Motivation: LP 1967: A 1st counter-example

# The Hirsch Conjecture and its relatives (part I of III)

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The Hirsch Conjecture	Motivation: LP	1967: A 1st counter-example	Cases and bounds	The d-step Theorem
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Motivation: Ll

1967: A 1st counter-example

Cases and bounds

The d-step Theorem

# Hirsch Wars Trilogy

#### Slides (Seville version, March 2012):

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- Episode I: The Phantom Conjecture. (Today)
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The Hirsch Conjecture	Motivation: LP	1967: A 1st counter-example	Cases and bounds	The d-step Theorem
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Definition

# A (convex) polyhedron *P* is the intersection of a finite family of affine half-spaces in $\mathbb{R}^d$ .



#### Definition

# A (convex) polytope *P* is the convex hull of a finite set of points in $\mathbb{R}^d$ .





#### Polytope = bounded polyhedron.

Every polytope is a polyhedron, every bounded polyhedron is a polytope.





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not cutting, but touching *P*.



# Let *P* be a polytope (or polyhedron) and let *H* be a hyperplane not cutting, but touching *P*.



The Hirsch Conjecture	Motivation: LP	1967: A 1st counter-example	Cases and bounds	The <i>d</i> -step Theorem		
Faces of P						

### We say that $H \cap P$ is a face of P.



The Hirsch Conjecture	Motivation: LP	1967: A 1st counter-example	Cases and bounds	The <i>d</i> -step Theorem		
Faces of P						

Faces of dimension 0 are called vertices.



The Hirsch Conjecture	Motivation: LP	1967: A 1st counter-example	Cases and bounds	The <i>d</i> -step Theorem		
Faces of <i>P</i>						

Faces of dimension 1 are called edges.



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#### Faces of P

Faces of dimension d - 1 are called facets.





Vertices and edges of a polytope *P* form a graph (finite, undirected)



The distance d(u, v) between vertices u and v is the length (number of edges) of the shortest path from u to v.

For example, d(u, v) = 2.



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Vertices and edges of a polytope *P* form a graph (finite, undirected)



The diameter of G(P) (or of P) is the maximum distance among its vertices:

$$diam(P) = max\{d(u, v) : u, v \in V\}.$$

The Hirsch Conjecture	Motivation: LP	1967: A 1st counter-example	Cases and bounds	The d-step Theorem
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Conjecture: Warren M. Hirsch (1957)

For every polytope *P* with *n* facets and dimension *d*,

 $\operatorname{diam}(P) \leq n-d.$ 

polytope	facets	dimension	n-d	diameter
cube	6	3	3	3
dodecahedron	12	3	9	5
octahedron	8	3	5	2
<i>k</i> -prism	k + 2	3	k - 1	$\lfloor k/2 \rfloor + 1$
<i>n</i> -cube	2 <i>n</i>	п	п	п

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- It was communicated by W. M. Hirsch to G. Dantzig in 1957 (Dantzig had recently invented the simplex method for linear programming).
- ② Several special cases have been proved: d ≤ 3, n − d ≤ 6, 0/1-polytopes, ...
- But in the general case we do not even know of a polynomial bound for diam(P) in terms of n and d.
- ④ In 1967, Klee and Walkup disproved the unbounded case.
- In 2010 I disproved the bounded case. But the construction does not produce polytopes whose diameter is more than a constant times the Hirsch bound.



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Linear programming						

A linear program is the problem of maximization (or minimization) of a linear functional subject to linear inequality constraints. That is:

Given

- a system  $Mx \leq b$  of linear inequalities  $(b \in \mathbb{R}^n, M \in \mathbb{R}^{d \times n})$ , and
- an objective function  $c^t \in \mathbb{R}^d$

Find

• max{ $c^t \cdot x : x \in \mathbb{R}^d$ ,  $Mx \le b$ } (and a point *x* where the maximum is attained).



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- In particular, in 1947 G. Dantzig devised the simplex method: The first practical algorithm for solving linear programs (and still the one most used).
- Around 1980 two polynomial time algorithms for linear programming were proposed by Khachiyan and Karmakar (*ellipsoid* and *interior point* method).
- None of these algorithms is strongly polynomial. Finding strongly polynomial algorithms for linear programming is one of the "mathematical problems for the 21st century" proposed by S. Smale in 2000.



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- The set of feasible solutions P = {x ∈ ℝ<sup>d</sup> : Mx ≤ b} is a polyhedron P with (at most) n facets and d dimensions.
- The optimal solution (if it exists) is always attained at a vertex.
- The simplex method [Dantzig 1947] solves the linear program by starting at any feasible vertex and moving along the graph of *P*, in a monotone fashion, until the optimum is attained.
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In this sense, more important than the standard Hirsch conjecture (which is false) is the following "polynomial version" of it:

### Polynomial Hirsch Conjecture

Let H(n, d) denote the maximum diameter of *d*-polyhedra with *n* facets. There is a constant *k* such that:

 $H(n,d) \leq n^k, \quad \forall n, d.$ 



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## "As simple as possible"

## Definition

A *d*-polytope/polyhedron is simple if at every vertex exactly *d* facets meet. ( $\simeq$  facet-defining hyperplanes are "in general position").

