

# On differentiable area–preserving maps of the plane

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**Abstract.**  $F : \mathbb{R}^2 \to \mathbb{R}^2$  is an *almost-area-preserving* map if: (a) F is a topological embedding, not necessarily surjective; and (b) there exists a constant s > 0 such that for every measurable set B,  $\mu(F(B)) = s\mu(B)$  where  $\mu$  is the Lebesgue measure. We study when a differentiable map whose Jacobian determinant is nonzero constant to be an almost-area-preserving map. In particular, if for all z, the eigenvalues of the Jacobian matrix  $DF_z$  are constant, F is an almost-area-preserving map with convex image.

Keywords: area-preserving maps, Jacobian conjecture.

Mathematical subject classification: 14R15, 26B10, 14E07, 14E25.

### 1 Introduction and statement of the results

We say that  $F \colon \mathbb{R}^2 \to \mathbb{R}^2$  is an **almost-area-preserving** map if it satisfies the following two conditions:

- (a) This F is a topological embedding; that is, a globally injective local homeomorphism.
- (b) There exists a constant s > 0 such that for every measurable set B ⊂ R<sup>2</sup> we have

$$\mu(F(B)) = s\mu(B),$$

where  $\mu$  is the Lebesgue measure.

This topological embedding does not have to be surjective, because its image  $F(\mathbb{R}^2)$  might be a proper subset of  $\mathbb{R}^2$  not necessarily convex.

The standard area-preserving diffeomorphisms of class  $C^1$  are examples of *almost-area-preserving* maps, see [OU41, KH].

Received 10 October 2008.

A differentiable planar map F is called **unipotent**, if its spectrum  $\text{Spc}(F) = \{\text{eigenvalues of } DF_z : z \in \mathbb{R}^2\}^1$  is the one point set  $\{1\}$ . In [Ch00], Chamberland proves that a real-analytic map of  $\mathbb{R}^2$  into itself has an inverse as long as it is unipotent (see also [Che99] and [VH97]). So, real-analytic-unipotent maps are almost-area-preserving. A proof for  $C^1$ -maps of the plane appears in [Ca00], where Campbell gives a normal form; this impressive result may be paraphrased as follows: A  $C^1$ -planar map  $F : \mathbb{R}^2 \to \mathbb{R}^2$  is unipotent, if and only if, it has the form

$$F(x, y) = \left(x + b\phi(ax + by) + c, y - a\phi(ax + by) + d\right) \quad \forall x, y \in \mathbb{R}, \quad (1)$$

where a, b, c and d are real constants, and  $\phi$  is a  $C^1$ -function on a single variable. Thus, any  $C^1$ -unipotent map of the plane is bijective. Therefore, the  $C^1$ -unipotent maps of the plane are also almost–area–preserving.

In [Ch03], Chamberland research the  $C^1$ -maps  $F \colon \mathbb{R}^2 \to \mathbb{R}^2$  with **constant** eigenvalues; that is, its spectrum has at most two elements. These maps are completely characterized in two cases: (a) F is a  $C^1$ -unipotent map, then F has the form (1) and (b) F is a polynomial map, then F takes the form

$$F(x, y) = (ax + by + \beta\varphi(\alpha x + \beta y) + e, cx + dy - \alpha\varphi(\alpha x + \beta y) + f)$$
(2)

for some real constant *a*, *b*, *c*, *d*, *e*, *f*,  $\alpha$  and  $\beta$ , and some polynomial  $\varphi$  of one variable. Furthermore, if *F* is a polynomial map on the plane and Spc(*F*) is bounded, Lemma 2.1 of [CGM01] implies that Spc(*F*) has at most two elements. Therefore, *polynomial planar maps whose bounded* Spc(*F*) *misses the zero are almost–area–preserving*.

**Theorem 1.** Let  $F : \mathbb{R}^2 \to \mathbb{R}^2$  be a differentiable map with  $\det(DF_z) \neq 0$ , for all  $z \in \mathbb{R}^2$ . If  $\operatorname{Spc}(F)$  has at most two elements then F is an almost–area–preserving map with convex image.

The almost–area–preserving maps of Theorem 1 extends the last examples, described in [Ca00] and [Ch03], to maps not necessarily  $C^1$ .

