



Common fixed point theorems for compatible and weakly compatible maps in Menger probabilistic G -metric spaces

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Abstract

In this paper, we prove some new common fixed point theorems for compatible and weakly compatible self-maps under ϕ -contractive conditions in Menger probabilistic G -metric spaces. Our results improve and generalize many comparable results in existing literature. Finally, an example is given as an application of our main results. ©2016 All rights reserved.

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1. Introduction

The concept of a probabilistic metric space was introduced and studied by Menger [10, 13]. Since then, many fixed point results for maps satisfying different contractive conditions have been studied [4, 5, 6, 15, 17]. Mustafa and Sims [12] defined the concept of a G -metric space and many fixed point theorems for contractive maps in G -metric spaces have been studied [1, 2]. Zhou et al. [16] defined the notion of a generalized probabilistic metric space (or a PGM -space), which was a generalization of a PM-space and a G -metric space. Since then, some results in Menger probabilistic G -metric spaces have been studied [18].

Jungck [7] initiated the concept of compatible maps in metric spaces and obtained some common fixed point theorems. In [8], the concept of weakly compatible maps was given. Mishra [11] introduced the concept of compatible maps in a Menger space, then, other authors have obtained many fixed point results for compatible maps and weakly compatible maps [3, 9, 14].

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In this paper, we first introduce the notion of compatible maps and weakly compatible maps in Menger probabilistic G -metric spaces. Then, we prove some new common fixed point theorems for compatible maps and weakly compatible maps satisfying ϕ -contractive conditions in Menger probabilistic G -metric spaces with a continuous t -norm Δ of H -type. As an application, we present an example to illustrate the validity of our main results. Our results generalize the results of [3] and many other results in corresponding literatures.

2. Preliminaries

Let \mathbb{R} denote the set of reals, \mathbb{R}^+ the nonnegative reals and \mathbb{Z}^+ be the set of all positive integers. A mapping $F : \mathbb{R} \rightarrow \mathbb{R}^+$ is called a distribution function if it is nondecreasing and left continuous with $\inf_{t \in \mathbb{R}} F(t) = 0$ and $\sup_{t \in \mathbb{R}} F(t) = 1$. We will denote by \mathcal{D} the set of all distribution functions, while H will always denote the specific distribution function defined by

$$H(t) = \begin{cases} 0, & t \leq 0, \\ 1, & t > 0. \end{cases}$$

A mapping $\Delta : [0, 1] \times [0, 1] \rightarrow [0, 1]$ is called a triangular norm (for short, a t -norm) if the following conditions are satisfied:

- (1) $\Delta(a, 1) = a$;
- (2) $\Delta(a, b) = \Delta(b, a)$;
- (3) $a \geq b, c \geq d \Rightarrow \Delta(a, c) \geq \Delta(b, d)$;
- (4) $\Delta(a, \Delta(b, c)) = \Delta(\Delta(a, b), c)$.

A typical example of a t -norm is Δ_{\min} , where $\Delta_{\min}(a, b) = \min\{a, b\}$, for each $a, b \in [0, 1]$.

Definition 2.1 ([5]). A t -norm Δ is said to be of H -type if the family of functions $\{\Delta^m(t)\}_{m=1}^{\infty}$ is equicontinuous at $t = 1$, where

$$\Delta^1(t) = \Delta(t, t), \quad \Delta^m(t) = \Delta(t, \Delta^{m-1}(t)), \quad \text{for } m = 2, 3, \dots, t \in [0, 1].$$

The t -norm Δ_{\min} is a trivial example of H -type, but there are other t -norms Δ of H -type with $\Delta \neq \Delta_{\min}$ (see, e.g., [5]).

Definition 2.2 ([12]). Let X be a nonempty set and $G : X \times X \times X \rightarrow \mathbb{R}^+$ be a function satisfying the following conditions:

- (G-1) $G(x, y, z) = 0$ if $x = y = z$ for all $x, y, z \in X$;
- (G-2) $G(x, x, y) > 0$ for all $x, y \in X$ with $x \neq y$;
- (G-3) $G(x, x, y) \leq G(x, y, z)$ for all $x, y, z \in X$ with $z \neq y$;
- (G-4) $G(x, y, z) = G(x, z, y) = G(y, z, x) = \dots$ for all $x, y, z \in X$;
- (G-5) $G(x, y, z) \leq G(x, a, a) + G(a, y, z)$ for all $x, y, z, a \in X$.

Then G is called a generalized metric or a G -metric on X and the pair (X, G) is a G -metric space.

Definition 2.3 ([16]). A Menger probabilistic G -metric space (shortly, a PGM -space) is a triple (X, G^*, Δ) , where X is a nonempty set, Δ is a continuous t -norm and G^* is a mapping from $X \times X \times X$ into \mathcal{D} ($G_{x,y,z}^*$ denotes the value of G^* at the point (x, y, z)) satisfying the following conditions:

- (PGM-1) $G_{x,y,z}^*(t) = 1$ for all $x, y, z \in X$ and $t > 0$ if and only if $x = y = z$;
- (PGM-2) $G_{x,x,y}^*(t) \geq G_{x,y,z}^*(t)$ for all $x, y, z \in X$ with $z \neq y$ and $t > 0$;
- (PGM-3) $G_{x,y,z}^*(t) = G_{x,z,y}^*(t) = G_{y,x,z}^*(t) = \dots$ (symmetry in all three variables);
- (PGM-4) $G_{x,y,z}^*(t+s) \geq \Delta(G_{x,a,a}^*(s), G_{a,y,z}^*(t))$ for all $x, y, z, a \in X$ and $s, t \geq 0$.

Example 2.4. Let (X, G) be a G -metric space. Define a mapping $G^* : X \times X \times X \rightarrow \mathcal{D}$ by

$$G^*(x, y, z)(t) = G_{x,y,z}^*(t) = H(t - G(x, y, z)) \quad (2.1)$$

for $x, y, z \in X$ and $t > 0$. Then (X, G^*, Δ) is a Menger PGM -space called the induced Menger PGM -space by (X, G) .

Definition 2.5 ([16]). Let (X, G^*, Δ) be a Menger PGM-space and x_0 be any point in X . For any $\epsilon > 0$ and δ with $0 < \delta < 1$, and (ϵ, δ) -neighborhood of x_0 is the set of all points y in X for which $G_{x_0,y,y}^*(\epsilon) > 1 - \delta$ and $G_{y,x_0,x_0}^*(\epsilon) > 1 - \delta$. We write

$$N_{x_0}(\epsilon, \delta) = \{y \in X : G_{x_0,y,y}^*(\epsilon) > 1 - \delta, G_{y,x_0,x_0}^*(\epsilon) > 1 - \delta\},$$

which means that $N_{x_0}(\epsilon, \delta)$ is the set of all points y in X for which the probability of the distance from x_0 to y being less than ϵ is greater than $1 - \delta$.

Definition 2.6 ([16]). Let (X, G^*, Δ) be a PGM-space, $\{x_n\}$ is a sequence in X .

