Solutions to a Singular Diffusion Equation

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§1. Introduction

We consider the following equation

$u_t = u_x ^{-\alpha} u_{xx},$	$(t,x) \in (0,T) \times (0,1)$	(E1)
u(t,0) = u(t,1) = 0,	$t \in [0,T]$	(E2)
$u(0,x) = u_0(x), u_0(x) \ge 0,$	0 < x < 1	(E3)

where $\alpha \geq 0$ and u_0 is a smooth function on (0,1). We may recognize this equation as a diffusion equation whose diffusion coefficient is $|u_x|^{-\alpha}$. So if there is a point where u_x is close to 0, then we can guess that very strong diffusion would be happen at that point. This is a simple example of *p*-Laplace equations. We refer to [EDB] for general regularity properties of solutions.

If we differentiate both sides of (E1)(with respect to x), and set $v = u_x$, then the equation would be described as follows

$$v_t = c(|v|^{p-2}v)_{xx} \quad (\mathbf{P})$$

where $p = 2 - \alpha$ and c is a certain constant. The property of the equation depends on p. If p > 2, this equation is called porous medium equation which presents a model of the diffusion in porous media. In the case of 1 , the equation is called plasma equation since it was derivedfrom the model describing the behavior of the plasma in strong magnetic $field. The later case (which corresponds to the case of <math>0 < \alpha < 1$ in (E1)), Berryman and Holland showed that all positive solution to the equation (P) vanishes in finite time (i.e. $\exists t_*$ such that $v(t, \cdot) \to 0$ as $t \to t_*$) under the Dirichlet boundary condition. Furthermore, the profile of each solution tends to that of a certain separable solution as $t \to t_*$ ([B],[BH1]).

But those results on (P) can not be applied directly to our problem. Because boundary conditions are different and another restriction $(\int_0^1 v(x)dx = 0)$ is required (so v(x) must be negative in some interval). We first look for non-negative separable solutions of (E1)-(E2) (§2), then we construct a stable difference scheme which approximates (E1) (§3). The result of the numerical experiment gives us a hint that the solutions to (E1)-(E3) also vanishes in finite time (We shall prove this fact in our forthcoming paper [OS]). We apply a rescaling technique to the scheme to obtain more precise value of the vanishing time and the asymptotic profile of the solutions (§4).

$\S 2.$ Separable Solution

First, we look for a non-negative separable solution $u(t,x) = U(x) \cdot T(t)$ of

$$u_t | u_x |^{\alpha} = u_{xx} \quad (2.1)$$

which is derived from (E1), where U(x) and T(t) are assumed to be nonnegative C^2 functions. Thus we get the following equations,

$$T^{\alpha-1}(t)T'(t) = U^{-1}(x)|U'(x)|^{-\alpha}U''(x) = -c \quad (S)$$

where c > 0, since $U''(x) \le 0$ can be obtained from U(0) = U(1) = 0 and $U \ge 0$.

Then we are led to the following equations for U(x) and T(t)

$$T(t)^{\alpha - 1} \cdot T'(t) = -c$$
(S1)
$$U''(x) = -cU(x)|U'(x)|^{\alpha}.$$
(S2)

Note if we assume $\tilde{U}(x) = \beta U(x)$ and $\tilde{T}(t) = \beta^{-1}T(t)$ where β is a positive constant, then $U(x)T(t) = \tilde{U}(x)\tilde{T}(t)$ and

$$\tilde{T}^{\alpha-1}(t)\tilde{T}'(t) = \tilde{U}^{-1}(x)|\tilde{U}'(x)|^{-\alpha}\tilde{U}''(x) = -\beta^{-\alpha}c.$$

Now, we may assume $c = 1/\alpha$ without loss of generality. Then from (S1), we can easily see that the separable solution can be written as follows

$$u(t, x) = (t_* - t)^{1/\alpha} U(x)$$

where $t_* > 0$ is the vanishing time and U(x) is a solution of the following equation

$$U''(x) = -\frac{1}{\alpha}U(x)|U'(x)|^{\alpha}, \quad U(x) > 0, \quad 0 < x < 1 \quad (D1)$$
$$U(0) = U(1) = 0. \quad (D2)$$

Thus, we can find U(x) from (D1), (D2) by the following way.

Proposition. Suppose $V(x) \ge 0$ satisfies the following equations

$$V''(x) = -\frac{1}{\alpha}V(x)(V'(x))^{\alpha}, \quad V'(x) \ge 0, \quad 0 \le x \le 1/2 \quad (V1)$$

$$V(0) = 0 \quad (V2)$$

$$V'(1/2) = 0. \quad (V3)$$

Then

$$U(x) = \begin{cases} V(x), & 0 \le x \le 1/2 \\ V(1-x), & 1/2 < x \le 1 \end{cases}$$

is a symmetric solution of (D1), (D2).

