

NUMERICAL METHODS FOR APPROXIMATING EIGENVALUES OF BOUNDARY VALUE PROBLEMS

KIAZ A. USMANI

Department of Applied Mathematics
University of Manitoba
Winnipeg, Manitoba R3T 2N2
Canada

and

MOHAMMAD ISA

College of Engineering
King Abdul Aziz University
P.O. Box 9027
Jeddah, Saudi Arabia

(Received November 21, 1985)

ABSTRACT. This paper describes some new finite difference methods for the approximation of eigenvalues of a two point boundary value problem associated with a fourth order linear differential equation of the type $(py''')'' - (qy')' + (r - \lambda s)y = 0$. The smallest positive eigenvalue of some typical eigensystems is computed to demonstrate the practical usefulness of the numerical techniques developed.

KEY WORDS AND PHRASES. Band matrices, Deflation, Finite-difference methods, Generalized matrix eigenvalue problem, Inverse power iteration, The Smallest eigenvalue of a matrix eigenvalue problem, Two-point boundary value problems.

1980 AMS SUBJECT CLASSIFICATION CODE. 65L15.

1. **INTRODUCTION.** In this paper we will consider the fourth order linear differential equation

$$Ly \equiv [p(x)y''(x)]'' - [q(x)y'(x)]' + [r(x) - \lambda s(x)]y(x) = 0. \quad (1.1)$$

$a \leq x \leq b$, associated with one of the following pairs of homogeneous boundary conditions

$$y(a) = y''(a) = y(b) = y''(b) = 0 \quad (1.2)$$

$$y(a) = y'(a) = y(b) = y'(b) = 0 \quad (1.3)$$

Boundary value problems of the type (1.1)-(1.2) and/or (1.1)-(1.3) together with some of their modifications occur frequently in applied mathematics, modern physics and electrical engineering, see [5, 7, 8, 12]. In (1.1), we assume that the real-valued functions $p(x)$, $r(x)$ and $s(x)$ are continuous on $[a, b]$ and satisfy the conditions

$p(x) \in C^2 [a,b]$, $q(x) \in C^1 [a,b]$ and $p(x), q(x), s(x) > 0$, $r(x) \geq 0$, $x \in [a,b]$

Recently, numerical techniques of order 2 and 4 have been developed for computing approximate values of λ for the boundary value problem (1.1)-(1.3) with $p(x) \equiv 1$, $q(x) \equiv 0$, see [1,2]. In the fourth order method, the problem is discretized to yield a generalized seven-band symmetric matrix eigenvalue problem of the form

$$AY = \Lambda h^4 BY \tag{1.5}$$

where Λ is an approximate value of λ with eigenvector Y and B is a diagonal matrix depending on the function $s(x)$. Consequently, the eigenvalue problem (1.5) can be converted to the usual standard problem of the type $MY = \Lambda Y$ without any excessive amount of computational effort. There are at present several areas of research activity surrounding the development and analysis of numerical methods for approximating Λ satisfying the generalized matrix eigenproblems of the type (1.5), see [4, 9, 10, 11, 13].

Usmani has developed [14] some new finite difference methods of order 2 and 4 for computing eigenvalues of the differential system (1.1) with $p(x) \equiv 1$, $q(x) \equiv 0$ (for $p(x) \equiv 0$, $q(x) \equiv 1$, see [15]) associated with the boundary conditions

$$y(a) = y'(a) = y''(b) = y'''(b) = 0. \tag{1.6}$$

The purpose of this work is to present some new finite difference methods for computing approximate values of λ for the boundary value problems (1.1)-(1.2) and (1.1)-(1.3). These methods lead to generalized eigenvalue problems of the form (1.5) where A is a five-band or seven-band matrix and B is a diagonal positive definite matrix. We preface the numerical methods by some analytical properties of the eigenvalues and eigenfunctions of the boundary value problems under discussion.

