\phi'(T)y(T) + \int_{T}^{t} (r(s)\phi'(s))'y(s) ds + \int_{T}^{t} p(s)\phi(s)h(y(g(s))) ds = \int_{T}^{t} \phi(s)f(s) ds.$$
(3.5)

Set

$$K = r(T)\phi'(T)y(T) - r(T)\phi(T)y'(T).$$
(3.6)

Dividing (3.5) by  $\phi^2(t)$  and rearranging terms we have

$$\frac{r(t)y'(t)}{\phi(t)} + \frac{K}{\phi^{2}(t)} - \frac{r(t)\phi'(t)y(t)}{\phi^{2}(t)} + \frac{1}{\phi^{2}(t)} \int_{T}^{t} (r(s)\phi'(s))'yds$$
  
+  $\frac{1}{\phi^{2}(t)} \int_{T}^{t} p(s)\phi(s)h(y(g(s)))ds = \frac{1}{\phi^{2}(t)} \int_{T}^{t}\phi(s)f(s)ds.$  (3.7)

Integrating (3.7) between T and t we have

$$\frac{r(t)y(t)}{\phi(t)} - \frac{r(T)y(T)}{\phi(T)} + \int_{T}^{t} \frac{r(s)\phi'(s)y(s)}{\phi^{2}(s)} ds - \int_{T}^{t} \frac{r'(s)y(s)}{\phi(s)} ds$$

$$+ \int_{T}^{t} K/\phi^{2}(s) ds - \int_{T}^{t} \frac{r(s)\phi'(s)y(s)}{\phi^{2}(s)} ds$$

$$+ \int_{T}^{t} \frac{1}{\phi^{2}(x)} \int_{T}^{x} [(r(s)\phi'(s))'y(s) + p(s)\phi(s)h(y(g(s)))] ds dx$$

$$= \int_{T}^{t} \frac{1}{\phi^{2}(x)} \int_{T}^{x} \phi(s) f(s) ds dx \qquad (3.8)$$

which leads to

$$\frac{r(t)y(t)}{\phi(t)} - \frac{r(T)y(T)}{\phi(T)} - \int_{T}^{t} \frac{r'(s)y(s)}{\phi(s)} ds$$

$$+ K \int_{T}^{t} \frac{1}{\phi^{2}(s) ds}$$

$$+ \int_{T}^{t} \frac{1}{\phi^{2}(x)} \int_{T}^{x} [(r(s)\phi'(s))'y(s) + p(s)\phi(s)h(y(g(s)))] ds dx$$

$$= \int_{T}^{t} \frac{1}{\phi^{2}(x)} \int_{T}^{x} \phi(s) f(s) ds dx. \qquad (3.9)$$

Since third, fourth and fifth terms on the left hand side of (3.9) are either nonnegative or finite, we immediately reach a contradiction in view of (3.1) and (3.2). The proof is complete.

COROLLARY 1. Suppose (i)-(iv) hold. Further suppose that equation a positive solution  $\phi(t)$  satisfying (3.1), (3.2) and (3.3). Then all solutions of equation (1.1) are oscillatory.

PROOF. Since  $(r(t)\,\varphi^{*}\,(t)\,)^{*}\geq 0$  , conclusion follows from Theorem 1. EXAMPLE 1. Consider the equations

$$y''(t) + e^{\pi}y(t-\pi) = 4e^{2t}cost + 3e^{2t}sint - e^{2t-\pi}sint$$
, (3.10)

and

$$y''(t) - e^{\pi}y(t-\pi) = 0$$
, (3.11)

for  $t > \pi$ . Equation (3.11) has  $y(t) = e^{t}$  as a solution which satisfies (3.1), (3.2) and (3.3). Thus all solutions of equation (3.10) are oscillatory. In fact  $y(t) = e^{2t}$ sint is one such solution.

REMARK. In Rankin's work  $\varphi ''(t) < 0$  where as here  $\varphi ''(t) > 0$  when  $r(t) \equiv 1.$ 

THEOREM 2. Suppose  $r(t) \equiv 1$  and (i)-(iv) hold. Further suppose that equation (1.2) has a positive solution  $\phi(t)$  such that  $\phi'(t) \geq 0$  ( $\ddagger 0$  in any subinterval) for  $t > t_0$ . Let (3.1) and (3.2) of Theorem (1) hold. Then all solutions of equation (1.1) are oscillatory. PROOF: Since

$$\phi''(t) > 0, \phi'(t) > 0$$
 and  $\phi(t) > 0$ , (3.12)

for  $t > t_0$ , there exist positive numbers  $c_1$  and  $c_2$  such that  $\phi(t) \ge c_1 t + c_2$ , and consequently  $\phi(t)$  satisfies (3.3). The proof is complete. We now have the following corollary.

