

## ON DUAL INTEGRAL EQUATIONS WITH HANKEL KERNEL AND AN ARBITRARY WEIGHT FUNCTION

C. NASIM

Department of Mathematics and Statistics  
The University of Calgary  
Calgary, Alberta  
T2N 1N4 Canada

(Received July 3, 1985)

**ABSTRACT.** In this paper we deal with dual integral equations with an arbitrary weight function and Hankel kernels of distinct and general order. We propose an operational procedure, which depends on exploiting the properties of the Mellin transforms, and readily reduces the dual equations to a single equation. This then can be inverted by the Hankel inversion to give us an equation of Fredholm type, involving the unknown function. Most of the known results are then derived as special cases of our general result.

**KEY WORDS AND PHRASES.** Dual integral equation, Bessel functions of first kind, Mellin transforms, the Parseval theorem, Banach space  $L(k-i\infty, k+i\infty)$ , Hankel transforms, Hankel inversion, Fredholm equation.

**AMS CLASSIFICATION CODE.** 45F10, 45E10

### 1. INTRODUCTION.

We shall consider dual integral equations of the type

$$\int_0^{\infty} 2^{2\alpha} t^{-2\alpha} J_{\nu}(xt)[1+w(t)]\phi(t)dt = f(x), \quad 0 < x < 1 \quad (1.1)$$
$$\int_0^{\infty} 2^{2\beta} t^{-2\beta} J_{\mu}(xt)\phi(t)dt = g(x), \quad x > 1.$$

Such equations arise in the discussion of mixed boundary value problems. If  $w(t) = 0$ , then (1.1) become dual equation of Titchmarsh type, [1]. Different methods for solving dual integral equations have been proposed by various authors, notably, Tranter, [2], Lebedev and Uflyand [3], Noble [4] and Cook [5]. More recently, Erdelyi and Sneddon gave a solution using fractional integral operators [6]. Basically, all these methods, make use of some form of integral operator to reduce the system (1.1) to a single equation, which is then solved using standard techniques.

In this paper we use a different approach. We develop an operational procedure, which consists in exploiting the properties of the Mellin transforms. By this technique the dual equations are readily reduced to a single integral equation, which in turn can be solved using the usual Hankel inversion. A somewhat similar method has been used for solving ordinary dual integral equations by Williams [7], Tanno, [8] and Nasim and Sneddan [9].

2. KNOWN RESULTS.

First, we write down some definitions and results which are used later.

Lemma 1 [1 p.94]. Let  $x^{k-1}f(x) \in L(0, \infty)$  and  $F(s) \in L(k-i\infty, k+i\infty)$ , then

$$F(s) = \int_0^\infty f(x)x^{s-1}dx, \quad s = k + i\tau, \quad -\infty < \tau < \infty$$

and

$$f(x) = \frac{1}{2\pi i} \lim_{\tau \rightarrow \infty} \int_{k-i\tau}^{k+i\tau} F(s)x^{-s}ds.$$

$F$  is then the Mellin transform of  $f$  written as

$$\mathcal{M}[f(x);s] = F(s)$$

and  $f$  is the inverse Mellin transform of  $F$ , written as

$$\mathcal{M}^{-1}[F(s);x] = f(x).$$

Lemma 2 (The Parseval theorem) [1 p.60].

If  $x^{-k}g(x) \in L(0, \infty)$  and  $F(s) \in L(k-i\infty, k+i\infty)$ ,

then

$$\int_0^\infty f(xt)g(t)dt = \frac{1}{2\pi i} \int_{k-i\infty}^{k+i\infty} F(s)G(1-s)x^{-s}ds,$$

where  $F$  and  $G$  are the Mellin transforms of  $f$  and  $g$  respectively.