2. PROPERTIES OF EIGENVALUES AND EIGENFUNCTIONS.

Let Π stand for any of the two boundary value problems (1.1)-(1.2) and (1.1)-(1.3).

THEOREM 2.1.

If λ_1 and λ_2 are two distinct eigenvalues of the problem Π and $y_1(x)$, $y_2(x)$ are the corresponding eigenfunctions, then

$$\int_a^b s(x) y_1(x) y_2(x) dx = 0. \tag{2.1}$$

PROOF. The proof is a direct consequence of Green's identity (see [3], p. 86) and the boundary conditions (1.2) and (1.3).

LEMMA 2.2. If $y(x)$ is an eigenfunction belonging to the eigenvalue λ of the boundary value problem Π , then $\overline{y}(x)$ is an eigenfunction belonging to the eigenvalue $\overline{\lambda}$.

PROOF. The proof is trivial and follows from $\overline{\overline{LY}} = 0$.

THEOREM 2.3.

The eigenvalues of the boundary value problem II, together with (1.4), are real. In fact

$$\lambda = \frac{\int_a^b [p(y'')^2 + q(y')^2 + r y^2] dx}{\int_a^b s y^2 dx} > 0. \tag{2.2}$$

PROOF. Let $\lambda = \mu + i\nu$, $\mu, \nu \in \mathbb{R}$, be an eigenvalue of the problem II with eigenfunction $y(x) = u(x) + i v(x)$ where $u(x)$ and $v(x)$ are real-valued functions. From Lemma 2.2, it follows that $\bar{\lambda}$ is also an eigenvalue of the problem II with respect to the eigenfunction $\bar{y}(x) = u(x) - i v(x)$. Now, from Theorem 2.1, it follows that

$$0 = \int_a^b s(x) y(x) \bar{y}(x) dx = \int_a^b s(x) |y(x)|^2 dx > 0 \tag{2.3}$$

because $s(x) > 0$ and $y(x) \neq 0$. The contradiction in (2.3) suggests that λ cannot be complex, hence it is real as required.

In order to prove (2.2), we multiply (1.1) by $y(x)$ and integrate the resulting equation twice from $x = a$ to $x = b$. We consequently arrive at (2.2) on using the conditions (1.1)-(1.4).

3. A SECOND ORDER METHOD FOR COMPUTING λ FOR (1.1)-(1.2).

For a positive integer $n \geq 4$, let $h = \frac{b-a}{n+1}$ and $x_i = a + ih$, $i = 0(1)n+1$. We shall also designate $y_i = y(x_i)$, $p_i = p(x_i)$ etc. We discretize the boundary value problem (1.1)-(1.2) by the following set of difference equations

$$(a) \quad [4p_1 + p_2 + h^2(q_{1/2} + q_{3/2}) + h^4 r_1] y_1 - [2p_1 + 2p_2 + h^2 q_{3/2}] y_2 + p_2 y_3 = \lambda h^4 s_1 y_1 + O(h^4), \tag{3.1a}$$

$$(b) \quad p_{i-1} y_{i-2} - [2p_{i-1} + 2p_{i+1} + h^2 q_{i-1/2}] y_{i-1} + [p_{i-1} + 4p_i + p_{i+1} + h^2(q_{i-1/2} + q_{i+1/2}) + h^4 r_i] y_i - [2p_i + 2p_{i+1} + h^2 q_{i+1/2}] y_{i+1} + p_{i+1} y_{i+2} = \lambda h^4 s_i y_i + O(h^6),$$

$$i = 2(1)n-1, \tag{3.1b}$$

$$(c) \quad p_{n-1} y_{n-2} - [2p_{n-1} + 2p_n + h^2 q_{n-1/2}] y_{n-1} + [p_{n-1} + 4p_n + h^2(q_{n-1/2} + q_{n+1/2}) + h^4 r_n] y_n = \lambda h^4 s_n y_n + O(h^4). \tag{3.1c}$$

