

## GENERALIZED ACTIONS

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**Abstract.** In this paper a generalization of the concept of action is considered. This notion is based on a new algebraic structure called generalized groups. An action is deduced by imposing an Abelian condition on a generalized group. Generalized actions on normal generalized groups are also considered.

### 1. Basic Notions

The theory of generalized groups was first introduced in [1]. A generalized group means a non-empty set  $G$  admitting an operation

$$\begin{aligned} G \times G &\rightarrow G \\ (a, b) &\mapsto ab \end{aligned}$$

called multiplication which satisfies the following conditions:

- i)  $(ab)c = a(bc)$  for all  $a, b, c$  in  $G$ ;
- ii) For each  $a \in G$  there exists a unique  $e(a) \in G$  such that  $ae(a) = e(a)a = a$ ;
- iii) For each  $a \in G$  there exists  $a^{-1} \in G$  such that  $aa^{-1} = a^{-1}a = e(a)$ .

**Theorem 1.1.** [1] For each  $a \in G$  there exists a unique  $a^{-1} \in G$ .

**Theorem 1.2.** [2] Let  $G$  be a generalized group and  $ab = ba$  for all  $a, b$  in  $G$ . Then  $G$  is a group.

**Example 1.1.** Let  $G = \mathbb{R} \times \mathbb{R} \setminus \{0\} \times \mathbb{R}$ , where  $\mathbb{R}$  is the set of real numbers. Then  $G$  with the multiplication  $(a_1, b_1, c_1)(a_2, b_2, c_2) = (b_1a_1, b_1b_2, b_1c_2)$  is a generalized group.

In this paper we consider a generalized action of a generalized group on a set.

**Definition 1.1.** We say that a generalized group  $G$  acts on a set  $S$  if there exists a function

$$\begin{aligned} G \times S &\rightarrow S \\ (g, x) &\mapsto gx \end{aligned}$$

which is called a generalized action such that:

- $(g_1g_2)x = g_1(g_2x)$  for all  $g_1, g_2 \in G$ , and  $x \in S$ ;
- For all  $x \in S$  there exists  $e(g) \in G$  such that  $e(g)x = x$ .

**Example 1.2.** Let

$$G = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix}; \quad a, b, c \text{ and } d \text{ are real numbers} \right\}.$$

Then  $G$  with the product

$$\left( \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \begin{bmatrix} e & f \\ g & h \end{bmatrix} \right) \mapsto \begin{bmatrix} a & f \\ g & d \end{bmatrix}$$

is a generalized group, and the function

$$\begin{aligned} G \times \mathbb{R}^4 &\rightarrow \mathbb{R}^4 \\ \left( \begin{bmatrix} a & b \\ c & d \end{bmatrix}, (e, f, g, h) \right) &\mapsto (a, f, g, d) \end{aligned}$$

is a generalized action of  $G$  on  $\mathbb{R}^4$ .

**Theorem 1.3.** Let  $\tau : G \times S \rightarrow S$  be a generalized action, and  $G$  be an Abelian generalized group. Then  $G$  is a group and  $\tau$  is an action.

**Proof:** By theorem 1.2,  $G$  is a group. So  $\tau$  is an action.  $\square$

## 2. Elementary Results on Generalized Actions

If  $G$  acts on a set  $S$ , then the relation  $\sim$  defined by:

$$x_1 \sim x_2 \Leftrightarrow (g_1x_1 = x_2 \text{ and } g_2x_2 = x_1 \text{ for some } g_1, g_2 \in G)$$

is an equivalence relation.

**Definition 2.1.** If  $x \in S$ , then  $O(x) = \{y \in S; x \sim y\}$  is called the generalized orbit of  $x$ .

Now we deduce a generalized subgroup by a generalized action.

**Theorem 2.1.** Let a generalized group  $G$  act on a set  $S$ . Then for every  $x \in S$ , the set  $I_x = \{g \in G; gx = x\}$  is a generalized subgroup of  $G$ .

**Proof:** For  $g \in I_x$  we have:

$$\begin{aligned} gx = x &\Rightarrow (e(g)g)x = x \Rightarrow e(g)(gx) = x \\ &\Rightarrow e(g)x = x \Rightarrow e(g) \in I_x, \end{aligned}$$

and

$$g^{-1}x = g^{-1}(gx) = (g^{-1}g)x = e(g)x = x.$$

So

$$g^{-1} \in I_x.$$

If

$$g_1, g_2 \in I_x,$$

then

$$(g_1g_2)x = g_1(g_2x) = g_1x = x.$$

Hence

$$g_1g_2 \in I_x.$$

Thus  $I_x$  is a generalized subgroup of  $G$ .  $\square$

**Theorem 2.2.** Let  $f : G \rightarrow E$  be a generalized group homomorphism. Then

$$\begin{aligned} \tau : G \times E &\rightarrow E \\ (g, h) &\mapsto f(g)h \end{aligned}$$

is a generalized action.

**Proof:** Let  $g, g' \in G$  and  $h \in E$ . Then:

$$\begin{aligned} \tau(g, \tau(g', h)) &= f(g)\tau(g', h) = f(g)(f(g')h) \\ &= f(gg')h = \tau(gg', h). \end{aligned}$$

Moreover if  $g \in f^{-1}(\{e(h)\})$ , then:

$$\begin{aligned} \tau(e(g), h) &= f(e(g))h \\ &= e(f(g))h = e(e(h))h \\ &= e(h)h = h. \end{aligned}$$

Thus  $\tau$  is a generalized action.  $\square$

**Example 2.1.** Let  $G = \mathbb{R} \times \mathbb{R} \setminus \{0\}$  with multiplication  $(a, b)(c, d) = (bc, bd)$ . Since

$$\begin{aligned} f : G &\rightarrow \mathbb{R} \\ (a, b) &\mapsto \frac{a}{b} \end{aligned}$$

is a homomorphism, when the multiplication of  $\mathbb{R}$  is  $ab = b$ , the function

$$\begin{aligned} G \times \mathbb{R} &\rightarrow \mathbb{R} \\ ((a, b), c) &\mapsto \frac{ac}{b} \end{aligned}$$

is a generalized action.

