

The Schwarzian derivative on symmetric spaces of Cayley type

By

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Abstract

Let M be a symmetric space of Cayley type and f a conformal diffeomorphism of M . We study a relationship between the conformal factor of f and a generalized Schwarzian derivative of f .

§ 1. Introduction

Let \mathcal{H} be the single sheeted hyperboloid with the unique Lorentz metric \underline{g} . A transformation f of \mathcal{H} is called conformal, if

$$f^*\underline{g} = \mathbf{c}_f \underline{g}$$

where \mathbf{c}_f is the conformal factor of f .

It is well known that \mathcal{H} is conformally equivalent to $S^1 \times S^1 \setminus \Delta_{S^1}$ where S^1 is the unit circle and Δ_{S^1} the null space. The group of (orientation preserving) conformal diffeomorphisms of \mathcal{H} coincides with $\text{Diff}(S^1)$, the group of diffeomorphisms of the circle S^1 . In [KS] Kostant and Sternberg, pointed out an interesting relationship between the Schwarzian derivative of a transformation $f \in \text{Diff}(S^1)$ and the corresponding conformal factor \mathbf{c}_f (which is a singular function on the null space). More precisely, they proved that \mathbf{c}_f tends to 1 on \mathcal{H} as we approach infinity, and that the Hessain of the (extended) \mathbf{c}_f is the Schwarzian derivative of f .

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The single sheeted hyperboloid is the simplest example of a large class of parahermitian symmetric spaces, the Cayley type spaces. A such space is characterized as an open orbit in $S \times S$ where S is the Shilov boundary of a bounded symmetric domain of tube type [K₁]. In this paper, we will use this characterization to extend the results of Kostant and Sternberg to symmetric spaces of Cayley type.

§ 2. Causal symmetric spaces, Symmetric spaces of Cayley type

A causal structure on a smooth n -manifold M is a cone field $\mathcal{C} = (C_p)_{p \in M}$ where

$$C_p \subset T_p M$$

is a causal cone *ie.* non-zero, closed convex cone which is pointed ($C_p \cap -C_p = \{0\}$), generating ($C_p - C_p = T_p M$) and such that C_p depends smoothly on $p \in M$.

If $M = G/H$ is a homogeneous space, where G is a Lie group and $H \subset G$ a closed subgroup, then the causal structure is said to be G -invariant if for any $g \in G$

$$C_{g \cdot x} = Dg(x)(C_x), \text{ for } x \in M,$$

where $Dg(x)$ is the derivative of g at x .

Let $M = G/H$ be a symmetric space, *ie.* there exists an involution σ of G such that $(G^\sigma)^\circ \subset H \subset G^\sigma$ where $(G^\sigma)^\circ$ is the identity component of G^σ .

Let $\mathfrak{g} = \text{Lie}(G)$ be the Lie algebra of G and put

$$\mathfrak{h} = \mathfrak{g}(+1, \sigma), \quad \mathfrak{q} = \mathfrak{g}(-1, \sigma)$$

the eigenspaces of σ . Then $\mathfrak{g} = \mathfrak{h} \oplus \mathfrak{q}$ and the tangent space $T_{x_0} M$ at $x_0 = 1H$ can be identified with \mathfrak{q} . In this identification, the derivative $Dg(x_0)$, $g \in H$ corresponds to $\text{Ad}(g)$. Therefore an invariant causal structure on M is determined by a causal cone C in \mathfrak{q} which is $\text{Ad}(H)$ -invariant.

Suppose that G is semi-simple with a finite centre and that the pair $(\mathfrak{g}, \mathfrak{h})$ is irreducible (*ie.* there is no non-trivial ideal in \mathfrak{g} which is invariant under σ). Then, there exists a Cartan involution θ commuting with the given involution σ .

Let K be the corresponding maximal compact subgroup of G . Let $\mathfrak{k} = \mathfrak{g}(+1, \theta)$, $\mathfrak{p} = \mathfrak{g}(-1, \theta)$. Then $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ is the corresponding Cartan decomposition of \mathfrak{g} .

Let $\text{Cone}_H(\mathfrak{q})$ be the set of $\text{Ad}(H)$ -invariant causal cones in \mathfrak{q} . Then following Ólafsson (see [H-Ó]) the symmetric space M is called

- (CC) Compactly Causal space if there exists a $C \in \text{Cone}_H(\mathfrak{q})$ such that $C^\circ \cap \mathfrak{k} \neq \emptyset$.
- (NCC) Non-Compactly Causal space if there exists a $C \in \text{Cone}_H(\mathfrak{q})$ such that $C^\circ \cap \mathfrak{p} \neq \emptyset$.
- (CT) Cayley Type space if it is (CC) and (NCC).