A differentiable map  $F : \mathbb{R}^2 \to \mathbb{R}^2$  shall be called **Jacobian map**, if for all  $z \in \mathbb{R}^2$ , its Jacobian determinant det $(DF_z)$  is nonzero constant; in this way, a Jacobian planar map F = (f, g) with f and g polynomials and det $(DF_z) = 1$ , shall be referred as a **Keller map**. In this context, the injective Jacobian maps of class  $C^1$  are almost-area-preserving. However, it is well know that there are Jacobian maps which are not injective as shown the map

$$F(x, y) = \sqrt{2} \left( e^{\frac{x}{2}} \cos(y e^{-x}), e^{\frac{x}{2}} \sin(y e^{-x}) \right)$$

<sup>&</sup>lt;sup>1</sup>The spectrum is also denoted by Spec(F), but we prefer Spc(F) in order to avoid some confusion with the algebraic notation  $\text{Spec}(\mathfrak{F})$  associated to a ring  $\mathfrak{F}$ .

mentioned in [ChM98]. Consequently, the goal is to give sufficient conditions on differentiable maps to insure that it is an almost–area–preserving map. To this end, for each  $\theta \in \mathbb{R}$  we denote by  $R_{\theta}$  the linear rotation

$$R_{\theta} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

and define the map  $F_{\theta} = R_{\theta} \circ F \circ R_{-\theta}$ .

**Definition 1.** We say that the differentiable map  $F : \mathbb{R}^2 \to \mathbb{R}^2$  satisfies the *B*condition if for each  $\theta \in \mathbb{R}$ , there does not exist a sequence  $(x_k, y_k) \in \mathbb{R}^2$ with  $x_k \to +\infty$  such that  $F_{\theta}((x_k, y_k)) \to p \in \mathbb{R}^2$  and  $DF_{\theta}(x_k, y_k)$  has a real eigenvalue  $\lambda_k$  satisfying  $x_k \lambda_k \to 0$ .

Definition 1 was motivated by the condition (\*) of [GN07] which claims: "For each  $\theta \in \mathbb{R}$ , there does not exist a sequence  $z_k \in \mathbb{R}^2$  with  $z_k \to \infty$  such that  $F_{\theta}(z_k) \to p \in \mathbb{R}^2$  and  $DF_{\theta}(z_k)$  has a real eigenvalue  $\lambda_k \to 0$ ."

If g(x, y) is a  $C^1$  function such that  $g(x, y) = \frac{y}{x}$  as long as  $x \ge 3$ , and the map  $F(x, y) = (e^{-x}, g(x, y))$  satisfies  $\det(DF_z) \ne 0$ , for all  $z \in \mathbb{R}^2$ . Then, for any unbounded sequence  $3 \le x_k \to +\infty$  there exist p = (0, 0) such that  $F(x_k, 0) \to p$  and  $DF(x_k, 0)$  has a real eigenvalue

$$\frac{1}{x_k} = \lambda_k \to 0$$

However, the limit of the product  $x_k \lambda_k$  is different from zero.

**Theorem 2.** If the differentiable Jacobian map  $F : \mathbb{R}^2 \to \mathbb{R}^2$  satisfies the *B*-condition then *F* is an almost–area–preserving map with convex image.

Theorem 2 improves the main result of [GN07] (see also [Ra02, R05]). Moreover, if Theorem 2 is valid for maps F, it remains true for -F. In fact, if in such theorem we change the pair  $\{F, \text{Spc}(F)\}$  by  $\{-F, \text{Spc}(-F)\}$  we may see that its conclusion remains valid. Also, for each  $A : \mathbb{R}^2 \to \mathbb{R}^2$  any arbitrary invertible linear map, we have that if F is as in Theorem 2 then  $A \circ F \circ A^{-1}$  is also an almost–area–preserving map with convex image.

The maps in Theorem 2 are injective, so we obtain the following corollary whose proof is presented at the end of Section 3.

**Corollary 1.** If F is as in Theorem 2 and  $\text{Spc}(F) \subset \{z \in \mathbb{C} : ||z|| < 1\}$ , then F has at most one fixed point.

