

MATRIX COEFFICIENTS OF THE MIDDLE DISCRETE SERIES OF $SU(2, 2)$

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1. INTRODUCTION

Among the discrete series representation of the non-compact real unitary group $SU(2, 2)$ of signature $(2+, 2-)$, there are representations whose Gel'fand-Kirillov dimensions are 5. Because other discrete series representations have Gel'fand-Kirillov dimension 6 (the large discrete series), or 4 (holomorphic or anti-holomorphic discrete series), and also because the $(\mathfrak{g}, \mathfrak{k})$ -cohomology of these representations have "Hodge type" $(2, 2)$ (others $(3, 1)$, $(1, 3)$, $(4, 0)$, $(0, 4)$), we call them *the middle discrete series*.

We determine the A -radial part of the matrix coefficients with minimal K -type of a representation belonging to the middle discrete series in this paper. It is written in terms of Gaussian hypergeometric series (Main Theorem 5.5). Our method of proof is a direct computation of the A -radial part of the Schmid operator, a gradient-type operator which characterize the minimal K -type vectors in the representation space of a discrete series representation (§3). The obtained operators constitute a holonomic system of 2 variables with rank 2 (§4). It is rather complicated difference-differential equations. We honestly solve this system step by step.

2. THE GROUP $SU(2, 2)$ AND ITS DISCRETE SERIES

2.1. Structure of $SU(2, 2)$ and its Lie algebra. Let G be the special unitary group $SU(2, 2)$ realized as

$$G = \{g \in SL_4(\mathbb{C}) \mid g^* I_{2,2} g = I_{2,2}\}, \quad I_{2,2} = \text{diag}(1, 1, -1, -1),$$

where $g^* = {}^t \bar{g}$ denotes the adjoint of a matrix g . Let $U(n)$ be the unitary group of degree n . Take a maximal compact subgroup $K = G \cap U(4) = S(U(2) \times U(2))$. We denote by $\mathfrak{g}, \mathfrak{k}$ the Lie algebra of G, K , respectively. Let $\theta(X) = -{}^t \bar{X}$ be a Cartan involution and $\mathfrak{g} = \mathfrak{k} + \mathfrak{p}$ the Cartan decomposition of \mathfrak{g} .

We set $\mathfrak{a} = \mathbb{R}H_1 + \mathbb{R}H_2$ with $H_1 = X_{23} + X_{32}, H_2 = X_{14} + X_{41}$, where the X_{ij} 's are elementary matrices given by

$$X_{ij} = (\delta_{ip}\delta_{jq})_{1 \leq p, q \leq 4} \quad \text{with Kronecker's delta } \delta_{ip}.$$

Then \mathfrak{a} is a maximally \mathbb{R} -split abelian subalgebra of \mathfrak{g} contained in \mathfrak{p} . Then the restricted root system $\Delta = \Delta(\mathfrak{g}, \mathfrak{a})$ is expressed as

$$\Delta = \Delta(\mathfrak{g}, \mathfrak{a}) = \{\pm\lambda_1 \pm \lambda_2, \pm 2\lambda_1, \pm 2\lambda_2\}.$$

where λ_j is the dual of H_j . We choose a positive system Δ^+ and a fundamental system Δ_{fund} of Δ :

$$\Delta^+ = \{\lambda_1 \pm \lambda_2, 2\lambda_1, 2\lambda_2\}, \quad \Delta_{\text{fund}} = \{\lambda_1 - \lambda_2, 2\lambda_2\}.$$

We also denote the corresponding nilpotent subalgebra by $\mathfrak{n} = \sum_{\beta \in \Delta^+} \mathfrak{g}_\beta$. Here \mathfrak{g}_β is the root subspace of \mathfrak{g} corresponding to $\beta \in \Delta^+$. Then one obtains an Iwasawa decomposition of \mathfrak{g} and G :

$$\mathfrak{g} = \mathfrak{n} + \mathfrak{a} + \mathfrak{k}, \quad G = NAK,$$

with $A = \exp \mathfrak{a}$, $N = \exp \mathfrak{n}$. Now let

$$\begin{aligned} E_1 &= H_{13} - \sqrt{-1}X_{13} + \sqrt{-1}X_{31}, & E_2 &= H_{24} - \sqrt{-1}X_{24} + \sqrt{-1}X_{42}, \\ E_3 &= 1/2(X_{12} - X_{21} - X_{14} + X_{23} + X_{32} - X_{41} - X_{34} + X_{43}), \\ E_4 &= \sqrt{-1}/2(X_{12} + X_{21} - X_{14} - X_{23} + X_{32} + X_{41} - X_{34} - X_{43}), \\ E_5 &= 1/2(X_{12} - X_{21} + X_{14} + X_{23} + X_{32} + X_{41} + X_{34} - X_{43}), \\ E_6 &= \sqrt{-1}/2(X_{12} + X_{21} + X_{14} - X_{23} + X_{32} - X_{41} + X_{34} + X_{43}), \end{aligned}$$

where $H_{ij} = \sqrt{-1}(X_{ii} - X_{jj})$ for $1 \leq i < j \leq 4$. Then it is easy to see that

$$\mathfrak{g}_{2\lambda_j} = \mathbb{R}E_j \quad (j = 1, 2), \quad \mathfrak{g}_{\lambda_1 + \lambda_2} = \mathbb{R}E_3 + \mathbb{R}E_4, \quad \mathfrak{g}_{\lambda_1 - \lambda_2} = \mathbb{R}E_5 + \mathbb{R}E_6.$$

2.2. Parametrization of the discrete series. Let us now parametrize the discrete series of $SU(2, 2)$. Take a compact Cartan subalgebra \mathfrak{t} defined by

$$\mathfrak{t} = \mathbb{R}\sqrt{-1}h^1 + \mathbb{R}\sqrt{-1}h^2 + \mathbb{R}\sqrt{-1}I_{2,2} \quad \text{with } h^1 = X_{11} - X_{22}, h^2 = X_{33} - X_{44}$$

and let $\mathfrak{t}_\mathbb{C}$ be its complexification. Then the absolute root system, of type A_3 , is given by

$$\tilde{\Delta} = \tilde{\Delta}(\mathfrak{g}_\mathbb{C}, \mathfrak{t}_\mathbb{C}) = \{ [\pm 2, 0; 0], [0, \pm 2; 0], [\pm 1, \pm 1; \pm 2] \}.$$

where $\beta = [r, s; u]$ means $r = \beta(h^1)$, $s = \beta(h^2)$ and $u = \beta(I_{2,2})$. We write the set of compact positive roots by $\tilde{\Delta}_c^+ = \{ [2, 0; 0], [0, 2; 0] \}$ and we fix it hereafter. The Weyl group $\tilde{W} = \tilde{W}(\mathfrak{g}_\mathbb{C}, \mathfrak{t}_\mathbb{C})$ is generated by s_1, s_2, s_3 where

$$\begin{aligned} s_1[r, s; u] &= [-r, s; u], \\ s_2[r, s; u] &= [(r - s + u)/2, (-r + s + u)/2; r + s], \\ s_3[r, s; u] &= [r, -s; u]. \end{aligned}$$

We identify \tilde{W} and the symmetric group \mathfrak{S}_4 of degree 4 by the map: $s_j \mapsto (j, j+1)$. The compact Weyl group is given by $\tilde{W}_c = \langle s_1, s_3 \rangle$, also identified canonically with the subgroup $\mathfrak{S}_2 \times \mathfrak{S}_2$.

There are exactly six positive systems $\tilde{\Delta}_I^+, \tilde{\Delta}_{II}^+, \dots, \tilde{\Delta}_{VI}^+$ containing $\tilde{\Delta}_c^+$, defined by $\tilde{\Delta}_J^+ = w_J \tilde{\Delta}_c^+$, where

$$\tilde{\Delta}^+ = \{ [2, 0; 0], [0, 2; 0], [\pm 1, \pm 1; 2] \}$$

and the elements $w_J \in \tilde{W}$ are given by

$$w_I = 1, w_{II} = s_2, w_{III} = s_2 s_3, w_{IV} = s_2 s_1, w_V = s_2 s_3 s_1, w_{VI} = s_2 s_1 s_3 s_2.$$

We denote by $\tilde{\Delta}_{J,n}^+$ the noncompact positive roots in $\tilde{\Delta}_J^+$.