3. DUAL INTEGRAL EQUATIONS.

Now, we write the system (1.1) as

$$\int_0^\infty h_1(xt)\{1+w(t)\}\phi(t)dt = x^{-2\alpha}f(x), \quad 0 < x < 1 \tag{3.1a}$$

$$\int_0^\infty h_2(xt)\phi(t)dt = x^{-2\beta}g(x), \quad x > 1 \tag{3.1b}$$

where  $h_1(x) = 2^{2\alpha}x^{-2\alpha}J_\nu(x)$  and  $h_2(x) = 2^{2\beta}x^{-2\beta}J_\mu(x)$ . Then the Mellin transforms of  $h_1$  and  $h_2$  are respectively,

$$H_1(s) = 2^{s-1} \frac{\Gamma(\frac{1}{2}s + \frac{1}{2}\nu - \alpha)}{\Gamma(1 - \frac{1}{2}s + \frac{1}{2}\nu + \alpha)}, \quad 2\alpha - \nu < \text{Re}(s) < 2\alpha$$

and

$$H_2(s) = 2^{s-1} \frac{\Gamma(\frac{1}{2}s + \frac{1}{2}\mu - \beta)}{\Gamma(1 - \frac{1}{2}s + \frac{1}{2}\mu + \beta)}, \quad 2\beta - \mu < \text{Re}(s) < 2\beta,$$

both belonging to  $L(k-i\infty, k+i\infty)$ ,  $s = k+i\tau$ , [10]. The left hand sides of the equations (3.1a) and (3.1b) represent functions for all values of  $x$  and we shall denote these by  $f_1(x)$  and  $g_1(x)$ , having Mellin transform  $F_1(s)$  and  $G_1(s)$ , respectively.

Now we set  $F_1(s)$  and  $G_1(s)$  both  $\in L(k-i\infty, k+i\infty)$  and put appropriate conditions on the functions  $w(x)$  and  $\phi(x)$ . Then, due to lemma 2, the equations (3.1) give, respectively

$$H_1(s)\{\Phi(1-s) + \Psi(1-s)\} = F_1(s) \tag{3.2}$$

$$H_2(s)\Phi(1-s) = G_1(s)$$

a.e. on  $s = k + i\tau$ ,  $-\infty < \tau < \infty$ , where,

$$\mathcal{M}[\phi(x);s] = \Phi(s), \text{ and } \mathcal{M}[w(x)\phi(x);s] = \Psi(s).$$

Next, consider the functions

$$H_1^*(s) = \frac{\Gamma(1 - \frac{1}{2}s + \frac{1}{2}\nu + \alpha)}{\Gamma(1 - \frac{1}{2}s + \frac{1}{2}\mu + \beta)}, \text{ Re}(s) < 2+2\alpha+\nu$$

$$H_2^*(s) = \frac{\Gamma(\frac{1}{2}s + \frac{1}{2}\nu - \alpha)}{\Gamma(\frac{1}{2}s + \frac{1}{2}\mu - \beta)}, \text{ Re}(s) > 2\alpha + \nu.$$

Note that

$$H_1(s)H_1^*(s) = H_2(s)H_2^*(s) = \frac{2^{s-1}\Gamma(\frac{1}{2}s + \frac{1}{2}\nu - \alpha)}{\Gamma(1 - \frac{1}{2}s + \frac{1}{2}\mu + \beta)}$$

$$\equiv K(s), \text{ say.}$$

Then [10 p.326]

$$k(x) = \mathcal{M}^{-1}[K(s);x] = (2x)^{-\gamma} J_{\lambda}(x),$$

where  $\gamma = \frac{1}{2}\mu - \frac{1}{2}\nu + \alpha + \beta$  and  $\lambda = \frac{1}{2}\nu + \frac{1}{2}\mu - \alpha + \beta$ .

We now write equations (3.2) as

$$H_1(s)\Phi(1-s) = F_1(s) - H_1(s)\Psi(1-s)$$

$$H_2(s)\Phi(1-s) = G_1(s).$$

Multiply the above equations by the function  $H_1^*(s)$  and  $H_2^*(s)$  respectively and using the definition of  $K(s)$ , we obtain the following pair of functional equations,

$$K(s)\Phi(1-s) = H_1^*(s)\{F_1(s) - H_1(s)\Psi(1-s)\} \tag{3.3a}$$

$$K(s)\Phi(1-s) = H_2^*(s)G_1(s) \tag{3.3b}$$

a.e. on  $s = k + i\tau$ ,  $-\infty < \tau < \infty$ .