For example, the hyperboloid of one sheet realized as $M = SO_0(2, 1)/SO_0(1, 1)$ is a special case of Cayley type symmetric spaces.

§ 3. Causal compactification of symmetric spaces of Cayley type

Let $D = G/K \subset V_{\mathbb{C}} = V + iV \simeq \mathbb{C}^n$ be a bounded symmetric domain in \mathbb{C} -vector space. The group G is the identity component of the group of holomorphic automorphisms of D , and $K = \{g \in G \mid g \cdot o = o\}$ the stabilizer of the base point $o = 1K \in D$, which is a maximal compact subgroup of G .

Suppose that D is of tube type, then V is an Euclidean Jordan algebra and

$$D \simeq T_{\Omega} = V + i\Omega$$

where Ω is the symmetric cone of V .

Let $z \mapsto \bar{z}$ the complex conjugation in $V_{\mathbb{C}}$ with respect to V and e the unit element of V . The set

$$S = \{z \in V_{\mathbb{C}} \mid \bar{z}z = e\}$$

is a connected submanifold of $V_{\mathbb{C}}$ which is a Riemannian symmetric space of compact type

$$S \simeq U/U_e,$$

where U is the identity component of the group of linear transformations $g \in GL(V_{\mathbb{C}})$ such that $gS = S$, and U_e is the stabilizer subgroup of $e \in S$.

There exists on $V_{\mathbb{C}}$ a U -invariant spectral norm $z \mapsto |z|$, and one can prove (see [F-K]) that D is the unit disc

$$D = \{z \in V_{\mathbb{C}} \mid |z| < 1\}$$

and S is its Shilov boundary.

Let

$$G(\Omega) = \{g \in GL(V) \mid g\Omega = \Omega\}.$$

It is a reductive Lie group which acts transitively on Ω . Let $G_0 = G(\Omega)^\circ$ be the identity component of $G(\Omega)$.

Let G^c be the identity component of the group of holomorphic automorphisms of T_Ω . Then G_0 is a Lie subgroup of G^c . The subgroups G_0 and $N^+ = \{t_v : z \mapsto z + v, v \in V\}$, together with the inversion $j : z \mapsto -z^{-1}$, generate the group G^c .

The quadratic representation P of the Jordan algebra V is given by $P(x) = 2L(x)^2 - L(x^2)$, where $L(x)$ is the multiplication by x .

The Lie algebra \mathfrak{g}^c of G^c is the set of vector fields on V of the form

$$X(z) = u + Tz + P(z)v \simeq (u, T, v),$$

where T is linear and $u, v \in V$.

Consider on G^c the involutions

$$\begin{aligned}\sigma^c(g) &= \nu \circ g \circ \nu \\ \theta^c(g) &= (-\nu) \circ g \circ (-\nu)\end{aligned}$$

where $\nu : z \mapsto \bar{z}^{-1}$. We use the same letters for the corresponding involutions on the Lie algebra \mathfrak{g}^c .

If $X = (u, T, v) \in \mathfrak{g}^c$, then

$$\sigma^c(X) = (v, -T^*, u) \quad \text{and} \quad \theta^c(X) = (-v, -T^*, -u),$$

Therefore,

$$\begin{aligned}\mathfrak{h}^c &:= \mathfrak{g}^c(\sigma^c, +1) = \{(u, T, u) \mid u \in V, T \in \mathfrak{k}_0\} \\ \mathfrak{q}^c &:= \mathfrak{g}^c(\sigma^c, -1) = \{(u, L(v), -u) \mid u, v \in V\} \\ \mathfrak{k}^c &:= \mathfrak{g}^c(\theta^c, +1) = \{(u, T, -u) \mid u \in V, T \in \mathfrak{k}_0\} \\ \mathfrak{p}^c &:= \mathfrak{g}^c(\theta^c, -1) = \{(u, L(v), u) \mid u \in V\}.\end{aligned}$$

Here \mathfrak{k}_0 is the algebra of derivations of V .