Another interesting property of the Keller maps as in Corollary 1 (i.e with  $\text{Spc}(F) \subset \{z \in \mathbb{C} : ||z|| < 1\}$ ) is obtained from Theorem B of [CGM99]. This

theorem proves the existence of a unique fixed point of F which is a global attractor for the discrete dynamical system generated by F (i.e for each  $p \in \mathbb{R}^2$  the  $\omega$ -limit set of the orbit  $(F^k(p))_{k\geq 0}^2$  is the one point set  $\{z \in \mathbb{R}^2 : F(z) = z\}$ ). This dynamical property is false for all the maps of class  $C^1$  as shown the global diffeomorphisms given in Theorem E of [CGM99]. If a is small enough, this map  $G_a$  given by

$$G_a(x, y) = \left(-\frac{ky^3}{1+x^2+y^2} - ax, \frac{ky^3}{1+x^2+y^2} - ay\right), \quad 1 < k < \frac{2}{\sqrt{3}}$$

satisfies  $G_a(0) = 0$  and  $\text{Spc}(G_a) \subset \{z \in \mathbb{C} : ||z|| < 1\}$ , but it has a periodic orbit. However, the Jacobian determinant of  $G_a$  is not constant.

**Problem 1.** Let  $F : \mathbb{R}^2 \to \mathbb{R}^2$  be a Jacobian map of class  $C^1$  with F(0) = 0 and  $\text{Spc}(F) \subset \{z \in \mathbb{C} : ||z|| < 1\}$ . Does it follow that 0 is a global attractor for F?

Observe that Theorem 1 follows directly of Theorem 2.

This paper is organized as follows: In Section 2, we show that the maps of Theorem 2 are injective maps whose image is convex. In Section 3, we conclude the proof of Theorem 2.

#### 2 A topological embedding on the plane

The present section is related to the Keller Jacobian Conjecture, more precisely its real version which claims: *Every polynomial map from*  $\mathbb{R}^n$  to  $\mathbb{R}^n$  with a constant nonzero Jacobian determinant is invertible. (See [ChM98, SX96, NX02, FGR03]). This conjecture remains open even when n = 2 but one knows that injectivity implies the surjectivity in this context, [BA62, Pa04]. There is quite a lot literature in problem of finding sufficient conditions for a  $C^1$  map from  $\mathbb{R}^2$ to  $\mathbb{R}^2$  to be injective. For example, Campbell in [Ca00] proved in the  $C^1$ -case that the fact that 1 is the only eigenvalue of all the Jacobian matrices is a sufficient condition. Then, Chamberland conjectured in [Ch00] that the fact that the spectrum is bounded away from 0 is sufficient to get the injectivity.

In [FGR04], we gave a proof of Chamberland Conjecture in dimension 2 (without assuming the  $C^1$ -hypothesis). More precisely, a differentiable map  $F : \mathbb{R}^2 \to \mathbb{R}^2$  is invertible as long as its spectrum, Spc(F) misses a set  $[0, \varepsilon)$  for some  $\varepsilon > 0$ . The idea of the proof is to study the foliation  $\mathcal{F}(f)$  given by the level curves  $\{f = constant\}$  of the first coordinate f of F = (f, g), [RR89].

<sup>&</sup>lt;sup>2</sup>The orbit  $(\overline{F^k(p)})_{k\geq 0}$  is the planar set given by the iterations of the map:  $\{F^k(p): k \in \mathbb{N} \cup \{0\}\}$ , where  $F^0$  denotes the identity map.

The non–injectivity of F implies that the foliation admits a Reeb component as in [HR57]. With a nice argument a sequence  $((x_k, y_k))_{k\geq 0}$  is found such that one of the eigenvalue  $\lambda_k$  of the Jacobian matrix  $DF_{(x_k,y_k)}$  is positive and satisfies  $\lim_{k\to\infty} \lambda_k = 0$ . A remark can be found in [GN07], where it is said that one can suppose that the sequence  $(F(x_k, y_k))_{k\geq 0}$  has a limit in  $\mathbb{R}^2$ . This motives to present Definition 1 and the following

**Theorem 3.** Suppose that the differentiable map  $F : \mathbb{R}^2 \to \mathbb{R}^2$  satisfies the *B*-condition and det $(DF_z) \neq 0$ , for all  $z \in \mathbb{R}^2$  then *F* is a topological embedding.

**Proof.** From [FGR04, Proposition 1.4], we shall have established that F = (f, g) will be injective if we prove that  $\mathcal{F}(f)$  has no half–Reeb component. In order to obtain this result we consider the map  $(f_{\theta}, g_{\theta}) = R_{\theta} \circ F \circ R_{-\theta}$ .