First we consider the equation (3.3a), whence, for  $x > 0$ ,

$$\frac{1}{2\pi i} \int_{k-i\infty}^{k+i\infty} K(s)\Phi(1-s)x^{-s}ds = \frac{1}{2\pi i} \int_{k-i\infty}^{k+i\infty} H_1^*(s)\{F_1(s) - H_1(s)\Psi(1-s)\}x^{-s}ds \tag{3.4}$$

Here  $K(s) \in L(k-i\infty, k+i\infty)$  if  $2\alpha - \nu < k < \frac{1}{2}\mu - \frac{1}{2}\nu + \alpha + \beta$  and if we let  $x^{-k}\phi(x) \in L(0, \infty)$ , then by applying Lemma 2, the left-hand side of (3.4) gives

$$\int_0^{\infty} k(xt)\phi(t)dt. \tag{3.5}$$

The right-hand side of (3.4) is

$$\frac{1}{2\pi i} \int_{k-i\infty}^{k+i\infty} \{F_1(s) - H_1(s)\Psi(1-s)\} \frac{\Gamma(1 - \frac{1}{2}s + \frac{1}{2}\nu + \alpha)}{\Gamma(1 - \frac{1}{2}s + \frac{1}{2}\mu + \beta)} x^{-s} ds$$

$$= \frac{1}{4\pi i} x^{1-2\alpha-\nu} \frac{d}{dx} \int_{k-i\infty}^{k+i\infty} \{F_1(s) - H_1(s)\Psi(1-s)\} \frac{\Gamma(\alpha - \frac{1}{2}s + \frac{1}{2}\nu)}{\Gamma(1 - \frac{1}{2}s + \frac{1}{2}\mu + \beta)} x^{\nu+2\alpha} s ds. \tag{3.6}$$

We define,

$$\begin{aligned} \mathcal{M}^{-1}\{F_1(s) - H_1(s)\Psi(1-s); x\} &= \mathcal{M}^{-1}\{F_1(s); x\} - \mathcal{M}^{-1}\{H_1(s)\Psi(1-s); x\} \\ &= f_1(x) - q(x), \end{aligned}$$

where

$$\begin{aligned} q(x) &= \frac{1}{2\pi i} \int_{k-i\infty}^{k+i\infty} H_1(s)\Psi(1-s)x^{-s} ds \\ &= \int_0^\infty h_1(xu)\omega(u)\phi(u) du \end{aligned} \tag{3.7}$$

Here  $H_1(s) \in L(k-i\infty, k+i\infty)$  if  $2\alpha - \nu < k < 2\alpha$  and if we let  $x^{-k}\omega(x)\phi(x) \in L(0, \infty)$ , the result then follows from lemma 2 above. The function  $\frac{\Gamma(\alpha - \frac{1}{2}s + \frac{1}{2}\nu)}{\Gamma(1 - \frac{1}{2}s + \frac{1}{2}\mu + \beta)} \in L(k-i\infty, k+i\infty)$  if  $k < 2\alpha + \nu$  and  $\alpha - \beta < \frac{1}{2}\mu - \frac{1}{2}\nu$ ; and if we assume that  $x^{-k}f_1(x)$  and  $x^{-k}q(x)$  both belong to  $L(0, \infty)$ , then by applying Lemma 2 on the  $s$ -integral, the expression (3.6) yields

$$\frac{1}{2}x^{1-2\alpha-\nu} \frac{d}{dx} \left[ x^{2\alpha+\nu} \int_0^x [f_1(t) - q(t)] \frac{1}{t} h_1^*\left(\frac{x}{t}\right) dt \right], \quad 0 < x < 1,$$

where,

$$\mathcal{M}^{-1}\left[\frac{\Gamma(\alpha - \frac{1}{2}s + \frac{1}{2}\nu)}{\Gamma(1 - \frac{1}{2}s + \frac{1}{2}\mu + \beta)}; x\right] = h_1^*(x) = \begin{cases} \frac{2}{\Gamma(\gamma-2\alpha+1)} x^{-\mu-2\beta} (x^2-1)^{\gamma-2\alpha}, & x > 1 \\ 0, & 0 < x < 1 \end{cases}$$

and  $\gamma - 2\alpha + 1 > 0$ , [10:p.350]. On simplifying the last expression, (3.6) then becomes

$$\begin{aligned} \frac{1}{\Gamma(\gamma - 2\alpha + 1)} x^{1-2\alpha-\nu} \frac{d}{dx} \left[ x^{\nu-\mu+2\alpha-2\beta} \int_0^x [f_1(t) - q(t)] t^{2\alpha+\nu-1} (x^2-t^2)^{\gamma-2\alpha} dt \right] \\ \equiv m_1(x), \quad 0 < x < 1. \end{aligned} \tag{3.8}$$