- (1) $\{x_n\}$ is said to be convergent to a point $x \in X$ (write $x_n \rightarrow x$), if for any $\epsilon > 0$ and $0 < \delta < 1$, there exists a positive integer $M_{\epsilon,\delta}$ such that $x_n \in N_{x_0}(\epsilon, \delta)$ whenever $n > M_{\epsilon,\delta}$;
- (2) $\{x_n\}$ is called a *Cauchy* sequence, if for any $\epsilon > 0$ and $0 < \delta < 1$, there exists a positive integer $M_{\epsilon,\delta}$ such that $G_{x_n,x_m,x_l}^*(\epsilon) > 1 - \delta$ whenever $n, m, l > M_{\epsilon,\delta}$;
- (3) (X, G^*, Δ) is said to be complete if every *Cauchy* sequence in X converges to a point in X .

Definition 2.7. Let $\phi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ be a function and $\phi^n(t)$ be the n th iteration of $\phi(t)$,

- (i) ϕ is non-decreasing;
- (i)' ϕ is strictly increasing;
- (ii) ϕ is upper semi-continuous from the right;
- (iii) $\sum_{n=0}^{\infty} \phi^n(t) < +\infty$ and $\phi(t) < t/2$ for all $t > 0$.

We define Φ_0 the class of functions $\phi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ satisfying conditions (i), (ii), (iii) and Φ_1 the class of functions $\phi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ satisfying conditions (i)', (ii), (iii).

Definition 2.8 ([4]). Let $F_1, F_2 \in \mathcal{D}$. The algebraic sum $F_1 \oplus F_2$ of F_1 and F_2 is defined by

$$(F_1 \oplus F_2)(t) = \sup_{t_1+t_2=t} \min\{F_1(t_1), F_2(t_2)\},$$

for all $t \in \mathbb{R}$.

We can analogously prove the following lemma as in Menger PM-spaces.

Lemma 2.9. Let (X, G^*, Δ) be a Menger PGM-space with Δ a continuous t -norm, $\{x_n\}$, $\{y_n\}$ and $\{z_n\}$ be sequences in X and $x, y, z \in X$, if $\{x_n\} \rightarrow x$, $\{y_n\} \rightarrow x$ and $\{z_n\} \rightarrow x$ as $n \rightarrow \infty$. Then

- (1) $\liminf_{n \rightarrow \infty} G_{x_n,y_n,z_n}^*(t) \geq G_{x,y,z}^*(t)$ for all $t > 0$;
- (2) $G_{x,y,z}^*(t + o) \geq \limsup_{n \rightarrow \infty} G_{x_n,y_n,z_n}^*(t)$ for all $t > 0$.

Lemma 2.10 ([5]). Let (X, G^*, Δ) be a Menger PGM-space. For each $\lambda \in (0, 1]$, define a function G_λ^* by

$$G_\lambda^*(x, y, z) = \inf_t \{t \geq 0 : G_{x,y,z}^*(t) > 1 - \lambda\} \tag{2.2}$$

for any $x, y, z \in X$, then

- (1) $G_\lambda^*(x, y, z) < t$ if and only if $G_{x,y,z}^*(t) > 1 - \lambda$;
- (2) $G_\lambda^*(x, y, z) = 0$ for all $\lambda \in (0, 1]$ if and only if $x = y = z$;
- (3) $G_\lambda^*(x, y, z) = G_\lambda^*(y, x, z) = G_\lambda^*(y, z, x) = \dots$;
- (4) If $\Delta = \Delta_{\min}$, then for every $\lambda \in (0, 1]$, $G_\lambda^*(x, y, z) \leq G_\lambda^*(x, a, a) + G_\lambda^*(a, y, z)$.

Lemma 2.11 ([18]). Let (X, G^*, Δ) be a Menger PGM-space and let $\{G_\lambda^*\}$, $\lambda \in (0, 1]$ be a family of functions on X defined by (2.2). If Δ is a t -norm of H -type, then for each $\lambda \in (0, 1]$, there exists $\mu \in [0, \lambda]$, such that for each $m \in \mathbb{Z}^+$,

$$G_\lambda^*(x_0, x_m, x_m) \leq \sum_{i=0}^{m-1} G_\mu^*(x_i, x_{i+1}, x_{i+1}),$$

$$G_\lambda^*(x_0, x_0, x_m) \leq \sum_{i=0}^{m-1} G_\mu^*(x_i, x_i, x_{i+1})$$

for all $x_0, x_1, \dots, x_m \in X$.

Lemma 2.12 ([18]). *Let (X, G^*, Δ) be a Menger PGM-space and Δ be a continuous t -norm. Then the following statements are equivalent:*

- (i) *the sequence $\{x_n\}$ is a Cauchy sequence;*
- (ii) *for any $\epsilon > 0$ and $0 < \lambda < 1$, there exists $M \in \mathbb{Z}^+$ such that $G_{x_n, x_m, x_m}^*(\epsilon) > 1 - \lambda$, for all $n, m > M$.*

3. Main results

In this section, we will establish some new common fixed point theorems for compatible maps and weakly compatible maps in Menger PGM-spaces. To this end, we first introduce the concepts of compatible maps and weakly compatible maps in Menger PGM-spaces.

Definition 3.1. Let S and T be two self-maps of a Menger PGM-space (X, G^*, Δ) . S and T are said to be compatible if $G_{STx_n, TSx_n, TSx_n}^*(t) \rightarrow 1$ and $G_{STx_n, STx_n, TSx_n}^*(t) \rightarrow 1$ for all $t > 0$ whenever $\{x_n\}$ is a sequence in X such that $\lim_{n \rightarrow \infty} Sx_n = \lim_{n \rightarrow \infty} Tx_n = u$ for some $u \in X$.

Definition 3.2. Let S and T be two self-maps of a Menger PGM-space (X, G^*, Δ) . S and T are said to be weakly compatible (or coincidentally commuting) if they commute at their coincidence points, i.e., if $Tu = Su$ for some $u \in X$ implies that $TSu = STu$.

The following lemmas will be useful in proving our main results.

Lemma 3.3. *Let $\{y_n\}$ be a sequence in a Menger PGM-space (X, G^*, Δ) , where Δ is a t -norm of H -type. If there exists a function $\phi \in \Phi_0$, such that*

$$G_{y_n, y_{n+1}, y_{n+1}}^*(\phi(t)) \geq \min\{G_{y_{n-1}, y_n, y_n}^*(t), G_{y_n, y_{n+1}, y_{n+1}}^*(t)\} \tag{3.1}$$

for all $t > 0$ and $n \in \mathbb{Z}^+$. Then $\{y_n\}$ is a Cauchy sequence in X .