By definition, the space of the Harish-Chandra parameters Ξ_c is given by

$$\Xi_c = \{ \Lambda \in \mathfrak{t}_\mathbb{C}^* \mid \Lambda \text{ is } \tilde{\Delta}\text{-regular, } K\text{-analytically integral and } \tilde{\Delta}_c^+\text{-dominant} \}.$$

Put $\Xi_J = \{\Lambda \in \Xi_c \mid \tilde{\Delta}_J^+ \text{-dominant}\}$. We also put $\rho_{G,J} = 2^{-1} \sum_{\beta \in \tilde{\Delta}_J^+} \beta$, $\rho_c = 2^{-1} \sum_{\beta \in \tilde{\Delta}_c^+} \beta$ and $\rho_{J,n} = 2^{-1} \sum_{\beta \in \tilde{\Delta}_{J,n}^+} \beta$ the half sum of positive roots, the half sum of compact positive roots and the half sum of noncompact positive roots, respectively. The space $\Xi_c \subset \mathfrak{t}_c^*$ are divided into six parts: $\Xi_c = \bigcup_{I \leq J \leq V} \Xi_J$. For $\Lambda \in \bigcup_{I \leq J \leq VI} \Xi_J$, we denote the corresponding discrete series by π_Λ . We say that π_Λ is the middle discrete series representation if $\Lambda \in \Xi_{III} \cup \Xi_{IV}$. Particularly in this case, we have

$$\Delta_{III}^+ = \{[1, \pm 1; \pm 2]\}, \quad \rho_{III,n} = [2, 0; 0], \quad \Delta_{IV}^+ = \{[\pm 1, 1; \pm 2]\}, \quad \rho_{IV,n} = [0, 2; 0].$$

2.3. Representations of the maximal compact subgroup. Let $d_1, d_2 \in \mathbb{Z}_{\geq 0}$ and $d_3 \in \mathbb{Z}$. For $d = [d_1, d_2; d_3] \in \mathfrak{t}_c^*$, define $\tau_d \in \hat{K}$ by the following rule ($j = 1, 2$):

$$(1) \quad \begin{aligned} \tau_d(h^j) f_{k_1 k_2}^{(d)} &= (2k_j - d_j) f_{k_1 k_2}^{(d)}, & \tau_d(I_{2,2}) f_{k_1 k_2}^{(d)} &= d_3 f_{k_1 k_2}^{(d)}, \\ \tau_d(e_+^j) f_{k_1 k_2}^{(d)} &= (d_j - k_j) f_{k_1 + \delta_{1j}, k_2 + \delta_{2j}}^{(d)}, & \tau_d(e_-^j) f_{k_1 k_2}^{(d)} &= k_j f_{k_1 - \delta_{1j}, k_2 - \delta_{2j}}^{(d)}. \end{aligned}$$

Here, $V_d = \{f_{k_1 k_2}^{(d)} \mid 0 \leq k_j \leq d_j\}_{\mathbb{C}}$ is the standard basis (see [2, §3]) and

$$h^1, \quad h^2, \quad e_+^1 = X_{12}, \quad e_+^2 = X_{34}, \quad e_-^j = {}^t e_+^j$$

are the generators of \mathfrak{k}_c . Then according to [2, Prop. 3.1], \hat{K} is exhausted by

$$\{(\tau_d, V_d) \mid d = [d_1, d_2; d_3], d_1 + d_2 + d_3 \text{ is even}\}.$$

The adjoint representation $\text{Ad} = \text{Ad}_{\mathfrak{p}_c}$ of K on \mathfrak{p}_c is decomposed into a direct sum of two irreducible subrepresentations: $\mathfrak{p}_c = \mathfrak{p}_+ + \mathfrak{p}_-$, where,

$$\mathfrak{p}_+ = \mathbb{C}X_{13} + \mathbb{C}X_{14} + \mathbb{C}X_{23} + \mathbb{C}X_{24}, \quad \mathfrak{p}_- = {}^t \mathfrak{p}_+.$$

In fact, $\text{Ad}_{\pm} = \text{Ad}|_{\mathfrak{p}_{\pm}}$ is isomorphic to $\tau_{[1,1;\pm 2]}$, respectively. For later use, we fix the K -isomorphisms $\iota_{\pm} : \mathfrak{p}_{\pm} \rightarrow V_{[1,1;\pm 2]}$ (write $f_{kl} = f_{kl}^{[1,1;\pm 2]}$):

$$\begin{aligned} \iota_+ : (X_{23}, X_{13}, X_{24}, X_{14}) &\mapsto (f_{00}, f_{10}, -f_{01}, -f_{11}), \\ \iota_- : (X_{41}, X_{31}, X_{42}, X_{32}) &\mapsto (f_{00}, f_{01}, -f_{10}, -f_{11}), \quad ([2, \text{Prop. 3.10}].) \end{aligned}$$

The irreducible decomposition of \mathfrak{t}_c -module $V_d \otimes \mathfrak{p}_c$ is given as

$$V_d \otimes \mathfrak{p}_c = V_d \otimes \mathfrak{p}_+ \oplus V_d \otimes \mathfrak{p}_-, \quad V_d \otimes \mathfrak{p}_{\pm} \simeq \bigoplus_{\epsilon_1, \epsilon_2 \in \{\pm 1\}} V_{[r+\epsilon_1, s+\epsilon_2; u \pm 2]}.$$

The projectors

$$P_{rs}^{(\epsilon_1, \epsilon_2)} : V_d \otimes \mathfrak{p}_+ \rightarrow V_{[r+\epsilon_1, s+\epsilon_2; u+2]}, \quad \bar{P}_{rs}^{(\epsilon_1, \epsilon_2)} : V_d \otimes \mathfrak{p}_- \rightarrow V_{[r+\epsilon_1, s+\epsilon_2; u-2]},$$

are explicitly given by [2, Lemma 3.12].

2.4. K -types of the middle discrete series representations. Let π_Λ be the discrete series representation of G with Harish-Chandra parameter $\Lambda \in \Xi_J$. Then the Blatter parameter of π_Λ becomes $\lambda = \Lambda + \rho_{G,J} - 2\rho_c$. In the following we put $d = [r, s; u]$.

If $\Lambda \in \Xi_{III}$ (resp. Ξ_{IV}), then the K -types τ_λ of π_Λ are parametrized by

$$\begin{aligned} [r, s; u] \text{ with } r > s + 2 + |u|, r \in \mathbb{Z}_{>0}, s \in \mathbb{Z}_{\geq 0}, r + s + u \in 2\mathbb{Z}, \\ (\text{resp. } [r, s; u] \text{ with } s > r + 2 + |u|, r \in \mathbb{Z}_{\geq 0}, s \in \mathbb{Z}_{>0}, r + s + u \in 2\mathbb{Z}). \end{aligned}$$

3. SCHMID'S DIFFERENTIAL OPERATOR

3.1. **(τ, τ^*) -matrix coefficient of the middle discrete series.** Let (π_Λ, H_Λ) be a middle discrete series representation, and (τ_d, V_d) its minimal K -type. Put $d = [r, s; u]$. Then the contragredient representation τ_d^* of τ_d is isomorphic to $\tau_{[r, s; -u]}$. We identify the representation spaces V_d, V_d^* with their unique images in H_Λ, H_Λ^* respectively. Then the matrix coefficient of π is defined by

$$\langle \pi_\Lambda(g)v, w^* \rangle$$

for $v \in V_d, w^* \in V_d^* \subset H_\Lambda^*$. Here we consider a more convenient vector-valued function:

$$\Phi_{\pi, \tau}(g) = \sum_{i, j, k, l} \langle \pi_\Lambda(g) f_{kl}^*, f_{ij}^* \rangle f_{ij} \otimes f_{kl}$$

where $\{f_{ij} = f_{ij}^{[r, s; u]}\}_{ij}$ (resp. $\{f_{kl} = f_{kl}^{[r, s; -u]}\}_{kl}$) is a standard basis of V_d (resp. V_d^*). Then we find that $\Phi_{\pi, \tau}$ belongs to the following function space:

$$C_{\tau, \tau^*}^\infty(K \backslash G / K) = \{ \phi: G \rightarrow V_d \otimes V_d^* \mid \phi(k_1 g k_2) = \tau_d(k_1) \otimes \tau_d^*(k_2^{-1}) \phi(g), \quad k_j \in K \}.$$

For simplicity, we write the index $M = (i, j; k, l)$ and coefficients $c_M(g) = \langle \pi_\Lambda(g) f_{ij}^*, f_{kl}^* \rangle$.

Due to the Cartan decomposition $G = KAK$, $c_M(g)$ is determined uniquely by its restriction to A .