Hence combining (3.5) and (3.8), the equation (3.4), finally becomes

$$\int_0^\infty k(xt)\phi(t)dt = m_1(x), \quad 0 < x < 1, \tag{3.9}$$

$$\alpha - \beta < \frac{1}{2}\mu - \frac{1}{2}\nu + 1.$$

The above analysis is justified if we consider the strip  $2\alpha - \nu < k < 2\alpha$ , with the condition that  $\alpha - \beta < \frac{1}{2}\mu - \frac{1}{2}\nu$ . The formula is actually valid for  $\alpha - \beta < \frac{1}{2}\mu - \frac{1}{2}\nu + 1$ , and it can be extended to the full range by analytic continuation.

Now simplify the expression (3.8), by making use of the definition of the functions  $f_1(t)$  and  $q(t)$  from (3.7), we get

$$\begin{aligned} m_1(x) &= \frac{1}{\Gamma(\gamma-2\alpha+1)} x^{1-2\alpha-\nu} \frac{d}{dx} \left[ x^{\nu-\mu+2\alpha-2\beta} \int_0^x t^{\nu-1} (x^2-t^2)^{\gamma-2\alpha} f(t) dt \right] \\ &- \frac{1}{\Gamma(\gamma-2\alpha+1)} x^{1-2\alpha-\nu} \frac{d}{dx} \left[ x^{\nu-\mu+2\alpha-2\beta} \int_0^x t^{\nu-1} (x^2-t^2)^{\gamma-2\alpha} dt \int_0^\infty u^{-2\alpha} J_\nu(ut)\phi(u)\omega(u) du \right] \\ &= I_1 - I_2, \text{ say.} \end{aligned}$$

On changing the order of integration in  $I_2$ , we can write the double integral as,

$$\int_0^\infty u^{2\alpha} \phi(u)\omega(u) du \int_0^x t^{\nu-1} (x^2-t^2)^{\gamma-2\alpha} J_\nu(ut) dt$$

$$= \frac{\beta(\gamma-2\alpha+1, \nu)}{\Gamma(\nu+1)2^{\nu+1}} x^{2(\nu+\gamma-2\alpha)} \int_0^\infty u^{\nu-2\alpha} \phi(u) \omega(u) {}_1F_2(\nu; \nu+1, \nu+\gamma-2\alpha+1; -\frac{x^2 u^2}{4}) du,$$

[10; p.327]. Then,

$$I_2 = \frac{\beta(\gamma-2\alpha+1, \nu)}{\Gamma(\gamma-2\alpha+1)\Gamma(\nu+1)2^{\nu+1}} x^{1-2\alpha-\nu} \frac{d}{dx} \left[ x^{2\nu} \int_0^\infty u^{\nu-2\alpha} \phi(u) \omega(u) {}_1F_2\left[\nu; \nu+1, \nu+\gamma-2\alpha+1; -\frac{x^2 u^2}{4}\right] du \right],$$

which on differentiating inside the integral sign and simplifying gives,

$$I_2 = 2^{2\alpha-\nu} x^{-\gamma} \int_0^\infty u^{-\gamma} \phi(u) \omega(u) J_\lambda(ux) du.$$

Hence,

$$m_1(x) = \frac{1}{\Gamma(\gamma-2\alpha+1)} x^{1-2\alpha-\nu} \frac{d}{dx} \left[ x^{\nu-\mu+2\alpha-2\beta} \int_0^x t^{\nu-1} (x^2-t^2)^{\gamma-2\alpha} f(t) dt \right] 2^{2\alpha-\gamma} x^{-\gamma} \int_0^\infty u^{-\gamma} \phi(u) \omega(u) J_\lambda(ux) du. \tag{3.10}$$

Next we consider the equation (3.3b), whence

$$\frac{1}{2\pi i} \int_{k-i\infty}^{k+i\infty} K(s) \Phi(1-s) x^{-s} ds = \frac{1}{2\pi i} \int_{k-i\infty}^{k+i\infty} H_2^*(s) G_1(s) x^{-s} ds \tag{3.11}$$

As before

$$\frac{1}{2\pi i} \int_{k-i\infty}^{k+i\infty} K(s) \Phi(1-s) x^{-s} ds = \int_0^\infty k(xt) \phi(t) dt, \tag{3.12}$$

where  $2\alpha-\nu < k < \frac{1}{2}\mu - \frac{1}{2}\nu + \alpha + \beta$ .