Proof. Let $\{G_\lambda^*\}$, $\lambda \in (0, 1]$ be the family of pseudo-metrics defined by (2.2). For each $\lambda \in (0, 1]$ and $n \in \mathbb{Z}^+$, putting $a_n = G_\lambda^*(y_{n-1}, y_n, y_n)$, we will prove that

$$a_{n+1} \leq \phi(a_n) \tag{3.2}$$

for all $n \in \mathbb{Z}^+$. In fact, since ϕ is upper semi-continuous from the right, for given $\epsilon > 0$ and each a_n , there exist $p_n > a_n$ such that $\phi(p_n) < \phi(a_n) + \epsilon$. By Lemma 2.10, it follows from $p_n > a_n = G_\lambda^*(y_{n-1}, y_n, y_n)$ that $G_{y_{n-1}, y_n, y_n}^*(p_n) > 1 - \lambda$ for all $n \in \mathbb{Z}^+$. Thus, by (3.1), we get

$$G_{y_n, y_{n+1}, y_{n+1}}^*(\phi(\max\{p_n, p_{n+1}\})) \geq \min\{G_{y_{n-1}, y_n, y_n}^*(p_n), G_{y_n, y_{n+1}, y_{n+1}}^*(p_{n+1})\} > 1 - \lambda.$$

Similarly by Lemma 2.10, we can have

$$G_\lambda^*(y_n, y_{n+1}, y_{n+1}) < \phi(\max\{p_n, p_{n+1}\}) = \max\{\phi(p_n), \phi(p_{n+1})\} \leq \phi(\max\{a_n, a_{n+1}\}) + \epsilon.$$

By the arbitrariness of ϵ , we have

$$a_{n+1} = G_\lambda^*(y_n, y_{n+1}, y_{n+1}) \leq \phi(\max\{a_n, a_{n+1}\}). \tag{3.3}$$

So, we can infer that $a_{n+1} \leq a_n$. If not, then by (3.3), we have $a_{n+1} \leq \phi(a_{n+1}) < a_{n+1}/2 < a_{n+1}$, which is a contradiction. Hence, (3.3) implies that $a_{n+1} \leq \phi(a_n)$, and (3.2) is proved.

Repeatedly using (3.2), we get

$$G_\lambda^*(y_n, y_{n+1}, y_{n+1}) \leq \phi(G_\lambda^*(y_{n-1}, y_n, y_n)) \leq \dots \leq \phi^n(G_\lambda^*(y_0, y_1, y_1)) \tag{3.4}$$

for all $n \in \mathbb{Z}^+$. Noting that Δ is a t -norm of H -type. By Lemma 2.11, for each $\lambda \in (0, 1]$, there exists $\mu \in (0, \lambda]$, such that

$$G_\lambda^*(y_n, y_m, y_m) \leq \sum_{i=n}^{m-1} G_\mu^*(y_i, y_{i+1}, y_{i+1}) \tag{3.5}$$

for all $m, n \in \mathbb{Z}^+$ with $m > n$. Since $\phi \in \Phi_0$, we have $\phi^n(G_\mu^*(y_0, y_1, y_1)) < +\infty$. So for given $\epsilon > 0$, there exists $n_0 \in \mathbb{Z}^+$ such that $\sum_{i=n}^\infty \phi^n(G_\mu^*(y_0, y_1, y_1)) < \epsilon$ for all $n \geq n_0$. Thus, it follows from (3.5) that

$$G_\lambda^*(y_n, y_m, y_m) \leq \sum_{i=n}^\infty \phi^n(G_\mu^*(y_0, y_1, y_1)) < \epsilon$$

for all $n \geq n_0$, which implies that $G_{y_n, y_m, y_m}^*(\epsilon) > 1 - \lambda$ for all $m, n \in \mathbb{Z}^+$ with $m > n \geq n_0$. By Lemma 2.12, $\{y_n\}$ is a *Cauchy* sequence in X . □

Lemma 3.4. *Let (X, G^*, Δ) be a Menger PGM-space and $x, y \in X$. If there exists $\phi \in \Phi_0$, such that*

$$G_{x,y,y}^*(\phi(t) + o) \geq G_{x,y,y}^*(t/2) \tag{3.6}$$

for all $t > 0$. Then $x = y$.

Proof. Let $\lambda \in (0, 1]$ and we put $a/2 = G_\lambda^*(x, y, y)$. Since $\phi(\cdot)$ is upper semi-continuous from the right at the point a , for given $\epsilon > 0$, there exists $s > a$ such that $\phi(s) < \phi(a) + \epsilon$. By Lemma 2.10, $s/2 > G_\lambda^*(x, y, y)$ implies that $G_{x,y,y}^*(s/2) > 1 - \lambda$. So, it follows from (3.6) that

$$G_{x,y,y}^*(\phi(s) + \epsilon) \geq G_{x,y,y}^*(\phi(s) + o) \geq G_{x,y,y}^*(s/2) > 1 - \lambda$$

which implies that $G_\lambda^*(x, y, y) < \phi(s) + \epsilon < \phi(a) + 2\epsilon$. By the arbitrariness of ϵ , we get $a/2 = G_\lambda^*(x, y, y) \leq \phi(a)$, thus $a = 0$, i.e., $G_\lambda^*(x, y, y) = 0$. By (2) of Lemma 2.10, we conclude that $x = y$. □

Lemma 3.5. *Let (X, G^*, Δ_{\min}) be a Menger PGM-space. Suppose that there exists a function $\phi \in \Phi$, such that*

$$G_{x,y,y}^*(\phi(t) + o) \geq \min\{G_{x,y,y}^*(t), G_{y,x,x}^*(t)\}. \tag{3.7}$$

Then $x = y$.

Proof. We know that

$$G_{y,x,x}^*(t) = G_{x,y,x}^*(t) \geq \Delta(G_{x,y,y}^*(t/2), G_{y,y,x}^*(t/2)) \geq G_{x,y,y}^*(t/2).$$

Since ϕ is upper-continuous from the right, it follows from (3.7) that

$$G_{x,y,y}^*(\phi(t) + o) \geq \min\{G_{x,y,y}^*(t), G_{x,y,y}^*(t/2)\} = G_{x,y,y}^*(t/2).$$

Then by Lemma 3.4, we can conclude that $x = y$. □

We are now ready to give our main results.

Theorem 3.6. *Let L, M, P and Q be self-maps on a complete Menger PGM-space (X, G^*, Δ_{\min}) , If the following conditions are satisfied:*

- (i) $L(X) \subseteq Q(X)$, $M(X) \subseteq P(X)$;
- (ii) either P or L is continuous;
- (iii) (L, P) is compatible and (M, Q) is weakly compatible;
- (iv) there exists $\phi \in \Phi_0$, such that

$$G_{Lx, My, My}^*(\phi(t)) \geq \min\{G_{Px, Lx, Lx}^*(t), G_{Qy, My, My}^*(t), G_{Px, Qy, Qy}^*(t), G_{Qy, Lx, Lx}^*(\beta t), [G_{Px, \xi, \xi}^* \oplus G_{\xi, My, My}^*]((2 - \beta)t)\} \tag{3.8}$$

for all $x, y, \xi \in X$, $\beta \in (0, 2)$ and $t > 0$. Then L, M, P and Q have a unique common fixed point in X .

