

On the derivations of gametic algebras for polyploidy with multiple alleles

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1. Introduction

1.1. In this paper we obtain some results concerning derivations of a class of genetic algebras. Let us set down our terminology and notation.

First of all, our base field is the field \mathbb{R} of real numbers. All genetic algebras are algebras over this field and "algebra" means \mathbb{R} -algebra, "linear mapping" means " \mathbb{R} -linear mapping". We adopt Gonshor's definition: A genetic algebra is a commutative algebra for which there exists a basis C_0, C_1, \dots, C_n with a multiplication table satisfying the following conditions:

If $C_i C_j = \sum_{k=0}^n \lambda_{ijk} C_k$ ($i, j = 0, \dots, n$) then:

- (i) $\lambda_{000} = 1$
- (ii) $\lambda_{0jk} = 0$ if $k < j$
- (iii) for $i > 0$ and $j > 0$, $\lambda_{ijk} = 0$ if $k \leq \max \{i, j\}$.

Any basis of A , satisfying conditions (i), (ii) and (iii), is called a canonical basis of A . In general, A may have many canonical bases.

It is well known ([10]) that, for a given genetic algebra A , there exists a unique non-zero homomorphism of algebras $w: A \rightarrow \mathbb{R}$. This homomorphism is defined by $w(C_0) = 1$ and $w(C_i) = 0$ ($i \geq 1$) and it is called the weight function of A . The algebra A is then a baric algebra. The kernel of w , which is an n -dimensional ideal of A , has C_1, \dots, C_n as a basis. This ideal will be indicated by N .

It is known that the numbers $\lambda_{000} = 1, \lambda_{011}, \dots, \lambda_{0nn}$ are, in fact, independent of the canonical basis of A . They are called the train roots or shortly the t -roots of A . The proof of this consists in the observation that these numbers are the proper values of all the linear mappings $x \mapsto bx$, where b is an arbitrary element of weight 1.

The concept of genetic algebra was introduced by Etherington ([1], [2]) in order to investigate the behavior of gametic and zygotic populations, in the case of diploid and tetraploid individuals with one locus and two alleles. Later, Gonshor ([3], [4]) carried these investigations to cover the case of multiallelism and polyploidy with mutations. He showed, in particular, that the gametic and zygotic algebra of such a population is a genetic algebra. Nowadays, many genetic systems are described by such algebras ([10]).

1.2. Let us indicate by $G(n+1, 2m)$ the gametic algebra of a $2m$ -ploid population with $n+1$ alleles, which we shall denote here by A_0, A_1, \dots, A_n . This algebra has a natural basis consisting of all monomials of degree m in the "variables" A_0, A_1, \dots, A_n . Each one of these monomials represents one of the gametic types of the population. The multiplication of two of these monomials is an algebraic representation of the distribution of gametic types obtained by the mating of the gametic types corresponding to the given monomials. The number of such monomials is $\binom{m+n}{n}$, the binomial number, and so the dimension of $G(n+1, 2m)$ is $\binom{n+m}{m}$. The basis consisting of these monomials is not a canonical basis of $G(n+1, 2m)$ but the set of monomials $A_0^{i_0} (A_0 - A_1)^{i_1} \dots (A_0 - A_n)^{i_n}$ with $i_0 + i_1 + \dots + i_n = m$ in the variables $A_0, A_0 - A_1, \dots, A_0 - A_n$ is a canonical basis, as shown by Gonshor ([4]). He showed that these monomials form a canonical basis, where the multiplication table is given by:

$$\begin{aligned} & [A_0^{i_0} (A_0 - A_1)^{i_1} \dots (A_0 - A_n)^{i_n}] [A_0^{j_0} (A_0 - A_1)^{j_1} \dots (A_0 - A_n)^{j_n}] \\ &= \begin{cases} \binom{2m}{m}^{-1} \binom{i_0+j_0}{m} A_0^{i_0+j_0-m} (A_0 - A_1)^{i_1+j_1} \dots (A_0 - A_n)^{i_n+j_n} & \text{if } i_0 + j_0 \geq m \\ 0 & \text{if } i_0 + j_0 < m. \end{cases} \end{aligned}$$

In particular,

$$A_0^m (A_0^{j_0} (A_0 - A_1)^{j_1} \dots (A_0 - A_n)^{j_n}) = \binom{2m}{m}^{-1} \binom{m+j_0}{m} A_0^{j_0} (A_0 - A_1)^{j_1} \dots (A_0 - A_n)^{j_n}$$

and so the t -roots of $G(n+1, 2m)$ are the real numbers $\binom{2m}{m}^{-1} \binom{m+j}{m}$ for $j = m, m-1, \dots, 1, 0$ (in this order). The t -root $\binom{2m}{m}^{-1} \binom{m+j}{m}$ of $G(n+1, 2m)$ has multiplicity $\binom{m-j+n}{m-j}^{-1}$, cf. Gonshor [4]; this is the number of monomials of degree $m-j$ in $(n+1)-1 = n$ variables; or, what is the same, the algebraic multiplicity of the proper value $\binom{2m}{m}^{-1} \binom{m+j}{m}$ of the linear mapping $x \mapsto A_0^m x$, $x \in G(n+1, 2m)$. Especially for $n=1$, i.e., two alleles in the locus under consideration, all t -roots are simple.