And

$$\begin{aligned} \frac{1}{2\pi i} \int_{k-i\infty}^{k+i\infty} H_2^*(s) G_1(s) x^{-s} ds &= \frac{1}{2\pi i} \int_{k-i\infty}^{k+i\infty} \frac{\Gamma(\frac{1}{2}s + \frac{1}{2}\nu - \alpha)}{\Gamma(\frac{1}{2}s + \frac{1}{2}\mu - \beta)} G_1(s) x^{-s} ds \\ &= -\frac{1}{2} x^{\nu-2\alpha-1} \frac{d}{dx} \left[ x^{2-\nu+2\alpha} \frac{1}{2\pi i} \int_{k-i\infty}^{k+i\infty} \frac{\Gamma(\frac{1}{2}s + \frac{1}{2}\nu - \alpha - 1)}{\Gamma(\frac{1}{2}s + \frac{1}{2}\mu - \beta)} G_1(s) x^{-s} ds \right] \end{aligned} \tag{3.13}$$

Here  $\frac{\Gamma(\frac{1}{2}s + \frac{1}{2}\nu - \alpha - 1)}{\Gamma(\frac{1}{2}s + \frac{1}{2}\mu - \beta)} \in L(k-i\infty, k+i\infty)$  if  $k > 2+2\alpha-\nu$  and  $\alpha-\beta > \frac{1}{2}\nu - \frac{1}{2}\mu$ .

Further if  $x^{-k} g_1(x) \in L(0, \beta)$ , then by Lemma 2, the above expression gives

$$-\frac{1}{2} x^{\nu-2\alpha-1} \frac{d}{dx} \left[ x^{2-\nu+2\alpha} \int_x^\infty g_1(t) \frac{1}{t} h_2^*\left(\frac{x}{t}\right) dt \right],$$

where

$$h_2^{-1} \left[ \frac{\Gamma(\frac{1}{2}s + \frac{1}{2}\nu - \alpha - 1)}{\Gamma(\frac{1}{2}s + \frac{1}{2}\mu - \beta)} ; x \right] = h_2^*(x) = \begin{cases} \frac{2}{\Gamma(\gamma-2\beta+1)} x^{\nu-2\alpha-2} (1-x^2)^{\gamma-2\beta}, & 0 < x < 1 \\ 0, & x > 1, \end{cases}$$

$\gamma-2\beta+1 > 0$  i.e.  $\frac{1}{2}\nu - \frac{1}{2}\mu - 1 < \alpha - \beta$ , [10, p.349].

Hence on simplifying, we have from (3.13),

$$\begin{aligned} \frac{1}{2\pi i} \int_{k-i\infty}^{k+i\infty} H_2^*(s) G_1(s) x^{-s} ds &= -\frac{x^{\nu-2\alpha-1}}{\Gamma(\gamma-2\beta+1)} \frac{d}{dx} \left[ \int_x^\infty t^{-\mu} (t^2-x^2)^{\gamma-2\beta} g(t) dt \right] \\ &\equiv m_2(x), \quad x > 1. \end{aligned} \tag{3.14}$$

From the results (3.12) and (3.14), the equation (3.11), then gives

$$\int_0^\infty k(xt)\phi(t)dt = m_2(x), \quad x > 1, \tag{3.15}$$

$$\frac{1}{2}^\nu \frac{1}{2}^{\mu-1} < \alpha - \beta$$

The above analysis is justified if we consider the strip

$$2\alpha - \nu + 2 < k < 2\beta \text{ and } \frac{1}{2}^\nu \frac{1}{2}^{\mu-1} < \alpha - \beta.$$

The formula is actually valid for  $\frac{1}{2}^\nu \frac{1}{2}^{\mu-1} < \alpha - \beta$ , and it can be extended to the full range by analytic continuation.