Proof. Let $x_0 \in X$. From condition (i), there exist $x_1, x_2 \in X$, such that $Lx_0 = Qx_1 = y_0$ and $Mx_1 = Px_2 = y_1$. Inductively, we can construct two sequences $\{x_n\}$ and $\{y_n\}$ in X , such that

$$Lx_{2n} = Qx_{2n+1} = y_{2n}, \quad Mx_{2n+1} = Px_{2n+2} = y_{2n+1}, \quad n = 0, 1, 2, \dots$$

• Assume that there exists $\phi \in \Phi_0$, such that (3.8) holds. Putting $x = x_{2n}$, $y = y_{2n+1}$, $\xi = y_{2n}$ in (3.8), we get

$$\begin{aligned} G_{y_{2n}, y_{2n+1}, y_{2n+1}}^*(\phi(t)) &= G_{Lx_{2n}, Mx_{2n+1}, Mx_{2n+1}}^*(\phi(t)) \\ &\geq \min\{G_{Px_{2n}, Lx_{2n}, Lx_{2n}}^*(t), G_{Qx_{2n+1}, Mx_{2n+1}, Mx_{2n+1}}^*(t), G_{Px_{2n}, Qx_{2n+1}, Qx_{2n+1}}^*(t), \\ &\quad G_{Qx_{2n+1}, Lx_{2n}, Lx_{2n}}^*(\beta t), [G_{Px_{2n}, y_{2n}, y_{2n}}^* \oplus G_{y_{2n}, Mx_{2n+1}, Mx_{2n+1}}^*]((2 - \beta)t)\} \\ &\geq \min\{G_{y_{2n-1}, y_{2n}, y_{2n}}^*(t), G_{y_{2n}, y_{2n+1}, y_{2n+1}}^*(t), G_{y_{2n-1}, y_{2n}, y_{2n}}^*((2 - \beta)/2), \\ &\quad G_{y_{2n}, y_{2n+1}, y_{2n+1}}^*((2 - \beta)/2)\}. \end{aligned}$$

Letting $\beta \rightarrow 0$, we obtain

$$G_{y_{2n}, y_{2n+1}, y_{2n+1}}^*(\phi(t)) \geq \min\{G_{y_{2n-1}, y_{2n}, y_{2n}}^*(t), G_{y_{2n}, y_{2n+1}, y_{2n+1}}^*(t)\}. \tag{3.9}$$

Similarly, we can prove that

$$G_{y_{2n+1}, y_{2n+2}, y_{2n+2}}^*(\phi(t)) \geq \min\{G_{y_{2n}, y_{2n+1}, y_{2n+1}}^*(t), G_{y_{2n+1}, y_{2n+2}, y_{2n+2}}^*(t)\}. \tag{3.10}$$

It follows from (3.9) and (3.10) that

$$G_{y_n, y_{n+1}, y_{n+1}}^*(\phi(t)) \geq \min\{G_{y_{n-1}, y_n, y_n}^*(t), G_{y_n, y_{n+1}, y_{n+1}}^*(t)\}, \quad n = 1, 2, \dots$$

By Lemma 3.3, we know that $\{y_n\}$ is a *Cauchy* sequence in X . Since (X, G^*, Δ) is complete, we can assume that $y_n \rightarrow z \in X$, and so

$$\lim_{n \rightarrow \infty} Lx_{2n} = \lim_{n \rightarrow \infty} Px_{2n} = \lim_{n \rightarrow \infty} Qx_{2n+1} = \lim_{n \rightarrow \infty} Mx_{2n+1} = z. \tag{3.11}$$

Now we prove z is a common fixed point of L, M, P and Q .

Case I. Suppose that P is continuous. By (3.11) we have $PLx_{2n} \rightarrow Pz$ and $PPx_{2n} \rightarrow Pz$. Noting that (L, P) is compatible, we get $G_{LPx_{2n}, PLx_{2n}, PLx_{2n}}^*(t) \rightarrow 1$ for all $t > 0$, and thus

$$G_{LPx_{2n}, Pz, Pz}^*(t) \geq \Delta(G_{LPx_{2n}, PLx_{2n}, PLx_{2n}}^*(t/2), G_{PLx_{2n}, Pz, Pz}^*(t/2)) \rightarrow 1, \quad (n \rightarrow \infty)$$

which shows that $LPx_{2n} \rightarrow Pz (n \rightarrow \infty)$.

We first prove that z is a fixed point of P and L . Putting $x = Px_{2n}$, $y = x_{2n+1}$, $\xi = LPx_{2n}$ and $\beta = 1$ in (3.8), we get

$$\begin{aligned} &G_{LPx_{2n}, Mx_{2n+1}, Mx_{2n+1}}^*(\phi(t)) \\ &\geq \min\{G_{PPx_{2n}, LPx_{2n}, LPx_{2n}}^*(t), G_{Qx_{2n+1}, Mx_{2n+1}, Mx_{2n+1}}^*(t), G_{PPx_{2n}, Qx_{2n+1}, Qx_{2n+1}}^*(t), \\ &\quad G_{Qx_{2n+1}, LPx_{2n}, LPx_{2n}}^*(t), [G_{PPx_{2n}, LPx_{2n}, LPx_{2n}}^* \oplus G_{LPx_{2n}, Mx_{2n+1}, Mx_{2n+1}}^*](t)\} \\ &\geq \min\{G_{PPx_{2n}, LPx_{2n}, LPx_{2n}}^*(t), G_{Qx_{2n+1}, Mx_{2n+1}, Mx_{2n+1}}^*(t), G_{PPx_{2n}, Qx_{2n+1}, Qx_{2n+1}}^*(t), \\ &\quad G_{Qx_{2n+1}, LPx_{2n}, LPx_{2n}}^*(t), G_{PPx_{2n}, LPx_{2n}, LPx_{2n}}^*(\epsilon), G_{LPx_{2n}, Mx_{2n+1}, Mx_{2n+1}}^*(t - \epsilon)\}, \end{aligned}$$

where $\epsilon \in (0, t)$. Letting $n \rightarrow \infty$, by Lemma 2.9, we get

$$G_{Pz, z, z}^*(\phi(t) + o) \geq \min\{1, 1, G_{Pz, z, z}^*(t), G_{z, Pz, Pz}^*(t), 1, G_{Pz, z, z}^*(t - \epsilon)\}.$$

Letting $\epsilon \rightarrow 0$, we get

$$G_{Pz,z,z}^*(\phi(t) + o) \geq \min\{G_{Pz,z,z}^*(t), G_{z,Pz,Pz}^*(t)\},$$

which implies that $Pz = z$ by Lemma 3.3.

Putting $x = \xi = z$, $y = x_{2n+1}$ and $\beta = 1$ in (3.8), we get

$$\begin{aligned} G_{Lz,Mx_{2n+1},Mx_{2n+1}}^*(\phi(t)) &\geq \min\{G_{Pz,Lz,Lz}^*(t), G_{Qx_{2n+1},Mx_{2n+1},Mx_{2n+1}}^*(t), G_{Pz,Qx_{2n+1},Qx_{2n+1}}^*(t), \\ &\quad G_{Qx_{2n+1},Lz,Lz}^*(t), [G_{Pz,z,z}^* \oplus G_{z,Mx_{2n+1},Mx_{2n+1}}^*](t)\} \\ &= \min\{G_{Pz,Lz,Lz}^*(t), G_{Qx_{2n+1},Mx_{2n+1},Mx_{2n+1}}^*(t), G_{Pz,Qx_{2n+1},Qx_{2n+1}}^*(t), \\ &\quad G_{Qx_{2n+1},Lz,Lz}^*(t), G_{z,Mx_{2n+1},Mx_{2n+1}}^*(t)\}. \end{aligned}$$

Letting $n \rightarrow \infty$, by Lemma 2.9, we get

$$G_{Lz,z,z}^*(\phi(t) + o) \geq \min\{G_{z,Lz,Lz}^*(t), 1, 1, G_{z,Lz,Lz}^*(t), 1\} = G_{z,Lz,Lz}^*(t) \geq G_{Lz,z,z}^*(t/2)$$

for all $t > 0$. By Lemma 3.4, we conclude that $Lz = z$. Therefore, z is a common fixed point of P and L .

