Relation between Equilibrium points for a Differential Inclusion and Solutions of a Variational Inequality

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We introduce a relation between equiliblium points for some differential inclusion and solutions of a variational inequality. At first we show convergence theorems of solutions for some differential inclusions.

1. Convergence Theorem for Differential Inclusions

Let X be a Hilbert space with an inner product (,), let $K \subset X$ be a non-empty closed convex subset of X, let A be a set-valued mapping from K to 2^X with convex compact set-value, and let $x() : [0,\infty) \to X$. We consider a differential inclusion DI(A, K) for A and K as follows:

$$DI(A,K) : \begin{cases} x(t) \in K \text{ for any } t \in [0,\infty), \\ \dot{x}(t) \in -A(x(t)) \text{ for almost any } t \in (0,\infty). \end{cases}$$

Next we give some definitions.

定義 (Def.) (1) x() is called a trajectory of DI(A, K), if a mapping $x() : [0,\infty) \to K$ is absolutely continuous and satisfies DI(A, K).

(2) A point $x^* \in K$ is said to be an equilibrium point for DI(A, K) if $0 \in -A(x^*)$.

Let $\varphi : X \to (-\infty, \infty]$ be a proper lower semi-continuous convex function. A subdifferential $\partial \varphi : X \to 2^X$ is defined by

$$\partial \varphi(x) = \{ w \in X : \varphi(y) \ge \varphi(x) + (w, y - x) \text{ for any } y \in X \}.$$

Then it is well-known that $x^* \in K$ is an equilibrium point of $DI(\partial \varphi, K)$ if and only if x^* is a minimum point of φ , i.e., $\varphi(x^*) = \min_{x \in X} \varphi(x)$. It is also known that $\partial \varphi$ has a property of *demipositivity*.

c \ddagger (Def.) A set-valued mapping $A : X \to 2^X$ is said to be *demi* positive if (1),(2) and (3) hold:

(1) $(v, x - y) \ge 0$ for all $x \in X, y \in A^{-1}(0)$ and $v \in A(x)$.

(2) There exists $y_0 \in A^{-1}(0)$ such that $0 \in A(x)$ whenever $(v, x - y_0) = 0$ for all $v \in A(x)$.

(3) For the y_0 in (2), if $x_n \to x$, $v_n \in A(x_n)$, $\{v_n\}$ is bounded and $\lim_{n\to\infty}(v_n, x_n - y_0) = 0$, then $0 \in A(x)$.

(Remark) If A satisfies (1) and (2), A is called *firmly* positive.

Bruck showed the convergence theorems with respect to a *demi* positive mapping.

定理(Theorem1)([1] Bruck, 1974)

Suppose $A : X \to 2^X$ is *demi* positive and that $x() : [0,\infty) \to X$ is an *absolutely continuous* mapping satisfying

 $\begin{cases} x(t) \in D(A) \text{ for all } t \geq 0, \\ \dot{x}(t) \in -A(x(t)) \text{ for almost all } t > 0, \\ \|x(t)\| \in L^{\infty}(0,\infty). \end{cases}$

Then there exists $x^* = w - \lim_{t\to\infty} x(t)$ and $x^* \in A^{-1}(0)$.

定理 (Theorem2) ([1] Bruck, 1974) Let $\varphi : X \to (-\infty, \infty]$ be a proper lower semi-continuous convex even function with a minimum. Then there exists a unique solution $x() : [0, \infty) \to X$, which is absolutely continuous on $[\delta, \infty)$ for all $\delta > 0$, satisfying

$$\begin{cases} x(t) \in D(\partial \varphi) \text{ for all } t > 0, \\ \dot{x}(t) \in -\partial \varphi(x(t)) \text{ for almost all } t > 0, \end{cases}$$

and there exists $x^* = s - \lim_{t\to\infty} x(t)$ such that $\varphi(x^*) = \min_{x\in X} \varphi(x)$.

We shall introduce the sufficient conditions of *demipositivity*.

定理 (Theorem3) ([1] Bruck, 1974) A set-valued mapping $A : X \to 2^X$ is *demi* positive when the following one of (a)-(e) holds:

(a) A is a subdifferential $\partial \varphi$ of a proper lower semi-continuous convex function $\varphi : X \to [-\infty, \infty)$ with a minimum in X.

(b) A is I - T, where I is an identity function and T is a non-expansive mapping with a fixed point.

(c) A is maximal monotone, odd and firmly positive.

(d) A is maximal monotone and $intA^{-1}(0) \neq \emptyset$.

(e) A is maximal monotone, firmly positive and weakly closed.