Proof. Multiply both sides of (V1) by $(V'(x))^{1-\alpha}$ and integrate them from 0 to x. Then with a standard calculation, we can obtain the following

$$V'(x) = (V'(0)^{2-\alpha} - c_{\alpha}V(x)^2)^{\frac{1}{2-\alpha}} \quad (2.2)$$

where $c_{\alpha} = \frac{2-\alpha}{2\alpha}$, and get

$$V(x) = V'(0)^{1-\frac{\alpha}{2}} c_{\alpha}^{-\frac{1}{2}} W^{-1}(V'(0)^{\frac{\alpha}{2}} c_{\alpha}^{\frac{1}{2}} x).$$

Here $W^{-1}(x)$ is the inverse function of a non-decreasing function W such that

$$W(y) := \int_0^y (1 - s^2)^{-\frac{1}{2 - \alpha}} ds, \ 0 \le y \le 1.$$

We note that the integral is convergent at y = 1 and we put $W(1) = M_{\alpha}(<\infty)$. But this solution only satisfies (V1) and (V2) in a certain interval not necessarily [0, 1/2]. To satisfy (V3), V has to attain its maximum value at $x_* \leq 1/2$. We can express the x_* at which V(x) attains its maximum as follows

$$x_* = V'(0)^{-\alpha/2} c_{\alpha}^{-1/2} M_{\alpha}.$$

And if V'(0) is sufficiently large so that $x_* \leq 1/2$, we can write the solution to (V1)-(V3) as follows

$$V(x) = \begin{cases} V'(0)^{1-\frac{\alpha}{2}} c_{\alpha}^{\frac{1}{2}} W^{-1}(V'(0)^{\frac{\alpha}{2}} c_{\alpha}^{\frac{1}{2}} x), & 0 \le x \le x_{*} \\ V'(0)^{1-\alpha/2} c_{\alpha}^{1/2}, & x_{*} < x \le 1/2. \end{cases}$$

Moreover, since $V'(x_*) = V''(x_*) = 0$ (because $\frac{d}{dx}W^{-1}(M) = 0$), we obtain $U(x) \in C^2(0,1)$. Obviously U(x) satisfies (D1) in (0,1/2) and U(x) satisfies (D2). Since the following equations

$$\frac{d}{dx}V(1-x) = -V'(1-x), \ \frac{d^2}{dx^2}V(1-x) = V''(1-x)$$

hold, U(x) satisfies (D1) also in (1/2, 1).

Remark. U(x) can be the profile of the separable solution of (E1)-(E2) (not (2.1)) only if V(x) attains its unique maximum value at x = 1/2. We can show this, for instance, by using the theory of viscosity solution.

§3 Difference Scheme

To calculate the numerical solution of (E), we introduce a modified equation (E') to overcome the difficulty in computing which occurs when the value of the u_x in (E1) reaches 0.

$$u_t = |u_x^2 + \delta|^{-\alpha/2} u_{xx}, \quad (t, x) \in (0, T) \times (0, 1), \quad (E')$$

This equation is an approximation of (E1).

Now we introduce our difference scheme for (E').

$$\frac{u_{j}^{n+1} - u_{j}^{n}}{\tau} = \{ (\frac{u_{j+1}^{n} - u_{j-1}^{n}}{2h})^{2} + \delta \}^{-\alpha/2} \cdot \frac{u_{j+1}^{n+1} - 2u_{j}^{n+1} + u_{j-1}^{n+1}}{h^{2}}, \quad (3.1)$$

$$u_{0}^{n} = u_{N}^{n} = 0, \quad (3.2)$$

$$u_{j}^{0} = u_{0}(jh), \quad (3.3)$$

$$1 < j < N - 1, n > 0,$$

where N is the number of meshes, h = 1/N is the mesh size, $\tau > 0$ is the discrete time increment, and u_j^n is the value of the numerical solution at net point $(n\tau, jh) \in [0, T] \times [0, 1]$.

We can show that the difference scheme (3.1)-(3.3) has L^{∞} -stability.

Proposition. (Stability of the scheme) Let $\{u_j^n\}$ be the solution of (3.1)-(3.3). Then $||u^n||_{\infty} \le ||u^0||_{\infty}$ for $\forall n > 0$ where $||u^n||_{\infty} = \max_j |u_j^n|$.