Next, from $Lz = z$ and (3.11), we can prove that z is also a common fixed point of M and Q , i.e., $Mz = Qz = z$.

In fact, since $L(X) \subseteq Q(X)$, there exists $v \in X$, such that $z = Lz = Qv$. Putting $x = x_{2n}$, $y = v$, $\xi = z$ and $\beta = 1$ in (3.8), we get

$$\begin{aligned} G_{Lx_{2n},Mv,Mv}^*(\phi(t)) &\geq \min\{G_{Px_{2n},Lx_{2n},Lx_{2n}}^*(t), G_{Qv,Mv,Mv}^*(t), G_{Px_{2n},Qv,Qv}^*(t), \\ &\quad G_{Qv,Lx_{2n},Lx_{2n}}^*(t), [G_{Px_{2n},z,z}^* \oplus G_{z,Mv,Mv}^*](t)\} \\ &\geq \min\{G_{Px_{2n},Lx_{2n},Lx_{2n}}^*(t), G_{Qv,Mv,Mv}^*(t), G_{Px_{2n},Qv,Qv}^*(t), \\ &\quad G_{Qv,Lx_{2n},Lx_{2n}}^*(t), G_{Px_{2n},z,z}^*(\epsilon), G_{z,Mv,Mv}^*(t - \epsilon)\}. \end{aligned}$$

Letting $n \rightarrow \infty$, by Lemma 2.9, we get

$$G_{z,Mv,Mv}^*(\phi(t) + o) \geq \min\{1, G_{z,Mv,Mv}^*(t), 1, 1, 1, G_{z,Mv,Mv}^*(t - \epsilon)\} = G_{z,Mv,Mv}^*(t - \epsilon)$$

for all $t > 0$ and $\epsilon \in (0, t)$. Letting $\epsilon \rightarrow 0$, we obtain $Mv = z$ by Lemma 3.4. So, we have $Qv = z = Mv$, i.e., v is a coincidence point of Q and M . Since (M, Q) is weakly compatible, we have $MQv = QMv$, and thus $Mz = Qz = z$. Therefore, z is a common fixed point of L , M , P and Q .

Case II. Suppose that L is continuous. Noting that $Lx_{2n} \rightarrow z$ and $Px_{2n} \rightarrow z$. We have $LLx_{2n} \rightarrow Lz$ and $LPx_{2n} \rightarrow Lz$. Since (L, P) is compatible, we have $G_{PLx_{2n},LPx_{2n},LPx_{2n}}^*(t) \rightarrow 1$ for all $t > 0$. From this fact, it is easy to prove that $PLx_{2n} \rightarrow Lz$. Putting $x = Lx_{2n}$, $y = x_{2n+1}$, $\xi = Lz$ and $\beta = 1$ in (3.8), we get

$$\begin{aligned} G_{LLx_{2n},Mx_{2n+1},Mx_{2n+1}}^*(\phi(t)) &\geq \min\{G_{PLx_{2n},LLx_{2n},LLx_{2n}}^*(t), G_{Qx_{2n+1},Mx_{2n+1},Mx_{2n+1}}^*(t), G_{PLx_{2n},Qx_{2n+1},Qx_{2n+1}}^*(t), \\ &\quad G_{Qx_{2n+1},LLx_{2n},LLx_{2n}}^*(t), [G_{PLx_{2n},Lz,Lz}^* \oplus G_{Lz,Mx_{2n+1},Mx_{2n+1}}^*](t)\} \\ &\geq \min\{G_{PLx_{2n},LLx_{2n},LLx_{2n}}^*(t), G_{Qx_{2n+1},Mx_{2n+1},Mx_{2n+1}}^*(t), G_{PLx_{2n},Qx_{2n+1},Qx_{2n+1}}^*(t), \\ &\quad G_{Qx_{2n+1},LLx_{2n},LLx_{2n}}^*(t), G_{PLx_{2n},Lz,Lz}^*(\epsilon), G_{Lz,Mx_{2n+1},Mx_{2n+1}}^*(t - \epsilon)\} \end{aligned}$$

for all $t > 0$ and $\epsilon \in (0, t)$. Letting $n \rightarrow \infty$, by Lemma 2.9, we get

$$G_{Lz,z,z}^*(\phi(t) + o) \geq \min\{1, 1, G_{Lz,z,z}^*(t), G_{z,Lz,Lz}^*(t), 1, G_{Lz,z,z}^*(t - \epsilon)\}.$$

Letting $\epsilon \rightarrow 0$, it follows that

$$G_{Lz,z,z}^*(\phi(t) + o) \geq \min\{G_{Lz,z,z}^*(t), G_{z,Lz,Lz}^*(t)\}$$

for all $t > 0$, which implies that $Lz = z$.

In the same way as in Case I, from $Lz = z$ and (3.11), it is not difficult to prove that $Mz = Qz = z$. Next, we only need to show that $Pz = z$.

Since $M(X) \subseteq P(X)$, there exists $w \in X$, such that $z = Mz = Pw$. Putting $x = w$, $y = x_{2n+1}$, $\xi = z$ and $\beta = 1$ in (3.8), we get

$$\begin{aligned} G_{Lw, Mx_{2n+1}, Mx_{2n+1}}^*(\phi(t)) &\geq \min\{G_{Pw, Lw, Lw}^*(t), G_{Qx_{2n+1}, Mx_{2n+1}, Mx_{2n+1}}^*(t), G_{Pw, Qx_{2n+1}, Qx_{2n+1}}^*(t), \\ &\quad G_{Qx_{2n+1}, Lw, Lw}^*(t), [G_{Pw, z, z}^* \oplus G_{z, Mx_{2n+1}, Mx_{2n+1}}^*](t)\} \\ &\geq \min\{G_{Pw, Lw, Lw}^*(t), G_{Qx_{2n+1}, Mx_{2n+1}, Mx_{2n+1}}^*(t), G_{Pw, Qx_{2n+1}, Qx_{2n+1}}^*(t), \\ &\quad G_{Qx_{2n+1}, Lw, Lw}^*(t), G_{z, Mx_{2n+1}, Mx_{2n+1}}^*(t)\}. \end{aligned}$$

Letting $n \rightarrow \infty$, by Lemma 2.9, we get

$$G_{Lw, z, z}^*(\phi(t) + o) \geq \min\{G_{z, Lw, Lw}^*(t), 1, 1, G_{z, Lw, Lw}^*(t), 1\} = G_{z, Lw, Lw}^*(t) \geq G_{Lw, z, z}^*(t/2)$$

for all $t > 0$, which implies that $Lw = z = Pw$. Noting that (L, P) is compatible and so it is also weakly compatible. Hence $Pz = PLw = LPw = Lz = z$. This shows that z is a common fixed point of L, M, P , and Q .

