# The Hirsch Conjecture and its relatives (part I of III) 

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$$
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$$

## Hirsch Wars Trilogy

## Slides (Seville version, March 2012):

http://personales.unican.es/santosf/Hirsch/Wars
(1) Episode I: The Phantom Conjecture. (Today)
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(3) Episode IV: A New Hope. (The day after)

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## Polyhedra and polytopes

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## Definition

A (convex) polyhedron $P$ is the intersection of a finite family of affine half-spaces in $\mathbb{R}^{d}$.

## Polyhedra and polytopes

## Definition

A (convex) polytope $P$ is the convex hull of a finite set of points in $\mathbb{R}^{d}$.


The dimension of $P$ is the dimension of its affine hull.

## Polyhedra and polytopes

## Polytope = bounded polyhedron.

Every polytope is a polyhedron, every bounded polyhedron is a polytope.


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## Faces of $P$

Let $P$ be a polytope (or polyhedron) and let $H$ be a hyperplane not cutting, but touching $P$.


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## Faces of $P$

We say that $H \cap P$ is a face of $P$.


## Faces of $P$

## Faces of dimension 0 are called vertices.



## Faces of $P$

Faces of dimension 1 are called edges.


## Faces of $P$

## Faces of dimension $d-1$ are called facets.



## The graph of a polytope

Vertices and edges of a polytope $P$ form a graph (finite, undirected)


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The distance $d(u, v)$ between vertices $u$ and $v$ is the length (number of edges) of the shortest path from $u$ to $v$.

For example $d(u, v)=$ ?

## The graph of a polytope

Vertices and edges of a polytope $P$ form a graph (finite, undirected)


The distance $d(u, v)$ between vertices $u$ and $v$ is the length (number of edges) of the shortest path from $u$ to $v$.

For example, $d(u, v)=2$.

## The graph of a polytope

Vertices and edges of a polytope $P$ form a graph (finite, undirected)


The diameter of $G(P)$ (or of $P$ ) is the maximum distance among its vertices:
$\operatorname{diam}(P)=\max \{d(u, v): u, v \in V\}$.

## The Hirsch conjecture

Conjecture: Warren M. Hirsch (1957)
For every polytope $P$ with $n$ facets and dimension $d$,

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\operatorname{diam}(P) \leq n-d
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| polytope | facets | dimension | $n-d$ | diameter |
| :--- | :---: | :---: | :---: | :---: |
| cube | 6 | 3 | 3 | 3 |
| dodecahedron | 12 | 3 | 9 | 5 |
| octahedron | 8 | 3 | 5 | 2 |
| $k$-prism | $k+2$ | 3 | $k-1$ | $\lfloor k / 2\rfloor+1$ |
| $n$-cube | $2 n$ | $n$ | $n$ | $n$ |

## Brief history of the conjecture

(1) It was communicated by W. M. Hirsch to G. Dantzig in 1957 (Dantzig had recently invented the simplex method for linear programming).
(2) Several special cases have been proved: $d \leq 3, n-d \leq 6$, 0/1-polytopes,
(3) But in the general case we do not even know of a polynomial bound for diam $(P)$ in terms of $n$ and $d$.
(4) In 1967, Klee and Walkup disproved the unbounded case.
(5) In 2010 I disproved the bounded case. But the construction does not produce polytopes whose diameter is more than a constant times the Hirsch bound.

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## Linear programming

A linear program is the problem of maximization (or minimization) of a linear functional subject to linear inequality constraints. That is:

Given

- a system $M x \leq b$ of linear inequalities $\left(b \in \mathbb{R}^{n}, M \in \mathbb{R}^{d \times n}\right)$, and
- an objective function $c^{t} \in \mathbb{R}^{d}$

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- $\max \left\{c^{t} \cdot x: x \in \mathbb{R}^{d}, M x \leq b\right\}$ (and a point $x$ where the maximum is attained).


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## A brief history of linear programming

- It was invented in the 1940's by G. Dantzig, L. Kantorovich and J. von Neumann.
- In particular, in 1947 G. Dantzig devised the simplex method: The first practical algorithm for solving linear programs (and still the one most used).
- Around 1980 two polynomial time algorithms for linear programming were proposed by Khachiyan and Karmakar (ellipsoid and interior point method).
- None of these algorithms is strongly polynomial. Finding strongly polynomial algorithms for linear programming is one of the "mathematical problems for the 21st century" proposed by S. Smale in 2000.