(Remark) (1) $A : X \to 2^X$ is called monotone if $(u - v, x - y) \ge 0$ for any $x, y \in D(A)$ and $u \in A(x), v \in A(y)$.

(2) A is called maximal monotone if it is not properly contained in any other monotone subset of X.

(3) A is said to be weakly closed if $x_n \to x$, $v_n \to v$, $v_n \in A(x_n)$ and then $v \in A(x)$.

There are many results of approximations of equilibrium points for Maximal operators ([2], [3], etc.)

2. Solutions of Variational Inequality and Equilibrium points of Differential

Variational Inequality

Let $F : K \to 2^X$ be a upper semi-continuous set-valued mapping such that F(x) is a non-empty convex compact subset of X for any $x \in X$, where F is said to be upper semi-continuous if for any open set U containing $F(x_0)$ there exists a neighborhood V of x_0 such that $F(V) \subset U$, where $F(V) = \bigcup_{x \in V} F(x)$. We give some definitions for solutions of variational inequalities for F and K.

定義 (Def.) [4] (1) $x^* \in K$ is called a solution of Stampacchia variational inequality SVI(F, K) if there exists $\xi^* \in F(x^*)$ such that $(\xi^*, y - x^*) \ge 0$ for all $y \in K$. 定義 (Def.) (2) $x^* \in K$ is called a solution of Strong Minty variational inequality SMVI(F, K) if for all $y \in K$, $(\eta, y - x^*) \ge 0$ for all $\eta \in F(y)$.

定義 (Def.) (3) $x^* \in K$ is called a solution of Weak Minty variational inequality WMVI(F, K) if for any $y \in K$ there exists $\eta_0 \in F(y)$ such that $(\eta_0, y - x^*) \ge 0$.

F is said to be pseudomonotone if for all $x, y \in K$ there exists $u \in F(x)$ such that $(u, y - x) \ge 0$ then $(v, y - x) \ge 0$ for all $v \in F(y)$. If *F* is pseudomonotone, the set of solutions of *SVI*(*F*, *K*) coincides with the set of solutions of *SMVI*(*F*, *K*), *WMVI*(*F*, *K*). Results with respect to the convergence theorems of variational inequalities are shown in many approaches ([5], [6], [7]).

Let $T_K(x) = \{v \in X : x + \alpha_n v_n \in K, \alpha_n > 0, \alpha_n \to 0, v_n \to v(n \to \infty)\}$ and let $N_K(x) = \{y \in X : (y, v) \le 0 \text{ for any } v \in T_K(x)\}$. $T_K(x)$ is called a tangent cone and $N_K(x)$ is called a normal cone. The following differential inclusion is said to be a differential variational inequality DVI(F, K).

$$DVI(F,K) : \begin{cases} x(t) \in K \text{ for all } t \in [0,\infty), \\ \dot{x}(t) \in -(F+N_K)(x(t)) \text{ for } a.e.t \in [0,\infty). \end{cases}$$

And we call the following differential inclusion a projected differential inclusion PDI(F, K).

$$PDI(F,K) : \begin{cases} x(t) \in K \text{ for all } t \in [0,\infty), \\ \dot{x}(t) \in P_{T_{K(x)}}(-F)(x(t)) \text{ for } a.e.t \in [0,\infty), \end{cases}$$

where $P_{T_{K(x)}}$ is a projection onto $T_K(x(t))$. It is shown that x(t) is a solution of DVI(F, K) if and only if x(t) is a solution of PDI(F, K).

G.P.Crespi and M.Rocca showed the following theorems ([8]).

定理 (Theorem (G.P.Crespi and M.Rocca,2004)) Let $x^* \in K$ be an equilibrium point of DVI(F, K) and assume that F is pseudomonotone. Then every solution x(t) of DVI(F, K) satisfies that

$$||x(t) - x^*|| \le ||x(s) - x^*||$$
 for $t \ge s$.

We shall introduce the relation between equilibrium points of DVI(F, K) and solutions of SVI(F, K).

定理 (Theorem) Let $K \subset X$ be a closed convex subset, and let $F : X \to 2^X$ be an upper semi-continuous mapping with non-empty convex and compact values. Assume F is pseudomonotone. Then, the following (a) and (b) are equivalent: (a) $x^* \in K$ is an equilibrium point of DVI(F, K). (b) $x^* \in K$ is a solution of SVI(F, K).

There are many results of convergence theorems to solutions of SVI(F, K) by using iterative schemes and also given many results of approximating solutions. We try to study the approximation theory and the iterative methods in order to find an equilibrium point of DI(F, K) with respect to the fixed point theory with good compositions of operator F of a large class of set-valued mappings.([9])

[Refferences]

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