Finally, we show the uniqueness. Let u be another common fixed point of L, M, P , and Q . Then $Lu = Mu = Pu = Qu = u$. Putting $x = \xi = z$, $y = u$ and $\beta = 1$ in (3.8), we get

$$\begin{aligned} G_{z, u, u}^*(\phi(t)) &= G_{Lz, Mu, Mu}^*(\phi(t)) \\ &\geq \min\{G_{Pz, Lz, Lz}^*(t), G_{Qu, Mu, Mu}^*(t), G_{Pz, Qu, Qu}^*(t), \\ &\quad G_{Qu, Lz, Lz}^*(t), [G_{Pz, z, z}^* \oplus G_{z, Mu, Mu}^*](t)\} \\ &\geq \min\{1, 1, G_{z, u, u}^*(t), G_{u, z, z}^*(t), G_{z, u, u}^*(t)\} \\ &= \min\{G_{z, u, u}^*(t), G_{u, z, z}^*(t)\}, \end{aligned}$$

which implies that $z = u$. Therefore, z is a unique common fixed point of L, M, P , and Q . □

Taking $\phi(t) = kt$ in Theorem 3.6, where $k \in (0, 1/2)$ is a constant, we get the following consequence.

Corollary 3.7. *Let L, M, P and Q be self-maps on a complete Menger PGM-space (X, G^*, Δ_{\min}) , satisfying conditions (i)-(iii) in Theorem 3.6 and the following*

(iv)' there exists a constant $k \in (0, 1/2)$, such that

$$\begin{aligned} G_{Lx, My, My}^*(kt) &\geq \min\{G_{Px, Lx, Lx}^*(t), G_{Qy, My, My}^*(t), G_{Px, Qy, Qy}^*(t), \\ &\quad G_{Qy, Lx, Lx}^*(\beta t), [G_{Px, \xi, \xi}^* \oplus G_{\xi, My, My}^*]((2 - \beta)t)\} \end{aligned} \tag{3.12}$$

for all $x, y, \xi \in X$, $\beta \in (0, 2)$ and $t > 0$. Then L, M, P and Q have a unique common fixed point in X .

Corollary 3.8. *Let L, M, P and Q be self-maps on a complete Menger PGM-space (X, G^*, Δ_{\min}) , satisfying conditions (i)-(iii) in Theorem 3.6 and the following:*

(iv)'' there exists $k \in (0, 1/2)$ such that

$$\begin{aligned} G_{Lp, Mq, Mq}^*(kx) &\geq \min\{G_{Pp, Lp, Lp}^*(x), G_{Qq, Mq, Mq}^*(x), G_{Pp, Qq, Qq}^*(x), \\ &\quad G_{Qq, Lp, Lp}^*(\beta x), G_{Pp, Mq, Mq}^*((2 - \beta)x)\} \end{aligned} \tag{3.13}$$

for all $p, q \in X$, $\beta \in (0, 2)$ and $x > 0$. Then L, M, P and Q have a unique common fixed point in X .

Proof. By (PGM-4), we have

$$G_{Pp, My, My}^*(t) \geq \sup_{0 < s < t} \min\{G_{Px, \xi, \xi}^*(s), G_{\xi, My, My}^*(t - s)\} = [G_{Px, \xi, \xi}^* \oplus G_{\xi, My, My}^*](t)$$

for all $x, y, \xi \in X$, $t > 0$. Hence, it is not difficult to see that (3.13) implies (3.12). So, the conclusion of Corollary 3.8 follows from Corollary 3.7 immediately. □

Taking $P = Q = I$ (the identity mapping on X), $L = A$, $M = B$ in Theorem 3.6, we have the following corollary.

Corollary 3.9. *Let A and B be self-maps on a complete Menger PGM-space (X, G^*, Δ_{\min}) . If there exists a function $\phi \in \Phi_0$, such that*

$$G_{Ax,By,By}^*(\phi(t)) \geq \min\{G_{x,Ax,Ax}^*(t), G_{y,By,By}^*(t), G_{x,y,y}^*(t), G_{y,Ax,Ax}^*(t), [G_{x,\xi,\xi}^* \oplus G_{\xi,By,By}^*]((2 - \beta)t)\}$$

for all $x, y, \xi \in X$, $\beta \in (0, 2)$, $t > 0$. Then A and B have a unique common fixed point in X .

Theorem 3.10. *Let A, B, S, T, L and M be self-maps on a complete Menger PGM-space (X, G^*, Δ_{\min}) , satisfying the following conditions:*

- (i) $L(X) \subseteq ST(X)$, $M(X) \subseteq AB(X)$;
- (ii) $AB = BA$, $ST = TS$, $LB = BL$, $MT = TM$;
- (iii) either AB or L is continuous;
- (iv) (L, AB) is compatible and (M, ST) is weakly compatible;
- (v) there exists $\phi \in \Phi_0$, such that

$$G_{Lx,My,My}^*(\phi(t)) \geq \min\{G_{ABx,Lx,Lx}^*(t), G_{STy,My,My}^*(t), G_{ABx,STy,STy}^*(t), G_{STy,Lx,Lx}^*(\beta t), [G_{ABx,\xi,\xi}^* \oplus G_{\xi,My,My}^*]((2 - \beta)t)\} \tag{3.14}$$

for all $x, y, \xi \in X$, $\beta \in (0, 2)$, $t > 0$. Then A, B, S, T, L and M have a unique common fixed point in X .

Proof. Putting $P = AB$ and $Q = ST$, it is easy to see that conditions (i) and (iii)-(v) of the theorem imply conditions (i)-(iv) of Theorem 3.6. Therefore, by Theorem 3.6, L, M, P and Q have a unique common fixed point z in X , i.e.,

$$Lz = Mz = Pz = Qz = z. \tag{3.15}$$

Now, we prove that z is a common fixed point of A and B . By (3.15) and condition (ii), we have $LBz = BLz = Bz$ and $PBz = (AB)Bz = (BA)Bz = B(AB)z = BPz = Bz$. thus, by condition (iv) of Theorem 3.6, putting $x = \xi = Bz$, $y = z$ and $\beta = 1$ in (3.8), we get

$$\begin{aligned} G_{Bz,z,z}^*(\phi(t)) &= G_{LBz,Mz,Mz}^*(\phi(t)) \\ &\geq \min\{G_{PBz,LBz,LBz}^*(t), G_{Qz,Mz,Mz}^*(t), G_{PBz,Qz,Qz}^*(t), \\ &\quad G_{Qz,LBz,LBz}^*(t), [G_{PBz,Bz,Bz}^* \oplus G_{Bz,Mz,Mz}^*](t)\} \\ &\geq \min\{1, 1, G_{Bz,z,z}^*(t), G_{z,Bz,Bz}^*(t), G_{Bz,z,z}^*(t)\} \\ &= \min\{G_{Bz,z,z}^*(t), G_{z,Bz,Bz}^*(t)\}, \end{aligned}$$

which implies that $Bz = z$, and so $z = Pz = ABz = Az$. Therefore, z is a common fixed point of A and B .