Lemma 3.1. *If c_M is not zero, it satisfies the condition:*

$$k_1 + l_1 + k_2 + l_2 = r + s.$$

Proof. The centralizer of A in K is

$$\{m = \text{diag}(u, \bar{u}\epsilon, u, \bar{u}\epsilon) \mid |u| = 1, \epsilon = \pm 1\}.$$

Therefore $\phi \in C_{\tau, \tau^*}^\infty(K \backslash G / K)$ satisfies

$$\phi(mam^{-1}) = \phi(a) \quad a \in A, m \in Z_K(A),$$

which implies the assertion. □

We can construct two intertwining operators Φ_π^R, Φ_π^L using the matrix coefficients:

$$\Phi_\pi^R \in \text{Hom}_{(\mathfrak{g}, K)}(\pi_\Lambda, C_{\tau_d}^\infty(K \backslash G)),$$

$$\Phi_\pi^L \in \text{Hom}_{(\mathfrak{g}, K)}(\pi_\Lambda^*, C_{\tau_d^*}^\infty(G / K)),$$

by

$$\Phi_\pi^R(v)(g) = \sum_{ij} \langle \pi(g)v, f_{ij}^* \rangle f_{ij},$$

$$\Phi_\pi^L(w)(g) = \sum_{kl} \langle f_{kl}^*, \pi^*(g^{-1})w \rangle f_{kl}.$$

If we put

$$\Phi_{\pi, \tau}^R(g) = \sum_{kl} \Phi_\pi^R(f_{kl})(g) \otimes f_{kl},$$

$$\Phi_{\pi, \tau}^L(g) = \sum_{ij} f_{ij} \otimes \Phi_\pi^L(f_{ij})(g),$$

then $\Phi_{\pi,\tau}^R(g)$ and $\Phi_{\pi^*,\tau}^L(g)$ are identical to $\Phi_{\pi,\tau}(g)$.

3.2. Some functions on A . We put $a_i = \exp(t_i)$ for the element $a = \exp(t_1 H_1 + t_2 H_2)$ of the \mathbb{R} -split torus A , We use for notation the following symbols:

$$\begin{aligned} \operatorname{sh}(x) &= (x - x^{-1})/2, & \operatorname{ch}(x) &= (x + x^{-1})/2, & \operatorname{cth}(x) &= \operatorname{ch}(x)/\operatorname{sh}(x), \\ D = D(a) &= \operatorname{sh}(a_1^2) - \operatorname{sh}(a_2^2), & p = p(a) &= \operatorname{ch}(a_1)\operatorname{ch}(a_2), & t = t(a) &= (\operatorname{ch}(a_1)/\operatorname{ch}(a_2))^2, \\ z_{\pm}(t) &= (\operatorname{ch}(a_1)/\operatorname{ch}(a_2) \pm \operatorname{ch}(a_2)/\operatorname{ch}(a_1)), & \partial_j &= a_j \frac{\partial}{\partial a_j}, & \partial_t &= t \frac{\partial}{\partial t}, & \partial_p &= p \frac{\partial}{\partial p}. \end{aligned}$$

3.3. The Schmid operator. Let τ_{d_1}, τ_{d_2} be representations of K . For $F(g) \in C_{d_1, d_2}^{\infty}(K \backslash G / K)$ and orthonormal basis $\{X_k\}$ of \mathfrak{p} ,

$$\begin{aligned} \nabla_{d_1, d_2}^R F(g) &= \sum_k R_{X_k} F(g) \otimes X_k, \\ \nabla_{d_1, d_2}^L F(g) &= \sum_k L_{X_k} F(g) \otimes X_k, \end{aligned}$$

are called the Schmid operator. Here R_g , (resp. L_g) is a right (resp. left) translation. Put $\mathcal{D}_{d_1, d_2}^{(J), R} = P_{d_2}^{(J)} \circ \nabla_{d_1, d_2}^R$, $\mathcal{D}_{d_1, d_2}^{(J), L} = P_{d_1}^{(J)} \circ \nabla_{d_1, d_2}^L$ with defining the projectors

$$P_d^{(J)} : V_d \otimes \mathfrak{p}_{\mathbb{C}} \rightarrow V_d^- = \bigoplus_{\beta \in \tilde{\Delta}_{n, J}^+} V_{d-\beta}.$$

Theorem 3.2 ([7]). *Let $\Lambda \in \Xi_J$. Then,*

$$\begin{aligned} \operatorname{Hom}_{(\mathfrak{g}, K)}(\pi_{\Lambda}, C_{\tau_d}^{\infty}(K \backslash G)) &\simeq \ker(\mathcal{D}_{d, d^*}^{(J), R}), \\ \operatorname{Hom}_{(\mathfrak{g}, K)}(\pi_{\Lambda}^*, C_{\tau_d^*}^{\infty}(G / K)) &\simeq \ker(\mathcal{D}_{d, d^*}^{(J), L}), \end{aligned}$$

where d is the Blattner parameter of π_{Λ} .

We see that $\nabla^{L/R}$ is also decomposed into $\nabla_+^{L/R} + \nabla_-^{L/R}$ along the decomposition $\mathfrak{p}_{\mathbb{C}} = \mathfrak{p}_+ + \mathfrak{p}_-$ (see [2, §6]). The following formula is found in [5]:

Theorem 3.3 (Koseki-Oda). *Let $\nabla_{\pm}^{R/L}$ be the Schmid operators and $\rho_A(\nabla_{\pm}^{R/L})$ their restriction to A . Put $Z_{13} = 2^{-1}(I_{2,2} + h^1 - h^2)$, $Z_{24} = 2^{-1}(I_{2,2} - h^1 + h^2)$ and $\tau_{\pm}^{(*)} = \tau^{(*)} \otimes \operatorname{Ad}_{\pm}$. Then, we have*

$$\begin{aligned} \rho_A(\nabla_+^R)\phi &= \frac{1}{2} \left(\partial_1 - \operatorname{sh}(a_1^2)^{-1} \tau(Z_{13}) - \operatorname{cth}(a_1^2) \tau_+^*(Z_{13}) + 2 \operatorname{cth}(a_1^2) + \frac{2}{D} \operatorname{sh}(a_1^2) \right) (\phi \otimes X_{13}) \\ &+ \frac{1}{2} \left(\partial_2 - \operatorname{sh}(a_2^2)^{-1} \tau(Z_{24}) - \operatorname{cth}(a_2^2) \tau_+^*(Z_{24}) + 2 \operatorname{cth}(a_2^2) - \frac{2}{D} \operatorname{sh}(a_2^2) \right) (\phi \otimes X_{24}) \\ &+ \frac{1}{D} (\operatorname{ch}(a_1) \operatorname{sh}(a_2) \tau(e_-^1) + \operatorname{sh}(a_1) \operatorname{ch}(a_2) \tau(e_-^2) + \operatorname{sh}(a_2) \operatorname{ch}(a_2) \tau_+^*(e_-^1) \\ &+ \operatorname{sh}(a_1) \operatorname{ch}(a_1) \tau_+^*(e_-^2)) (\phi \otimes X_{14}) \\ &- \frac{1}{D} (\operatorname{sh}(a_1) \operatorname{ch}(a_2) \tau(e_+^1) + \operatorname{ch}(a_1) \operatorname{sh}(a_2) \tau(e_+^2) + \operatorname{sh}(a_1) \operatorname{ch}(a_1) \tau_+^*(e_+^1) \\ &+ \operatorname{sh}(a_2) \operatorname{ch}(a_2) \tau_+^*(e_+^2)) (\phi \otimes X_{23}), \end{aligned}$$