Suppose by way of contradiction that  $\mathcal{F}(f)$  has a half-Reeb component. From [FGR04, Proposition 1.5] we can select some  $\theta \in \mathbb{R}$  for which  $\mathcal{F}(f_{\theta})$  has a half-Reeb component whose projection is an unbounded interval; thus there are  $a_0 > 0$  and a half-Reeb component  $\mathcal{A}$  of  $\mathcal{F}(f_{\theta})$  such that  $[a_0, +\infty) \subset \Pi(\mathcal{A})$ , where  $\Pi(x, y) = x$ . Then, for some  $a > a_0$  large enough the line  $\Pi^{-1}(a)$  intersects the two non-compact edges of  $\mathcal{A}$  but it is disjoint of the compact edge. Since  $\mathcal{A}$  is the union of an increasing sequence of compact sets bounded by the compact edge and a compact segment of leaf. Then, from our selection of  $a > a_0$  we have that for any  $x \ge a$ , the line  $\Pi^{-1}(x)$  intersects exactly one trajectory  $\alpha_x \subset \mathcal{A}$  of  $\mathcal{F}(f_{\theta})|_{\mathcal{A}}$  such that  $\Pi(\alpha_x) \cap [x, +\infty) = \{x\}$ . If  $x \ge a$ , the intersection  $\alpha_x \cap \Pi^{-1}(x)$  is a compact subset of  $\mathcal{A}$ . Therefore, we can define two functions

$$H: (a, +\infty) \to \mathbb{R}$$
 by  $H(x) = \sup \{y: (x, y) \in \alpha_x \cap \Pi^{-1}(x)\},\$ 

and

 $\varphi \colon (a, +\infty) \to \mathcal{A}$  by  $\varphi(x) = f_{\theta}(x, H(x)).$ 

For every interval  $[a, b) \subset \mathbb{R}$  the function H is bounded, because the graph of the restriction  $H|_{[a,b)}$  is contained in the compact subset of  $\mathcal{A}$  whose boundary is  $\Pi^{-1}(a) \cup \alpha_b$ . Moreover, when  $x \ge a$  is kept fixed, the point  $(x, H(x)) \in \alpha_x \cap \Pi^{-1}(x)$  is a local extremal of the differentiable function  $(x, y) \mapsto f_{\theta}(x, y)$ . Thus,

(a) if  $x \ge a$  every partial derivative satisfies  $(f_{\theta})_{y}(x, H(x)) = 0$ .

The function  $\varphi$  is bounded because its image is contained in  $f_{\theta}(\Gamma)$  where  $\Gamma$  is the compact edge of  $\mathcal{A}$ . This  $\varphi$  is continuous because the leaves  $\alpha_x$  depends continuously of x (i.e  $\mathcal{F}(f_{\theta})$  is a  $C^0$ -foliation). And,  $\varphi$  is strictly monotone because  $\mathcal{F}(f_{\theta})$  is topological transversal to  $\Gamma \setminus \{\text{some point}\}$ . Therefore:

- (b) This  $\varphi(x) = f_{\theta}(x, H(x))$  is bounded, continuous and strictly monotone; in particular  $\varphi$  is differentiable a.e.
- (c) We claim that the image  $F_{\theta}(\mathcal{A})$  is bounded, where  $F_{\theta} = (f_{\theta}, g_{\theta})$ .

Consider  $\Gamma$  the compact edge of  $\mathcal{A}$  which is homeomorphic to an interval, and denote by I the compact interval  $f_{\theta}(\Gamma)$ . From our construction of  $\mathcal{F}(f_{\theta})$ , the compact continuous curve  $F_{\theta}(\Gamma)$  is the union of exactly two graphs of continuous functions  $I \mapsto \mathbb{R}$ . Moreover, the intersection of this two graphs is a point in  $F_{\theta}(\Gamma)$  where the vertical foliation has a topological tangency. Both functions  $I \mapsto \mathbb{R}$  are bounded, and every vertical interval whose end points belong these graphs is the image under  $F_{\theta}$  of a compact segment of leaf contained in  $\mathcal{A}$ . Since the adherence of a bounded set is also bounded and  $\mathcal{A} \setminus \{\text{non-compact edges}\}$  is the union of such type of compact segment of leafs we obtain (c).

Since  $f_{\theta}$  is differentiable at (x, H(x)) and H is upper semicontinuous, we can proceed as in [FGR04] and obtain that  $\varphi$  has the following property:

(d) For some full measure subset  $M \subset (a, +\infty)$  such  $\varphi$  is differentiable on M and for all  $x \in M$  the Jacobian matrix of  $F_{\theta}$  at (x, H(x)) is

$$DF_{\theta}(x, H(x)) = \left(\begin{array}{cc} \varphi'(x) & 0\\ (g_{\theta})_x(x, H(x)) & (g_{\theta})_y(x, H(x)) \end{array}\right).$$

In other words, if  $x \in M$ , then  $\varphi'(x) = (f_{\theta})_x(x, H(x)) \in \operatorname{Spc}(F)$ .