A *d*-polytope is simplicial if every facet has exactly *d* vertices. That is, if every proper face is a simplex. ( $\simeq$  vertices are "in general position").

Of course, the (polar) dual of a simple polytope is simplicial, and vice-versa.

### Lemma (Klee 1964)

For every n and d the maximum diameter of d-polytopes / d-polyhedra with n facets is achieved at a simple one.

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### Remark

We will often dualize the problem. We want to travel from one facet to another of a polytope Q (the polar of P) along the "dual graph", whose edges correspond to *ridges* of Q.



By the Klee lemma we can restrict our attention to simplicial polytopes; their face lattices are *simplicial complexes* with the topology of a (d - 1)-sphere. (*Simplicial* (d - 1)-spheres).

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"but not simpler"					

Q: What is the polar of a (simple) unbounded polyhedron?



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The polar of an unbounded *d*-polyhedron with *n* facets "is" a regular triangulation of *n* points in  $\mathbb{R}^{d-1}$ .

Klee and Walkup proved:

Theorem (Klee-Walkup 1967)

There is a 4-dimensional unbounded polyhedron with 8 facets and diameter 5.

Let us prove the following equivalent version:

### Theorem

There is a regular triangulation of 8 points in  $\mathbb{R}^3$  that has two tetrahedra at distance five from one another.

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### Proof.

This is a (Cayley Trick view of a) 3D triangulation with 8 vertices and diameter 4:



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Three steps are needed to go from any light triangle to any dark triangle.

### Proof.

This is a (Cayley Trick view of a) 3D triangulation with 8 vertices and diameter 4:



Gluing two more tetrahedra (one on top, one on bottom), we get diameter 5.



# The Klee-Walkup Hirsch-sharp (9,4)-polytope

The counter-example to the unbounded Hirsch conjecture is **equivalent** to the existence of a 4-polytope with 9 facets and with diameter 5:

## The Klee-Walkup Hirsch-sharp (9,4)-polytope

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The Hirsch Conjecture	Motivation: LP	1967: A 1st counter-example	Cases and bounds	The <i>d</i> -step Theorem

Hirsch conjecture holds for

● *d* ≤ 3: [Klee 1966].

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# Polynomial bounds, under perturbation

# Given a linear program with *d* variables and *n* restrictions, we consider a random perturbation of the matrix, within a parameter $\epsilon$ (normal distribution).

#### Theorem [Spielman-Teng 2004] [Vershynin 2006]

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Let H(n, d) := max. diameter of a *d*-polyhedron with *n* facets.

 $H(n,d) \leq n^{\log_2 d+2}, \quad \forall n, d.$ 

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## Normal simplicial complexes

#### Definition

A pure simplicial complex is called **normal** if the dual graph of every link is connected. (That is, if every link is strongly connected)

The Kalai-Kleitman bound follows from the following recursion (where, now, H(n, d) denotes the max. diameter among normal and pure simplicial (d - 1)-complexes with *n* vertices):

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### Proof.

Let u, v be two simplices in a normal, pure simplic. complex K.

- For each *i* ∈ N, let *U<sub>i</sub>* be the *i*-neighborhood of *u* (the subcomplex consisting of all simplices at distance at most *i* from *u*). Let *V<sub>i</sub>* the *j*-neighborhood of *v*.
- Let  $i_0$  (resp.  $j_0$ ) be the smallest value such that  $U_{i_0}$  (resp.  $V_{j_0}$ ) contains more than half of the vertices. This implies  $i_0 1$  and  $j_0 1$  are at most  $H(\lfloor n/2 \rfloor, d)$ .
- Let  $u' \in U_{i_0}$  and  $v' \in V_{j_0}$  having a common vertex. Then: dist $(u', v') \le H(n-1, d-1)$ .
- So:  $d(u, v) \leq dist(u, u') + dist(u', v') + dist(v', v) \leq$

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- If *P* and *Q* satisfy it, then so does  $P \times Q$ :  $\delta(P \times Q) = \delta(P) + \delta(Q)$ . In particular:

For every  $n \le 2d$ , there are polytopes in which the bound is tight (products of simplices). We call these "Hirsch-sharp" polytopes.

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# Wedging, a.k.a. one-point-suspension




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The Hirsch Conjecture	Motivation: LP	1967: A 1st counter-example	Cases and bounds	The <i>d</i> -step Theorem 000€00

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# Wedging, a.k.a. one-point-suspension





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## Wedging, a.k.a. one-point-suspension







#### Two important remarks

The *d*-step Theorem follows from and implies (respectively) the following:

#### Lemma

For every d-polytope P with n facets and diameter  $\delta$  there is a d + 1-polytope with one more facet and the same diameter  $\delta$ .

#### Corollary

There is a function f(k) := H(2k, k) such that

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Thank you						

## TO BE CONTINUED