# ON DETERMINANT PRESERVERS OVER SKEW FIELDS 

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#### Abstract

We characterize all the semilinear transformations on matrices over skew fields that preserve the Dieudonné determinant.


## 1 - Introduction

Throughout this work, $D$ is a skew field (division ring) which is considered as finite-dimensional vector space over a field $K$, which may be identified with a subfield of the center of $D$.

In [3], Draxl gave some equivalent conditions to the invertibility of a matrix.
Theorem 1.1. Let $A \in M_{n}(D)$. Then the following conditions are equivalent:
i) $A \in G L_{n}(D)$, i.e., $A$ is invertible;
ii) $A B=I$, for some $B \in M_{n}(D)$, i.e., $A$ has a right inverse;
iii) $B A=I$, for some $B \in M_{n}(D)$, i.e., $A$ has a left inverse;
iv) the rows of $A$ are left linearly independent over $D$;
$\mathbf{v}$ ) the columns of $A$ are right linearly independent over $D$.

The theorem below says that we can decompose any invertible matrix in the Bruhat normal form ([3]).

Theorem 1.2. Let $A \in M_{n}(D)$ be an invertible matrix. There exists a decomposition of $A$ such that $A=T U P(\pi) V$, where $T$ is a lower triangular matrix, $V$ is an upper triangular matrix, both with 1 's on the main diagonal, and

[^0]$u_{i j}=u_{i} \delta_{i j}$ with $u_{i} \neq 0$, for each $i$, with $\pi$ and $U$ uniquely determined by $A$, i.e.,
\[

A=\left[$$
\begin{array}{lll}
1 & & 0  \tag{1.1}\\
& \ddots & \\
* & & 1
\end{array}
$$\right]\left[$$
\begin{array}{lll}
u_{1} & & 0 \\
& \ddots & \\
0 & & u_{n}
\end{array}
$$\right] P(\pi)\left[$$
\begin{array}{lll}
1 & & * \\
& \ddots & \\
0 & & 1
\end{array}
$$\right]
\]

Of course we can extend the concept of the Bruhat normal form of a matrix to singular matrices in analogous way of the one done by Draxl to prove Theorem 1.2, i.e., any matrix can be expressed in the form (1.1), where some of the $u_{i}$ 's may be zeroes.

Definition 1.3. Let $A \in M_{n}(D)$ be a matrix which admits a decomposition of the type (1.1), such that only $m(\leq n)$ of the $u_{i}$ 's are nonzero. Then we say that $A$ has rank $m$.

Therefore, one can say that $A$ has rank 1 if and only if it has the form $x y$ where $x$ is a $n \times 1$ matrix and $y$ is a $1 \times n$ matrix, both non zero. Notice, also, that if $X$ is invertible and $Y$ is a matrix with rank $m$, then $X Y$ has rank $m$.

We will need the next lemma in a very important proof in the last section.
Lemma 1.4. Let $A \in M_{n}(D)$ a matrix with rank $r$. Then there exists a matrix $B \in M_{n}(D)$ with rank $n-r$ such that $A+B$ is nonsingular.

Proof: Let $A=T U P(\pi) V$ and, without loss of generality, one supposes that in (1.1), the $u_{1}, \ldots, u_{r}$ are nonzero and the $u_{r+1}=\ldots=u_{n}=0$. Thus, let $U^{\prime} \in M_{n}(D)$ be a diagonal matrix such that $u_{1}^{\prime}=\ldots=u_{r}^{\prime}=0$ and $u_{r+1}^{\prime}=\ldots=$ $u_{n}^{\prime}=1$. Now, one only has to consider the matrix $B=T U^{\prime} P(\pi) V$.

## 2 - The Dieudonné determinant

Let $D^{*}$ be the non abelian multiplicative group $D-\{0\}$. We denote by $\left[D^{*}, D^{*}\right]$ the normal subgroup of the commutators of $D^{*}$. The Dieudonné determinant is the application

$$
\operatorname{det}: M_{n}(D) \longrightarrow D^{*} /\left[D^{*}, D^{*}\right] \cup\{0\}
$$

such that, in the conditions of Theorem 1.2,

$$
\operatorname{det} A=\left\{\begin{array}{cl}
0 & \text { if } A \notin G L_{n}(D) \\
{\left[\operatorname{sgn}(\pi) \prod_{t=1}^{n} u_{t}\right]} & \text { if } A \in G L_{n}(D)
\end{array}\right.
$$

where $[x]$ represents the class of $x$. This determinant has the important property

$$
\operatorname{det} A B=\operatorname{det} A \operatorname{det} B
$$

Note that $D^{*} /\left[D^{*}, D^{*}\right] \cup\{0\}$ is a multiplicative semigroup with a zero, such that all nonzero elements are invertible.

