

Eigenvalue Problem related to Euler-Bernoulli Equation with Joint Boundary Condition

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Abstract

We consider the control system of two vibrating beams which are coupled at a joint. The displacement of the beam is described by an Euler-Bernoulli equation with control applied at a coupled point. Our purpose is to argue the controllability of the system. To this purpose, we discuss the eigenvalue problem related to this system.

1 Introduction

Let us consider the controllability problem for a system coupled by Euler-Bernoulli beams. For $m \in (0, 1)$, we put $x_0 = 0$, $x_1 = m$ and $x_2 = 1$. The displacement of each beam at time t is described by $y_i(x, t)$ on $I_i = (x_{i-1}, x_i)$, $i = 1, 2$, and satisfies the Euler-Bernoulli equation:

$$\rho_i \ddot{y}_i + T_i y_i^{(4)} = 0 \quad \text{on } I_i \times (0, T) \tag{1}$$

where $\dot{y}_i(x, t) = \partial y_i(x, t) / \partial t$, $y_i^{(k)}(x, t) = \partial^k y_i(x, t) / \partial x^k$. ρ_i is mass density and T_i is flexural rigidity respectively on I_i . Let both ends be clamped:

$$(B_0 y)(t) := (y_1(0, t), y_1^{(1)}(0, t), y_2(1, t), y_2^{(1)}(1, t)) = 0. \tag{2}$$

At the coupled point $x = m$, we apply control $F = (f_1, f_2, f_3, f_4)$ as follows:

$$\left. \begin{aligned} (B_1 y)(t) &:= y_1(m, t) - y_2(m, t) = f_1(t), \\ (B_2 y)(t) &:= y_1^{(1)}(m, t) - y_2^{(1)}(m, t) = f_2(t), \\ (B_3 y)(t) &:= T_1 y_1^{(2)}(m, t) - T_2 y_2^{(2)}(m, t) = f_3(t), \\ (B_4 y)(t) &:= T_1 y_1^{(3)}(m, t) - T_2 y_2^{(3)}(m, t) = f_4(t). \end{aligned} \right\} \tag{3}$$

Initial condition is given as follows

$$y_i(x, 0) = y_i^0(x), \quad \dot{y}_i(x, 0) = y_i^1(x), \quad x \in I_i, \quad i = 1, 2. \tag{4}$$

We assume that controls f_i belong to $L^2(0, T)$, $i = 1, 2, 3, 4$. In this paper, we treat controllability of the above system. Roughly speaking, the system (1)(2)(3)(4) is controllable if for any initial value (y_i^0, y_i^1) and final value (z_i^0, z_i^1) , $i = 1, 2$, there exists a control $F = (f_1, f_2, f_3, f_4)$ such that the corresponding solution of the system (1)(2)(3)(4) satisfies the final condition $(y_i(x, T), \dot{y}_i(x, T)) = (z_i^0(x), z_i^1(x))$, $i = 1, 2$.

2 Eigenvalue Problem

Let us identify $v \in L^2(I)$ with $\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \in H = L^2(I) = L^2(I_1) \times L^2(I_2)$ where $v_i = v|_{I_i}$, $i = 1, 2$, $I_1 = (0, m)$, $I_2 = (m, 1)$. Then H becomes a Hilbert space with inner product

$$(v, w) = \rho_1(v_1, w_1)_{L^2(I_1)} + \rho_2(v_2, w_2)_{L^2(I_2)} \quad \text{for } v = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}, w = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} \in H.$$

We define an operator A in H by

$$Av = \begin{pmatrix} (T_1/\rho_1)v_1^{(4)} \\ (T_2/\rho_2)v_2^{(4)} \end{pmatrix} \quad \text{for } v = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \in \mathcal{D}(A) := H^4(I_1) \times H^4(I_2)$$

and an operator \mathcal{A} by restricting A to

$$\mathcal{D}(\mathcal{A}) := \{v \in H^4(I_1) \times H^4(I_2); B_0v = 0, Bv := (B_1v, B_2v, B_3v, B_4v) = 0\}.$$

For this operator \mathcal{A} , we have

Lemma 1 *The operator \mathcal{A} is a selfadjoint operator in H with compact resolvent.*

The proof of this lemma is easy to verify.