COROLLARY 2: Suppose equation (1.2) has a positive nonoscillatory solution z(t) such that z'(t) > 0. Further suppose that equation (1.1) has a non-oscillatory solution. Then either

$$\liminf_{t\to\infty} \int^{t} \frac{1}{z^{2}(s)} \int^{s} z(x) f(x) dx ds > -\infty$$
(3.13)

or

$$\limsup_{t \to \infty} \int_{-\infty}^{\infty} \frac{1}{z^2(s)} \int_{-\infty}^{s} z(x) f(x) dx ds < \infty .$$
 (3.14)

EXAMPLE 2. The equation

$$y''(t) + \frac{2}{t^2}y(t) = -\sin t + \frac{4}{t^2} + \frac{2\sin t}{t^2}$$
 (3.15)

has the nonoscillatory solution  $y(t) = 2 + \sin t$ . Now consider

$$y''(t) - \frac{2}{t^2} y(t) = 0$$
, (3.16)

which has  $z(t) = t^2$  as a nonoscillatory solutions satisfying the conditions and conclusion of Corollary 2.

#### 4. ASYMPTOTIC NONOSCILLATION

Example 2 shows that when (3.1) and (3.2) are relaxed then equation (1.1) may have nonoscillatory solutions. In this section we give conditions when nonoscillatory solutions of (1.1) approach limits.

THEOREM 3: Suppose (i)-(iv) hold. Let  $\phi(t)$  be a positive solution of equation (1.2) such that  $\phi'(t) \ge 0$  ( $\ddagger 0$  in any subinterval of t for  $t > t_0$ ),

$$\lim_{t\to\infty} \inf \int^{t} \frac{1}{\phi^{2}(\mathbf{x})} \int^{\mathbf{x}} \phi(\mathbf{s}) f(\mathbf{s}) \, d\mathbf{s} d\mathbf{x} < 0 , \qquad (4.1)$$

and

$$\limsup_{t\to\infty}\int^{t} \frac{1}{\phi^{2}(x)} \int^{x} \phi(s) f(s) ds dx > 0.$$
(4.2)

Let y(t) be a bounded solution of equation (1.1). If y(t) is nonoscillatory then y(t) tends to a finite limit.

PROOF. Without any loss of generality, let  $T \ge t_0$  be large enough so that y(t) > 0 and y(g(t)) > 0 for t  $\ge T$ . Suppose to the contrary that

Then there exists a sequence  $\left\{ \mathtt{T}_{n}\right\} _{n=1}^{\infty}$  such that  $\mathtt{T}_{n}\rightarrow\infty$  as  $n\rightarrow\infty$  and n=1

 $y'(T_n) = 0$ . Let k be a large positive integer such that

$$\frac{y(T_k)r(T_k)}{\phi(T_k)} < Min \begin{bmatrix} -\liminf_{t \to \infty} \int_{T_k}^{t} \frac{1}{\phi^2(x)} & \int_{T_k}^{x} \phi(s)f(s) ds dx \\ & T_k \end{bmatrix}$$

$$\limsup_{t \to \infty} \int_{T_k}^{t} \frac{1}{\phi^2(x)} \int_{T_k}^{x} \phi(s) f(s) ds dx \qquad (4.4)$$

7

Following the proof of Theorem 1, we obtain from (3.9)

$$\frac{r(t)y(t)}{\phi(t)} - \int_{T_k}^t \frac{r'(s)y(s)ds}{\phi(s)} + r(T_k)\phi'(T_k)y(T_k) \int_{T_k}^t \frac{1}{\phi^2(x)} dx$$

+ 
$$\int_{T_{k}}^{t} \frac{1}{\phi^{2}(x)} \int_{T_{k}}^{x} p(s) (y(s)h(\phi(g(s))) + \phi(s)h(y(g(s)))) dsdx$$
  
=  $\int_{T_{k}}^{t} \frac{1}{\phi^{2}(x)} \int_{T_{k}}^{x} \phi(s)f(s) dsdx + \frac{y(T_{k})r(T_{k})}{\phi(T_{k})}$ . (4.5)

144

In view of (4.1), (4.2) and (4.4), we reach a contradiction in (4.5). The proof is complete.

REMARK. Example 2 shows that conditions (4.1) and (4.2) cannot be weakened.

COROLLARY 3. Suppose conditions of Theorem 3 hold. Let y(t) be any solution of equation (1.1) such that  $\frac{y(t)}{\phi(t)} \rightarrow 0$  as  $t \rightarrow \infty$ . If y(t) is nonoscillatory then y(t) tends to a finite or infinite limit as  $t \rightarrow \infty$ .

REMARK. Recently Graef and Spikes [1], Hammett [2], Kusano and Onose [5,6], Philos and Starkos [7], this author [10,11] have studied asymptotic nonoscillation with regard to equation (1.1). However all these results make use of an integral condition on p(t). Theorem 3 and Corollary 3 present a different approach.

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