## 3 - Nonsingular rank 1 preservers

Let $\left\{t_{1}, \ldots, t_{m}\right\}$ be a basis of $D$ over $K$. We define $e^{i, l}$ as the $n \times 1$ matrix with $t_{l}$ in position $i$ and 0 elsewhere, and $e_{j, l}$ as the $1 \times n$ matrix with $t_{l}$ in position $j$ and 0 elsewhere defined. We suppose that $t_{1}=1$ and define $e^{i}=e^{i, 1}$ and $e_{j}=e_{j, 1}$.

Let us consider $\mathcal{C}$, the right vector space over $D$ generated by $e^{i}$,s, and $\mathcal{R}$, the left vector space over $D$ generated by $e_{j}$ 's.

The set $\left\{e^{i, l} \mid i=1, \ldots, n\right.$ and $\left.l=1, \ldots, m\right\}$ is a basis of $\mathcal{C}$ considered as vector space over $K$ and $\left\{e_{j, l} \mid j=1, \ldots, n\right.$ and $\left.l=1, \ldots, m\right\}$ is a basis of $\mathcal{R}$ consider as vector space over $K$.

The dimension of $\mathcal{C}$ over $D, \operatorname{dim}_{D} \mathcal{C}$, is $n$, and over $K$ is $[D: K] \operatorname{dim}_{D} \mathcal{C}$. Similarly, $\operatorname{dim}_{D} \mathcal{R}=n$ and $\operatorname{dim}_{K} \mathcal{R}=[D: K] \operatorname{dim}_{D} \mathcal{R}$.

Throughout this work $n>1$. The case $n=1$ is trivial.
Definition 3.1. Let $f$ be a transformation of $M_{n}(D)$ which is additive and $f(\alpha X)=\alpha f(X)$, for all $\alpha \in K$ and $X \in M_{n}(D)$. Then we say that $f$ is semilinear.

The next theorem is a generalization of results by Mink in [7], Wong in [8] and Marcus and Moyls in [6]. Though the first part of the proof is similar to the one done by Mink in [7], we use different arguments and for a sake of completeness we present the entire proof. Also, Jacob in [5], proved in a very intricated way some results similars to ours. He used some results of affine geometry and a concept of coherence invariant mapping. Our proofs only appeal to matrix concepts.

Theorem 3.2. Let $f$ be a nonsingular semilinear transformation on $M_{n}(D)$. If the set of rank 1 matrices is invariant under $f$, then there exist nonsingular matrices $A, B$ and a bijective map $\sigma$ of $D$, with $\sigma_{\mid K}=\operatorname{Id}_{K}$, such that either $\sigma$ is a homorphism and

$$
f(X)=A \bar{X} B
$$

for all $X \in M_{n}(D)$, or $\sigma$ is an anti-homorphism and

$$
f(X)=A \overline{X^{\prime}} B
$$

for all $X \in M_{n}(D)$, where $\bar{X}=\left(\bar{x}_{i j}\right)=\left(\sigma\left(x_{i j}\right)\right)$.
Proof: Let $u$ and $v$ be any vectors of $\mathcal{C}$ and $\mathcal{R}$, respectively. Then $u v$ is a matrix of $M_{n}(D)$ which rank is 1 . Therefore the rank of $f(u v)$ is also 1, i.e.,

$$
\begin{equation*}
f(u v)=x^{u v} y_{u v} \tag{3.1}
\end{equation*}
$$

where $x^{u v} \in \mathcal{C}$ and $y_{u v} \in \mathcal{R}$, not equal to zero.
First, let us prove that, for any $v$ and $v^{\prime}$, at least one of the conditions