### 3. Generalized Action of Normal Generalized Groups on a Set

A generalized group  $G$  is called a normal generalized group if  $e(ab) = e(a)e(b)$  for all  $a, b \in G$ . In this section we assume that  $G$  is a normal generalized group.

**Definition 3.1.** [3] A generalized subgroup  $N$  of a generalized group  $G$  is called a generalized normal subgroup if there exist generalized group  $E$  and a homomorphism  $f : G \rightarrow E$  such that for all  $a \in G$ ,

$$N_a = \phi \text{ or } N_a = \text{kernel } f_a,$$

where  $N_a = N \cap G_a$ ,  $G_a = \{g \in G; e(g) = e(a)\}$ , and  $f_a = f|_{G_a}$ .

**Example 3.1.** Let  $G$  be the generalized group of Example 2.1. Then  $N = \{(a, b); a = b \text{ or } a = 3b\}$  is a generalized normal subgroup of  $G$ .

**Theorem 3.1.** Let  $G$  be a normal generalized group, and  $f : G \rightarrow G$  be a generalized groups homomorphism. Moreover let  $N = \ker f$ . Then

$$\begin{aligned} \tau : \frac{G}{N} \times f(G) &\rightarrow f(G) \\ (gN_g, x) &\mapsto f(g)x \end{aligned}$$

is a generalized action.

**Proof:**

- i) If  $(g_1N_{g_1}, x_1) = (g_2N_{g_2}, x_2)$ , then  $g_1N_{g_1} = g_2N_{g_2}$  and  $x_1 = x_2$ .  
So  $N_{g_1} = N_{g_2}$ ,  $x_1 = x_2$  and  $g_1 = ng_2$  for some  $n \in N_{g_1}$ . Hence

$$f(g_1) = f(ng_2) = f(n)f(g_2) = f(e(g_2))f(g_2) = f(g_2).$$

Therefore  $f(g_1)x_1 = f(g_2)x_2$ . Thus  $\tau$  is well defined;

- ii) Let  $g_1N_{g_1}, g_2N_{g_2} \in \frac{G}{N}$  and  $x \in S$  are given. Then

$$\begin{aligned} \tau(g_1N_{g_1}, \tau(g_2N_{g_2}, x)) &= f(g_1)\tau(g_2N_{g_2}, x) = f(g_1)(f(g_2)x) \\ &= f(g_1g_2)x = \tau((g_1N_{g_1})(g_2N_{g_2}), x); \end{aligned}$$

- iii) If  $x \in f(G)$ , then  $x = f(g)$  for some  $g \in G$ , and we have

$$\tau(e(g)N_g, x) = f(e(g))x = f(e(g))f(g) = f(g) = x.$$

□

**Notation.** We denote the set

$$\left\{ \begin{array}{l} \varphi_g : S \rightarrow S, \quad g \in G \\ x \mapsto gx \end{array} \right\}$$

by  $H(S)$ .

The following example shows that  $H(S)$  with multiplication  $\varphi_{g_1}\varphi_{g_2} := \varphi_{g_1} \circ \varphi_{g_2}$  is not a generalized group.

**Example 3.2.** Let  $S = \mathbb{R} \times \mathbb{R} \setminus \{0\}$ , and  $G = \mathbb{R} \times \{1\}$  with multiplication:  $(a, 1)(b, 1) = (b, 1)$ . Then the function

$$\begin{aligned} G \times S &\rightarrow S \\ ((a, 1), (c, d)) &\mapsto (c, d) \end{aligned}$$

is a generalized action, but  $H(S)$  is not a generalized group. Because the inverse of an element is not unique.

**Theorem 3.2.** Let a generalized group  $G$  act on a set  $S$ , and the function

$$\begin{aligned} G &\rightarrow H(S) \\ g &\mapsto \varphi_g \end{aligned}$$

be a one-to-one mapping. Then  $H(S)$  with the multiplication  $\varphi_{g_1}\varphi_{g_2} := \varphi_{g_1} \circ \varphi_{g_2}$  is a generalized group. Moreover if  $G$  be normal, then  $H(S)$  is a normal generalized group.

**Proof:** Suppose that  $\varphi_g \in H(S)$  is given. If  $\varphi_g\varphi_h = \varphi_h\varphi_g = \varphi_g$ , then  $\varphi_{gh} = \varphi_{hg} = \varphi_g$ . So  $gh = hg = g$ . Hence the identity of  $\varphi_g$  is  $\varphi_{e(g)}$ . Thus  $h = e(g)$ .

One can easily deduce other properties of generalized group. Now let  $G$  be a normal generalized group, and  $\varphi_{g_1}, \varphi_{g_2} \in H(S)$ . Then

$$e(\varphi_{g_1}\varphi_{g_2}) = e(\varphi_{g_1g_2}) = \varphi_{e(g_1g_2)} = \varphi_{e(g_1)e(g_2)} = e(\varphi(g_1))e(\varphi(g_2)).$$

□

## References

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- [3] Mehrabi M., Molaei M. R., Oloomi A., *Generalized Subgroups and Homomorphisms*, 1999 (submitted for publication).