Of special importance in genetics are the algebras $G(n+1, 2)$ and $G(2, 2m)$. They correspond to multiallelism and polyploidy respectively. We give some emphasis to these two sequences of gametic algebras.

1.3. Given an algebra A over the real field \mathbb{R} , a derivation of A is a linear mapping $d : A \rightarrow A$ such that $d(ab) = ad(b) + d(a)b$ for any a, b in A . If d_1 and d_2 are derivations of A , the linear mapping $d_1 d_2 - d_2 d_1$ is also a derivation of A . So the set of all derivations of A may be equipped with the operation $(d_1, d_2) \rightarrow d_1 d_2 - d_2 d_1$. This set of derivations is a real Lie algebra, called the derivation algebra of A (cf. [8]).

We shall be concerned here with finding a basis of the derivation algebra of $G(n+1, 2m)$. It should be interesting to find the genetic interpretations of the results presented here.

2. Multiallelism only

In this case, the algebras $G(n+1, 2)$ describe the gametic population of a diploid and multiallelic population. The natural basis of $G(n+1, 2)$ is the set of monomials of degree 1, namely A_0, A_1, \dots, A_n . The multiplication table is $A_i A_j = 1/2 A_i + 1/2 A_j$, which reads genetically as "the gametes produced by a zygote resulting from the mating of gametes A_i and A_j will be A_i and A_j , with equal probability". One canonical basis is defined by $C_0 = A_0$, $C_i = A_0 - A_i$ ($i \geq 1$) and now the multiplication table is $C_0^2 = C_0$, $C_0 C_i = 1/2 C_i$, $C_i C_j = 0$ if $i \geq 1$ and $j \geq 1$. The t -roots of $G(n+1, 2)$ are $1, 1/2, 1/2, \dots, 1/2$. The weight function w of $G(n+1, 2)$ is given by $w(C_0) = 1$, $w(C_i) = 0$ ($i \geq 1$) or by $w(A_i) = 1$ ($i = 0, 1, \dots, n$). It is well known that $G(n+1, 2)$ satisfies the polynomial equation $x^2 = w(x)x$ for every x in $G(n+1, 2)$. This identity may be linearized to give the two variables identity $2xy = w(x)y + w(y)x$.

We prove in this paragraph that $G(n+1, 2)$ has the greatest derivation algebra among all genetic algebras of dimension $n+1$ and is the only with this property. First of all, we consider the class of baric (commutative) algebras which have a unique weight function.

Theorem 1. *Let A be a baric algebra having a unique weight function w . For every derivation d of A we have $wod = 0$.*

Proof. Call σ_t the automorphism of A defined by

$$\sigma_t = 1_A + td + \frac{t^2 d^2}{2!} + \dots + \frac{t^n d^n}{n!} + \dots = e^{td},$$

for each real number t (Jacobson [8]) where 1_A is the identity of A . Hence $w \circ \sigma_t$ is an algebra homomorphism from A to \mathbb{R} , and is clearly non zero. By our hypothesis, $w \circ \sigma_t = w$, for all $t \in \mathbb{R}$. If we take derivatives in both sides of this equality we obtain $w \circ d\sigma_t/dt = 0$; in particular, when $t = 0$, we have $wod = 0$.

Corollary 1. Let A be a baric algebra of dimension $n+1$ with unique weight homomorphism. Then the dimension of the derivation algebra of A is not greater than $n(n+1)$. In particular for every genetic algebra of dimension $n+1$, its derivation algebra has dimension not greater than $n(n+1)$.

Proof. Each derivation maps A into the kernel of the weight function, which has dimension n .

Corollary 2. Let A be a baric algebra with a unique weight function w . Then the derivation algebra of A can be identified with a subalgebra of the Lie algebra of matrices (a_{ij}) ($0 \leq i, j \leq n$) such that $a_{0i} = 0$ ($i = 0, \dots, n$).

Proof. Construct a basis c_0, c_1, \dots, c_n of A such that $w(c_0) = 1$ and $w(c_i) = 0$ ($i = 1, \dots, n$). For each derivation d of A , $d(c_i)$ doesn't depend on c_0 .

Proposition 1. The derivations of $G(n+1, 2)$ are exactly those linear mappings d such that $w \circ d = 0$.