1) $x^{u v} \| x^{u v^{\prime}}$ (i.e., $x^{u v}$ and $x^{u v^{\prime}}$ are linearly dependent);
2) $y_{u v} \| y_{u v^{\prime}}$,
holds. The matrix $u v+u v^{\prime}$ has rank 1 , and so $f\left(u v+u v^{\prime}\right)=x^{u v} y_{u v}+x^{u v^{\prime}} y_{u v^{\prime}}$ also has rank 1. But

$$
\begin{aligned}
f\left(u v+u v^{\prime}\right) & =x^{u v} y_{u v}+x^{u v^{\prime}} y_{u v^{\prime}} \\
& =\left[\begin{array}{ll}
x^{u v} & x^{u v^{\prime}}
\end{array}\right]\left[\begin{array}{l}
y_{u v} \\
y_{u v^{\prime}}
\end{array}\right] .
\end{aligned}
$$

If $x^{u v}$ X $x^{u v^{\prime}}$, then there exists an invertible matrix $P \in M_{n}(D)$ such that $P\left[\begin{array}{ll}x^{u v} & x^{u v^{\prime}}\end{array}\right]=\left[e^{1} e^{2}\right]$. Hence

$$
\begin{aligned}
f\left(u v+u v^{\prime}\right) & =\left[\begin{array}{ll}
x^{u v} & x^{u v^{\prime}}
\end{array}\right]\left[\begin{array}{c}
y_{u v} \\
y_{u v^{\prime}}
\end{array}\right] \\
& =P^{-1}\left[\begin{array}{cc}
e^{1} & e^{2}
\end{array}\right]\left[\begin{array}{c}
y_{u v} \\
y_{u v^{\prime}}
\end{array}\right] \\
& =P^{-1}\left[\begin{array}{c}
y_{u v} \\
y_{u v^{\prime}} \\
0 \\
\vdots \\
0
\end{array}\right]
\end{aligned}
$$

and thus $y_{u v} \| y_{u v^{\prime}}$.
Similarly, it can be proved that, for any $u$ and $u^{\prime}, x^{u v} \| x^{u^{\prime} v}$ or $y_{u v} \| y_{u^{\prime} v}$.
Let us show now that, for all $v^{\prime}, x^{u v} \| x^{u v^{\prime}}$ or, for all $v^{\prime}, y_{u v} \| y_{u v^{\prime}}$, for a given $u$. For, if $x^{u v} \nVdash x^{u w}$, for some $w \in \mathcal{R}$, then $y_{u v} \| y_{u w}$. In this case $y_{u v} \| y_{u v^{\prime}}$, for all $v^{\prime}$,
since, given $x^{u w^{\prime}}, x^{u w^{\prime}} X_{x^{u v}}$ or $x^{u w^{\prime}} \nmid x^{u w}$, i.e., $y_{u w^{\prime}} \| y_{u v}$ or $y_{u w^{\prime}} \| y_{u w}$. Similarly, we can prove that, for any $v, x^{u v} \| x^{u^{\prime} v}$, for all $u^{\prime}$, or $y_{u v} \| y_{u^{\prime} v}$, for all $u^{\prime}$.

Each non zero vector $x^{u v}$, or each $y_{u v}$, of (3.1), is determined only to within a scalar. For, supposing that $x^{u v} \| x^{u v^{\prime}}$, for all $v^{\prime}$, i.e., $x^{u v^{\prime}}=x^{u v} \alpha_{v^{\prime}}$, for all $v^{\prime}$, it follows that $f\left(u v^{\prime}\right)=x^{u v^{\prime}} \alpha_{v^{\prime}}^{-1} \alpha_{v^{\prime}} y_{u v^{\prime}}$; thus, without loss of generality, for each $u$,

$$
\begin{equation*}
x^{u v}=x^{u v^{\prime}}, \tag{3.2}
\end{equation*}
$$

for all $v^{\prime}$, or

$$
\begin{equation*}
y_{u v}=y_{u v^{\prime}}, \tag{3.3}
\end{equation*}
$$

for all $v^{\prime}$, and, for each $v$,

$$
\begin{equation*}
x^{u v} \| x^{u^{\prime} v} \tag{3.4}
\end{equation*}
$$

for all $u^{\prime}$, or

$$
\begin{equation*}
y_{u v} \| y_{u^{\prime} v} \tag{3.5}
\end{equation*}
$$

for all $u^{\prime}$.
It is clear that, for each $u$, either equation (3.2) holds or (3.3) does. Otherwise, it would follow that $f\left(u v-u v^{\prime}\right)=0$, for $v \neq v^{\prime}$, which is impossible, since $u\left(v-v^{\prime}\right)$ is of rank 1 .