$$\begin{aligned}
\rho_A(\nabla_-^R)\phi &= \frac{1}{2} \left(\partial_1 + \text{sh}(a_1^2)^{-1}\tau(Z_{13}) + \text{cth}(a_1^2)\tau_2^-(Z_{13}) + 2 \text{cth}(a_1^2) + \frac{2}{D} \text{sh}(a_1^2) \right) (\phi \otimes X_{31}) \\
&+ \frac{1}{2} \left(\partial_2 + \text{sh}(a_2^2)^{-1}\tau(Z_{24}) + \text{cth}(a_2^2)\tau_2^-(Z_{24}) + 2 \text{cth}(a_2^2) - \frac{2}{D} \text{sh}(a_2^2) \right) (\phi \otimes X_{42}) \\
&- \frac{1}{D} (\text{ch}(a_1) \text{sh}(a_2)\tau(e_+^1) + \text{sh}(a_1) \text{ch}(a_2)\tau(e_+^2) + \text{sh}(a_2) \text{ch}(a_2)\tau_2^-(e_+^1) \\
&+ \text{sh}(a_1) \text{ch}(a_1)\tau_2^-(e_+^2)) (\phi \otimes X_{41}) \\
&+ \frac{1}{D} (\text{sh}(a_1) \text{ch}(a_2)\tau(e_-^1) + \text{ch}(a_1) \text{sh}(a_2)\tau(e_-^2) + \text{sh}(a_1) \text{ch}(a_1)\tau_2^-(e_-^1) \\
&+ \text{sh}(a_2) \text{ch}(a_2)\tau_2^-(e_-^2)) (\phi \otimes X_{32}), \\
\rho_A(\nabla_+^L)\phi &= -\frac{1}{2} \left(\partial_1 - \text{sh}(a_1^2)^{-1}\tau^*(Z_{13}) - \text{cth}(a_1^2)\tau_+(Z_{13}) + 2 \text{cth}(a_1^2) + \frac{2}{D} \text{sh}(a_1^2) \right) (\phi \otimes X_{13}) \\
&- \frac{1}{2} \left(\partial_2 - \text{sh}(a_2^2)^{-1}\tau^*(Z_{24}) - \text{cth}(a_2^2)\tau_+(Z_{24}) + 2 \text{cth}(a_2^2) - \frac{2}{D} \text{sh}(a_2^2) \right) (\phi \otimes X_{24}) \\
&- \frac{1}{D} (\text{ch}(a_1) \text{sh}(a_2)\tau^*(e_-^1) + \text{sh}(a_1) \text{ch}(a_2)\tau^*(e_-^2) + \text{sh}(a_2) \text{ch}(a_2)\tau_+(e_-^1) \\
&+ \text{sh}(a_1) \text{ch}(a_1)\tau_+(e_-^2)) (\phi \otimes X_{14}) \\
&+ \frac{1}{D} (\text{sh}(a_1) \text{ch}(a_2)\tau^*(e_+^1) + \text{ch}(a_1) \text{sh}(a_2)\tau^*(e_+^2) + \text{sh}(a_1) \text{ch}(a_1)\tau_+(e_+^1) \\
&+ \text{sh}(a_2) \text{ch}(a_2)\tau_+(e_+^2)) (\phi \otimes X_{23}), \\
\rho_A(\nabla_-^L)\phi &= -\frac{1}{2} \left(\partial_1 + \text{sh}(a_1^2)^{-1}\tau^*(Z_{13}) + \text{cth}(a_1^2)\tau^-(Z_{13}) + 2 \text{cth}(a_1^2) + \frac{2}{D} \text{sh}(a_1^2) \right) (\phi \otimes X_{31}) \\
&- \frac{1}{2} \left(\partial_2 + \text{sh}(a_2^2)^{-1}\tau^*(Z_{24}) + \text{cth}(a_2^2)\tau^-(Z_{24}) + 2 \text{cth}(a_2^2) - \frac{2}{D} \text{sh}(a_2^2) \right) (\phi \otimes X_{42}) \\
&+ \frac{1}{D} (\text{ch}(a_1) \text{sh}(a_2)\tau^*(e_+^1) + \text{sh}(a_1) \text{ch}(a_2)\tau^*(e_+^2) + \text{sh}(a_2) \text{ch}(a_2)\tau^-(e_+^1) \\
&+ \text{sh}(a_1) \text{ch}(a_1)\tau^-(e_+^2)) (\phi \otimes X_{41}) \\
&- \frac{1}{D} (\text{sh}(a_1) \text{ch}(a_2)\tau^*(e_-^1) + \text{ch}(a_1) \text{sh}(a_2)\tau^*(e_-^2) + \text{sh}(a_1) \text{ch}(a_1)\tau^-(e_-^1) \\
&+ \text{sh}(a_2) \text{ch}(a_2)\tau^-(e_-^2)) (\phi \otimes X_{32}).
\end{aligned}$$

4. HOLONOMIC SYSTEM FOR THE SPHERICAL FUNCTIONS

We treat the case of $\Lambda \in \Xi_{\text{III}} \cup \Xi_{\text{IV}}$. Then, the Blattner parameter of π_Λ in $\Lambda \in \Xi_{\text{III}}$ (resp. $\Lambda \in \Xi_{\text{IV}}$) is $d = \Lambda + [1, -1; 0]$ (resp. $\Lambda + [-1, 1; 0]$).

Lemma 4.1. *The projector $P_d^{(\text{III})}$ decomposes into four projectors as follows:*

$$\begin{aligned}
P_d^{(\text{III})} &= P^{(-,+)} \oplus P^{(-,-)} \oplus \bar{P}^{(-,+)} \oplus \bar{P}^{(-,-)}, \\
P_d^{(\text{IV})} &= P^{(+,-)} \oplus P^{(-,-)} \oplus \bar{P}^{(+,-)} \oplus \bar{P}^{(-,-)}.
\end{aligned}$$

Proof. We find that

$$\tilde{\Delta}_{n,III}^+ = \{[1, 1; \pm 2], [1, -1; \pm 2]\}, \quad \tilde{\Delta}_{n,IV}^+ = \{[1, 1; \pm 2], [-1, 1; \pm 2]\}$$

Thus the lemma follows. \square

According to Theorem 3.2, spherical functions are characterized by the differential equations derived by the composition of the Schmid operator and projectors which appears in the decomposition of $P_d^{(III)}$. Let $\Phi_{\pi_\Lambda, \tau_d}(a) = \sum_M c_M(a) f_{k_1, l_1} \otimes f_{k_2, l_2}$ for $M = (k_1, l_1; k_2, l_2)$. Then c_M 's satisfy the following system which is equivalent to $\mathcal{D}_{d_1, d_2}^{(III), R/L} \Phi_{\pi_\Lambda, \tau_d} = 0$:

Lemma 4.2.

$$\begin{aligned} (2) \quad & (r_2 - k_2) \left\{ \partial_1 - \frac{1}{2}(u_1 + 2k_1 - r_1 - 2l_1 + s_1) \frac{1}{\text{sh}(a_1^2)} \right. \\ & - \frac{1}{2}(u_2 + 2k_2 - r_2 - 2l_2 + s_2) \text{cth}(a_1^2) + (k_2 + 1) \frac{\text{sh}(a_1^2)}{D} \left. \right\} c_{k_1, l_1; k_2, l_2} \\ & + (k_2 + 1)(s_2 - l_2 + 1) \frac{\text{sh}(a_2^2)}{D} c_{k_1, l_1; k_2+1, l_2-1} \\ & + 2(k_2 + 1)(r_1 - k_1 + 1) \frac{\text{sh}(a_1) \text{ch}(a_2)}{D} c_{k_1-1, l_1; k_2+1, l_2} \\ & + 2(k_2 + 1)(s_1 - l_1 + 1) \frac{\text{ch}(a_1) \text{sh}(a_2)}{D} c_{k_1, l_1-1; k_2+1, l_2} = 0, \\ (3) \quad & (k_2 + 1) \left\{ \partial_2 - \frac{1}{2}(u_1 - 2k_1 + r_1 + 2l_1 - s_1) \frac{1}{\text{sh}(a_2^2)} \right. \\ & - \frac{1}{2}(u_2 - 2k_2 + r_2 + 2l_2 - s_2 - 4) \text{cth}(a_2^2) - (r_2 - k_2) \frac{\text{sh}(a_2^2)}{D} \left. \right\} c_{k_1, l_1; k_2+1, l_2-1} \\ & - (r_2 - k_2) l_2 \frac{\text{sh}(a_1^2)}{D} c_{k_1, l_1; k_2, l_2} \\ & - 2(r_2 - k_2)(k_1 + 1) \frac{\text{ch}(a_1) \text{sh}(a_2)}{D} c_{k_1+1, l_1; k_2, l_2-1} \\ & - 2(r_2 - k_2)(l_1 + 1) \frac{\text{sh}(a_1) \text{ch}(a_2)}{D} c_{k_1, l_1+1; k_2, l_2-1} = 0, \\ (4) \quad & (k_2 + 1) \left\{ \partial_1 + \frac{1}{2}(u_1 + 2k_1 - r_1 - 2l_1 + s_1) \frac{1}{\text{sh}(a_1^2)} \right. \\ & + \frac{1}{2}(u_2 + 2k_2 - r_2 - 2l_2 + s_2 + 4) \text{cth}(a_1^2) + (r_2 - k_2) \frac{\text{sh}(a_1^2)}{D} \left. \right\} c_{k_1, l_1; k_2+1, l_2-1} \\ & + (r_2 - k_2) l_2 \frac{\text{sh}(a_2^2)}{D} c_{k_1, l_1; k_2, l_2} \\ & + 2(r_2 - k_2)(k_1 + 1) \frac{\text{sh}(a_1) \text{ch}(a_2)}{D} c_{k_1+1, l_1; k_2, l_2-1} \\ & + 2(r_2 - k_2)(l_1 + 1) \frac{\text{ch}(a_1) \text{sh}(a_2)}{D} c_{k_1, l_1+1; k_2, l_2-1} = 0, \\ (5) \quad & (r_2 - k_2) \left\{ \partial_2 + \frac{1}{2}(u_1 - 2k_1 + r_1 + 2l_1 - s_1) \frac{1}{\text{sh}(a_2^2)} \right. \end{aligned}$$

$$\begin{aligned}
& + \frac{1}{2}(u_2 - 2k_2 + r_2 + 2l_2 - s_2) \operatorname{cth}(a_2^2) - (k_2 + 1) \frac{\operatorname{sh}(a_2^2)}{D} \} c_{k_1, l_1; k_2, l_2} \\
& - (k_2 + 1)(s_2 - l_2 + 1) \frac{\operatorname{sh}(a_1^2)}{D} c_{k_1, l_1; k_2+1, l_2-1} \\
& - 2(k_2 + 1)(r_1 - k_1 + 1) \frac{\operatorname{ch}(a_1) \operatorname{sh}(a_2)}{D} c_{k_1-1, l_1; k_2+1, l_2} \\
& - 2(k_2 + 1)(s_1 - l_1 + 1) \frac{\operatorname{sh}(a_1) \operatorname{ch}(a_2)}{D} c_{k_1, l_1-1; k_2+1, l_2} = 0.
\end{aligned}$$