Proof. It is enough to prove that, if $w \circ d = 0$ then d is a derivation of $G(n+1, 2)$. In fact, if $x, y \in G(n+1, 2)$, then $2d(xy) = d(2xy) = d(w(x)y + w(y)x) = w(x)d(y) + w(y)d(x) = w(x)d(y) + xw(d(y)) + w(y)d(x) + yw(d(x)) = 2xd(y) + 2d(x)y$ and so $d(xy) = d(x)y + xd(y)$.

Proposition 2. Let A_0, A_1, \dots, A_n be the natural basis of $G(n+1, 2)$ and let d_{ij} ($i \neq j$) be defined by

$$d_{ij}(A_k) = \begin{cases} A_i - A_j & \text{if } k = i \\ 0 & \text{otherwise.} \end{cases}$$

Then the elements d_{ij} ($i \neq j, 0 \leq i, j \leq n$) form a basis of the derivation algebra of $G(n+1, 2)$.

Proof. By Prop. 1, each d_{ij} is a derivation. It is enough to prove that they are linearly independent. Suppose $\lambda_{ij} \in \mathbb{R}$ and $\sum \lambda_{ij} d_{ij} = 0$ (here $i, j = 0, 1, \dots, n$ and $i \neq j$). Then for a fixed k ,

$$0 = \sum_{\substack{i,j \\ i \neq j}} \lambda_{ij} d_{ij}(A_k) = \sum_{\substack{j=0 \\ j \neq k}}^n \lambda_{kj} d_{kj}(A_k) = \sum_{\substack{j=0 \\ j \neq k}}^n \lambda_{kj} (A_k - A_j) \text{ and}$$

so $\left(\sum_{\substack{j=0 \\ j \neq k}}^n \lambda_{kj} \right) A_k = \sum_{\substack{j=0 \\ j \neq k}}^n \lambda_{kj} A_j$. By comparing coefficients we get $\lambda_{kj} = 0$.

The condition $wod = 0$, which characterizes the derivations of $G(n+1, 2)$, is still characteristic for the derivations of this algebra in the

sense of the following theorem, which is similar to a theorem of Gonshor [4], giving $G(n+1, 2)$ as the only (up to isomorphism) baric algebra of dimension $n+1$ such that every linear mapping preserving weight is a homomorphism of algebras.

Theorem 2. Let A be a commutative baric algebra of dimension $n+1$, with weight function w . Suppose that every linear mapping $d: A \rightarrow A$ such that $wod = 0$, is a derivation of A . Then A is (isomorphic to) $G(n+1, 2)$.

Proof. We will show that every element $a \in A$ such that $w(a) = 1$ is an idempotent. In fact, given $a \in A$ with $w(a) = 1$, consider $d_a: A \rightarrow A$ given by $d_a(x) = w(x)a - x$. We have $w(d_a(x)) = w(w(x)a - x) = w(x)w(a) - w(x) = 0$. Hence, by our hypothesis, d_a is a derivation. Hence $d_a(a^2) = 2ad_a(a)$. But $d_a(a^2) = w(a^2)a - a^2 = a - a^2$ and $d_a(a) = w(a)a - a = 0$. Hence $a = a^2$. Taking now a basis A_0, A_1, \dots, A_n of A such that $w(A_i) = 1$, we have $w(1/2(A_i + A_j)) = 1$ and so $1/2(A_i + A_j) = [1/2(A_i + A_j)]^2$ from what follows $A_i A_j = 1/2 A_i + 1/2 A_j$ and the isomorphism is clear.

3. Polyploidy only

In this case, the algebras $G(2, 2m)$ describe the gametic population corresponding to a $2m$ -ploid and diallelic population. The natural basis of $G(2, 2m)$ is the set of monomials of degree m in the two variables A_0 and A_1 . They are $A_0^m, A_0^{m-1} A_1, \dots, A_0 A_1^{m-1}, A_1^m$, so the dimension of $G(2, 2m)$ is $m+1$. The product of two of such monomials is given by

$$(A_0^i A_1^{m-i})(A_0^j A_1^{m-j}) = \binom{2m}{m}^{-1} \sum_{k=0}^m \binom{i+j}{k} \binom{2m-i-j}{m-k} A_0^k A_1^{m-k}$$

which is an algebraic way of expressing the distribution of probability for the gametes produced by the zygote obtained by mating the gametes $A_0^i A_1^{m-i}$ and $A_0^j A_1^{m-j}$.