On other hand, if $x^{u v}=x^{u v^{\prime}}$, for all $v^{\prime}$, then there exists $w \in \mathcal{R}$ such that $y_{u v} \nVdash y_{u w}$. For, if $y_{u w}=\alpha_{w} y_{u v}$, for all $w$, then the map defined by $w \rightarrow x^{u v} \alpha_{w} y_{u v}$, is injective. But $\operatorname{dim}_{K} \mathcal{R}=[D: K] \operatorname{dim}_{D} \mathcal{R}$ and the dimension of the image over $K$ is less or equal than $[D: K]$, a contradiction. (Note we have assumed that $\operatorname{dim}_{D} \mathcal{R}>1$.)

Either the equation (3.2) holds, for all $u$, or (3.3) does, for all $u$. In fact, suppose that $x^{u v}=x^{u v^{\prime}}$ and $y_{u^{\prime} v}=y_{u^{\prime} v^{\prime}}$, for some $u$ different from $u^{\prime}$ and for all $v^{\prime}$. As we have seen in the last paragraph, there exists $w$ such that $y_{u v} \nmid y_{u w}$. Then $y_{u v} \nVdash y_{u^{\prime} v}$ or $y_{u w} \nmid y_{u^{\prime} v}$, and, therefore, $x^{u^{\prime} v}=x^{u v} \beta$, for some $\beta$, or $x^{u^{\prime} v}=x^{u w} \beta$, for some $\beta$. Suppose that the first case happens. Choose $v^{\prime} \neq v$ such that $x^{u^{\prime} v} \nmid x^{u^{\prime} v^{\prime}}$. Then

$$
\begin{aligned}
f\left(\left(u+u^{\prime}\right)\left(c v+v^{\prime}\right)\right) & =c x^{u v} y_{u v}+x^{u v^{\prime}} y_{u v^{\prime}}+c x^{u^{\prime} v} y_{u^{\prime} v}+x^{u^{\prime} v^{\prime}} y_{u^{\prime} v^{\prime}} \\
& =x^{u v}\left(c y_{u v}+y_{u v^{\prime}}+c \beta y_{u^{\prime} v}\right)+x^{u^{\prime} v^{\prime}} y_{u^{\prime} v}
\end{aligned}
$$

for an arbitrary scalar $c \in K$. Since $x^{u v} \| x^{u^{\prime} v} \forall x^{u^{\prime} v^{\prime}}$, as we have proven in the beginning of this proof, $\left(c y_{u v}+y_{u v^{\prime}}+c \beta y_{u^{\prime} v}\right) \| y_{u^{\prime} v}$. But $c \beta y_{u^{\prime} v} \| y_{u^{\prime} v}$ and thus
$\left(c y_{u v}+y_{u v^{\prime}}\right) \| y_{u^{\prime} v}$, for all scalar $c \in K$, which is impossible, since $y_{u v} \not X y_{u^{\prime} v}$. Similarly, we can also prove that the second case can not happen.

Either the equation (3.4) holds, for all $v$, or (3.5) does, for all $v$. Suppose for some $v_{1}$ and $v_{2}$, we have $x^{u_{1} v_{1}} \| x^{u v_{1}}$, for all $u$, and $y_{u_{1} v_{2}} \| y_{u v_{2}}$, for all $u$. Let us make

$$
x \mathcal{R}=\{x y \mid y \in \mathcal{R}\}
$$

and

$$
\mathcal{C} y=\{x y \mid x \in \mathcal{C}\} .
$$

We have

$$
f\left(u v_{1}\right)=x^{u v_{1}} y_{u v_{1}}=x^{u_{1} v_{1}} \alpha_{u} y_{u v_{1}} \in x^{u_{1} v_{1}} \mathcal{R}
$$

and

$$
f\left(u v_{2}\right)=x^{u v_{2}} y_{u v_{2}}=x^{u v_{2}} \beta_{u} y_{u_{1} v_{2}} \in \mathcal{C} y_{u_{1} v_{2}} .
$$

