

The Optimal Stopping Problem for Fuzzy Random Sequences

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1. Introduction and notations

Fuzzy random variables was first studied by Puri and Ralescu [7] and have been studied by many authors. Stojaković [9] discussed fuzzy conditional expectation and Puri and Ralescu [8] studied fuzzy martingales. This paper discusses optimal stopping problems of a sequence of fuzzy random variables.

Let (Ω, \mathcal{M}, P) be a probability space, \mathcal{M} is a σ -field and P is a probability measure. Let \mathbf{R} be the set of all real numbers and let \mathbf{N} be the set of all nonnegative integers. \mathcal{B} denotes the Borel σ -field of \mathbf{R} and \mathcal{I} denotes the set of all bounded closed sub-intervals of \mathbf{R} . A fuzzy set \tilde{a} is called a fuzzy number if the membership function $\tilde{a} : \mathbf{R} \mapsto [0, 1]$ is normal, upper-semicontinuous, convex and has a compact support. \mathcal{R} denotes the set of all fuzzy numbers. We write the α -cut ($\alpha \in [0, 1]$) of a fuzzy number $\tilde{a} \in \mathcal{R}$ by

$$\tilde{a}_\alpha := [\tilde{a}_\alpha^-, \tilde{a}_\alpha^+], \quad \alpha \in [0, 1].$$

A map $\tilde{X} : \Omega \mapsto \mathcal{R}$ is called a fuzzy random variable if

$$\{(\omega, x) \mid \tilde{X}(\omega)(x) \geq \alpha\} = \{(\omega, x) \mid x \in \tilde{X}_\alpha(\omega)\} \in \mathcal{M} \times \mathcal{B} \quad \text{for all } \alpha \in [0, 1], \quad (1.2)$$

where $\tilde{X}_\alpha(\omega) = [\tilde{X}_\alpha^-(\omega), \tilde{X}_\alpha^+(\omega)] := \{x \in \mathbf{R} \mid \tilde{X}(\omega)(x) \geq \alpha\} (\in \mathcal{I})$ is α -cut of fuzzy numbers $\tilde{X}(\omega)$ for $\omega \in \Omega$.

Lemma 1.1 ([10, Theorems 2.1 and 2.2]). For a map $\tilde{X} : \Omega \mapsto \mathcal{R}$, the following (i) and (ii) are equivalent:

- (i) \tilde{X} is a fuzzy random variable.
- (ii) The maps $\omega \mapsto \tilde{X}_\alpha^-(\omega)$ and $\omega \mapsto \tilde{X}_\alpha^+(\omega)$ are measurable for all $\alpha \in [0, 1]$.

A fuzzy random variable \tilde{X} is called integrably bounded if $\omega \mapsto \tilde{X}_\alpha^-(\omega)$ and $\omega \mapsto \tilde{X}_\alpha^+(\omega)$ are integrable for all $\alpha \in [0, 1]$. For an integrably bounded fuzzy random variable \tilde{X} , we define closed intervals

$$E(\tilde{X})_\alpha = \left[\int_\Omega \tilde{X}_\alpha^-(\omega) dP(\omega), \int_\Omega \tilde{X}_\alpha^+(\omega) dP(\omega) \right], \quad \alpha \in [0, 1]. \quad (1.3)$$

Then the map $\alpha \mapsto E(\tilde{X})_\alpha$ is left-continuous by the dominated convergence theorem. Therefore, the expectation $E(\tilde{X})$ is a fuzzy number defined by

$$E(\tilde{X})(x) := \sup_{\alpha \in [0, 1]} \min \{ \alpha, 1_{E(\tilde{X})_\alpha}(x) \} \quad \text{for } x \in \mathbf{R}. \quad (1.4)$$

For an integrably bounded fuzzy random variable \tilde{X} and a sub- σ -field $\mathcal{N}(\subset \mathcal{M})$, the conditional expectation $E(\tilde{X}|\mathcal{N})$ is defined as follows : For $\alpha \in [0, 1]$, there exist unique classical conditional expectations $E(\tilde{X}_\alpha^-|\mathcal{N})$ and $E(\tilde{X}_\alpha^+|\mathcal{N})$ such that

$$\int_{\Lambda} E(\tilde{X}_\alpha^-|\mathcal{N})(\omega) dP(\omega) = \int_{\Lambda} \tilde{X}_\alpha^-(\omega) dP(\omega) \quad \text{for all } \Lambda \in \mathcal{N}, \quad (1.5)$$

and

$$\int_{\Lambda} E(\tilde{X}_\alpha^+|\mathcal{N})(\omega) dP(\omega) = \int_{\Lambda} \tilde{X}_\alpha^+(\omega) dP(\omega) \quad \text{for all } \Lambda \in \mathcal{N}. \quad (1.6)$$