Let λ be an eigenvalue for \mathcal{A} with corresponding eigenfunction ϕ . Then we have

$$\mathcal{A}\phi = \lambda\phi \tag{1}$$

with boundary conditions

$$B_0\phi = 0, \quad B\phi = 0. \tag{2}$$

We introduce functions C_{\pm}, S_{\pm} by

$$C_{\pm}(\theta) := \frac{\cosh \theta \pm \cos \theta}{2}, \quad S_{\pm}(\theta) := \frac{\sinh \theta \pm \sin \theta}{2} \quad \text{for } \theta \in \mathbf{R}.$$

Let $\phi_i = \phi|_{I_i}$, $\alpha_i = (\rho_i/T_i)^{\frac{1}{4}}$, $i = 1, 2$. A system of fundamental solutions to (1) in each I_i is given by $\{C_{\pm}(\alpha_i\omega(x - x_{i-1})), S_{\pm}(\alpha_i\omega(x - x_{i-1}))\}$ and we have

$$\left. \begin{aligned} \phi_i(x) &= (p_1^i C_+ + p_2^i S_+ + p_3^i C_- + p_4^i S_-)(\alpha_i\omega(x - x_{i-1})), \\ (\phi_i)^{(1)}(x) &= \alpha_i\omega(p_1^i S_- + p_2^i C_+ + p_3^i S_+ + p_4^i C_-)(\alpha_i\omega(x - x_{i-1})), \\ (\phi_i)^{(2)}(x) &= \alpha_i^2\omega^2(p_1^i C_- + p_2^i S_- + p_3^i C_+ + p_4^i S_+)(\alpha_i\omega(x - x_{i-1})), \\ (\phi_i)^{(3)}(x) &= \alpha_i^3\omega^3(p_1^i S_+ + p_2^i C_- + p_3^i S_- + p_4^i C_+)(\alpha_i\omega(x - x_{i-1})) \end{aligned} \right\}$$

for $x \in I_i$ where $\omega = \lambda^{\frac{1}{4}}$. By (2), we have $p_1^1 = p_2^1 = 0$ and therefore

$$\left. \begin{aligned} \phi_1(x) &= (p_3^1 C_- + p_4^1 S_-)(\alpha_1\omega x), \\ (\phi_1)^{(1)}(x) &= \alpha_1\omega(p_3^1 S_+ + p_4^1 C_-)(\alpha_1\omega x), \\ (\phi_1)^{(2)}(x) &= \alpha_1^2\omega^2(p_3^1 C_+ + p_4^1 S_+)(\alpha_1\omega x), \\ (\phi_1)^{(3)}(x) &= \alpha_1^3\omega^3(p_3^1 S_- + p_4^1 C_+)(\alpha_1\omega x). \end{aligned} \right\} \tag{3}$$

By (2), we have

$$\gamma_2 \alpha_2 p^2 = \gamma_2 \alpha_2 \begin{pmatrix} p_1^2 \\ p_2^2 \\ p_3^2 \\ p_4^2 \end{pmatrix} = \begin{pmatrix} \gamma_2 \alpha_2 C_-^1(\omega) & \gamma_2 \alpha_2 S_-^1(\omega) \\ \gamma_2 \alpha_1 S_+^1(\omega) & \gamma_2 \alpha_1 C_-^1(\omega) \\ \gamma_1 \alpha_2 C_+^1(\omega) & \gamma_1 \alpha_2 S_+^1(\omega) \\ \gamma_1 \alpha_1 S_-^1(\omega) & \gamma_1 \alpha_1 C_+^1(\omega) \end{pmatrix} \begin{pmatrix} p_3^1 \\ p_4^1 \end{pmatrix} \quad (4)$$

where $\gamma_i = T_i \alpha_i^2$, $i = 1, 2$, $\beta_1 = \alpha_1 m$, $S_{\pm}^1(\omega) = S_{\pm}(\beta_1 \omega)$, $C_{\pm}^1(\omega) = C_{\pm}(\beta_1 \omega)$. By (2), we see