Consider the convex cones in \mathfrak{q}^c

$$\begin{aligned}C_1 &= \{(u, L(v), -u) \mid u + v \in -\bar{\Omega}, u - v \in \bar{\Omega}\}, \\ C_2 &= \{(u, L(v), -u) \mid u + v \in \bar{\Omega}, u - v \in \bar{\Omega}\}.\end{aligned}$$

Then C_1 and C_2 are $\text{Ad}(H^c)$ -invariant causal cones and

$$C_1 \cap \mathfrak{p}^c \neq \emptyset, \quad C_2 \cap \mathfrak{k}^c \neq \emptyset.$$

Let $\mathbf{c} : z \mapsto i(e+z)(e-z)^{-1}$ be the Cayley transform corresponding to the bounded symmetric domain D . Then we have

Theorem 3.1 ($[K_1, K_2]$).

1. $H := \mathbf{c}^{-1} \circ G_0 \circ \mathbf{c} = H^c := G \cap G^c$.
2. $M = G/H \simeq G^c/H^c$ is a symmetric space of Cayley type, and every Cayley type space is given in this way.

Let

$$\Delta_S = \{(z, w) \in S \times S \mid \Delta(z - w) = 0\}$$

be the null space of $S \times S$, where Δ is the determinant function of V , extended to $V_{\mathbb{C}}$.

The group G acts diagonally on $S \times S$. Furthermore,

Theorem 3.2 ($[K_1, K_2]$). *G acts transitively on $S \times S \setminus \Delta_S$ and the stabilizer of the base point $(e, -e) \in S \times S \setminus \Delta_S$ is the subgroup H . Therefore, $M = G/H \simeq S \times S \setminus \Delta_S$ and $S \times S$ is the (causal) compactification of M .*

For example,

$$\begin{aligned} D &= SU(n, n)/S(U(n) \times U(n)) \\ &= \{z \in \text{Mat}(n, \mathbb{C}) \mid I_n - z^*z \gg 0\} \\ S &= U(n) \\ M &= SU(n, n)/GL(n, \mathbb{C}) \times \mathbb{R}^+ \\ &\simeq \{(z, w) \in U(n) \times U(n) \mid \text{Det}(z - w) \neq 0\}, \end{aligned}$$

and

$$\begin{aligned} D &= Sp(n, \mathbb{R})/U(n) \\ &= \{z \in \text{Sym}(n, \mathbb{C}) \mid I_n - z^*z \gg 0\} \\ S &= U(n)/O(n) \\ &= \{z \in U(n) \mid z^t = z\} \\ M &= Sp(n, \mathbb{R})/GL(n, \mathbb{R}) \times \mathbb{R}^+ \\ &\simeq \{(z, w) \in U(n) \times U(n) \mid z^t = z, w^t = w, \text{Det}(z - w) \neq 0\}. \end{aligned}$$

§ 4. The Schwarzian derivative on the one-sheeted hyperboloid

Recall the classical cross-ratio of four points in the complex plane

$$[z_1, z_2, z_3, z_4] = \frac{z_1 - z_3}{z_2 - z_3} : \frac{z_1 - z_4}{z_2 - z_4}.$$

In [C] Élie Cartan have proved the following formula for the cross-ratio.

Theorem 4.1. *Consider $f : S^1 \rightarrow S^1$ and four points $x_1, x_2, x_3, x_4 \in S^1$ tending to $x \in S^1$. Then*

$$\begin{aligned} \frac{[f(x_1), f(x_2), f(x_3), f(x_4)]}{[x_1, x_2, x_3, x_4]} - 1 &= \frac{1}{6} S(f)(x)(x_1 - x_2)(x_3 - x_4) \\ &\quad + [\text{higher order terms}] \end{aligned}$$

where $S(f)$ denote the Schwarzian derivative of f ,

$$S(f) = \frac{f'''}{f'} - \frac{3}{2} \left(\frac{f''}{f'} \right)^2.$$

Recall that the one sheeted hyperboloid can be realized as

$$\begin{aligned} \mathcal{H} &= SL(2, \mathbb{R}) / \mathbb{R}_+^* \\ &\simeq SU(1, 1) / SO(1, 1) \\ &\simeq S^1 \times S^1 \setminus \Delta_{S^1} \\ &= \{(e^{i\theta_1}, e^{i\theta_2}) : \theta_1 \neq \theta_2\}. \end{aligned}$$

\mathcal{H} carries a (unique up to multiplicative constant) Lorentz metric, $\underline{\mathbf{g}}$, invariant under $SL(2, \mathbb{R})$,

$$\underline{\mathbf{g}} = \frac{d\theta_1 d\theta_2}{|e^{i\theta_1} - e^{i\theta_2}|^2}.$$