Then we can easily check the maps $\alpha \mapsto E(\tilde{X}_\alpha^-|\mathcal{N})(\omega)$ and $\alpha \mapsto E(\tilde{X}_\alpha^+|\mathcal{N})(\omega)$ are left-continuous by the monotone convergence theorem. Therefore, we define

$$E(\tilde{X}_\alpha|\mathcal{N})(\omega) := [E(\tilde{X}_\alpha^-|\mathcal{N})(\omega), E(\tilde{X}_\alpha^+|\mathcal{N})(\omega)] \quad \text{for } \omega \in \Omega. \quad (1.7)$$

and we give a conditional expectation by a fuzzy random variable

$$E(\tilde{X}|\mathcal{N})(\omega)(x) := \sup_{\alpha \in [0,1]} \min \left\{ \alpha, 1_{E(\tilde{X}_\alpha|\mathcal{N})(\omega)}(x) \right\} \quad \text{for } x \in \mathbf{R}. \quad (1.8)$$

2. An optimal stopping problem

Let $\{\tilde{X}_n\}_{n \in \mathbf{N}}$ be a sequence of fuzzy random variables. \mathcal{M}_n ($n \in \mathbf{N}$) denotes the smallest σ -field on Ω generated by $\{\tilde{X}_{k,\alpha}^-, \tilde{X}_{k,\alpha}^+ \mid k = 0, 1, 2, \dots, n; \alpha \in [0, 1]\}$, and \mathcal{M}_∞ denotes the smallest σ -field generated by $\bigcup_{n \in \mathbf{N}} \mathcal{M}_n$. A map $\tau : \Omega \mapsto \mathbf{N} \cup \{\infty\}$ is called a stopping time if

$$\{\tau = n\} \in \mathcal{M}_n \quad \text{for all } n \in \mathbf{N}. \quad (2.1)$$

Lemma 2.1. For a finite stopping time τ , we define

$$\tilde{X}_\tau(\omega) := \tilde{X}_n(\omega), \quad \omega \in \{\tau = n\} \quad \text{for } n \in \mathbf{N}. \quad (2.2)$$

Then, \tilde{X}_τ is a fuzzy random variable.

Let $g : \mathcal{I} \mapsto \mathbf{R}$ be a weighting function, which is continuous and monotone (see Fortemps and Roubens [3]). Using this g , the scalarization of the fuzzy reward will be done by

$$G_\tau(\omega) := \begin{cases} \int_0^1 g(\tilde{X}_{\tau,\alpha}(\omega)) d\alpha, & \text{if } \tau(\omega) < \infty \\ \limsup_{n \rightarrow \infty} \int_0^1 g(\tilde{X}_{n,\alpha}(\omega)) d\alpha & \text{if } \tau(\omega) = \infty. \end{cases} \quad (2.3)$$

Note that $g(\tilde{X}_{\tau,\alpha}(\omega)) \in \mathbf{R}$ and the map $\alpha \mapsto g(\tilde{X}_{\tau,\alpha}(\omega))$ is left-continuous on $(0, 1]$, so that the right-hand integral of (2.3) is well-defined. From the linearity of the weighting function g , we define

$$E(G_\tau) := E \left(\int_0^1 g(\tilde{X}_{\tau,\alpha}(\cdot)) d\alpha \right) = \int_0^1 g(E(\tilde{X}_\tau)_\alpha) d\alpha \quad \text{for stopping times } \tau. \quad (2.4)$$

Definition 2.1. A stopping time τ^* is called optimal if $E(G_{\tau^*}) \geq E(G_\tau)$ for all stopping times τ .

Define

$$Z_n(\omega) := \operatorname{ess\,sup}_{\tau: \tau \geq n} E(G_\tau | \mathcal{M}_n) = \operatorname{ess\,sup}_{\tau: \tau \geq n} E \left(\int_0^1 g(\tilde{X}_{\tau, \alpha}(\cdot)) \, d\alpha | \mathcal{M}_n \right), \quad (2.5)$$

for $\omega \in \Omega$, $n \in \mathbf{N}$.

