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LAX PAIRS

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In the pioneering paper [3], Lax stated a condition under which certain one parameter families of operators $\{L(t)\}$ are isospectral, i.e., all the L(t) have the same spectrum. Lax actually asserted that his condition implied the unitary equivalence of all the L(t). Unfortunately it is not clear from [3] exactly when this condition is applicable. Furthermore there seems to be no clear statement nor proof of this in the Literature [See [1], Chapter 3 where this is discussed]. The purpose of this note is to state and prove such a result and show as Lax affirmed that it can indeed be used to prove the unitary equivalence of Schrödinger operators whose potentials evolve according to the Korteweg-de Vries equation.

The main theorem depends heavily on Kato's paper [2]. We refer to it for background and notation.

Theorem. Let H be a Hilbert space, $\{L(t)\}$, $\{A(t)\}$, $t \in [0,T]$ families of self-adjoint operators in H and Y, V, W Hilbert spaces which are densely and continuously imbedded in H and satisfy $Y \subseteq V$, $Y \subseteq W$. Suppose in addition:

- 1. For each $t \in [0,T]$ D(L(t)) = V and D(A(t)) = W.
- 2. $t \longmapsto L(t)$ is strongly continuously differentiable (V,H).
- 3. a) For each $t \in [0,T]$, A(t) maps Y continuously into V.
- (Y,V).
- c) $t \longmapsto A(t)$ is continuous $[0,T] \rightarrow B(W,H)$ and strongly continuously differentiable (W,H).
- 4. There is a family of isomorphisms $\{S(t)\}$, $t \in [0,T]$ from Y onto H such that $t \longmapsto S(t)$ is strongly differentiable (Y,H) and

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$$S(t)A(t)S(t)^{-1} = A(t) + B(t),$$

where $B(t) \in B(H)$ and $t \longmapsto B(t)$ is strongly continuous (H). 5. L(t) maps Y into W and, for each $t \in [0,T]$ $\phi \in Y$,

$$\frac{d}{dt} L(t)\phi = -i [A(t), L(t)]\phi,$$

the derivative being taken in H, which makes sense in virtue of 2. Also the commutator above makes sense given the mapping properties of L(t) and A(t).

Then all the operators L(t) are unitarily equivalent.

Remark. A pair of operator families $\{L(t)\}$, $\{A(t)\}$ satisfying the above condition is called a $Lax\ pair$.

In the following, $C^n_b(\mathbb{R})$ denotes the space of all C^n functions $u:\mathbb{R} \to \mathbb{R}$ such that $\|u\|_n = \sup_{\substack{j \leq n \\ x \in \mathbb{R}}} |u^{(j)}(x)| < \infty$.

Corollary. Suppose that for all $t \in [0,T]$, $u(t) \in C_b^6(\mathbb{R})$, $t \longmapsto u(t)$ is continuous $[0,T] \to C_b^6(\mathbb{R})$ and $C^1[0,T] \to C_b^1(\mathbb{R})$. If u satisfies the Korteweg-de Vries equation

$$u_t + uu_x + u_{xxx} = 0$$

then the Schrödinger operators

$$L(t) = \partial_x^2 + u(t)/6 \quad (t \in [0,T])$$

are all unitarily equivalent operators in $H = L^{2}(\mathbb{R})$.

We remark that his corollary has been rigourously shown [see [1]] by other methods.

Proof of Theorem. We apply Theorem 6.1 of [2]. By 3c) and Remark 6.2 of [2] there is a family $\{U(t)\}$, $t \in [0,T]$ in B(H) such that

- (i) U(t) is strongly continuous (H).
- (ii) U(t) $W \subseteq W$ for each $t \in [0,T]$ and $\{U(t)\}$ is strongly continuous (W).
- (iii) $\{U(t)\}$ is strongly continuously differentiable (W,H) and for all $\phi \in H$ $t\longmapsto U(t)\phi$ is a solution to the initial value problem

$$\begin{cases} \frac{d}{dt} \ \psi(t) = -i \ A(t) \psi(t), \\ \psi(0) = \phi. \end{cases} \tag{*}$$

Each U(t) is a unitary operator in H: By differentiation all solutions of (*) have constant H norm. Thus U(t) is isometric. By reversing the initial value problem (i.e. taking as initial point t instead of θ and solving backwards, which is clearly possible) we conclude U(t) is surjective and thus unitary.

U(t) leaves Y invariant. To see this apply Theorem 6.2 of [2] with hypotheses 3. and 4. Note $t \longmapsto A(t)$ is continuous $[0,T] \rightarrow B(Y,H)$ because the inclusion $Y \rightarrow W$ is continuous by the closed graph theorem. Thus if $\varphi \in Y$ the initial value problem (*) has a strongly continuous solutions $\psi \colon [0,T] \rightarrow Y$. By uniqueness of solutions which follows from linearity and the constancy of the norms of solutions to (*)] we conclude the invariance of Y.