A canonical basis for $G(2, 2m)$ is the set of monomials $A_0^i (A_0 - A_1)^{m-i}$ ($0 \leq i \leq m$), with multiplication given by

$$\begin{aligned} & [A_0^i (A_0 - A_1)^{m-i}] [A_0^j (A_0 - A_1)^{m-j}] = \\ & = \begin{cases} \binom{2m}{m}^{-1} \binom{i+j}{m} A_0^{i+j-m} (A_0 - A_1)^{2m-i-j} & \text{if } i+j \geq m \\ 0 & \text{otherwise.} \end{cases} \end{aligned}$$

If we call $A_0^m = c_0, A_0^{m-1} (A_0 - A_1) = c_1, \dots, (A_0 - A_1)^m = c_m$ then we have $c_i c_j = \binom{2m}{i+j}^{-1} \binom{m}{i+j} c_{i+j}$ if $i+j \leq m$ and 0 otherwise. The t -roots are $t_i = \binom{2m}{i}^{-1} \binom{m}{i}$ ($i = 0, 1, \dots, m$) and so $1 = t_0 > t_1 = 1/2 > t_2 > \dots > t_m$.

We construct a derivation δ of $G(2, 2m)$ by defining δ to be the linear mapping $\delta(c_i) = ic_i (i = 0, 1, \dots, m)$. It is easy to verify that δ is indeed a derivation.

A second derivation η is defined in the following way:

$$\eta(c_i) = \frac{t_{i+1}}{t_i - t_{i+1}} c_{i+1} \text{ for } 0 \leq i \leq m-1 \text{ and } \eta(c_m) = 0.$$

(Observe that η is nilpotent). In order to prove that η is a derivation, it is enough to prove that $\eta(c_i c_j) = c_i \eta(c_j) + \eta(c_i) c_j$ holds for all i and j . If $i + j > m$ then $c_i c_j = 0$ so $\eta(c_i c_j) = 0$; on the other hand,

$$\eta(c_i) c_j + c_i \eta(c_j) = \frac{t_{i+1}}{t_i - t_{i+1}} c_{i+1} c_j + \frac{t_{j+1}}{t_j - t_{j+1}} c_i c_{j+1} = 0$$

because $i + j + 1 > m$. If $i + j = m$, then $\eta(c_i c_j) = \eta(c_0 c_m) = \eta(t_m c_m) = t_m \eta(c_m) = 0$ and $c_i \eta(c_j) + \eta(c_i) c_j = c_i \frac{t_{j+1}}{t_j - t_{j+1}} c_{j+1} + \frac{t_{i+1}}{t_i - t_{i+1}} c_{i+1} c_j = 0$ again because $i + j + 1 = m + 1 > m$. Now for the case $i + j < m$, we must observe that the sequence $t_1/(t_0 - t_1), t_2/(t_1 - t_2), \dots, t_m/(t_{m-1} - t_m)$ is nothing but the sequence $1, 1 - 1/m, 1 - 2/m, \dots, 1/m$. With this, we have

$$\eta(c_i c_j) = \eta(c_0 c_{i+j}) = \eta(t_{i+j} c_{i+j}) =$$

$$= t_{i+j} \frac{t_{i+j+1}}{t_{i+j} - t_{i+j+1}} c_{i+j+1} \text{ and } \eta(c_i) c_j + c_i \eta(c_j) =$$

$$= \frac{t_{i+1}}{t_i - t_{i+1}} c_{i+1} c_j + \frac{t_{j+1}}{t_j - t_{j+1}} c_i c_{j+1} = \left(\frac{t_{i+1}}{t_i - t_{i+1}} + \frac{t_{j+1}}{t_j - t_{j+1}} \right) c_0 c_{i+j+1} =$$

$$= \left(\frac{t_{i+1}}{t_i - t_{i+1}} + \frac{t_{j+1}}{t_j - t_{j+1}} \right) t_{i+j+1} c_{i+j+1}. \text{ We must prove that}$$

$$\frac{t_{i+j}}{t_{i+j} - t_{i+j+1}} = \frac{t_{i+1}}{t_i - t_{i+1}} + \frac{t_{j+1}}{t_j - t_{j+1}}. \text{ We have } \frac{t_{i+j}}{t_{i+j} - t_{i+j+1}} =$$

$$= \frac{t_{i+j+1} - t_{i+j+1} + t_{i+j}}{t_{i+j} - t_{i+j+1}} = 1 + \frac{t_{i+j+1}}{t_{i+j} - t_{i+j+1}} = \frac{t_{i+1}}{t_i - t_{i+1}} + \frac{t_{j+1}}{t_j - t_{j+1}}$$

(because in any arithmetic sequence $\alpha_1, \alpha_2, \dots$ we have $\alpha_1 + \alpha_{i+j+1} = \alpha_{i+1} + \alpha_{j+1}$). This proves that η is a derivation of $G(2, 2m)$.

It is also clear that δ and η are linearly independent.

Theorem 3. Every derivation d of $G(2, 2m)$ is a linear combination of δ and η . Precisely, if α_{10} and α_{11} are the components of $d(c_0)$ and $d(c_1)$ in the direction of c_1 , then $d = \alpha_{10}\eta + \alpha_{11}\delta$.