Lemma 2.2. Define

$$\sigma^*(\omega) := \inf \{n \mid G_n(\omega) = Z_n(\omega)\}, \quad \omega \in \Omega,$$

where the infimum of the empty set is understood to be $+\infty$. If $\sigma^* < \infty$, then σ^* is an optimal stopping time for Definition 2.1.

3. A fuzzy stopping problem

Definition 3.1. A fuzzy stopping time is a map $\tilde{\tau} : \mathbf{N} \times \Omega \mapsto [0, 1]$ satisfying the following (i) – (iii):

- (i) For each $n \in \mathbf{N}$, $\tilde{\tau}(n, \cdot)$ is \mathcal{M}_n -measurable.
- (ii) For each $\omega \in \Omega$, $n \mapsto \tilde{\tau}(n, \omega)$ is non-increasing.
- (iii) For each $\omega \in \Omega$, there exists an integer n_0 such that $\tilde{\tau}(n, \omega) = 0$ for all $n \geq n_0$.

In the grade of membership of stopping times, ‘0’ and ‘1’ represent ‘stop’ and ‘continue’ respectively. The following lemmas imply the properties of fuzzy stopping times.

Lemma 3.1.

- (i) Let $\tilde{\tau}$ be a fuzzy stopping time. Define a map $\tilde{\tau}_\alpha : \Omega \mapsto \mathbf{N}$ by

$$\tilde{\tau}_\alpha(\omega) = \inf \{n \in \mathbf{N} \mid \tilde{\tau}(n, \omega) < \alpha\} \quad (\omega \in \Omega) \quad \text{for } \alpha \in (0, 1], \quad (3.1)$$

where the infimum of the empty set is understood to be $+\infty$. Then, we have:

- (a) $\{\tilde{\tau}_\alpha \leq n\} \in \mathcal{M}_n$ ($n \in \mathbf{N}$);
- (b) $\tilde{\tau}_\alpha(\omega) \leq \tilde{\tau}_{\alpha'}(\omega)$ ($\omega \in \Omega$) if $\alpha \geq \alpha'$;
- (c) $\lim_{\alpha' \uparrow \alpha} \tilde{\tau}_{\alpha'}(\omega) = \tilde{\tau}_\alpha(\omega)$ ($\omega \in \Omega$) if $\alpha > 0$;
- (d) $\tilde{\tau}_0(\omega) := \lim_{\alpha \downarrow 0} \tilde{\tau}_\alpha(\omega) < \infty$ ($\omega \in \Omega$).

(ii) Let $\{\tilde{\tau}_\alpha\}_{\alpha \in [0,1]}$ be maps $\tilde{\tau}_\alpha : \Omega \mapsto \mathbf{N}$ satisfying the above (a) – (d). Define a map $\tilde{\tau} : \mathbf{N} \times \Omega \mapsto [0, 1]$ by

$$\tilde{\tau}(n, \omega) := \sup_{\alpha \in [0,1]} \{\alpha \wedge 1_{\{\tilde{\tau}_\alpha > n\}}(\omega)\}, \quad n \in \mathbf{N}, \omega \in \Omega. \quad (3.2)$$

Then $\tilde{\tau}$ is a fuzzy stopping time.

Let $g : \mathcal{I} \mapsto \mathbf{R}$ be a weighting function (see [3]). For a fuzzy stopping time $\tilde{\tau}(n, \omega)$, the scalarization of the fuzzy reward will be done by

$$G_{\tilde{\tau}}(\omega) := \int_0^1 g(\tilde{X}_{\tilde{\tau}_\alpha, \alpha}(\omega)) d\alpha, \quad \omega \in \Omega, \quad (3.3)$$

where $\tilde{\tau}_\alpha$ is defined by (3.1). Note that $g(\tilde{X}_{\tilde{\tau}_\alpha, \alpha}(\omega)) \in \mathbf{R}$ and the map $\alpha \mapsto g(\tilde{X}_{\tilde{\tau}_\alpha, \alpha}(\omega))$ is left-continuous on $(0, 1]$, so that the integral of (3.3) is well-defined. From the linearity of the weighting function g , we define

$$E(G_{\tilde{\tau}}) := E\left(\int_0^1 g(\tilde{X}_{\tilde{\tau}_\alpha, \alpha}(\cdot)) d\alpha\right) = \int_0^1 g(E(\tilde{X}_{\tilde{\tau}_\alpha})_\alpha) d\alpha \quad (3.4)$$

for fuzzy stopping times $\tilde{\tau}$.