As for left equation systems, we have the following system:

$$\begin{aligned}
(6) \quad & (r_1 - k_1) \left\{ \partial_1 - \frac{1}{2}(u_2 + 2k_2 - r_2 - 2l_2 + s_2) \frac{1}{\operatorname{sh}(a_1^2)} \right. \\
& - \frac{1}{2}(u_1 + 2k_1 - r_1 - 2l_1 + s_1) \operatorname{cth}(a_1^2) + (k_1 + 1) \frac{\operatorname{sh}(a_1^2)}{D} \} c_{k_1, l_1; k_2, l_2} \\
& + (k_1 + 1)(s_1 - l_1 + 1) \frac{\operatorname{sh}(a_2^2)}{D} c_{k_1+1, l_1-1; k_2, l_2} \\
& + 2(k_1 + 1)(r_2 - k_2 + 1) \frac{\operatorname{sh}(a_1) \operatorname{ch}(a_2)}{D} c_{k_1+1, l_1; k_2-1, l_2} \\
& + 2(k_1 + 1)(s_2 - l_2 + 1) \frac{\operatorname{ch}(a_1) \operatorname{sh}(a_2)}{D} c_{k_1+1, l_1; k_2, l_2-1} = 0, \\
(7) \quad & (k_1 + 1) \left\{ \partial_2 - \frac{1}{2}(u_2 - 2k_2 + r_2 + 2l_2 - s_2) \frac{1}{\operatorname{sh}(a_2^2)} \right. \\
& - \frac{1}{2}(u_1 - 2k_1 + r_1 + 2l_1 - s_1 - 4) \operatorname{cth}(a_2^2) - (r_1 - k_1) \frac{\operatorname{sh}(a_2^2)}{D} \} c_{k_1+1, l_1-1; k_2, l_2} \\
& - (r_1 - k_1) l_1 \frac{\operatorname{sh}(a_1^2)}{D} c_{k_1, l_1; k_2, l_2} \\
& - 2(r_1 - k_1)(k_2 + 1) \frac{\operatorname{ch}(a_1) \operatorname{sh}(a_2)}{D} c_{k_1, l_1-1; k_2+1, l_2} \\
& - 2(r_1 - k_1)(l_2 + 1) \frac{\operatorname{sh}(a_1) \operatorname{ch}(a_2)}{D} c_{k_1, l_1-1; k_2, l_2+1} = 0, \\
(8) \quad & (k_1 + 1) \left\{ \partial_1 + \frac{1}{2}(u_2 + 2k_2 - r_2 - 2l_2 + s_2) \frac{1}{\operatorname{sh}(a_1^2)} \right. \\
& + \frac{1}{2}(u_1 + 2k_1 - r_1 - 2l_1 + s_1 + 4) \operatorname{cth}(a_1^2) + (r_1 - k_1) \frac{\operatorname{sh}(a_1^2)}{D} \} c_{k_1+1, l_1-1; k_2, l_2} \\
& + (r_1 - k_1) l_1 \frac{\operatorname{sh}(a_2^2)}{D} c_{k_1, l_1; k_2, l_2} \\
& + 2(r_1 - k_1)(k_2 + 1) \frac{\operatorname{sh}(a_1) \operatorname{ch}(a_2)}{D} c_{k_1, l_1-1; k_2+1, l_2} \\
& + 2(r_1 - k_1)(l_2 + 1) \frac{\operatorname{ch}(a_1) \operatorname{sh}(a_2)}{D} c_{k_1, l_1-1; k_2, l_2+1} = 0, \\
(9) \quad & (r_1 - k_1) \left\{ \partial_2 + \frac{1}{2}(u_2 - 2k_2 + r_2 + 2l_2 - s_2) \frac{1}{\operatorname{sh}(a_2^2)} \right.
\end{aligned}$$

$$\begin{aligned}
& + \frac{1}{2}(u_1 - 2k_1 + r_1 + 2l_1 - s_1) \operatorname{cth}(a_2^2) - (k_1 + 1) \frac{\operatorname{sh}(a_2^2)}{D} \} c_{k_1, l_1; k_2, l_2} \\
& - (k_1 + 1)(s_1 - l_1 + 1) \frac{\operatorname{sh}(a_1^2)}{D} c_{k_1+1, l_1-1; k_2, l_2} \\
& - 2(k_1 + 1)(r_2 - k_2 + 1) \frac{\operatorname{ch}(a_1) \operatorname{sh}(a_2)}{D} c_{k_1+1, l_1; k_2-1, l_2} \\
& - 2(k_1 + 1)(s_2 - l_2 + 1) \frac{\operatorname{sh}(a_1) \operatorname{ch}(a_2)}{D} c_{k_1+1, l_1; k_2, l_2-1} = 0.
\end{aligned}$$

4.1. Going up/down equations. We can reduce the obtained equations to the following going up system (10), (11), (12), (13) as follows:

Lemma 4.3.

$$\begin{aligned}
(10) \quad & (r - k_2) \{ \operatorname{cth}(a_1) \partial_1 - (s - l_1 - l_2) \operatorname{cth}^2(a_1) \\
& - \frac{1}{2}(-u - k_1 + k_2 + l_1 - l_2) + 2(k_2 + 1) \frac{\operatorname{ch}^2(a_1)}{D} \} c_{k_1, l_1; k_2, l_2} \\
& + 2(k_2 + 1)(r - k_1 + 1) \frac{\operatorname{ch}(a_1) \operatorname{ch}(a_2)}{D} c_{k_1-1, l_1; k_2+1, l_2} \\
& = -2(k_2 + 1)(s - l_2 + 1) \frac{\operatorname{cth}(a_1) \operatorname{sh}(a_2) \operatorname{ch}(a_2)}{D} c_{k_1, l_1; k_2+1, l_2-1} \\
& - 2(k_2 + 1)(s - l_1 + 1) \frac{\operatorname{cth}(a_1) \operatorname{ch}(a_1) \operatorname{sh}(a_2)}{D} c_{k_1, l_1-1; k_2+1, l_2},
\end{aligned}$$

$$\begin{aligned}
(11) \quad & (r - k_2) \{ \operatorname{cth}(a_2) \partial_2 - (s - l_1 - l_2) \operatorname{cth}^2(a_2) \\
& - \frac{1}{2}(u - k_1 + k_2 + l_1 - l_2) - 2(k_2 + 1) \frac{\operatorname{ch}^2(a_2)}{D} \} c_{k_1, l_1; k_2, l_2} \\
& - 2(k_2 + 1)(r - k_1 + 1) \frac{\operatorname{ch}(a_1) \operatorname{ch}(a_2)}{D} c_{k_1-1, l_1; k_2+1, l_2} \\
& = 2(k_2 + 1)(s - l_2 + 1) \frac{\operatorname{sh}(a_1) \operatorname{ch}(a_1) \operatorname{cth}(a_2)}{D} c_{k_1, l_1; k_2+1, l_2-1} \\
& + 2(k_2 + 1)(s - l_1 + 1) \frac{\operatorname{sh}(a_1) \operatorname{ch}(a_2) \operatorname{cth}(a_2)}{D} c_{k_1, l_1-1; k_2+1, l_2},
\end{aligned}$$