Notice that this argument shows that $\{U(t)\}$ is strongly continuous (Y). We now show that $\{U(t)\}$ is continuously strongly differentiable (Y,V). Indeed, if \emptyset 6 Y

$$U(t)\phi - \phi = -i \int_{0}^{t} A(\theta)U(\theta)\phi d\theta,$$

the integral being a priori an H valued integral. But by 3a) it follows easily that $\theta \longmapsto A(\theta)U(\theta)\phi$ is continuous $\llbracket \theta,T \rrbracket \to V$ and so by the fundamental theorem of calculus $t\longmapsto U(t)\phi$ is differentiable (V).

To complete the proof of the theorem we prove that if $\phi \in Y$, $U^*(t)L(t)U(t)\phi$ is constant. To do this it clearly

suffices to prove that $\langle L(t)U(t)\phi, U(t)\psi \rangle$ is constant for all $\psi \in Y$. A straight forward argument shows $t \longmapsto L(t)U(t)\phi$ is strongly continuously differentiable (H) and

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$$\frac{d}{dt} L(t)U(t)\phi = \left[\frac{d}{dt} L(t)\right]U(t)\phi + L(t) \frac{d}{dt} U(t)\phi.$$

Thus $t \longmapsto \langle L(t)U(t)\phi, U(t)\psi \rangle$ is a differentiable function and

$$\frac{d}{dt} \langle L(t)U(t)\phi, U(t)\psi \rangle =$$

$$= \langle \left[\frac{d}{dt} L(t)\right]U(t)\phi + L(t) \frac{d}{dt} U(t)\phi, U(t)\psi \rangle +$$

$$+ \langle L(t)U(t)\phi, \frac{d}{dt} U(t)\psi \rangle = \langle \left[\frac{d}{dt} L(t)\right]U(t)\phi -$$

$$- i L(t)A(t)U(t)\phi + i A(t)L(t)U(t)\phi, U(t)\psi \rangle =$$

$$= 0$$

by assumption 5. This completes the proof.

Proof of the Corollary. Let $Y = H^5(\mathbb{R})$, $W = H^3(\mathbb{R})$, $V = H^2(\mathbb{R})$

$$S(t) = \left[\partial_{x}^{5} + I\right]$$
 (independently of t)

$$A(t) = i \left[24 \vartheta_x^3 + 3 u(t) \vartheta_x + 3 \vartheta_x u(t) \right] = i \left[24 \vartheta_x^3 + 6 u(t) \vartheta_x + 3 u'(t) \right].$$

We show conditions 1 - 5 of the theorem hold:

1. Follows from the Kato-Rellich Theorem [Theorem X.12 [4]] and 3a. follows from elementary mapping properties of differential operators. To check 2, it suffices to observe that u(t) [considered as a multiplication operator in $L^{2}(R)$] is strongly continuously differentiable (H) as a function of t. To verify 3b. note that, since $t \mapsto u(t)$ is continuous with values in $C_h^3(\mathbb{R})$, $t \longmapsto 3u(t)\partial_x + 3\partial_x u(t)$ is continuous $B(H^3(\mathbb{R}), H^2(\mathbb{R}))$. From this it follows that $t \longmapsto A(t)$ is continuous $B(H^5(\mathbb{R}), H^2(\mathbb{R}))$. A similar argument proves 3c.

To prove 4 we begin with some domain considerations: Obviously

 $D(S(t)A(t)S(t)^{-1}) = \{ \phi \in L^{2}(\mathbb{R}) : A(t)S(t)^{-1} \phi \in H^{5}(\mathbb{R}) \}.$

If $w \in H^5(\mathbb{R})$ and $A(t)w \in H^5(\mathbb{R})$ then

$$24 \vartheta_x^3 w = -3u(t)\vartheta_x w - 3\vartheta_x u(t)w - iA(t)w \in H^{4}(\mathbb{R}).$$

By elliptic regularity, $w \in \operatorname{H}^7(\mathbb{R})$; Since $u(t) \in \operatorname{C}^6_h(\mathbb{R})$ for each t the previous equation and elliptic regularity again imply $w \in H^8(\mathbb{R})$. From this follows immediately that

$$D(S(t)A(t)S(t)^{-1}) = H^{3}(\mathbb{R}).$$

By commutation properties of differential operators

$$[\partial^{5}+I]A(t)[\partial^{5}+I]^{-1} = A(t) + T(t)[\partial^{5}+I]^{-1},$$

where T(t) is a differential operator of order 5 with at least continuous coefficients. Thus T(t) maps $H^5(\mathbb{R})$ continuously into $L^2(\mathbb{R})$. Furthermore since the coefficients of T(t) are x-derivatives of u of order < 6 it follows $t \longmapsto T(t)$ is continuous $\lceil 0, T \rceil \rightarrow B(H^5(\mathbb{R}), L^2(\mathbb{R}))$.

Finally property 5. is precisely the commutation relation shown in Lax's paper.

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