Proof. First of all, we recall that for any derivation d of $G(2, 2m)$, we have $wod = 0$, where w is the weight function of $G(2, 2m)$. This implies that for $0 \leq j \leq m$, $d(c_j)$ is a linear combination of c_1, \dots, c_m , say $d(c_j) = \sum_{i=1}^m \alpha_{ij} c_i$. From $c_0^2 = c_0$ (again!) we have

$$\sum_{i=1}^m \alpha_{i0} c_i = d(c_0) = 2c_0 d(c_0) = 2c_0 \left(\sum_{i=1}^m \alpha_{i0} c_i \right) = \sum_{i=1}^m 2\alpha_{i0} c_0 c_i = \sum_{i=1}^m 2\alpha_{i0} t_i c_i.$$

Comparing coefficients and remembering that $t_1 = 1/2$ and $t_i < 1/2$ for $i \geq 2$, we conclude that α_{10} is arbitrary but $\alpha_{20} = \alpha_{30} = \dots = \alpha_{m0} = 0$. This means that

$$(1) \quad d(c_0) = \alpha_{10} c_1$$

From the equality $c_0 c_1 = t_1 c_1$ we get, applying d ,

$$\alpha_{10} c_1 c_1 + c_0 \left(\sum_{i=1}^m \alpha_{i1} c_i \right) = t_1 \left(\sum_{i=1}^m \alpha_{i1} c_i \right) \text{ or}$$

$\alpha_{10} t_2 c_2 + \sum_{i=1}^m \alpha_{i1} t_i c_i = \sum_{i=1}^m \alpha_{i1} t_1 c_i$. The comparison of coefficients gives the relations:

$$\begin{cases} \alpha_{10} t_2 + \alpha_{21} t_2 = \alpha_{21} t_1 \\ \alpha_{i1} t_i = \alpha_{i1} t_1 \quad (i > 2), \end{cases}$$

from which we deduce that $\alpha_{21} = t_2/(t_1 - t_2) \alpha_{10}$ and $\alpha_{i1} = 0$ for $i > 2$. Hence:

$$(2) \quad d(c_1) = \alpha_{11} c_1 + \alpha_{10} \frac{t_2}{t_1 - t_2} c_2.$$

Taking now $c_0 c_2 = t_2 c_2$ we get:

$$\alpha_{10} c_1 c_2 + c_0 \left(\sum_{i=1}^m \alpha_{i2} c_i \right) = t_2 \left(\sum_{i=1}^m \alpha_{i2} c_i \right) \text{ or}$$

$$\alpha_{10} t_3 c_3 + \sum_{i=1}^m \alpha_{i2} t_i c_i = \sum_{i=1}^m \alpha_{i2} t_2 c_i \text{ and so}$$

$$\begin{cases} \alpha_{12} t_1 = \alpha_{12} t_2 \\ \alpha_{10} t_3 + \alpha_{32} t_3 = \alpha_{32} t_2 \\ \alpha_{i2} t_i = \alpha_{i2} t_2 \quad (i > 3) \end{cases}$$

from which we obtain $\alpha_{12} = 0$, $\alpha_{32} = \frac{t_3}{t_2 - t_3} \alpha_{10}$ and $\alpha_{i2} = 0$ for $i > 3$.

Hence, for the moment, we have the equality

$$(3) \quad d(c_2) = \alpha_{22}c_2 + \alpha_{10} \frac{t_3}{t_2 - t_3} c_3$$

Naturally, by repetition of this argument, we will conclude that

$$(4) \quad d(c_k) = \alpha_{kk}c_k + \alpha_{10} \frac{t_{k+1}}{t_k - t_{k-1}} c_{k+1}$$

for any $k \leq m-1$ and $d(c_m) = \alpha_{mm}c_m$. We prove now that

$$(5) \quad \alpha_{kk} = k\alpha_{11} \quad (k = 1, 2, \dots, m)$$

by induction on k . The case $k = 1$ is obvious. Suppose now that $1 < k \leq m-1$ and that we have already proved that $\alpha_{k-1, k-1} = (k-1)\alpha_{11}$. This means that

$$d(c_{k-1}) = (k-1)\alpha_{11} c_{k-1} + \alpha_{10} \frac{t_k}{t_{k-1} - t_k} c_k.$$