Now combining the results (3.9) and (3.15), we have,

$$\int_0^\infty k(xt)\phi(t)dt = m(x), \quad 0 < x < \infty,$$

where 
$$m(x) = \begin{cases} m_1(x), & 0 < x < 1 \\ m_2(x), & x > 1 \end{cases}, \quad m_1(x) \text{ and } m_2(x) \text{ defined by (3.10) and}$$

(3.14) respectively,

and 
$$|\alpha - \beta| < \frac{1}{2}^\mu - \frac{1}{2}^\nu + 1.$$

Or, 
$$\int_0^\infty (2xt)^{-\gamma} J_\lambda(xt)\phi(t) = m(x),$$

which by the usual Hankel inversion gives,

$$\begin{aligned} \phi(x) &= 2^\gamma x^{\gamma+1} \int_0^\infty t^{\gamma+1} J_\lambda(xt)m(t)dt \\ &= 2^\gamma x^{\gamma+1} \int_0^1 t^{\gamma+1} J_\lambda(xt)m_1(t)dt + 2^\gamma x^{\gamma+1} \int_1^\infty t^{\gamma+1} J_\lambda(xt)m_2(t)dt \end{aligned}$$

Now substituting the values of  $m_1(t)$  and  $m_2(t)$  above, and simplifying, we obtain,

$$\begin{aligned} \phi(x) &= \frac{2^\gamma}{\Gamma(\gamma-2\alpha+1)} x^{\gamma+1} \int_0^1 t^{2-2\nu+\lambda} J_\lambda(xt) d\left[ t^{\nu-\mu+2\alpha-2\beta} \int_0^t u^{\nu-1} (t^2-u^2)^{\gamma-2\alpha} f(u) du \right] \\ &\quad - \frac{2^\gamma}{\Gamma(\gamma-2\beta+1)} x^{\gamma+1} \int_1^\infty t^\lambda J_\lambda(xt) d\left[ \int_t^\infty u^{1-\mu} (u^2-t^2)^{\gamma-2\beta} g(u) du \right] \\ &\quad - 2^{2\gamma-2\alpha} x^{\gamma+1} \int_0^1 t J_\lambda(xt) dt \int_0^\infty u^{-\gamma} \phi(u) \omega(u) J_\lambda(ut) du \\ &= I_1 - I_2 - I_3, \text{ say} \\ &= I_1 - I_2 - 2^{2\gamma-2\alpha} x^{\gamma+1} \int_0^\infty u^{-\gamma} \phi(u) \omega(u) du \int_0^1 t J_\lambda(xt) J_\lambda(ut) dt \\ &= I_1 - I_2 - 2^{2\gamma-2\alpha} x^{\gamma+1} \int_0^\infty u^{-\gamma} \phi(u) \omega(u) \frac{L(u,x)}{u^{-x}} du, \tag{3.16} \end{aligned}$$

where  $L(u,x) = u J_{\lambda+1}(u) J_\lambda(x) - x J_{\lambda+1}(x) J_\lambda(u)$ ,  $\lambda = \frac{1}{2}^\mu + \frac{1}{2}^\nu - \alpha + \beta$ ,  $\gamma = \frac{1}{2}^\mu - \frac{1}{2}^\nu + \alpha + \beta$ , and

$$|\alpha - \beta| < \frac{1}{2}^\mu - \frac{1}{2}^\nu + 1.$$

This is the integral equation of the Fredholm type and can be written as

$$\phi(x) = A(x) + \int_0^\infty K(x,u)\phi(u)du.$$

Thus the solution of this single integral equation gives us the value of the unknown function  $\phi(x)$ , which is the solution of the system (3.1), as well.

4. SPECIAL CASES.

In particular if  $\mu = \nu$ , then the solution of the system

$$\int_0^\infty 2^{2\alpha} t^{-2\alpha} J_\nu(xt)[1+\omega(t)]\phi(t)dt = f(x), \quad 0 < x < 1 \tag{4.1}$$

$$\int_0^\infty 2^{2\beta} t^{-2\beta} J_\nu(xt)\phi(t)dt = g(x), \quad x > 1,$$

is the solution of the equation,

$$\phi(x) = \frac{2^{\alpha+\beta} x^{\alpha+\beta+1}}{\Gamma(\alpha-\beta+1)} \int_0^1 t^{2-\nu-\alpha+\beta} J_{\nu-\alpha+\beta}(xt) d\left[ t^{2\alpha-2\beta} \int_0^t u^{\nu-1} (t^2-u^2)^{\beta-\alpha} f(u) du \right]$$