$$\begin{aligned}
(12) \quad & (r - k_1) \{ \operatorname{cth}(a_1) \partial_1 - (s - l_1 - l_2) \operatorname{cth}^2(a_1) \\
& - \frac{1}{2}(u + k_1 - k_2 - l_1 + l_2) + 2(k_1 + 1) \frac{\operatorname{ch}^2(a_1)}{D} \} c_{k_1, l_1; k_2, l_2} \\
& + 2(k_1 + 1)(r - k_2 + 1) \frac{\operatorname{ch}(a_1) \operatorname{ch}(a_2)}{D} c_{k_1+1, l_1; k_2-1, l_2} \\
& = -2(k_1 + 1)(s - l_1 + 1) \frac{\operatorname{cth}(a_1) \operatorname{sh}(a_2) \operatorname{ch}(a_2)}{D} c_{k_1+1, l_1-1; k_2, l_2} \\
& - 2(k_1 + 1)(s - l_2 + 1) \frac{\operatorname{cth}(a_1) \operatorname{ch}(a_1) \operatorname{sh}(a_2)}{D} c_{k_1+1, l_1; k_2, l_2-1},
\end{aligned}$$

$$\begin{aligned}
(13) \quad & (r - k_1) \{ \operatorname{cth}(a_2) \partial_2 - (s - l_1 - l_2) \operatorname{cth}^2(a_2) \\
& - \frac{1}{2}(-u + k_1 - k_2 - l_1 + l_2) - 2(k_1 + 1) \frac{\operatorname{ch}^2(a_2)}{D} \} c_{k_1, l_1; k_2, l_2}
\end{aligned}$$

$$\begin{aligned}
& -2(k_1 + 1)(r - k_2 + 1) \frac{\text{ch}(a_1) \text{ch}(a_2)}{D} c_{k_1+1, l_1; k_2-1, l_2} \\
& = 2(k_1 + 1)(s - l_1 + 1) \frac{\text{sh}(a_1) \text{ch}(a_1) \text{cth}(a_2)}{D} c_{k_1+1, l_1-1; k_2, l_2} \\
& + 2(k_1 + 1)(s - l_2 + 1) \frac{\text{sh}(a_1) \text{ch}(a_2) \text{cth}(a_2)}{D} c_{k_1+1, l_1; k_2, l_2-1}.
\end{aligned}$$

Going down equations are as follows:

$$\begin{aligned}
(14) \quad & k_2 \{ \text{cth}(a_1) \partial_1 + (s - l_1 - l_2) \text{cth}^2(a_1) \\
& + \frac{1}{2} (-u - k_1 + k_2 + l_1 - l_2) + 2(r - k_2 + 1) \frac{\text{ch}^2(a_1)}{D} \} c_{k_1, l_1; k_2, l_2} \\
& + 2(r - k_2 + 1)(k_1 + 1) \frac{\text{ch}(a_1) \text{ch}(a_2)}{D} c_{k_1+1, l_1; k_2-1, l_2} \\
& = -2(r - k_2 + 1)(l_2 + 1) \frac{\text{cth}(a_1) \text{sh}(a_2) \text{ch}(a_2)}{D} c_{k_1, l_1; k_2-1, l_2+1} \\
& - 2(r - k_2 + 1)(l_1 + 1) \frac{\text{cth}(a_1) \text{ch}(a_1) \text{sh}(a_2)}{D} c_{k_1, l_1+1; k_2-1, l_2},
\end{aligned}$$

$$\begin{aligned}
(15) \quad & k_2 \{ \text{cth}(a_2) \partial_2 + (s - l_1 - l_2) \text{cth}^2(a_2) \\
& + \frac{1}{2} (u - k_1 + k_2 + l_1 - l_2) - 2(r - k_2 + 1) \frac{\text{ch}^2(a_2)}{D} \} c_{k_1, l_1; k_2, l_2} \\
& - 2(r - k_2 + 1)(k_1 + 1) \frac{\text{ch}(a_1) \text{ch}(a_2)}{D} c_{k_1+1, l_1; k_2-1, l_2} \\
& = 2(r - k_2 + 1)(l_2 + 1) \frac{\text{sh}(a_1) \text{ch}(a_1) \text{cth}(a_2)}{D} c_{k_1, l_1; k_2-1, l_2+1} \\
& + 2(r - k_2 + 1)(l_1 + 1) \frac{\text{sh}(a_1) \text{ch}(a_2) \text{cth}(a_2)}{D} c_{k_1, l_1+1; k_2-1, l_2},
\end{aligned}$$

$$\begin{aligned}
(16) \quad & k_1 \{ \text{cth}(a_1) \partial_1 + (s - l_1 - l_2) \text{cth}^2(a_1) \\
& + \frac{1}{2} (u + k_1 - k_2 - l_1 + l_2) + 2(r - k_1 + 1) \frac{\text{ch}^2(a_1)}{D} \} c_{k_1, l_1; k_2, l_2} \\
& + 2(r - k_1 + 1)(k_2 + 1) \frac{\text{ch}(a_1) \text{ch}(a_2)}{D} c_{k_1-1, l_1; k_2+1, l_2} \\
& = -2(r - k_1 + 1)(l_1 + 1) \frac{\text{cth}(a_1) \text{sh}(a_2) \text{ch}(a_2)}{D} c_{k_1-1, l_1+1; k_2, l_2} \\
& - 2(r - k_1 + 1)(l_2 + 1) \frac{\text{cth}(a_1) \text{ch}(a_1) \text{sh}(a_2)}{D} c_{k_1-1, l_1; k_2, l_2+1},
\end{aligned}$$

$$\begin{aligned}
(17) \quad & k_1 \{ \text{cth}(a_2) \partial_2 + (s - l_1 - l_2) \text{cth}^2(a_2) \\
& + \frac{1}{2} (-u + k_1 - k_2 - l_1 + l_2) - 2(r - k_1 + 1) \frac{\text{ch}^2(a_2)}{D} \} c_{k_1, l_1; k_2, l_2} \\
& - 2(r - k_1 + 1)(k_2 + 1) \frac{\text{ch}(a_1) \text{ch}(a_2)}{D} c_{k_1-1, l_1; k_2+1, l_2} \\
& = 2(r - k_1 + 1)(l_1 + 1) \frac{\text{sh}(a_1) \text{ch}(a_1) \text{cth}(a_2)}{D} c_{k_1-1, l_1+1; k_2, l_2}
\end{aligned}$$

$$+ 2(r - k_1 + 1)(l_2 + 1) \frac{\text{sh}(a_1) \text{ch}(a_2) \text{cth}(a_2)}{D} c_{k_1-1, l_1; k_2, l_2+1}.$$

To make equations more “symmetric”, we consider (10) \pm (11), etc, and rewrite them using p and t . Put

$$c_{k_1, l_1; k_2, l_2}(a) = (\text{sh}(a_1) \text{sh}(a_2))^{|s-l_1-l_2|} (\text{ch}(a_1) \text{ch}(a_2))^{-(r+s+2)/2} \tilde{c}_{k_1, l_1; k_2, l_2}(a).$$

In the following, we assume that $0 \leq l_1 + l_2 \leq s$. We remark that

$$\begin{aligned} 2\partial_p &= \text{cth}(a_1)\partial_1 + \text{cth}(a_2)\partial_2, \\ 4\partial_t &= \text{cth}(a_1)\partial_1 - \text{cth}(a_2)\partial_2. \end{aligned}$$

Then, we have

Lemma 4.4.

$$(18) \quad (r - k_2)(\partial_p - l_1)\tilde{c}_{k_1, l_1; k_2, l_2} = (k_2 + 1)(s - l_2 + 1)p\tilde{c}_{k_1, l_1; k_2+1, l_2-1} \\ + (k_2 + 1)(s - l_1 + 1)\tilde{c}_{k_1, l_1-1; k_2+1, l_2},$$

$$(19) \quad (r - k_2) \left(2\partial_t + \frac{u}{2} + (k_2 + 1) \frac{t+1}{t-1} \right) \tilde{c}_{k_1, l_1; k_2, l_2} \\ + 2(k_2 + 1)(r - k_1 + 1)z_-(t)^{-1}\tilde{c}_{k_1-1, l_1; k_2+1, l_2} \\ = (k_2 + 1)(s - l_2 + 1)z_-(t)^{-1}(2 - pz_+)\tilde{c}_{k_1, l_1; k_2+1, l_2-1} \\ + (k_2 + 1)(s - l_1 + 1)z_-(t)^{-1}(z_+ - 2p)\tilde{c}_{k_1, l_1-1; k_2+1, l_2},$$

$$(20) \quad k_2 \{ (p^2 - z_+(t)p + 1)(\partial_p + l_1 - s) \\ + (s - l_1 - l_2)(2p - z_+(t)p) \} \tilde{c}_{k_1, l_1; k_2, l_2} \\ = (r - k_2 + 1)(l_2 + 1)p\tilde{c}_{k_1, l_1; k_2-1, l_2+1} \\ + (r - k_2 + 1)(l_1 + 1)\tilde{c}_{k_1, l_1+1; k_2-1, l_2},$$

