

# On Modular Invariance Equations

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Modular invariance equations for Bose-Mesner algebras were introduced by Eiichi Bannai [1] in connection with fusion algebras in conformal field theory.

Modular invariance equations are deeply related to spin models. Some spin models have been constructed from solutions of modular invariance equations [2, 3, 5]. Basic theory of modular invariance equations was given by Eiichi Bannai, Etsuko Bannai and François Jaeger [4]. Recently it turned out that every spin model can be obtained from a solution of the modular invariance equation of some self-dual Bose-Mesner algebra [6, 8, 7].

Here we consider the modular invariance equation in the case  $d = 3$ . We will give formulas which represent the entries of  $P$  by three parameters.

Let  $\mathcal{A}$  be a Bose-Mesner algebra of a symmetric association scheme of class  $d$  on a finite set  $X$ ,  $|X| = n$ . We assume that  $\mathcal{A}$  is self-dual so that the eigenmatrix  $P$  satisfies  $P^2 = nI$ . The *modular invariance equation* for  $\mathcal{A}$  takes the form:

$$(PT)^3 = t_0(\sqrt{n})^3 I, \quad (1)$$

where  $T = \text{diag}[t_0, t_1, \dots, t_d]$  with  $d + 1$  unknowns  $t_0, t_1, \dots, t_d$ .

First we represent the entries of  $P$  by four parameters for any self-dual Bose-Mesner algebra.

**Proposition 1** *Let  $P$  denote the eigenmatrix of a Bose-Mesner algebra such that  $P^2 = nI$ . Then the entries of  $P$  are represented by four parameters  $\theta_i := P_{i1}$  ( $i = 0, 1, 2, 3$ ) as follows.*

$$P = \begin{pmatrix} 1 & \theta_0 & k_2 & k_3 \\ 1 & \theta_1 & (k_2/k_1)\theta_2 & (k_3/k_1)\theta \\ 1 & \theta_2 & a & (k_3/k_2)c \\ 1 & \theta_3 & c & b \end{pmatrix},$$

where

$$\begin{aligned} k_2 &= \frac{\theta_0(1 + \theta_1)(\theta_0 - \theta_3 + \theta_3(\theta_1 - \theta_3))}{(\theta_3 - \theta_2)(\theta_0 + \theta_2\theta_3)}, \\ k_3 &= \frac{\theta_0(1 + \theta_1)(\theta_0 - \theta_2 + \theta_2(\theta_1 - \theta_2))}{(\theta_2 - \theta_3)(\theta_0 + \theta_2\theta_3)}, \\ a &= \frac{\theta_0 - \theta_3 + \theta_2(\theta_1 - \theta_3)}{\theta_3 - \theta_2}, \\ b &= \frac{\theta_0 - \theta_2 + \theta_3(\theta_1 - \theta_2)}{\theta_2 - \theta_3}, \\ c &= \frac{\theta_0 - \theta_3 + \theta_3(\theta_1 - \theta_3)}{\theta_3 - \theta_2}, \end{aligned}$$

unless the denominators are not zero.

Conversely, the matrix given by the above satisfies  $P^2 = nI$  for any  $\theta_i$  ( $i = 0, 1, 2, 3$ ) unless the denominators are nonzero.

Next suppose that there exists a diagonal matrix  $T$  with diagonal entries  $t_i$  ( $i = 0, 1, 2, 3$ ) which satisfies the modular invariance equation (1).

**Proposition 2** *Set  $s = t_1 t_2 t_3$  and*

$$L = s(t_1^{-1} + t_2^{-1} + t_3^{-1}) - s^{-1}(t_1 + t_2 + t_3).$$

*Then*

$$\begin{aligned} t_0 &= s^3, \\ \sqrt{n} &= \frac{(s^3 - t_1)(s^3 - t_2)(s^3 - t_3)}{s^5 L}, \\ P_{01} &= \frac{t_1(s^2 - t_1^2)(s^4 - 1)(s^3 - t_2)(s^3 - t_3)(s^3 t_2^3 + 1)(s^3 t_3^3 + 1)}{s^9(t_1 - t_2)(t_1 - t_3)(st_2 + 1)(st_3 + 1)L^2}, \\ P_{11} &= \frac{t_1(s^3 - t_2)(s^3 - t_3)((s^2 - s^{-2}) + (st_1^{-1} - s^{-1}t_1) - L)}{s^3(t_1 - t_2)(t_1 - t_3)L}, \\ P_{12} &= \frac{(s^3 - t_1)(s^3 - t_3)(s^2 - t_2^2)(s^3 t_1^3 + 1)}{t_1 s^5(t_1 - t_2)(t_3 - t_2)(st_1 + 1)L}. \end{aligned}$$

$P_{0i}$  ( $i \in \{2, 3\}$ ) are obtained by exchanging  $t_1$  and  $t_i$  in  $P_{01}$ .

$P_{ii}$  ( $i \in \{2, 3\}$ ) are obtained by exchanging  $t_1$  and  $t_i$  in  $P_{11}$ .

For  $P_{ij}$  ( $i, j \in \{1, 2, 3\}$  and  $i \neq j$ ), put  $\{i, j, k\} = \{1, 2, 3\}$ ,

then  $P_{ij}$  is obtained by permutating  $t_1 \rightarrow t_i, t_2 \rightarrow t_j, t_3 \rightarrow t_k$

in  $P_{12}$ .

Conversely, the matrix  $P$  with above entries satisfies  $P^2 = nI$  and  $(PT)^3 = t_0(\sqrt{n})^3 I$  for any non-zero value of  $t_i$  ( $i = 1, 2, 3$ ) unless the denominators are nonzero.

## 参考文献

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