But $f\left(u\left(v_{1}+v_{2}\right)\right)=x^{u_{1} v_{1}} \alpha_{u} y_{u v_{1}}+x^{u v_{2}} \beta_{u} y_{u_{1} v_{2}}$ has rank 1. Therefore either $x^{u_{1} v_{1}} \| x^{u v_{2}}$ or $y_{u v_{1}} \| y_{u_{1} v_{2}}$, i.e., either $f\left(u v_{1}\right)$ or $f\left(u v_{2}\right)$ is in $\mathcal{C} y_{u_{1} v_{2}} \cap x^{u_{1} v_{1}} \mathcal{R}$. Let us consider the semilinear applications $\varphi_{1}$ of $\mathcal{C}$ into $x^{u_{1} v_{1}} \mathcal{R}$ defined by $\varphi_{1}(u)=$ $f\left(u v_{1}\right)$ and $\varphi_{2}$ of $\mathcal{C}$ into $\mathcal{C} y_{u_{1} v_{2}}$ defined by $\varphi_{2}(u)=f\left(u v_{2}\right)$. Then $\mathcal{C}$ is the union of the proper subspaces $\varphi_{1}^{-1}\left(\mathcal{C} y_{u_{1} v_{2}} \cap x^{u_{1} v_{1}} \mathcal{R}\right)$ with $\varphi_{2}^{-1}\left(\mathcal{C} y_{u_{1} v_{2}} \cap x^{u_{1} v_{1}} \mathcal{R}\right)$, which is impossible.

Suppose now the equations (3.2) and (3.4) both hold. Then $x^{u}=x^{u v}$, for all $u$ and $v$, and $x^{u}=x^{u^{\prime}} \alpha_{u}$ for all $u$. It is easy to see in these conditions, that, for example, all the $m n$ vectors $\alpha_{e^{1}} y_{e^{1} e_{j, l}}$ are linearly independent. Then we may write $\alpha_{e^{2}} y_{e^{2} e_{1}}$ as a linear combination of these vectors, for instance,

$$
\alpha_{e^{2}} y_{e^{2} e_{1}}=\sum_{j, l} c_{j, l} \alpha_{e^{1}} y_{e^{1} e_{j, l}} .
$$

But then

$$
f\left(e^{1}\left(\sum_{j, l} c_{j, l} e_{j, l}\right)-e^{2} e_{1}\right)=0
$$

which is absurd, since $f$ is nonsingular.
Similarly we can prove that (3.3) and (3.5) could not both hold.
We are able to say now that either

$$
x^{u v}=x^{u},
$$

for all $u$ and $v$, and

$$
y_{u v} \| y_{v},
$$

for all $u$ and $v$, or

$$
y_{u v}=y_{u},
$$

for all $u$ and $v$, and

$$
x^{u v} \| x^{v}
$$

for all $u$ and $v$.
Suppose the first case happens. Let $u^{\prime} \in \mathcal{C}$ and $v^{\prime} \in \mathcal{R}$ be vectors such that $x^{u} \nVdash x^{u^{\prime}}$ and $y_{v} \nVdash y_{v^{\prime}}$. Since $f(u v)=x^{u} \alpha(u, v) y_{v}$ we have

$$
\begin{aligned}
f\left[\left(u+u^{\prime}\right)\left(v+v^{\prime}\right)\right] & =x^{u} \alpha(u, v) y_{v}+x^{u} \alpha\left(u, v^{\prime}\right) y_{v^{\prime}}+x^{u^{\prime}} \alpha\left(u^{\prime}, v\right) y_{v}+x^{u^{\prime}} \alpha\left(u^{\prime}, v^{\prime}\right) y_{v^{\prime}} \\
& =x^{u}\left(\alpha(u, v) y_{v}+\alpha\left(u, v^{\prime}\right) y_{v^{\prime}}\right)+x^{u^{\prime}}\left(\alpha\left(u^{\prime}, v\right) y_{v}+\alpha\left(u^{\prime}, v^{\prime}\right) y_{v^{\prime}}\right),
\end{aligned}
$$

which implies that

$$
\left(\alpha(u, v) y_{v}+\alpha\left(u, v^{\prime}\right) y_{v^{\prime}}\right) \|\left(\alpha\left(u^{\prime}, v\right) y_{v}+\alpha\left(u^{\prime}, v^{\prime}\right) y_{v^{\prime}}\right)
$$

and therefore $\alpha(u, v)=\alpha\left(u, v^{\prime}\right) \alpha\left(u^{\prime}, v^{\prime}\right)^{-1} \alpha\left(u^{\prime}, v\right)$. If we redefine $x^{u}$ as $x^{u} \alpha\left(u, v^{\prime}\right)$ when $u \neq 0$, and $x^{0}=0$, and $y_{v}$ as $\alpha\left(u^{\prime}, v^{\prime}\right)^{-1} \alpha\left(u^{\prime}, v\right) y_{v}$ when $v \neq 0$, and $y_{0}=0$, then