Let $f : S^1 \rightarrow S^1$ be a diffeomorphism viewed as a conformal transformation of $(\mathcal{H}, \underline{\mathbf{g}})$, $f^* \underline{\mathbf{g}} = \mathbf{c}_f \underline{\mathbf{g}}$. Applying the Cartan formula, when $\theta_1, \theta_2 \rightarrow \theta$, we get

$$\begin{aligned} \mathbf{c}_f(\theta_1, \theta_2) - 1 &= \frac{f^* \underline{\mathbf{g}}(\theta_1, \theta_2)}{\underline{\mathbf{g}}(\theta_1, \theta_2)} - 1 \\ &= \frac{1}{6} S(f)(e^{i\theta})(e^{i\theta_1} - e^{i\theta_2})^2 + \dots \end{aligned}$$

Then we have

Theorem 4.2 (Kostant-Sternberg [KS]). *The conformal factor $\mathbf{c}_f \rightarrow 1$ as $(\theta_1, \theta_2) \rightarrow \Delta_{S^1}$. In the other word \mathbf{c}_f tends to 1 on \mathcal{H} as we approach the infinity. So let us extend \mathbf{c}_f to be defined on $S^1 \times S^1$ by setting it equal to 1 on Δ_{S^1} . Then \mathbf{c}_f is twice differentiable on $S^1 \times S^1$, it has Δ_{S^1} as critical manifold and the Hessian $\text{Hess}(\mathbf{c}_f)$ is equal to $S(f)$.*

§ 5. The Schwarzian derivative on symmetric spaces of Cayley type

The Kantor [Kan] cross-ratio for z_1, z_2, z_3, z_4 in $V_{\mathbb{C}}$, is the rational function

$$[z_1, z_2, z_3, z_4] = \frac{\Delta(z_1 - z_3)}{\Delta(z_2 - z_3)} : \frac{\Delta(z_1 - z_4)}{\Delta(z_2 - z_4)}$$

where Δ is the determinant function of V (extended to $V_{\mathbb{C}}$).

The cross-ratio is invariant under the group G^c (when it is well defined) : The invariance under translations is clear. The invariance under the group G_0 follows from

the relation $\Delta(gz) = \chi(g)\Delta(z)$ where χ is a character of G_0 . The invariance under the inversion follows from the Hua identity $\Delta(w^{-1} - z^{-1}) = \Delta(z)^{-1}\Delta(z - w)\Delta(w)^{-1}$.

On the Cayley type symmetric space $M \simeq S \times S \setminus \Delta_S$ there exists a G -invariant measure

$$\underline{g} = |\Delta(z - w)|^{-\frac{2n}{r}} d\sigma(z)d\sigma(w),$$

where n is the dimension of V and r its rank.

Let $\langle \cdot, \cdot \rangle$ be the inner product of the Euclidean Jordan algebra V extended to a Hermitian inner product of $V_{\mathbb{C}}$.

Let $f : V_{\mathbb{C}} \rightarrow V_{\mathbb{C}}$ be a map of class C^3 . Let $z_j = z + ta_ju$ be four points tending to $z \in \bar{D}$, where $t \in \mathbb{R}$ and $a_i \in \mathbb{R}$ for $j = 1, 2, 3, 4$.

Theorem 5.1. *For any $\alpha \in \mathbb{R}$ we have*

$$\frac{[f(z_1), f(z_2), f(z_3), f(z_4)]^\alpha}{[z_1, z_2, z_3, z_4]^\alpha} - 1 = \alpha t^2 (a_1 - a_2)(a_3 - a_4) S(f)(z) + o(t^3)$$

where

$$S(f) = \frac{1}{6} \langle f''', f'^{-1} \rangle - \frac{1}{4} \langle P(f'') f'^{-1}, f'^{-1} \rangle$$

with $f' = Df(z)u$, $f'' = D^2f(z)(u, u)$ and $f''' = D^3f(z)(u, u, u)$

One can also prove

Theorem 5.2. *Let f be an orientation-preserving diffeomorphism of (M, \underline{g}) . Then*

1. $\mathbf{c}_f(z, w) \rightarrow 1$ as $z \rightarrow w$, the function \mathbf{c}_f extends smoothly to $S \times S$ and has, moreover, Δ_S as its critical set.
2. The Schwarzian $S(f)$ completely determines \mathbf{c}_f .

The complete proofs will appear in a forthcoming paper.

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