$$\begin{pmatrix} C_+^2(\omega) & S_+^2(\omega) & C_-^2(\omega) & S_-^2(\omega) \\ S_-^2(\omega) & C_+^2(\omega) & S_+^2(\omega) & C_-^2(\omega) \end{pmatrix} \begin{pmatrix} p_1^2 \\ p_2^2 \\ p_3^2 \\ p_4^2 \end{pmatrix} = 0, \quad (5)$$

where $\beta_2 = \alpha_2(1 - m)$, $S_{\pm}^2(\omega) = S_{\pm}(\beta_2 \omega)$, $C_{\pm}^2(\omega) = C_{\pm}(\beta_2 \omega)$. Let

$$\begin{aligned} D(\omega) &= \begin{pmatrix} D_{11}(\omega) & D_{12}(\omega) \\ D_{21}(\omega) & D_{22}(\omega) \end{pmatrix} \\ &:= \begin{pmatrix} C_+^2(\omega) & S_+^2(\omega) & C_-^2(\omega) & S_-^2(\omega) \\ S_-^2(\omega) & C_+^2(\omega) & S_+^2(\omega) & C_-^2(\omega) \end{pmatrix} \begin{pmatrix} \gamma_2 \alpha_2 C_-^1(\omega) & \gamma_2 \alpha_2 S_-^1(\omega) \\ \gamma_2 \alpha_1 S_+^1(\omega) & \gamma_2 \alpha_1 C_-^1(\omega) \\ \gamma_1 \alpha_2 C_+^1(\omega) & \gamma_1 \alpha_2 S_+^1(\omega) \\ \gamma_1 \alpha_1 S_-^1(\omega) & \gamma_1 \alpha_1 C_+^1(\omega) \end{pmatrix}. \end{aligned}$$

Then

$$\begin{aligned} D_{11}(\omega) &= (\gamma_2 \alpha_2 C_+^2 \cdot C_-^1 + \gamma_2 \alpha_1 S_+^2 \cdot S_+^1 + \gamma_1 \alpha_2 C_-^2 \cdot C_+^1 + \gamma_1 \alpha_1 S_-^2 \cdot S_-^1)(\omega), \\ D_{12}(\omega) &= (\gamma_2 \alpha_2 C_+^2 \cdot S_-^1 + \gamma_2 \alpha_1 S_+^2 \cdot C_-^1 + \gamma_1 \alpha_2 C_-^2 \cdot S_+^1 + \gamma_1 \alpha_1 S_-^2 \cdot C_+^1)(\omega), \\ D_{21}(\omega) &= (\gamma_2 \alpha_2 S_-^2 \cdot C_-^1 + \gamma_2 \alpha_1 C_+^2 \cdot S_+^1 + \gamma_1 \alpha_2 S_+^2 \cdot C_+^1 + \gamma_1 \alpha_1 C_-^2 \cdot S_-^1)(\omega), \\ D_{22}(\omega) &= (\gamma_2 \alpha_2 S_-^2 \cdot S_-^1 + \gamma_2 \alpha_1 C_+^2 \cdot C_-^1 + \gamma_1 \alpha_2 S_+^2 \cdot S_+^1 + \gamma_1 \alpha_1 C_-^2 \cdot C_+^1)(\omega). \end{aligned}$$