We next prove that z is also a fixed point of T and S . In fact, by (3.15) and condition (ii), we have $MTz = TMz = Tz$ and $QTz = (ST)Tz = (TS)Tz = TQz = Tz$. Putting $x = \xi = z$, $y = Tz$ and $\beta = 1$ in (3.8), we get

$$\begin{aligned} G_{z,Tz,Tz}^*(\phi(t)) &= G_{Lz,MTz,MTz}^*(\phi(t)) \\ &\geq \min\{G_{Pz,Lz,Lz}^*(t), G_{QTz,MTz,MTz}^*(t), G_{Pz,QTz,QTz}^*(t), \\ &\quad G_{QTz,Lz,Lz}^*(t), [G_{Pz,z,z}^* \oplus G_{z,MTz,MTz}^*](t)\} \\ &\geq \min\{1, 1, G_{z,Tz,Tz}^*(t), G_{Tz,z,z}^*(t), G_{z,Tz,Tz}^*(t)\} \\ &= \min\{G_{z,Tz,Tz}^*(t), G_{Tz,z,z}^*(t)\}, \end{aligned}$$

which implies that $Tz = z$, and so $Sz = STz = Qz = z$. This shows that z is also a common fixed point of T and S . Therefore, z is a common fixed point of A, B, S, T, L and M . Since z is a unique common fixed point of P, Q, L and M , it is easy to see that z is also a unique common fixed point of A, B, S, T, L and M . This completes the proof. □

Remark 3.11. We can also obtain Theorem 3.6 by putting $B = T = I$ and $S = Q$ and $A = P$ in Theorem 3.10. Therefore, Theorem 3.6 and Theorem 3.10 are equivalent.

Taking $\phi(t) = kt$ in Theorem 3.10, where $k \in (0, 1/2)$ is a constant, we get the following consequence.

Corollary 3.12. *Let A, B, S, T, L and M be self-maps on a complete Menger PGM-space (X, G^*, Δ_{\min}) , satisfying the conditions (i)-(iv) of Theorem 3.10 and the following:*

(v)' *there exists $k \in (0, 1/2)$, such that*

$$G_{Lx, My, My}^*(kt) \geq \min\{G_{ABx, Lx, Lx}^*(t), G_{STy, My, My}^*(t), G_{ABx, STy, STy}^*(t), G_{STy, Lx, Lx}^*(\beta t), [G_{ABx, \xi, \xi}^* \oplus G_{\xi, My, My}^*]((2 - \beta)t)\}$$
(3.16)

for all $x, y, \xi \in X, \beta \in (0, 2)$ and $t > 0$. Then A, B, S, T, L and M have a unique common fixed point in X .

Corollary 3.13. *Let A, B, S, T, L and M be self-maps on a complete Menger PGM-space (X, G^*, Δ) , satisfying the conditions (i)-(iv) of Theorem 3.10 and the following:*

(v)'' *there exists $k \in (0, 1/2)$, such that*

$$G_{Lx, My, My}^*(kt) \geq \min\{G_{ABx, Lx, Lx}^*(t), G_{STy, My, My}^*(t), G_{ABx, STy, STy}^*(t), G_{STy, Lx, Lx}^*(\beta t), G_{ABx, My, My}^*((2 - \beta)t)\}$$
(3.17)

for all $x, y, \xi \in X, \beta \in (0, 2)$ and $t > 0$. Then A, B, S, T, L and M have a unique common fixed point in X .

Proof. We know that $G_{ABx, My, My}^*(t) \geq [G_{ABx, \xi, \xi}^* \oplus G_{\xi, My, My}^*](t)$ for all $x, y, \xi \in X$ and $t > 0$. Hence, it is not difficult to see that (3.17) in Corollary 3.13 implies (3.16) in Corollary 3.12, and so the conclusion of Corollary 3.13 follows from Corollary 3.12 immediately. □

Theorem 3.14. *Let $P_1, P_2, \dots, P_{2n}, Q_0$ and Q_1 be self-maps on a complete Menger PGM-space (X, G^*, Δ_{\min}) , satisfying conditions:*

- (i) $Q_0(X) \subseteq P_1 P_3 \cdots P_{2n-1}(X), Q_1(X) \subseteq P_2 P_4 \cdots P_{2n}(X);$
- (ii) $P_2(P_4 \cdots P_{2n}) = (P_4 \cdots P_{2n})P_2,$
 $P_2 P_4(P_6 \cdots P_{2n}) = (P_6 \cdots P_{2n})P_2 P_4,$
 \vdots
 $P_2 \cdots P_{2n-1}(P_{2n}) = (P_{2n})P_2 \cdots P_{2n-1},$
 $Q_0(P_4 \cdots P_{2n}) = (P_4 \cdots P_{2n})Q_0,$
 $Q_0(P_6 \cdots P_{2n}) = (P_6 \cdots P_{2n})Q_0,$
 \vdots
 $Q_0(P_{2n}) = (P_{2n})Q_0,$
 $P_1(P_3 \cdots P_{2n-1}) = (P_3 \cdots P_{2n-1})P_1,$
 $P_1 P_3(P_5 \cdots P_{2n-1}) = (P_5 \cdots P_{2n-1})P_1 P_3,$
 \vdots
 $P_1 \cdots P_{2n-3}(P_{2n-1}) = (P_{2n-1})P_1 \cdots P_{2n-3},$
 $Q_1(P_3 \cdots P_{2n-1}) = (P_3 \cdots P_{2n-1})Q_1,$
 $Q_1(P_5 \cdots P_{2n-1}) = (P_5 \cdots P_{2n-1})Q_1,$
 \vdots
 $Q_1 P_{2n-1} = P_{2n-1} Q_1;$

- (iii) either $P_2 \cdots P_{2n}$ or Q_0 is continuous;
- (iv) $(Q_0, P_2 \cdots P_{2n})$ is compatible and $(Q_1, P_1 \cdots P_{2n-1})$ is weakly compatible;
- (v) there exists $\phi \in \Phi_0$, such that

$$G_{Q_0x, Q_1y, Q_1y}^*(\phi(t)) \geq \min\{G_{P_2P_4 \cdots P_{2n}x, Q_0x, Q_0x}^*(t), G_{P_1P_3 \cdots P_{2n-1}y, Q_1y, Q_1y}^*(t), G_{P_2P_4 \cdots P_{2n}x, P_1P_3 \cdots P_{2n-1}y, P_1P_3 \cdots P_{2n-1}y}^*(t), G_{P_1P_3 \cdots P_{2n-1}y, Q_0x, Q_0x}^*(\beta t), [G_{P_2P_4 \cdots P_{2n}x, \xi, \xi}^* \oplus G_{\xi, Q_1y, Q_1y}^*]((2 - \beta)t)\} \tag{3.18}$$

for all $x, y, \xi \in X$, $\beta \in (0, 2)$ and $t > 0$. Then $P_1, P_2, \dots, P_{2n}, Q_0$ and Q_1 have a unique common fixed point in X .

Proof. The proof is similar to that of Theorem 3.10. □

4. Common fixed point theorems in G -metric spaces

In this section, we shall use the obtained results in Section 3 to get some corresponding fixed point theorems for compatible and weakly compatible maps in G -metric spaces.