From the equality $c_1 c_{k-1} = t_k c_k$ we get $d(c_1)c_{k-1} + c_1 d(c_{k-1}) = t_k d(c_k)$ and so:

$$\left[\alpha_{11}c_1 + \alpha_{10} \frac{t_2}{t_1 - t_2} c_2 \right] c_{k-1} + c_1 \left[(k-1)\alpha_{11} c_{k-1} + \alpha_{10} \frac{t_k}{t_{k-1} - t_k} c_k \right] =$$

$$= t_k \left[\alpha_{kk}c_k + \alpha_{10} \frac{t_{k+1}}{t_k - t_{k+1}} c_{k+1} \right]. \text{ This gives:}$$

$$\alpha_{11}t_k c_k + \alpha_{10} \frac{t_2}{t_1 - t_2} t_{k+1} c_{k+1} + \alpha_{11}(k-1)t_k c_k +$$

$$+ \alpha_{10} \frac{t_k}{t_{k-1} - t_k} t_{k+1} c_{k+1} = t_k \alpha_{kk} c_k + t_k \alpha_{10} \frac{t_{k+1}}{t_k - t_{k+1}} c_{k+1} \text{ and so:}$$

$$\begin{cases} \alpha_{11} + \alpha_{11}(k-1) = \alpha_{kk} \\ \frac{t_2}{t_1 - t_2} + \frac{t_k}{t_{k-1} - t_k} = \frac{t_k}{t_k - t_{k+1}} \end{cases}$$

The first is the desired equality and the second is an identity for every k (as in the proof that η was a derivation). The relations (1) to (5) show exactly that $d = \alpha_{10}\eta + \alpha_{11}\delta$.

Corollary 1. For any $m \geq 1$, the derivation algebra of $G(2, 2m)$ is isomorphic to the non abelian Lie algebra of dimension 2.

Proof. Clear, since δ and η do not commute. In fact, $\delta\eta - \eta\delta = \eta$.

Corollary 2. The proper values of a non-nilpotent derivation of $G(2, 2m)$ are of the form $0, \alpha, 2\alpha, \dots, m\alpha$, for some non-zero real number α .

4. Multiallelism and Polyploidy

As we know, $G(n+1, 2m)$ has a canonical basis consisting of all monomials $A_0^{i_0}(A_0 - A_1)^{i_1} \dots (A_0 - A_n)^{i_n}$ with $i_0 + i_1 + \dots + i_n = m$. The t -roots are given by

$$t_0 = 1, t_1 = 1/2, \dots, t_j = \frac{\binom{2m-j}{m}}{\binom{2m}{m}}, \dots, t_m = \frac{1}{\binom{2m}{m}}$$

with multiplicities $1, n, \dots, \binom{j+n-1}{j}, \dots, \binom{m+n-1}{m}$ respectively.

In order to simplify notations, we denote the variables $A_0, A_0 - A_1, \dots, A_0 - A_n$ by X_0, X_1, \dots, X_n . So we have the multiplication table of $G(n+1, 2m)$:

$$\begin{aligned} & (X_0^{i_0} X_1^{i_1} \dots X_n^{i_n}) (X_0^{j_0} X_1^{j_1} \dots X_n^{j_n}) \\ &= \begin{cases} \binom{2m}{m}^{-1} \binom{i_0+j_0}{m} X_0^{i_0+j_0-m} X_1^{i_1+j_1} \dots X_n^{i_n+j_n} & \text{if } i_0 + j_0 \geq m \\ 0 & \text{otherwise} \end{cases} \end{aligned}$$

The weight function of $G(n+1, 2m)$ is defined to be 1 on X_0^m and 0 on the other monomials.

Let us call now V_i the subspace of $G(n+1, 2m)$ generated by the monomials of degree $m-i$ in the variable X_0 . So V_0 is generated by X_0^m , V_1 is generated by $X_0^{m-1} X_i$ ($i = 1, \dots, n$), and so on. Each subspace V_i is the proper subspace of the linear mapping $x \mapsto X_0^m x$, $x \in G(n+1, 2m)$, corresponding to the proper value t_i . We have the direct sum decomposition $V_0 \oplus V_1 \oplus \dots \oplus V_m = G(n+1, 2m)$. Observe also that $V_1 \oplus \dots \oplus V_m$ is the kernel of w . When $n = 1$ (polyploidy only), each subspace V_i has dimension 1, because the t -roots are all simple.

Lemma 1. For any derivation d of $G(n+1, 2m)$, $d(X_0^m) = A \in V_1$, that is, $d(V_0) \subset V_1$.

Proof. We already know that $wod = 0$. So we may write $d(X_0^m) = A + v_2 + v_3 + \dots + v_{m-1} + v_m$, with $A \in V_1$ and $v_i \in V_i$ ($i \geq 2$). The equality $(X_0^m)^2 = X_0^m$ implies that $2X_0^m(A + v_2 + \dots + v_{m-1} + v_m) = A + v_2 + \dots + v_{m-1} + v_m$. But $X_0^m v_i = t_i v_i$ ($i = 1, \dots, m$) and $t_1 = 1/2$, which imply that

$$A + 2t_2 v_2 + \dots + 2t_{m-1} v_{m-1} + 2t_m v_m = A + v_2 + \dots + v_{m-1} + v_m \text{ and so}$$

$$v_2 = v_3 = \dots = v_{m-1} = v_m = 0, \text{ that is } d(X_0^m) = A \in V_1.$$

Lemma 2. For any derivation d of $G(n+1, 2m)$ and any $1 \leq j \leq n$, we have $d(X_0^{m-1} X_j) = B_j + \frac{1}{t_1 - t_2} A(X_0^{m-1} X_j)$, where B_j is some element of V_1 and $A = d(X_0^m)$. In particular, $d(V_1) \subset V_1 \oplus V_2$.