To proceed we shall only consider the case in which  $\varphi'(x) \ge 0$ , because in the other case we can use  $\limsup_{x\to\infty} x\varphi'(x)$ .

If  $\liminf_{x\to\infty} x\varphi'(x) = 0$ , there is a sequence  $(x_k, H(x_k)) \to \infty$  such that  $DF_{\theta}(x_k, H(x_k))$  has a real eigenvalue  $\lambda_k = \varphi'(x_k)$  for which  $\lim x_k \lambda_k = 0$  and  $F_{\theta}(x_k, H(x_k))$  tends to a finite value in the closure  $\overline{F_{\theta}(\mathcal{A})}$  (which is compact by (c)). This contradicts the *B*-condition.

If  $\liminf_{x\to\infty} x\varphi'(x) \neq 0$ , then  $\liminf_{x\to\infty} x\varphi'(x) > 0$ . This implies that there are constants  $\alpha_0 \ge a$  and  $\ell > 0$  such that  $\ell \le x\varphi'(x)$  if  $x \ge \alpha_0$ . From (b) there is a constant K > 0 such that for all  $x > \alpha_0, 0 \le \varphi(x) - \varphi(\alpha_0) \le K$ . Take  $c_0 > \alpha_0$  so that  $K < \int_{\alpha_0}^{c_0} \frac{\ell}{x} dx$ . Then

$$K < \int_{\alpha_0}^{c_0} \frac{\ell}{x} dx \le \int_{\alpha_0}^{c_0} \varphi'(x) dx \le \varphi(c_0) - \varphi(\alpha_0) \le K$$

This contradiction proves the theorem.

**Lemma 1.** If some level curve  $\{f = c\}$  is disconnected, then  $\mathcal{F}(f)$  has a half-Reeb component.

**Proof.** We refeer the reader to the proof of Theorem 2.1 of [GR06].

**Corollary 2.** If  $F : \mathbb{R}^2 \to \mathbb{R}^2$  is as in Theorem 2, then F is injective and  $F(\mathbb{R}^2)$  is convex.

**Proof.** Let  $p, q \in F(\mathbb{R}^2)$  and let  $[p, q] = \{(1 - t)p + tq : 0 \le t \le 1\}$ . Take  $\theta \in \mathbb{R}$  so that  $R_{\theta}([p, q])$  is contained in the vertical line x = c. Lemma 1 implies that the level curve  $\{f_{\theta} = c\}$  is a connected subset of the straight line x = c connecting  $R_{\theta}(p)$  with  $R_{\theta}(q)$ ; that is  $R_{\theta}([p, q]) \subset F_{\theta}(\mathbb{R}^2)$  which implies that  $[p, q] \subset F(\mathbb{R}^2)$  and concludes the proof.

Let us finish with an example of a map F = (f, g) whose image is not convex and the foliation  $\mathcal{F}(f)$  has no Reeb component in the sense of [HR57].

Example. If we consider

$$f(x, y) = \exp(y) \cos\left(2 \arctan(x) - \frac{\pi}{2}\right)$$

and

$$g(x, y) = \exp(y) \sin\left(2\arctan(x) - \frac{\pi}{2}\right),$$

the map F = (f, g) is injective because of the foliation  $\mathcal{F}(f)$  has no half-Reeb component ([FGR04, Proposition 1.4]). More precisely, for every  $c \neq 0$  the level curve  $\{f = c\}$  is the graph of a function and  $\{f = 0\}$  is the vertical axis. Therefore, F is a smooth diffeomorphism between  $\mathbb{R}^2$  and the open set  $\mathbb{R}^2 \setminus (\{0\} \times (-\infty, 0])$  which in particular is a *non convex image*.

#### **3** Differentiable almost-area-preserving maps

In this section we conclude the proof of Theorem 2 which implies Theorem 1. This proof shall be completed at the end of this section. By [RR89, Theorem 3.4] if  $\det(DF_z) \neq 0$  for all  $z \in \mathbb{R}^2$ , the non–connected function  $z \mapsto \det(DF_z)$  has constant sign, so in the rest of this section we may assume that  $\det(DF_z) > 0$ .