Theorem 4.1. *Let L, M, P and Q be self-maps on a complete G -metric space (X, G) satisfying the following conditions:*

- (i) $L(X) \subseteq Q(X)$, $M(X) \subseteq P(X)$;
- (ii) either P or L is continuous;
- (iii) (L, P) is compatible and (M, Q) is weakly compatible;
- (iv) there exists $\phi \in \Phi_1$, such that for all $x, y, \in X$,

$$G(Lx, My, My) \leq \phi(G(x, y, y)),$$

where

$$G(x, y, y) = \max\{G(Px, Lx, Lx), G(Qy, My, My), G(Px, Qy, Qy), [G(Qy, Lx, Lx) + G(Px, My, My)]/2\}.$$

Then L, M, P and Q have a unique common fixed point in X .

Proof. Let (X, G^*, Δ_{\min}) be the induced Menger PGM-space by (X, G) , where G^* is defined by (2.1). It is easy to see that conditions (i)-(iii) of Theorem 4.1 imply conditions (i)-(iii) of Theorem 3.6, respectively. It remains to prove that condition (iv) of Theorem 4.1 implies condition (iv) of Theorem 3.10.

By (2.1), we know that the value of each function $G_{u,v,v}^*(\cdot)$ ($u, v \in X$) in the induced Menger PGM-space only can equal 0 or 1. Hence, without loss of generality, we may assume that

$$\min\{G_{Px, Lx, Lx}^*(t), G_{Qy, My, My}^*(t), G_{Px, Qy, Qy}^*(t), G_{Qy, Lx, Lx}^*(\beta t), [G_{Px, \xi, \xi}^* \oplus G_{\xi, My, My}^*]((2 - \beta)t)\} = 1.$$

This implies that

$$G(Px, Lx, Lx) < t, \quad G(Qy, My, My) < t, \quad G(Px, Qy, Qy) < t$$

and

$$G(Qy, Lx, Lx) < \beta t, \quad G(Px, My, My) < (2 - \beta)t. \tag{4.1}$$

It follows from (4.1) that implies that $[G(Qy, Lx, Lx) + G(Px, My, My)]/2 < t$. Thus, we have $G(x, y, y) < t$. Noting that ϕ is strictly increasing, by condition (iv) we get $G(Lx, My, My) \leq \phi(G(x, y, y)) < \phi(t)$, which implies that $G_{Lx, My, My}^*(\phi(t)) = 1$. Hence inequality (3.8) holds, i.e., condition (iv) of Theorem 3.6 is satisfied. Therefore, the conclusion follows from Theorem 3.6 immediately. □

In the same way, by Theorem 3.10, we can prove the following theorem.

Theorem 4.2. *Let A, B, S, T, L and M be self-maps on a complete G -metric space (X, G) satisfying the following conditions:*

- (i) $L(X) \subseteq ST(X), M(X) \subseteq AB(X)$;
- (ii) $AB = BA, ST = TS, LB = BL, MT = TM$;
- (iii) either AB or L is continuous;
- (iv) (L, AB) is compatible and (M, ST) is weakly compatible;
- (v) there exists $\phi \in \Phi_1$, such that for all $x, y \in X$,

$$G(Lx, My, My) \leq \phi(G_1(x, y, y)),$$

where

$$G_1(x, y, y) = \min\{G(ABx, Lx, Lx), G(STy, My, My), G(ABx, STy, STy), [G(STy, Lx, Lx) + G(ABx, My, My)]/2\}.$$

Then A, B, S, T, L and M have a unique common fixed point in X .

Taking $P = Q = I, L = A, M = B$ in Theorem 4.1, we get the following consequence.

Corollary 4.3. *Let A and B be self-maps on a complete G -metric space (X, G) , if that there exists $\phi \in \Phi_1$, such that*

$$G(Ax, By, By) \leq \phi(\max\{G(x, Ax, Ax), G(y, By, By), G(x, y, y), [G(y, Ax, Ax) + G(x, By, By)]/2\})$$

for all $x, y \in X$. Then A and B have a unique common fixed point in X .

5. An application

In this section, we provide an example to illustrate the validity of Theorem 3.6.

Example 5.1. Let $X = [0, 1]$. Define a function $G^* : X^3 \times [0, 1] \rightarrow [0, 1]$ by $G_{x,y,z}^*(t) = \frac{t}{t+G(x,y,z)}$, where $G(x, y, z) = |x - y| + |y - z| + |z - x|$, for all $x, y, z \in X$, and $t > 0$. It is easy to verify that (X, G^*, Δ_{\min}) is a Menger PGM-space. Define L, M, P and $Q: X \rightarrow X$ as follows

$$Lx = \frac{1}{8}x, \quad Mx = \begin{cases} 0, & x \in [0, \frac{1}{2}), \\ \frac{1}{7}, & x \in [\frac{1}{2}, 1]. \end{cases}$$

$$Px = \frac{1}{2}x, \quad Qx = \begin{cases} \frac{1}{3}x, & x \in [0, \frac{1}{2}), \\ 1, & x \in [\frac{1}{2}, 1]. \end{cases}$$

Let $\phi(t) = \frac{3}{7}t$. Then it is obvious that $\phi \in \Phi_0$. Consider the sequence $\{x_n = \frac{1}{n}\}$ in X , then

$$\lim_{n \rightarrow \infty} Lx_n = \lim_{n \rightarrow \infty} Px_n = 0.$$

We can verify that $G_{LPx_n, PLx_n, PLx_n}^*(t) \rightarrow 1$ and $G_{PLx_n, LPx_n, LPx_n}^*(t) \rightarrow 1$ for all $t > 0$. So (L, P) is compatible. Also, (M, Q) is weakly compatible.

On the other hand, if $x \in [0, 1]$ and $y \in [0, \frac{1}{2})$, then for any $t > 0$, we have

$$G_{Lx, My, My}^*(\frac{3}{7}t) = \frac{t}{t + \frac{7}{12}x} > \frac{t}{t + \frac{3}{4}x} = G_{Px, Lx, Lx}^*(t)$$

$$\geq \min\{G_{Px, Lx, Lx}^*(t), G_{Qy, My, My}^*(t), G_{Px, Qy, Qy}^*(t), G_{Qy, Lx, Lx}^*(\beta t), [G_{Px, \xi, \xi}^* \oplus G_{\xi, My, My}^*]((2 - \beta)t)\}.$$

If $x \in [0, 1]$ and $y \in [\frac{1}{2}, 1]$, then for any $t > 0$, we have

$$\begin{aligned} G_{Lx, My, My}^*\left(\frac{3}{7}t\right) &= \frac{t}{t + \frac{2}{3} - \frac{7}{12}x} > \frac{t}{t + \frac{3}{4}x} = G_{Px, Lx, Lx}^*(t) \\ &\geq \min\{G_{Px, Lx, Lx}^*(t), G_{Qy, My, My}^*(t), G_{Px, Qy, Qy}^*(t), G_{Qy, Lx, Lx}^*(\beta t), \\ &\quad [G_{Px, \xi, \xi}^* \oplus G_{\xi, My, My}^*]((2 - \beta)t)\}. \end{aligned}$$

Thus, all the conditions of Theorem 3.6 are satisfied and 0 is the unique common fixed point in X .

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