Proof: Call $d(X_0^{m-1} X_j) = B_j + C_j + v_3 + \dots + v_{m-1} + v_m$, with $B_j \in V_1$, $C_j \in V_2$ and $v_i \in V_i$ ($i \geq 3$). From the equality $X_0^m(X_0^{m-1} X_j) = t_1(X_0^{m-1} X_j)$ we obtain:

$A(X_0^{m-1} X_j) + X_0^m(B_j + C_j + v_3 + \dots + v_m) = t_1(B_j + C_j + v_3 + \dots + v_m)$, that is, $A(X_0^{m-1} X_j) + t_1 B_j + t_2 C_j + t_3 v_3 + \dots + t_m v_m = t_1(B_j + C_j + v_3 + \dots + v_m)$.

But $A(X_0^{m-1} X_j)$ belongs to V_2 so we must have:

$$\begin{cases} t_1 C_j = t_2 C_j + A(X_0^{m-1} X_j) \\ t_i v_i = t_1 v_i \quad (i \geq 3) \end{cases} \quad \text{or}$$

$$\begin{cases} C_j = \frac{1}{t_1 - t_2} A(X_0^{m-1} X_j) \\ v_i = 0 \quad (i \geq 3) \end{cases}$$

which gives $d(X_0^{m-1} X_j) = B_j + \frac{1}{t_1 - t_2} A(X_0^{m-1} X_j)$.

A repetition of the same argument will prove that for any derivation d of $G(n+1, 2m)$ and any $1 \leq j, k \leq m$,

$$d(X_0^{m-2} X_j X_k) = P_{jk} + \frac{1}{t_2 - t_3} A(X_0^{m-2} X_j X_k)$$

where P_{jk} is some element of V_2 , depending on X_j and X_k . More generally, we will have the formulae

$$d(X_0^{m-p} X_{i_1} \dots X_{i_p}) = P_{i_1 \dots i_p} + \frac{1}{t_p - t_{p+1}} A(X_0^{m-p} X_{i_1} \dots X_{i_p})$$

which describe, at least partially, the action of d on the basis of V_p , for every $p \leq m-1$. Here $P_{i_1 \dots i_p}$ is some element of V_p , depending on X_{i_1}, \dots, X_{i_p} .

Lemma 3. For any derivation d of $G(n+1, 2m)$ we have

$$d(X_{i_1} \dots X_{i_m}) = P_{i_1 \dots i_m} \in V_m.$$

Proof. We have $X_0^m(X_{i_1} \dots X_{i_m}) = t_m(X_{i_1} \dots X_{i_m})$ from which we obtain $A(X_{i_1} \dots X_{i_m}) + X_0^m d(X_{i_1} \dots X_{i_m}) = t_m d(X_{i_1} \dots X_{i_m})$. But $A(X_{i_1} \dots X_{i_m}) = 0$ because A is a linear combination of monomials like $X_0^{m-1} X_i$. If we decompose $d(X_{i_1} \dots X_{i_m})$ as $v_1 + v_2 + \dots + v_{m-1} + P_{i_1 \dots i_m}$, with $v_i \in V_i$ ($i = 1, \dots, m-1$) and $P_{i_1 \dots i_m} \in V_m$, we have $t_1 v_1 + t_2 v_2 + \dots + t_{m-1} v_{m-1} + t_m P_{i_1 \dots i_m} = t_m(v_1 + v_2 + \dots + v_{m-1} + P_{i_1 \dots i_m})$ and so $v_1 = v_2 = \dots = v_{m-1} = 0$.

We need now a better understanding of the elements $P_{i_1 \dots i_p}$ ($2 \leq p \leq m$) which appeared above.

Lemma 4. For any derivation d of $G(n+1, 2m)$ and any monomial $X_0^{m-2} X_j X_k$ in V_2 , we have:

$$d(X_0^{m-2} X_j X_k) = \frac{1}{t_2} [(X_0^{m-1} X_j) B_k + (X_0^{m-1} X_k) B_j] + \frac{1}{t_2 - t_3} A(X_0^{m-2} X_j X_k),$$

where B_j and B_k are those elements of Lemma 2.