We put

$$\begin{aligned} d(\omega) &:= 4 \det D(\omega) \\ &= 4\gamma_2^2 \alpha_2 \alpha_1 (S_+^2 \cdot S_-^2 - C_+^2 \cdot C_-^2) \cdot (S_+^1 \cdot S_-^1 - C_-^1 \cdot C_+^1)(\omega) \\ &\quad + 4\gamma_2 \gamma_1 \alpha_2^2 (S_+^2 \cdot C_+^2 - S_-^2 \cdot C_-^2) \cdot (S_+^1 \cdot C_-^1 - C_+^1 \cdot S_-^1)(\omega) \\ &\quad + 8\gamma_2 \gamma_1 \alpha_2 \alpha_1 (S_+^2 \cdot S_+^2 - C_+^2 \cdot C_-^2) \cdot (S_+^1 \cdot S_+^1 - C_+^1 \cdot C_-^1)(\omega) \\ &\quad + 4\gamma_2 \gamma_1 \alpha_1^2 (S_+^2 \cdot C_-^2 - C_+^2 \cdot S_-^2) \cdot (S_+^1 \cdot C_+^1 - S_-^1 \cdot C_-^1)(\omega) \\ &\quad + 4\gamma_1^2 \alpha_1 \alpha_2 (S_+^2 \cdot S_-^2 - C_-^2 \cdot C_+^2) \cdot (S_+^1 \cdot S_-^1 - C_+^1 \cdot C_-^1)(\omega). \end{aligned} \quad (6)$$

By (4), (5), we have

$$D(\omega) \begin{pmatrix} p_3^1 \\ p_4^1 \end{pmatrix} = 0.$$

Since ϕ is an eigenfunction if and only if $(p_3^1, p_4^1) \neq 0$, we see that $\lambda = \omega^4$ is an eigenvalue of \mathcal{A} if $d(\omega) = 0$, $\omega > 0$. Let ω_n , $n \in \mathbb{N}$, is the n -th positive zero of $d(\omega)$. Then $\lambda_n := \omega_n^4$,

$0 < \omega_1 < \omega_2 < \dots$, is the n -th eigenvalue of \mathcal{A} . We can verify that λ_n is a simple eigenvalue. Let ϕ^n be an eigenfunction corresponding to λ_n , normalized in H . In the following, let $\varphi(\omega)$ be a function defined by

$$\varphi(\omega) = A \cos \beta_1 \omega \cos \beta_2 \omega - B \sin \beta_1 \omega \sin \beta_2 \omega + C \sin(\beta_1 - \beta_2) \omega \quad (7)$$

where $A = (\gamma_1 \alpha_1 + \gamma_2 \alpha_2)(\gamma_1 \alpha_2 + \gamma_2 \alpha_1)$, $B = \gamma_1 \gamma_2 (\alpha_1 + \alpha_2)^2$, $C = \gamma_1 \gamma_2 (\alpha_1^2 - \alpha_2^2)$. We denote the n -th positive zero of φ by μ_n .

Lemma 2 $d(\omega)$ is written as

$$d(\omega) = e^{(\beta_1 + \beta_2)\omega} (\varphi(\omega) - h(\omega)), \quad \omega \in \mathbf{R}$$

where $h(\omega) \in C^1(\mathbf{R})$ and $h(\omega) \rightarrow 0$, $h'(\omega) \rightarrow 0$ exponentially as $\omega \rightarrow \infty$.

Proof By (6), $h(\omega) = \varphi(\omega) - e^{-(\beta_1 + \beta_2)\omega} d(\omega)$ and $h'(\omega)$ converge to 0 exponentially as $\omega \rightarrow \infty$.

To discuss controllability, we treat the moment problem on the system (1)(2)(3)(4). According to Krabs [4] or Russell [12], to solve the moment problem, we need the following conditions:

$$\liminf_{n \rightarrow \infty} (\omega_{n+1}^2 - \omega_n^2) > \frac{2\pi}{T}, \quad (8)$$

$$\limsup_{y \rightarrow \infty} \limsup_{x \rightarrow \infty} \frac{d(x+y) - d(x)}{y} < \frac{T}{2\pi} \quad (9)$$

where $d(x) =$ number of ω_j with $\omega_j < x^2$. The aim of this paper is to prove the following

Theorem 1 We have

- (1) There exist M and N such that $\omega_{M+n} - \mu_{N+n} \rightarrow 0$,
- (2) $0 < \frac{1}{a}(\pi - \sin^{-1} k) \leq \liminf_{n \rightarrow \infty} (\omega_{n+1} - \omega_n) \leq \limsup_{n \rightarrow \infty} (\omega_{n+1} - \omega_n) < \infty$,
- (3) $\lim_{n \rightarrow \infty} (\omega_{n+1}^2 - \omega_n^2) = \infty$.