Proof. We prove it by showing the following inequalities hold.

$$\max_{j} u_{j}^{n} \leq \max_{j} u_{j}^{0} \quad (3.4)$$
$$\min_{j} u_{j}^{n} \geq \min_{j} u_{j}^{0}. \quad (3.5)$$

First, we rewrite (3.3) as follows

$$-\lambda_j^n u_{j+1}^{n+1} + (1+2\lambda_j^n) u_j^{n+1} - \lambda_j^n u_{j-1}^{n+1} = u_j^n$$

where

$$\lambda_j^n = \{ (\frac{u_{j+1}^n - u_{j-1}^n}{2h})^2 + \delta \}^{-\alpha/2} \cdot \frac{\tau}{h^2}.$$

Suppose for a fixed $n, u_m^n = \max_i u_j^n$. Then we can easily see that

$$\sup_{j} u_{j}^{n} = u_{m}^{n}$$

$$\leq -\lambda_{m}^{n-1}u_{m+1}^{n} + (1+2\lambda_{m}^{n-1})u_{m}^{n} - \lambda_{m-1}^{n-1}u_{m-1}^{n}$$

$$= u_{m}^{n-1}$$

$$\leq \sup_{j} u_{j}^{n-1}$$

and thus we can obtain (3.4). (3.5) can be shown in the same way.

Such a stability results is proved in [CGHH] for a singular equation related to a level set method for geometric evolutions in [CGG]. However our equation (E1) is not included in [CGHH].

§4 Rescaling

We computed the numerical solution for (3.1)-(3.3) with several cases of (E1). From the computation, we can see that the solution to (E1)-(E3) vanishes in finite time. So we tried to calculate u(t,x) more accurately especially when it vanishes, by using a "rescaling" approach for u and variable time increment τ in the following way.

Suppose

$$v(t,x) = Mu(M^{-\alpha}t,x).$$
 (3.6)

It is easy to see that if u(t, x) satisfies (2.1) then so does v(t, x). So we observe the value of $||u^n||_{\infty}$ at every time step. If the value become smaller than the given threshold (for instance 1/2), then we rescale u and τ by (3.6) with $M = ||u^n||_{\infty}^{-1}$ (i.e. multiply u_j^n by M and τ by $M^{-\alpha}$), and continue to calculate the values of the solution for the next time step, watching in the same way. Thus, we can keep the value of δ small enough compared with u, and τ would get smaller and smaller as t_n gets close to the vanishing time. In this way, we can obtain more accurate value of u and its vanishing time numerically.

For semilinear heat equations, such a rescaling technique is applied in [Ch].

§5. Result of Numerical Experiment

We computed the asymptotic behavior of the solutions to (E1)-(E3) by the scheme (3.1)-(3.3) with h = 1/64 (N = 64), $\tau = 2.5 \cdot h^2$ and $\delta = 10^{-100}$. Note that we took 0.5 as a threshold of the rescaling, so if $||u(t, \cdot)||_{\infty} < 1/2$ then rescaling would be done, so the $u(t, \cdot)$ would be magnified and the value of τ becomes smaller. We present rescaled profiles of u for 3 different initial data with $\alpha = 0.5$ (Figure 1 - 3). Each figure contains its initial data u_0 (labeled t0), and rescaled profile of $u(t, \cdot)$ (labeled t1-t5). The profile tj is obtained by rescaling j times of original picture. The time T_j of the profile tj is displayed below the each figures.

Initial data for each figures are as follows.

Figure 1.
$$u_0(x) = \sin \pi x$$

Figure 2. $u_0(x) = \frac{64}{27}x^3(1-x)$

Figure 3. $u_0(x) = \frac{16}{15}\mu(\mu(x))$ where $\mu(x) = \frac{15}{4}x(1-x)$.

The rescaled profile of numerical solutions to (E1)-(E3) can be seen to approach asymptotically to a certain profile.

All computed asymptotic profiles of u with different initial data (plotted in Figure 1 - 3) coincide, at least in plotting resolution as shown in Figure 4.

Furthermore, the asymptotic profile (labeled pde) also coincide with the numerical solution for (D1)-(D2) (labeled ode) obtained by solving (V1) - (V3) by shooting method (Figure 5).

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Figure 1.

T_{0}	=	0
T_1	=	0.04516602
T_2	=	0.08173087
T_3	=	0.1078698
T_4	=	0.1262872
T_{5}	=	0.1392649



Figure 2.

T_{0}	=	0
T_1	=	0.02868652
T_2	=	0.06010765
T_3	=	0.08589717
T_4	=	0.1042887
T_5	=	0.1170933



Figure 3.

T_{0}	Ξ	0.
T_1	=	0.02624512
T_2	=	0.06630449
T_3	=	0.09247656
T_4	=	0.1109373
T_{5}	=	0.1239462

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Figure 4. The asymptotic profiles of Figure 1 - 3 (labeled ft1 - ft3). They coincide with in plotting resolution.



Figure 5. The asymplotic profiles of Figure 1 - 3 (labeled pde) and rescaled profile of separable solution obtained by solving (V1)-(V3) numerically. They alose coincide with in plotting resolution.