The difference equation (3.1b) is obtained by writing (1.1) at $x = x_i$, in the form

$$h^2(py'')''_i - h^2(qy')'_i + h^2(r_i - \lambda s_i) y_i = 0,$$

$$(py'')_{i-1} - 2(py'')_i + (py'')_{i+1} - h[(qy')_{i+1/2} - (qy')_{i-1/2}] + h^2(r_i - \lambda s_i)y_i = 0(h^4),$$

or

$$\begin{aligned} & p_{i-1}[y_{i-2} - 2y_{i-1} + y_i] - 2p_i[y_{i-1} - 2y_i + y_{i+1}] \\ & + p_{i+1}[y_i - 2y_{i-1} + y_{i+2}] - h^2[q_{i+1/2}(y_{i+1} - y_i) - q_{i-1/2}(y_i - y_{i-1})] \\ & + h^4(r_i - \lambda s_i)y_i = 0(h^6), \end{aligned} \quad (3.2)$$

which can be arranged in the desired form (3.1b). The difference equations (3.1a) and (3.1c) are introduced so that the resulting coefficient matrix in (3.1) is a five-band symmetric matrix. In order to obtain (3.1a), we write (1.1) at $x = x_1$ in the form

$$\begin{aligned} & h^2(py'')_1'' - h^2(qy')_1' + h^2(r_1 - \lambda s_1)y_1 = 0, \\ & p_0y_0'' - 2p_1y_1'' + p_2y_2'' - h(q_3/2y_3/2 - q_1/2y_1/2) + h^2(r_1 - \lambda s_1)y_1 = \\ & 0(h^4), \end{aligned}$$

or

$$\begin{aligned} & -2p_1(y_0 - 2y_1 + y_2) + p_2(y_1 - 2y_2 + y_3) - h^2[q_1/2(y_2 - y_1) \\ & - q_1/2(y_1 - y_0)] + h^4(r_1 - \lambda s_1)y_1 = 0(h^4). \end{aligned} \quad (3.3)$$

The preceding equation is easily arranged in the form (3.1a). The difference equation (3.1c) is developed in an analogous manner by writing (1.1) at $x = x_n$. The system of linear equations (3.1) can be written in matrix form

$$(A + h^4R)y = \lambda h^4Sy + t(h) \quad (3.4)$$

where A is a symmetric five-band matrix. The matrices $R = \text{diag}(r_i)$, $S = \text{diag}(s_i)$ are diagonal matrices and $y = [y_1 \ y_2 \ \dots \ y_n]^T$, $t(h) = [t_1 \ t_2 \ \dots \ t_n]^T$. Here $t_1, t_n = 0(h^4)$ and $t_i = 0(h^6)$, $i = 2(1)n-1$.

Thus, our method for computing approximations Λ for λ satisfying (1.1)-(1.2) can be expressed as a generalized five-band symmetric matrix eigenvalue problem

$$(A + h^4R)Y = \Lambda h^4SY. \quad (3.5)$$

It can be proved that A is a positive definite matrix and hence for any stepsize $h > 0$, the approximations Λ for λ by (3.5) are real and positive for all $p, q, s > 0$ and $r \geq 0$. That our method provides $0(h^2)$ convergent approximations Λ for λ can be established following Grigorieff [6]. We omit the long and tedious details of convergence proof for brevity.

Normally, only one or a few of the extreme eigenvalues of (1.1)-(1.2) are needed in applications. In what follows, we will compute only the smallest eigenvalue of the

system to illustrate our method based on (3.1). We consider the eigenvalue problems

$$[(1 + x^2)y'']'' - [(1 + x^2)y']' + \left[\frac{1}{(1 + x)^2} - \lambda(1 + x)^4\right]y = 0 \tag{3.6}$$

with boundary conditions (1.2) at $a = 0, b = 1$, and

$$[e^x y'']'' - [e^x y']' + [\sin x - \lambda \cos x]y = 0 \tag{3.7}$$

with boundary conditions (1.2) at $a = 0, b = 1$. We computed approximations to the smallest eigenvalue Λ_1 of these eigensystems by our method (3.1) or equivalently (3.5). The corresponding relative errors are shown in Table I. It is evident from the entries of the accompanying table that our numerical method provides $O(h^2)$ convergent approximations. In computing the relative errors, we assumed that $\lambda_1 = \Lambda_1$ with $h = 2^{-8}$, because exact value of λ_1 cannot be obtained by analytical methods for these eigensystems.