By this theorem, it is clear that $\{\omega_n\}_{n \in \mathbf{N}}$ satisfies the condition (8). Moreover, the condition (8) verify the condition (9).

Some simple facts for $\varphi(\omega)$ are given in the following

Lemma 3 In the formula (7), we have

- (1) $A \geq B > 0$,
- (2) $A = B$ if and only if $\rho_1 T_1 = \rho_2 T_2$.
- (3) $C = 0$ if and only if $\rho_1 T_2 = \rho_2 T_1$.
- (4) $A = B$, $C = 0$ if and only if $(\rho_1, T_1) = (\rho_2, T_2)$.
- (5) $A > B$ or $C \neq 0$ if and only if $(\rho_1, T_1) \neq (\rho_2, T_2)$.

(6) φ is written as

$$\varphi(\omega) = D(\cos a\omega + k \sin(b\omega + \tau)), \quad 0 \leq k < 1 \quad (10)$$

where $D = (A+B)/2$, $a = \beta_1 + \beta_2$, $b = \beta_1 - \beta_2$, $k = R/D$, $R = \sqrt{((A-B)/2)^2 + C^2}$, $\tau = \cos^{-1}(C/R) \in [0, \pi]$ for $R \neq 0$ and $\tau = 0$ for $R = 0$.

Proof We see (1) from $A = B + \alpha_1\alpha_2(\gamma_1 - \gamma_2)^2 \geq B > 0$. The assertions (2), (3), (4) and (5) are clear. We have (6) since

$$\begin{aligned} \varphi(\omega) &= \frac{A+B}{2} \cos(\beta_1 + \beta_2)\omega + \frac{A-B}{2} \cos(\beta_1 - \beta_2)\omega + C \sin(\beta_1 - \beta_2)\omega \\ &= D \cos a\omega + R \sin(b\omega + \tau) = D(\cos a\omega + k \sin(b\omega + \tau)). \end{aligned}$$

where $k \geq 0$ satisfies

$$k^2 = \frac{R^2}{D^2} = \frac{(A+B)^2 - 4(AB - C^2)}{(A+B)^2} = 1 - \frac{4(\gamma_1 + \gamma_2)^2 \gamma_1 \gamma_2 (\alpha_1 + \alpha_2)^2 \alpha_1 \alpha_2}{(A+B)^2} < 1.$$

We assume $\beta_1 \geq \beta_2 > 0$ for simplicity. So we have $a > b \geq 0$. We put $f_k(\omega) = \cos a\omega + k \sin(b\omega + \tau)$. Since $f_k(\omega) = 0$ implies $|\cos a\omega| = |k \sin(b\omega + \tau)| \leq k$, all the positive zeros of $\varphi(\omega)$ are in the set $\{\omega > 0; |\cos a\omega| \leq k\} = \bigcup_{n=1}^{\infty} \mathcal{I}_n(k)$, $\mathcal{I}_n(k) = [s_n(k), t_n(k)] \subset \mathcal{J}_n = [(n-1)\pi/a, n\pi/a]$, $n = 1, 2, \dots$ where $s_n(k) = (2n-1)\pi/2a - \sin^{-1} k/a$, $t_n(k) = (2n-1)\pi/2a + \sin^{-1} k/a$. We write $\mathcal{I}_n = \mathcal{I}_n(k)$, $s_n = s_n(k)$, $t_n = t_n(k)$ and $f(\omega) = f_k(\omega)$. In Theorem 2 below, we prove that there exists exactly one zero of f in each $\mathcal{I}_n \subset \mathcal{J}_n$.