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## Connection to the Hirsch conjecture

- The set of feasible solutions $P=\left\{x \in \mathbb{R}^{d}: M x \leq b\right\}$ is a polyhedron $P$ with (at most) $n$ facets and $d$ dimensions.
- The optimal solution (if it exists) is always attained at a vertex.
- The simplex method [Dantzig 1947] solves the linear program by starting at any feasible vertex and moving along the graph of $P$, in a monotone fashion, until the optimum is attained.
- In particular, (the polynomial version of) the Hirsch conjecture is related to the question of whether the simplex method is a polynomial-time algorithm. A polynomial pivot rule for the simplex method would answer Smale's question in the affirmative.


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## Polynomial Hirsch conjecture

In this sense, more important than the standard Hirsch conjecture (which is false) is the following "polynomial version" of it:
Polynomial Hirsch Conjecture
Let $H(n, d)$ denote the maximum diameter of $d$-polyhedra with $n$ facets. There is a constant $k$ such that:

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H(n, d) \leq n^{k}, \quad \forall n, d .
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## "As simple as possible"

## Definition

A $d$-polytope/polyhedron is simple if at every vertex exactly $d$ facets meet. ( $\simeq$ facet-defining hyperplanes are "in general position").
A $d$-polytope is simplicial if every facet has exactly $d$ vertices. That is, if every proper face is a simplex. ( $\simeq$ vertices are "in general position").

Lemma (Klee 1964)
For every $n$ and $d$ the maximum diameter of $d$-polytopes
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## Lemma (Klee 1964)

For every $n$ and $d$ the maximum diameter of $d$-polytopes / $d$-polyhedra with $n$ facets is achieved at a simple one.

## "As simple as possible"

## Remark

We will often dualize the problem. We want to travel from one facet to another of a polytope $Q$ (the polar of $P$ ) along the "dual graph", whose edges correspond to ridges of $Q$.


By the Klee lemma we can restrict our attention to simplicial
polytopes; their face lattices are simplicial complexes with the topology of a $(d-1)$-sphere. (Simplicial $(d-1)$-spheres).

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Q: What is the polar of a (simple) unbounded polyhedron?
A: It must be a simplicial complex with the topology of a ball and with some "convexity constraint"


The polar of an unbounded $d$-polyhedron with $n$ facets "is" a regular triangulation of $n$ points in $\mathbb{R}^{d-1}$.

## The Klee-Walkup non-Hirsch (8,4)-polyhedron

Klee and Walkup proved:

## Theorem (Klee-Walkup 1967)

There is a 4-dimensional unbounded polyhedron with 8 facets and diameter 5.

Let us prove the following equivalent version:

Theorem
There is a regular triangulation of 8 points in $\mathbb{R}^{3}$ that has two tetrahedra at distance five from one another.

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## Proof.

This is a (Cayley Trick view of a) 3D triangulation with 8 vertices and diameter 4:


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This is a (Cayley Trick view of a) 3D triangulation with 8 vertices and diameter 4:


Three steps are needed to go from any light triangle to any dark triangle.

The Klee-Walkup non-Hirsch (8,4)-polyhedron

## Proof.

This is a (Cayley Trick view of a) 3D triangulation with 8 vertices and diameter 4:


Gluing two more tetrahedra (one on top, one on bottom), we get diameter 5.

## The Klee-Walkup Hirsch-sharp $(9,4)$-polytope

The counter-example to the unbounded Hirsch conjecture is equivalent to the existence of a 4 -polytope with 9 facets and with diameter 5 :

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## bounded Hirsch-sharp $\Rightarrow$ unbounded non-Hirsch

From a bounded (9,4)-polytope we get an unbounded (8,4)-polyhedron with (at least) the same diameter by projectively sending the " 9 th facet" to infinity. ( $9=n>2 d=8$ is needed)


## The Klee-Walkup Hirsch-sharp (9,4)-polytope

The counter-example to the unbounded Hirsch conjecture is equivalent to the existence of a 4-polytope with 9 facets and with diameter 5 :

## bounded Hirsch-sharp $\Leftarrow$ unbounded non-Hirsch

From an unbounded ( 8,4 )-polyhedron of diameter $>4$ we get a (9,4)-polytope with diameter (at least) 5 , by considering "infinity" a new facet $F$.