TABLE I

Observed relative errors for $h = 2^{-m}, m = 3(1)7$

Problem	h	Λ_1	Relative Error $\left 1 - \frac{\lambda_1}{\Lambda_1}\right $
(3.6)	2^{-3}	24.634,681	2.448-2*
	2^{-4}	25.085,489	6.068-3
	2^{-5}	25.199,984	1.497-3
	2^{-6}	25.228,721	3.563-4
	2^{-7}	25.235,913	7.125-5
	2^{-8}	25.237,711	0.0
	(3.7)	2^{-3}	19.548,553
2^{-4}		19.921,847	6.294-3
2^{-5}		20.016,196	1.551-3
2^{-6}		20.039,847	3.691-4
2^{-7}		20.045,764	7.380-5
2^{-8}		20.047,244	0.0

* We write 2.448-2 for 2.448×10^{-2} .

4. A METHOD FOR COMPUTING λ FOR (1.1)-(1.3).

We omit the lengthy details of the development of our numerical method but we remark that a second order method for computing approximations Λ to λ satisfying (1.1)-(1.3) is based on

$$(A' + h^4 R)Y = \Lambda h^4 SY \tag{4.1}$$

where A' differs from A introduced in (3.5) in the first and the last rows only. The first row of A' is

$$[\{ 2p_0 + 4p_1 + p_2 + h^2(q_{1/2} + q_{3/2}) \} - \{ 2p_1 + 2p_2 + h^2q_{3/2} \} p_2 \ 0 \dots 0]$$

and the last row of A' is

$$[0 \dots 0 \ p_{n-1} \ - \{ 2p_{n-1} + 2p_n + h^2q_{n-1/2} \} \ \{ p_{n-1} + 4p_n + 2p_{n+1} + h^2(q_{n-1/2} + q_{n+1/2}) \}]$$

Again, as in the previous section, the matrix A' is a five-band symmetric matrix.

Another second order method for computing approximations Λ to λ satisfying (1.1)-(1.3) is based on

$$(A'' + h^4R)Y = \Lambda h^4SY \tag{4.2}$$

where A'' , as before, differs from A in the first and the last rows only.

The first and the last rows of A'' are

$$[\{ 4p_0 + 4p_1 + p_2 + h^2(q_{1/2} + q_{3/2}) \} - \{ 1/2 p_0 + 2p_1 + 2p_2 + h^2q_{3/2} \} p_2 \ 0 \dots 0]$$

and

$$[0 \dots 0 \ p_{n-1} \ - \{ 2p_{n-1} + 2p_n + 1/2 p_{n+1} + h^2q_{n-1/2} \} \ \{ p_{n+1} + 4p_n + 4p_{n-1} + h^2(q_{n-1/2} + q_{n+1/2}) \}]$$

respectively. The numerical results for computing Λ based on (4.2) are slightly better than those based on (4.1), but the matrix A'' is no longer a symmetric matrix.

We illustrate our methods based on (4.1) and (4.2) by computing Λ_1 satisfying (3.7) and the boundary conditions (1.3) with $a = 0$ and $b = 1$.