Theorem 2 For each $n \in \mathbb{N}$, there exist $u_n, v_n \in \mathcal{I}_n$ such that

- (1) $f(u_n) = 1 - k = -f(v_n)$ and $f(\omega)$ is monotone decreasing on $[u_n, v_n]$ for odd n ,
- (2) $f(u_n) = k - 1 = -f(v_n)$ and $f(\omega)$ is monotone increasing on $[u_n, v_n]$ for even n ,
- (3) $|f(\omega)| \geq 1 - k$ for $\omega \in \mathcal{J}_n \setminus [u_n, v_n]$
- (4) only zero of f exists in (u_n, v_n) for any n , which implies that $\mu_n \in \mathcal{I}_n$ for any $n \in \mathbb{N}$.

First, we show, for sufficiently small k , $\mu_n \in \mathcal{I}_n$ for every $n \in \mathbb{N}$.

Lemma 4 Let $k \in [0, 1/\sqrt{2}]$. Then we have

- (1) for odd n , $f(s_n) \geq 0 \geq f(t_n)$ and $f(\omega)$ is monotone decreasing on $[s_n, t_n]$,
 - (2) for even n , $f(t_n) \geq 0 \geq f(s_n)$ and $f(\omega)$ is monotone increasing on $[s_n, t_n]$,
- Consequently, in \mathcal{J}_n , $f(\omega)$ has only one zero in $[s_n, t_n]$.

Proof We only show (1). (2) is proved similarly.

$$\begin{aligned} f(s_n) &= \cos\left(\frac{(2n-1)\pi}{2} - \sin^{-1} k\right) - k \sin(bs_n + \tau) \\ &= (-1)^{n+1} k - k \sin(bs_n + \tau) = k - k \sin(bs_n + \tau) \geq 0 \\ f(t_n) &= (-1)^n k - k \sin(bs_n + \tau) = -k - k \sin(bs_n + \tau) \leq -k + k = 0. \end{aligned}$$

In $[s_n, t_n]$, we have $\sin a\omega \geq 1/\sqrt{2}$ and

$$f'(\omega) = -a \sin a\omega + kb \cos(b\omega + \tau) \leq -a/\sqrt{2} + b/\sqrt{2} < 0.$$

In the following, we put $\bar{k} = kb^2/a^2$, $\bar{s}_n = s_n(\bar{k})$, $\bar{t}_n = t_n(\bar{k})$, $\bar{\mathcal{I}}_n = \mathcal{I}_n(\bar{k})$, and $\bar{\mu}_n = \mu_n(\bar{k})$, $\bar{f}(\omega) = f_{\bar{k}}(\omega)$ and $S = \{k \in [0, 1]; \mu_n(k) \in \mathcal{I}_n(k) \subset \mathcal{J}_n \text{ for each } n \in \mathbb{N}\}$.

Lemma 5 For $\bar{k} \in S$, the conclusion of Theorem 2 is valid.

Proof We have

$$\begin{aligned} f''(\omega) &= f''_k(\omega) = -a^2 \cos a\omega - kb^2 \sin(b\omega + \tau) \\ &= -a^2(\cos a\omega + \bar{k} \sin(b\omega + \tau)) = -a^2 \bar{f}_k(\omega) = -a^2 \bar{f}(\omega). \end{aligned}$$

Let n be odd. The case where n is even is also treated similarly. Then $\bar{f}((n-1)\pi/a) \geq 1-k > 0 > k-1 \geq \bar{f}(\pi/a)$. Since $\bar{\mu}_n$ is the only zero of \bar{f} in $((n-1)\pi/a, n\pi/a)$, we have $f''(\omega) < 0$ for $\omega \in ((n-1)\pi/a, \bar{\mu}_n)$, $f''(\omega) > 0$ for $\omega \in (\bar{\mu}_n, n\pi/a)$. Thus $f(\omega)$ is concave on $((n-1)\pi/a, \mu_n)$ and convex on $(\mu_n, n\pi/a)$. Let $y_n, z_n \in \mathcal{J}_n$ with $f(y_n) = \max_{\omega \in \mathcal{I}_n} f(\omega) \geq 1-k$ and $f(z_n) = \min_{\omega \in \mathcal{I}_n} f(\omega) \leq k-1$. Then, we find u_n, v_n with $s_n \leq y_n < \mu_n < v_n \leq z_n \leq t_n$ such that $f(u_n) = 1-k$ and $f(v_n) = k-1$. Thus, f is monotone decreasing on $[u_n, v_n] \subset [y_n, z_n]$.