$$
f(u v)=x^{u} y_{v} .
$$

From the fact

$$
x^{u \alpha} y_{v}=f((u \alpha) v)=f(u(\alpha v))=x^{u} y_{\alpha v}
$$

since $x^{u \alpha} \| x^{u}$, we deduce

$$
x^{u \alpha}=x^{u} \bar{\alpha},
$$

and

$$
y_{\alpha v}=\bar{\alpha} y_{v}
$$

where $\bar{\alpha} \in D$. These two equations allow us to conclude that $\bar{\alpha}$ depends neither on $v$ nor on $u$, respectively.

The application $\sigma$ which maps each $\alpha$ to $\bar{\alpha}$ is an automorphism of $D$. First, we have, for any $\alpha, \beta \in D$,

$$
x^{u} \overline{\alpha \beta}=x^{u \alpha \beta}=x^{u \alpha} \bar{\beta}=x^{u} \bar{\alpha} \bar{\beta},
$$

which means $\sigma(\alpha \beta)=\sigma(\alpha) \sigma(\beta)$. It is easy to see $\sigma(\alpha+\beta)=\sigma(\alpha)+\sigma(\beta)$. The endomorphism $\sigma$ is also injective, since it extends the $\operatorname{Id}_{K}$, hence it is an automorphism of $D$, since $D$ is finite-dimensional over $K$.

For each $\alpha \in D$, we have $f\left(e^{i} \alpha e_{j}\right)=x^{e^{i}} \sigma(\alpha) y_{e_{j}}$, and therefore $f(X)=$ $A \bar{X} B$, for all $X \in M_{n}(D)$, where $A$ is the matrix whose columns are $x^{e^{1}}, \ldots, x^{e^{n}}$ and $B$ is the matrix whose rows are $y_{e_{1}}, \ldots, y_{e_{n}}$, and

$$
\bar{X}=\left(\bar{x}_{i j}\right)=\left(\sigma\left(x_{i j}\right)\right) .
$$

Let us note that $x^{e^{1}}, \ldots, x^{e^{n}}$ and $y_{e_{1}}, \ldots, y_{e_{n}}$ are linearly independent. For, if $\sum_{i} x^{e^{i}} \alpha_{i}=0$, then

$$
0=\sum_{i} x^{e^{i}} \alpha_{i} y_{v}=f\left(\sum_{i} e^{i} \sigma^{-1}\left(\alpha_{i}\right) v\right)
$$

which implies $\sum_{i} e^{i} \sigma^{-1}\left(\alpha_{i}\right)=0$, i.e., $\alpha_{1}=\ldots=\alpha_{n}=0$. Similarly we prove $y_{e_{1}}, \ldots, y_{e_{n}}$ are left linearly independent. This fact leads us to the conclusion that $A$ and $B$ are invertible ([3]).

Using similar arguments, we conclude for the other case that $f(X)=A \overline{X^{\prime}} B$, for all $X \in M_{n}(D)$, where $A$ is the invertible matrix whose columns are $x^{e_{1}}, \ldots, x^{e_{n}}$ and $B$ is the invertible matrix whose rows are $y_{e^{1}}, \ldots, y_{e^{n}}$.

## 4 - Dieudonné determinant preservers

Next, we still work on generalizations for skew fields of results obtained before ([7]). The last theorem will have a crucial role and the concept of Dieudonné determinant will be needed.

Lemma 4.1. Let $f$ be a semilinear map on $M_{n}(D)$. If $f$ preserves Dieudonné determinant, then $f$ is nonsingular.

Proof: Suppose that $f(X)=0$. Let $Y$ be a matrix of rank $n-\operatorname{rank} X$ such that $X+Y$ is nonsingular (Lemma 1.4). Then

$$
\begin{aligned}
\operatorname{det}(f(Y)) & =\operatorname{det}(f(X)+f(Y)) \\
& =\operatorname{det}(f(X+Y)) \\
& =\operatorname{det}(X+Y) \\
& \neq 0 .
\end{aligned}
$$

Hence $\operatorname{det}(Y) \neq 0$, i.e., $Y$ is nonsingular and therefore $X=0$. We conclude that $f$ is nonsingular.