$$(21) \quad (r - k_1)(\partial_p - l_2)\tilde{c}_{k_1, l_1; k_2, l_2} = (k_1 + 1)(s - l_1 + 1)p\tilde{c}_{k_1+1, l_1-1; k_2, l_2} \\ + (k_1 + 1)(s - l_2 + 1)\tilde{c}_{k_1+1, l_1; k_2, l_2-1},$$

$$(22) \quad (r - k_1) \left(2\partial_t - \frac{u}{2} + (k_1 + 1) \frac{t+1}{t-1} \right) \tilde{c}_{k_1, l_1; k_2, l_2} \\ + 2(k_1 + 1)(r - k_2 + 1)z_-(t)^{-1}\tilde{c}_{k_1+1, l_1; k_2-1, l_2} \\ = (k_1 + 1)(s - l_1 + 1)z_-(t)^{-1}(2 - pz_+)\tilde{c}_{k_1+1, l_1-1; k_2, l_2} \\ + (k_1 + 1)(s - l_2 + 1)z_-(t)^{-1}(z_+ - 2p)\tilde{c}_{k_1+1, l_1; k_2, l_2-1},$$

$$(23) \quad k_1 \{ (p^2 - z_+(t)p + 1)(\partial_p + l_2 - s) \\ + (s - l_1 - l_2)(2p - z_+(t)p) \} \tilde{c}_{k_1, l_1; k_2, l_2} \\ = (r - k_1 + 1)(l_1 + 1)p\tilde{c}_{k_1-1, l_1+1; k_2, l_2} \\ + (r - k_1 + 1)(l_2 + 1)\tilde{c}_{k_1-1, l_1; k_2, l_2+1}.$$

As we know, the equations (21), (22) and (23) can be obtained by flipping indices 1 and 2:

Remark 4.5. We have similar equations when $s \leq l_1 + l_2 \leq 2s$.

5. SOLUTION FOR THE HOLONOMIC SYSTEM: THE MAIN THEOREM

5.1. Separation of variables. We treat the case when $l_1 + l_2 \leq s$.

Proposition 5.1. Write $M = (k_1, l_1; k_2, l_2)$. Then \tilde{c}_M can be written in the form of “separation of variables”:

$$\tilde{c}_M(a) = \sum_{i=0}^{l_1+l_2} (-1)^{r-k_1-l_1} \binom{r}{k_1} \binom{r}{k_2} p^{l_1+l_2-i} s_{M,i}(t).$$

We can prove it by induction on $l_1 + l_2$. Assume that $l_1 = l_2 = 0$. By (18), we have,

$$\partial_p \tilde{c}_{k_1,0;k_2,0} = 0,$$

so that actually we can put $s_{(k_1,0;k_2,0),0}(t) := \tilde{c}_{k_1,0;k_2,0}(a)$. Next assume that $l_1 + l_2 > 0$. If $l_1 \neq l_2$ and $k_1 < r$, $k_2 < r$, then (18)/($r - k_2$) - (21)/($r - k_1$) shows the assertion. Otherwise, we can assume $k_2 \neq r$. Consulting (18), we readily prove the formula.

According to Proposition 5.1, we can rewrite the difference equations of Lemma 4.4 in terms of p and t . Comparing the coefficients as a polynomial of p , we have the following.

Lemma 5.2. 1. If $0 \leq k_2 < r$, then,

$$(24) \quad (l_2 - i) s_{(k_1, l_1; k_2, l_2), i} = (s - l_2 + 1) s_{(k_1, l_1; k_2+1, l_2-1), i} \\ - (s - l_1 + 1) s_{(k_1, l_1-1; k_2+1, l_2), i-1},$$

$$(25) \quad \left(2\partial_t + \frac{u}{2} + (k_2 + 1) \frac{t+1}{t-1} \right) s_{(k_1, l_1; k_2, l_2), i} - \frac{2k_1}{z_-(t)} s_{(k_1-1, l_1; k_2+1, l_2), i} \\ = (s - l_2 + 1) \left(\frac{2}{z_-(t)} s_{(k_1, l_1; k_2+1, l_2-1), i-1} - \frac{t+1}{t-1} s_{(k_1, l_1; k_2+1, l_2-1), i} \right) \\ - (s - l_1 + 1) \left(\frac{t+1}{t-1} s_{(k_1, l_1-1; k_2+1, l_2), i-1} - \frac{2}{z_-(t)} s_{(k_1, l_1-1; k_2+1, l_2), i} \right),$$

$$(26) \quad l_2 s_{(k_1, l_1; k_2, l_2), i+1} - (l_1 + 1) s_{(k_1, l_1+1; k_2, l_2-1), i} \\ = (s - l_2 - i) s_{(k_1, l_1; k_2+1, l_2-1), i+1} - (l_1 - i) z_+(t) s_{(k_1, l_1; k_2+1, l_2-1), i} \\ + (2l_1 + l_2 - s - i) s_{(k_1, l_1; k_2+1, l_2-1), i-1}.$$

2. If $0 \leq k_1 < r$, then,

$$(27) \quad (l_1 - i) s_{(k_1, l_1; k_2, l_2), i} = (s - l_1 + 1) s_{(k_1+1, l_1-1; k_2, l_2), i} \\ - (s - l_2 + 1) s_{(k_1+1, l_1; k_2, l_2-1), i-1},$$

$$(28) \quad \left(2\partial_t - \frac{u}{2} + (k_1 + 1) \frac{t+1}{t-1} \right) s_{(k_1, l_1; k_2, l_2), i} - \frac{2k_2}{z_-(t)} s_{(k_1+1, l_1; k_2-1, l_2), i} \\ = (s - l_1 + 1) \left(\frac{2}{z_-(t)} s_{(k_1+1, l_1-1; k_2, l_2), i-1} - \frac{t+1}{t-1} s_{(k_1+1, l_1-1; k_2, l_2), i} \right) \\ - (s - l_2 + 1) \left(\frac{t+1}{t-1} s_{(k_1+1, l_1; k_2, l_2-1), i-1} - \frac{2}{z_-(t)} s_{(k_1+1, l_1; k_2, l_2-1), i} \right),$$

$$(29) \quad l_1 s_{(k_1, l_1; k_2, l_2), i+1} - (l_2 + 1) s_{(k_1, l_1-1; k_2, l_2+1), i} \\ = (s - l_1 - i) s_{(k_1+1, l_1-1; k_2, l_2), i+1} - (l_2 - i) z_+(t) s_{(k_1+1, l_1-1; k_2, l_2), i} \\ + (2l_2 + l_1 - s - i) s_{(k_1+1, l_1-1; k_2, l_2), i-1}.$$

5.2. Expression of peripheral entries using Gaussian hypergeometric functions. First assume that $l_1 = l_2 = 0$. We simply write $s_{k_1, k_2} = s_{(k_1, 0; k_2, 0), 0}$. By (19) and (22), we have

$$(r - k_2) \left(\partial_t + \frac{u}{4} + \frac{k_2 + 1}{2} \frac{t + 1}{t - 1} \right) s_{k_1; k_2} + \frac{(k_2 + 1)(r - k_1 + 1)}{z_-(t)} s_{k_1 - 1; k_2 + 1} = 0,$$

$$(r - k_1 + 1) \left(\partial_t - \frac{u}{4} + \frac{k_1}{2} \frac{t + 1}{t - 1} \right) s_{k_1 - 1; k_2 + 1} + \frac{k_1(r - k_2)}{z_-(t)} s_{k_1; k_2} = 0.$$

Eliminating $s_{k_1 - 1; k_2 + 1}$, we have

$$\left\{ \left(\partial_t - \frac{u}{4} + \frac{k_1 + 1}{2} \frac{t + 1}{t - 1} \right) \left(\partial_t + \frac{u}{4} + \frac{k_2 + 1}{2} \frac{t + 1}{t - 1} \right) - k_1(k_2 + 1)z_-(t)^{-2} \right\} s_{k_1; k_2} = 0.$$

Considering $r + s = k_1 + k_2$, we have

$$\left(\partial_t^2 + \frac{r + s + 2}{2} \frac{t + 1}{t - 1} \partial_t + \frac{u(k_1 - k_2)}{8} \frac{t + 1}{t - 1} + \frac{(r + s + 2)^2 - (k_1 - k_2)^2 - u^2}{16} \right) s_{k_1; k_2} = 0$$

and its Riemann's P scheme is:

$$P \begin{bmatrix} 0 & 1 & \infty \\ \frac{r+s+2}{4} - \frac{k_1-k_2+u}{4} & 0 & \frac{r+s+2}{4} + \frac{k_1-k_2-u}{4} \\ \frac{r+s+2}{4} + \frac{k_1-k_2+u}{4} & -(r+s+1) & \frac{r+s+2}{4} - \frac{k_1-k_2-u}{4} \end{bmatrix}.$$

In general, let $\Phi(m_1, m_2) = \Phi(m_1, m_2; u; t)$ be a regular function around 1 having the P -scheme

$$P \begin{bmatrix} 0 & 1 & \infty \\ \frac{m_1+m_2+2}{4} - \frac{m_1-m_2+u}{4} & 0 & \frac{m_1+m_2+2}{4} - \frac{m_1-m_2-u}{4} \\ \frac{m_1+m_2+2}{4} + \frac{m_1-m_2+u}{4} & -(m_1+m_2+1) & \frac{m_1+m_2+2}{4} + \frac{m_1-m_2-u}{4} \end{bmatrix}$$

with condition $\Phi(m_1, m_2; u; 1) = \binom{r+s}{m_1}^{-1}$. We also write $\Phi(m) = \Phi(m, r + s - m)$ for simplicity. Then it follows $s_{(k_1, 0; k_2, 0), 0} = c_0 \Phi(k_1, k_2)$.