The smallest eigenvalue Λ_1 is computed employing inverse power iteration method and the numerical results are summarized in Table II

Table II

Observed relative errors for Problem (3.7)-(1.3) with $a = 0, b = 1$

Method	h	Λ_1	Relative error
(4.1)	2^{-3}	841.550	1.374-1
	2^{-4}	925.773	3.393-2
	2^{-5}	949.245	8.364-3
	2^{-6}	955.283	1.990-3
	2^{-7}	956.803	3.980-4
	2^{-8}	957.184	0.0
(4.2)	2^{-3}	922.198	3.805-2
	2^{-4}	949.282	8.428-3
	2^{-5}	955.404	1.967-3
	2^{-6}	956.847	4.553-4
	2^{-7}	957.197	8.983-5
	2^{-8}	957.283	0.0

5. HIGHER ORDER METHODS FOR SPECIAL CASE OF (1.1).

In this section we consider the linear differential equation

$$y^{(4)} - q(x)y'' + (r(x) - \lambda s(x))y = 0 \tag{5.1}$$

associated with the boundary conditions (1.2) or (1.3). For $n \geq 7$, let the step-size h and the sequence $\{x_i\}$ be defined as in section 3.

Case 1. The boundary value problem (5.1)-(1.2) is discretized by the following difference equations

$$\begin{aligned} \text{(a)} \quad & (44 + 12h^2q_1 + 6h^4r_1)Y_1 - (38 + 6h^4q_1)Y_2 + 12Y_3 - Y_4 = 6\Lambda h^4s_1Y_1 \\ \text{(b)} \quad & - (38 + 8h^2q_2)Y_1 + (56 + 15h^2q_2 + 6h^4r_2)Y_2 - (39 + 8h^2q_2)Y_3 \\ & + (12 + \frac{h^2}{2}q_2)Y_4 - Y_5 = 6\Lambda h^4s_2Y_2 \\ \text{(c)} \quad & - Y_{i-3} + (12 + \frac{h^2}{2}q_i)Y_{i-2} - (39 + 8h^2q_i)Y_{i-1} + (56 + 15h^2q_i + 6h^4r_i)Y_i \\ & - (39 + 8h^2q_i)Y_{i+1} + (12 + \frac{h^2}{2}q_i)Y_{i+2} - Y_{i+3} = 6\Lambda h^4s_iY_i, \quad i = 3(1)n-2, \\ \text{(d)} \quad & - Y_{n-4} + (12 + \frac{h^2}{2}q_{n-1})Y_{n-3} - (39 + 8h^2q_{n-1})Y_{n-2} + (56 + 15h^2q_{n-1} + \\ & 6h^4r_{n-1})Y_{n-1} - (38 + 8h^2q_{n-1})Y_n = 6\Lambda h^4s_{n-1}Y_{n-1}, \\ \text{(e)} \quad & -Y_{n-3} + 12Y_{n-2} - (38 + 6h^2q_n)Y_{n-1} + (44 + 12h^2q_n + 6h^4r_n)Y_n = 6\Lambda h^4s_nY_n. \end{aligned} \tag{5.2}$$

The system of equations (5.2) can be written in the form

$$(A + h^2QB + 6h^4R)Y = 6\Lambda h^4SY \tag{5.3}$$

where

$$A = J^3 + 6J^2, \quad J = (j_{mn}) \text{ is a tridiagonal matrix with } j_{mm} = 2,$$

$j_{m,m+1} = -1$, and $B = (b_{ij})$ is a five-band matrix so that

$$b_{11} = b_{nn} = 12, \quad b_{1,2} = b_{n,n-1} = 6 \quad \text{and}$$

$$b_{ij} = \left\{ \begin{array}{l} 15, \\ -8, \\ 1/2, \end{array} \quad \left. \begin{array}{l} i = j \\ |i - j| = 1 \\ |i - j| = 2. \end{array} \right\}$$