Definition 3.2.

- (i) Let $\alpha \in [0, 1]$. A stopping time τ^* is called α -optimal if $g(E(\tilde{X}_{\tau^*})_\alpha) \geq g(E(\tilde{X}_\tau)_\alpha)$ for all stopping times τ .
- (ii) A fuzzy stopping time $\tilde{\tau}^*$ is called optimal if $E(G_{\tilde{\tau}^*}) \geq E(G_{\tilde{\tau}})$ for all fuzzy stopping times $\tilde{\tau}$.

Define a sequence of subsets $\{\Lambda_n\}_{n=0}^\infty$ of Ω by

$$\Lambda_n := \{\omega \in \Omega \mid g(\tilde{X}_{n, \alpha}(\omega)) \geq E(g(\tilde{X}_{n+1, \alpha}) | \mathcal{M}_n)(\omega)\}, \quad n \in \mathbf{N}.$$

Assumption A (Monotone case).

$$\Lambda_0 \subset \Lambda_1 \subset \Lambda_2 \subset \Lambda_3 \subset \cdots \quad \text{and} \quad \bigcup_{n=0}^\infty \Lambda_n = \Omega.$$

In order to characterize α -optimal stopping times, let

$$\gamma_n^\alpha := \operatorname{ess\,sup}_{\tilde{\tau} : \tilde{\tau}_\alpha \geq n} E(g(\tilde{X}_{\tilde{\tau}_\alpha, \alpha}) | \mathcal{M}_n) \quad \text{for } n \in \mathbf{N}. \quad (3.5)$$

And we define a map $\tilde{\sigma}_\alpha^* : \Omega \mapsto \mathbf{N}$ by

$$\tilde{\sigma}_\alpha^*(\omega) := \inf \{n \mid g(\tilde{X}_{n, \alpha}(\omega)) = \gamma_n^\alpha(\omega)\} \quad (3.6)$$

for $\omega \in \Omega$ and $\alpha \in [0, 1]$, where the infimum of the empty set is understood to be $+\infty$. Then, the next lemma is given by Chow et al. [2].

Lemma 3.2 ([2, Theorems 4.1 and 4.5]). *Suppose Assumption A holds. Then, the following (i) and (ii) hold:*

- (i) $\gamma_n^\alpha(\omega) = \max\{g(\tilde{X}_{n,\alpha})(\omega), \gamma_{n+1}^\alpha(\omega)\}$ a.a. $\omega \in \Omega$ for $n \in \mathbf{N}$.
- (ii) Let $\alpha \in [0, 1]$. If $\tilde{\sigma}_\alpha^* < \infty$ a.s., then $\tilde{\sigma}_\alpha^*$ is α -optimal and $E(\gamma_0^\alpha) = E(g(\tilde{X}_{\tilde{\sigma}_\alpha^*, \alpha}))$.

In order to construct an optimal fuzzy stopping time from α -optimal stopping times $\{\tilde{\sigma}_\alpha^*\}_{\alpha \in [0,1]}$, we need a regularity condition.

Assumption B (Regularity of fuzzy stopping times). A fuzzy stopping time $\tilde{\sigma}^*$ is called regular if the map $\alpha \mapsto \tilde{\sigma}_\alpha^*(\omega)$ is non-increasing for each $\omega \in \Omega$.

Under Assumption B, we can assume the left-continuity of the map $\alpha \mapsto \tilde{\sigma}_\alpha^*(\omega)$ and we can define a map $\tilde{\sigma}^* : \mathbf{N} \times \Omega \mapsto [0, 1]$ by

$$\tilde{\sigma}^*(n, \omega) := \sup_{\alpha \in [0,1]} \min\{\alpha, 1_{\{\tilde{\sigma}_\alpha^* > n\}}(\omega)\}, \quad n \in \mathbf{N}, \omega \in \Omega. \quad (3.7)$$

Theorem 3.1. *Suppose Assumptions A and B hold. Then $\tilde{\sigma}^*$ is an optimal fuzzy stopping time.*

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