$$- \frac{2^{\alpha+\beta}}{\Gamma(\alpha-\beta+1)} x^{\alpha+\beta+1} \int_1^\infty t^{\nu-\alpha+\beta} J_{\nu-\alpha+\beta}(xt) d\left[ \int_t^\infty u^{1-\nu} (u^2-t^2)^\alpha \beta g(u) du \right]$$

$$- 2^{2\beta} x^{\alpha+\beta+1} \int_0^\infty u^{-\alpha-\beta} \phi(u) \omega(u) L(u, x) \frac{du}{u-x^2}, \tag{4.2}$$

where  $L(u, x) = u J_{\nu-\alpha+\beta+1}(u) J_{\nu-\alpha+\beta}(x) - x J_{\nu-\alpha+\beta+1}(x) J_{\nu-\alpha+\beta}(u)$ ,

and  $|\alpha-\beta| < 1$ , derived as a special case from (3.16).

If we consider  $0 < \alpha-\beta < 1$ , then the differentiation under the integral sign in the second term of (4.2) can be carried out, and we have

$$\phi(x) = I_1 - I_2 - I_3, \tag{4.3}$$

where

$$I_2 = \frac{2^{\alpha+\beta+1}}{\Gamma(\alpha-\beta)} x^{\alpha+\beta+1} \int_1^\infty t^{\nu-\alpha+\beta+1} J_{\nu-\alpha+\beta}(xt) dt \int_t^\infty u^{1-\nu} (u^2-t^2)^{\alpha-\beta-1} g(u) du.$$

The special case  $\mu = \nu = 0, \beta = 0, \alpha = \frac{1}{2}$  is of interest, since it arises in the discussion of certain contact problems in elasticity. The dual equations (4.1) now become

$$\int_0^\infty t^{-1} J_0(xt)[1+\omega(t)]\phi(t)dt = f(x), \quad 0 < x < 1$$

$$\int_0^\infty J_0(xt)\phi(t)dt = g(x), \quad x > 1,$$

where the unknown function  $\phi$  satisfies the Fredholm equation, which can be derived from (4.3) to give,

$$\phi(x) = \frac{2}{\pi} x \int_0^1 \cos(xt) d\left[ \int_0^t \frac{f(u)}{\sqrt{t^2-u^2}} du \right]$$

$$+ \frac{2}{\pi} x \int_1^\infty \cos(xt) dt \int_t^\infty \frac{ug(u)}{\sqrt{u^2-t^2}} du + \int_0^\infty K(x, u)\phi(u)\omega(u) du$$

with

$$K(x, u) = \frac{x}{\pi u} \left[ \frac{\sin(x+u)}{x+u} + \frac{\sin(x-u)}{x-u} \right]. \quad [6; 4.6.28].$$

On the other hand, if we consider  $-1 < \alpha-\beta < 0$ , then the differentiation under the integral sign in the first term of (4.2) can be carried out, and then we have

$$\phi(x) = I_1 - I_2 - I_3, \tag{4.4}$$

where

$$I_1 = \frac{2^{\alpha+\beta+1}}{\Gamma(\beta-\alpha)} x^{\alpha+\beta+1} \int_0^1 t^{1-\nu+\alpha-\beta} J_{\nu-\alpha+\beta}(xt) dt \int_0^t u^{\nu+1} (t^2-u^2)^{\beta-\alpha-1} f(u) du.$$

One can, now deduce the special case when  $\nu = 0$ ,  $\beta = 0$  and  $\alpha = -\frac{1}{2}$  easily. In this case the solution of the dual equations

$$\int_0^\infty t J_0(xt)[1+\omega(t)]\phi(t)dt = f(x), \quad 0 < x < 1$$

$$\int_0^\infty J_0(xt)\phi(t)dt = g(x), \quad x > 1$$

is the solution of the equation, from (4.4),

$$\phi(x) = \frac{2}{\pi} \int_0^1 \sin(xt) dt \int_0^t \frac{uf(u)}{\sqrt{t^2-u^2}} du - \frac{2}{\pi} \int_1^\infty \sin(xt) d \left[ \int_t^\infty \frac{ug(u)}{\sqrt{u^2-t^2}} du \right] + \int_0^\infty K(x,u)\phi(u)du,$$

with

$$K(x,u) = \frac{1}{\pi} \left[ \frac{\sin(u+x)}{u+x} - \frac{\sin(u-x)}{u-x} \right], \quad [6; 4,6,40].$$

ACKNOWLEDGEMENT: This research is partially supported by a grant from Natural Sciences and Engineering Research Council of Canada.