Case 2. The boundary value problem (5.1)-(1.3) is discretized by the difference equations (see [1] also)

$$\begin{aligned} \text{(a)} \quad & (76 + 2h^2q_0 + 12h^2q_1 + 6h^4r_1)Y_1 - (42 + 6h^2q_1)Y_2 + 12Y_3 - Y_4 = 6\Lambda h^4s_1Y_1, \\ \text{(b)} \quad & - (42 + \frac{h^2}{2}q_0 + 8h^2q_2)Y_1 + (\frac{113}{2} + 15h^2q_2 + 6h^4r_2)Y_2 - (39 + 8h^2q_2)Y_3 \\ & + (12 + \frac{h^2}{2}q_2)Y_4 - Y_5 = 6\Lambda h^4s_2Y_2, \\ \text{(c)} \quad & \text{The same equation as (5.1c), } i = 3(1)n-2, \end{aligned} \tag{5.4}$$

$$(d) - Y_{n-4} + (12 + \frac{h^2}{2}q_{n-1})Y_{n-3} - (39 + 8h^2q_{n-1})Y_{n-2} + (\frac{113}{2} + 15h^2q_{n-1} + 6h^4r_{n-1})Y_{n-1} - (42 + 8h^2q_{n-1} + \frac{h^2}{2}q_{n+1})Y_n = 6\Lambda h^4 s_{n-1} Y_{n-1},$$

$$(e) - Y_{n-3} + 12Y_{n-2} - (42 + 6h^2q_n)Y_{n-1} + (76 + 12h^2q_n + 2h^2q_{n+1} + 6h^4r_n)Y_n = 6\Lambda h^4 s_n Y_n.$$

We computed approximations to Λ_1 for the boundary value problems (5.1)-(1.2) and (5.1)-(1.3) with $q(x) = 1 + x^2$, $r(x) = \frac{1}{(1+x)^2}$, $s(x) = (1 + x)^4$, $a = 0$, $b = 1$. In both cases we assumed that $\lambda_1 = \Lambda_1$ with $h = 2^{-8}$. It is abundantly clear from the entries of the Table III that both our methods based on (5.2) and (5.4) are fourth order methods.

TABLE III

Observed relative errors ($O(h^4)$ -convergent numerical techniques)

Problem & method	h	Λ_1	Relative error
Problem (5.1)-(1.2) based on method (5.2)	2^{-3}	19.807,299	7.203-4
	2^{-4}	19.820,723	4.256-5
	2^{-5}	19.821,518	2.469-6
	2^{-6}	19.821,564	1.324-7
	2^{-7}	19.821,567	5.515-8
	2^{-8}	19.821.567	0.0
Problem (5.1)-(1.3) based on method (5.4)	2^{-3}	93.932,101	3.772-3
	2^{-4}	94.265,002	2.268-4
	2^{-5}	94.285,062	1.398-5
	2^{-6}	94.286,299	8.632-7
	2^{-7}	94.286,376	4.800-8
	2^{-8}	94.286,380	0.0

ACKNOWLEDGEMENT: This work was supported in part by a grant from NSERC of Canada. The author also wishes to thank Mr. Manzoor Hussain for the numerical implementation of the methods developed in this paper.