We only have to prove now that if $f$ preserves Dieudonné determinant, then $f$ preserves rank 1 .

Theorem 4.2. A semilinear map $f$ on $M_{n}(D)$ preserves the Dieudonné determinant if and only if there exist nonsingular matrices $A, B$ and a bijective map $\sigma$ of $D$, with $\sigma_{\mid K}=\mathrm{Id}_{K}$, such that either $\sigma$ is a homorphism and

$$
f(X)=A \bar{X} B,
$$

for all $X \in M_{n}(D)$, or $\sigma$ is an anti-homorphism and

$$
f(X)=A \overline{X^{\prime}} B,
$$

for all $X \in M_{n}(D)$, with $\bar{X}=\left(\bar{x}_{i j}\right)=\left(\sigma\left(x_{i j}\right)\right)$.
Proof: Let $X$ be a matrix of rank 1 and suppose that $f(X)$ has rank $k$. One assumes that $X=T_{1} U_{1} P\left(\pi_{1}\right) V_{1}$ and $f(X)=T_{2} U_{2} P\left(\pi_{2}\right) V_{2}$ with $T_{i}, V_{i}, \pi_{i}$ as in Theorem 1.2, and, without loss of generality, $U_{1}=\alpha E_{11}$ and $U_{2}=\alpha_{1} E_{11}+$ $\cdots+\alpha_{k} E_{k k}$. Let $\xi$ be an indeterminate over $K$ and make $Y=T_{2} U_{Y} P\left(\pi_{2}\right) V_{2}$, with $U_{Y}=E_{k+1 k+1}+\cdots+E_{n n}$. Then

$$
\begin{aligned}
\operatorname{det}(\xi f(X)+Y) & =\operatorname{det}\left(\xi T_{2}\left(U_{2}+U_{Y}\right) P\left(\pi_{2}\right) V_{2}\right) \\
& =\xi^{k} \alpha_{1} \cdots \alpha_{k}
\end{aligned}
$$

On the other hand,

$$
\begin{aligned}
\operatorname{det}(\xi f(X)+Y) & =\operatorname{det}\left(f\left(\xi X+f^{-1}(Y)\right)\right. \\
& =\operatorname{det}\left(\xi X+f^{-1}(Y)\right)
\end{aligned}
$$

Since $\operatorname{det}\left(f^{-1}(Y)\right)=\operatorname{det}(Y)=0$, the rank of $f^{-1}(Y)$ is less than $n$. In other hand, it can't be less than $n-2$. This would imply that $\operatorname{det}(\xi f(X)+Y)=0$. Then the rank of $f^{-1}(Y)$ is $n-1$ and determinant (4.1) is a polynomial in $\xi$. Thus $k=1$, and $T$ preserves rank 1 matrices.

We note now that if $X=T U P(\pi) V$,

$$
X=\left[\begin{array}{lll}
1 & & 0 \\
& \ddots & \\
* & & 1
\end{array}\right]\left[\begin{array}{lll}
u_{1} & & 0 \\
& \ddots & \\
0 & & u_{n}
\end{array}\right] P(\pi)\left[\begin{array}{lll}
1 & & * \\
& \ddots & \\
0 & & 1
\end{array}\right]
$$

then $\bar{X}=\bar{T} \bar{U} P(\pi) \bar{V}$,

$$
\bar{X}=\left[\begin{array}{lll}
1 & & 0 \\
& \ddots & \\
\bar{*} & & 1
\end{array}\right]\left[\begin{array}{ccc}
\sigma\left(u_{1}\right) & & 0 \\
& \ddots & \\
0 & & \sigma\left(u_{n}\right)
\end{array}\right] P(\pi)\left[\begin{array}{lll}
1 & & \bar{*} \\
& \ddots & \\
0 & & 1
\end{array}\right] .
$$

Therefore $\operatorname{det}(\bar{X})=\sigma(\operatorname{det}(X))$. Since either $f(X)=A \bar{X} B$, for all $X$, or $f(X)=$ $A \overline{X^{\prime}} B$, for all $X$, and $\operatorname{det}(f(X))=\operatorname{det}(X)$, the result follows. Note that $\sigma(x y)=$ $\sigma(x) \sigma(y)$, implies that $\operatorname{det}(A B)=1$.

The converse is obvious.
Notice that if $D$ is a (commutative) field, then the last theorem reduces to the one obtained by Frobenius and by Mink.

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