Proof of Theorem 2 There exists $N \in \mathbb{N}$ such that $0 \leq (b/a)^{2N} \leq 1/2$. Let $k \in [0, 1)$ and $k_i = k(b/a)^{2i}$, $i = 0, 1, 2, \dots, N$. Then $k_N \in S$ by Lemma 4. Therefore, by Lemma 5, $k_i \in S$, $i = 1, 2, \dots, N-1$. In particular, $k_1 = k(b/a)^2 = \bar{k} \in S$. Thus, by using Lemma 5 again, we can prove Theorem 2.

Next, we want to show that, for sufficiently large n , there exists only one zero of $d(\omega)$ in each \mathcal{J}_n . More precisely, we have

Theorem 3 There exists $M, N \in \mathbb{N}$ such that $\omega_{M+n} \in \mathcal{J}_{N+n}$ for $n = 0, 1, \dots$.

To prove the above theorem, we prepare Lemma 6 and lemma 7 given below:

Lemma 6 For any $n \in \mathbb{N}$, the following inequality holds:

$$|f'(\mu_n)| \geq \delta = \sqrt{(1-k^2)(a^2-b^2)}. \quad (11)$$

Proof Since $\mu_n, n \in \mathbb{N}$, are zeros of f , we have

$$f(\mu_n) = \cos a\mu_n + k \sin(b\mu_n + \tau) = 0, \quad (12)$$

$$f'(\mu_n) = -a \sin a\mu_n + kb \cos(b\mu_n + \tau). \quad (13)$$

If $b = 0$, then $(f'(\mu_n))^2 = a^2 \sin^2 a\mu_n = a^2(1 - \cos^2 \tau) \geq a^2(1 - k^2)$. Hence we have (11). If $b \neq 0$, then

$$\begin{aligned} f'(\mu_n)^2 &= \frac{(a^2-b^2)}{b^2} \left(\sin a\mu_n - \frac{af'(\mu_n)}{a^2-b^2} \right)^2 + (1-k^2)(a^2-b^2) \\ &\geq (1-k^2)(a^2-b^2). \end{aligned}$$

Thus we have (11).

Lemma 7 *There exists an interval $[a_n, b_n] \subset [u_n, v_n]$ and $l \in [0, 1 - k]$ such that*

$$|f(\omega)| \leq l, \quad |f'(\omega)| \geq \delta/2 \quad \text{for } \omega \in [a_n, b_n], \quad (14)$$

$$|f(\omega)| \geq l \quad \text{for } \omega \in \mathcal{J}_n \setminus [a_n, b_n]. \quad (15)$$

Proof By uniform continuity of $f'(\omega)$ and Lemma 6, there exists $c > 0$ with $l = \delta c/2 < 1 - k$ such that

$$|f'(\omega)| \geq \delta/2 \quad \text{for } \omega \in [\mu_n - c, \mu_n + c]. \quad (16)$$

Therefore, we have $|f(\omega)| \geq (\delta/2)|\omega - \mu_n|$ on $[\mu_n - c, \mu_n + c]$. If n is odd (resp. even), we define a_n, b_n with $\mu_n - c < a_n < b_n < \mu_n + c$ by $f(a_n) = l$ (resp. $-l$) and $f(b_n) = -l$ (resp. l). Hence we have

$$\{\omega \in [\mu_n - c, \mu_n + c]; |f(\omega)| \leq l\} = [a_n, b_n]. \quad (17)$$

By (16) and (17), we see (14), and by Theorem 3, (15).

We put $g(\omega) = \varphi(\omega) - h(\omega) = Df(\omega) - h(\omega)$. Since $h(\omega), h'(\omega) \rightarrow 0$ as $\omega \rightarrow \infty$, there exists $N \in \mathbb{N}$ such that $|h(\omega)| < Dl$ and $|h'(\omega)| < D\delta/2$ for $\omega > (N - 1)\pi/a$.