5.3. Reduction of general coefficients $s_{M, i}$. To describe general solutions, we introduce the notion of height and bias. Write $M = (k_1, l_1; k_2, l_2)$ as before. Define $h = h(M, i) = \min(i, l_1, l_2, l_1 + l_2 - i)$ and

$$b = b(M, i) = \begin{cases} 0 & i \leq \min(l_1, l_2), \\ \operatorname{sgn}(l_2 - l_1)(i - \min(l_1, l_2)) & \min(l_1, l_2) \leq i \leq \max(l_1, l_2), \\ l_2 - l_1 & \max(l_1, l_2) \leq i. \end{cases}$$

Then we have,

Proposition 5.3.

$$(30) \quad s_{M, i} = \sum_{j=b-h}^{b+h} Q_j(-z_+) \Phi(k_1 + l_1 + j)$$

for a polynomial $Q_j(t) = Q_j(M, i; t)$ which is actually independent of the choice of r, k_1 and k_2 . The degree of Q_j is equal to $h - |j - b|$ and it follows

$$Q_j(-z_+) = (-1)^{\deg Q_j} Q_j(z_+).$$

5.4. Polynomials $Q_j(z_+)$. The remaining paper deals with the determination of the polynomial Q_j . We can deduce the difference equations of Q_j equivalent to (26). Proposition 5.3 says that Q_j is in the form

$$Q_j(z_+) = \sum_{m \geq 0} \tilde{\beta}_m(M, i, j) z_+^{h-|j|-2m}.$$

For simplicity, we put $\tilde{\beta}_m(M, i, j) = \binom{s}{l_1} \binom{s}{l_2} \beta_m(M, i, j)$. Comparing the coefficient of $z_+^{h-|j|-2m}$, we see that our difference equations become as follows: If $j \geq 0$, then,

$$(31) \quad \begin{aligned} (s-i+1)i\beta_m(M, i, j) &= (s-l_1)l_2\beta_m(M + (0, 1; 0, -1), i-1, j-1) \\ &+ l_1(s-l_2-i+1)\beta_{m-1}(M + (0, -1; 1, 0), i-1, j+1) \\ &+ (l_1-i+1)l_2\beta_m(M + (0, 0; 1, -1), i-1, j) \\ &+ (2l_1+l_2-s-i+1)l_2\beta_{m-1}(M + (0, 0; 1, -1), i-2, j). \end{aligned}$$

If $j < 0$, then,

$$(32) \quad \begin{aligned} (s-i+1)i\beta_m(M, i, j) &= (s-l_1)l_2\beta_{m-1}(M + (0, 1; 0, -1), i-1, j-1) \\ &+ l_1(s-l_2-i+1)\beta_m(M + (0, -1; 1, 0), i-1, j+1) \\ &+ (l_1-i+1)l_2\beta_m(M + (0, 0; 1, -1), i-1, j) \\ &+ (2l_1+l_2-s-i+1)l_2\beta_{m-1}(M + (0, 0; 1, -1), i-2, j). \end{aligned}$$

The solution can be expressed as follows:

Proposition 5.4. *Assume that $0 \leq l_1 + l_2 \leq s$. Then,*

$$\beta_m = \alpha(m; i, |j|) \binom{l_1}{i-j_+-m} \binom{l_2}{i+j_--m} \sum_{n=0}^m \binom{s-l_1}{j+m-n} \binom{s-l_2}{m-n} \binom{s-i+n}{n}$$

for

$$\alpha(m; i, j) = \binom{i-j-m}{m} \binom{i}{m}^{-1} \binom{s}{i}^{-1}, \quad j_+ = \begin{cases} j & (j \geq 0), \\ 0 & (j < 0) \end{cases}$$

and $j_- = (-j)_+$.

We can check that each $\beta_m(M, i, j)$ fits the definition of h as $\beta_m(M, i, j)$ is nonzero if and only if $i - |j| - 2m \geq 0$, $l_1 - i + j_+ + m \geq 0$ and $l_2 - i - j_- + m \geq 0$.

Main Theorem 5.5. *Let π_Λ be a middle discrete series representation with $\Lambda = [r-1, s+1; u] \in \Xi_{\text{III}}$, and τ_d the minimal K -type of π_Λ with $d = [r, s; u]$. For a (τ_d, τ_d^*) -matrix coefficient $\Phi_{\pi, \tau}$, put*

$$\Phi_{\pi, \tau}(a) = \sum_{k_1, l_1; k_2, l_2} c_{k_1, l_1; k_2, l_2}(a) f_{k_1, l_1; k_2, l_2}.$$

Then, $c_M(a)$ ($M = (k_1, l_1; k_2, l_2)$) is given by the following:

1. Suppose that $l_1 + l_2 \leq s$. The matrix coefficients $c_{k_1, l_1; k_2, l_2}(a_1, a_2)$ can be expressed as follows:

$$\begin{aligned} c_M(a_1, a_2) &= c_0 (-1)^{r-k_1-l_1} (\operatorname{sh}(a_1) \operatorname{sh}(a_2))^{s-l_1-l_2} \\ &\times \sum_{i=0}^{l_1+l_2} (\operatorname{ch}(a_1) \operatorname{ch}(a_2))^{-(r+s+2)/2+l_1+l_2-i} \binom{r}{k_1} \binom{r}{k_2} \binom{s}{l_1} \binom{s}{l_2} \\ &\times \sum_{j=b-h}^{b+h} (-1)^{h-|j-b|} \sum_{\mu=0}^{\lfloor \frac{i-|j-b|}{2} \rfloor} \beta_\mu(M, i, j) \left(\frac{\operatorname{ch}(a_1)}{\operatorname{ch}(a_2)} + \frac{\operatorname{ch}(a_2)}{\operatorname{ch}(a_1)} \right)^{h-|j-b|-2\mu} \\ &\times \Phi \left(k_1 + l_1 + j, k_2 + l_2 - j; u; \left(\frac{\operatorname{ch}(a_1)}{\operatorname{ch}(a_2)} \right)^2 \right). \end{aligned}$$

2. Suppose that $s < l_1 + l_2 \leq 2s$. Define $M^\wedge = (r-k_1, s-l_1; r-k_2, s-l_2)$, $b^\wedge = b(M^\wedge, i)$ and $h^\wedge = h(M^\wedge, i)$. Then,

$$\begin{aligned} c_M(a_1, a_2) &= c_0 (-1)^{r-k_1-l_1} (\operatorname{sh}(a_1) \operatorname{sh}(a_2))^{-s+l_1+l_2} \\ &\times \sum_{i=0}^{l_1+l_2} (\operatorname{ch}(a_1) \operatorname{ch}(a_2))^{-(r+s+2)/2+2s-l_1-l_2-i} \binom{r}{k_1} \binom{r}{k_2} \binom{s}{l_1} \binom{s}{l_2} \\ &\times \sum_{j=b^\wedge-h^\wedge}^{b^\wedge+h^\wedge} (-1)^{h^\wedge-|j-b^\wedge|} \sum_{m=0}^{\lfloor \frac{i-|j-b^\wedge|}{2} \rfloor} \beta_m(M^\wedge, i, j) \left(\frac{\operatorname{ch}(a_1)}{\operatorname{ch}(a_2)} + \frac{\operatorname{ch}(a_2)}{\operatorname{ch}(a_1)} \right)^{h^\wedge-|j-b^\wedge|-2m} \\ &\times \Phi \left(k_2 + l_2 + j, k_1 + l_1 - j; -u; \left(\frac{\operatorname{ch}(a_1)}{\operatorname{ch}(a_2)} \right)^2 \right). \end{aligned}$$

Remark 5.6. We can determine the unique unknown constant c_0 by using the normalization condition, i.e., by specification of the value of Φ at the identity of G .

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