## Some known cases

Hirsch conjecture holds for

- d $\leq$ 3: [Klee 1966].
- $n-d \leq 6$ : [Klee-Walkup, 1967] [Bremner-Schewe, 2008]
- $H(9,4)=H(10,4)=5$ [Klee-Walkup, 1967]
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## Polynomial bounds, under perturbation

Given a linear program with $d$ variables and $n$ restrictions, we consider a random perturbation of the matrix, within a parameter $\epsilon$ (normal distribution).

Theorem [Spielman-Teng 2004] [Vershynin 2006]
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## The two best general bounds

Let $H(n, d):=$ max. diameter of a $d$-polyhedron with $n$ facets.

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\begin{aligned}
& \text { Theorem [Kalai-Kleitman 1992], "quasi-polynomial" } \\
& \qquad H(n, d) \leq n^{\log _{2} d+2}, \quad \forall n \text {, d. } \\
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## Normal simplicial complexes

## Definition

A pure simplicial complex is called normal if the dual graph of every link is connected. (That is, if every link is strongly connected)

The Kalai-Kleitman bound follows from the following recursion (where, now, $H(n, d)$ denotes the max. diameter among normal and pure simplicial ( $d-1$ )-complexes with $n$ vertices):


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## Proof.

Let $u, v$ be two simplices in a normal, pure simplic. complex $K$.

- For each $i \in \mathbb{N}$, let $U_{i}$ be the $i$-neighborhood of $u$ (the subcomplex consisting of all simplices at distance at most $i$ from $u$ ). Let $V_{j}$ the $j$-neighborhood of $V$.
- Let $i_{0}$ (resp. $j_{0}$ ) be the smallest value such that $U_{i_{0}}$ (resp. $V_{j_{0}}$ ) contains more than half of the vertices. This implies $i_{0}-1$ and $j_{0}-1$ are at most $H(\lfloor n / 2\rfloor, d)$.
- Let $u^{\prime} \in U_{i_{0}}$ and $v^{\prime} \in V_{j_{0}}$ having a common vertex. Then:

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\operatorname{dist}\left(u^{\prime}, v^{\prime}\right) \leq H(n-1, d-1)
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- So: $d(u, v) \leq \operatorname{dist}\left(u, u^{\prime}\right)+\operatorname{dist}\left(u^{\prime}, v^{\prime}\right)+\operatorname{dist}\left(v^{\prime}, v\right) \leq$

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## Why is $n-d$ a "reasonable" bound?

- It holds with equality in simplices $(n=d+1, \delta=1)$ and cubes ( $n=2 d, \delta=d$ ).
- If $P$ and $Q$ satisfy it, then so does $P \times Q: \delta(P \times Q)=$ $\delta(P)+\delta(Q)$. In particular:

For every $n \leq 2 d$, there are polytopes in which the bound is tight (products of simplices). We call these "Hirsch-sharp" polytopes.
a For every $n>d$, it is easy to construct unbounded polyhedra where the bound is tight.

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It is possible to go from $u$ to $v$ so that at each step we abandon a facet containing $u$ and we enter a facet containing $v$.
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## Two important remarks

The $d$-step Theorem follows from and implies (respectively) the following:

Lemma
For every d-polytope $P$ with $n$ facets and diameter $\delta$ there is a $d+1$-polytope with one more facet and the same diameter $\delta$.

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There is a function $f(k):=H(2 k, k)$ such that


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## Lemma

For every $d$-polytope $P$ with $n$ facets and diameter $\delta$ there is a $d+1$-polytope with one more facet and the same diameter $\delta$.

## Corollary

There is a function $f(k):=H(2 k, k)$ such that

$$
H(n, d) \leq f(n-d), \quad \forall n, d
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## Thank you

## TO BE CONTINUED