REFERENCES

1. CHAWLA, M.M. A New Fourth Order Finite Difference Method for Computing Eigenvalues of Fourth Order Two Point Boundary Value Problems, IMA J. of Numerical Analysis, 3 (1983), 291-293.
2. CHAWLA, M.M. and KATTI, C.P. A New Symmetric Five Diagonal Finite Difference Method for Computing Eigenvalues of Fourth Order Two Point Boundary Value Problem, J. Computational and Applied Maths., 8 (1982), 135-136.
3. CODDINGTON, E.A. and LEVINSON, N. Theory of Ordinary Differential Equations, McGraw-Hill Book Company, New York, 1955.
4. EDWARDS, Bruce. Computation of Eigenvalues Using Two Point Boundary Value Problem Codes, Internat. J. Numer. Methods Engrg., 18 (1982), 1736-1738.
5. FOX, L. The Numerical Solution of Two Point Boundary Value Problems in Ordinary Differential Equations, Oxford University Press, Oxford, 1957.
6. GRIGORIEFF, R.D. Diskrete Approximation von Eigenwertproblemen II, Numerische Mathematik, 24 (1975), 415-433.
7. HILDEBRAND, F.B. Methods of Applied Mathematics, Prentice-Hall, Engelwood Cliffs, N.J., 1952.
8. HILDEBRAND, F.B. Advanced Calculus for Applications, Prentice-Hall, Engelwood, Cliff, N.J., 1964.
9. KELLER, H.B. On the Accuracy of Finite Difference Approximations to the Eigenvalues of Differential and Integral Operators, Numer. Math., 7 (1965), 412-419.
10. KELLER, H.B. Numerical Methods for Two Point Boundary Value Problems, Blaisdell, Waltham, Massachusetts, 1968.
11. MCCORMICK, STEPHEN F. A mesh refinement method for $AX = \lambda BX$, Math. Comp. 36 (1981), 485-498.
12. REISS, E. J., CALLEGARI, A.J. and AHLUWALIA, D.S. Ordinary Differential Equations with Applications, Holt, Rinehart and Winston, New York, 1976.
13. TURYN, Lawrence. Perturbation of Two Point Boundary Value Problems with Eigenvalue Parameter in the Boundary Conditions, Proc. Roy. Soc. Edinburgh Section A, 94 (1983), 213-219.
14. USMANI, Riaz A. Finite Difference Methods for Computing Eigenvalues of Fourth Order Boundary Value Problems, Int. J. Math. and Mathematical Sciences, 9 (1986), 137-143.
15. USMANI, Riaz A. Some New Finite Difference Methods for Computing Eigenvalues of Two Point Boundary Value Problems, Computers and Maths. with Applications, 11 (1985), 903-909.

Special Issue on Decision Support for Intermodal Transport

Call for Papers

Intermodal transport refers to the movement of goods in a single loading unit which uses successive various modes of transport (road, rail, water) without handling the goods during mode transfers. Intermodal transport has become an important policy issue, mainly because it is considered to be one of the means to lower the congestion caused by single-mode road transport and to be more environmentally friendly than the single-mode road transport. Both considerations have been followed by an increase in attention toward intermodal freight transportation research.

Various intermodal freight transport decision problems are in demand of mathematical models of supporting them. As the intermodal transport system is more complex than a single-mode system, this fact offers interesting and challenging opportunities to modelers in applied mathematics. This special issue aims to fill in some gaps in the research agenda of decision-making in intermodal transport.

The mathematical models may be of the optimization type or of the evaluation type to gain an insight in intermodal operations. The mathematical models aim to support decisions on the strategic, tactical, and operational levels. The decision-makers belong to the various players in the intermodal transport world, namely, drayage operators, terminal operators, network operators, or intermodal operators.

Topics of relevance to this type of decision-making both in time horizon as in terms of operators are:

- Intermodal terminal design
- Infrastructure network configuration
- Location of terminals
- Cooperation between drayage companies
- Allocation of shippers/receivers to a terminal
- Pricing strategies
- Capacity levels of equipment and labour
- Operational routines and lay-out structure
- Redistribution of load units, railcars, barges, and so forth
- Scheduling of trips or jobs
- Allocation of capacity to jobs
- Loading orders
- Selection of routing and service

Before submission authors should carefully read over the journal's Author Guidelines, which are located at <http://www.hindawi.com/journals/jamds/guidelines.html>. Prospective authors should submit an electronic copy of their complete manuscript through the journal Manuscript Tracking System at <http://mts.hindawi.com/>, according to the following timetable:

Manuscript Due	June 1, 2009
First Round of Reviews	September 1, 2009
Publication Date	December 1, 2009

Lead Guest Editor

Gerrit K. Janssens, Transportation Research Institute (IMOB), Hasselt University, Agoralaan, Building D, 3590 Diepenbeek (Hasselt), Belgium; Gerrit.Janssens@uhasselt.be

Guest Editor

Cathy Macharis, Department of Mathematics, Operational Research, Statistics and Information for Systems (MOSI), Transport and Logistics Research Group, Management School, Vrije Universiteit Brussel, Pleinlaan 2, 1050 Brussel, Belgium; Cathy.Macharis@vub.ac.be