Proof. Take the equality $(X_0^{m-1} X_j)(X_0^{m-1} X_k) = t_2(X_0^{m-2} X_j X_k)$. By derivation, we obtain:

$$(X_0^{m-1} X_j)(B_k + C_k) + (X_0^{m-1} X_k)(B_j + C_j) = t_2(P_{jk} + \frac{1}{t_2 - t_3} A(X_0^{m-2} X_j X_k))$$

where C_k and C_j are those elements of Lemma 2. But $(X_0^{m-1} X_j)C_k$ and $(X_0^{m-1} X_k)C_j$ are in V_3 , hence we must have $(X_0^{m-1} X_j)B_k + (X_0^{m-1} X_k)B_j = t_2 P_{jk}$.

Lemma 4 is the first induction step in the following:

Lemma 5. For any derivation d of $G(n+1, 2m)$ and any monomial $X_0^{m-p} X_{i_1} \dots X_{i_p}$ in V_p ($2 \leq p \leq m$) we have the following recurrence relation:

$$\begin{aligned} d(X_0^{m-p} X_{i_1} \dots X_{i_p}) &= \frac{1}{t_p} [P_{i_1 \dots i_{p-1}} (X_0^{m-1} X_{i_p}) + \\ &+ B_{i_p} X_0^{m-(p-1)} X_{i_1} \dots X_{i_{p-1}}] + \frac{1}{t_p - t_{p+1}} A(X_0^{m-p} X_{i_1} \dots X_{i_p}). \end{aligned}$$

Proof. Start with $(X_0^{m-(p-1)} X_{i_1} \dots X_{i_{p-1}})(X_0^{m-1} X_{i_p}) = t_p(X_0^{m-p} X_{i_1} \dots X_{i_p})$ and use induction.

Remark. The recurrence relation expressed in lemma 5 can be resolved to give the following explicit formula for d :

$$\begin{aligned} d(X_0^{m-p} X_{i_1} \dots X_{i_p}) &= \frac{1}{t_p} \sum_{j=1}^p X_0^{m-p} X_{i_1} \dots \hat{X}_{i_j} \dots X_{i_p} B_{i_j} + \\ &+ \frac{1}{t_p - t_{p+1}} A(X_0^{m-p} X_{i_1} \dots X_{i_p}), \text{ where } \wedge \text{ indicates absence.} \end{aligned}$$

The preceding lemmas describe the action of a derivation on the canonical basis of $G(n+1, 2m)$. These formulae have some indeterminates, which are the elements A, B_1, \dots, B_n of V_1 . Let us call this sequence the *characteristic sequence* of the derivation d . Hence, given a derivation d of $G(n+1, 2m)$ we can associate to it an element of the vector space $(V_1)^{n+1}$ (direct product of V_1 , $(n+1)$ -times). Conversely, given any element of

$(V_1)^{n+1}$, we define a derivation d of $G(n+1, 2m)$ in the following (recurrent) way: If we give (A, B_1, \dots, B_n) in $(V_1)^{n+1}$, then $d(A_0^m) = A$, $d(A_0^{m-1} X_i) =$
 $= B_i + \frac{1}{t_1 - t_2} A(X_0^{m-1} X_i)$, $d(X_0^{m-2} X_j X_k) = \frac{1}{t_2} (X_0^{m-1} X_j) B_k +$

$+ (X_0^{m-1} X_k) B_j + \frac{1}{t_2 - t_3} A(X_0^{m-2} X_j X_k)$, and so on. The proof that this d is a derivation offers no difficulty.

On the other hand, the correspondence $d \mapsto (A, B_1, \dots, B_n)$ is linear, as it becomes clear by looking to the formulae above. As we can see easily, the zero derivation corresponds to the sequence $(0, 0, \dots, 0)$.

A basis for the derivation algebra is obtained by standard ways. If we take $B_1 = \dots = B_n = 0$ than we will have n derivations corresponding to the choices $A = X_0^{m-1} X_i$ ($i = 1, \dots, n$). These derivations are all nilpotent. (These derivations look like η in theorem 3). Then taking $A = 0$, $B_i = X_0^{m-1} X_i$, $B_j = 0$ ($j \neq i$) we obtain another n derivations, which look like δ in theorem 3. The remaining derivations appear when we take $A = 0$, $B_i = X_0^{m-1} X_j$ ($j \neq i$), $B_k = 0$ ($k \neq i$). These are nilpotent. We have proved

Theorem 4. *The derivation algebra of $G(n+1, 2m)$ has dimension $n(n+1)$. In fact it has a basis consisting of n diagonalisable derivations and n^2 nilpotent derivations.*

Remark. One of the referees has simplified the proofs in our earlier version of this paper, by proving that a genetic algebra with weight function w over any field of characteristic 0 whose t -roots $\gamma_{011}, \dots, \gamma_{0nn}$ are all different from 1, satisfies $wod = 0$ for all derivations d . In the case the field is \mathbb{R} , this result appears as a particular case of our corollary to th.1.

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