**Lemma 2.** Let  $G: \mathbb{R}^2 \to \mathbb{R}^2$  be an injective differentiable (not necessarily  $C^1$ ) map and let s > 0 a constant such that for all  $z \in \mathbb{R}^2$ ,  $|\det(DG_z)| = s$ . If  $B \subset \mathbb{R}^2$  is a measurable set and G(B) has finite Lebesgue measure then

$$\mu(G(B)) = s\mu(B)$$

where  $\mu$  is the Lebesgue-measure in  $\mathbb{R}^2$ .

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 $\square$ 

**Proof.** If follows directly of applying [P, Corollary 10.6.10] (a change of variables); because  $\mu(G(B)) < \infty$ , G is a differentiable injective map and the Jacobian determinant det $(DG_z)$  is constant.

**Proof of Theorem 2.** By Corollary 2, F is an injective map with convex image. Then, it is sufficient to prove that Statement (b) in the definition of almost–area–preserving maps is true.

Let  $B \subset \mathbb{R}^2$  be any measurable set.

(a.1) We claim that if  $\mu(F(B)) < \infty$  or  $\mu(B) < \infty$ , then  $\mu(F(B)) = s\mu(B)$ where  $s = |\det(DF_z)|$ .

By Lemma 2 (a.1) holds when  $\mu(F(B)) < \infty$ . In the other case,  $\mu(B) < \infty$ , so we consider A = F(B) and  $G = F^{-1}$ . As  $\mu(G(A)) = \mu(B) < \infty$  we may apply Lemma 2 and obtain that  $\mu(G(A)) = \frac{1}{s}\mu(A)$  because  $|\det(DG_z)| = \frac{1}{s}$ . From this, (a.1) holds.

(a.2) We claim that if B is a measurable set of the plane  $\mu(F(B)) = s\mu(B)$ .

If we does not have the condition of (a.1)  $\mu(F(B))$  and  $\mu(B)$  have no finite measure, so (a.2) is true.

Therefore, F is an almost–area–preserving map.

**Corollary 3.** Let  $F : \mathbb{R}^2 \to \mathbb{R}^2$  be as in Theorem 2. If  $(B_n)_n$  is an infinite sequence of measurable sets for which there exist a constant  $\delta > 0$ , such that for all  $N \in \mathbb{N}$ ,  $\mu(B_{N+1} \setminus \bigcup_{n=1}^N B_n) > \delta$ . Then,  $F(\bigcup_n B_n)$  has no finite measure.

**Proof.** Suppose, by contradiction, that  $\mu(F(\bigcup_n B_n)) < \infty$ . Consider,  $A_1 = B_1$ , and for every *N* natural greater than one set  $A_{N+1} = B_{N+1} \setminus \bigcup_{n=1}^N B_n$ . Given  $K \in \mathbb{N}$ , by using the definition of almost–area–preserving, we have that

$$\mu\left(F\left(\bigcup_{n}B_{n}\right)\right) > \mu\left(\bigcup_{N=2}^{K+1}F(A_{N})\right) = \sum_{N=2}^{K+1}s\mu(A_{N}) = s\delta K.$$

Then, the natural numbers  $\mathbb{N}$  is bounded. This contradiction conclude the proof.

**Remark 1.** Corollary 3 remains true if take *F* as any almost–area–preserving map whose image may be non–convex. For instance, take the map  $F(x, y) = (\exp(x), y \exp(-x))$  for which  $F(\mathbb{R}^2) \neq \mathbb{R}^2$ .

**Proof of Corollary 1.** Consider  $G : \mathbb{R}^2 \to \mathbb{R}^2$  given by G(z) = F(z) - z for all  $z \in \mathbb{R}^2$ . This map has no positive eigenvalue because Spc(G) is contained in  $\{z \in \mathbb{R}^2 : \Re(z) < 0\}$ , so it satisfies Theorem 2 because Spc(G) avoid an open real neighborhood of the origin. Since G is injective we conclude the proof of Corollary 1.

Acknowledgments. This paper was written during a stay of the author at ICTP. We wish to thank the members of the Mathematics Section, specially to professor Lê Dũng Tráng. We also express our gratitude to professors J. Llibre, A. Gasull and F. Mañosas from the *Universitat Autònoma de Barcelona* for several comments in the "Seminar of the Dynamical System Group". We wish to thank to the referee whose comments have appreciated and incorporated into this work. I am particularly indebted to professor Carlos Gutiérrez for useful comments to this work.

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