Let n be odd with $n > N$. Then, by Lemma 7, we have $f(a_n) = l, f(b_n) = -l$ and $f'(\omega) < -\delta/2$ for $\omega \in [a_n, b_n]$. Hence $g(a_n) = Df(a_n) - h(a_n) = Dl - h(a_n) > Dl - Dl = 0$ and $g(b_n) = Df(b_n) - h(b_n) = Dl - h(b_n) < -Dl + Dl = 0$. Thus, for $\omega \in [a_n, b_n]$, $g'(\omega) = Df'(\omega) - h'(\omega) \leq -D\delta/2 + |h'(\omega)| < -D\delta/2 + D\delta/2 = 0$ which implies that $g(\omega)$ has a unique zero in (a_n, b_n) . For $\omega \in \mathcal{J}_n \setminus [a_n, b_n]$, by (14), we have $|g(\omega)| \geq |Df(\omega)| - |h(\omega)| \geq Dl - Dl = 0$. Therefore, $g(\omega)$ has a unique zero in \mathcal{J}_n . The case with even $n \geq N$ is also similarly proved. Let ω_M be a zero of $g(\omega)$ in \mathcal{J}_N . Thus $\omega_{M+n} \in \mathcal{J}_{N+n}$ for $n = 0, 1, 2, \dots$

Proof of Theorem 1 Since $f(\mu_{N+n}) = g(\omega_{M+n}) = 0$, we have

$$h(\omega_{M+n}) = Df(\omega_{M+n}) - g(\omega_{M+n}) = D(f(\omega_{M+n}) - f(\mu_{N+n})). \quad (18)$$

By Mean Value Theorem, there exists $\theta \in (0, 1)$ such that $f(\omega_{M+n}) - f(\mu_{N+n}) = (\omega_{M+n} - \mu_{N+n})f'(\mu_{N+n} + \theta(\omega_{M+n} - \mu_{N+n}))$. Thus, by (14) and (18),

$$|\omega_{N+n} - \mu_{N+n}| \leq \frac{|f(\omega_{M+n}) - f(\mu_{N+n})|}{|f'(\mu_{N+n} + \theta(\omega_{M+n} - \mu_{N+n}))|} \leq \frac{2}{D\delta} |h(\omega_{M+n})| \rightarrow 0$$

as $n \rightarrow \infty$. Therefore,

$$\begin{aligned} \liminf_{n \rightarrow \infty} (\omega_{n+1} - \omega_n) &= \liminf_{n \rightarrow \infty} (\omega_{M+n+1} - \omega_{M+n}) \\ &= \liminf_{n \rightarrow \infty} (\omega_{M+n+1} - \mu_{N+n+1} + \mu_{N+n+1} - \mu_{N+n} + \mu_{N+n} - \omega_{M+n}) \\ &= \liminf_{n \rightarrow \infty} (\mu_{N+n+1} - \mu_{N+n}) = \liminf_{n \rightarrow \infty} (\mu_{n+1} - \mu_n). \end{aligned}$$

By $s_n < \mu_n < t_n < s_{n+1} < \mu_{n+1} < t_{n+1}$, we have

$$\begin{aligned} \mu_{n+1} - \mu_n &\geq s_{n+1} - t_n = \left(\frac{2n+1}{2a} \pi - \frac{\sin^{-1} k}{a} \right) - \left(\frac{2n-1}{2a} \pi + \frac{\sin^{-1} k}{a} \right) \\ &= \frac{\pi}{a} - \frac{2 \sin^{-1} k}{a} = \frac{1}{a} (\pi - 2 \sin^{-1} k) \end{aligned}$$

The above theorem implies that

$$\liminf_{n \rightarrow \infty} (\omega_{n+1}^2 - \omega_n^2) \geq \liminf_{n \rightarrow \infty} (\omega_{n+1} + \omega_n) \liminf_{n \rightarrow \infty} (\omega_{n+1} - \omega_n) = \infty. \quad (19)$$

3 Concluding Remarks

This paper is only a first step to the controllability theory for the Euler-Bernoulli equation using the moment problem method [4], [12].

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