#### REFERENCES

1. E.C. Titchmarsh, Introduction to the Theory of Fourier Integrals, Second Edition, Clarendon Press, Oxford, 1948.
2. C.J. Tranter, A further note on dual integral equations and an application to the diffraction of electromagnetic waves, Quart. J. Mech. and Appl. Math., **7** (1954), 318.
3. N.N. Lebedev, Ya. C. Uflyand, Appl. Math. Mech. **22**, 442 (English translation).
4. B. Noble, The solution of Bessel function dual integral equations by a multiplying-factor method, Proc. Cambridge Phil Soc. **59** (1963a) 351-362.
5. J.C. Cooke, A solution of Tranter's dual integral equation problem, Quart. J. Mech. Appl. Math., **9** (1956), 103.
6. I.N. Sneddon, Mixed boundary value problems in potential theory, John Wiley & Sons, Inc., New York, 1966.
7. W.E. Williams, The solution of certain dual integral equations, Proc. Edinburgh Math. Soc. (2), **12** (1961), 213-216.
8. Y. Tanno, On dual integral equations as convolution transforms, Tohoku Math. J. (2), **20**, (1968), 554-566.
9. C. Nasim and I.N. Sneddon, A general procedure for deriving solutions of dual integral equations, J. Engg. Sc. Vol. **12**(3), (1978), 115-128.
10. A. Erdelyi et al., Tables of integral transforms, vol. I, McGraw-Hill, New York, 1958.

## Special Issue on Decision Support for Intermodal Transport

### Call for Papers

Intermodal transport refers to the movement of goods in a single loading unit which uses successive various modes of transport (road, rail, water) without handling the goods during mode transfers. Intermodal transport has become an important policy issue, mainly because it is considered to be one of the means to lower the congestion caused by single-mode road transport and to be more environmentally friendly than the single-mode road transport. Both considerations have been followed by an increase in attention toward intermodal freight transportation research.

Various intermodal freight transport decision problems are in demand of mathematical models of supporting them. As the intermodal transport system is more complex than a single-mode system, this fact offers interesting and challenging opportunities to modelers in applied mathematics. This special issue aims to fill in some gaps in the research agenda of decision-making in intermodal transport.

The mathematical models may be of the optimization type or of the evaluation type to gain an insight in intermodal operations. The mathematical models aim to support decisions on the strategic, tactical, and operational levels. The decision-makers belong to the various players in the intermodal transport world, namely, drayage operators, terminal operators, network operators, or intermodal operators.

Topics of relevance to this type of decision-making both in time horizon as in terms of operators are:

- Intermodal terminal design
- Infrastructure network configuration
- Location of terminals
- Cooperation between drayage companies
- Allocation of shippers/receivers to a terminal
- Pricing strategies
- Capacity levels of equipment and labour
- Operational routines and lay-out structure
- Redistribution of load units, railcars, barges, and so forth
- Scheduling of trips or jobs
- Allocation of capacity to jobs
- Loading orders
- Selection of routing and service

Before submission authors should carefully read over the journal's Author Guidelines, which are located at <http://www.hindawi.com/journals/jamds/guidelines.html>. Prospective authors should submit an electronic copy of their complete manuscript through the journal Manuscript Tracking System at <http://mts.hindawi.com/>, according to the following timetable:

Manuscript Due	June 1, 2009
First Round of Reviews	September 1, 2009
Publication Date	December 1, 2009

### Lead Guest Editor

**Gerrit K. Janssens**, Transportation Research Institute (IMOB), Hasselt University, Agoralaan, Building D, 3590 Diepenbeek (Hasselt), Belgium; [Gerrit.Janssens@uhasselt.be](mailto:Gerrit.Janssens@uhasselt.be)

### Guest Editor

**Cathy Macharis**, Department of Mathematics, Operational Research, Statistics and Information for Systems (MOSI), Transport and Logistics Research Group, Management School, Vrije Universiteit Brussel, Pleinlaan 2, 1050 Brussel, Belgium; [Cathy.Macharis@vub.ac.be](mailto:Cathy.Macharis@vub.ac.be)